

Signetics

PLD  
Data  
Manual



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**SCHWEBER  
ELECTRONICS**



**PHILIPS**

Signetics

Application Specific Products



PLD  
Data Manual  
1989

Signetics Approach  
to  
Logic Flexibility:  
Programmable Logic  
Devices

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### Application Specific Products

The continuing trend of system integration has created new challenges for Design Engineering. They must strive to consolidate higher complexity, and more feature intensive circuits into designs without sacrificing flexibility. Today's competitive electronic marketplace has created the need for logic devices, which can provide cost effective methods of reducing random logic requirements, interface with fixed and custom LSI logic, and maintain the flexible features required to make necessary system modifications prior to production. Signetics has responded to this need with Signetics Programmable Logic Devices (Signetics PLD).

The Signetics Programmable Logic family consists of devices which are designed to address logic needs ranging from random gates in the case of the Field Programmable Gate Arrays, to highly sophisticated state machines in the case of Field Programmable Logic Sequencers. Signetics pioneered the fully-programmable AND/OR/INVERT architecture in 1975. In 1987, Signetics introduced yet another new concept in PLD architectures. Moving away from an AND-OR array structure, the Signetics' Programmable Macro Logic architecture relies on a single NAND array concept. Signetics' novel architectural approach to Programmable Logic incorporates all the advantages associated with more dense complex gate arrays while retaining all the benefits of instantly programmable PLDs. By using the programmable features allowed by either powerful architecture, Signetics Programmable Logic can encompass wide-ranging levels of integration without the necessity of a multitude of devices, each with a different I/O configuration. The flexible programming structure allows the designer to "mold" the device architecture to the range of applications typically found in system design. In this way, one device can be used to perform several functions in the same design.

The 1988 – 1989 Signetics Programmable Logic Data Manual contains information that the designer will require in order to effectively utilize these products.

Signetics Application Specific Products Marketing

### Application Specific Products

DEFINITIONS		
Data Sheet Identification	Product Status	Definition
<i>Objective Specification</i>	Formative or In Design	This data sheet contains the design target or goal specifications for product development. Specifications may change in any manner without notice.
<i>Preliminary Specification</i>	Preproduction Product	This data sheet contains preliminary data and supplementary data will be published at a later date. Signetics reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.
<i>Product Specification</i>	Full Production	This data sheet contains Final Specifications. Signetics reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

## Application Specific Products

Preface .....	iii
Product Status .....	iv
<b>Section 1 – General Information</b>	
Alphanumeric Index .....	1-3
Selection Guide .....	1-4
Device Programmer Reference Guides .....	1-6
Ordering Information .....	1-10
<b>Section 2 – Introduction</b>	
What Is Signetics Programmable Logic .....	2-3
Quality and Reliability .....	2-28
<b>Section 3 – PAL<sup>®</sup>-Type Devices Data Sheets</b>	
<b>Series 20</b>	
PLC16V8                   Erasable and OTP PAL <sup>®</sup> -Type Device .....	3-3
PLHS16L8A               PAL <sup>®</sup> -Type Device .....	3-13
PLHS16L8B               PAL <sup>®</sup> -Type Device .....	3-20
PLUS16R8D               PAL <sup>®</sup> -Type Devices .....	3-27
PLHS18P8A               PAL <sup>®</sup> -Type Device .....	3-30
PLHS18P8B               PAL <sup>®</sup> -Type Device .....	3-37
<b>Series 24</b>	
PLC20V8                   Erasable and OTP PAL <sup>®</sup> -Type Device .....	3-44
PLUS20R8D               PAL <sup>®</sup> -Type Devices .....	3-54
<b>Section 4 – Programmable Logic Array Devices Data Sheets</b>	
<b>Series 20</b>	
PLS151                   Field-Programmable Gate Array (18 × 15 × 12); 25ns .....	4-3
PLC153                   Erasable and OTP Programmable Logic Array (18 × 32 × 10); 45/60ns .....	4-9
PLS153                   Field-Programmable Logic Array (18 × 42 × 10); 40ns .....	4-16
PLS153A                  Field-Programmable Logic Array (18 × 42 × 10); 30ns .....	4-22
PLHS153                  Field-Programmable Logic Array (18 × 42 × 10); 20ns .....	4-28
PLUS153B                 Field-Programmable Logic Array (18 × 42 × 10); 15ns .....	4-34
PLUS153D                 Field-Programmable Logic Array (18 × 42 × 10); 12ns .....	4-40
<b>Series 24</b>	
PLS161                   Field-Programmable Logic Array (12 × 48 × 8); 50ns .....	4-46
PLS162                   Field-Programmable Address Decoder (16 × 5); 30ns .....	4-52
PLS163                   Field-Programmable Address Decoder (12 × 9); 30ns .....	4-58
PLS173                   Field-Programmable Logic Array (22 × 42 × 10); 30ns .....	4-64
PLUS173B                 Field-Programmable Logic Array (22 × 42 × 10); 15ns .....	4-70
PLUS173D                 Field-Programmable Logic Array (22 × 42 × 10); 12ns .....	4-76
PLC473-60               Erasable and OTP Programmable Logic Array (20 × 24 × 11); 60ns .....	4-82
PLHS473                  Field-Programmable Logic Array (20 × 24 × 11); 22ns .....	4-89
<b>Series 28</b>	
PLS100/101               Programmable Logic Array (16 × 48 × 8); 50ns .....	4-95
PLS103                   Programmable Gate Array (16 × 9 × 9); 35ns .....	4-102
<b>Section 5 – Programmable Logic Sequencer Devices Data Sheets</b>	
<b>Series 20</b>	
PLS155                   Field-Programmable Logic Sequencer (16 × 45 × 12); 18.2MHz .....	5-3
PLS157                   Field-Programmable Logic Sequencer (16 × 45 × 12); 18.2MHz .....	5-14
PLS159A                  Field-Programmable Logic Sequencer (16 × 45 × 12); 25MHz .....	5-25
<b>Series 24</b>	
PLS167                   Field-Programmable Logic Sequencer (14 × 48 × 6); 20MHz .....	5-35
PLS167A                  Field-Programmable Logic Sequencer (14 × 48 × 6); 25MHz .....	5-47
PLS168                   Field-Programmable Logic Sequencer (12 × 48 × 8); 20MHz .....	5-59
PLS168A                  Field-Programmable Logic Sequencer (12 × 48 × 8); 25MHz .....	5-71
PLS179                   Field-Programmable Logic Sequencer (20 × 45 × 12); 25MHz .....	5-83

# Contents

<b>Series 28</b>		
PLS105	Field-Programmable Logic Sequencer (16 × 48 × 8); 20MHz .....	5-93
PLS105A	Field-Programmable Logic Sequencer (16 × 48 × 8); 25MHz .....	5-105
PLUS405	Field-Programmable Logic Sequencer (16 × 64 × 8); 50MHz .....	5-117
<b>Section 6 – Programmable Macro Logic Devices Data Sheets</b>		
PLHS501	Programmable Macro Logic .....	6-3
PLHS502	Programmable Macro Logic .....	6-13
<b>Section 7 – Military Products</b>		
<b>Military Errata</b> .....		7-1
<b>Section 8 – Development Software</b>		
AMAZE – Automatic Map and Zap Equations Design Software .....		8-3
<b>Section 9 – Application Notes</b>		
<b>PLD Application Notes</b>		
AN7	Single Chip Multiprocessor Arbiter .....	9-3
AN8	Introduction to Signetics Programmable Logic .....	9-15
AN10	4-Bit Binary-To-7 Segment Decoder .....	9-27
AN11	PLD Programmable Retriggerable One-Shot .....	9-51
AN13	Oscillator With PLS159 .....	9-55
AN14	Latches and Flip-Flops With PLS153 .....	9-60
AN15	PLS159 Primer .....	9-73
AN16	PLS159 as Modulo Counters .....	9-84
AN17	Electronic Combination Lock .....	9-91
AN18	Schmitt Trigger Using PLS153 and PLS159 .....	9-94
AN19	Electronic Dice .....	9-102
AN21	9-Bit Parity Generator/Checker With PLS153/153A .....	9-106
AN22	PLS151 Toolkit .....	9-112
AN23	PLS168/168A Primer .....	9-120
AN24	PLS173 as a 10-Bit Comparator, 74LS460 .....	9-133
AN25	A Simple Entry/Exit Meeting Device (PLS157) .....	9-139
AN26	PLHS18P8A Primer .....	9-145
AN27	PLHS473 Primer .....	9-154
AN28	High-Speed 12-Bit Tracking A/D Converter Using PLS179 .....	9-162
<b>PML Application Notes</b>		
AN29	PLHS501 Programmable Macro Logic Primer .....	9-172
<b>Designing with Programmable Macro Logic</b>		
Chapter 1	Introduction to PML Design Concepts .....	9-187
	Performance .....	9-187
	NAND Gate Flip-Flops .....	9-194
Chapter 2	Functional Fit .....	9-197
Chapter 3	Design Examples .....	9-200
Chapter 4	Successor Architectures .....	9-205
Chapter 5	Support Issues .....	9-206
Chapter 6	PLHS501 Examples Using AMAZE Revision 1.6 .....	9-207
	Simple Gate Implementations .....	9-207
	8-Bit Barrel Shifter .....	9-210
	12-Bit Comparator with Dual 1-of-8 Decoders .....	9-216
	8-Bit Carry Look-Ahead Adder .....	9-219
	32-to-5-Bit Priority Encoder .....	9-222
	8-Bit Shift Register with Sequence Detector .....	9-227
	4-Bit Synchronous Counter .....	9-233
<b>List of Figures</b>		
1.1	PML Basic Functions .....	9-187
1.2	PLHS501 Logic Diagram .....	9-189
1.3	Tpd3 – 22ns max .....	9-190
1.4	Tpd4 – 30ns max .....	9-191
1.5	Tpd1 – 25ns max .....	9-192
1.6	Tpd7 – 8ns max .....	9-193
1.7	Edge-Triggered D Flip-Flop .....	9-194
1.8	PLHS501 Test Flip-Flop .....	9-195
1.9	Partial PLHS501 Fusemap Showing Test Flip-Flop Fusing .....	9-195
1.10	Waveforms of Test Flip-Flop .....	9-196
2.1	16 Input NAND Formed From 2 Input Gates .....	9-198

# Contents

3.1	Decoder Implementation in NAND Foldback Structure .....	9-200
3.2	Two Flip-Flops Implemented in the NAND Foldback Structure .....	9-201
3.3	68000 Microprocessor Address Decoder .....	9-201
3.4	8-Bit Barrel Shifter Implemented with the PLHS501 .....	9-202
3.5	Partial NAND Gate Equivalence of the 8-Bit Look-Ahead Adder .....	9-203
3.6	12-Bit Ripple Counter .....	9-204
3.7	Encoder .....	9-204
4.1	PLHS502 Diagram .....	9-205
6.1	Gates Pin List .....	9-207
6.2	Gates Boolean Equations .....	9-208
6.3	Gates Simulation Input File .....	9-208
6.4	Gates Simulation Log File .....	9-209
6.5	Barrel Shifter Pin List .....	9-210
6.6	8-Bit Barrel Shifter Schematic .....	9-210
6.7	Barrel Shifter Boolean Equations .....	9-211
6.8	Barrel Shifter Simulation Input File .....	9-214
6.9	Barrel Shifter Simulation Log File .....	9-215
6.10	12-Bit Comparator Pin List .....	9-216
6.11	12-Bit Comparator with Dual 1 – 8 Decoders Block Diagram .....	9-216
6.12	12-Bit Comparator Boolean Equations .....	9-217
6.13	12-Bit Comparator Simulation Input File .....	9-218
6.14	12-Bit Comparator Simulation Log File .....	9-218
6.15	8-Bit Adder Pin List .....	9-219
6.16	8-Bit Carry Look-Ahead Adder Block Diagram and Equations .....	9-219
6.17	8-Bit Adder Boolean Equations .....	9-220
6.18	8-Bit Adder Simulation Input File .....	9-220
6.19	8-Bit Adder Simulation Log File .....	9-221
6.20	Encoder Pin List .....	9-222
6.21	32 to 5 Priority Encoder Block Diagram .....	9-222
6.22	Encoder Boolean Equations .....	9-223
6.23	Encoder Simulation Input File .....	9-225
6.24	Encoder Simulation Log File .....	9-226
6.25	8-Bit Shifter Pin List .....	9-227
6.26	Shift Register with Sequence Detector Block Diagram .....	9-227
6.27	8-Bit Shifter Boolean Equations .....	9-228
6.28	Portion of STD Files .....	9-230
6.29	8-Bit Shifter Simulation Input File .....	9-231
6.30	8-Bit Shifter Simulation Log File .....	9-232
6.31	4-Bit Counter Pin List .....	9-233
6.32	4-Bit Counter Boolean Equations .....	9-234
6.33	4-Bit Counter Simulation Input File .....	9-235
6.34	4-Bit Counter Simulation Log File .....	9-236
<b>List of Tables</b>		
1.1	Example Demonstration .....	9-188
2.1	Equivalency Ratio .....	9-198
2.2	PLHS501 Gate Count Equivalents .....	9-199
<b>Section 10 – Package Outlines</b>		
A	PLASTIC: Leadged Chip Carrier .....	10-3
F	CERAMIC: Dual-In-Line .....	10-6
FA	CERAMIC: Dual-In-Line With Quartz Window .....	10-8
N	PLASTIC: Dual-In-Line .....	10-10
<b>Section 11 – Sales Offices</b>		
	Office Listing .....	11-3





Application Specific Products

### INDEX

Alphanumeric Index .....	1-3
Selection Guide .....	1-4
Device Programmer Reference Guides .....	1-6
Ordering Information .....	1-10



## Application Specific Products

AN7		Single Chip Multiprocessor Arbiter .....	9-3
AN8		Introduction To Signetics Programmable Logic .....	9-15
AN10		4-Bit Binary-To-7 Segment Decoder .....	9-27
AN11		PLD Programmable Retriggerable One-Shot .....	9-51
AN13		Oscillator With PLS159 .....	9-55
AN14		Latches & Flip-Flops With PLS153 .....	9-60
AN15		PLS159 Primer .....	9-73
AN16		PLS159 As Modulo Counters .....	9-84
AN17		Electronic Combination Lock .....	9-91
AN18		Schmitt Trigger Using PLS153 and PLS159 .....	9-94
AN19		Electronic Dice .....	9-102
AN21		9-Bit Parity Generator/Checker With 82S153/153A .....	9-106
AN22		PLS151 Toolkit .....	9-112
AN23		PLS168/168A Primer .....	9-120
AN24		PLS173 As A 10-Bit Comparator, 74LS460 .....	9-133
AN25		A Simple Entry/Exit Meeting Device (PLS157) .....	9-139
AN26		PLHS18P8A Primer .....	9-145
AN27		PLHS473 Primer .....	9-154
AN28		High-Speed 12-Bit Tracking A/D Converter Using PLS179 .....	9-162
AN29		PLHS501 Programmable Macro Logic Primer .....	9-172
PLC16V8	Series 20	Erasable and OTP PAL <sup>®</sup> -Type Device .....	3-3
PLC20V8	Series 24	Erasable and OTP PAL <sup>®</sup> -Type Device .....	3-44
PLC153	Series 20	Erasable and OTP Programmable Logic Array (18 × 42 × 10) .....	4-9
PLC473	Series 24	Erasable-Programmable Logic Array (20 × 24 × 11) .....	4-82
PLHS153	Series 20	Field-Programmable Logic Array (18 × 42 × 10) .....	4-28
PLHS473	Series 24	Field-Programmable Logic Array (20 × 24 × 11) .....	4-89
PLHS16L8A	Series 20	PAL <sup>®</sup> -Type Device .....	3-13
PLHS16L8B	Series 20	PAL <sup>®</sup> -Type Device .....	3-20
PLHS18P8A	Series 20	PAL <sup>®</sup> -Type Device .....	3-30
PLHS18P8B	Series 20	PAL <sup>®</sup> -Type Device .....	3-37
PLHS501	Series 52	Programmable Macro Logic .....	6-3
PLHS502	Series 64	Programmable Macro Logic .....	6-13
PLS100/PLS101	Series 28	Field-Programmable Logic Array (16 × 48 × 8) .....	4-95
PLS103	Series 28	Field-Programmable Gate Array (16 × 9 × 9) .....	4-102
PLS105	Series 28	Field-Programmable Logic Sequencer (16 × 48 × 8) .....	5-93
PLS105A	Series 28	Field-Programmable Logic Sequencer (16 × 48 × 8) .....	5-105
PLS151	Series 20	Field-Programmable Gate Array (18 × 15 × 12) .....	4-3
PLS153	Series 20	Field-Programmable Logic Array (18 × 42 × 10) .....	4-16
PLS153A	Series 20	Field-Programmable Logic Array (18 × 42 × 10) .....	4-22
PLS155	Series 20	Field-Programmable Logic Sequencer (16 × 45 × 12) .....	5-3
PLS157	Series 20	Field-Programmable Logic Sequencer (16 × 45 × 12) .....	5-14
PLS159A	Series 20	Field-Programmable Logic Sequencer (16 × 45 × 12) .....	5-25
PLS161	Series 24	Field-Programmable Logic Array (12 × 48 × 8) .....	4-46
PLS162	Series 24	Field-Programmable Address Decoder (16 × 5) .....	4-52
PLS163	Series 24	Field-Programmable Address Decoder (12 × 9) .....	4-58
PLS167	Series 24	Field-Programmable Logic Sequencer (14 × 48 × 6) .....	5-35
PLS167A	Series 24	Field-Programmable Logic Sequencer; Enhanced Speed (14 × 48 × 6) .....	5-47
PLS168	Series 24	Field-Programmable Logic Sequencer (12 × 48 × 8) .....	5-59
PLS168A	Series 24	Field-Programmable Logic Sequencer; Enhanced Speed (12 × 48 × 8) .....	5-71
PLS173	Series 24	Field-Programmable Logic Array (22 × 42 × 10) .....	4-64
PLS179	Series 24	Field-Programmable Logic Sequencer (20 × 45 × 12) .....	5-83
PLUS153B	Series 20	Field-Programmable Logic Array (18 × 42 × 10) .....	4-34
PLUS153D	Series 20	Field-Programmable Logic Array (18 × 42 × 10) .....	4-40
PLUS16R8D	Series 20	PAL <sup>®</sup> -Type Devices .....	3-27
PLUS173B	Series 24	Field-Programmable Logic Array (22 × 42 × 10) .....	4-70
PLUS173D	Series 24	Field-Programmable Logic Array (22 × 42 × 10) .....	4-76
PLUS20R8D	Series 24	PAL <sup>®</sup> -Type Devices (20 × 64 × 8) .....	3-54
PLUS405	Series 28	Field-Programmable Logic Sequencer (16 × 64 × 8) .....	5-117

**Signetics**

**Selection  
Guide**

**Application Specific Products**

SIGNETICS PN	ARCHITECTURE	PACKAGE	TOTAL INPUTS (# Dedicated)	PRODUCT TERMS	INTERNAL STATE REGISTERS (# Dedicated)	OUTPUTS C, I/O, R/RI/O	T <sub>PD</sub> (Max)	F <sub>MAX</sub>	I <sub>CC</sub> (Max)
<b>PGA</b>									
PLS103	16 × 9 × 9	28-Pin	16 (16)	9	0	9 C	35ns		170mA
PLS151	18 × 15 × 12	20-Pin	18 (6)	15	0	12 I/O	25ns		155mA
<b>PAD</b>									
PLS162	16 × 5	24-Pin	16 (16)	5	0	5 C	30ns		155mA
PLS163	12 × 9	24-Pin	12 (12)	9	0	9 C	30ns		155mA
<b>PLA</b>									
PLS100	16 × 48 × 8	28-Pin	16 (16)	48	0	8 C	50ns		170mA
PLC153-45/60	18 × 42 × 10	20-Pin	18 (8)	42	0	10 I/O	45/60ns		60mA*
PLS153	18 × 42 × 10	20-Pin	18 (8)	42	0	10 I/O	40ns		155mA
PLS153A	18 × 42 × 10	20-Pin	18 (8)	42	0	10 I/O	30ns		155mA
PLHS153	18 × 42 × 10	20-Pin	18 (8)	42	0	10 I/O	20ns		155mA
PLUS153B	18 × 42 × 10	20-Pin	18 (8)	42	0	10 I/O	15ns		200mA
PLUS153D	18 × 42 × 10	20-Pin	18 (8)	42	0	10 I/O	12ns		200mA
PLS161	12 × 48 × 8	24-Pin	12 (12)	48	0	8 C	50ns		170mA
PLS173	22 × 42 × 10	24-Pin	22 (12)	42	0	10 I/O	30ns		170mA
PLUS173B	22 × 42 × 10	24-Pin	22 (12)	42	0	10 I/O	15ns		200mA
PLUS173D	22 × 42 × 10	24-Pin	22 (12)	42	0	10 I/O	12ns		200mA
PLC473-60	20 × 24 × 11	24-Pin	20 (11)	24	0	2 C, 9 I/O	60ns		60mA*
PLHS473	20 × 24 × 11	24-Pin	20 (11)	24	0	2 C, 9 I/O	22ns		155mA
<b>PAL<sup>®</sup>-TYPE</b>									
PLHS18P8A	18 × 72 × 8	20-Pin	18 (10)	72	0	8 I/O	20ns		155mA
PLHS18P8B	18 × 72 × 8	20-Pin	18 (10)	72	0	8 I/O	15ns		155mA
PLHS16L8A	16 × 64 × 8	20-Pin	16 (10)	64	0	2 C, 6 I/O	20ns		155mA
PLHS16L8B	16 × 64 × 8	20-Pin	16 (10)	64	0	2 C, 6 I/O	15ns		155mA
PLUS16XXD**	16 × 64 × 8	20-Pin	Variable	64	0-8	Variable	10ns	56MHz	180mA
PLC16V8Q	16 × 72 × 8	20-Pin	16 (8)	72	8 (0)	8 RI/O	35, 45ns	18, 13MHz	50mA*
PLC16V8H	16 × 72 × 8	20-Pin	16 (8)	72	8 (0)	8 RI/O	35, 45ns	18, 13MHz	90mA*
PLC20V8Q	20 × 72 × 8	24-Pin	20 (12)	72	8 (0)	8 RI/O	35, 45ns	18, 13MHz	50mA*
PLC20V8H	20 × 72 × 8	24-Pin	20 (12)	72	8 (0)	8 RI/O	35, 45ns	18, 13MHz	90mA*
PLUS20XXD**	20 × 64 × 8	24-Pin	Variable	64	0-8	Variable	10ns	56MHz	210mA
<b>PLS</b>									
PLS105	16 × 48 × 8	28-Pin	16 (16)	48	6 (6)	8 R		13.9MHz	180mA
PLS105A	16 × 48 × 8	28-Pin	16 (16)	48	6 (6)	8 R		20MHz	180mA
PLUS405	16 × 64 × 8	28-Pin	16 (16)	64	8 (8)	8 R		33MHz	225mA
PLS155	16 × 45 × 12	20-Pin	16 (4)	45	4 (0)	8 I/O, 4 RI/O	50ns	14.3MHz	190mA
PLS157	16 × 45 × 12	20-Pin	16 (4)	45	6 (0)	6 I/O, 6 RI/O	50ns	14.3MHz	190mA
PLS159A	16 × 45 × 12	20-Pin	16 (4)	45	8 (0)	4 I/O, 8 RI/O	35ns	18MHz	190mA
PLS167	14 × 48 × 6	24-Pin	14 (14)	48	8 (6)	6 R		13.9MHz	180mA
PLS167A	14 × 48 × 6	24-Pin	14 (14)	48	8 (6)	6 R		20MHz	180mA
PLS168	12 × 48 × 8	24-Pin	12 (12)	48	10 (6)	8 R		13.9MHz	180mA
PLS168A	12 × 48 × 8	24-Pin	12 (12)	48	10 (6)	8 R		20MHz	180mA
PLS179	20 × 45 × 12	24-Pin	20 (8)	45	8 (0)	4 I/O and 8 RI/O	35ns	18MHz	210mA
<b>PML</b>									
PLHS501	32 × 116 × 24	52-Pin	32 (24)	72	0	16 C and 8 I/O	22ns		295mA
PLHS502	32 × 144 × 24	68-Pin	32 (24)	64	16 (0)	16 C or R, 8 I/O or RI/O	20ns	50MHz	370mA

**OUTPUTS:**

C = Combinatorial output

R = Registered output

I/O = Combinatorial I/O

R I/O = Registered I/O

\* Measured at 15MHz (TTL input level)

\*\* Under development

**NOTES:**F<sub>MAX</sub> = 1/(T<sub>IS</sub> + T<sub>CKO</sub>) worst case

® PAL is a trademark of Monolithic Memories Inc., a wholly owned subsidiary of Advanced Micro Devices, Inc.

PGA = Programmable Gate Array

PAD = Programmable Address Decoder

PLA = Programmable Logic Array

PAL<sup>®</sup>-Type = Programmable Array Logic (Fixed OR Array)-Type

PLS = Programmable Logic Sequencer

PML = Programmable Macro Logic

**Signetics**

**Programmer  
Reference  
Guides**

**Application Specific Products**

DEVICE PROGRAMMER REFERENCE GUIDE

DATA I/O CORPORATION  
 10525 WILLOWS RD. N.E.  
 REDMOND, WA 98073-9746  
 (800) 247-5700

PART NUMBER	DEVICE CODES <sup>2</sup>		MODEL 29B			UNISITE 40			MODEL 60		
	FAMILY CODES	PIN CODES	SYSTEM REVISION	ADAPTOR REVISION		SYSTEM REVISION	ADAPTOR REVISION		SYSTEM REVISION	ADAPTOR REVISION	
				DIP	PLCC		DIP	PLCC		DIP	PLCC
<b>PAL-TYPE DEVICES</b>											
PLC16V8	86	3B	303A-V04	303A-011A; V05	303A-011B; V03	V2.1	SITE 40; 1.0	CHIPSITE; 1.0	TBA	TBA	TBA
PLC20V8	86	4E	303A-V04	303A-011A; V06	303A-011B; V03	V2.1	SITE 40; 1.0	CHIPSITE; 1.0	TBA	TBA	TBA
PLHS16L8A/B	1A	17	303A-V04	303A-012; V02	---	V2.1	SITE 40; 1.0	CHIPSITE; 1.0	---	---	---
PLHS18P8A/B	1A	33	303A-V04	303A-012; V01	---	V2.1	SITE 40; 1.0	CHIPSITE; 1.0	---	---	---
<b>PLA DEVICES</b>											
PLS100/101	96	01/61	303A-V04	303A-001; V01, V05	---	V1.5	SITE 40; 1.0	CHIPSITE; 1.0	60A/H; V01	360A003	TBA
PLS103	96	02/62	303A-V04	303A-001; V01, V05	---	V1.5	SITE 40; 1.0	CHIPSITE; 1.0	60A/H; V01	360A003	TBA
PLS151	96	64	303A-V04	303A-011A; V02 303A-001; V06	303A-011B; V02	V1.5	SITE 40; 1.0	CHIPSITE; 1.0	---	---	---
PLC153	86	65	303A-V04	303A-011A; V05	303A-011B; V03	V2.1	SITE 40; 1.0	CHIPSITE; 1.0	TBA	TBA	TBA
PLS153/153A	96	65	303A-V04	303A-011A; V02 303A-001; V05	303A-011B; V02	V1.5	SITE 40; 1.0	CHIPSITE; 1.0	60A/H; V01	360A002	TBA
PLHS153	1A	65	303A-V04	303A-012; V02	---	V2.1	SITE 40; 1.0	CHIPSITE; 1.0	---	---	---
PLUS153B/D	1B	65	303A-V04	303A-011A; V07	303A-011B; V03	V2.1	SITE 40; 1.0	CHIPSITE; 1.0	TBA	TBA	TBA
PLS161	96	69	303A-V04	303A-001; V05 303A-011A; V02	NOT AVAILABLE IN PLCC	V1.5	SITE 40; 1.0	NOT AVAILABLE IN PLCC	60A/H; V01	360A002	NOT AVAILABLE IN PLCC
PLS162	96	73	---	---	"	V1.5	SITE 40; 1.0	"	60A/H; V05	306A004	"
PLS163	96	75	---	---	"	V1.5	SITE 40; 1.0	"	60A/H; V05	360A004	"
PLS173 <sup>1</sup>	96	76	303A-V04	303A-011A; V02	303A-011B; V02	V1.7	SITE 40; 1.0	CHIPSITE; 1.0	60A/H; V08	360A002	TBA
PLUS173B/D	1B	76	303A-V04	303A-011A; V07	303A-011B; V03	V2.1	SITE 40; 1.0	"	TBA	TBA	TBA
PLC473	86	78	303A-V04	303A-011A; V02	TBA	V2.1	SITE 40; 1.0	"	TBA	TBA	TBA
PLHS473	1A	78	303A-V04	303A-012; V01	---	V2.1	SITE 40; 1.0	"	---	---	---



PART NUMBER	DEVICE CODES <sup>2</sup>		MODEL 29B			UNISITE 40			MODEL 60		
	FAMILY CODES	PIN CODES	SYSTEM REVISION	ADAPTOR REVISION		SYSTEM REVISION	ADAPTOR REVISION		SYSTEM REVISION	ADAPTOR REVISION	
				DIP	PLCC		DIP	PLCC		DIP	PLCC
<b>PLS DEVICES</b>											
PLS105/105A	96	03/63	303A; V04	303A-011A; V02 303A-001; V01, 05	303A-011B; V02	V1.5	SITE 40; 1.0	CHIPSITE; 1.0	60A/H; V01	360A003	TBA
PLS155	96	67	303A; V04	303A-011A; V02 303A-001; V05	303A-011B; V02	V1.5	SITE 40; 1.0	CHIPSITE; 1.0	60A/H; V01	360A002	TBA
PLS157	96	68	303A; V04	303A-001; V05 303A-011A; V02	303A-011B; V02	V1.5	SITE 40; 1.0	CHIPSITE; 1.0	60A/H; V01	360A002	TBA
PLS159A	64	66	303A; V04	303A-011A; V02	303A-011B; V02	V1.5	SITE 40; 1.0	CHIPSITE; 1.0	TBA	TBA	TBA
PLS167/167A	96	60	303A; V04	303A-011A; V02	303A-011B; V02	V1.5	SITE 40; 1.0	CHIPSITE; 1.0	60A/H; V05	360A002	TBA
PLS168/168A <sup>1</sup>	96	74	303A; V04	303A-011A; V02	303A-011B; V02	V1.5	SITE 40; 1.0	CHIPSITE; 1.0	60A/H; V05	360A002	TBA
PLS179	96	77	303A; V04	303A-011A; V02	303A-011B; V02	V1.7	SITE 40; 1.0	CHIPSITE; 1.0	TBA	TBA	TBA
PLUS405	TBA	TBA	303A; V04	303A-011A; V07	303A-011B; V03	TBA	TBA	TBA	TBA	TBA	TBA
<b>PML DEVICES</b>											
PLHS501	010	707	---	---	---	V1.7	---	CHIPSITE; 1.0	---	---	---
PLHS502	TBA	TBA	---	---	---	TBA	---	---	---	---	---

The software and hardware revisions listed are the earliest revisions that support these products. Later revisions can also be assumed to support these products.

**NOTES:**

- Also supported on 303A-001; V06.
- For Unisite model users only;
  - \*Family codes listed above must be preceeded with a "0" when programming PLCC packages.
  - \*Pin codes listed above must be preceeded with a "7" when programming PLCC packages.
- " --- " indicates no support planned.

## DEVICE PROGRAMMER REFERENCE GUIDE

STAG MICRO SYSTEMS, INC.

WESTERN AREA: 1600 WYATT DRIVE, SUITE 3, SANTA CLARA, CA. 95054 (408) 988-1118

EASTERN AREA: 3 NORTHERN BLVD., SUITE B4, AMHERST, N.H. 03031 (603) 673-4380

PART NUMBER	DEVICE CODES		MODEL ZL30	MODEL ZL30A		PPZ: ZM2200	
	FAMILY CODES	PIN CODES	(DIP ONLY)	DIP	PLCC	DIP	PLCC
<b>PAL-TYPE DEVICES</b>							
PLC16V8	12	154	30A27	30A27	30A001	30	**
PLC20V8	12	155	30A28	30A28	30A001	TBA	**
PLHS16L8A/B	10	029	NA	30A29 <sup>1</sup>	30A101	TBA	**
PLHS18P8A/B	10	10	NA	30A23 <sup>1</sup>	30A101	29	**
<b>PLA DEVICES</b>							
PLS100/101	13	00	30A01	30A01	30A001	17	**
PLS103	13	01	NA	30A01 <sup>2</sup>	30A001	TBA	**
PLS151	14	04	30A01	30A01	30A001	26	**
PLC153	12	05	30A27	30A27	30A001	34	**
PLS153/153A	14	05	30A01	30A01	30A001	17	**
PLUS153B/D	11	05	30A27	30A27	30A001	34	**
PLS161	15	90	NA	30A01 <sup>2</sup>	NOT AVAILABLE	24	NOT AVAILABLE
PLS162	15	94	NA	30A01 <sup>2</sup>	IN PLCC	28 <sup>3</sup>	IN PLCC
PLS163	15	95	NA	30A01 <sup>2</sup>	"	26 <sup>4</sup>	"
PLS173	15	96	30A01	30A01	30A001	23	**
PLUS173B/D	11	96	30A27	30A27	30A001	TBA	**
PLC473	12	132	30A24	30A24	30A001	32	**
PLHS473	10	132	NA	30A27 <sup>1</sup>	30A101	30	**
<b>PLS DEVICES</b>							
PLS105/105A	13	02	30A01	30A01	30A001	17	**
PLS155	14	06	30A01	30A01	30A001	17	**
PLS157	14	07	30A01	30A01	30A001	17	**
PLS159A	13	08	30A25	30A25	30A001	27	**
PLS167/167A	15	91	30A01	30A01	30A001	TBA	**
PLS168/168A	15	97	30A01	30A01	30A001	23	**
PLS179	15	130	30A27	30A27	30A001	24	**
<b>PML DEVICES</b>							
PLHS501	10	133	NA	NA	30A22 <sup>1</sup>	NA	NA
PLHS502	TBA	TBA	NA	NA	TBA	NA	NA

The software and hardware revisions listed are the earliest revisions that support these products. Lates revisions can also be assumed to support these products.

**NOTES:**

1. Requires 30A101 Adaptor; includes PLCC support.
  2. Requires 30A100 Adaptor.
  3. Requires 30-1594 Adaptor.
  4. Requires 30-1595 Adaptor.
- \*\* Socket Adaptors required.

## Application Specific Products

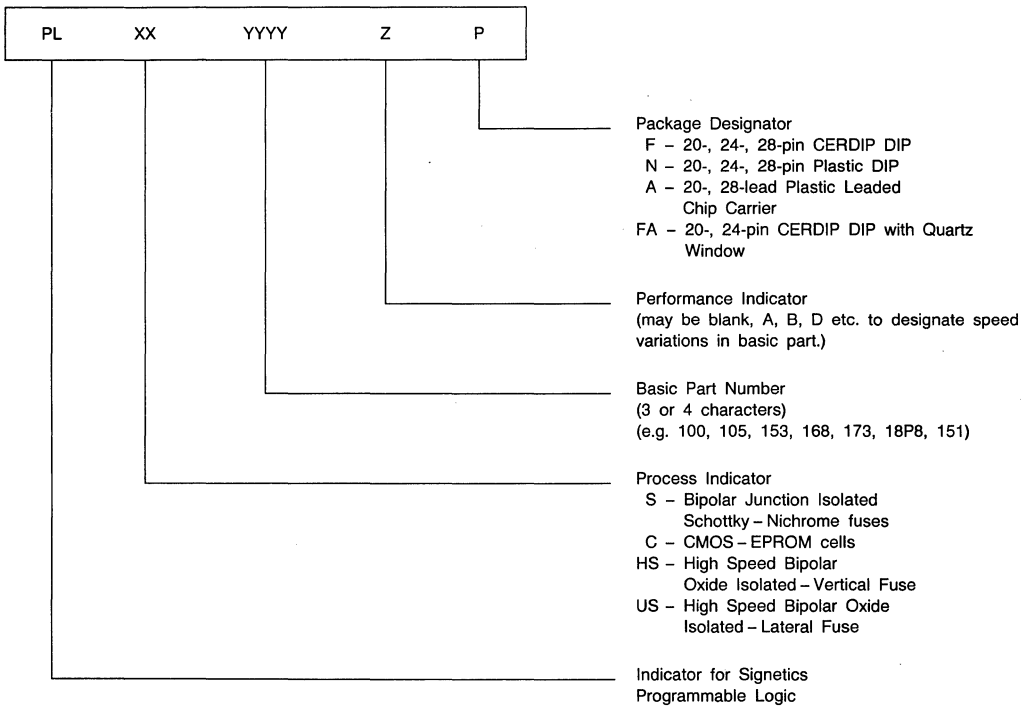
Signetics Programmable Logic Devices may be ordered by contacting either the local Signetics sales office, Signetics representatives or authorized distributors. A complete listing is located in the back of this manual.

Table 1 provides part number definition for Signetics PLD's. The Signetics part number system allows complete ordering information to be specified in the part number. The part number and product

description is located on each data sheet.

Military versions of these commercial products may be ordered. Please refer to the military products data manual for complete ordering information.

## New Signetics PLD Part Numbering System



### INDEX

What is Signetics Programmable Logic .....	2-3
Quality and Reliability .....	2-28



## Application Specific Products

### WHAT IS PROGRAMMABLE LOGIC

In 1975, Signetics Corporation developed a new product family by combining its expertise in semi-custom gate array products and fuse-link Programmable Read Only Memories (PROMs). Out of this marriage came Signetics Programmable Logic Family. The PLS100 Field-Programmable Logic Array (FPLA) was the first member of this family. The FPLA was an important industry first in two ways. First, the AND/OR/INVERT architecture allowed the custom implementations of Sum of Product logic equations. Second, the three-level fusing allows complete flexibility in the use of this device family. All logic interconnections from input to output are programmable.

Development of this family did not stop with the PLS100. In 1977, the PLS103 Field-Programmable Gate Array (FPGA) and the PLS107 Field-Programmable ROM Patch (FPRP) were introduced.

The PLS105 Field-Programmable Logic Sequencer (FPLS) was announced in 1979. This device represents a significant step forward for PLD. The FPLS is a fully-implemented Mealy State Machine on a chip. Incorporated into its architecture are 48 P-terms, an 8-bit Output Register, and a 6-bit internal State Register. Reference Figure 1.

The FPLS can synchronously perform sequential routines at 20MHz. All of these products are now known as the Signetics PLD Series 28 Programmable Logic Family.

Signetics next innovation in this area was the Series 20 Programmable Logic Family. All members of this family are assembled in 20-pin packages. While reducing the number of pins in this family, Signetics has utilized controlled I/O in order to maintain the utility of the Series 20. Appropriate control terms have been included to allow active control of pin direction. Reference Figure 2.

The latest addition to the Signetics Programmable Logic families is the Series 24 devices. The PLS161 FPLA and the PLS167 FPLS are 24-pin devices comparable to the 28-pin PLS100 and PLS105 respectively. These devices have been followed by the PLS162/PLS163 Field-Programmable Address Decoder and the PLS168 FPLS.

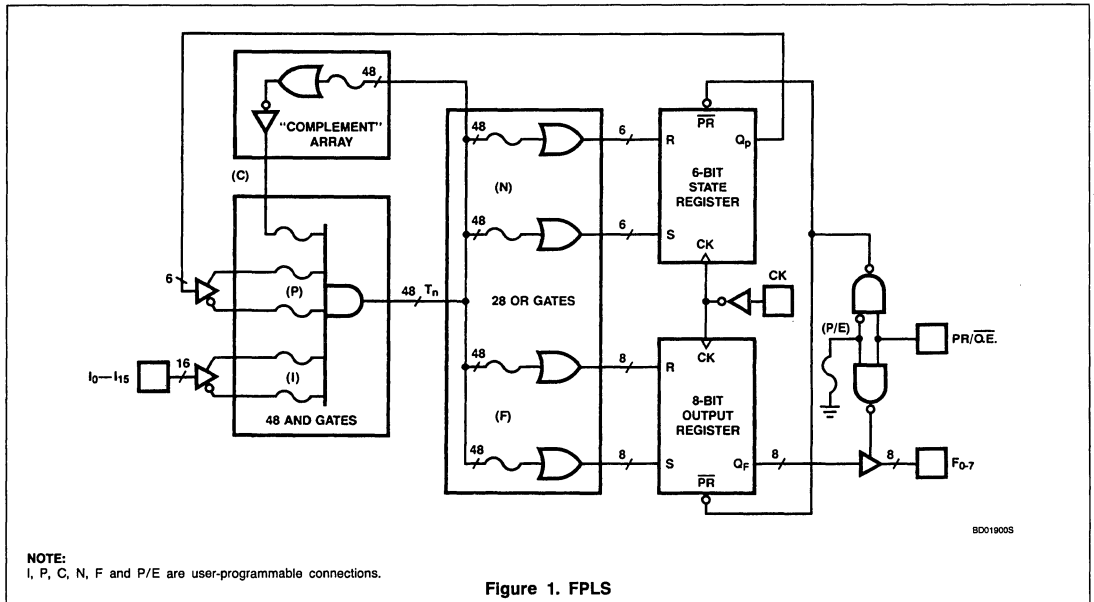
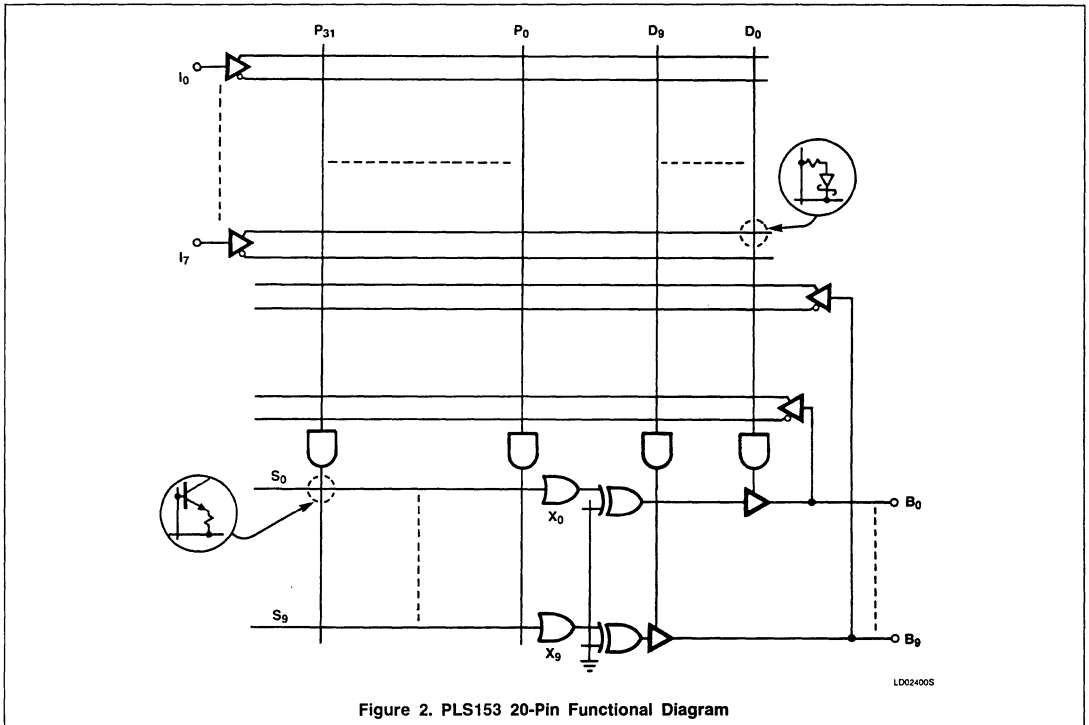


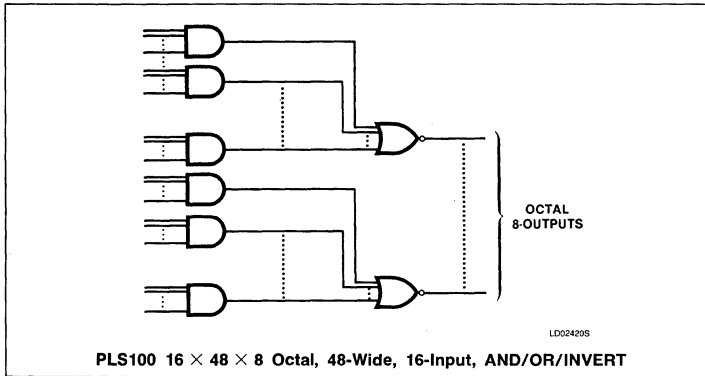
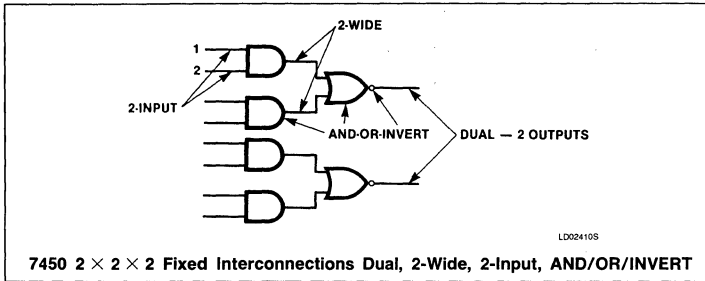
Figure 1. FPLS

Table 1. PLD Product Family

PART NUMBER	TYPE	CONFIGURATION
<b>20-PIN</b>		
PLS151	PGA	18-Input/12-Output
PLS153/153A/PLHS153	PLA	18-Input/10-Output – 42-Term
PLUS153B/153D/PLC153	PLA	18 input/10-Output – 42-Term
PLS155-159	PLS	16-Input/12-Output – 45-Term
PLS155	PLS	4 Registered Outputs
PLS157	PLS	6 Registered Outputs
PLS159	PLS	8 Registered Outputs
PLHS18P8A/B	PAL-Type	18-Input/10-Output – 72-Term
PLHS16L8A/B/D	PAL-Type	16-Input/8-Output – 64-Term
PLC16V8 Series	PAL-Type	18-Input/8-Output – 72-Term
<b>24-PIN</b>		
PLS161	PLA	12-Input/8-Output – 48-Term
PLS162	PGA	16-Input/5-Output
PLS163	PGA	12-Input/9-Output
PLS167/A	PLS	14-Input/6-Output – 48-Term 8-Bit State Registers 6-Output Registers
PLS168/A	PLS	12-Input/8-Output – 48-Term 10-Bit State Registers 8-Output Registers
PLS173/PLUS173B/D	PLA	22-Input/10-Output – 42-Term
PLS179	PLS	16-Input/12-Output – 42-Term 8-Bit State and Output Registers
PLHS473/PLC473	PLA	20-Inputs/11-Output – 24-Term
PLC20V8 Series	PAL-Type	22-Input/8-Output – 72-Term
<b>28-PIN</b>		
PLS100/101	PLA	16-Inputs/8-Output – 48-Term
PLS103	PGA	16-Inputs/9-Output
PLS105/105A/PLC105	PLS	16-Inputs/8-Output – 48-Term 6-Bit State Register 8-Output Registers
PLUS405	PLS	16-Inputs/8-Outputs – 64-Terms 8-Bit State and Output Registers
<b>52-, 68-PIN</b>		
PLHS501	PML	32-Input/24-Output – 116-Term
PLHS502	PML	32-Input/24-Output – 144-Term







**PRODUCT DESCRIPTION**

While all PLD devices are architecturally similar, the Field-Programmable Logic Array is most representative of the concepts involved. The FPLA is an AND/OR/INVERT device, with all internal interconnections programmable via fuse links. If we compare the PLS100 FPLS to the familiar 7450 AOI gate, the similarity of function becomes apparent.

**Package-Gate Replacement Potential**

All Signetics PLD devices are capable of replacing multiple discrete logic devices. The number of packages is dependent on the application and the device used.

If all product terms and inputs on the PLS100 are utilized, a total of 272 gates and 140 I.C.s can theoretically be replaced. (See Table 2.) Since the PLS100 is made up of logic structures which are not available as commercial logic devices, such as 32 input AND gates and 48 input OR gates, these numbers are based on breakdowns of these high complexity logic structures into structures which are available as discrete logic.

The typical application does not fully utilize the FPLA, however. We can assume that the typical application is as defined in Table 3.

The replacement of 15-20 I.C.s with one PLS100 is not unusual.

**Table 2. Gate Replacement (All Terms Used)**

	Gates	I.C.s
Each P-Term = 2 8-Input AND Gates & 1 2-Input AND Gate =	144	108
OR Matrix = 16 4-Input OR Gates =	128	32
	272	140

**Table 3. Typical Application**

4 Variables/P-Term	40 Gates
4 P-Terms/Output	15-20 I.C.s

**PLD ECONOMICS**

The reason any product line exists is because it solves a problem in a cost-effective manner.

PLD is no different in this respect. Let's assume that one PLS100 is replacing only 10 TTL logic packages.

If we assume that the average selling price of an SSI level device is \$0.25, then we have a basis for comparison.

10 I.C.s @ 0.35 = \$3.50  
1 PLS100 FPLA = \$7.00

Considering piece-part cost alone does not fare well for the PLS100 FPLA. But, part cost is one of the smaller costs in systems manufacturing. Let's next consider PC board costs.

**PC BOARD**

The purchase price of a PCB is calculated on a per square inch basis. Typical costs at the 5K level are \$0.23/in<sup>2</sup>, the cost for LS is 1.2in<sup>2</sup> = \$0.23/in<sup>2</sup> = \$0.28. For a 28-pin FPLA device, the packing density is

1-PLS100 per 2.5in<sup>2</sup>, giving a cost of 2.5in<sup>2</sup> × \$0.23/in<sup>2</sup> = \$0.58.

**PCB FABRICATION**

Now let's consider the cost of building the board. The primary cost for PCB fabrication is parts preparation and stuffing.

Estimates by PCB manufacturers indicate a nominal cost of \$0.14 per device for LS TTL and \$0.16 for 28-pin FPLA. There is also a basic cost of \$0.02 per in<sup>2</sup> for handling, soldering, and inspecting.

The cost of incoming inspection and inventory/usage must also be considered in any fair comparison.

**INCOMING INSPECTION**

The cost of incoming inspection can be calculated on a per-pin basis. Assuming an equal mix of 14- and 16-pin SSI parts and a testing cost of \$0.01 per pin, the LS TTL cost is \$0.15 per I.C. The corresponding cost for

the PLS100 would be \$0.01 × 28 or \$0.28 total.

**COMPONENT INVENTORY/USAGE**

The inventory cost for LS TTL parts is dominated by inventory maintenance, while the LSI type parts, the piece price dominates. Assuming a 2% usage rate due to parts breakage, burnout, etc., in the manufacturing process, the parts cost for LS TTL is 2% × \$0.25 = \$0.005. Adding \$0.02 per device for inventory maintenance, the total LS cost \$0.03. For FPLA, 2% = \$7.00 ± \$0.02 = \$0.16.

Consideration must also be given to testing the completed PCB and Rework costs.

**PCB TESTING**

Testing costs are generally figured on a PCB basis and are usually go-no-go tests using a "bed of nails". For this comparison, assume a PCB of 5" × 7". The cost for testing the completed PCB is estimated to be \$3.60 for 20 I.C.s. This breaks down as \$0.18 per LS TTL device or about \$0.45 per FPLA device.

**PCB REWORK**

The main causes of rework are poorly plated holes, solder bridges, and parts inserted incorrectly. The "bed of nails" test can usually detect all of the faults. Rework costs about 50% of test costs. The result is \$1.80 per PCB, or \$0.09 per device for LS TTL and \$0.18 for the 28-pin FPLA.

System manufacturing costs are harder to define. For this comparison we estimated \$0.28 for each LS device and about \$0.65 for the FPLA. These costs include backplane wiring, final system assembly and test costs.

Now using these figures, the comparison in Table 4 can be made.

**Table 4. Cost Analysis**

	LS TTL	FPLA
<b>IC COMPONENTS</b>	.35	7.00
<b>PCB MANUFACTURING</b>		
Incoming Inspection	.15	.28
Component Inventory/Usage	.03	.16
PC Board	.28	.58
Fabrication	.14	.16
Test	.18	.45
Rework	.09	.18
<b>ASSEMBLY LABOR</b>	.28	.65
<b>COST PER COMPONENT</b>	1.50	9.46
<b>NUMBER OF COMPONENTS</b>	<u>× 10</u>	<u>× 1</u>
<b>TOTAL</b>	15.00	9.46
<b>CONCLUSION:</b>		
THE FPLA is a 37% savings over the LS TTL DESIGN.		





**Step 3**

Select which output pins correspond to each output function. In this case  $F_0 = \text{Pin } 18 = X_0$ , and  $F_1 = \text{Pin } 17 = X_1$ .

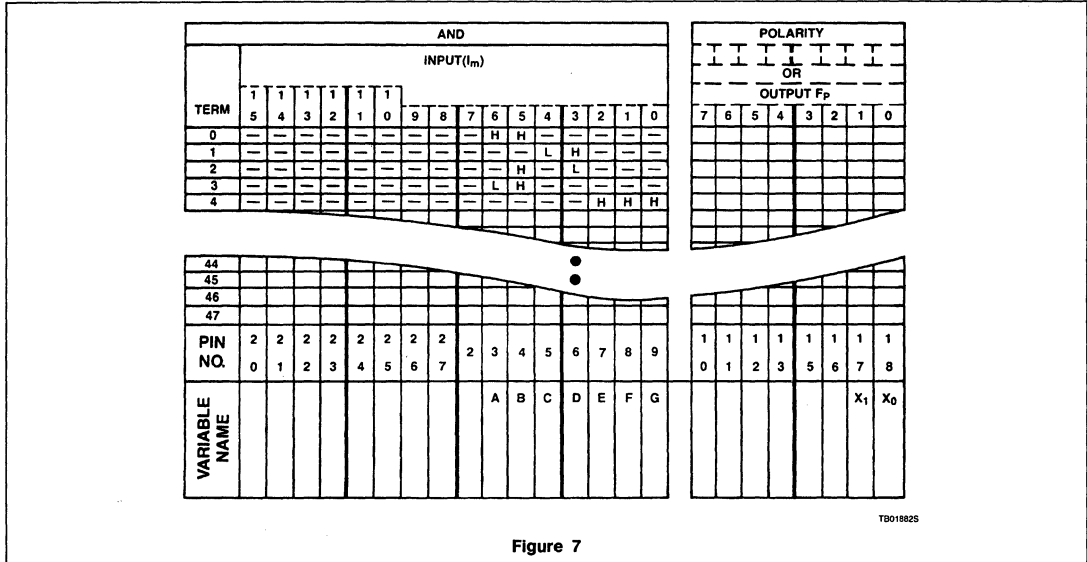


Figure 7

TB01825

**Step 4**

Select the Output Active Level desired for each Output Function. For  $X_0$  the active

level is high for a positive logic expression of this equation. Therefore, it is only necessary to place an (H) in the Active Level box above Output Function 0, ( $F_0$ ). Conversely,  $X_1$  can

be expressed as  $\bar{X}_1$  by placing an (L) in the Active Level box above Output Function 1, ( $F_1$ ).

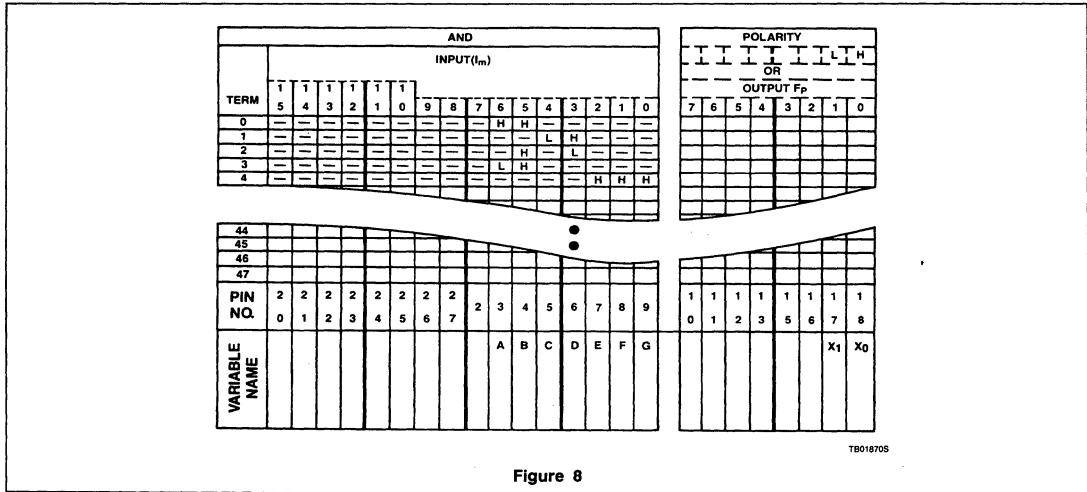


Figure 8

TB018705

**Step 5**

Select the P-Terms you wish to make active for each Output Function. In this case  $X_0 = P_0 + P_1 + P_2$ , so an A has been placed in the intersection box for  $P_0$  and  $X_0$ ,  $P_1$  and  $X_0$  and  $P_2$  and  $X_0$ .

Terms which are not active for a given output are made inactive by placing a (●) in the box under that P-term. Leave all unused P-terms unprogrammed.

Continue this operation until all outputs have been defined in the Program Table.

**Step 6**

Enter the data into a Signetics approved programmer. The input format is identical to the Signetics Program Table. You specify the P-terms, Output Active Level, and which P-terms are active for each output exactly the way it appears on the Program Table.

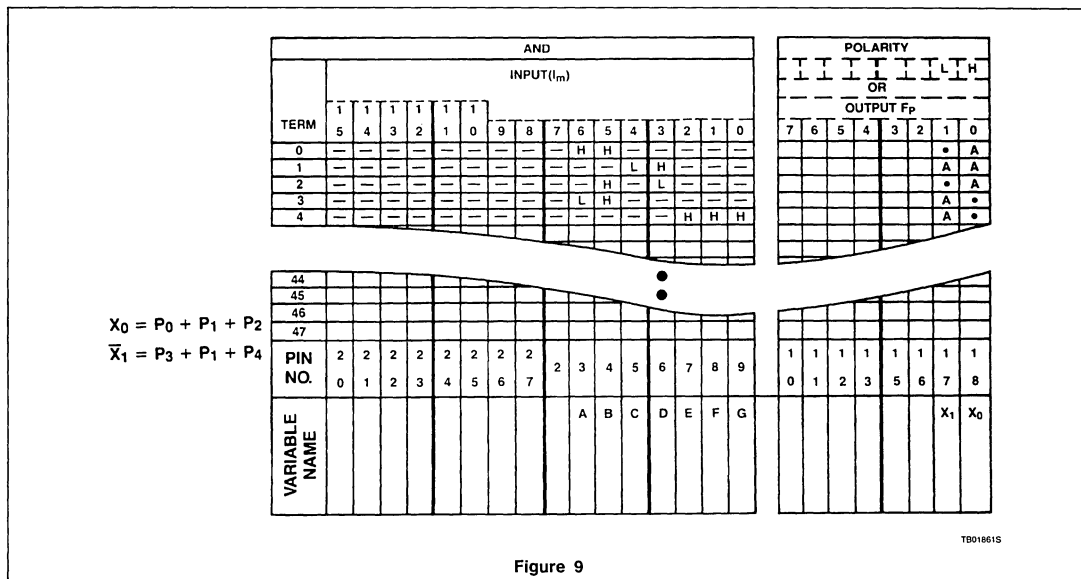


Figure 9

**PLD LOGIC SYNTHESIS**

**20-PIN**

When fewer inputs and outputs are required in a logic design and low cost is most important, the Signetics 20-pin PLD should be

considered first choice. The PLS153 is an FPLA with 8 inputs, 10 I/O pins, and 42 product terms. The user can configure the device by defining the direction of the I/O pins. This is easily accomplished by using the direction control terms  $D_0 - D_9$  to establish

the direction of pins  $B_0 - B_9$ . The D-terms control the Tri-state buffers found on the outputs of the EX-OR gates. Figures 10 and 11 show how the D-term configures each  $B_x$  pin.

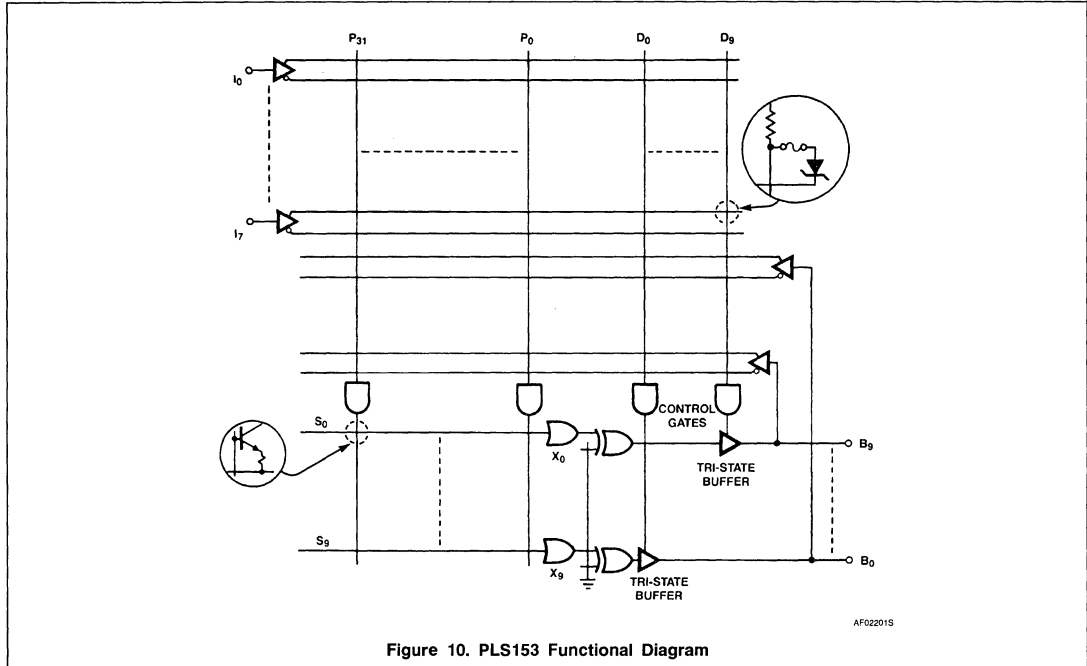


Figure 10. PLS153 Functional Diagram

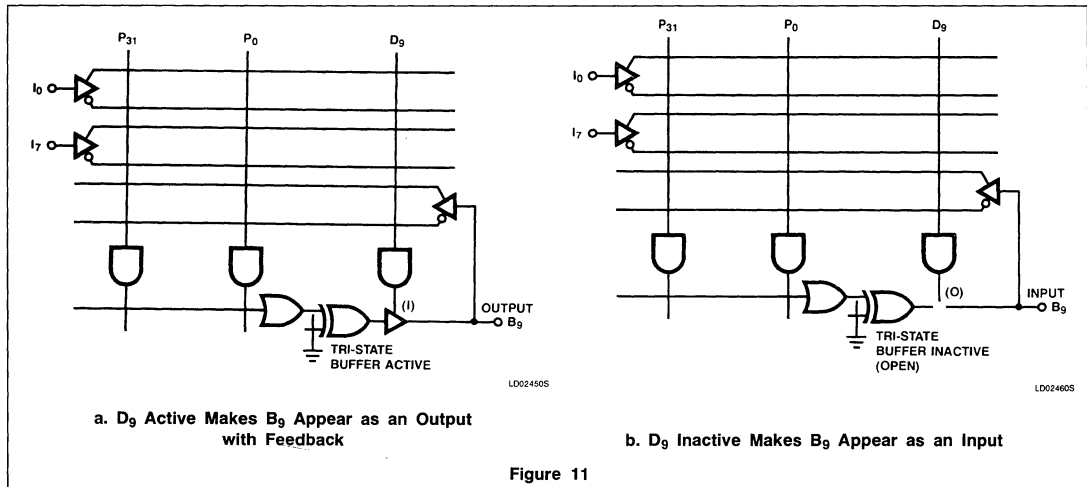
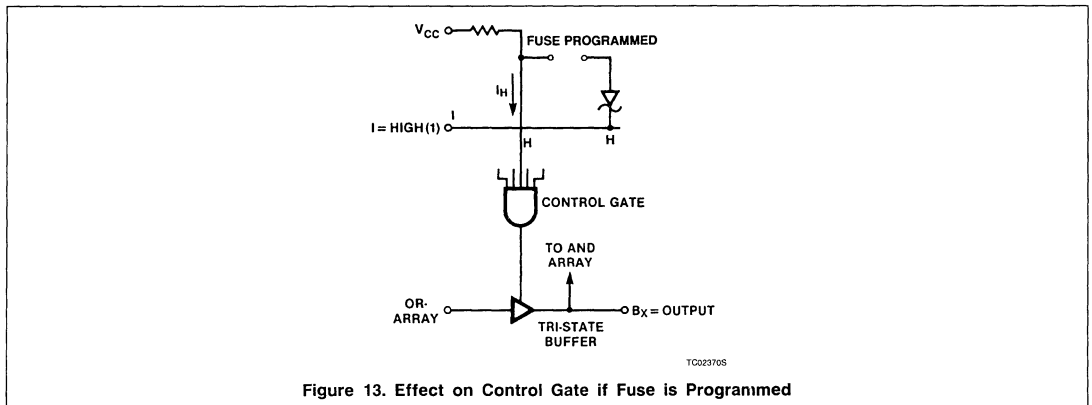
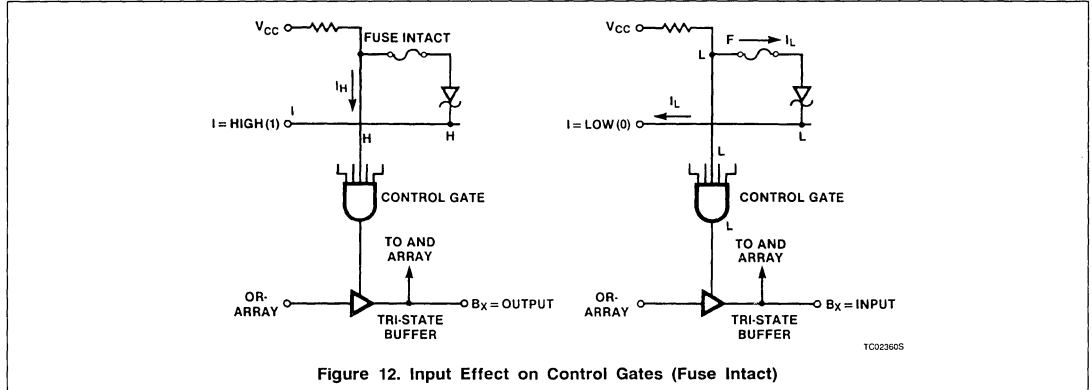


Figure 11

To control each D-term, it is necessary to understand that each control gate is a 36-input AND gate. To make the Tri-state buffer active ( $B_x$  pin an output), the output of the control gate must be at logic HIGH (1). This can be accomplished in one of two ways. A

HIGH can be forced on all control gate input nodes, or fuses can be programmed. When a fuse is programmed, that control gate input node is internally pulled up to HIGH (1). See Figure 12 and Figure 13.

Programming the fuse permanently places a HIGH (1) on the input to the control gate. The input pin no longer has any effect on that state.





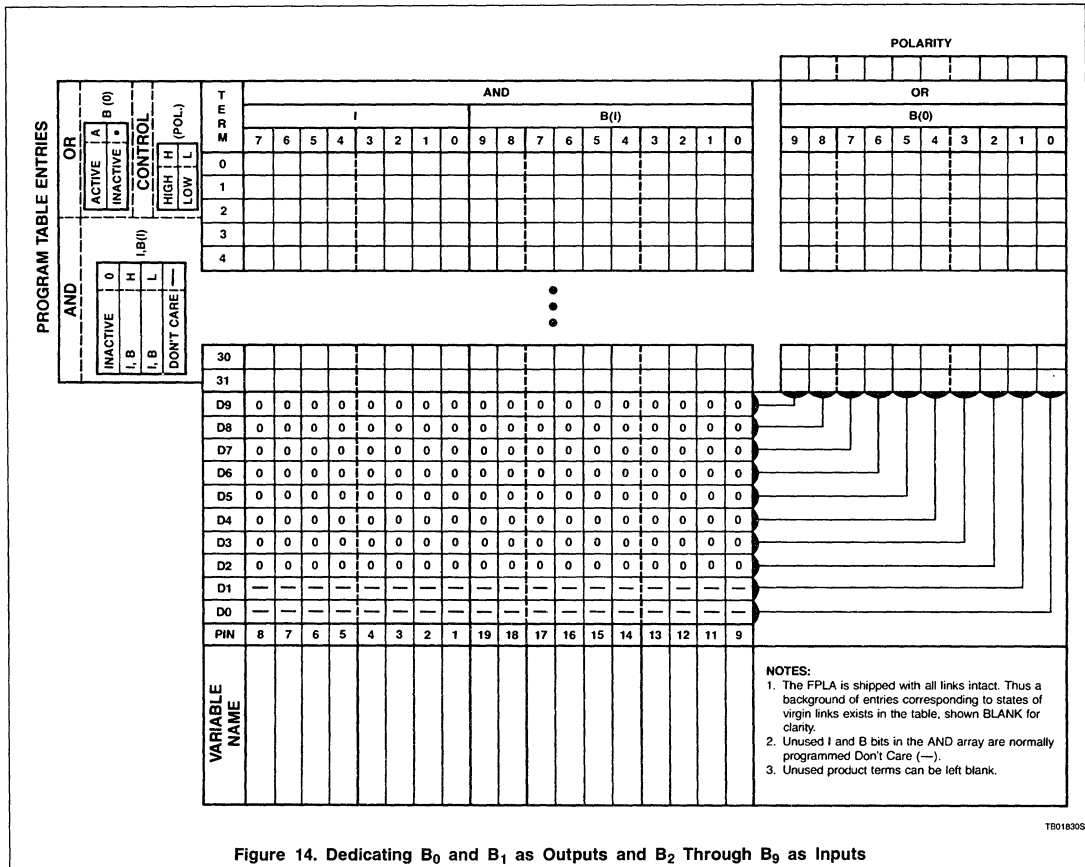
**DEDICATING B<sub>x</sub> PIN DIRECTION**

Since each input to the D-terms is true and complement buffered (see Figure 11), when the device is shipped with all fuses intact, all control gates have half of the 36 input lines at logic low (0). The result of this is all Control Gate outputs are low (0) and the Tri-state buffers are inactive. This results in all B<sub>x</sub> pins being in the input condition. The resultant

device is, therefore, an 18-input, 0-output FPLA. While useful as a bit bucket or Write-Only-Memory (WOM), most applications require at least one output. Clearly, the first task is to determine which of the B<sub>x</sub> pins are to be outputs. The next step is to condition the control gate to make the Tri-state buffer for those gates active. To dedicate B<sub>0</sub> and B<sub>1</sub> as outputs, it is necessary to program all fuses to the inputs to Control Gates D<sub>0</sub> and D<sub>1</sub>. This internally pulls all inputs to those gates to

HIGH (1) permanently. Since all inputs to the Control Gates are HIGH (1), the output is HIGH (1) and the Tri-state buffers for B<sub>0</sub> and B<sub>1</sub> are active. This permanently enables B<sub>0</sub> and B<sub>1</sub> as outputs. Note that even though B<sub>0</sub> and B<sub>1</sub> are outputs, the output data is available to the AND array via the internal feedback (see Figure 11a).

To program this data, the PLS153 Program Table is used as shown in Figure 14.



TB016305

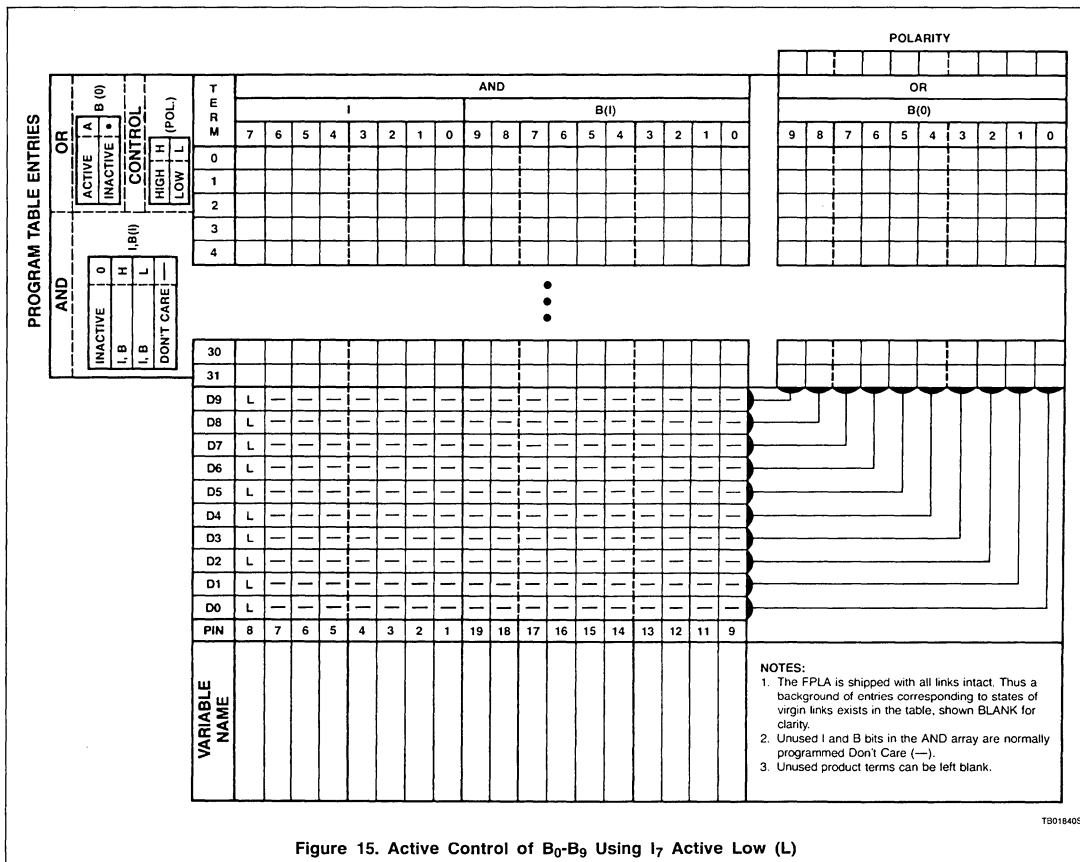
By placing a (—) Don't Care in each input box you are specifying that the True and Complement fuses are programmed on each Control Gate, thus permanently dedicating the B<sub>0</sub> and B<sub>1</sub> pins as outputs. By placing a (0) in all input boxes for B<sub>2</sub>–B<sub>9</sub>, you are specifying that both True and Complement fuses are intact. This causes a low (0) to be forced on half of the Control Gate inputs, guaranteeing the output of the Control Gate will be low (0). When the Control Gate outputs are low (0), the Tri-state buffer is inactive

and the B<sub>2</sub>–B<sub>9</sub> pins are enabled as inputs. All B<sub>x</sub> pin directions can be controlled in this manner.

### ACTIVE DIRECTION CONTROL

Sometimes it is necessary to be able to actively change the direction of the B<sub>x</sub> pins without permanently dedicating them. Some applications which require this include Tri-state bus enable, multi-function decoding, etc. This can easily be done by programming

the Control Gate to respond to one or more input pins. It is only necessary to select which I<sub>x</sub> and B<sub>x</sub> pins will control the pin directions and the active level HIGH (H) or LOW (L) that will be used. The PLS153 Program Table in Figure 15 shows the method of controlling B<sub>0</sub>–B<sub>9</sub> with I<sub>7</sub>. When I<sub>7</sub> is LOW (L), pins B<sub>0</sub>–B<sub>9</sub> are outputs when I<sub>7</sub> is HIGH (H), pins B<sub>0</sub>–B<sub>9</sub> are inputs. Note that by programming all other I<sub>x</sub> and B<sub>x</sub> pins as DON'T CARE (—), they are permanently disconnected from control of B<sub>x</sub> pin direction.



The previous 28-pin logic synthesis example (Page 2-5) could be done on the PLS153 as follows:

$$X_0 = AB + \bar{C}D + B\bar{D}$$

$$\bar{X}_1 = \bar{A}B + \bar{C}D + EFG$$

Note that B<sub>0</sub> was used as a CHANGE input. When B<sub>0</sub> is HIGH (H) the outputs appear on B<sub>8</sub> and B<sub>9</sub>. When B<sub>0</sub> is LOW (L), the outputs appear on B<sub>6</sub> and B<sub>7</sub>. B<sub>1</sub> through B<sub>5</sub> are not used and therefore left unprogrammed.

### THE ROLE OF AMAZE (AUTOMATIC MAP AND ZAP ENTRY) IN LOGIC DEVELOPMENT

AMAZE is a software development package which provides the logic designer with a multi-mode data input capability. This software package, which has been developed for both mainframe and microcomputer environments, allows data entry in the program table format previously described, or on one of two equation formats. Both Boolean Logic Equations and State Variable Equations are supported on AMAZE. In addition to the flexible input formats offered, AMAZE also provides full

device documentation, and a functional simulator. The simulator features manual and automatic modes. In the automatic mode, the software generates a set of input vectors which can be used as functional test vectors. The manual mode is an interactive procedure which allows the designer to input vectors to the simulator. The AMAZE simulator then responds with the appropriate output vector. In both modes, the simulator uses the functional model generated by the user's input data.

For more information on AMAZE refer to Section 8 of the 1987 Signetics Programmable Logic Data Manual.

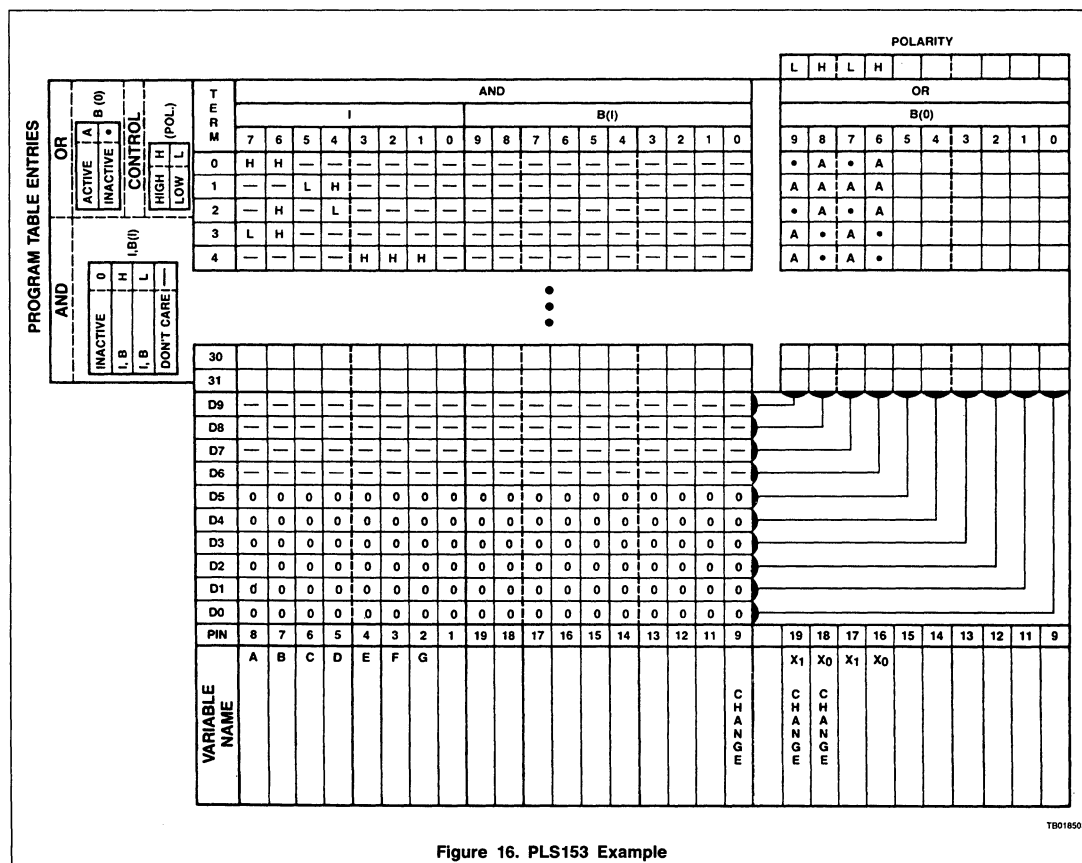


Figure 16. PLS153 Example

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**SEQUENTIAL LOGIC CONSIDERATIONS**

The PLS105 and PLS155 - PLS159 represent significant increases in complexity when compared to the combinatorial logic devices pre-

viously discussed. By combining the AND/OR combinatorial logic with clocked output flip-flops and appropriate feedback, Signetics has created the first family of totally flexible sequential logic machines.

The PLS105 FPLS (Field-Programmable Logic Sequencer) is an example of a high-order machine whose applications are manifold. Application areas for this device include high-speed data controllers, microprocessor and minicomputer bus arbitration, industrial controls, timing generation, multi-function counters and shift registers, and microprocessor-driven microcontrollers. The PLS105 is fully capable of performing fast sequential operations in relatively low-speed processor systems. By placing repetitive sequential operations on the PLS105, processor overhead is reduced. Each PLS105 can be viewed as a high-speed, 48-state subroutine.

The following pages summarize the PLS105 architecture and features.

**FPLS Architecture**

The PLS105 Logic Sequencer is a programmable state machine of the Mealy type, in which the output is a function of the present state and the present input.

With the FPLS a user can program any logic sequence expressed as a series of jumps between stable states, triggered by a valid input condition (I) at clock time (t). All stable states are arbitrarily assigned and stored in the State Register. The logic output of the machine is also programmable, and is stored in the Output Register.

**Clocked Sequence**

A synchronous logic sequence can be represented as a group of circles interconnected with arrows. The circles represent stable states, labeled with an arbitrary numerical code (binary, hex, etc.) corresponding to discrete states of a suitable register. The arrows represent state transitions, labeled with symbols denoting the jump condition and the required change in output. The number of states in the sequence depends on the length and complexity of the desired algorithm.

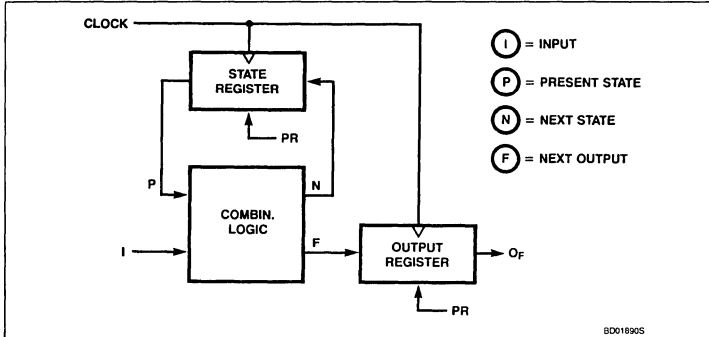


Figure 17. Basic Architecture of PLS105 FPLS. I, P, N, and F are Multi-line Paths Denoting Groups of Binary Variables Programmed by The User.

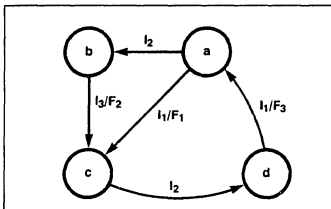


Figure 18. Typical State Diagram. I<sub>1-3</sub> Are Jump Conditions Which Must be Satisfied Before Any Transitions Take Place. F<sub>r</sub> Are Changes in Output Triggered by I<sub>m</sub>, and Stored in The Output Register. State Transitions a → b and c → d Involve No Output Change.

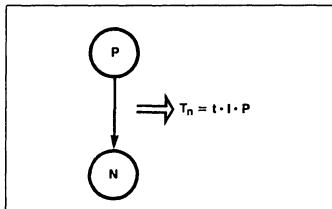


Figure 19. Typical State Transition Between Any Two States of Figure 18. The Arrow Connecting the Two States Gives Rise to a Transition Term T<sub>n</sub>. I is the Jump Condition.

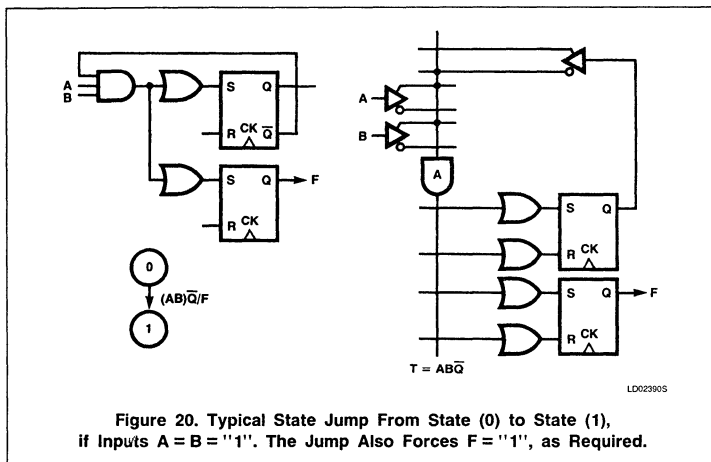


Figure 20. Typical State Jump From State (0) to State (1), if Inputs A = B = "1". The Jump Also Forces F = "1", as Required.

**State Jumps**

The state from which a jump originates is referred to as the Present state (P), and the state to which a jump terminates is defined as the Next state (N). A state jump always causes a change in state, but may or may not cause a change in machine output (F).

State jumps can occur only via "transition terms"  $T_n$ . These are logical AND functions of the clock (t), the Present state (P), and a valid input (I). Since the clock is actually applied to the State Register,  $T_n = I \bullet P$ . When  $T_n$  is "true", a control signal is generated and used at clock time (t) to force the contents of the State Register from (P) to (N), and to change the contents of the Output Register (if necessary). The simple state jump in Figure 20, involving 2 inputs, 1 state bit, and 1 output bit, illustrates the equivalence of discrete and programmable logic implementations.

**FPLS Logic Structure**

The FPLS consists of programmable AND and OR gate arrays which control the Set and Reset inputs of a State Register, as well as monitor its output via an internal feedback path. The arrays also control an independent Output Register, added to store output commands generated during state transitions, and to hold the output constant during state sequences involving no output changes. If desired, any number of bits of the Output Register can be used to extend the width of the State Register, via external feedback.

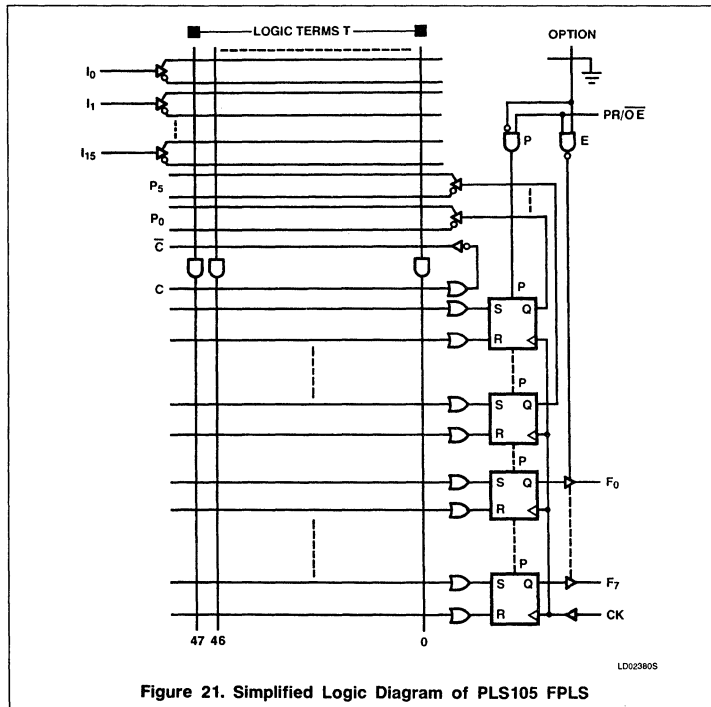


Figure 21. Simplified Logic Diagram of PLS105 FPLS

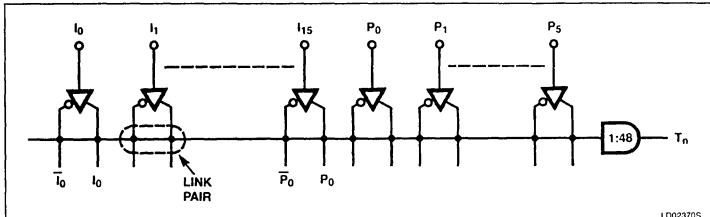


Figure 22. Typical AND Gate Coupled to (I) and (P) Inputs. If at Least One Link Pair Remains Intact,  $T_n$  is Unconditionally Forced Low.

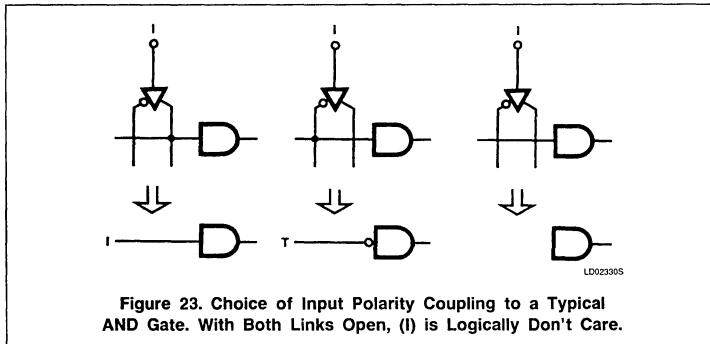


Figure 23. Choice of Input Polarity Coupling to a Typical AND Gate. With Both Links Open, (I) is Logically Don't Care.

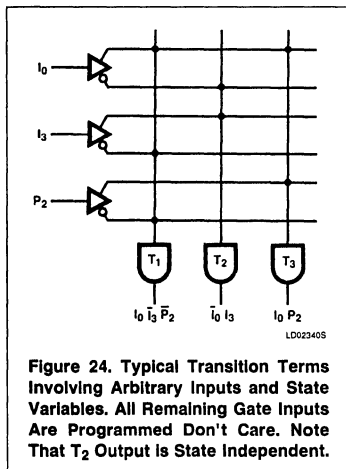


Figure 24. Typical Transition Terms Involving Arbitrary Inputs and State Variables. All Remaining Gate Inputs Are Programmed Don't Care. Note That  $T_2$  Output is State Independent.

**Input Buffers**

16 external inputs ( $I_m$ ) and 6 internal inputs ( $P_s$ ), fed back from the State Register, are combined in the AND array through two sets of True/Complement (T/C) buffers. There are a total of 22 T/C buffers, all connected to multi-input AND gates via fusible links which are initially intact.

Selective fusing of these links allows coupling either True, Complement, or Don't Care values of ( $I_m$ ) and ( $P_s$ ).

**"AND" Array**

State jumps and output changes are triggered at clock time by valid transition terms  $T_n$ . These are logical AND functions of the present state (P) and the present input (I).

The FPLS AND Array contains a total of 48 AND gates. Each gate has 45 inputs — 44 connected to 22 T/C input buffers, and 1 dedicated to the Complement Array. The outputs of all AND gates are propagated through the OR Array, and used at clock time (t) to force the contents of the State Register from (P) to (N). They are also used to control the Output Register, so that the FPLS 8-bit output  $F_r$  is a function of the inputs and present state.

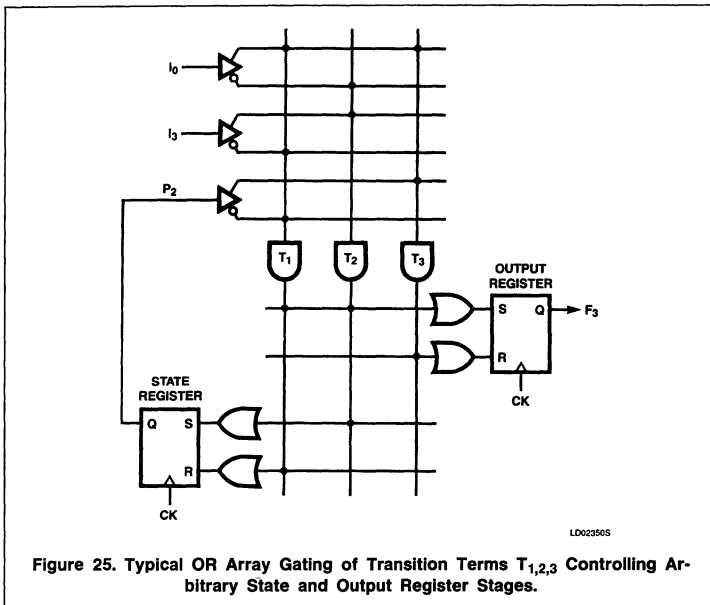


Figure 25. Typical OR Array Gating of Transition Terms  $T_{1,2,3}$  Controlling Arbitrary State and Output Register Stages.

**"OR" Array**

In general, a clocked sequence will consist of several stable states and transitions, as determined by the complexity of the desired algorithm. All state and output changes in the state diagram imply changes in the contents of State and Output Registers.

Thus, each flip-flop in both registers may need to be conditionally set or reset several times with  $T_n$  commands. This is accomplished by selectively ORing through a programmable OR Array all AND gate outputs  $T_n$  necessary to activate the proper flip-flop control inputs.

The FPLS OR Array consists of 14 pairs of OR gates, controlling the S/R inputs of 14 State and Output Register stages, and a single OR gate for the Complement Array. All gates have 48 inputs for connecting to all 48 AND gates.

**Complement Array**

The COMPLEMENT Array provides an asynchronous feedback path from the OR Array back to the AND Array.

This structure enables the FPLS to perform both direct and complement sequential state jumps with a minimum of transition (AND) terms.

Typically direct jumps, such as  $T_1$  and  $T_2$  in Figure 27 require only a single AND gate each.

But a complement jump such as  $T_3$  generally requires many AND gates if implemented as a direct jump. However, by using the Complement Array, the logic requirements for this type of jump can be handled with just one more gate from the AND Array.

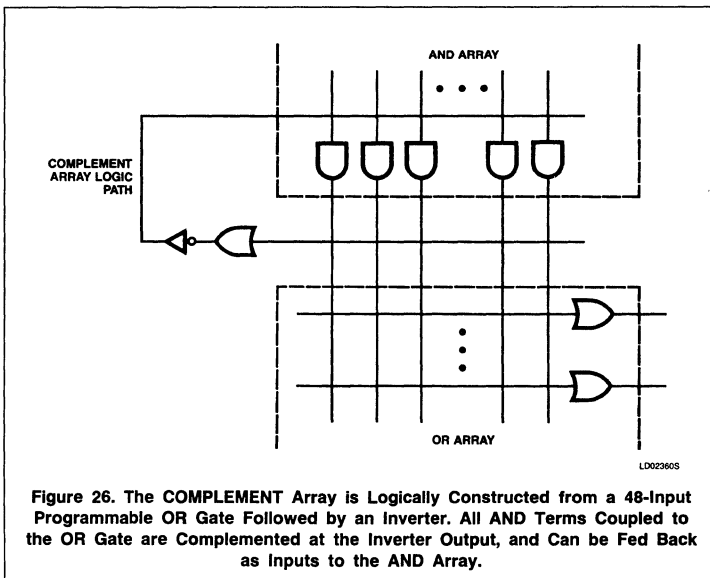
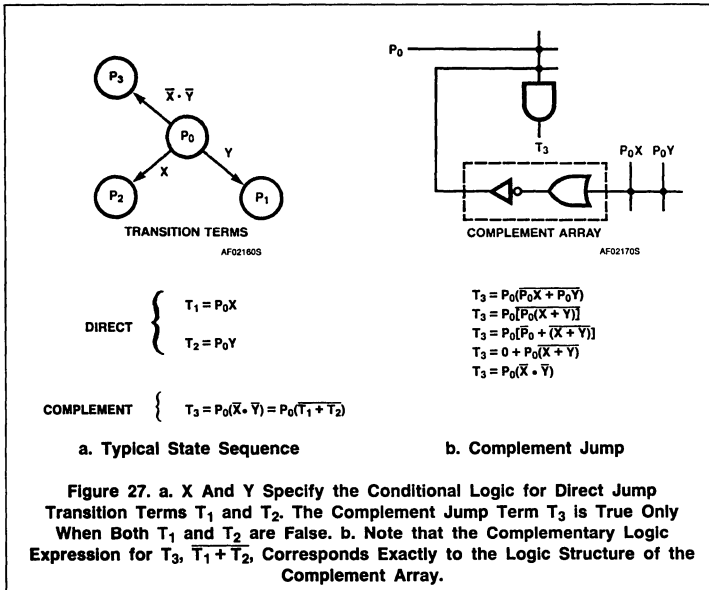
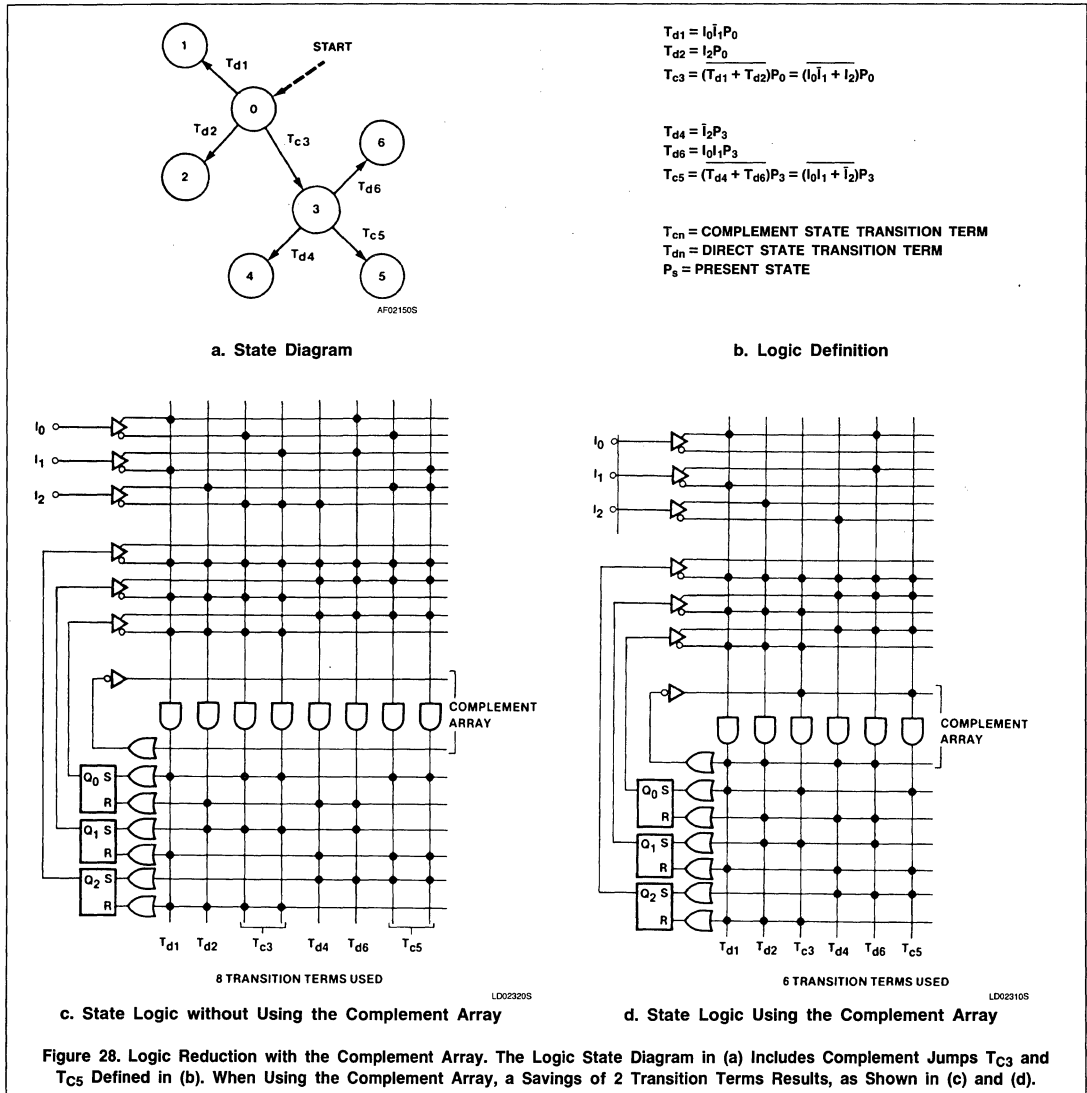


Figure 26. The COMPLEMENT Array is Logically Constructed from a 48-Input Programmable OR Gate Followed by an Inverter. All AND Terms Coupled to the OR Gate are Complemented at the Inverter Output, and Can be Fed Back as Inputs to the AND Array.



As indicated in Figure 28, the single Complement Array gate may be used for many states of the state diagram. This happens because all transition terms linked to the OR gate include the present state as a part of their conditional logic. In any particular state, only those transition terms which are a function of that state are enabled; all other terms coupled to different states are disabled and do not influence the output of the Complement Array. As a general rule of thumb, the Complement Array can be used as many times as there are states.





**Table 5. 20-Pin PLD Sequential Family Summary**

DEVICE	REGISTERED OUTPUTS	OUTPUT TYPE
PLS155	4-Bit Register	T.S.
PLS157	6-Bit Register	T.S.
PLS159	8-Bit Register	T.S.

**PLD-20 SEQUENTIAL DEVICES**

The 20-pin PLD family also includes sequential devices. These devices are all similar in architecture. The major difference consists of the number of outputs which are registered.

**FEATURES**

The PLD-20 sequencers have been designed with a maximum of flexibility in mind. Each element of the architecture contributes to the ease of use the PLD-20 family provides. Each part has the features listed:

- J/K flip-flop Output Register
- Dynamic control of flip-flop type (J/K or D)

- Parallel bus load
- Asynchronous preset and reset capability
- Combinational I/O pins
- Programmable enable pins
- Output feedback to AND Array available

**OUTPUT REGISTER**

The Output Register of the PLD-20 sequential devices are comprised of fully implemented J/K flip-flops. Each flip-flop is positive edge-triggered from a common clock.

In addition, a dynamically controllable "fold-back" buffer between the J and K inputs to the flip-flop allows the designer to change the function of the flip-flop from J/K to D-type under the control of the flip-flop control term (F). A fuse allows the designer to dedicate the flip-flop as a permanent D-type by programming the fuse.

By leaving the fuse intact, the flip-flop control line (F) is maintained as the active mode control. If the output of F is logic Low (0), then the flip-flop is configured as a D-type. If the output of F is a logic High (1), then the flip-flop is configured as a J/K type. Term F is programmed in the same manner as the 32 logic transition terms (T). It is well to note at this time that when the flip-flop is configured as a D-type, the OR-term driving the K input of the flip-flop must not be active.

During all modes of operation, the output register data is fed back to the AND Array. This feedback is used to establish present-state to next-state jumps.

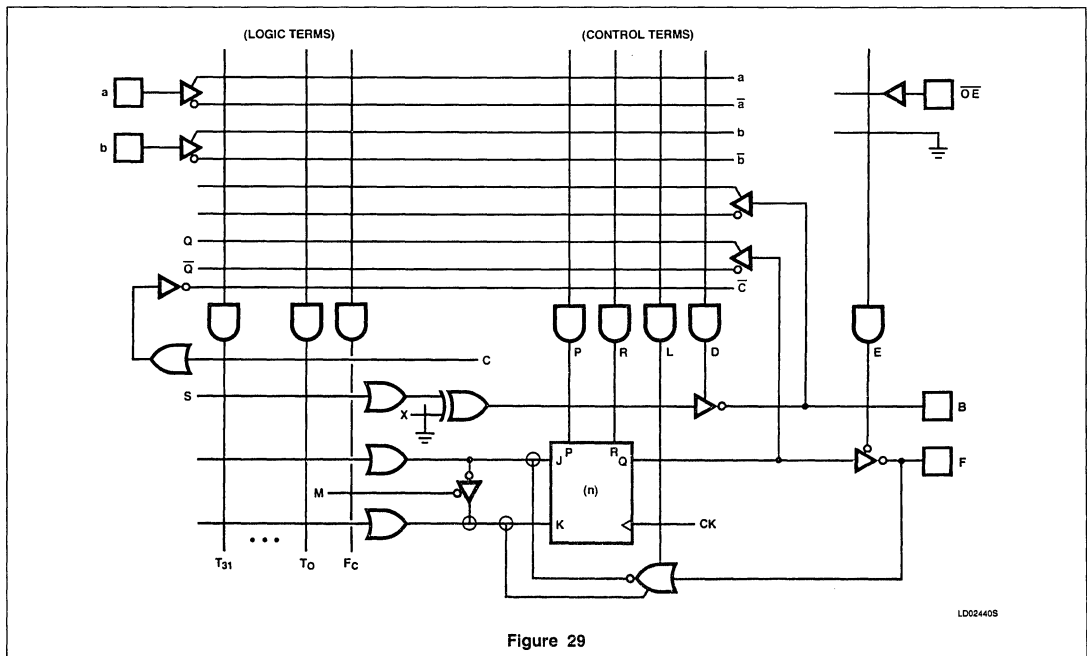


Figure 29

**PARALLEL BUS LOADING**

The Output Register may be loaded from the bus via the load control term (L). This feature

forces the data contained on the  $F_0$  pin into the J/K flip-flop. It operates synchronously with the rising edge of the clock. This feature

can be used to preload a state into the machine, or to latch input data into the AND Array.

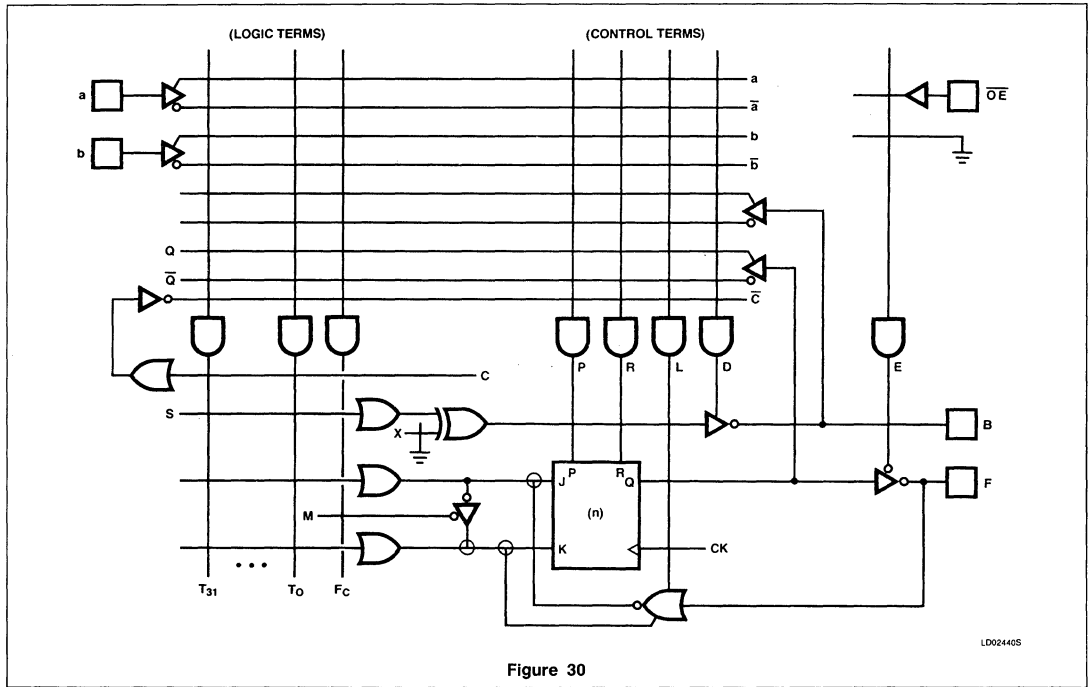


Figure 30

**PRESET AND RESET**

Asynchronous preset and reset capability has been provided on the PLD-20 sequential

devices. This feature is controlled in the AND-Array on the PLS159. However, the preset and reset function on the PLS155 is controlled via the OR Array. The PLS157 preset

and reset controls are split between the two arrays. See the individual data sheets for details.

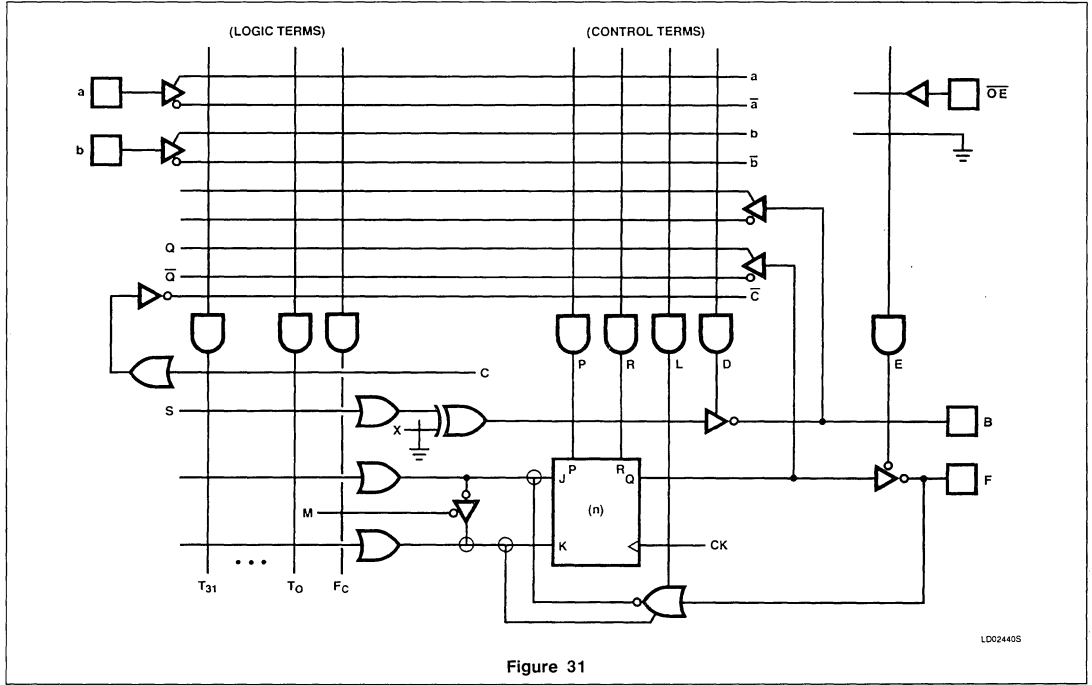


Figure 31

**COMBINATIONAL I/O PINS**

Each PLD-20 sequential device has a number of combinational pins ( $B_n$ ) which can be

programmed and used exactly as the B pins on the PLS153 FPLA. The direction control term (D) establishes the data flow on these

pins. The individual data sheet should be consulted for the quantity and pin number assignment for each device.

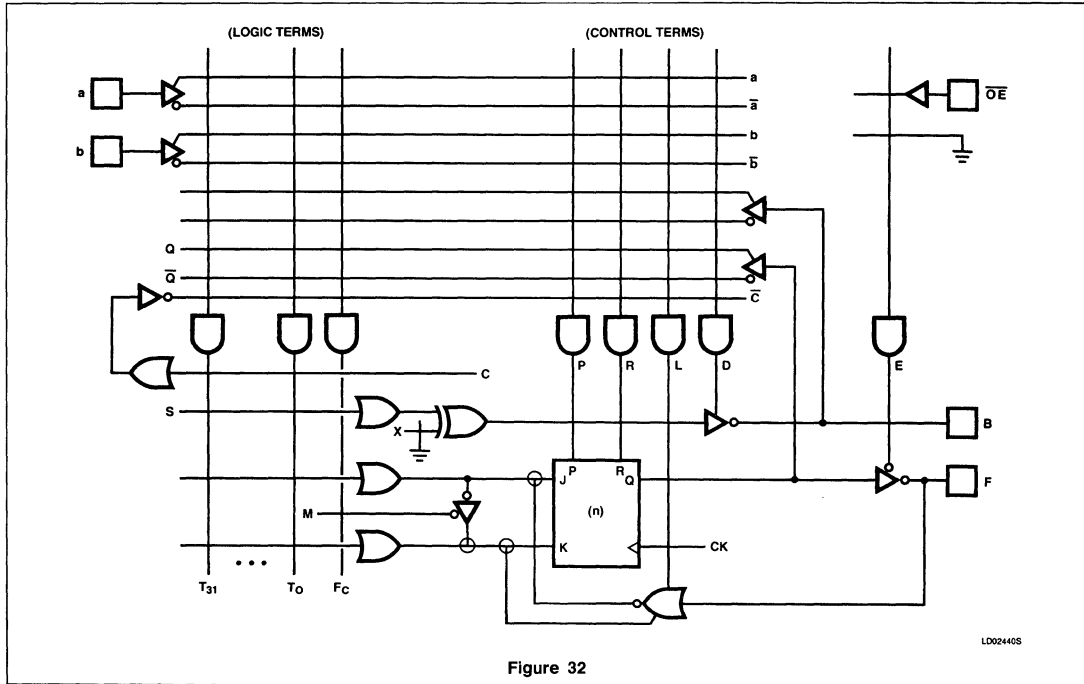


Figure 32

### PLA vs. PAL® ARRAYS

The PLA architecture provides the most efficient means of implementing logic. The 28-pin devices, PLS100/101 and PLS103 are unique in their ability to directly implement logic.

They offer the most useable P-terms, the highest number of inputs and outputs, and the most straightforward programming of any logic device in the industry. The following diagrams illustrate the relative ease of programming the flexible PLA structure against the fixed OR Array of the PAL.

The Signetics approach to programmable logic gives the designer the flexibility he needs where he needs it—in the device itself. The combination of totally flexible architecture, more useable product terms, and ease of logic implementation make Signetics Programmable Logic Family the obvious choice.

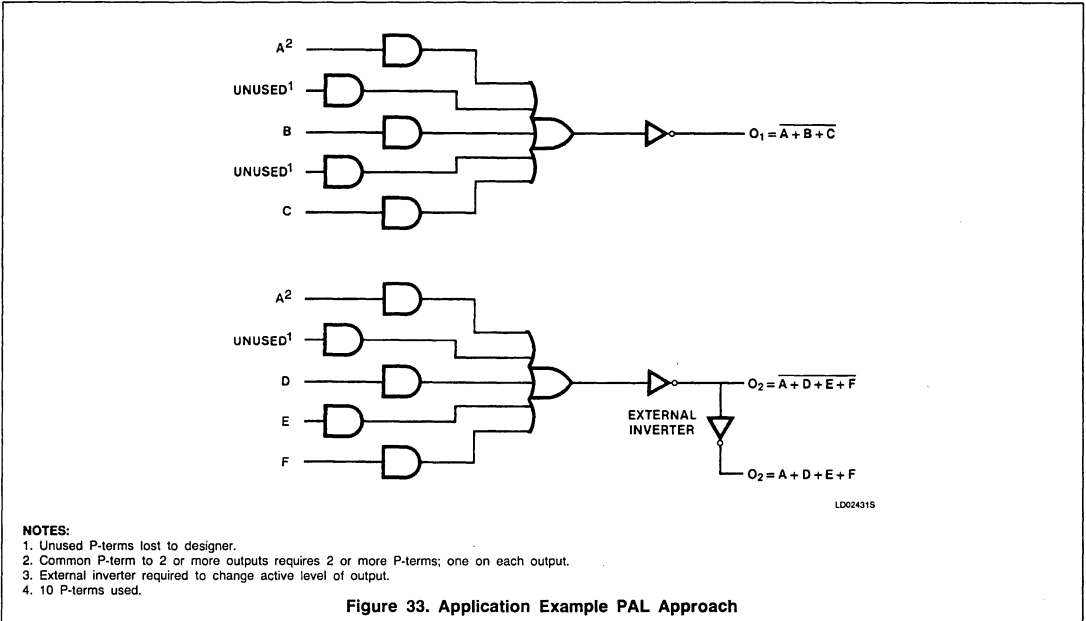


Figure 33. Application Example PAL Approach

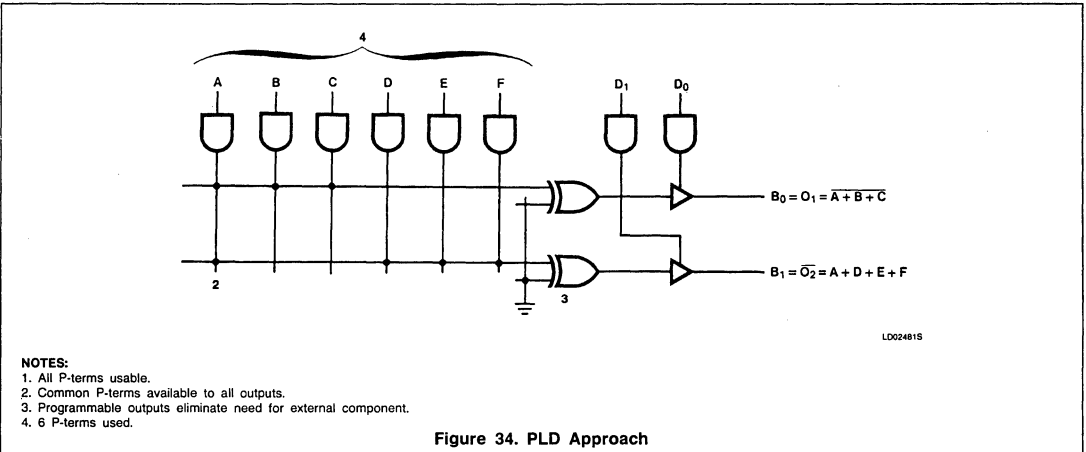


Figure 34. PLD Approach

## Application Specific Products

### SIGNETICS PROGRAMMABLE LOGIC QUALITY

Signetics has put together winning processes for manufacturing Programmable Logic. Our standard is zero defects, and current customer quality statistics demonstrate our commitment to this goal.

The PLD's produced in the Application Specific Products Division must meet rigid criteria as defined by our design rules and as evaluated with a thorough product characterization and quality process. The capabilities of our manufacturing process are measured and the results evaluated and reported through our corporate-wide QA05 data base system. The SURE (Systematic Uniform Reliability Evaluation) program monitors the performance of our product in a variety of accelerated environmental stress conditions. All of these programs and systems are intended to prevent product-related problems and to inform our customers and employees of our progress in achieving zero defects.

### RELIABILITY BEGINS WITH THE DESIGN

Quality and reliability must begin with design. No amount of extra testing or inspection will produce reliable ICs from a design that is inherently unreliable. Signetics follows very strict design and layout practices with its circuits. To eliminate the possibility of metal migration, current density in any path cannot exceed  $2 \times 10^5$  amps/cm<sup>2</sup>. Layout rules are followed to minimize the possibility of shorts, circuit anomalies, and SCR type latch-up effects. Numerous ground-to-substrate connections are required to ensure that the entire chip is at the same ground potential, thereby precluding internal noise problems.

### PRODUCT CHARACTERIZATION

Before a new design is released, the characterization phase is completed to insure that the distribution of parameters resulting from lot-to-lot variations is well within specified limits. Such extensive characterization data

also provides a basis for identifying unique application-related problems which are not part of normal data sheet guarantees. Characterization takes place from  $-55^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$  and at  $+10\%$  supply voltage.

### QUALIFICATION

Formal qualification procedures are required for all new or changed products, processes and facilities. These procedures ensure the high level of product reliability our customers expect. New facilities are qualified by corporate groups as well as by the quality organizations of specific units that will operate in the facility. After qualification, products manufactured by the new facility are subjected to highly accelerated environmental stresses to ensure that they can meet rigorous failure rate requirements. New or changed processes are similarly qualified.

### QA05 - QUALITY DATA BASE REPORTING SYSTEM

The QA05 data reporting system collects the results of product assurance testing on all finished lots and feeds this data back to concerned organizations where appropriate action can be taken. The QA05 reports EPQ (Estimated Process Quality) and AOQ (Average Outgoing Quality) results for electrical, visual/mechanical, hermeticity, and documentation audits. Data from this system is available on request.

### THE SURE PROGRAM

The SURE (Systematic Uniform Reliability Evaluation) program audits/monitors products from all Signetics' divisions under a variety of accelerated environmental stress conditions. This program, first introduced in 1964, has evolved to suit changing product complexities and performance requirements.

The SURE program has two major functions: Long-term accelerated stress performance audit and a short-term accelerated stress monitor. In the case of Bipolar Memory and Programmable Logic products, samples are

selected that represent all generic product groups in all wafer fabrication and assembly locations.

### THE LONG-TERM AUDIT

One-hundred devices from each generic family are subjected to each of the following stresses every eight weeks:

- High Temperature Operating Life:  
 $T_J = 150^{\circ}\text{C}$ , 1000 hours, static biased or dynamic operation, as appropriate (worst case bias configuration is chosen)
- High Temperature Storage:  $T_J = 150^{\circ}\text{C}$ , 1000 hours
- Temperature Humidity Biased Life:  $85^{\circ}\text{C}$ , 85% relative humidity, 1000 hours, static biased
- Temperature Cycling (Air-to-Air):  $-65^{\circ}\text{C}$  to  $+150^{\circ}\text{C}$ , 1000 cycles

### THE SHORT-TERM MONITOR

Every other week a 50-piece sample from each generic family is run to 168 hours of pressure pot (15psig,  $121^{\circ}\text{C}$ , 100% saturated steam) and 300 cycles of thermal shock ( $-65^{\circ}\text{C}$  to  $+150^{\circ}\text{C}$ ).

In addition, each Signetics assembly plant performs SURE product monitor stresses weekly on each generic family and molded package by pin count and frame type. Fifty-piece samples are run on each stress, pressure pot to 96 hours, thermal shock to 300 cycles.

### SURE REPORTS

The data from these test matrices provides a basic understanding of product capability, an indication of major failure mechanisms and an estimated failure rate resulting from each stress. This data is compiled periodically and is available to customers upon request.

Many customers use this information in lieu of running their own qualification tests, thereby eliminating time-consuming and costly additional testing.

## Quality and Reliability

### RELIABILITY ENGINEERING

In addition to the product performance monitors encompassed in the Programmable Logic SURE program, Signetics' Corporate and Division Reliability Engineering departments sustain a broad range of evaluation and qualification activities.

Included in the engineering process are:

- Evaluation and qualification of new or changed materials, assembly/wafer-fab processes and equipment, product designs, facilities and subcontractors.
- Device or generic group failure rate studies.
- Advanced environmental stress development.
- Failure mechanism characterization and corrective action/prevention reporting.

The environmental stresses utilized in the engineering programs are similar to those utilized for the SURE monitor; however, more highly-accelerated conditions and extended durations typify the engineering projects. Additional stress systems such as biased pressure pot, power-temperature cycling, and cycle-biased temperature-humidity, are also included in the evaluation programs.

### FAILURE ANALYSIS

The SURE Program and the Reliability Engineering Program both include failure analysis activities and are complemented by corporate, divisional and plant failure analysis departments. These engineering units provide a service to our customers who desire detailed failure analysis support, who in turn provide Signetics with the technical understanding of the failure modes and mechanisms actually experienced in service. This information is essential in our ongoing effort to accelerate and improve our understanding of product failure mechanisms and their prevention.

### ZERO DEFECTS PROGRAM

In recent years, United States industry has increasingly demanded improved product quality. We at Signetics believe that the customer has every right to expect quality products from a supplier. The benefits which are derived from quality products can be summed up in the words, *lower cost of ownership*.

Those of you who invest in costly test equipment and engineering to assure that incoming products meet your specifications have a special understanding of the cost of ownership. And your cost does not end there; you are also burdened with inflated inventories, lengthened lead times and more rework.

### SIGNETICS UNDERSTANDS CUSTOMERS' NEEDS

Signetics has long had an organization of quality professionals, inside all operating units, coordinated by a corporate quality department. This broad decentralized organization provides leadership, feedback, and direction for achieving a high level of quality. Special programs are targeted on specific quality issues. For example, in 1978 a program to reduce electrically defective units for a major automotive manufacturer improved outgoing quality levels by an order of magnitude.

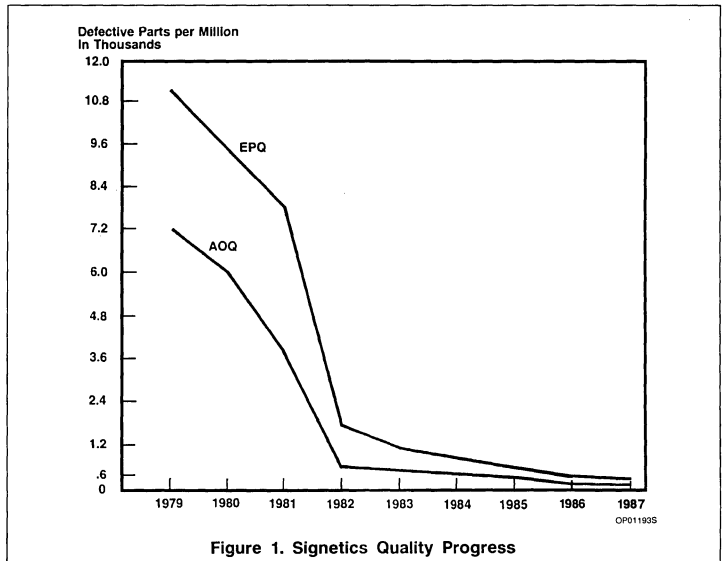
In 1980 we recognized that in order to achieve outgoing levels on the order of 100PPM (parts per million), down from an industry practice of 10,000PPM, we needed to supplement our traditional quality programs with one that encompassed all activities and all levels of the company. Such unprecedented

low defect levels could only be achieved by contributions from all employees, from the R and D laboratory to the shipping dock. In short, from a program that would effect a total cultural change within Signetics in our attitude toward quality.

### QUALITY PAYS OFF FOR OUR CUSTOMERS

Signetics' dedicated programs in product quality improvement, supplemented by close working relationships with many of our customers, have improved outgoing product quality more than twenty-fold since 1980. Today, many major customers no longer test Signetics circuits. Incoming product moves directly from the receiving dock to the production line, greatly accelerating throughput and reducing inventories. Other customers have pared significantly the amount of sampling done on our products. Others are beginning to adopt these cost-saving practices.

We closely monitor the electrical, visual, and mechanical quality of all our products and review each return to find and correct the cause. Since 1981, over 90% of our customers report a significant improvement in overall quality (see Figure 1).





## Quality and Reliability

At Signetics, quality means more than working circuits. It means on-time delivery of the right product at the agreed upon price. Signetics considers Performance to Customer Request and Performance to Original Schedule Date to be key Quality issues. Employees treat delinquencies as quality defects. They analyze the cause for the delinquency and seek corrective action to prevent future occurrence. Continuous effort is given to try to achieve the ultimate goal of zero delinquencies.

### ONGOING QUALITY PROGRAM

The quality improvement program at Signetics is based on "Do it Right the First Time". The intent of this innovative program is to change the perception of Signetics' employees that somehow quality is solely a manufacturing issue where some level of defects is inevitable. This attitude has been replaced by one of acceptance of the fact that all errors and defects are preventable, a point of view shared by all technical and administrative functions equally.

This program extends into every area of the company, and more than 40 quality improvement teams throughout the organization drive its ongoing refinement and progress.

Key components of the program are the Quality College, the "Make Certain" Program, Corrective Action Teams, and the Error Cause Removal System.

The core concepts of doing it right the first time are embodied in the four absolutes of quality:

1. The definition of quality is conformance to requirements.
2. The system to achieve quality improvement is prevention.

3. The performance standard is zero defects.
4. The measurement system is the cost of quality.

### QUALITY COLLEGE

Almost continuously in session, Quality College is a prerequisite for all employees. The intensive curriculum is built around the four absolutes of quality; colleges are conducted at company facilities throughout the world.

### "MAKING CERTAIN" - ADMINISTRATIVE QUALITY IMPROVEMENT

Signetics' experience has shown that the largest source of errors affecting product and service quality is found in paperwork and in other administrative functions. The "Make Certain" program focuses the attention of management and administrative personnel on error prevention, beginning with each employee's own actions.

This program promotes defect prevention in three ways: by educating employees as to the impact and cost of administrative errors, by changing attitudes from accepting occasional errors to one of accepting a personal work standard of zero defects, and by providing a formal mechanism for the prevention of errors.

### CORRECTIVE ACTION TEAMS

Employees with the perspective, knowledge, and necessary skills to solve a problem are formed into ad hoc groups called Corrective Action Teams. These teams, a major force within the company for quality improvement, resolve administrative, technical and manufacturing problems.

### ECR SYSTEM (ERROR CAUSE REMOVAL)

The ECR System permits employees to report to management any impediments to doing the job right the first time. Once such an impediment is reported, management is obliged to respond promptly with a corrective program. Doing it right the first time in all company activities produces lower cost of ownership through defect prevention.

### PRODUCT QUALITY PROGRAM

To reduce defects in outgoing products, we created the Product Quality Program. This is managed by the Product Engineering Council, composed of the top product engineering and test professionals in the company. This group:

1. Sets aggressive product quality improvement goals;
2. provides corporate-level visibility and focus on problem areas;
3. serves as a corporate resource for any group requiring assistance in quality improvement; and
4. drives quality improvement projects.

As a result of this aggressive program, every major customer who reports back to us on product performance is reporting significant progress.

### VENDOR CERTIFICATION PROGRAM

Our vendors are taking ownership of their own product quality by establishing improved process control and inspection systems. They subscribe to the zero defects philosophy. Progress has been excellent.

## Quality and Reliability

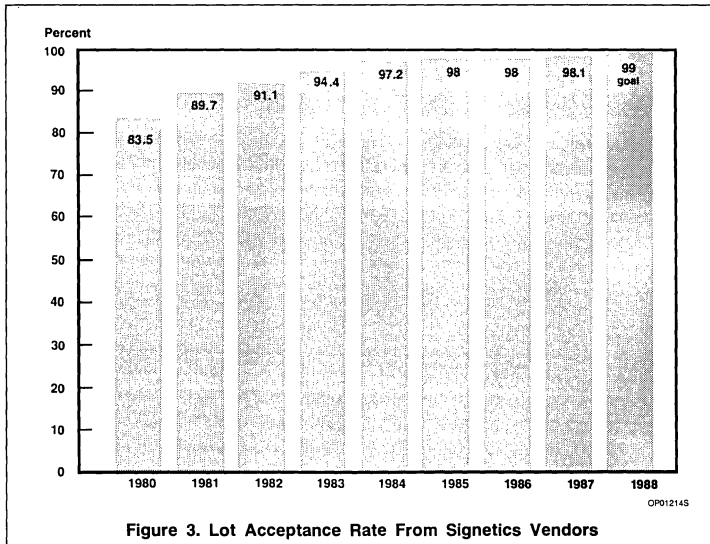


Figure 3. Lot Acceptance Rate From Signetics Vendors

Through intensive work with vendors, we have improved our lot acceptance rate on incoming materials as shown in Figure 3. Simultaneously, waivers of incoming material have been eliminated.

### MATERIAL WAIVERS

1988 - STD = 0 Waivers

1987 - 0

1986 - 0

1985 - 0

1984 - 0

1983 - 0

1982 - 2

1981 - 134

Higher incoming quality material ensures higher outgoing quality products.

### QUALITY AND RELIABILITY ORGANIZATION

Quality and reliability professionals at the divisional level are involved with all aspects of the product, from design through every step in the manufacturing process, and provide product assurance testing of outgoing product. A separate corporate-level group provides direction and common facilities.

Quality and Reliability Functions

- Manufacturing quality control
- Product assurance testing
- Laboratory facilities - failure analysis, chemical, metallurgy, thin film, oxides
- Environmental stress testing

- Quality and reliability engineering
- Customer liaison

### COMMUNICATING WITH EACH OTHER

For information on Signetics' quality programs or for any question concerning product quality, the field salesperson in your area will provide you with the quickest access to answers. Or, write on your letter-head directly to the corporate V.P. of quality at the corporate address shown at the back of this manual.

We are dedicated to preventing defects. When product problems do occur, we want to know about them so we can eliminate their causes. Here are some ways we can help each other:

- Provide us with one informed contact within your organization. This will establish continuity and build confidence levels.
- Periodic face-to-face exchanges of data and quality improvement ideas between your engineers and ours can help prevent problems before they occur.
- Test correlation data is very useful. Line-pull information and field failure reports also help us improve product performance.
- Provide us with as much specific data on the problem as soon as possible to speed analysis and enable us to take corrective action.
- An advance sample of the devices in question can start us on the problem

resolution before physical return of shipment.

This team work with you will allow us to achieve our mutual goal of improved product quality.

### MANUFACTURING: DOING IT RIGHT THE FIRST TIME

In dealing with the standard manufacturing flows, it was recognized that significant improvement would be achieved by "doing every job right the first time", a key concept of the quality improvement program. During the development of the program many profound changes were made. Figure 4, *Programmable Logic Process Flow*, shows the result. Key changes included such things as implementing 100% temperature testing on all products as well as upgrading test handlers to insure 100% positive binning. Some of the other changes and additions were to tighten the outgoing QA lot acceptance criteria to the tightest in the industry, with zero defect lot acceptance sampling across all three temperatures.

The achievements resulting from the improved process flow have helped Signetics to be recognized as the leading Quality supplier of Programmable Logic. These achievements have also led to our participation in several Ship-to-Stock programs, which our customers use to eliminate incoming inspection. Such programs reduce the user *cost of ownership* by saving both time and money.

### OUR GOAL: 100% PROGRAMMING YIELD

Our original goal back in the early 1970s was to develop a broad line of programmable products which would be recognized as having the best programming yield in the industry. Within the framework of a formal quality program, our efforts to improve circuit designs and refine manufacturing controls have resulted in major advances toward that goal.

Also within the framework of our formal quality program we have now established a stated goal of 100% programming yield. Through the increasing effectiveness of a quality attitude of "Do It Right The First Time" we're moving ever closer to that target.

Signetics PLD programming yields have been shown in collected data from internal audits and customer reporting to be consistently higher than comparable devices produced by our competition. We use systematic methods involving publication of exacting specifications of our programming algorithms, and through evaluation of those algorithms as implemented in industry standard programming equipment. Because of this we can assure our customers who program Signetics PLD's on such qualified equipment they will see consistently high yields. Our data base shows that average lot programming yield exceeds 97%.

# Quality and Reliability

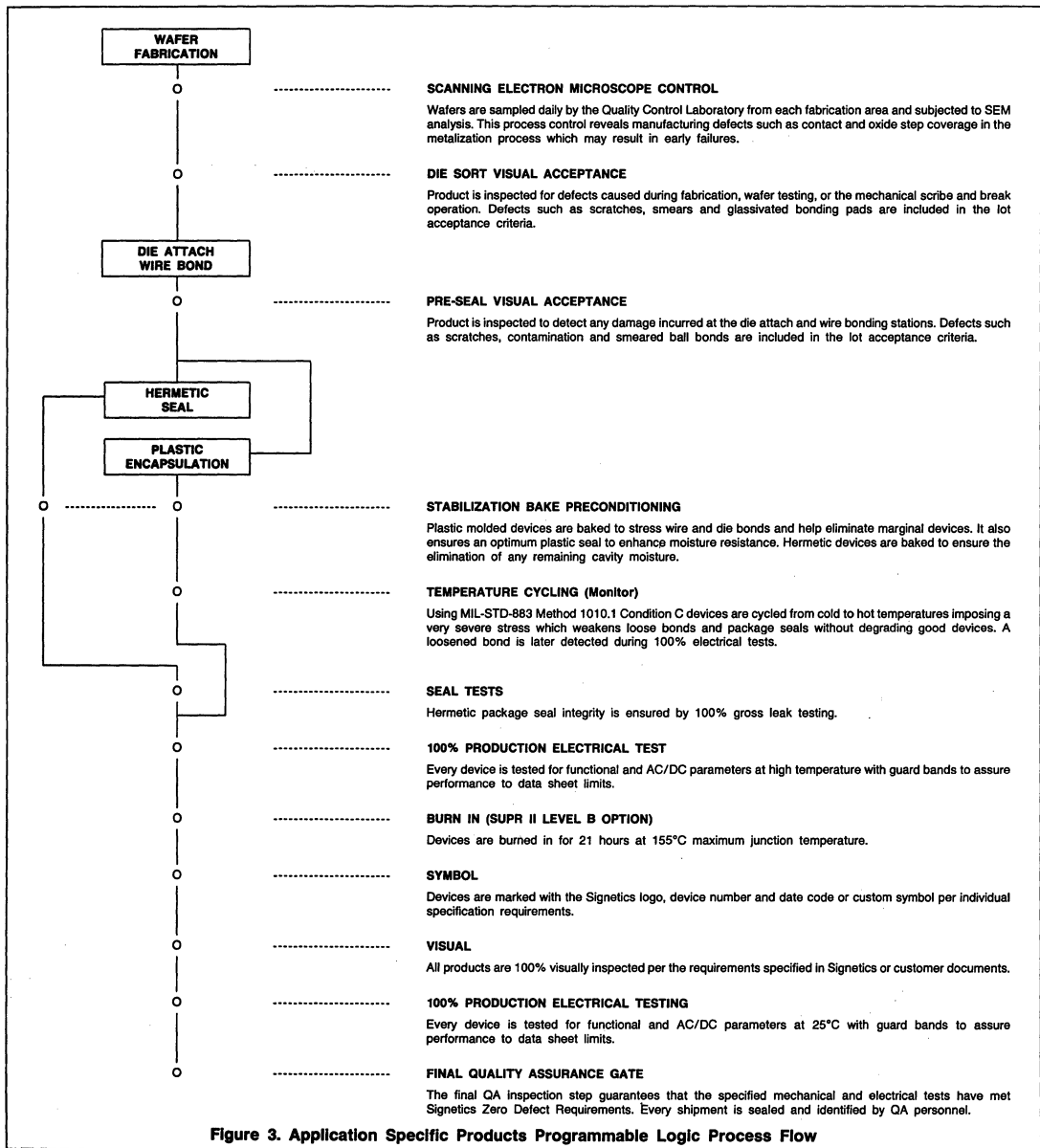
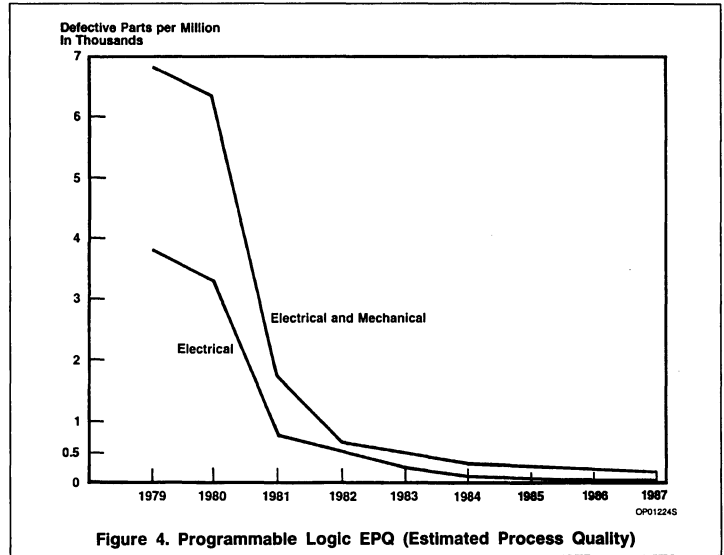


Figure 3. Application Specific Products Programmable Logic Process Flow

## Quality and Reliability

As time goes on the drive for a product line that has Zero Defects will grow in intensity. These efforts will provide both Signetics and our customers with the ability to achieve the mutual goal of improved product quality.

The Application Specific Quality Assurance department has monitored PPM progress, which can be seen in Figure 4. We are pleased with the progress that has been made, and expect to achieve even more impressive results as the procedures for accomplishing these tasks are fine tuned.

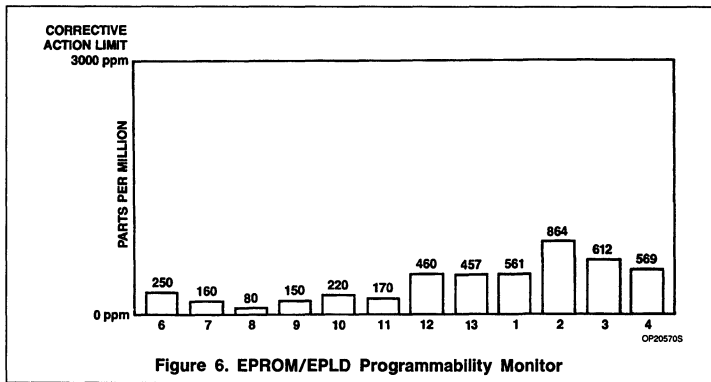
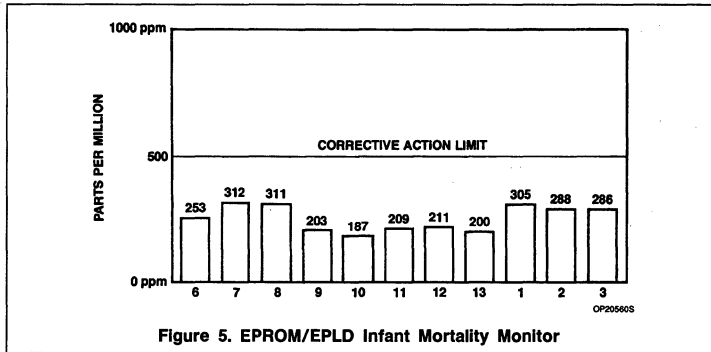


## Quality and Reliability

The Application Specific Reliability Department has established an ongoing Infant Mortality Monitor, the results of which can be seen in Figure 5. This monitor is used to determine and drive ongoing Corrective Action for the purposes of continuously improving product reliability.

The real measure of any quality improvement program is the result that our customers see. The meaning of *Quality* is more than just working circuits. It means commitment to *On Time Delivery at the Right Place of the Right Quantity of the Right Product at the Agreed Upon Price.*

Product Programmability, as illustrated in Figure 6, is continuously monitored to assure that the highest performance possible is attained.



## Quality and Reliability

### CMOS RELIABILITY INFORMATION

All Signetics' EPROM die are designed as low power UV light erasable and electrically programmable read only memories. They have been designed to perform over military and commercial temperature ranges. These die are assembled in EPROM packages that comply with industry standard packages: Cer-dip (Quartz window), Plastic DIP (One Time Programmable) and Plastic Leaded Chip Carrier (One Time Programmable).

The following descriptions are of the tests and calculations performed on each device organization and package type to validate the quality and reliability of the CMOS design and technology. All described tests are performed on each package type, with the exception of the 'Program-erase cycling' test for the One Time Programmable devices.

### ELECTROSTATIC DISCHARGE PROTECTION (ESD)

This test is performed to validate the product's tolerance to electrostatic discharge damage.

Both MIL-STD-883 criteria (human body model) and mechanical model charged device test are performed.

### HIGH TEMPERATURE STORAGE LIFE TEST (HTSL)

Another popular name for this test is data retention bake. This process is used to thermally accelerate charge loss from the floating gate. The test is performed by subjecting devices that contain a 100% programmed data pattern to a 250°C bake with no applied electrical bias or clocks.

In addition to charge loss, this test is used to detect mechanical reliability (i.e., bond integrity) and process instability.

### DYNAMIC LOW TEMPERATURE LIFE TEST (DLTL)

This test is performed at -10°C to detect the effects of hot electron injection into the gate oxide as well as package-related failures (i.e., metal corrosion). The biasing and clocking conditions for this test are identical to the DHTL #1 test.

### TEMPERATURE CYCLE (TMCL)

This test consists of performing 200 cycles of ambient air temperature of the chamber and housing the unbiased subject devices from -65°C to +150°C and back. The 200 cycles are performed at 20 minutes per cycle.

### DYNAMIC HIGH TEMPERATURE LIFE TEST (DHTL #1)

This test is used to accelerate failure mechanisms by operating the devices at 125°C ambient temperature with worst-case specified power supply voltages of  $V_{CC}$  and  $V_{PP}$  at 5.5V. The memory is sequentially addressed to exercise the fully-loaded outputs. A checkerboard complement data pattern is used to simulate random patterns expected during actual use.

### DYNAMIC HIGH TEMPERATURE LIFE TEST (DHTL #2)

This test is used to accelerate oxide breakdown failures and to further accelerate the failure mechanisms of DHTL #1. The test setup is identical to the one used for the DHTL #1 test except the temperature is 150°C and the  $V_{CC}$  and  $V_{PP}$  power supply voltages are 6.5V, resulting in a 20% increase over the specified operational electrical field across the gate oxides of the device (1.25mV/cm for 325Å oxide thickness). This represents a 55 × electrical field induced acceleration in addition to the thermal acceleration at 150°C.

### PROGRAM-ERASE CYCLING AND PROGRAMMABILITY

All four power supply voltage combinations for  $V_{CC}$  and  $V_{PP}$  are tested for programmability ( $V_{CC} = 6.0V \pm 0.25V$  and  $V_{PP} = 12.5V \pm 0.5V$  in program mode). The number of possible program/erase cycles is then tested to establish program-erase cycling expectations.

### FAILURE RATE PREDICTIONS

In preparation for the various life tests, a 168 hour, 125°C, 5.5V production burn-in is performed on the devices. The infant mortality rejects are removed from the population in order to develop long-term failure rate information during the random failure rate portion of the device life cycle.

The failure rate calculation combines all failure mechanisms by activation energies and associated device hours for the 125°C, 5.5V Dynamic Life Test (DHTL #1), the 150°C, 6.5V Dynamic Life Test (DHTL #2), the 150°C, 7.5V Static Life Test and the 250°C Bake.

The activation energies for the various EPROM failure mechanisms are:

Defective bit	0.6eV
charge gain/loss (electron hopping conduction)	
Oxide breakdown	0.3eV
Silicon defects	0.3eV
Contamination	1.0 - 1.2eV
Intrinsic charge loss	1.4eV

#### NOTE:

The combined failure rate for the stresses is the sum of failure rates by activation energies.

## Quality and Reliability

### METHODS OF FAILURE RATE CALCULATIONS

Actual Device Hours = Number of Devices × Number of Hours. In order to determine the Equivalent Hours derated to a given operating temperature, the junction temperatures of the devices should be calculated using the known thermal resistance of the package ( $\theta_{JA}$ ) and the power dissipation of the devices:

$$T_{1,2} = \theta_{JA} (IV)_{1,2} + T_{A1,2} \quad (1)$$

Using the Arrhenius relation, the test temperature and the derated operating temperature will yield the thermal acceleration factor from  $T_1$  to  $T_2$ :

$$\frac{R_1}{R_2} = \frac{A \cdot \exp\left[\frac{E_A}{kT_1}\right]}{A \cdot \exp\left[\frac{E_A}{kT_2}\right]} = \exp\left[\frac{E_A}{k} \left[\frac{1}{T_1} - \frac{1}{T_2}\right]\right] \quad (2)$$

$k = 8.617 \times 10^{-5}$  eV/Kelvin (Boltzmann's constant)

A = proportionality constant for a given failure mechanism

$R_1$  = mean time to failure @  $T_1$

$R_2$  = mean time to failure @  $T_2$

$E_A$  = activation energy for the failure mechanism

$T_1$  = operating temperature

$T_2$  = life test temperature

An additional 55 × acceleration factor should be added for the 150°C/6.5V dynamic life test due to the time-dependent oxide failure acceleration (20% higher than specified power supply voltage).

Multiplying the actual device hours by the acceleration factor for each failure mechanism will result in the equivalent hours.

Poisson statistics are applied to estimate the performance of the population from the life test results of a sample test. This is useful when the probability of failures is small and the failures occur randomly in time. A commonly used formula for estimating the failure rate is the "chi-squared" equation:

$$F_C = \frac{\chi^2}{2nt} \times 100\% \quad (3)$$

$F_C$  = calculated failure rate estimate (in %/1000 hrs) at upper confidence limit

$\chi^2$  = "chi-squared" value for  $2F_A + 2$  degrees of freedom for  $\alpha$  where  $F_A$  is the number of actual failures ( $\chi^2$  comes from available tables for a known  $\alpha$ )

$\alpha = 1 - B$ , where B is the confidence limit (B is stated in %).

n = number of units in test

t = test time in thousands of hours (equivalent)

Equation 3 will calculate the estimated failure rates/1000 hrs for 60% confidence level (industry standard) for each failure mechanism.

### THE SURE PROGRAM

The SURE (Systematic Uniform Reliability Evaluation) program audits/monitors products from all Signetics' divisions under a variety of accelerated environmental stress conditions. This program, first introduced in 1964, has evolved to suit changing product complexities and performance requirements.

The SURE program has two major functions: long-term accelerated stress performance audit and a short-term accelerated stress monitor. In the case of Memory products, samples are selected that represent product groups from all wafer fabrication and assembly locations.

### SURE REPORTS

The data from these test matrices provides a basic understanding of product capability, an indication of major failure mechanisms and an estimated failure rate resulting from each stress. This data is compiled periodically and is available to customers upon request.

### INDEX

<b>Series 20</b>		
PLC16V8	Erasable and OTP PAL <sup>®</sup> -Type Device .....	3-3
PLHS16L8A	PAL <sup>®</sup> -Type Device .....	3-13
PLHS16L8B	PAL <sup>®</sup> -Type Device .....	3-20
PLUS16R8D	PAL <sup>®</sup> -Type Devices .....	3-27
PLHS18P8A	PAL <sup>®</sup> -Type Device .....	3-30
PLHS18P8B	PAL <sup>®</sup> -Type Device .....	3-37
<b>Series 24</b>		
PLC20V8	Erasable and OTP PAL <sup>®</sup> -Type Device .....	3-44
PLUS20R8D	PAL <sup>®</sup> -Type Devices .....	3-54





## PLC16V8 Series Erasable and OTP PAL<sup>®</sup>-Type Device

Signetics Programmable Logic  
Product Specification

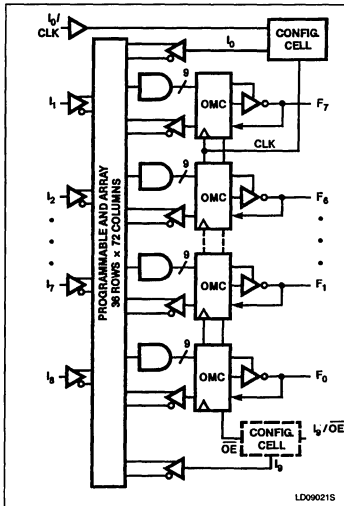
### Application Specific Products • Series 20

#### DESCRIPTION

The PLC16V8 Programmable Array Logic device is a 20-pin CMOS PLD designed to replace full-power as well as quarter-power and half-power Series 20 PAL<sup>®</sup> devices. Available in four speed/power configurations, the generic PLC16V8 device can be configured to emulate 22 different PAL devices in multiple speed/power configurations. The more complex AND/OR logic functions can be easily implemented with the PLC16V8 because of the flexibility inherent to its generic Output Macro Cell architecture.

The PLC16V8 is a two-level logic element comprised of 10 inputs, 72 AND gates and 8 Output Macro Cells (OMC). Each Output Macro Cell can be individually configured as a dedicated input, a dedicated output, a bidirectional I/O or as a registered output with feedback. This generic architecture provides a means of reducing documentation, inventory and manufacturing related costs. Furthermore, the PLC16V8 series devices are designed to accept both TTL and CMOS input levels to facilitate logic integration in almost any system environment.

#### FUNCTIONAL DIAGRAM



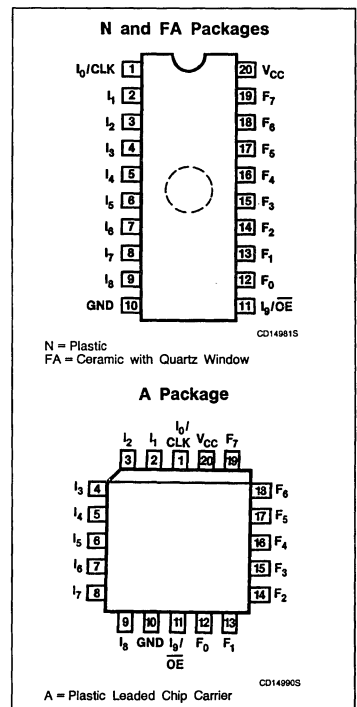
#### FEATURES

- 100% functional replacement for Series 20 PAL devices
  - $I_{OL} = 24mA$
- Low power performance: 50 and 90mA max
  - All inputs and outputs switching at 15MHz
- Equivalent bipolar performance
  - 35 and 45ns  $t_{PD}$
  - 28.5 and 22.2MHz  $f_{MAX}$  (async)
- EPROM cell technology
  - Erasable
  - 100% testable
  - Reconfigurable (quartz window package only)
- TTL and CMOS compatible
- Security fuse
- Available in 300mil-wide DIP with quartz window, plastic DIP (OTP), or PLCC (OTP)

#### PIN LABEL DESCRIPTIONS

I	Dedicated input
B	Bidirectional input/output
O	Dedicated output
D	Registered output (D-type flip-flop)

#### PIN CONFIGURATIONS



#### PAL DEVICE TO PLC16V8 OUTPUT PIN CONFIGURATION CROSS REFERENCE

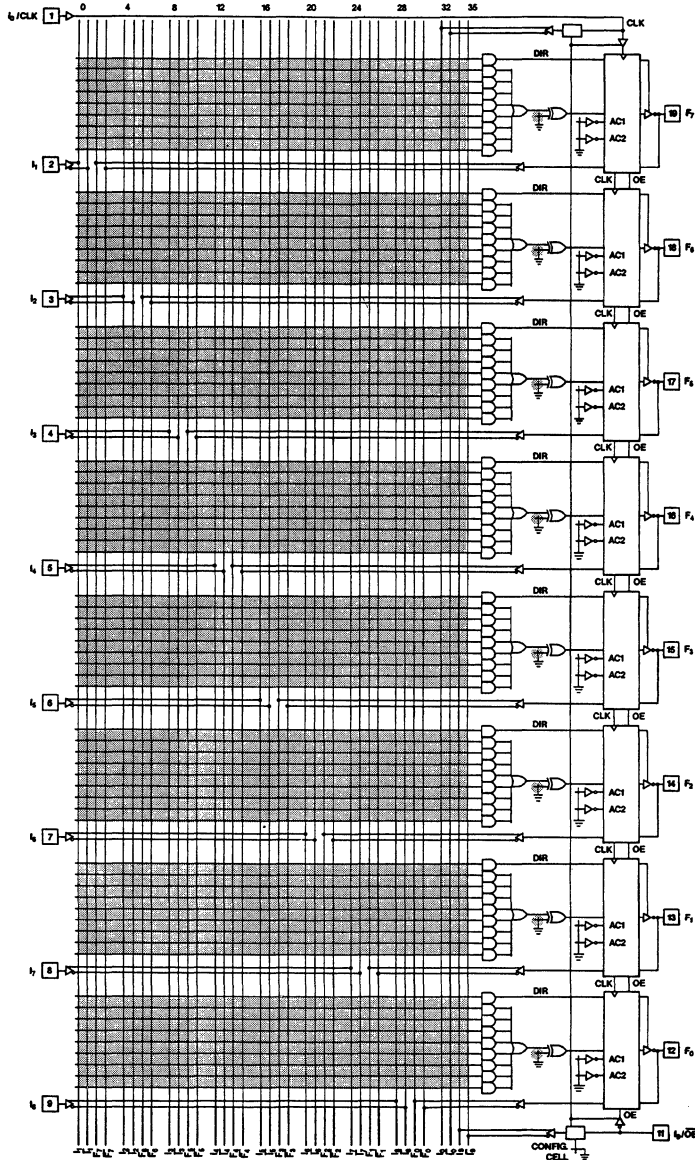
PIN NO.	PLC 16V8	16L8 16H8 16P8	16R4 16RP4	16R6 16RP6	16R8 16RP8	16L2 16H2 16P2	14L4 14H4 14P4	12L6 12H6 12P6	10L8 10H8 10P8
1	I <sub>0</sub> /CLK	I	CLK	CLK	CLK	I	I	I	I
19	F <sub>7</sub>	B	B	B	D	I	I	I	O
18	F <sub>6</sub>	B	B	D	D	I	I	O	O
17	F <sub>5</sub>	B	D	D	D	I	O	O	O
16	F <sub>4</sub>	B	D	D	D	O	O	O	O
15	F <sub>3</sub>	B	D	D	D	O	O	O	O
14	F <sub>2</sub>	B	D	D	D	I	O	O	O
13	F <sub>1</sub>	B	B	D	D	I	I	O	O
12	F <sub>0</sub>	B	B	B	D	I	I	I	O
11	I <sub>9</sub> /OE	I	OE	OE	OE	I	I	I	I

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# Erasable and OTP PAL<sup>®</sup>-Type Device

## PLC16V8 Series

### LOGIC DIAGRAM



LD090305

**NOTES:**

In the unprogrammed or virgin state:

All cells are in a conductive state.  
All AND gate locations are pulled to a logic "0" (Low).  
Output polarity is non-inverting.

Pins 1 and 11 are configured as Inputs 0 and 9, respectively, via the configuration cell. The clock and  $\overline{OE}$  functions are disabled.

All output macro cells (OMC) are configured as bidirectional I/O, with the outputs disabled via the direction term.  
Ⓢ Denotes a programmable cell location.

# Erasable and OTP PAL®-Type Device

## PLC16V8 Series

3

The Signetics state-of-the-art Floating-Gate CMOS EPROM process yields bipolar equivalent performance at one-quarter to one-half the power consumption. The erasable nature of the EPROM process enables Signetics to functionally test the devices prior to shipment to the customer. Additionally, this allows Signetics to extensively stress test, as well as ensure the threshold voltage of each individual EPROM cell. 100% programming yield is subsequently guaranteed.

Signetics' AMAZE PLD design software supports all aspects of design, simulation and programming. For simple conversion of existing PAL device codes into the PLC16V8 series format, a PAL-to-V8 Converter is also available. This stand-alone, single-disk software package translates a PAL device code (from a device or a JEDEC standard fuse map) into an equivalent PLC16V8 series JEDEC format. The PAL-to-V8 converter, which runs on an IBM PC or compatible, includes the necessary programmer interface software for most commercially available programmers.

### THE OUTPUT MACRO CELL (OMC)

The PLC16V8 has 8 individually programmable Output Macro Cells. The 72 AND inputs (or product terms) from the programmable AND array are connected to the 8 OMCs in groups of 9. Eight of the AND terms are dedicated to logic functions; the ninth is for asynchronous direction control.

Each OMC can be independently programmed via 16 architecture control bits, AC1<sub>n</sub> and AC2<sub>n</sub> (one pair per macro cell). Similarly, each OMC has a programmable output polarity control bit (X<sub>n</sub>). By configuring the pair of architecture control bits according to the table, 4 different configurations may be implemented.

### CONFIGURATION CELL

A single configuration cell controls the functions of Pins 1 and 11. Refer to Functional Diagram. When the configuration cell is programmed, Pin 1 is a dedicated clock and Pin 11 is dedicated for output enable. When the configuration cell is unprogrammed, Pins 1 and 11 are both dedicated inputs. Note that the output enable for all registered OMCs is common — from Pin 11 only. Output enable control of the bidirectional I/O OMCs is provided from the AND array via the direction product term.

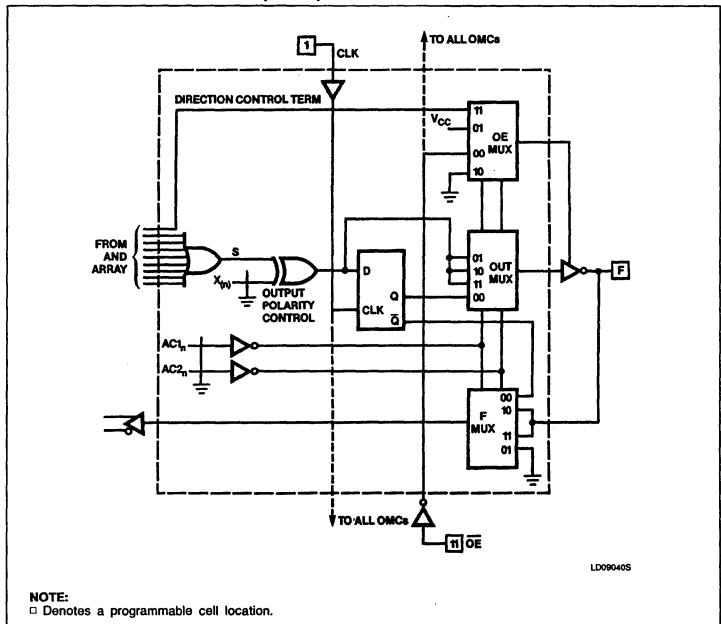
If any one OMC is configured as registered, the configuration cell will be automatically config-

FUNCTION	CONTROL CELL CONFIGURATIONS			COMMENTS
	AC1 <sub>n</sub>	AC2 <sub>n</sub>	CONFIG. CELL	
Registered mode	Programmed	Programmed	Programmed	Dedicated clock from Pin 1. OE Control for all registered OMCs from Pin 11 only.
Bidirectional I/O mode <sup>1</sup>	Unprogrammed	Unprogrammed	Unprogrammed	Pins 1 and 11 are dedicated inputs. 3-State control from AND array only.
Fixed input mode	Unprogrammed	Programmed	Unprogrammed	Pins 1 and 11 are dedicated inputs.
Fixed output mode	Programmed	Unprogrammed	Unprogrammed	Pins 1 and 11 are dedicated inputs. The feedback path (via F <sub>MUX</sub> ) is disabled.

**NOTE:**

1. This is the virgin state as shipped from the factory.

### OUTPUT MACRO CELL (OMC)



ured (via the design software) to ensure that the clock and output enable functions are enabled on Pins 1 and 11, respectively. If none of the OMCs are registered, the configuration cell will be programmed such that Pins 1 and

11 are dedicated inputs. The programming codes are as follow:

Pin 1 = CLK, Pin 11 = OE	L
Pin 1 and Pin 11 = Input	H

# Erasable and OTP PAL<sup>®</sup>-Type Device

## PLC16V8 Series

### ORDERING INFORMATION

DESCRIPTION		ORDER CODE
<b>Propagation Delay (Max)</b>		
$t_{PD} = 35ns$	$f_{MAX} = 18.1MHz$ (Synchronous)	$I_{CC}$ (Active at 15MHz) 50mA
		90mA
$t_{PD} = 45ns$	$f_{MAX} = 13.3MHz$ (Synchronous)	50mA
		90mA
<b>Package Type</b>		<b>PACKAGE<sup>1</sup></b>
20-pin Plastic DIP (one time programmable; OTP)		N
20-pin Plastic Leaded Chip Carrier		A
20-pin Ceramic DIP with quartz window (reprogrammable)		FA

**NOTE:**

1. The package order code directly follows the device order code, i.e., PLC16V8Q35N for Plastic DIP (OTP).

### ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
$V_{CC}$	Supply voltage	-0.5 to +7	$V_{DC}$
$V_{IN}$	Input voltage	-0.5 to $V_{CC} + 0.5$	$V_{DC}$
$V_{OUT}$	Output voltage	-0.5 to $V_{CC} + 0.5$	$V_{DC}$
$I_{IN}$	Input currents	-10 to +10	mA
$I_{OUT}$	Output currents	+24	mA
$T_A$	Operating temperature range	0 to +75	°C
$T_{STG}$	Storage temperature range	-65 to +150	°C

### THERMAL RATINGS

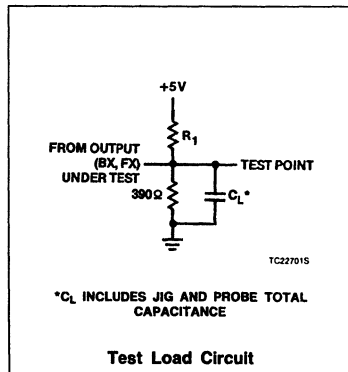
TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

The PLC16V8 device is also processed to military requirements for operation over the military temperature range. For specifications and ordering information consult the Signetics Military Data Book.

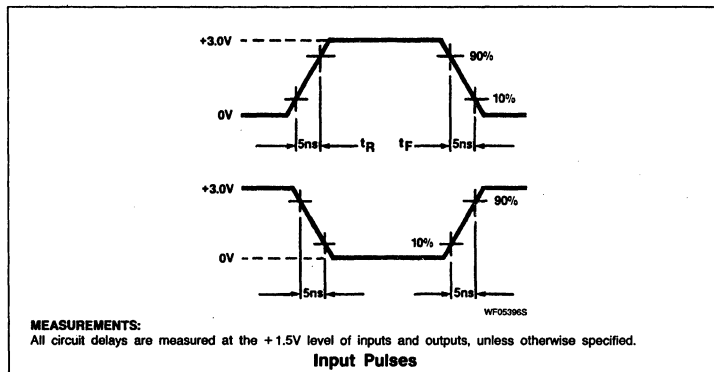
**NOTE:**

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

### AC TEST CONDITIONS



### VOLTAGE WAVEFORMS



# Erasable and OTP PAL<sup>®</sup>-Type Device

## PLC16V8 Series

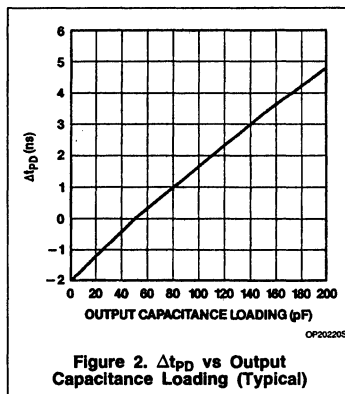
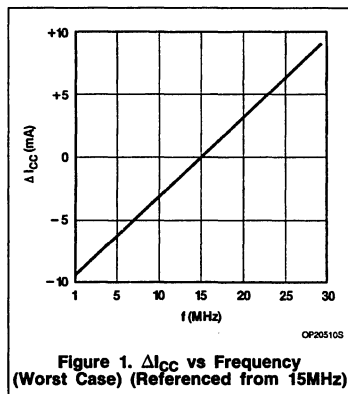
### DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75 ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min	-0.3		0.8	V
V <sub>IH</sub>	High	V <sub>CC</sub> = Max	2.0		V <sub>CC</sub> + 0.3	V
<b>Output voltage<sup>2</sup></b>						
V <sub>OL</sub>	Low	V <sub>CC</sub> = Min I <sub>OL</sub> = 24mA			0.5	V
V <sub>OH</sub>	High	I <sub>OH</sub> = -3.2mA	2.4			V
<b>Input current</b>						
I <sub>IL</sub>	Low <sup>6</sup>	V <sub>IN</sub> = GND			-10	μA
I <sub>IH</sub>	High	V <sub>IN</sub> = V <sub>CC</sub>			10	μA
<b>Output current</b>						
I <sub>O(OFF)</sub>	Hi-Z state	V <sub>OUT</sub> = V <sub>CC</sub> V <sub>OUT</sub> = GND			10 -10	μA μA
I <sub>OS</sub>	Short-circuit <sup>3, 7</sup>	V <sub>OUT</sub> = GND			-130	mA
I <sub>CC</sub>	V <sub>CC</sub> supply current (Active) <sup>4</sup>	I <sub>OUT</sub> = 0mA f = 15MHz <sup>5</sup>	Quarter power (Q)		50	mA
			Half power (H)		90	mA
<b>Capacitance</b>						
C <sub>I</sub>	Input	V <sub>CC</sub> = 5V V <sub>IN</sub> = 2.0V		12		pF
C <sub>B</sub>	I/O	V <sub>B</sub> = 2.0V		15		pF

3

**NOTES:**

1. All typical values are at V<sub>CC</sub> = 5V, T<sub>A</sub> = +25°C.
2. All voltage values are with respect to network ground terminal.
3. Duration of short-circuit should not exceed one second. Test one at a time.
4. Tested with TTL input levels: V<sub>IL</sub> = 0.45V, V<sub>IH</sub> = 2.4V. Measured with all inputs and outputs switching.
5. Refer to Figure 1, ΔI<sub>CC</sub> vs Frequency (worst case). (Referenced from 15MHz)
6. I<sub>IL</sub> for Pin 1 (I<sub>0</sub>/CLK) is ±10μA with V<sub>IN</sub> = 0.4V.
7. Refer to Figure 2 for Δt<sub>PD</sub> vs output capacitance loading.



# Erasable and OTP PAL<sup>®</sup>-Type Device

## PLC16V8 Series

### AC ELECTRICAL CHARACTERISTICS $0^{\circ}\text{C} \leq T_A \leq +75^{\circ}\text{C}$ , $4.75\text{V} \leq V_{\text{CC}} \leq 5.25\text{V}$ $R_2 = 390\Omega$

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION <sup>1</sup>		PLC16V8Q-35 PLC16V8H-35		PLC16V8Q-45 PLC16V8H-45		UNIT
				R <sub>1</sub> ( $\Omega$ )	C <sub>L</sub> (pF)	Min	Max	Min	Max	
<b>Pulse width</b>										
t <sub>CKP</sub>	Clock period (Minimum t <sub>IS</sub> + t <sub>CKO</sub> )	CLK +	CLK +			55		75		ns
t <sub>CKH</sub>	Clock width High	CLK -	CLK +			20		25		ns
t <sub>CKL</sub>	Clock width Low	CLK +	CLK -			20		25		ns
<b>Hold time</b>										
t <sub>IH</sub>	Input or feedback data hold time	Input $\pm$	CLK +			0		0		ns
<b>Setup time</b>										
t <sub>IS</sub>	Input or feedback data setup time	CLK +	I $\pm$ , F $\pm$			30		40		ns
<b>Propagation delay</b>										
t <sub>PD</sub>	Delay from input to active output	F $\pm$	I $\pm$ , F $\pm$	200	50		35		45	ns
t <sub>CKO</sub>	Clock High to output valid access Time	F $\pm$	CLK +	200	50		25		35	ns
t <sub>OE1</sub> <sup>3</sup>	Product term enable to active output	F $\pm$	I $\pm$ , F $\pm$	Active-High R = 1.5k Active-Low R = 550	50		35		45	ns
t <sub>OD1</sub> <sup>2</sup>	Product term disable to outputs off	F $\pm$	I $\pm$ , F $\pm$	From V <sub>OH</sub> R = $\infty$ From V <sub>OL</sub> R = 200	5		35		45	ns
t <sub>OD2</sub> <sup>2</sup>	Pin 11 output disable High to outputs off	F $\pm$	OE -	From V <sub>OH</sub> R = $\infty$ From V <sub>OL</sub> R = 200	5		25		30	ns
t <sub>OE2</sub> <sup>3</sup>	Pin 11 output enable to active output	F $\pm$	OE +	Active-High R = 1.5k Active-Low R = 550	50		25		30	ns
t <sub>PPR</sub>	Power-up reset	F +	V <sub>CC</sub> +				35		45	ns
<b>Frequency of operation (t<sub>IS</sub> + t<sub>CKO</sub>)</b>										
f <sub>MAX</sub>	Maximum frequency	Synch. Asynch.		200	50		18.1 28.5		13.3 22.2	MHz

#### NOTES:

1. Refer also to AC Test Conditions. (Test Load Circuit)

2. 3-State levels are measured  $\pm 0.5\text{V}$  from the active steady-state level.

3. Resistor values of 1.5k and 550 $\Omega$  provide 3-State levels of 1.0V and 2.0V, respectively. Output timing measurements are to 1.5V level.

# Erasable and OTP PAL®-Type Device

# PLC16V8 Series

## POWER-UP RESET

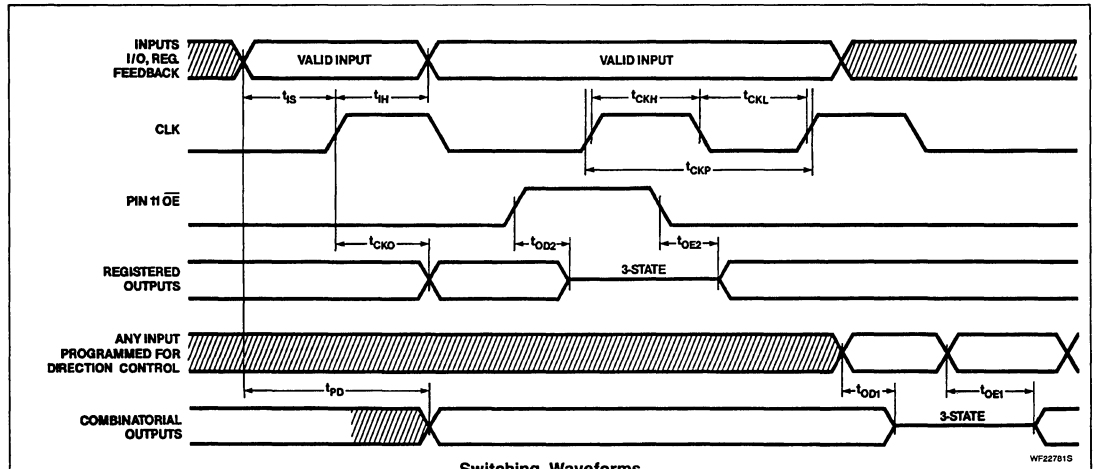
In order to facilitate state machine design and testing, a power-up reset function has been incorporated in the PLC16V8. All internal registers will reset to active-Low (logical "0") after a specified period of time ( $t_{PPR}$ ). Therefore, any OMC that has been configured as a

registered output will always produce an active-High on the associated output pin because of the inverted output buffer. The internal feedback ( $\bar{Q}$ ) of a registered OMC will also be set High. The programmed polarity of OMC will not affect the active-High output condition during a system power-up condition.

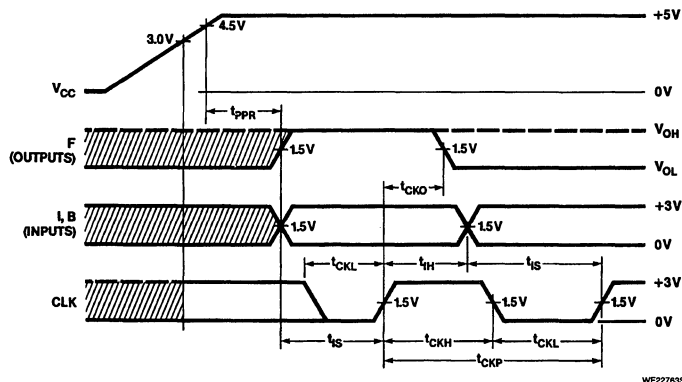
The following conditions must be considered when the asynchronous power-up reset occurs.  $V_{CC}$  rise to 4.5V (90%) must be monotonic. The clock input must stabilize to a valid TTL level prior to the  $V_{CC}$  rise to 60% (3.0V). All input setup and hold times ( $t_{IS}$  and  $t_{IH}$ ) must be adhered to prior to clocking the device.

## TIMING DIAGRAMS

3



Switching Waveforms



**NOTE:**  
Diagram presupposes that the outputs (F) are enabled. The reset occurs regardless of the output condition (enabled or disabled).

Power-Up Reset



# Erasable and OTP PAL®-Type Device

## PLC16V8 Series

### REGISTER PRELOAD FUNCTION (DIAGNOSTIC MODE ONLY)

In order to facilitate the testing of state machine/controller designs, a diagnostic mode register preload feature has been incorporated into the PLC16V8 series device. This feature enables the user to load the registers

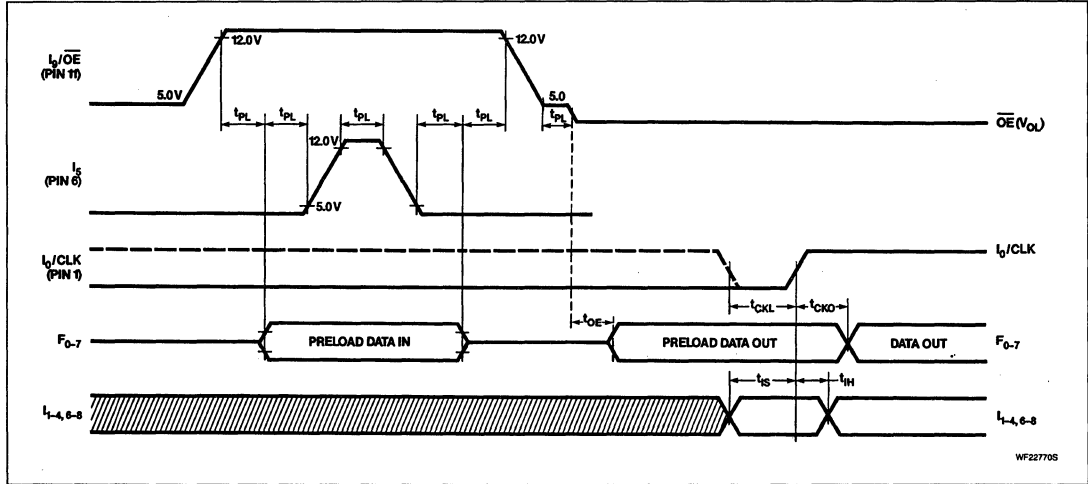
with predetermined states while a super voltage is applied to Pins 11 and 6 ( $I_9/\overline{OE}$  and  $I_5$ ). (See diagram for timing and sequence.)

To read the data out, Pins 11 and 6 must be returned to normal TTL levels. The outputs,  $F_{0-7}$ , must be enabled in order to read data out. The Q outputs of the registers will reflect

data in as input via  $F_{0-7}$  during preload. Subsequently, the register  $\overline{Q}$  output via the feedback path will reflect the complement of the data in as input via  $F_{0-7}$ .

Refer to the voltage waveform for timing and voltage references.

### REGISTER PRELOAD (DIAGNOSTIC MODE)



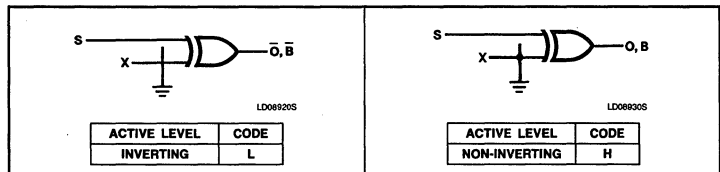
### LOGIC PROGRAMMING

The FPLA can be programmed by means of Logic Programming equipment.

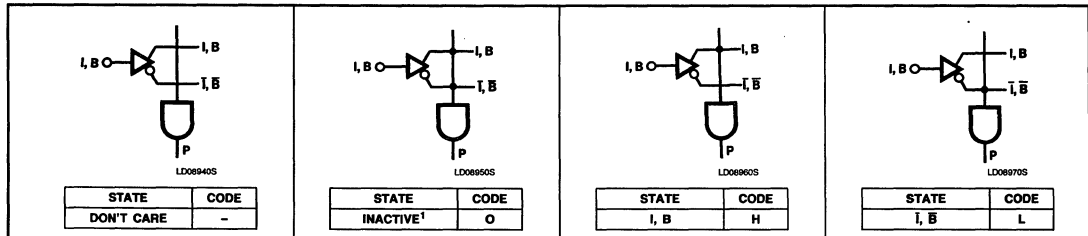
With Logic programming, the AND/Ex-OR gate input connections necessary to implement the desired logic function are coded directly from logic equations using the Program Table. Similarly, various OMC configurations are implemented by programming the Architecture Control bits AC1 and AC2, as shown below. Note that the configuration cell is automatically programmed based on the OMC configuration.

In this table, the logic state of variables I, P, and B associated with each Sum Term S is assigned a symbol which results in the proper fusing pattern of corresponding link pairs, defined as follows:

### OUTPUT POLARITY — (O, B)



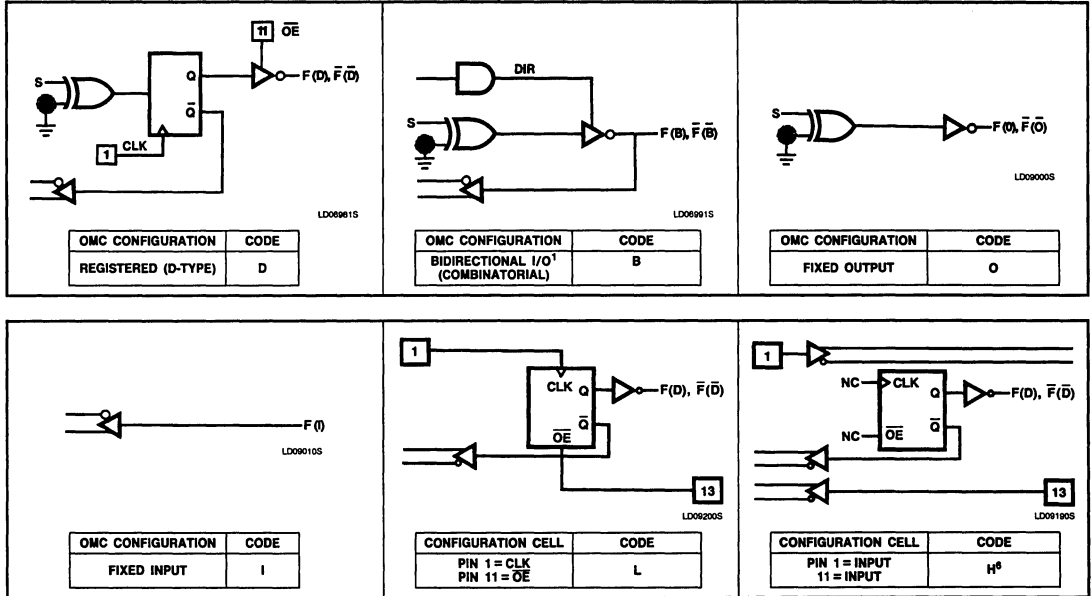
### "AND" ARRAY — (I, B)



# Erasable and OTP PAL®-Type Device

## PLC16V8 Series

### ARCHITECTURE CONTROL — AC1 and AC2



3

**NOTE:**

- A factory shipped unprogrammed device is configured such that:
1. All cells are in a conductive state.
  2. All AND gates are pulled to a logic "0" (Low).
  3. Output polarity is non-inverting.
  4. Pins 1 and 11 are configured as inputs 0 and 9. The clock and OE functions are disabled.
  5. All Output Macro Cells (OMCs) are configured as bidirectional I/O, with the outputs disabled via the direction term.
  6. This configuration cannot be used if any OMCs are configured as registered (Code = D). The configuration cell will be automatically configured to ensure that the clock and output enable functions are enabled on Pins 1 and 11, respectively, if any one OMC is programmed as registered.

### ERASURE CHARACTERISTICS (For Quartz Window Packages Only)

The erasure characteristics of the PLC16V8 Series devices are such that erasure begins to occur upon exposure to light with wavelengths shorter than approximately 4000 Angstroms (Å). It should be noted that sunlight and certain types of fluorescent lamps have wavelengths in the 3000–4000 Å range. Data shows that constant exposure to room level fluorescent lighting could erase a typical PLC16V8 in approximately three years, while

it would take approximately one week to cause erasure when exposed to direct sunlight. If the PLC16V8 is to be exposed to these types of lighting conditions for extended periods of time, opaque labels should be placed over the window to prevent unintentional erasure.

The recommended erasure procedure for the PLC16V8 is exposure to shortwave ultraviolet light which has a wavelength of 2537 Angstroms (Å). The integrated dose (i.e., UV intensity × exposure time) for erasure should be a minimum of 15Wsec/cm<sup>2</sup>. The erasure

time with this dosage is approximately 30 to 35 minutes using an ultraviolet lamp with a 12,000µW/cm<sup>2</sup> power rating. The device should be placed within one inch of the lamp tubes during erasure. The maximum integrated dose a CMOS EPLD can be exposed to without damage is 7258Wsec/cm<sup>2</sup> (1 week @ 12000µW/cm<sup>2</sup>). Exposure of these CMOS EPLDs to high intensity UV light for longer periods may cause permanent damage:

The maximum number of guaranteed erase/write cycles is 50. Data retention exceeds 20 years.

# Erasable and OTP PAL®-Type Device

## PLC16V8 Series

### PROGRAM TABLE

Y E R R O R	CONFIGURATION CELL (CLK/OE CONTROL)																	
	ARCH. CONTROL BITS																	
	AND								OR (FIXED)									
	OUTPUT POLARITY								F (B, O, D)									
	9	8	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
0											D	6	5	4	3	2	1	0
1											A							
2											A							
3											A							
4											A							
5											A							
6											A							
7											A							
8											A							
9											D							
10											A							
11											A							
12											A							
13											A							
14											A							
15											A							
16											A							
17											A							
18											D							
19											A							
20											A							
21											A							
22											A							
23											A							
24											A							
25											A							
26											A							
27											D							
28											A							
29											A							
30											A							
31											A							
32											A							
33											A							
34											A							
35											A							
36											D							
37											A							
38											A							
39											A							
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41											A							
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66											A							
67											A							
68											A							
69											A							
70											A							
71											A							
71	PIN 11	9	8	7	6	5	4	3	2	1	19	18	17	16	15	14	13	12
71	19	18	17	16	15	14	13	12	OR ARRAY (FIXED)									
71	19	18	17	16	15	14	13	12	DIRECTION CONTROL									
71	19	18	17	16	15	14	13	12	ACTIVE OUTPUT									
71	19	18	17	16	15	14	13	12	NOT USED									

**NOTES:**  
 In the unprogrammed or virgin state:  
 • All AND gate locations are pulled to a logic "0" (Low).  
 • Output polarity is non-inverting.  
 • Pins 1 and 11 are configured as inputs 0 and 9, respectively, via the configuration cell. The clock and OE functions are disabled.  
 • All output macro cells (OMC) are configured as combinatorial I/O, with the outputs disabled via the direction control term.

CUSTOMER NAME \_\_\_\_\_  
 PURCHASE ORDER # \_\_\_\_\_  
 SIGNETICS DEVICE # \_\_\_\_\_ CF (XXXX)  
 CUSTOMER SYMBOLIZED PART # \_\_\_\_\_  
 TOTAL NUMBER OF PARTS \_\_\_\_\_  
 PROGRAM TABLE # \_\_\_\_\_ REV. \_\_\_\_\_ DATE \_\_\_\_\_

AND ARRAY		CONTROL		OR ARRAY (FIXED)	
INACTIVE	O	OMC ARCH.		NON-INVERTING	H
L F A B	H	REGISTERED (D-TYPE)	D	INVERTING	L
L F A B	L	FIXED INPUT	I	CONFIG. CELL*	
DON'T CARE	-	FIXED OUTPUT	O	PIN 1 = CLK; PIN 11 = OE	L
		BIDIRECTIONAL I/O	B	PIN 1, PIN 11 = INPUT	H
				DIRECTION CONTROL	
				ACTIVE OUTPUT	A
				NOT USED	X

\* THE CONFIGURATION CELL IS AUTOMATICALLY PROGRAMMED BASED ON THE OMC ARCHITECTURE.

TB036105

# PLHS16L8A PAL<sup>®</sup>-Type Device

Signetics Programmable Logic  
Product Specification

## Application Specific Products

- Series 20

### DESCRIPTION

The PLHS16L8A is a high-speed "A" version PAL<sup>®</sup>-type device. The sum of products (AND-OR) architecture is comprised of 64 AND gates and 8 OR gates. The Signetics PLHS16L8A offers 100% functional compatibility with other PAL 16L8 devices. Specified at a tpd of 20ns (maximum), the PLHS16L8A is 20% faster than other "A" version PAL 16L8 devices. And, the PLHS16L8A consumes 20% less power than most other "A" speed 16L8 devices.

All AND gates are linked to 10 dedicated inputs, 6 bidirectional I/O and 2 dedicated outputs. On-chip buffers couple either true (I, B) or complement (I, B) input polarities to all AND gates. The 64 AND gates are separated into eight groups of eight product terms each. Within each group, seven of the AND terms are OR'ed together, while the eighth is used to control the 3-State function of the bidirectional I/O. All outputs (bidirectional and dedicated) are inverting.

In the virgin state, the AND array fuses are back-to-back CB-EB diode pairs, which act as open connections. Current is avalanched across individual diode pairs during fusing, which essentially short circuits the EB diode and provides

the connection for the associated product term.

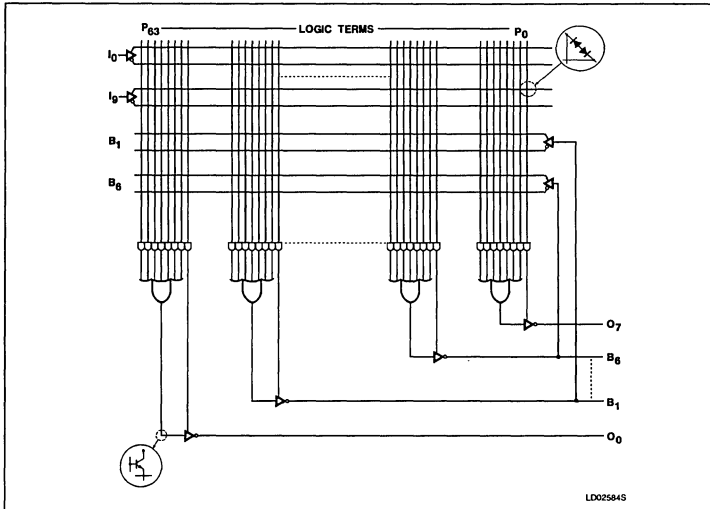
The PLHS16L8A is field-programmable, allowing the user to quickly generate custom patterns using standard programming equipment.

Order codes are listed in the Ordering Information Table.

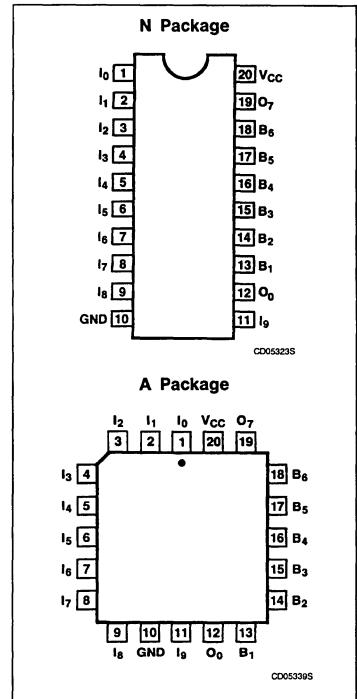
### FEATURES

- 20% faster than other "A" version PAL devices
  - $t_{pd} = 20\text{ns (MAX)}$
- $I_{CC}$  supply current: 155mA (worst-case)
- 100% functionally and pin-for-pin compatible with AmPAL16L8A, MMI PAL16L8A, TIBPAL16L8-25 and NSC PAL16L8A devices
- Field-programmable
- 10 dedicated inputs
- 8 outputs
  - 6 bidirectional I/O
  - 2 dedicated outputs
- Individual 3-State control of all outputs
- 64 AND gates/product terms
- Security Fuse

### FUNCTIONAL DIAGRAM



### PIN CONFIGURATIONS



3

### APPLICATIONS

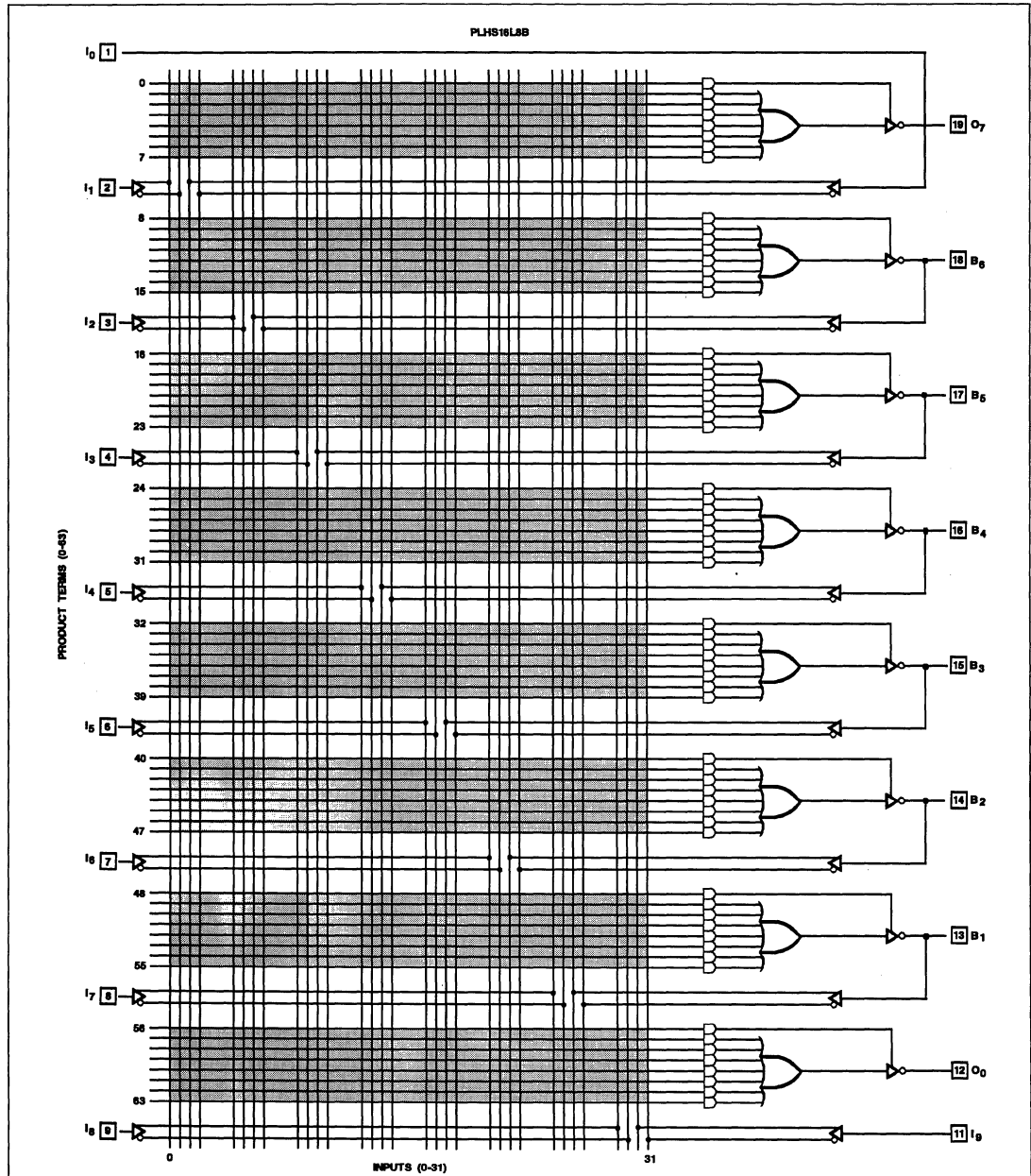
- 100% functional replacement for 20-pin 16L8 combinatorial PAL devices
- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping/decoding
- Multiplexing

® PAL is a registered trademark of Monolithic Memories, Inc., a wholly owned subsidiary of Advanced Micro Devices Inc.

# PAL<sup>®</sup>-Type Device

# PLHS16L8A

## FPLA LOGIC DIAGRAM



**NOTES:**  
 1. All unprogrammed or virgin "AND" gate locations are pulled to logic "1".  
 2. Programmable connections.

LD02626S

PAL<sup>®</sup>-Type Device

PLHS16L8A

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
20-pin Plastic DIP (300mil-wide)	PLHS16L8AN
20-pin Plastic Leaded Chip Carrier	PLHS16L8AA

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	-0.5 to +7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	-0.5 to +5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage	-0.5 to V <sub>CC</sub> Max	V <sub>DC</sub>
V <sub>OUTPRG</sub>	Output voltage (programming)	+21	V <sub>DC</sub>
I <sub>IN</sub>	Input current	-30 to +5	mA
I <sub>OUT</sub>	Output current	+100	mA
I <sub>OUTPRG</sub>	Output current (programming)	+170	mA
T <sub>A</sub>	Operating temperature range	0 to +75	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

PAL<sup>®</sup>-Type Device

PLHS16L8A

**DC ELECTRICAL CHARACTERISTICS**  $0^{\circ}\text{C} \leq T_A \leq 75^{\circ}\text{C}$ ,  $4.75\text{V} \leq V_{CC} \leq 5.25\text{V}$ 

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
$V_{IL}$	Low	$V_{CC} = \text{Min}$			+0.8	V
$V_{IH}$	High	$V_{CC} = \text{Max}$	+2.0			V
$V_{IC}$	Clamp	$V_{CC} = \text{Min}$ , $I_{IN} = -18\text{mA}$		-0.9	-1.2	V
<b>Output voltage</b>						
$V_{OL}$	Low	$V_{CC} = \text{Min}$ , $V_{IN} = V_{IH}$ or $V_{IL}$			+0.50	V
$V_{OH}$	High	$I_{OL} = +24\text{mA}$ $I_{OH} = -3.2\text{mA}$	+2.4	+3.5		V
<b>Input current</b>						
$I_{iL}$	Low	$V_{CC} = \text{Max}$		-20	-100	$\mu\text{A}$
$I_{iH}$	High	$V_{IN} = +0.40\text{V}$			+25	$\mu\text{A}$
$I_i$	High	$V_{IN} = +2.7\text{V}$ $V_{IN} = +5.5\text{V}$			+1.0	mA
<b>Output current</b>						
$I_{OZH}$	Output leakage	$V_{CC} = \text{Max}$ , $V_{IL} = 0.8\text{V}$ , $V_{IH} = 2.0\text{V}$			+100	$\mu\text{A}$
$I_{OZL}$	Output leakage	$V_{OUT} = +2.7\text{V}$			-50	$\mu\text{A}$
$I_{OS}$	Short circuit <sup>3</sup>	$V_{OUT} = +0.40\text{V}$ $V_{OUT} = +0.5\text{V}$	-30	-60	-90	mA
$I_{CC}$	$V_{CC}$ current	$V_{CC} = \text{Max}$ , All inputs = GND		100	155	mA
<b>Capacitance<sup>4</sup></b>						
$C_{IN}$	Input	$V_{CC} = +5\text{V}$		6		pF
$C_{OUT}$	I/O	$V_{IN} = 2.0\text{V}$ @ $f = 1\text{MHz}$ $V_{OUT} = 2.0\text{V}$ @ $f = 1\text{MHz}$		9		pF

**NOTES:**

1. Typical limits are at  $V_{CC} = 5.0\text{V}$  and  $T_A = +25^{\circ}\text{C}$ .

2. These are absolute values with respect to device ground and all overshoots due to system or tester noise are included.

3. Not more than one output should be tested at a time. Duration of the short circuit should not be more than one second.  $V_{OUT} = 0.5\text{V}$  has been chosen to avoid test problems caused by tester ground degradation.

4. These parameters are not 100% tested, but are periodically sampled.

PAL<sup>®</sup>-Type Device

PLHS16L8A

**AC ELECTRICAL CHARACTERISTICS**  $R_1 = 200\Omega$ ,  $R_2 = 390\Omega$ ,  $0^\circ\text{C} \leq T_A \leq +75^\circ\text{C}$ ,  $4.75\text{V} \leq V_{CC} \leq 5.25\text{V}$ 

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ	Max	
$t_{PD}$	Propagation delay	Input $\pm$	Output $\pm$	$C_L = 50\text{pF}$		14	20	ns
$t_{EA}$	Output enable	Input $\pm$	Output -	$C_L = 50\text{pF}$		14	20	ns
$t_{ER}$	Output disable	Input $\pm$	Output +	$C_L = 5\text{pF}$		14	20	ns

**NOTES:**

1. Typical limits are at  $V_{CC} = 5.0\text{V}$  and  $T_A = +25^\circ\text{C}$ .
2.  $t_{PD}$  is tested with switch  $S_1$  closed and  $C_L = 50\text{pF}$ .
3. For 3-State output; output enable times are tested with  $C_L = 50\text{pF}$  to the 1.5V level, and  $S_1$  is open for high-impedance to High tests and closed for high-impedance to Low tests. Output disable times are tested with  $C_L = 5\text{pF}$ . High-to-High impedance tests are made to an output voltage of  $V_{OH} = -0.5\text{V}$  with  $S_1$  open, and Low-to-High impedance tests are made to the  $V_{OL} = +0.5\text{V}$  level with  $S_1$  closed.

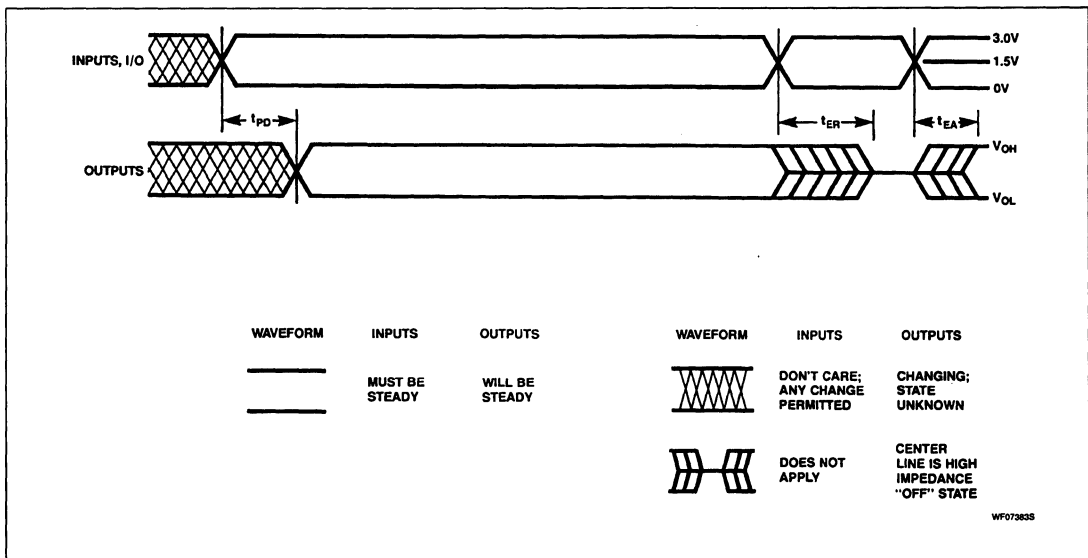
**VIRGIN STATE**

A factory shipped virgin device contains all fusible links open, such that:

1. All outputs are enabled.
2. All p-terms are enabled in the AND array.

**TIMING DEFINITIONS**

SYMBOL	PARAMETER
$t_{PD}$	Input to output propagation delay.
$t_{ER}$	Input to output disable (3-State) delay (Output Disable).
$t_{EA}$	Input to Output Enable delay (Output Enable).

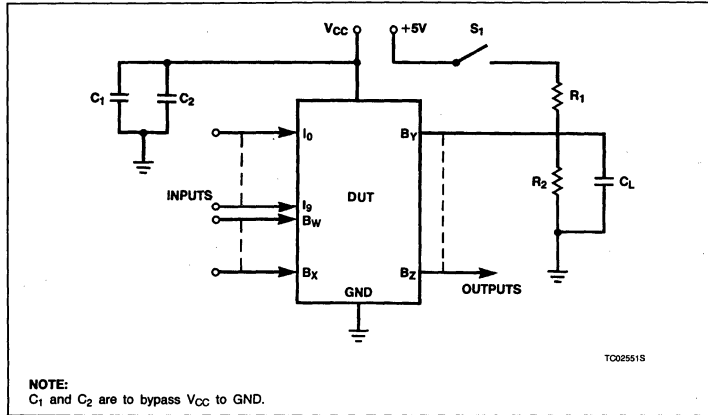
**TIMING DIAGRAMS**



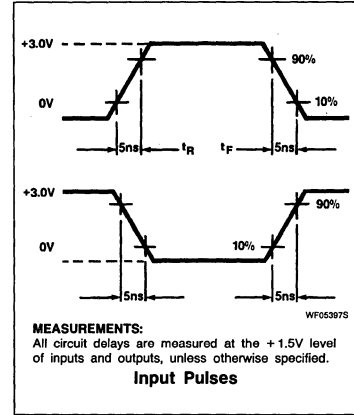
# PAL<sup>®</sup>-Type Device

# PLHS16L8A

## AC TEST LOAD CIRCUIT



## VOLTAGE WAVEFORMS



## LOGIC PROGRAMMING

PLHS16L8A logic designs can be generated using any commercially available, JEDEC standard design software that supports the 16L8 architecture. No JEDEC fuse map conversion or translation is necessary when using the PLHS16L8A.

PLHS16L8A designs can also be generated using the program table format, detailed on the following page. This program table entry (PTE) format is supported on the Signetics AMAZE PLD design software. AMAZE is available free of charge to qualified users.

To implement the desired logic functions, each logic variable (I, B, P and D) from the logic equations is assigned a symbol. TRUE (High), COMPLEMENT (Low), DON'T CARE and INACTIVE symbols are defined below.

## "AND" ARRAY — (I, B)

<p style="text-align: center;">TC02861S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>INACTIVE<sup>2</sup></td><td>O</td></tr> </table>	STATE	CODE	INACTIVE <sup>2</sup>	O	<p style="text-align: center;">TC02861S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>TRUE</td><td>H</td></tr> </table>	STATE	CODE	TRUE	H	<p style="text-align: center;">TC02871S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>COMPLEMENT</td><td>L</td></tr> </table>	STATE	CODE	COMPLEMENT	L	<p style="text-align: center;">TC02841S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>DON'T CARE<sup>1</sup></td><td>-</td></tr> </table>	STATE	CODE	DON'T CARE <sup>1</sup>	-
STATE	CODE																		
INACTIVE <sup>2</sup>	O																		
STATE	CODE																		
TRUE	H																		
STATE	CODE																		
COMPLEMENT	L																		
STATE	CODE																		
DON'T CARE <sup>1</sup>	-																		

**NOTES:**

1. This is the initial state of all diodes pairs.
2. All unused product terms must be programmed with all pairs of diodes in the INACTIVE state (all fuses on an unused p-term must be programmed).

# PAL<sup>®</sup>-Type Device

PLHS16L8A

## PROGRAM TABLE

**Notes**

- The FPLA is shipped with all fuses open.
- Unused I and B bits in the AND array exist as Don't Care (-) in the virgin state.
- All p-terms are active until programmed otherwise.
- All unused product terms must be programmed with all pairs of fuses in the INACTIVE state (all fuses on an unused p-term must be programmed).
- Data cannot be entered into the OR array field due to the fixed nature of the device architecture.

**OR (FIXED)**

DIRECTION	D
ACTIVE OUTPUT	A
NOT USED	/

**AND**

INACTIVE	O
I, B	H
i, b	L
DONT CARE	-

CUSTOMER NAME \_\_\_\_\_

PURCHASE ORDER # \_\_\_\_\_

SIGNETICS DEVICE # \_\_\_\_\_ CF (XXXX)

CUSTOMER SYMBOLIZED PART # \_\_\_\_\_

TOTAL NUMBER OF PARTS \_\_\_\_\_

PROGRAM TABLE # \_\_\_\_\_ REV \_\_\_\_\_ DATE \_\_\_\_\_

T M R M M	AND																OR (FIXED)							
	INPUT (I)								INPUTS (B)								OUTPUTS (B, O)							
	9	8	7	6	5	4	3	2	1	0	6	5	4	3	2	1	7	6	5	4	3	2	1	0
0																	D	A	A	A	A	A	A	A
1																	D	A	A	A	A	A	A	A
2																	D	A	A	A	A	A	A	A
3																	D	A	A	A	A	A	A	A
4																	D	A	A	A	A	A	A	A
5																	D	A	A	A	A	A	A	A
6																	D	A	A	A	A	A	A	A
7																	D	A	A	A	A	A	A	A
8																	D	A	A	A	A	A	A	A
9																	D	A	A	A	A	A	A	A
10																	D	A	A	A	A	A	A	A
11																	D	A	A	A	A	A	A	A
12																	D	A	A	A	A	A	A	A
13																	D	A	A	A	A	A	A	A
14																	D	A	A	A	A	A	A	A
15																	D	A	A	A	A	A	A	A
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39																	D	A	A	A	A	A	A	A
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61																	D	A	A	A	A	A	A	A
62																	D	A	A	A	A	A	A	A
63																	D	A	A	A	A	A	A	A
PN	11	9	8	7	6	5	4	3	2	1	18	17	16	15	14	13	19	18	17	16	15	14	13	12
VARIABLE NAME																								

3

# PLHS16L8B PAL<sup>®</sup>-Type Device

Signetics Programmable Logic  
Product Specification

## Application Specific Products ● Series 20

### DESCRIPTION

The PLHS16L8B is a very high-speed "B" version PAL<sup>®</sup>-type device. The sum of products (AND-OR) architecture is comprised of 64 AND gates and 8 OR gates. The Signetics PLHS16L8B offers 100% functional compatibility with other PAL 16L8 devices. Specified at 155mA I<sub>CC</sub> (maximum), the PLHS16L8B consumes 20% less power than other "B" version PAL 16L8 devices.

All AND gates are linked to 10 dedicated inputs, 6 bidirectional I/O and 2 dedicated outputs. On-chip buffers couple either true (I, B) or complement (I, B) input polarities to all AND gates. The 64 AND gates are separated into eight groups of eight product terms each. Within each group, seven of the AND terms are OR'ed together, while the eighth is used to control the 3-State function of the bidirectional I/O. All outputs (bidirectional and dedicated) are inverting.

In the virgin state, the AND array fuses are back-to-back CB-EB diode pairs which act as open connections. Current is avalanched across individual diode pairs during fusing, which essentially short circuits the EB diode and provides the connection for the associated product term.

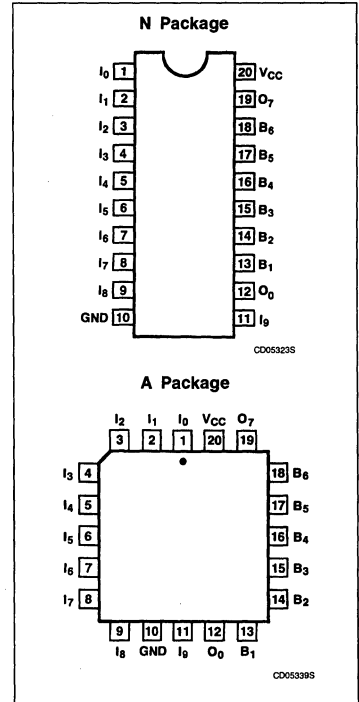
The PLHS16L8B is field-programmable, allowing the user to quickly generate custom patterns using standard programming equipment.

Order codes are listed in the Ordering Information Table.

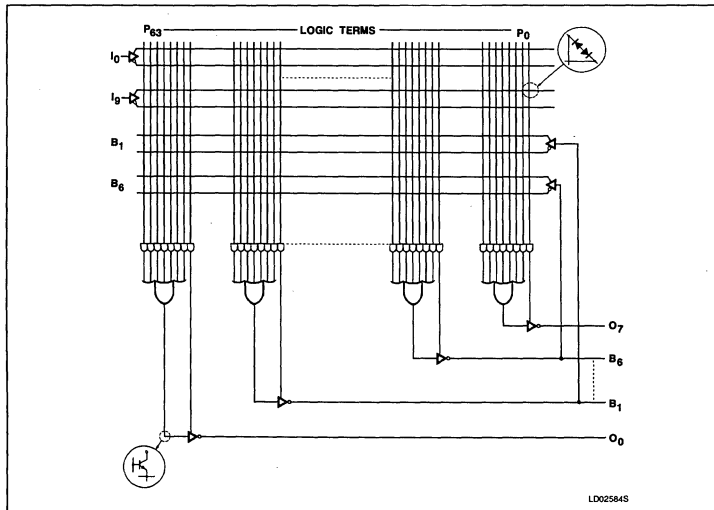
### FEATURES

- Consumes 20% less power than other "B" version PAL devices
  - 155mA I<sub>CC</sub> (worst-case)
- I/O propagation delay: 15ns (MAX)
- 100% functionally and pin-for-pin compatible with AmpAL16L8B, MMI PAL16L8B, TIBPAL16L8-15 and NSC PAL16L8B devices
- Field-programmable
- 10 dedicated inputs
- 8 outputs
  - 6 bidirectional I/O
  - 2 dedicated outputs
- Individual 3-State control of all outputs
- 64 AND gates/product terms
- Security Fuse

### PIN CONFIGURATIONS



### FUNCTIONAL DIAGRAM



### APPLICATIONS

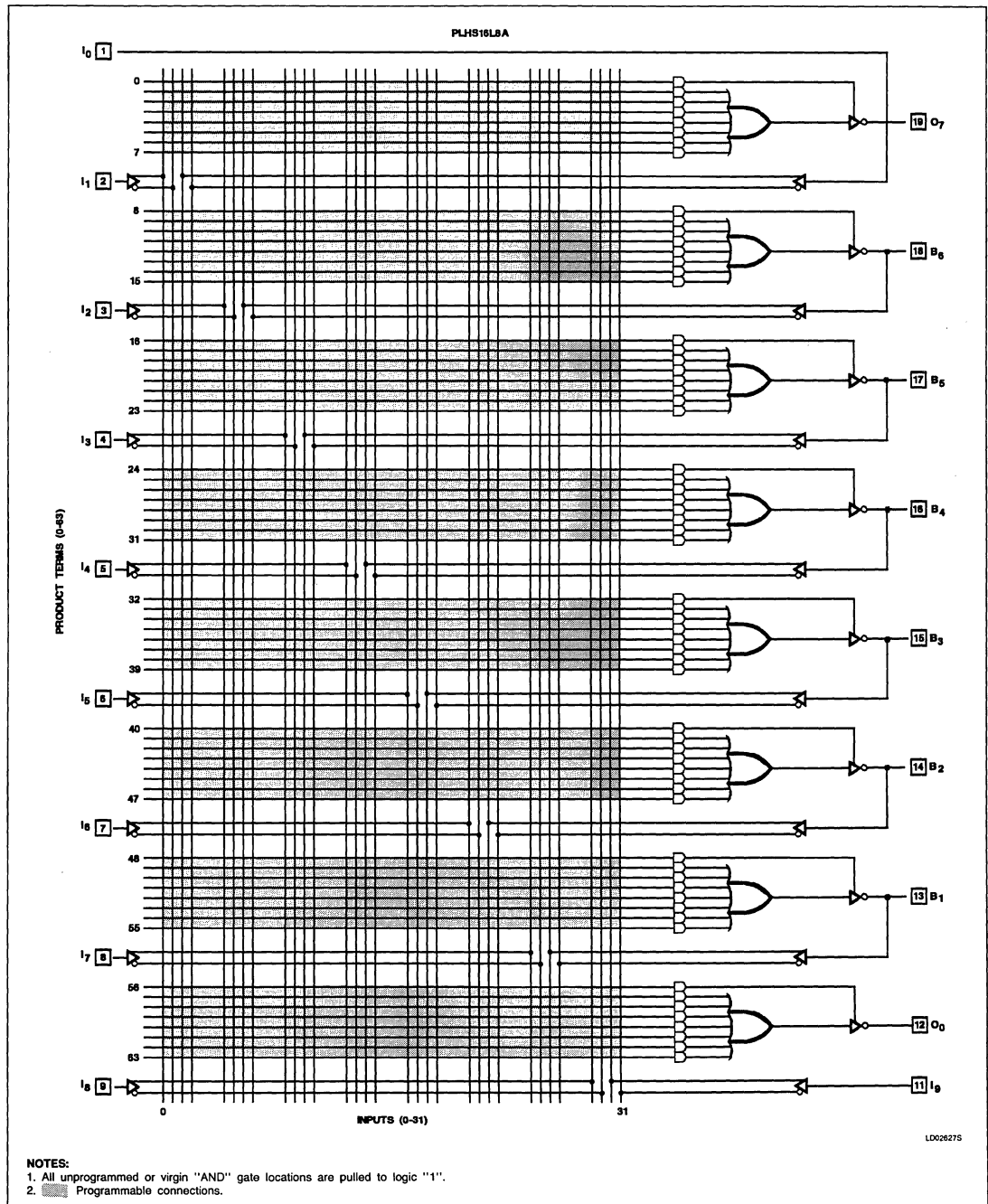
- 100% functional replacement for 20-pin 16L8 combinatorial PAL devices
- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping/decoding
- Multiplexing

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# PAL<sup>®</sup>-Type Device

# PLHS16L8B

## FPLA LOGIC DIAGRAM



**NOTES:**

1. All unprogrammed or virgin "AND" gate locations are pulled to logic "1".
2. Programmable connections.

PAL<sup>®</sup>-Type Device

PLHS16L8B

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
20-pin Plastic DIP (300mil-wide)	PLHS16L8BN
20-pin Plastic Leaded Chip Carrier	PLHS16L8BA

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	-0.5 to +7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	-0.5 to +5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage	-0.5 to V <sub>CC</sub> Max	V <sub>DC</sub>
V <sub>OUTPRG</sub>	Output voltage (programming)	+21	V <sub>DC</sub>
I <sub>IN</sub>	Input current	-30 to +5	mA
I <sub>OUT</sub>	Output current	+100	mA
I <sub>OUTPRG</sub>	Output current (programming)	+170	mA
T <sub>A</sub>	Operating temperature range	0 to +75	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

PAL<sup>®</sup>-Type Device

PLHS16L8B

**DC ELECTRICAL CHARACTERISTICS**  $0^{\circ}\text{C} \leq T_A \leq 75^{\circ}\text{C}$ ,  $4.75\text{V} \leq V_{CC} \leq 5.25\text{V}$ 

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
$V_{IL}$	Low	$V_{CC} = \text{Min}$			+0.8	V
$V_{IH}$	High	$V_{CC} = \text{Max}$	+2.0			V
$V_{IC}$	Clamp	$V_{CC} = \text{Min}$ , $I_{IN} = -18\text{mA}$		-0.9	-1.2	V
<b>Output voltage</b>						
$V_{OL}$	Low	$V_{CC} = \text{Min}$ , $V_{IN} = V_{IH}$ or $V_{IL}$			+0.50	V
$V_{OH}$	High	$I_{OL} = +24\text{mA}$ $I_{OH} = -3.2\text{mA}$	+2.4	+3.5		V
<b>Input current</b>						
$I_{IL}$	Low	$V_{CC} = \text{Max}$		-20	-100	$\mu\text{A}$
$I_{IH}$	High	$V_{IN} = +0.40\text{V}$			+25	$\mu\text{A}$
$I_I$	High	$V_{IN} = +2.7\text{V}$ $V_{IN} = +5.5\text{V}$			+1.0	$\text{mA}$
<b>Output current</b>						
$I_{OZH}$	Output leakage	$V_{CC} = \text{Max}$ , $V_{IL} = 0.8\text{V}$ , $V_{IH} = 2.0\text{V}$			+100	$\mu\text{A}$
$I_{OZL}$	Output leakage	$V_{OUT} = +2.7\text{V}$			-50	$\mu\text{A}$
$I_{OS}$	Short circuit <sup>3</sup>	$V_{OUT} = +0.40\text{V}$ $V_{OUT} = +0.5\text{V}$	-30	-60	-90	$\text{mA}$
$I_{CC}$	$V_{CC}$ current	$V_{CC} = \text{Max}$ , All inputs = GND		100	155	$\text{mA}$
<b>Capacitance<sup>4</sup></b>						
$C_{IN}$	Input	$V_{CC} = +5\text{V}$		6		pF
$C_{OUT}$	I/O	$V_{IN} = 2.0\text{V}$ @ $f = 1\text{MHz}$ $V_{OUT} = 2.0\text{V}$ @ $f = 1\text{MHz}$		9		pF

**NOTES:**

1. Typical limits are at  $V_{CC} = 5.0\text{V}$  and  $T_A = +25^{\circ}\text{C}$ .
2. These are absolute values with respect to device ground and all overshoots due to system or tester noise are included.
3. Not more than one output should be tested at a time. Duration of the short circuit should not be more than one second.  $V_{OUT} = 0.5\text{V}$  has been chosen to avoid test problems caused by tester ground degradation.
4. These parameters are not 100% tested, but are periodically sampled.

# PAL<sup>®</sup>-Type Device

PLHS16L8B

## AC ELECTRICAL CHARACTERISTICS $R_1 = 200\Omega, R_2 = 390\Omega, 0^\circ\text{C} \leq T_A \leq +75^\circ\text{C}, 4.75\text{V} \leq V_{CC} \leq 5.25\text{V}$

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ	Max	
$t_{PD}$	Propagation delay	Input $\pm$	Output $\pm$	$C_L = 50\text{pF}$		12	15	ns
$t_{EA}$	Output enable	Input $\pm$	Output -	$C_L = 50\text{pF}$		12	15	ns
$t_{ER}$	Output disable	Input $\pm$	Output +	$C_L = 5\text{pF}$		12	15	ns

**NOTES:**

1. Typical limits are at  $V_{CC} = 5.0\text{V}$  and  $T_A = +25^\circ\text{C}$ .
2.  $t_{PD}$  is tested with switch  $S_1$  closed and  $C_L = 50\text{pF}$ .
3. For 3-State output; output enable times are tested with  $C_L = 50\text{pF}$  to the 1.5V level, and  $S_1$  is open for high-impedance to High tests and closed for high-impedance to Low tests. Output disable times are tested with  $C_L = 5\text{pF}$ . High-to-High impedance tests are made to an output voltage of  $V_{OH} = -0.5\text{V}$  with  $S_1$  open, and Low-to-High impedance tests are made to the  $V_{OL} = +0.5\text{V}$  level with  $S_1$  closed.

### VIRGIN STATE

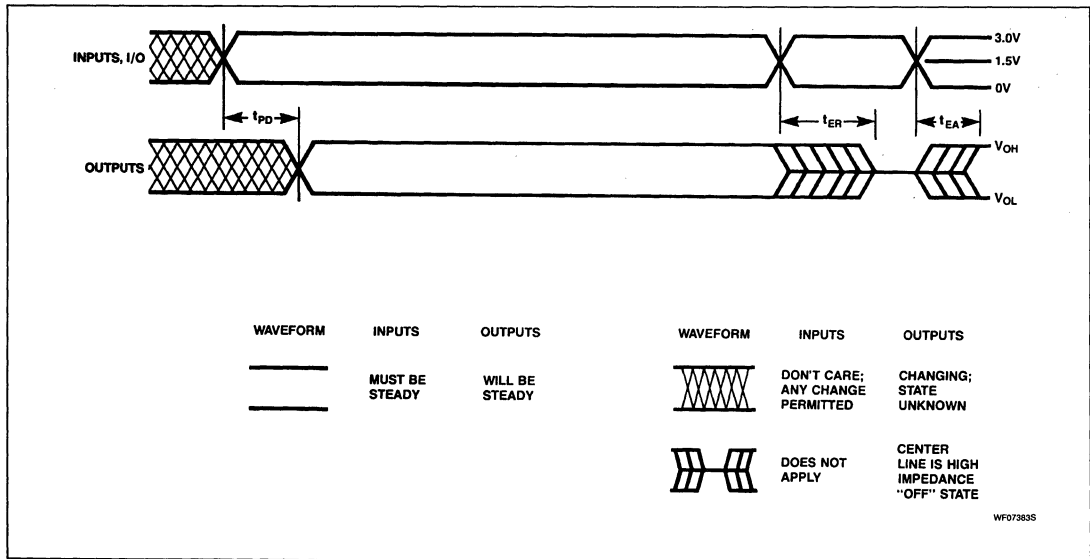
A factory shipped virgin device contains all fusible links open, such that:

1. All outputs are enabled.
2. All p-terms are enabled in the AND array.

### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Input to output propagation delay.
$t_{ER}$	Input to output disable (3-State) delay (Output Disable).
$t_{EA}$	Input to Output Enable delay (Output Enable).

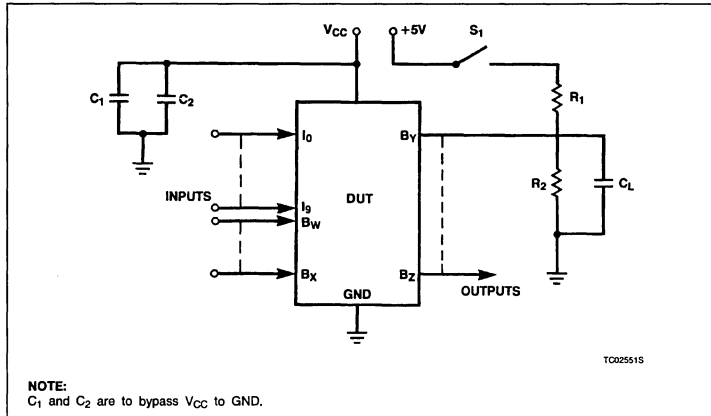
### TIMING DIAGRAMS



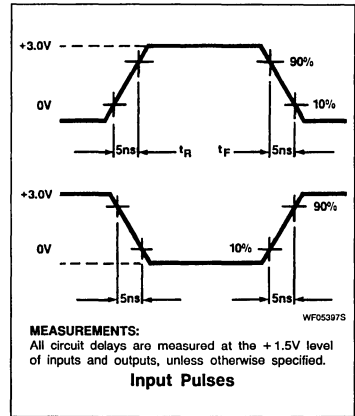
# PAL<sup>®</sup>-Type Device

# PLHS16L8B

## AC TEST LOAD CIRCUIT



## VOLTAGE WAVEFORMS



3

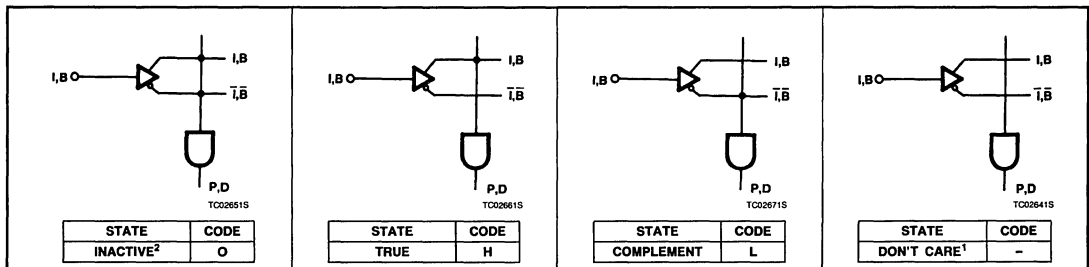
## LOGIC PROGRAMMING

PLHS16L8B logic designs can be generated using any commercially available, JEDEC standard design software that supports the 16L8 architecture. No JEDEC fuse map conversion or translation is necessary when using the PLHS16L8B.

PLHS16L8B designs can also be generated using the program table format, detailed on the following page. This program table entry (PTE) format is supported on the Signetics AMAZE PLD design software. AMAZE is available free of charge to qualified users.

To implement the desired logic functions, each logic variable (I, B, P and D) from the logic equations is assigned a symbol. TRUE (High), COMPLEMENT (Low), DON'T CARE and INACTIVE symbols are defined below.

## "AND" ARRAY — (I, B)



**NOTES:**

1. This is the initial state of all diodes pairs.
2. All unused product terms must be programmed with all pairs of diodes in the INACTIVE state (all fuses on an unused p-term must be programmed).



# PAL<sup>®</sup>-Type Device

# PLHS16L8B

## PROGRAM TABLE

<p><b>Notes</b></p> <ol style="list-style-type: none"> <li>The FPLA is shipped with all links open.</li> <li>Unused I and B bits in the AND array exist as Don't Care (-) in the origin state.</li> <li>All p-terms are active until programmed otherwise.</li> <li>All unused product terms must be programmed with all pairs of fuses in the INACTIVE state (all fuses on an unused p-term must be programmed).</li> <li>Data cannot be entered into the OR array field due to the fixed nature of the device architecture.</li> </ol>		<b>AND</b>										<b>OR (FIXED)</b>													
		<b>INPUT (I)</b>										<b>INPUTS (B)</b>					<b>OUTPUTS (B, O)</b>								
		9	8	7	6	5	4	3	2	1	0	6	5	4	3	2	1	7	6	5	4	3	2	1	0
T E R M																									
0																	D								
1																	A								
2																	A								
3																	A								
4																	A								
5																	A								
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62																	A								
63																	A								
PIN	11	9	8	7	6	5	4	3	2	1	18	17	16	15	14	13	19	18	17	16	15	14	13	12	
VARIABLE NAME																									
CUSTOMER NAME																									
PURCHASE ORDER #																									
SIGNETICS DEVICE #																									
CUSTOMER SYMBOLIZED PART #																									
TOTAL NUMBER OF PARTS																									
PROGRAM TABLE #																									
REV																									
DATE																									

T802024S

## Application Specific Products

- Series 20

### FEATURES

- **Ultra high-speed:**
  - $t_{PD} = 10\text{ns}$
  - $f_{MAX} = 55.5\text{MHz}$  (with feedback)
  - $t_{S} = 10\text{ns}$  (worst case)
  - $t_{CKO} = 8\text{ns}$  (worst case)
- **100% functionally and pin-for-pin compatible with industry standard 20-pin PAL ICs**
- **Power-up reset function to enhance state machine design and testability**
- **Design support provided via AMAZE and other CAD tools for Series 20 PAL devices**
- **Field-programmable on industry standard programmers**
- **Security fuse**
- **Individual 3-State control of all outputs**

### DESCRIPTION

The Signetics PLUS16XXD family is an ultra high-speed 10ns version of existing Series 20 PAL devices.

The PLUS16XXD family is 100% functional and pin-compatible with the 16L8, 16R8, 16R6, and 16R4 Series devices.

The sum of products (AND/OR) architecture is comprised of 64 AND gates and 8 OR gates. Multiple bidirectional pins provide variable input/output pin ratios. Individual 3-State control of all outputs and registers with feedback (R8, R6, R4) is also provided.

The PLUS16R8D, R6D, and R4D have D-type flip-flops which are loaded on the Low-to-High transition of the clock input.

In order to facilitate state machine design and testing, a power-up reset function has been incorporated into these devices to reset all internal registers to active-Low after a specific period of time.

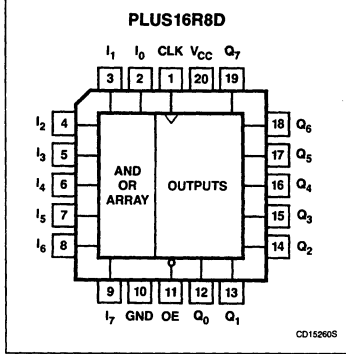
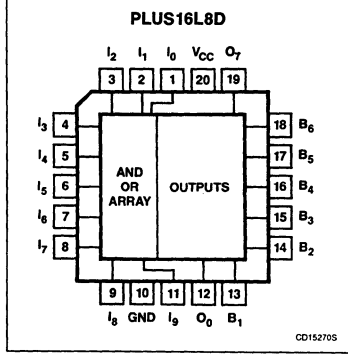
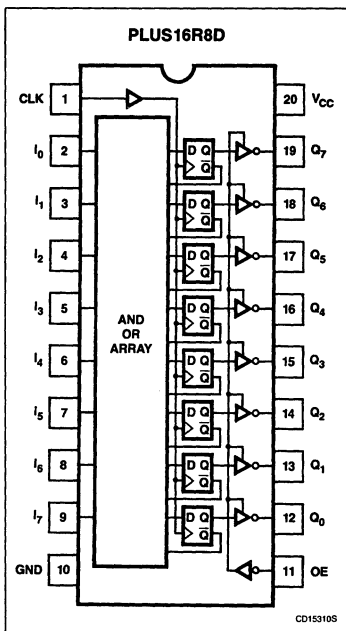
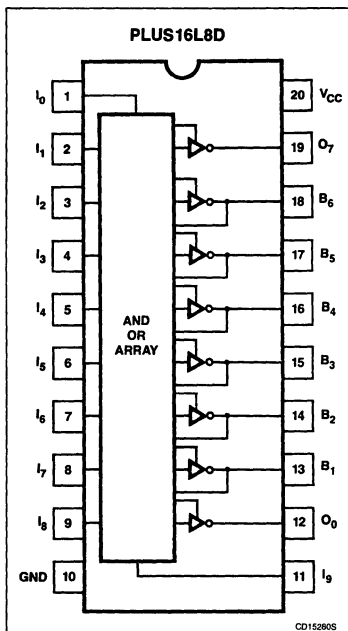
The Signetics State-of-the-Art oxide isolation Bipolar fabrication process is employed to achieve high-performance operation.

The PLUS16XXD family of devices are field programmable, enabling the user to quickly generate custom patterns using standard programming equipment.

DEVICE NUMBER	DEDICATED INPUTS	COMBINATORIAL OUTPUTS	REGISTERED OUTPUTS	$t_{PD}$	$I_{CC}$	$f_{MAX}$ WITHOUT FEEDBACK	$f_{MAX}$ WITH FEEDBACK
PLUS16L8D	10	8(6 I/O)	0	10ns	180mA		
PLUS16R8D	8	0	8		180mA	62.5MHz	55.5MHz
PLUS16R6D	8	2 I/O	6	10ns	180mA	62.5MHz	55.5MHz
PLUS16R4D	8	4 I/O	4	10ns	180mA	62.5MHz	55.5MHz

PAL<sup>®</sup>-Type Devices

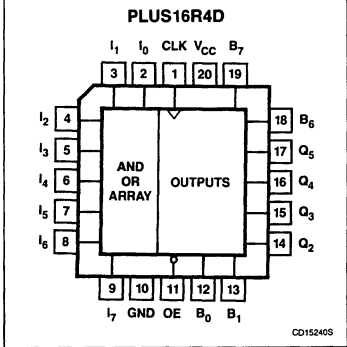
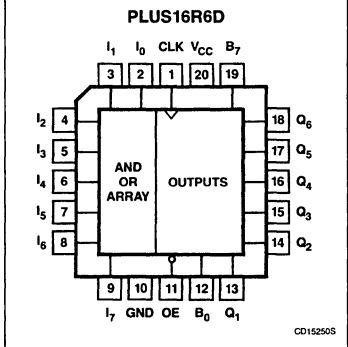
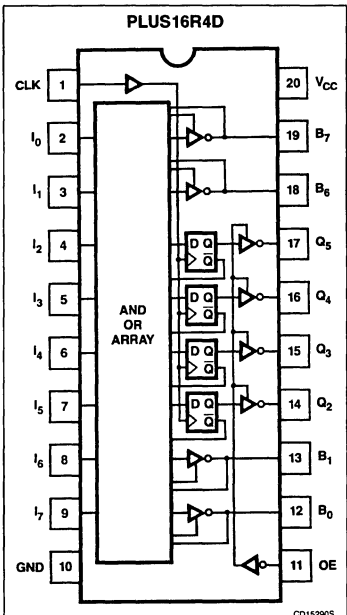
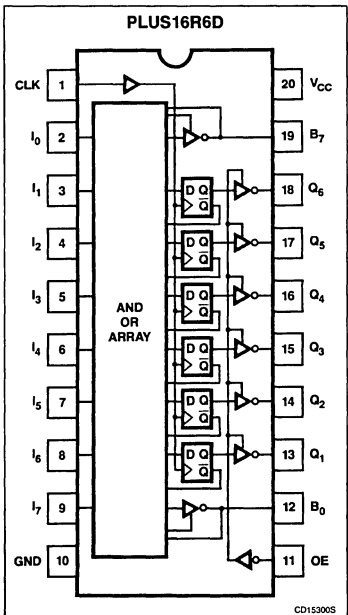
PLUS16R8D Series



PAL<sup>®</sup>-Type Devices

PLUS16R8D Series

3



## PLHS18P8A PAL<sup>®</sup>-Type Device

Signetics Programmable Logic  
Product Specification

### Application Specific Products • Series 20

#### DESCRIPTION

The PLHS18P8A is a two-level logic element consisting of 72 AND gates and 8 OR gates with fusible connections for programming I/O polarity and direction.

All AND gates are linked to 10 inputs (I) and 8 bidirectional I/O lines (B). These yield variable I/O gate configurations via 8 direction control gates, ranging from 18 inputs to 8 outputs.

On-chip T/C buffers couple either True (I, B) or Complement (I, B) input polarities to all AND gates. The 72 AND gates are separated into 8 groups of 9 each. Each group of 9 is associated with one bidirectional pin. In each group, eight of the AND terms are ORed together, while the ninth is used to establish I/O direction. All outputs are individually programmable via an Ex-OR gate to allow implementation of AND/OR or NAND/NOR logic functions.

In the virgin state, the AND array fuses are back-to-back CB-EB diode pairs which will act as open connections. Current is avalanched across individual diode pairs during fusing, which essentially short circuits the EB diode and provides the connection for the associated product term.

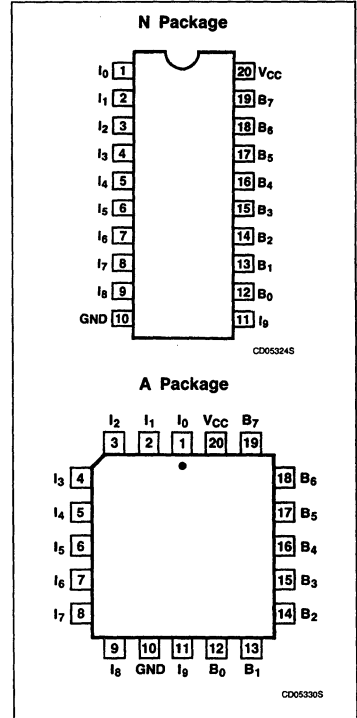
The PLHS18P8A is field-programmable, allowing the user to quickly generate custom pattern using standard programming equipment.

Order codes are listed in the Ordering Information Table.

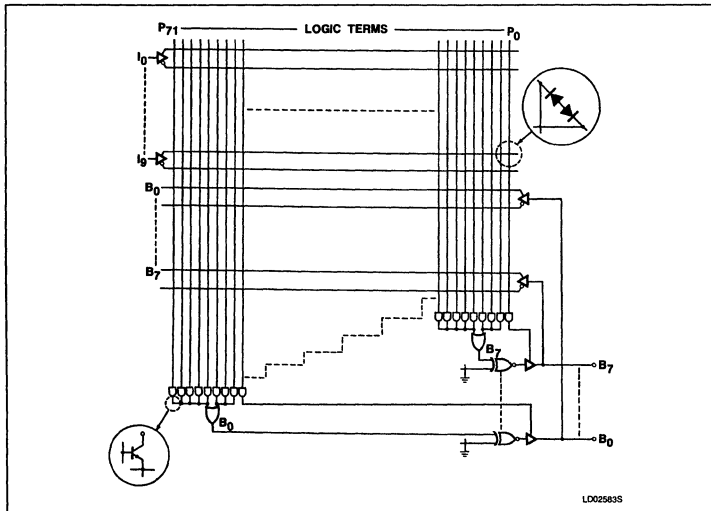
#### FEATURES

- 100% functionally compatible with AmPAL18P8A and all 16L8, 16P8, 16H8, 16L2, 16H2, 14L4, 14H4, 12L6, 12H6, 10L8, 10H8, 16LD8 and 16HD8 PAL type products
- Field-Programmable
- 10 inputs
- 8 bidirectional I/O lines
- 72 AND gates/product terms - configured into eight groups of nine
- Programmable output polarity (3-State output)
- I/O propagation delay: 20ns (max)
- Power dissipation: 500mW (typ)
- TTL compatible
- Security Fuse

#### PIN CONFIGURATIONS



#### FUNCTIONAL DIAGRAM



#### APPLICATIONS

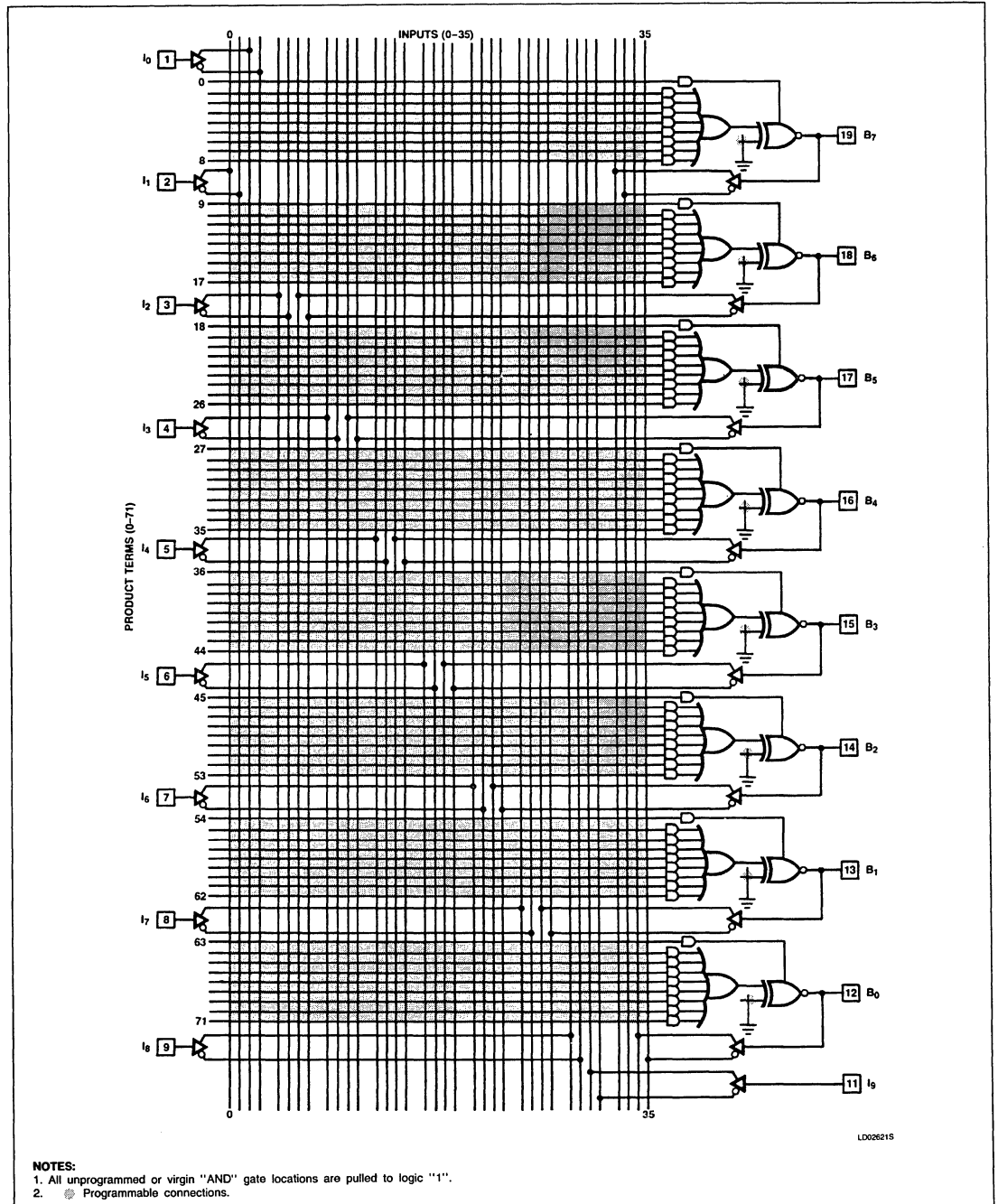
- 100% functional replacement for all 20-pin combinatorial PAL devices
- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping
- Multiplexing

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PAL<sup>®</sup>-Type Device

PLHS18P8A

FPLA LOGIC DIAGRAM



3

PAL<sup>®</sup>-Type Device

PLHS18P8A

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
20-pin Plastic DIP (300mil-wide)	PLHS18P8AN
20-pin Plastic Leaded Chip Carrier	PLHS18P8AA

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	-0.5 to +7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	-0.5 to +5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage	-0.5 to V <sub>CC</sub> Max	V <sub>DC</sub>
V <sub>OUTPRG</sub>	Output voltage (programming)	+21	V <sub>DC</sub>
I <sub>IN</sub>	Input current	-30 to +5	mA
I <sub>OUT</sub>	Output current	+100	mA
I <sub>OUTPRG</sub>	Output current (programming)	+170	mA
T <sub>A</sub>	Operating temperature range	0 to +75	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

## NOTE:

- Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

PAL<sup>®</sup>-Type Device

PLHS18P8A

**DC ELECTRICAL CHARACTERISTICS**  $0^{\circ}\text{C} \leq T_A \leq 75^{\circ}\text{C}$ ,  $4.75\text{V} \leq V_{CC} \leq 5.25\text{V}$ 

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IL</sub> V <sub>IH</sub> V <sub>I</sub>	Low High Clamp	V <sub>CC</sub> = Min V <sub>CC</sub> = Max V <sub>CC</sub> = Min, I <sub>IN</sub> = -18mA	+2.0	-0.9	+0.8 -1.2	V V V
<b>Output voltage</b>						
V <sub>OL</sub> V <sub>OH</sub>	Low High	V <sub>CC</sub> = Min, V <sub>IN</sub> = V <sub>IH</sub> or V <sub>IL</sub> I <sub>OL</sub> = +24mA I <sub>OH</sub> = -3.2	+2.4	+3.5	+0.50	V V
<b>Input current</b>						
I <sub>IL</sub> I <sub>IH</sub> I <sub>I</sub>	Low High High	V <sub>CC</sub> = Max V <sub>IN</sub> = +0.40V V <sub>IN</sub> = +2.7V V <sub>IN</sub> = +5.5V		-20	-100 +25 +1.0	μA μA mA
<b>Output current</b>						
I <sub>OZH</sub> I <sub>OZL</sub> I <sub>SC</sub>	Output leakage Output leakage Short circuit <sup>3</sup>	V <sub>CC</sub> = Max, V <sub>IL</sub> = 0.8V, V <sub>IH</sub> = 2.0V V <sub>OUT</sub> = +2.7V V <sub>OUT</sub> = +0.40V V <sub>OUT</sub> = +0.5V	-25	-60	+100 -250 -90	μA μA mA
I <sub>CC</sub>	V <sub>CC</sub> current	V <sub>CC</sub> = Max, All inputs = GND		100	155	mA
<b>Capacitance<sup>4</sup></b>						
C <sub>IN</sub> C <sub>OUT</sub>	Input I/O	V <sub>CC</sub> = +5V V <sub>IN</sub> = 2.0V @ f = 1MHz V <sub>OUT</sub> = 2.0V @ f = 1MHz		6 9		pF pF

**NOTES:**

1. Typical limits are at V<sub>CC</sub> = 5.0V and T<sub>A</sub> = +25°C.
2. These are absolute values with respect to device ground and all overshoots due to system or tester noise are included.
3. Not more than one output should be tested at a time. Duration of the short circuit should not be more than one second. V<sub>OUT</sub> = 0.5V has been chosen to avoid test problems caused by tester ground degradation.
4. These parameters are not 100% tested, but are periodically sampled.

3



# PAL<sup>®</sup>-Type Device

# PLHS18P8A

## AC ELECTRICAL CHARACTERISTICS $R_1 = 200\Omega$ , $R_2 = 390\Omega$ , $0^\circ\text{C} \leq T_A \leq +75^\circ\text{C}$ , $4.75\text{V} \leq V_{CC} \leq 5.25\text{V}$

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ	Max	
$t_{PD}$	Propagation delay	Input $\pm$	Output $\pm$	$C_L = 50\text{pF}$		14	20	ns
$t_{EA}$	Output enable	Input $\pm$	Output -	$C_L = 50\text{pF}$		14	20	ns
$t_{ER}$	Output disable	Input $\pm$	Output +	$C_L = 5\text{pF}$		14	20	ns

**NOTES:**

1. Typical limits are at  $V_{CC} = 5.0\text{V}$  and  $T_A = +25^\circ\text{C}$ .
2.  $T_{PD}$  is tested with switch  $S_1$  closed and  $C_L = 50\text{pF}$ .
3. For 3-State output; output enable times are tested with  $C_L = 50\text{pF}$  to the 1.5V level, and  $S_1$  is open for high-impedance to High tests and closed for high-impedance to Low tests. Output disable times are tested with  $C_L = 5\text{pF}$ . High-to-High impedance tests are made to an output voltage of  $V_{OH} = -0.5\text{V}$  with  $S_1$  open, and Low-to-High impedance tests are made to the  $V_{OL} = +0.5\text{V}$  level with  $S_1$  closed.

### VIRGIN STATE

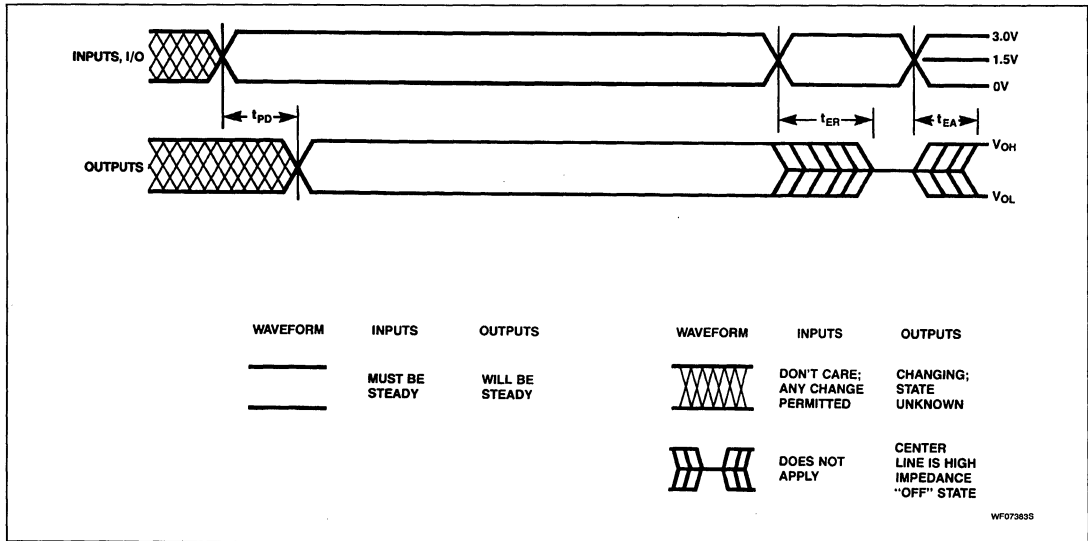
A factory shipped virgin device contains all fusible links open, such that:

1. All outputs are at "H" polarity.
2. All outputs are enabled.
3. All p-terms are enabled.

### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Input to output propagation delay.
$t_{ER}$	Input to output disable (3-State) delay (Output Disable).
$t_{EA}$	Input to Output Enable delay (Output Enable).

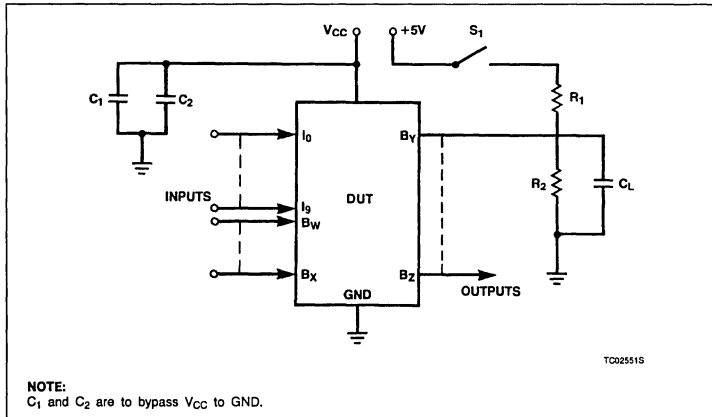
### TIMING DIAGRAMS



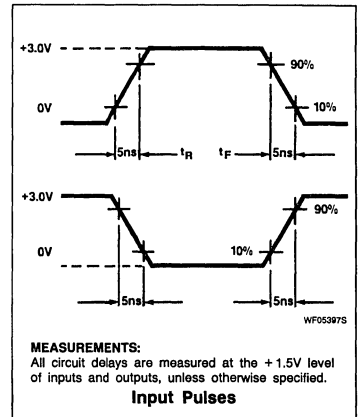
# PAL<sup>®</sup>-Type Device

# PLHS18P8A

## AC TEST LOAD CIRCUIT



## VOLTAGE WAVEFORMS



3

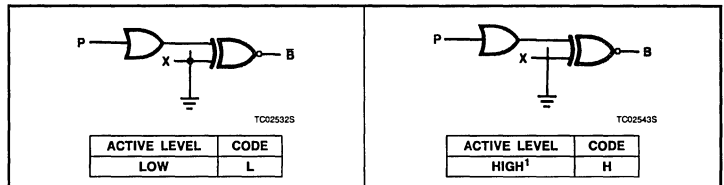
## LOGIC PROGRAMMING

PLHS18P8A logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

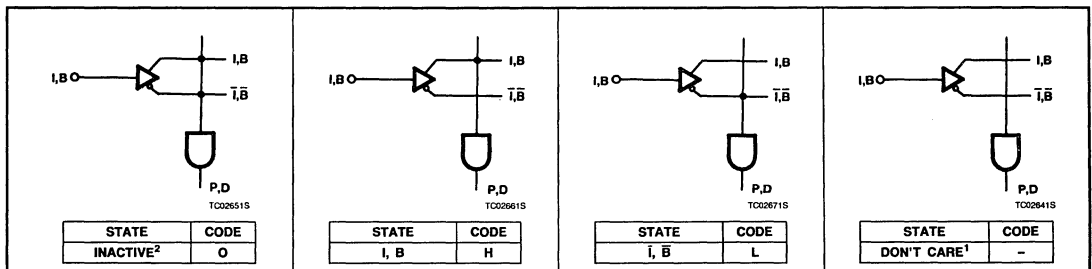
PLHS18P8A logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

## OUTPUT POLARITY — (B)



## "AND" ARRAY — (I, B)



**NOTES:**

1. This is the initial state of all link pairs.
2. All unused product terms must be programmed with all pairs of fuses in the INACTIVE state (all fuses on an unused p-term must be programmed).

PAL®-Type Device

PLHS18P8A

PROGRAM TABLE

**Notes:**  
 1. The PFA is applied with all bits open.  
 2. Unused P-terms (B bits) in the AND array exist as Don't Care (-) in the virgin state.  
 3. All P-terms are active until programmed otherwise.  
 4. All unused product terms must be programmed in the virgin state (all based on an unused P-term must be programmed).  
 5. Data cannot be entered into the OR array field due to the fixed nature of the device architecture.

T E R M	AND																POLARITY											
	I								B (I)								OR (FIXED)						B (O)					
	9	8	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0		
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VARIABLE NAME	11	9	8	7	6	5	4	3	2	1	19	18	17	16	15	14	13	12	19	18	17	16	15	14	13	12		

CUSTOMER NAME \_\_\_\_\_

PURCHASE ORDER # \_\_\_\_\_

SIGNETICS DEVICE # \_\_\_\_\_ CF (XXXX)

CUSTOMER SYMBOLIZED PART # \_\_\_\_\_

TOTAL NUMBER OF PARTS \_\_\_\_\_

PROGRAM TABLE # \_\_\_\_\_ REV \_\_\_\_\_ DATE \_\_\_\_\_

CONTROL	P(O) (POL)		OR (FIXED)	
AND	L(R) (L(R))		DIRECTION	
	H	L	ACTIVE OUTPUT	A
	LOW		NOT USED	

TB02023S

### Application Specific Products • Series 20

#### DESCRIPTION

The PLHS18P8B is a two-level logic element consisting of 72 AND gates and 8 OR gates with fusible connections for programming I/O polarity and direction.

All AND gates are linked to 10 inputs (I) and 8 bidirectional I/O lines (B). These yield variable I/O gate configurations via 8 direction control gates, ranging from 18 inputs to 8 outputs.

On-chip T/C buffers couple either True (I, B) or Complement (I, B) input polarities to all AND gates. The 72 AND gates are separated into 8 groups of 9 each. Each group of 9 is associated with one bidirectional pin. In each group, eight of the AND terms are ORed together, while the ninth is used to establish I/O direction. All outputs are individually programmable via an Ex-OR gate to allow implementation of AND/OR or NAND/NOR logic functions.

In the virgin state, the AND array fuses are back-to-back CB-EB diode pairs which will act as open connections. Current is avalanched across individual diode pairs during fusing, which essentially short circuits the EB diode and provides the connection for the associated product term.

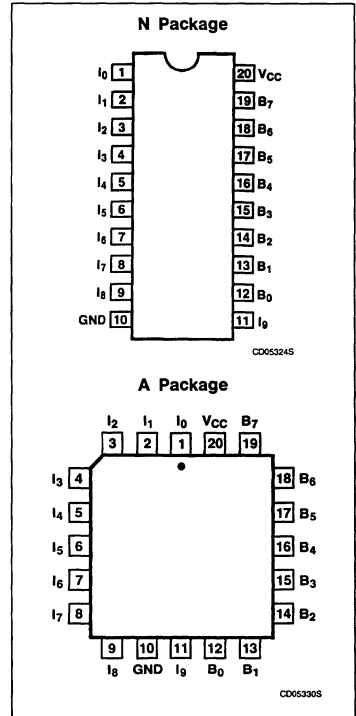
The PLHS18P8B is field-programmable, allowing the user to quickly generate custom pattern using standard programming equipment.

Order codes are listed in the Ordering Information Table.

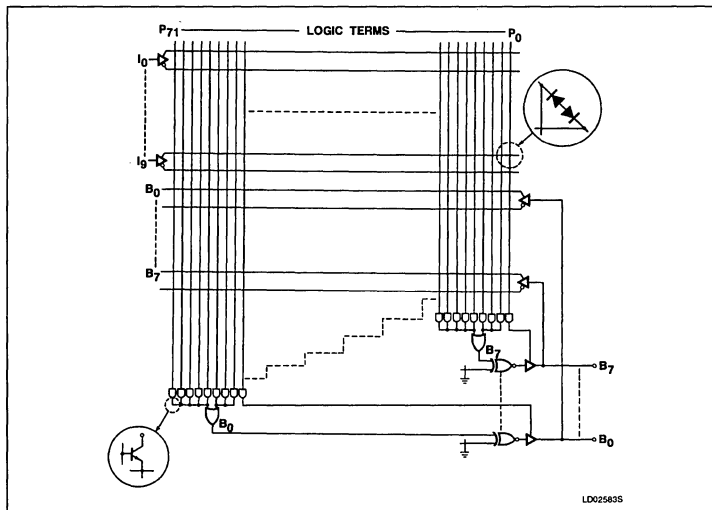
#### FEATURES

- 100% functionally compatible with AmPAL18P8B and all 16L8, 16P8, 16H8, 16L2, 16H2, 14L4, 14H4, 12L6, 12H6, 10L8, 10H8, 16LD8 and 16HD8 PAL type products
- Field-Programmable
- 10 inputs
- 8 bidirectional I/O lines
- 72 AND gates/product terms - configured into eight groups of nine
- Programmable output polarity (3-State output)
- I/O propagation delay: 15ns (max)
- Power dissipation: 500mW (typ)
- TTL compatible
- Security Fuse

#### PIN CONFIGURATIONS



#### FUNCTIONAL DIAGRAM



#### APPLICATIONS

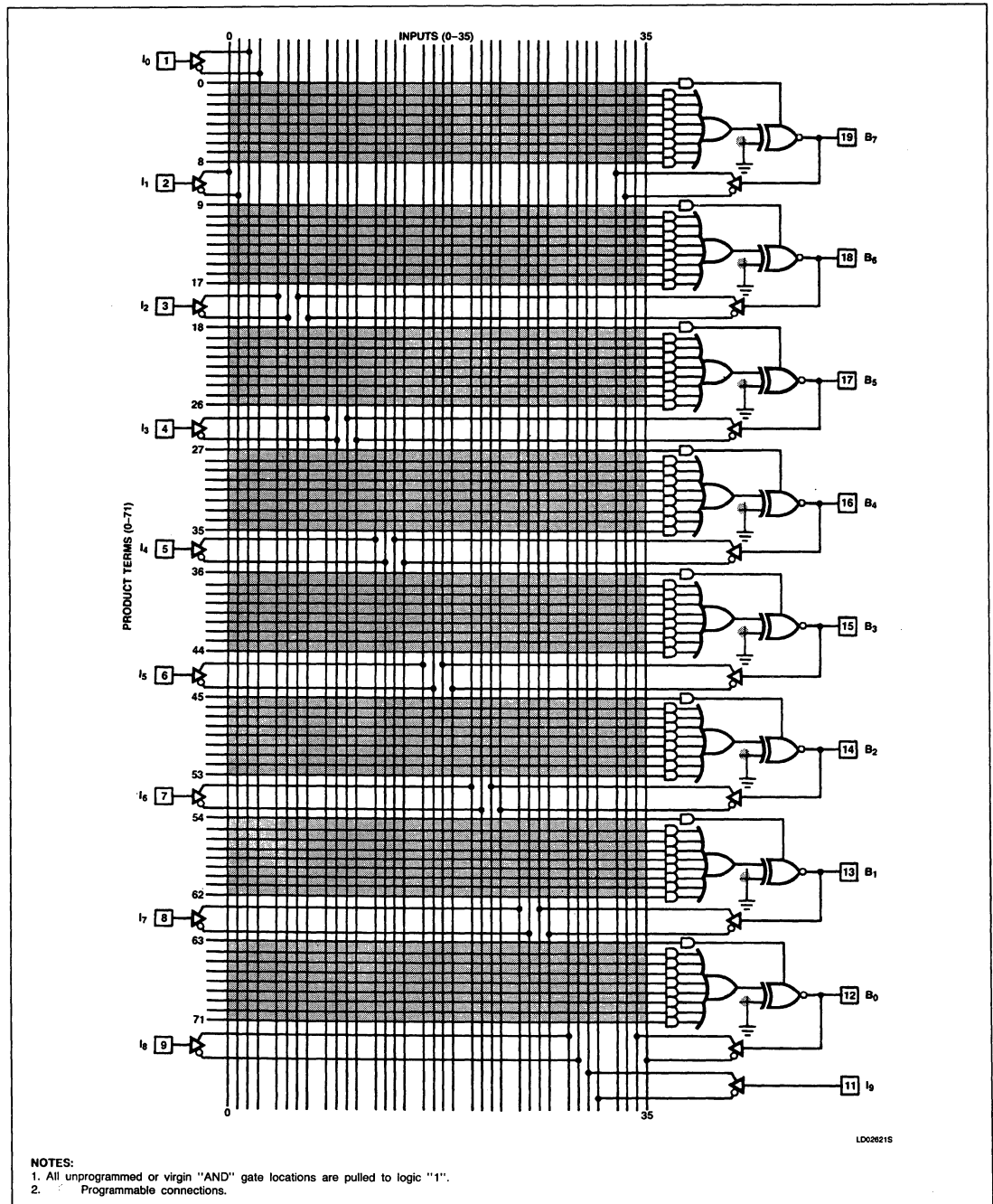
- 100% functional replacement for all 20-pin combinatorial PAL devices
- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping
- Multiplexing

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PAL<sup>®</sup>-Type Device

PLHS18P8B

FPLA LOGIC DIAGRAM



PAL<sup>®</sup>-Type Device

PLHS18P8B

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
20-pin Plastic DIP (300mil-wide)	PLHS18P8BN
20-pin Plastic Leaded Chip Carrier	PLHS18P8BA

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1\*</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	-0.5 to +7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	-0.5 to +5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage	-0.5 to V <sub>CC</sub> Max	V <sub>DC</sub>
V <sub>OUTPRG</sub>	Output voltage (programming)	+21	V <sub>DC</sub>
I <sub>IN</sub>	Input current	-30 to +5	mA
I <sub>OUT</sub>	Output current	+100	mA
I <sub>OUTPRG</sub>	Output current (programming)	+170	mA
T <sub>A</sub>	Operating temperature range	0 to +75	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

PAL<sup>®</sup>-Type Device

## PLHS18P8B

DC ELECTRICAL CHARACTERISTICS  $0^{\circ}\text{C} \leq T_A \leq 75^{\circ}\text{C}$ ,  $4.75\text{V} \leq V_{CC} \leq 5.25\text{V}$ 

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
$V_{IL}$ $V_{IH}$ $V_I$	Low High Clamp	$V_{CC} = \text{Min}$ $V_{CC} = \text{Max}$ $V_{CC} = \text{Min}, I_{IN} = -18\text{mA}$	+2.0		+0.8 -1.2	V V V
<b>Output voltage</b>						
$V_{OL}$ $V_{OH}$	Low High	$V_{CC} = \text{Min}, V_{IN} = V_{IH} \text{ or } V_{IL}$ $I_{OL} = +24\text{mA}$ $I_{OH} = -3.2$	+2.4	+3.5	+0.50	V V
<b>Input current</b>						
$I_{IL}$ $I_{IH}$ $I_I$	Low High High	$V_{CC} = \text{Max}$ $V_{IN} = +0.40\text{V}$ $V_{IN} = +2.7\text{V}$ $V_{IN} = +5.5\text{V}$		-20	-100 +25 +1.0	$\mu\text{A}$ $\mu\text{A}$ mA
<b>Output current</b>						
$I_{OZH}$ $I_{OZL}$ $I_{SC}$	Output leakage Output leakage Short circuit <sup>3</sup>	$V_{CC} = \text{Max}, V_{IL} = 0.8\text{V}, V_{IH} = 2.0\text{V}$ $V_{OUT} = +2.7\text{V}$ $V_{OUT} = +0.40\text{V}$ $V_{OUT} = +0.5\text{V}$	-30	-60	+100 -250 -90	$\mu\text{A}$ $\mu\text{A}$ mA
$I_{CC}$	$V_{CC}$ current	$V_{CC} = \text{Max}, \text{All inputs} = \text{GND}$		100	155	mA
<b>Capacitance<sup>4</sup></b>						
$C_{IN}$ $C_{OUT}$	Input I/O	$V_{CC} = +5\text{V}$ $V_{IN} = 2.0\text{V} @ f = 1\text{MHz}$ $V_{OUT} = 2.0\text{V} @ f = 1\text{MHz}$		6 9		pF pF

**NOTES:**

1. Typical limits are at  $V_{CC} = 5.0\text{V}$  and  $T_A = +25^{\circ}\text{C}$ .
2. These are absolute values with respect to device ground and all overshoots due to system or tester noise are included.
3. Not more than one output should be tested at a time. Duration of the short circuit should not be more than one second.  $V_{OUT} = 0.5\text{V}$  has been chosen to avoid test problems caused by tester ground degradation.
4. These parameters are not 100% tested, but are periodically sampled.

# PAL<sup>®</sup>-Type Device

# PLHS18P8B

## AC ELECTRICAL CHARACTERISTICS $R_1 = 200\Omega, R_2 = 390\Omega, 0^\circ\text{C} \leq T_A \leq +75^\circ\text{C}, 4.75\text{V} \leq V_{CC} \leq 5.25\text{V}$

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ	Max	
$t_{PD}$	Propagation delay	Input $\pm$	Output $\pm$	$C_L = 50\text{pF}$		12	15	ns
$t_{EA}$	Output enable	Input $\pm$	Output -	$C_L = 50\text{pF}$		12	15	ns
$t_{ER}$	Output disable	Input $\pm$	Output +	$C_L = 5\text{pF}$		12	15	ns

**NOTES:**

1. Typical limits are at  $V_{CC} = 5.0\text{V}$  and  $T_A = +25^\circ\text{C}$ .
2.  $T_{PD}$  is tested with switch  $S_1$  closed and  $C_L = 50\text{pF}$ .
3. For 3-State output; output enable times are tested with  $C_L = 50\text{pF}$  to the 1.5V level, and  $S_1$  is open for high-impedance to High tests and closed for high-impedance to Low tests. Output disable times are tested with  $C_L = 5\text{pF}$ . High-to-High impedance tests are made to an output voltage of  $V_{OH} = -0.5\text{V}$  with  $S_1$  open, and Low-to-High impedance tests are made to the  $V_{OL} = +0.5\text{V}$  level with  $S_1$  closed.

### VIRGIN STATE

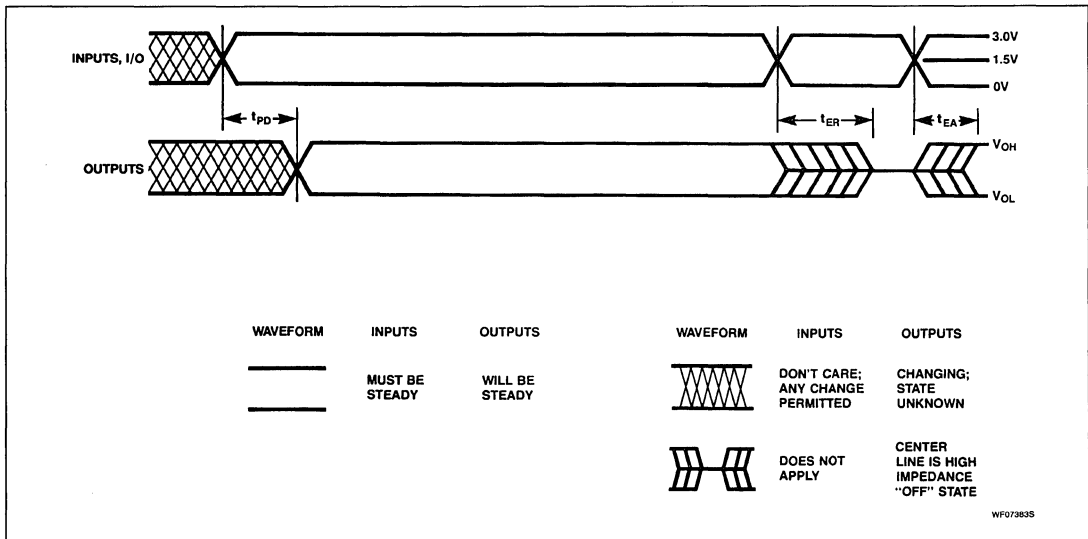
A factory shipped virgin device contains all fusible links open, such that:

1. All outputs are at "H" polarity.
2. All outputs are enabled.
3. All p-terms are enabled.

### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Input to output propagation delay.
$t_{ER}$	Input to output disable (3-State) delay (Output Disable).
$t_{EA}$	Input to Output Enable delay (Output Enable).

### TIMING DIAGRAMS



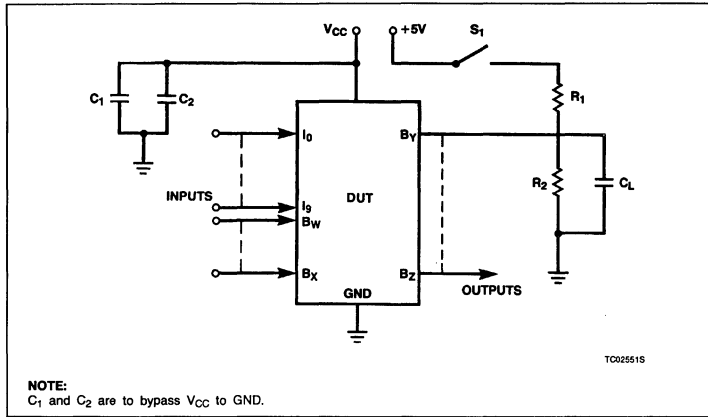
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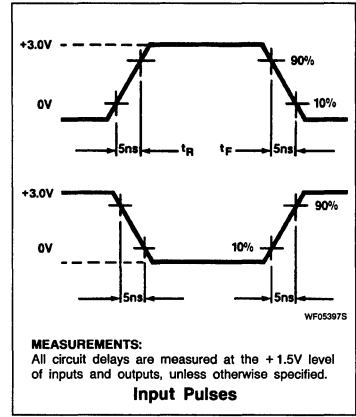
# PAL<sup>®</sup>-Type Device

# PLHS18P8B

## AC TEST LOAD CIRCUIT



## VOLTAGE WAVEFORMS



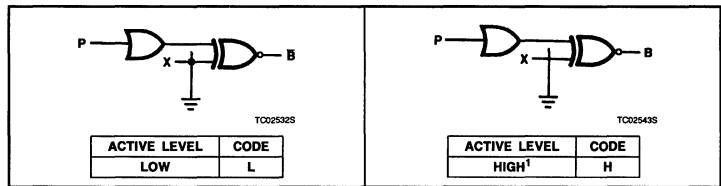
## LOGIC PROGRAMMING

PLHS18P8B logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

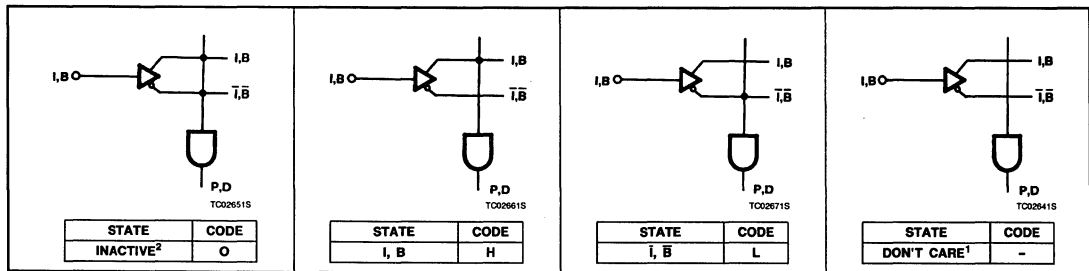
PLHS18P8B logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

## OUTPUT POLARITY — (B)



## "AND" ARRAY — (I, B)



**NOTES:**

1. This is the initial state of all link pairs.
2. All unused product terms must be programmed with all pairs of fuses in the INACTIVE state (all fuses on an unused p-term must be programmed).



# PLC20V8 Series Erasable and OTP PAL<sup>®</sup>-Type Device

Signetics Programmable Logic  
Product Specification

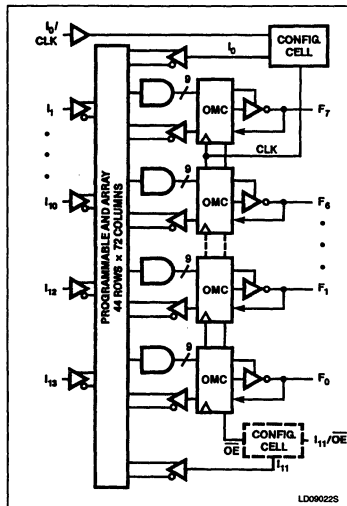
## Application Specific Products • Series 24

### DESCRIPTION

The PLC20V8 Programmable Array Logic device is a 24-pin CMOS PLD designed to replace full-power as well as quarter-power and half-power Series 24 PAL<sup>®</sup> devices. Available in four speed/power configurations, the generic PLC20V8 device can be configured to emulate 21 different PAL devices in multiple speed/power configurations. The more complex AND-OR logic functions can be easily implemented with the PLC20V8 because of the flexibility inherent to its generic Output Macro Cell architecture.

The PLC20V8 is a two-level logic element comprised of 14 inputs, 72 AND gates and 8 Output Macro Cells (OMC). Each Output Macro Cell can be individually configured as a dedicated input, a dedicated output, a bidirectional I/O or as a registered output with feedback. This generic architecture provides a means of reducing documentation, inventory and manufacturing related costs. Furthermore, the PLC20V8 series devices are designed to accept both TTL and CMOS input levels to facilitate logic integration in almost any system environment.

### FUNCTIONAL DIAGRAM



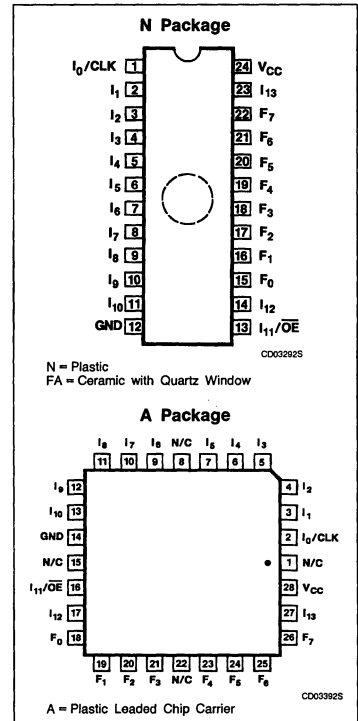
### FEATURES

- 100% functional replacement for Series 24 PAL devices
  - $I_{OL} = 24mA$
- Low power performance: 50 and 90mA max
  - All inputs and outputs switching at 15MHz
- Equivalent bipolar performance
  - 35 and 45ns  $t_{PD}$
  - 28.5 and 22.2MHz  $f_{MAX}$  (async)
- EPROM cell technology
  - Erasable
  - 100% testable
  - Reconfigurable (quartz window package only)
- TTL and CMOS compatible
- Security fuse
- Available in 300mil-wide DIP with quartz window, plastic DIP (OTP), or PLCC (OTP)

### PIN LABEL DESCRIPTIONS

I	Dedicated input
B	Bidirectional input/output
O	Dedicated output
D	Registered output (D-type flip-flop)

### PIN CONFIGURATIONS



### PAL DEVICE TO PLC20V8 OUTPUT PIN CONFIGURATION CROSS REFERENCE (DIP Packages Only)

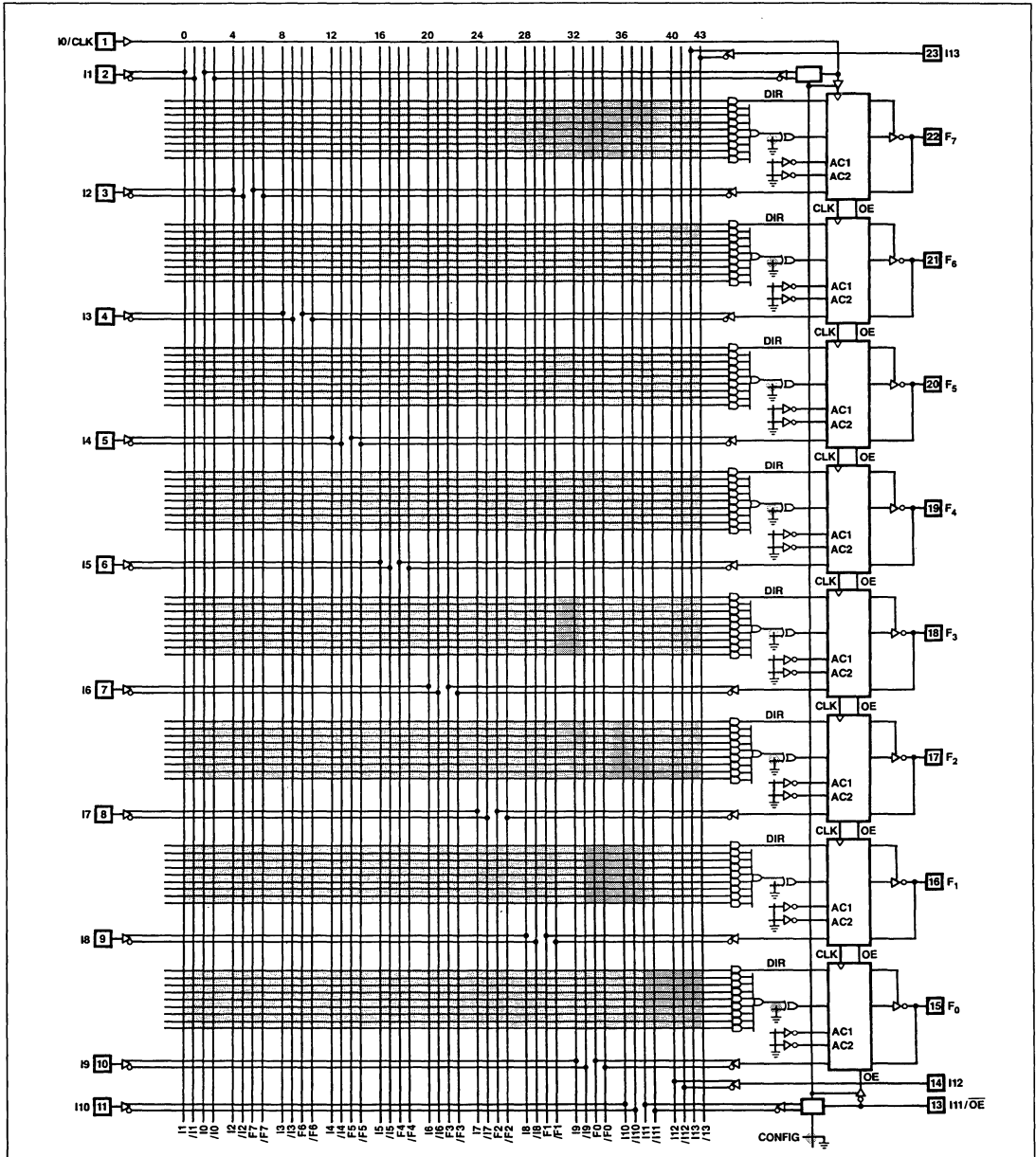
PIN NO.	PLC 20V8	20R8 20RP8	20R6 20RP6	20R4 20RP4	20L8 20H8 20P8	20L2 20H2 20P2	18L4 18H4 18P4	16L6 16H6 16P6	14L8 14H8 14P8
1	I <sub>0</sub> /CLK	CLK	CLK	CLK	I	I	I	I	I
13	I <sub>11</sub> /OE	OE	OE	OE	I	I	I	I	I
14	I <sub>12</sub>	I	I	I	I	I	I	I	I
15	F <sub>0</sub>	D	B	B	O	I	I	I	O
16	F <sub>1</sub>	D	D	B	B	I	O	O	O
17	F <sub>2</sub>	D	D	D	B	I	O	O	O
18	F <sub>3</sub>	D	D	D	B	O	O	O	O
19	F <sub>4</sub>	D	D	D	B	O	O	O	O
20	F <sub>5</sub>	D	D	D	B	I	O	O	O
21	F <sub>6</sub>	D	D	B	B	I	I	O	O
22	F <sub>7</sub>	D	B	B	O	I	I	I	O
23	I <sub>13</sub>	I	I	I	I	I	I	I	I

® PAL is a registered trademark of Monolithic Memories, Inc., a wholly owned subsidiary of Advanced Micro Devices, Inc.

# Erasable and OTP PAL<sup>®</sup>-Type Device

## PLC20V8 Series

### LOGIC DIAGRAM



3

**NOTES:**

In the unprogrammed or virgin state:  
 All cells are in a conductive state.  
 All AND gate locations are pulled to a logic "0" (Low).  
 Output polarity is non-inverting.

Pins 1 and 13 are configured as inputs 0 and 11, respectively, via the configuration cell. The clock and OE functions are disabled.  
 All output macro cells (OMC) are configured as bidirectional I/O, with the outputs disabled via the direction term.  
 ⊗ Denotes a programmable cell location.

LD091805

# Erasable and OTP PAL®-Type Device

## PLC20V8 Series

The Signetics state-of-the-art Floating-Gate CMOS EPROM process yields bipolar equivalent performance at one-quarter to one-half the power consumption. The erasable nature of the EPROM process enables Signetics to functionally test the devices prior to shipment to the customer. Additionally, this allows Signetics to extensively stress test, as well as ensure the threshold voltage of each individual EPROM cell. 100% programming yield is subsequently guaranteed.

Signetics' AMAZE PLD design software supports all aspects of design, simulation and programming. For simple conversion of existing PAL device codes into the PLC20V8 series format, a PAL-to-V8 converter is also available. SimPal, (sim'pal), a stand-alone, single-disk software package translates a PAL device code (from a device or a JEDEC standard fuse map) into an equivalent PLC20V8 series JEDEC format. The SimPal PAL-to-V8 converter, which runs on an IBM PC or compatible, includes the necessary programmer interface software for most commercially available programmers.

### THE OUTPUT MACRO CELL (OMC)

The PLC20V8 has 8 individually programmable Output Macro Cells. The 72 AND inputs (or product terms) from the programmable AND array are connected to the 8 OMCs in groups of 9. Eight of the AND terms are dedicated to logic functions; the ninth is for asynchronous direction control.

Each OMC can be independently programmed via 16 architecture control bits,  $AC1_n$  and  $AC2_n$  (one pair per macro cell). Similarly, each OMC has a programmable output polarity control bit ( $X_n$ ). By configuring the pair of architecture control bits according to the table, 4 different configurations may be implemented.

### CONFIGURATION CELL

A single configuration cell controls the functions of Pins 1 and 13. Refer to Functional Diagram. When the configuration cell is programmed, Pin 1 is a dedicated clock and Pin 13 is dedicated for output enable. When the configuration cell is unprogrammed, Pins 1 and 13 are both dedicated inputs. Note that the output enable for all registered OMCs is common — from Pin 13 only. Output enable control of the bidirectional I/O OMCs is provided from the AND array via the direction product term.

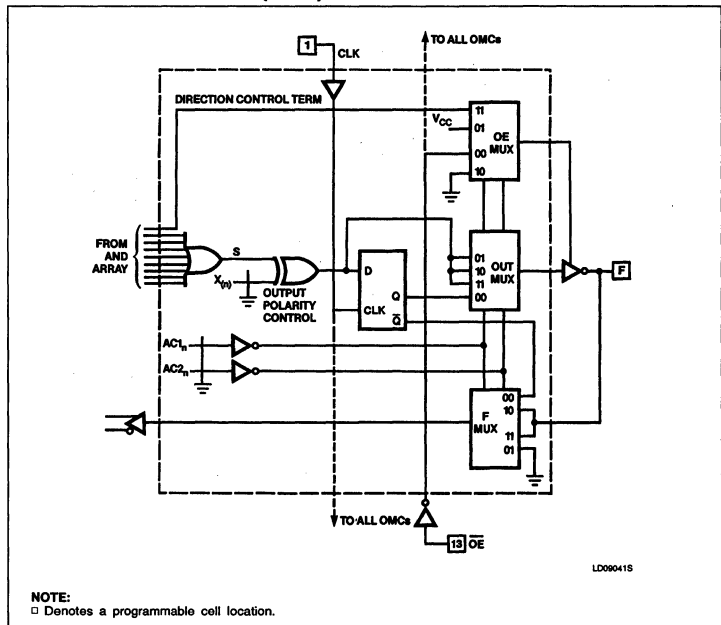
If any one OMC is configured as registered, the configuration cell will be automatically config-

FUNCTION	CONTROL CELL CONFIGURATIONS			COMMENTS
	$AC1_n$	$AC2_n$	CONFIG. CELL	
Registered mode	Programmed	Programmed	Programmed	Dedicated clock from Pin 1. $\overline{OE}$ Control for all registered OMCs from Pin 13 only.
Bidirectional I/O mode <sup>1</sup>	Unprogrammed	Unprogrammed	Unprogrammed	Pins 1 and 13 are dedicated inputs. 3-State control from AND array only.
Fixed input mode	Unprogrammed	Programmed	Unprogrammed	Pins 1 and 13 are dedicated inputs.
Fixed output mode	Programmed	Unprogrammed	Unprogrammed	Pins 1 and 13 are dedicated inputs. The feedback path (via $F_{MUX}$ ) is disabled.

**NOTE:**

1. This is the virgin state as shipped from the factory.

### OUTPUT MACRO CELL (OMC)



**NOTE:**  
□ Denotes a programmable cell location.

ured (via the design software) to ensure that the clock and output enable functions are enabled on Pins 1 and 13, respectively. If none of the OMCs are registered, the configuration cell will be programmed such that Pins 1 and

13 are dedicated inputs. The programming codes are as follow:

Pin 1 = CLK, Pin 13 = $\overline{OE}$	L
Pin 1 and Pin 13 = Input	H

# Erasable and OTP PAL<sup>®</sup>-Type Device

## PLC20V8 Series

### ORDERING INFORMATION

DESCRIPTION		ORDER CODE
Propagation Delay (Max)		
$t_{PD} = 35ns$	$f_{MAX} = 18.1MHz$ (Synchronous)	50mA
		90mA
$t_{PD} = 45ns$	$f_{MAX} = 13.3MHz$ (Synchronous)	50mA
		90mA
Package Type		PACKAGE <sup>1</sup>
24-pin Plastic DIP (one time programmable; OTP)		N
24-pin Plastic Leaded Chip Carrier (one time programmable; OTP)		A
24-pin Ceramic DIP with quartz window (reprogrammable)		FA

3

**NOTE:**

1. The package order code directly follows the device order code, i.e., PLC20V8Q35N for Plastic DIP (OTP).

### ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
$V_{CC}$	Supply voltage	-0.5 to +7	$V_{DC}$
$V_{IN}$	Input voltage	-0.5 to $V_{CC} + 0.5$	$V_{DC}$
$V_{OUT}$	Output voltage	-0.5 to $V_{CC} + 0.5$	$V_{DC}$
$I_{IN}$	Input currents	-10 to +10	mA
$I_{OUT}$	Output currents	+24	mA
$T_A$	Operating temperature range	0 to +75	°C
$T_{STG}$	Storage temperature range	-65 to +150	°C

### THERMAL RATINGS

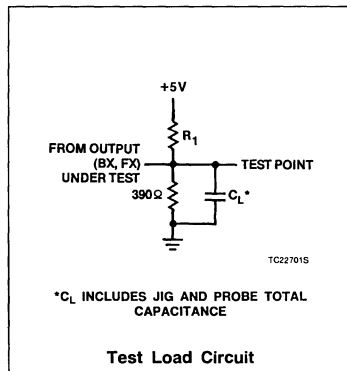
TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

The PLC20V8 device is also processed to military requirements for operation over the military temperature range. For specifications and ordering information consult the Signetics Military Data Book.

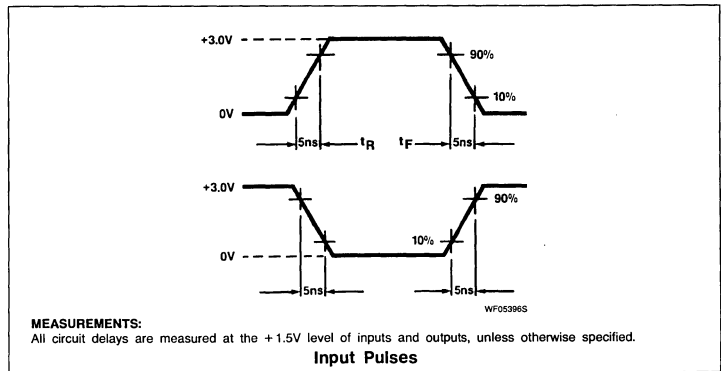
**NOTE:**

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

### AC TEST CONDITIONS



### VOLTAGE WAVEFORMS



# Erasable and OTP PAL®-Type Device

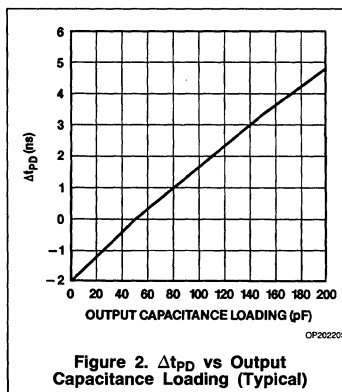
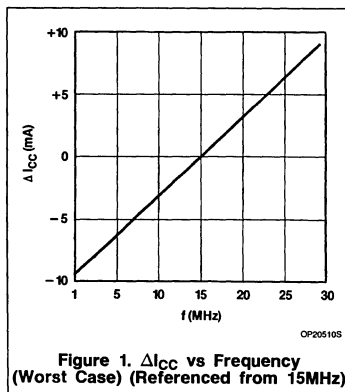
## PLC20V8 Series

### DC ELECTRICAL CHARACTERISTICS $0^{\circ}\text{C} \leq T_A \leq +75^{\circ}\text{C}$ , $4.75 \leq V_{CC} \leq 5.25\text{V}$

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
$V_{IL}$	Low	$V_{CC} = \text{Min}$	-0.3		0.8	V
$V_{IH}$	High	$V_{CC} = \text{Max}$	2.0		$V_{CC} + 0.3$	V
<b>Output voltage<sup>2</sup></b>						
$V_{OL}$	Low	$V_{CC} = \text{Min}$ $I_{OL} = 24\text{mA}$			0.5	V
$V_{OH}$	High	$I_{OH} = -3.2\text{mA}$	2.4			V
<b>Input current</b>						
$I_{IL}$	Low <sup>6</sup>	$V_{IN} = \text{GND}$			-10	$\mu\text{A}$
$I_{IH}$	High	$V_{IN} = V_{CC}$			10	$\mu\text{A}$
<b>Output current</b>						
$I_{O(\text{OFF})}$	Hi-Z state	$V_{OUT} = V_{CC}$ $V_{OUT} = \text{GND}$			10 -10	$\mu\text{A}$ $\mu\text{A}$
$I_{OS}$	Short-circuit <sup>3, 7</sup>	$V_{OUT} = \text{GND}$			-130	mA
$I_{CC}$	$V_{CC}$ supply current (Active) <sup>4</sup>	$I_{OUT} = 0\text{mA}$ $f = 15\text{MHz}$ <sup>5</sup>	Quarter power (Q)		50	mA
			Half power (H)		90	mA
<b>Capacitance</b>						
$C_I$	Input	$V_{CC} = 5\text{V}$ $V_{IN} = 2.0\text{V}$		12		pF
$C_B$	I/O	$V_B = 2.0\text{V}$		15		pF

**NOTES:**

- All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
- All voltage values are with respect to network ground terminal.
- Duration of short-circuit should not exceed one second. Test one at a time.
- Tested with TTL input levels:  $V_{IL} = 0.45\text{V}$ ,  $V_{IH} = 2.4\text{V}$ . Measured with all inputs and outputs switching.
- Refer to Figure 1,  $\Delta I_{CC}$  vs Frequency (worst case). (Referenced from 15MHz)
- $I_{IL}$  for Pin 1 ( $I_0/\text{CLK}$ ) is  $\pm 10\mu\text{A}$  with  $V_{IN} = 0.4\text{V}$ .
- Refer to Figure 2 for  $\Delta t_{PD}$  vs output capacitance loading.



# Erasable and OTP PAL<sup>®</sup>-Type Device

## PLC20V8 Series

### AC ELECTRICAL CHARACTERISTICS $0^{\circ}\text{C} \leq T_A \leq +75^{\circ}\text{C}$ , $4.75\text{V} \leq V_{CC} \leq 5.25\text{V}$ $R_2 = 390\Omega$

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION <sup>1</sup>		PLC20V8Q-35 PLC20V8H-35		PLC20V8Q-45 PLC20V8H-45		UNIT
				R <sub>1</sub> ( $\Omega$ )	C <sub>L</sub> (pF)	Min	Max	Min	Max	
<b>Pulse width</b>										
t <sub>CKP</sub>	Clock period (Minimum t <sub>IS</sub> + t <sub>CKO</sub> )	CLK +	CLK +			55		75		ns
t <sub>CKH</sub>	Clock width High	CLK -	CLK +			20		25		ns
t <sub>CKL</sub>	Clock width Low	CLK +	CLK -			20		25		ns
<b>Hold time</b>										
t <sub>IH</sub>	Input or feedback data hold time	Input $\pm$	CLK +			0		0		ns
<b>Setup time</b>										
t <sub>IS</sub>	Input or feedback data setup time	CLK +	I $\pm$ , F $\pm$			30		40		ns
<b>Propagation delay</b>										
t <sub>PD</sub>	Delay from input to active output	F $\pm$	I $\pm$ , F $\pm$	200	50		35		45	ns
t <sub>CKO</sub>	Clock High to output valid access Time	F $\pm$	CLK +	200	50		25		35	ns
t <sub>OE1</sub> <sup>3</sup>	Product term enable to active output	F $\pm$	I $\pm$ , F $\pm$	Active-High R = 1.5k Active-Low R = 550	50		35		45	ns
t <sub>OD1</sub> <sup>2</sup>	Product term disable to outputs off	F $\pm$	I $\pm$ , F $\pm$	From V <sub>OH</sub> R = $\infty$ From V <sub>OL</sub> R = 200	5		35		45	ns
t <sub>OD2</sub> <sup>2</sup>	Pin 13 output disable High to outputs off	F $\pm$	OE -	From V <sub>OH</sub> R = $\infty$ From V <sub>OL</sub> R = 200	5		25		30	ns
t <sub>OE2</sub> <sup>3</sup>	Pin 13 output enable to active output	F $\pm$	OE +	Active-High R = 1.5k Active-Low R = 550	50		25		30	ns
t <sub>PPR</sub>	Power-up reset	F +	V <sub>CC</sub> +				35		45	ns
<b>Frequency of operation (t<sub>IS</sub> + t<sub>CKO</sub>)</b>										
f <sub>MAX</sub>	Maximum frequency	Synch. Asynch.		200	50		18.1 28.5		13.3 22.2	MHz

#### NOTES:

1. Refer also to AC Test Conditions. (Test Load Circuit)
2. 3-State levels are measured  $\pm 0.5\text{V}$  from the active steady-state level.
3. Resistor values of 1.5k and 550 $\Omega$  provide 3-State levels of 1.0V and 2.0V, respectively. Output timing measurements are to 1.5V level.



# Erasable and OTP PAL®-Type Device

## PLC20V8 Series

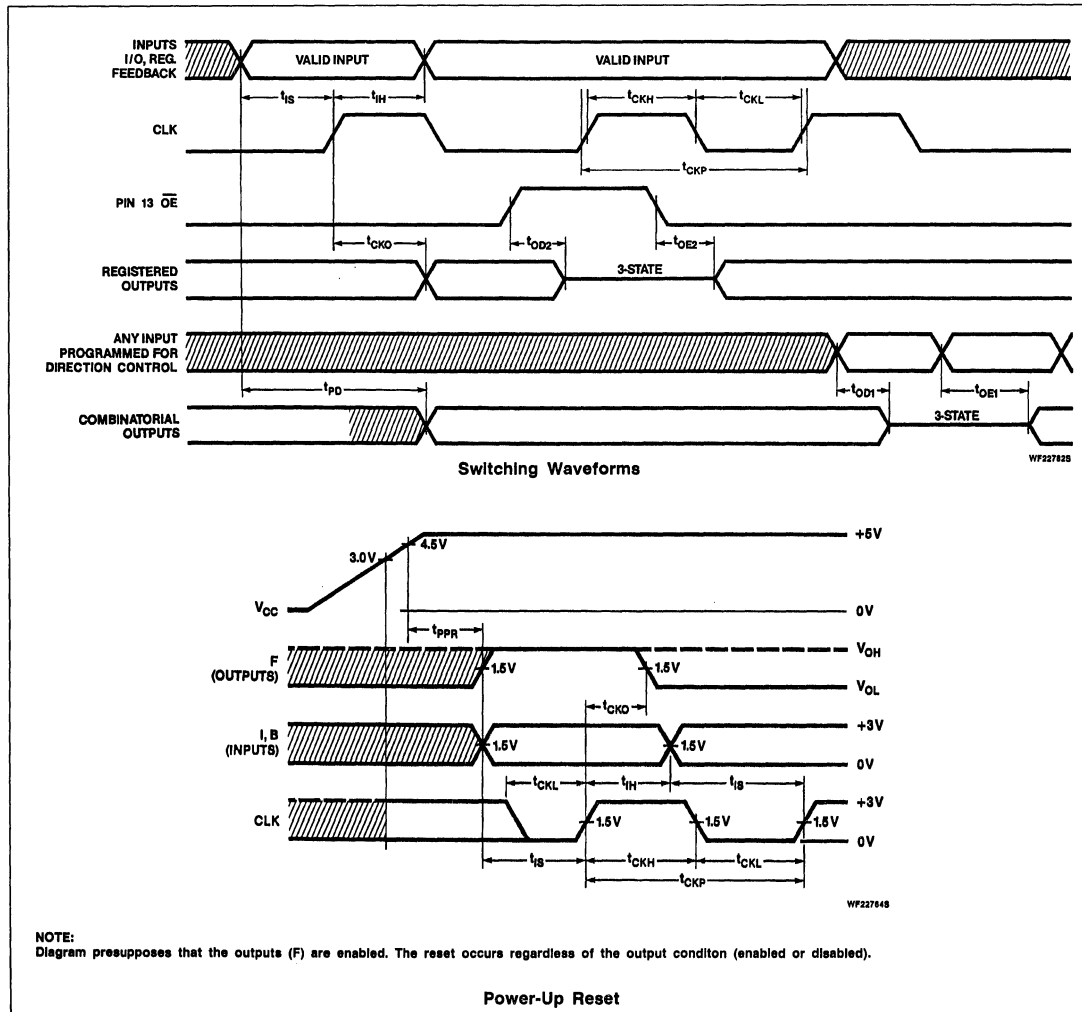
### POWER-UP RESET

In order to facilitate state machine design and testing, a power-up reset function has been incorporated in the PLC20V8. All internal registers will reset to active-Low (logical "0") after a specified period of time ( $t_{PPR}$ ). Therefore, any OMC that has been configured as a

registered output will always produce an active-High on the associated output pin because of the inverted output buffer. The internal feedback ( $\bar{Q}$ ) of a registered polarity of OMC will not affect the active-High output condition during a system power-up condition.

The following conditions must be considered when the asynchronous power-up reset occurs.  $V_{CC}$  rise to 4.5V (90%) must be monotonic. The clock input must stabilize to a valid TTL level prior to the  $V_{CC}$  rise to 60% (3.0V). All input setup and hold times ( $t_{IS}$  and  $t_{IH}$ ) must be achieved prior to clocking the device.

### TIMING DIAGRAMS



# Erasable and OTP PAL®-Type Device

# PLC20V8 Series

## REGISTER PRELOAD FUNCTION (DIAGNOSTIC MODE ONLY)

In order to facilitate the testing of state machine/controller designs, a diagnostic mode register preload feature has been incorporated into the PLC20V8 series device. This feature enables the user to load the registers

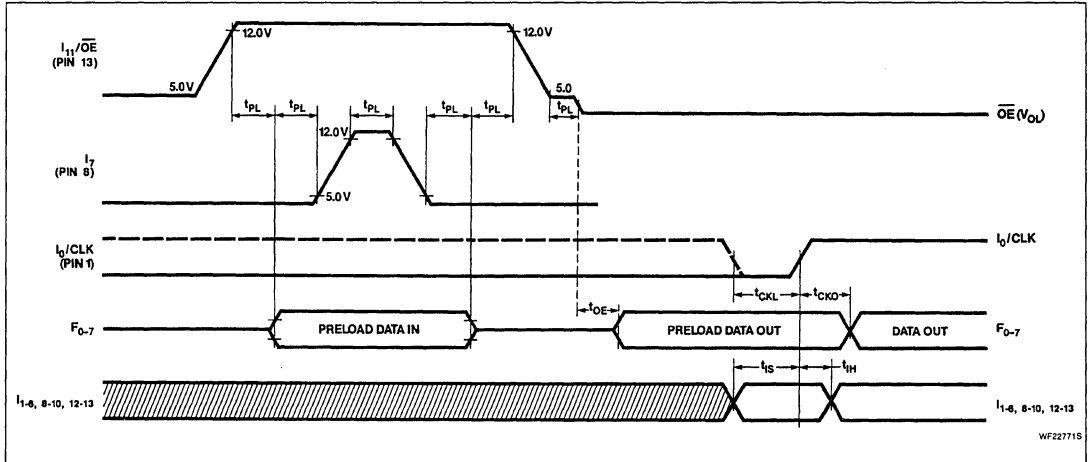
with predetermined states while a super voltage is applied to Pins 13 and 8 ( $I_{11}/\overline{OE}$  and  $I_7$ ). (See diagram for timing and sequence.)

To read the data out, Pins 13 and 8 must be returned to normal TTL levels. The outputs,  $F_{0-7}$ , must be enabled in order to read data out. The Q outputs of the registers will reflect

data in as input via  $F_{0-7}$  during preload. Subsequently, the register  $\overline{Q}$  output via the feedback path will reflect the complement of the data in as input via  $F_{0-7}$ .

Refer to the voltage waveform for timing and voltage references.

## REGISTER PRELOAD (DIAGNOSTIC MODE)



WF227715

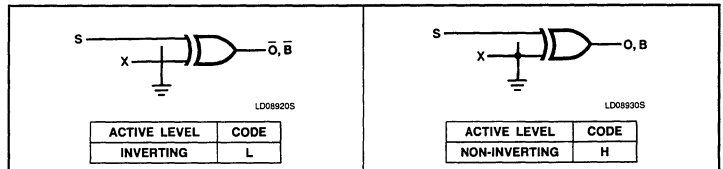
## LOGIC PROGRAMMING

The EPLD can be programmed by means of Logic Programming equipment.

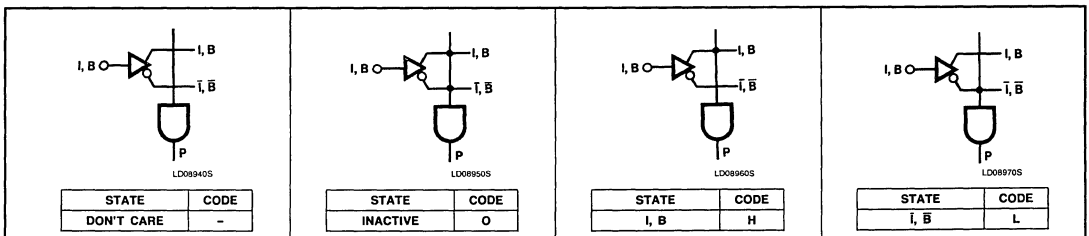
With Logic programming, the AND/Ex-OR gate input connections necessary to implement the desired logic function are coded directly from logic equations using the Program Table. Similarly, various OMC configurations are implemented by programming the Architecture Control bits AC1 and AC2, as shown below. Note that the configuration cell is automatically programmed based on the OMC configuration.

In this table, the logic state of variables I, P, and B associated with each Sum Term S is assigned a symbol which results in the proper fusing pattern of corresponding link pairs, defined as follows:

## OUTPUT POLARITY — (O, B)



## "AND" ARRAY — (I, B)



# Erasable and OTP PAL®-Type Device

## PLC20V8 Series

### ARCHITECTURE CONTROL — AC1 and AC2

<p style="text-align: right; font-size: small;">LD05981S</p> <table border="1" style="width: 100%; border-collapse: collapse; margin-top: 10px;"> <thead> <tr> <th style="text-align: left;">OMC CONFIGURATION</th> <th style="text-align: left;">CODE</th> </tr> </thead> <tbody> <tr> <td>REGISTERED (D-TYPE)</td> <td>D</td> </tr> </tbody> </table>	OMC CONFIGURATION	CODE	REGISTERED (D-TYPE)	D	<p style="text-align: right; font-size: small;">LD06991S</p> <table border="1" style="width: 100%; border-collapse: collapse; margin-top: 10px;"> <thead> <tr> <th style="text-align: left;">OMC CONFIGURATION</th> <th style="text-align: left;">CODE</th> </tr> </thead> <tbody> <tr> <td>BIDIRECTIONAL I/O (COMBINATORIAL)</td> <td>B</td> </tr> </tbody> </table>	OMC CONFIGURATION	CODE	BIDIRECTIONAL I/O (COMBINATORIAL)	B	<p style="text-align: right; font-size: small;">LD09000S</p> <table border="1" style="width: 100%; border-collapse: collapse; margin-top: 10px;"> <thead> <tr> <th style="text-align: left;">OMC CONFIGURATION</th> <th style="text-align: left;">CODE</th> </tr> </thead> <tbody> <tr> <td>FIXED OUTPUT</td> <td>O</td> </tr> </tbody> </table>	OMC CONFIGURATION	CODE	FIXED OUTPUT	O
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<p style="text-align: right; font-size: small;">LD09010S</p> <table border="1" style="width: 100%; border-collapse: collapse; margin-top: 10px;"> <thead> <tr> <th style="text-align: left;">OMC CONFIGURATION</th> <th style="text-align: left;">CODE</th> </tr> </thead> <tbody> <tr> <td>FIXED INPUT</td> <td>I</td> </tr> </tbody> </table>	OMC CONFIGURATION	CODE	FIXED INPUT	I	<p style="text-align: right; font-size: small;">LD06200S</p> <table border="1" style="width: 100%; border-collapse: collapse; margin-top: 10px;"> <thead> <tr> <th style="text-align: left;">CONFIGURATION CELL</th> <th style="text-align: left;">CODE</th> </tr> </thead> <tbody> <tr> <td>PIN 1 = CLK PIN 13 = OE</td> <td>L</td> </tr> </tbody> </table>	CONFIGURATION CELL	CODE	PIN 1 = CLK PIN 13 = OE	L	<p style="text-align: right; font-size: small;">LD09190S</p> <table border="1" style="width: 100%; border-collapse: collapse; margin-top: 10px;"> <thead> <tr> <th style="text-align: left;">CONFIGURATION CELL</th> <th style="text-align: left;">CODE</th> </tr> </thead> <tbody> <tr> <td>PIN 1 = INPUT 13 = INPUT</td> <td>H<sup>6</sup></td> </tr> </tbody> </table>	CONFIGURATION CELL	CODE	PIN 1 = INPUT 13 = INPUT	H <sup>6</sup>
OMC CONFIGURATION	CODE													
FIXED INPUT	I													
CONFIGURATION CELL	CODE													
PIN 1 = CLK PIN 13 = OE	L													
CONFIGURATION CELL	CODE													
PIN 1 = INPUT 13 = INPUT	H <sup>6</sup>													

**NOTE:**

A factory shipped unprogrammed device is configured such that:

1. All cells are in a conductive state.
2. All AND gates are pulled to a logic "0" (Low).
3. Output polarity is non-inverting.
4. Pins 1 and 13 are configured as inputs 0 and 11. The clock and OE functions are disabled.
5. All Output Macro Cells (OMCs) are configured as bidirectional I/O, with the outputs disabled via the direction term.
6. This configuration cannot be used if any OMCs are configured as registered (Code = D). The configuration cell will be automatically configured to ensure that the clock and output enable functions are enabled on Pins 1 and 13, respectively, if any one OMC is programmed as registered.

### ERASURE CHARACTERISTICS (For Quartz Window Packages Only)

The erasure characteristics of the PLC20V8 Series devices are such that erasure begins to occur upon exposure to light with wavelengths shorter than approximately 4000 Angstroms (Å). It should be noted that sunlight and certain types of fluorescent lamps have wavelengths in the 3000 - 4000Å range. Data shows that constant exposure to room level fluorescent lighting could erase a typical PLC20V8 in approximately three years, while

it would take approximately one week to cause erasure when exposed to direct sunlight. If the PLC20V8 is to be exposed to these types of lighting conditions for extended periods of time, opaque labels should be placed over the window to prevent unintentional erasure.

The recommended erasure procedure for the PLC20V8 is exposure to shortwave ultraviolet light which has a wavelength of 2537 Angstroms (Å). The integrated dose (i.e., UV intensity × exposure time) for erasure should be a minimum of 15Wsec/cm<sup>2</sup>. The erasure

time with this dosage is approximately 30 to 35 minutes using an ultraviolet lamp with a 12,000µW/cm<sup>2</sup> power rating. The device should be placed within one inch of the lamp tubes during erasure. The maximum integrated dose a CMOS EPLD can be exposed to without damage is 7258Wsec/cm<sup>2</sup> (1 week @ 12000µW/cm<sup>2</sup>). Exposure of these CMOS EPLDs to high intensity UV light for longer periods may cause permanent damage.

The maximum number of guaranteed erase/write cycles is 50. Data retention exceeds 20 years.

# Erasable and OTP PAL®-Type Device

## PLC20V8 Series

### PROGRAM TABLE

CUSTOMER NAME _____ PURCHASE ORDER # _____ SIGNETICS DEVICE # _____ CF (XXXX) CUSTOMER SYMBOLIZED PART # _____ TOTAL NUMBER OF PARTS _____ PROGRAM TABLE # _____ REV. _____ DATE _____		CONFIGURATION CELL (CLK/OE CONTROL)																					
		AND ARCH. CONTROL BITS										OUTPUT POLARITY											
		AND										OR (FIXED) F(A, O, D)											
Y	X	13	12	11	10	9	8	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
0	1															D	A	A	A	A	A	A	A
2	3															A	A	A	A	A	A	A	A
4	5															A	A	A	A	A	A	A	A
6	7															A	A	A	A	A	A	A	A
8	9															A	A	A	A	A	A	A	A
10	11															A	A	A	A	A	A	A	A
12	13															A	A	A	A	A	A	A	A
14	15															A	A	A	A	A	A	A	A
16	17															A	A	A	A	A	A	A	A
18	19															A	A	A	A	A	A	A	A
20	21															A	A	A	A	A	A	A	A
22	23															A	A	A	A	A	A	A	A
24	25															A	A	A	A	A	A	A	A
26	27															A	A	A	A	A	A	A	A
28	29															A	A	A	A	A	A	A	A
30	31															A	A	A	A	A	A	A	A
32	33															A	A	A	A	A	A	A	A
34	35															A	A	A	A	A	A	A	A
36	37															A	A	A	A	A	A	A	A
38	39															A	A	A	A	A	A	A	A
40	41															A	A	A	A	A	A	A	A
42	43															A	A	A	A	A	A	A	A
44	45															A	A	A	A	A	A	A	A
46	47															A	A	A	A	A	A	A	A
48	49															A	A	A	A	A	A	A	A
50	51															A	A	A	A	A	A	A	A
52	53															A	A	A	A	A	A	A	A
54	55															A	A	A	A	A	A	A	A
56	57															A	A	A	A	A	A	A	A
58	59															A	A	A	A	A	A	A	A
60	61															A	A	A	A	A	A	A	A
62	63															A	A	A	A	A	A	A	A
64	65															A	A	A	A	A	A	A	A
66	67															A	A	A	A	A	A	A	A
68	69															A	A	A	A	A	A	A	A
70	71															A	A	A	A	A	A	A	A
72	73															A	A	A	A	A	A	A	A
74	75															A	A	A	A	A	A	A	A
76	77															A	A	A	A	A	A	A	A
78	79															A	A	A	A	A	A	A	A
80	81															A	A	A	A	A	A	A	A
82	83															A	A	A	A	A	A	A	A
84	85															A	A	A	A	A	A	A	A
86	87															A	A	A	A	A	A	A	A
88	89															A	A	A	A	A	A	A	A
90	91															A	A	A	A	A	A	A	A
92	93															A	A	A	A	A	A	A	A
94	95															A	A	A	A	A	A	A	A
96	97															A	A	A	A	A	A	A	A
98	99															A	A	A	A	A	A	A	A
100	101															A	A	A	A	A	A	A	A
102	103															A	A	A	A	A	A	A	A
104	105															A	A	A	A	A	A	A	A
106	107															A	A	A	A	A	A	A	A
108	109															A	A	A	A	A	A	A	A
110	111															A	A	A	A	A	A	A	A
112	113															A	A	A	A	A	A	A	A
114	115															A	A	A	A	A	A	A	A
116	117															A	A	A	A	A	A	A	A
118	119															A	A	A	A	A	A	A	A
120	121															A	A	A	A	A	A	A	A
122	123															A	A	A	A	A	A	A	A

**NOTES:**  
 In the unprogrammed or virgin state:  
 • All AND gate locations are pulled to a logic "0" (Low).  
 • Output polarity is non-inverting.  
 • Pins 1 and 11 are configured as inputs 0 and 9, respectively, via the configuration cell. The clock and OE functions are disabled.  
 • All output macro cells (OMC) are configured as combinatorial I/O, with the outputs disabled via the direction control term.

AND ARRAY		CONTROL				OR ARRAY (FIXED)	
INACTIVE	O	OMC ARCH.		OUTPUT POLARITY		DATA CANNOT BE ENTERED INTO THE OR ARRAY FIELD DUE TO THE FIXED NATURE OF THE DEVICE ARCHITECTURE.	
L F & B	H	REGISTERED (D-TYPE)	D	NON-INVERTING	H	DIRECTION CONTROL	
L F & B	L	FIXED INPUT	I	INVERTING	L		
DON'T CARE	-	FIXED OUTPUT	O	CONFIG. CELL*		ACTIVE OUTPUT	A
		BIDIRECTIONAL I/O	B	PIN 1 = CLK; PIN 13 = OE	L	NOT USED	✓
				PIN 1, PIN 13 = INPUT	H		

\* THE CONFIGURATION CELL IS AUTOMATICALLY PROGRAMMED BASED ON THE OMC ARCHITECTURE.

T8036205

## PLUS20R8D Series PAL<sup>®</sup>-Type Devices

Signetics Programmable Logic  
*Preliminary Specification*

### Application Specific Products

- Series 24

### FEATURES

- Ultra high-speed:
  - $t_{PD} = 10\text{ns}$
  - $f_{MAX} = 55.5\text{MHz}$  (with feedback)
  - $t_{IS} = 10\text{ns}$  (worst case)
  - $t_{CKO} = 8\text{ns}$  (worst case)
- 100% functionally and pin-for-pin compatible with industry standard 24-pin PAL ICs
- Power-up reset function to enhance state machine design and testability
- Design support provided via AMAZE and other CAD tools for Series 24 PAL devices
- Field-programmable on industry standard programmers
- Security fuse
- Individual 3-State control of all outputs

### DESCRIPTION

The Signetics PLUS20XXD family is an ultra high-speed 10ns version of existing Series 24 PAL devices.

The PLUS20XXD family is 100% functional and pin-compatible with the 20L8, 20R8, 20R6, and 20R4 Series devices.

The sum of products (AND-OR) architecture is comprised of 64 AND gates and 8 OR gates. Multiple bidirectional pins provide variable input/output pin ratios. Individual 3-State control of all outputs and registers with feedback (R8, R6, R4) is also provided.

The PLUS20R8D, R6D, and R4D have D-type flip-flops which are loaded on the Low-to-High transition of the clock input.

In order to facilitate state machine design and testing, a power-up reset function has been incorporated into these devices to reset all internal registers to active-Low after a specific period of time.

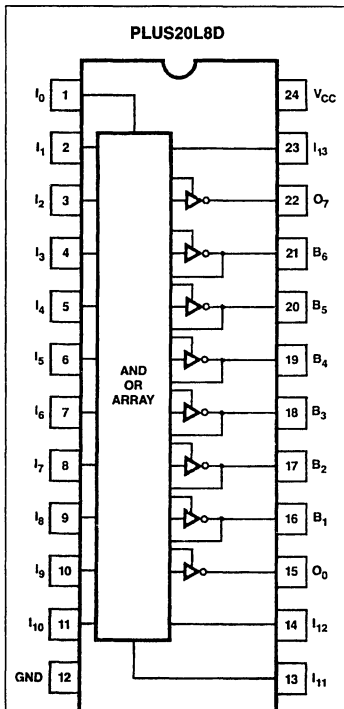
The Signetics State-of-the-Art oxide isolation Bipolar fabrication process is employed to achieve high-performance operation.

The PLUS20XXD family of devices are field programmable, enabling the user to quickly generate custom patterns using standard programming equipment.

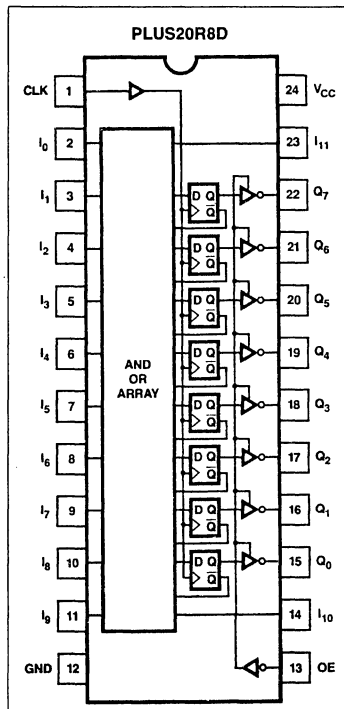
DEVICE NUMBER	DEDICATED INPUTS	COMBINATORIAL OUTPUTS	REGISTERED OUTPUTS	$t_{PD}$	$I_{CC}$	$f_{MAX}$ WITHOUT FEEDBACK	$f_{MAX}$ WITH FEEDBACK
PLUS20L8D	14	8(6 I/O)	0	10ns	210mA		
PLUS20R8D	12	0	8		210mA	62.5MHz	55.5MHz
PLUS20R6D	12	2 I/O	6	10ns	210mA	62.5MHz	55.5MHz
PLUS20R4D	12	4 I/O	4	10ns	210mA	62.5MHz	55.5MHz

PAL<sup>®</sup>-Type Devices

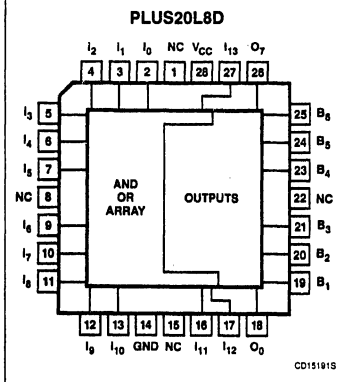
PLUS20R8D Series



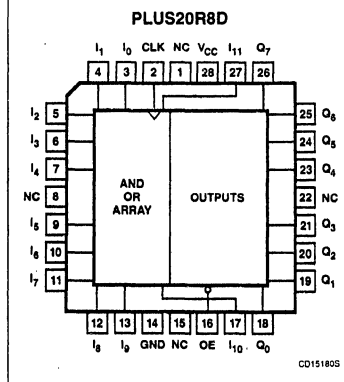
CD152005



CD152005



CD151815

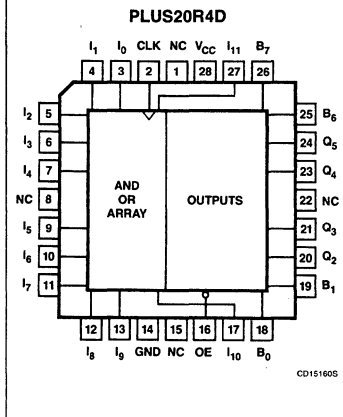
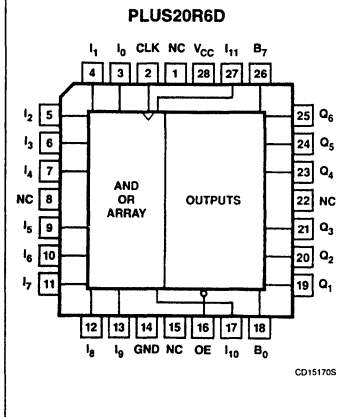
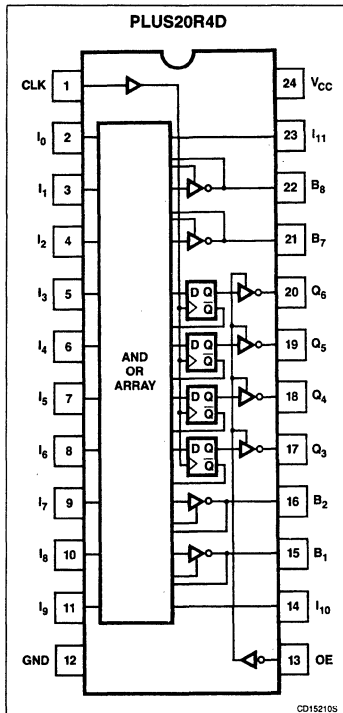
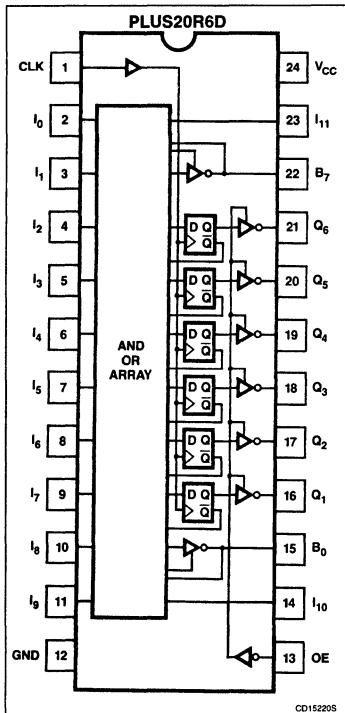


CD151805

3

PAL<sup>®</sup>-Type Devices

PLUS20R8D Series



### INDEX

<b>Series 20</b>	
PLS151	Field-Programmable Gate Array (18 × 15 × 12); 25ns ..... 4-3
PLC153	Erasable and OTP Programmable Logic Array (18 × 32 × 10); 45/60ns ..... 4-9
PLS153	Field-Programmable Logic Array (18 × 42 × 10); 40ns ..... 4-16
PLS153A	Field-Programmable Logic Array (18 × 42 × 10); 30ns ..... 4-22
PLHS153	Field-Programmable Logic Array (18 × 42 × 10); 20ns ..... 4-28
PLUS153B	Field-Programmable Logic Array (18 × 42 × 10); 15ns ..... 4-34
PLUS153D	Field-Programmable Logic Array (18 × 42 × 10); 12ns ..... 4-40
<b>Series 24</b>	
PLS161	Field-Programmable Logic Array (12 × 48 × 8); 50ns ..... 4-46
PLS162	Field-Programmable Address Decoder (16 × 5); 30ns ..... 4-52
PLS163	Field-Programmable Address Decoder (12 × 9); 30ns ..... 4-58
PLS173	Field-Programmable Logic Array (22 × 42 × 10); 30ns ..... 4-64
PLUS173B	Field-Programmable Logic Array (22 × 42 × 10); 15ns ..... 4-70
PLUS173D	Field-Programmable Logic Array (22 × 42 × 10); 12ns ..... 4-76
PLC473-60	Erasable and OTP Programmable Logic Array (20 × 24 × 11); 60ns . 4-82
PLHS473	Field-Programmable Logic Array (20 × 24 × 11); 22ns ..... 4-89
<b>Series 28</b>	
PLS100/101	Programmable Logic Array (16 × 48 × 8); 50ns ..... 4-95
PLS103	Programmable Gate Array (16 × 9 × 9); 35ns ..... 4-102





# PLS151

## Field-Programmable Gate Array (18 × 15 × 12)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

- Series 20

### DESCRIPTION

The PLS151 is a single level logic element, consisting of 15 AND gates with fusible link connections for programming I/O polarity, I/O direction and output enable control.

All gates are linked to 6 inputs (I) and 12 bidirectional I/O lines (B). These yield variable I/O gate configurations via 3 direction control gates (D), ranging from 18 inputs to 12 outputs.

On chip T/C buffers couple either True (I, B) or Complement ( $\bar{I}$ ,  $\bar{B}$ ) input polarities to each AND gate. The polarity of all gate outputs is individually programmable through a set of EX-OR gates for implementing AND/NAND logic functions. Alternately, if desired, OR/NOR logic functions can also be realized by programming for each gate the complement of its inputs and outputs (DeMorgan's Theorem).

The PLS151 is field programmable, enabling the user to quickly generate custom patterns using standard programming equipment.

Order codes are listed in the Ordering Information Table.

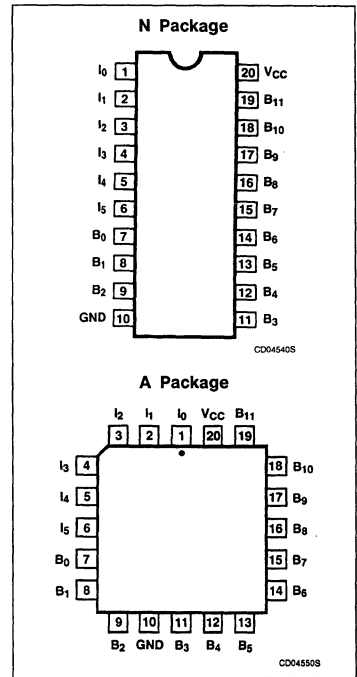
### FEATURES

- Field-Programmable (Ni-Cr link)
- 6 inputs
- 15 product terms:
  - 12 logic terms
  - 3 control terms
- 12 bidirectional I/O lines
- Programmable output polarity
  - Active-High or -Low outputs
- Programmable output enable
- Power dissipation: 575mW (typ.)
- I/O propagation delay: 25ns (max.)
- Input loading: -100 $\mu$ A (max.)
- TTL compatible
- 3-State outputs

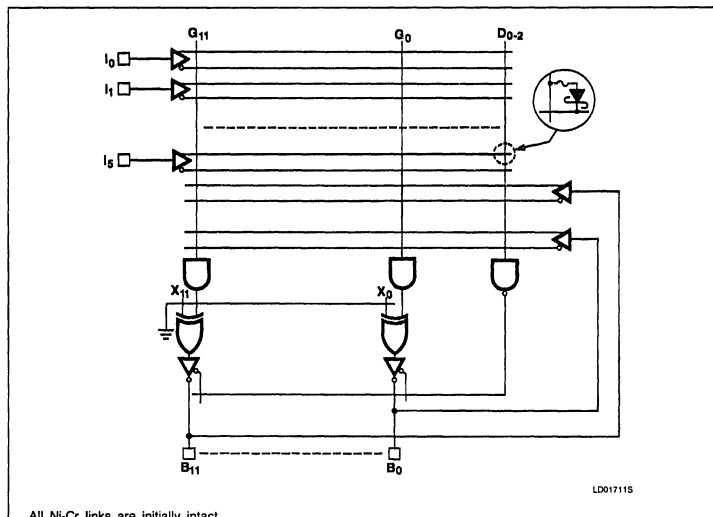
### APPLICATIONS

- Random gating functions
- Address decoding
- Code detectors
- Memory mapped I/O
- Fault monitors
- I/O port decoders

### PIN CONFIGURATIONS



### FUNCTIONAL DIAGRAM



### LOGIC FUNCTION

**TYPICAL OUTPUT FUNCTIONS:**

**ACTIVE-HIGH**

$$X = A \cdot \bar{B} \cdot C \dots$$

**ACTIVE-LOW**

$$X = \bar{A} \cdot \bar{B} \cdot C \dots$$

$$X = \bar{A} + B + \bar{C} + \dots$$

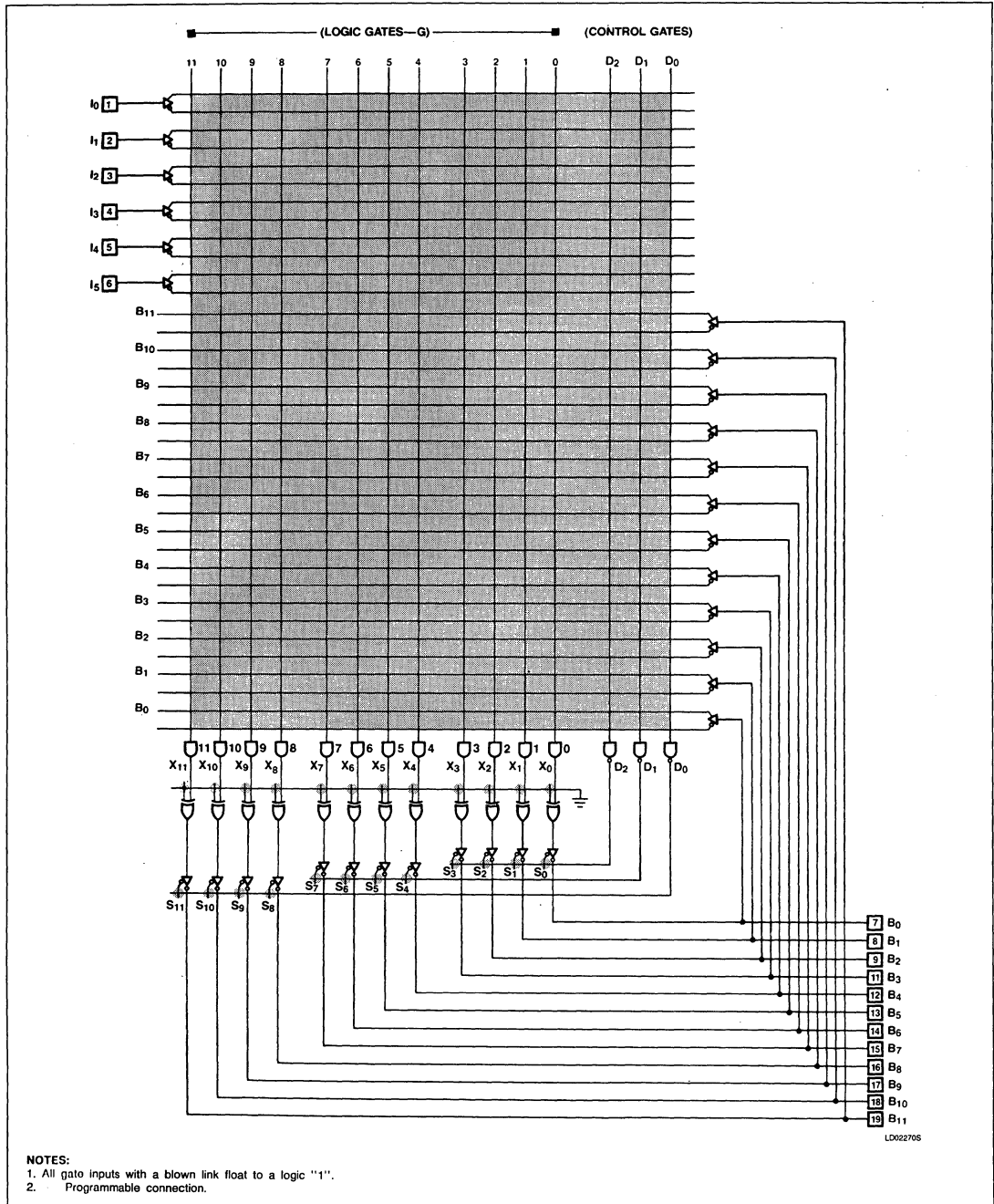
**NOTES:**

- For each of the 12 outputs, either function X (Active-High) or  $\bar{X}$  (Active-Low) is available, but not both. The desired output polarity is programmed via the EX-OR gates.
- X, A, B, C, etc. are user defined connections to fixed inputs (I) and bidirectional pins (B).

# Field-Programmable Gate Array (18 × 15 × 12)

PLS151

## FPGA LOGIC DIAGRAM



# Field-Programmable Gate Array (18 × 15 × 12)

PLS151

**ORDERING INFORMATION**

DESCRIPTION	ORDER CODE
20-pin Plastic DIP 300mil-wide	PLS151N
20-pin Plastic Leaded Chip Carrier	PLS151A

**THERMAL RATINGS**

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

**ABSOLUTE MAXIMUM RATINGS<sup>1</sup>**

SYMBOL	PARAMETER	RATINGS <sup>1</sup>		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

**NOTE:**

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other conditions above those indicated in the operational and programming specification of the device is not implied.

**DC ELECTRICAL CHARACTERISTICS** 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75V ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min	2.0		0.8	V
V <sub>IH</sub>	High	V <sub>CC</sub> = Max			V	
V <sub>IC</sub>	Clamp <sup>2, 3</sup>	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA			-1.2	V
<b>Output voltage<sup>2</sup></b>						
V <sub>OL</sub>	Low	V <sub>CC</sub> = Min	2.4		0.5	V
V <sub>OH</sub>	High	I <sub>OL</sub> = 10mA I <sub>OH</sub> = -2mA				V
<b>Input current<sup>6</sup></b>						
I <sub>IL</sub>	Low	V <sub>CC</sub> = Max			-100	μA
I <sub>IH</sub>	High	V <sub>IN</sub> = 0.45V V <sub>IN</sub> = 5.5V				40
<b>Output current</b>						
I <sub>O(OFF)</sub>	Hi-Z state	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V	-15		80	μA
I <sub>OS</sub>	Short circuit <sup>3, 4</sup>	V <sub>OUT</sub> = 0.45V V <sub>OUT</sub> = 0V			-70	mA
I <sub>CC</sub>	V <sub>CC</sub> supply current	V <sub>CC</sub> = Max		115	155	mA
<b>Capacitance</b>						
C <sub>IN</sub>	Input	V <sub>CC</sub> = 5V			8	pF
C <sub>B</sub>	I/O	V <sub>IN</sub> = 2.0V V <sub>B</sub> = 2.0V			15	pF

Notes on following page.

# Field-Programmable Gate Array (18 × 15 × 12)

PLS151

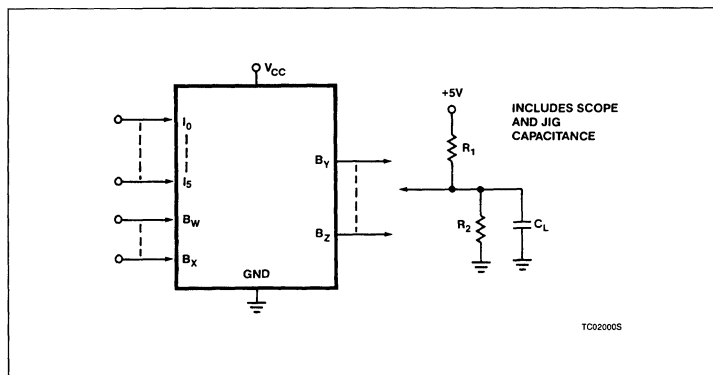
## AC ELECTRICAL CHARACTERISTICS $R_1 = 470\Omega$ , $R_2 = 1k\Omega$ , $0^\circ C \leq T_A \leq +75^\circ C$ , $4.75V \leq V_{CC} \leq 5.25V$

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ <sup>1</sup>	Max	
$t_{PD}$	Propagation delay	Output $\pm$	Input $\pm$	$C_L = 30pF$		16	25	ns
$t_{OE}$	Output enable	Output -	Input $\pm$			17	25	ns
$t_{OD}$	Output disable <sup>5</sup>	Output +	Input $\pm$	$C_L = 5pF$		17	25	ns

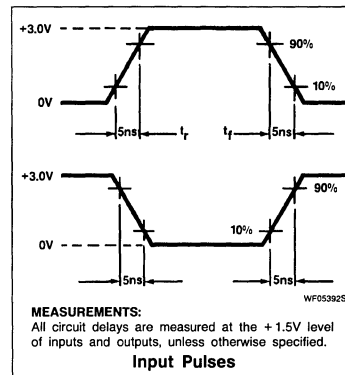
**NOTES:**

1. All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
2. All voltage values are with respect to network ground terminal.
3. Test one pin at a time.
4. Duration of short circuit should not exceed 1 second.
5. Measured at  $V_T = V_{OL} + 0.5V$ .
6.  $I_{IL}$  and  $I_{IH}$  limits are for dedicated inputs only ( $I_O - I_S$ ).

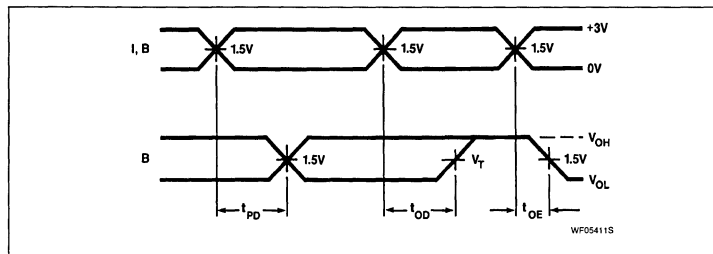
### TEST LOAD CIRCUITS



### VOLTAGE WAVEFORMS



### TIMING DIAGRAM



### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Propagation delay between input and output.
$t_{OD}$	Delay between input change and when output is off (Hi-Z or High).
$t_{OE}$	Delay between input change and when output reflects specified output level.

# Field-Programmable Gate Array (18 × 15 × 12)

PLS151

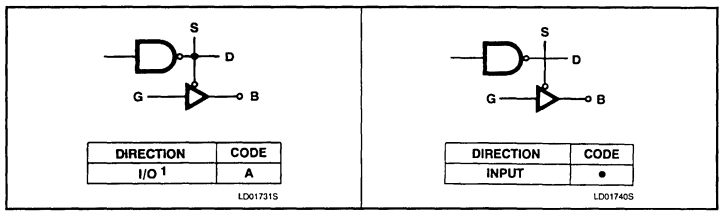
## LOGIC PROGRAMMING

In a virgin device all Ni-Cr links are intact. PLS151 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

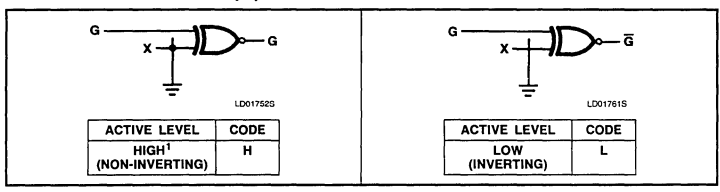
PLS151 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

## I/O DIRECTION - (B)



## OUTPUT POLARITY - (B)



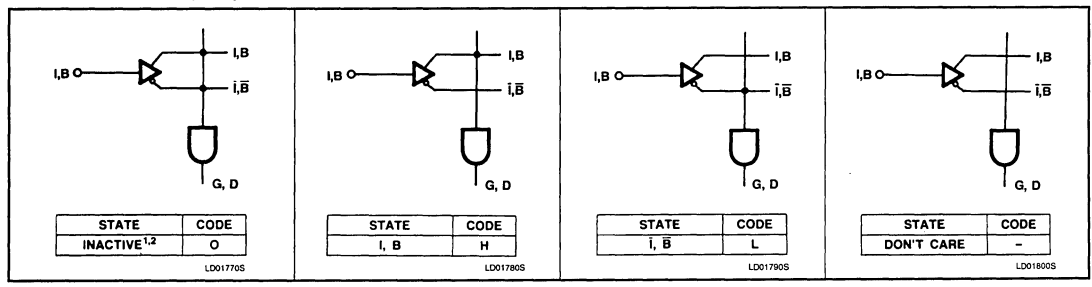
4

## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

1. All outputs are at 'H' polarity.
2. All P<sub>n</sub> terms are disabled.
3. All P<sub>n</sub> terms are active on all outputs.
4. All B terms are I/O unless otherwise programmed.

## "AND" ARRAY - (I, B)



### NOTES:

1. This is the initial unprogrammed state of all links.
2. Any gate P<sub>n</sub> will be unconditionally inhibited if both the True and Complement of an input (either I or B) are left intact.



### Application Specific Products • Series 20

### Signetics Programmable Logic Product Specification

#### DESCRIPTION

The PLC153 CMOS devices are two-level logic Erasable and OTP (One Time Programmable) Programmable Logic Arrays. The PLC153 devices are low power versions of the Signetics PLS153/153A and PLHS153 Bipolar Programmable Logic devices. EPROM cells provide the connections for the programmable AND array, the programmable OR array and the Ex-OR output polarity gates.

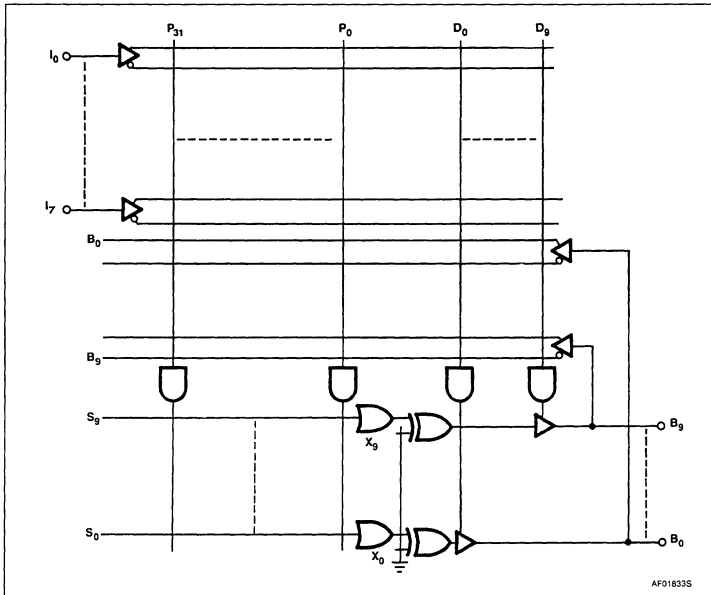
On-chip buffers couple either True (I, B) or Complement ( $\bar{I}$ ,  $\bar{B}$ ) inputs to all AND gates, whose outputs can be optionally linked to all OR gates. Their output polarity, in turn, is individually programmable through a set of Ex-OR gates for implementing AND/OR or AND/NOR logic functions.

The PLC153 is field-programmable, using Floating-Gate EPROM cells. This enables the generation of custom logic patterns using standard programming equipment.

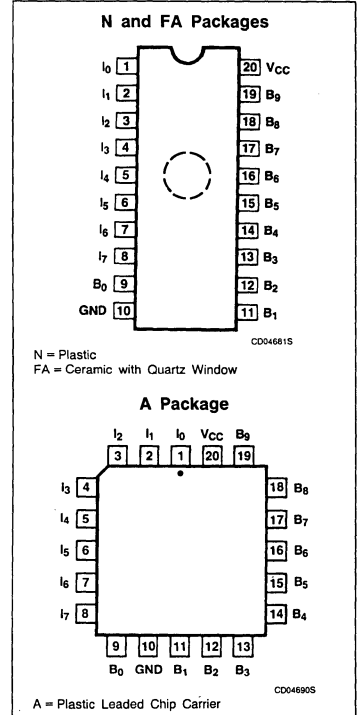
#### FEATURES

- Low power, 100% functional replacement for PLS153 Series PLAs
- EPROM cell technology
  - Erasable (quartz window package only)
  - 100% Testable
  - Reconfigurable
- 8 dedicated inputs
- 42 AND gates
- 10 OR gates
- 10 bidirectional I/O lines
- Active-High or -Low outputs
- 42 product terms:
  - 32 logic terms
  - 10 control terms
- I/O propagation delay: 45 and 60ns (max.)
- Input loading: - 10 $\mu$ A (max)
- Power dissipation: 60mA at 15MHz (max)
- 3-State outputs
- CMOS and TTL compatible

#### FUNCTIONAL DIAGRAM



#### PIN CONFIGURATIONS



#### APPLICATIONS

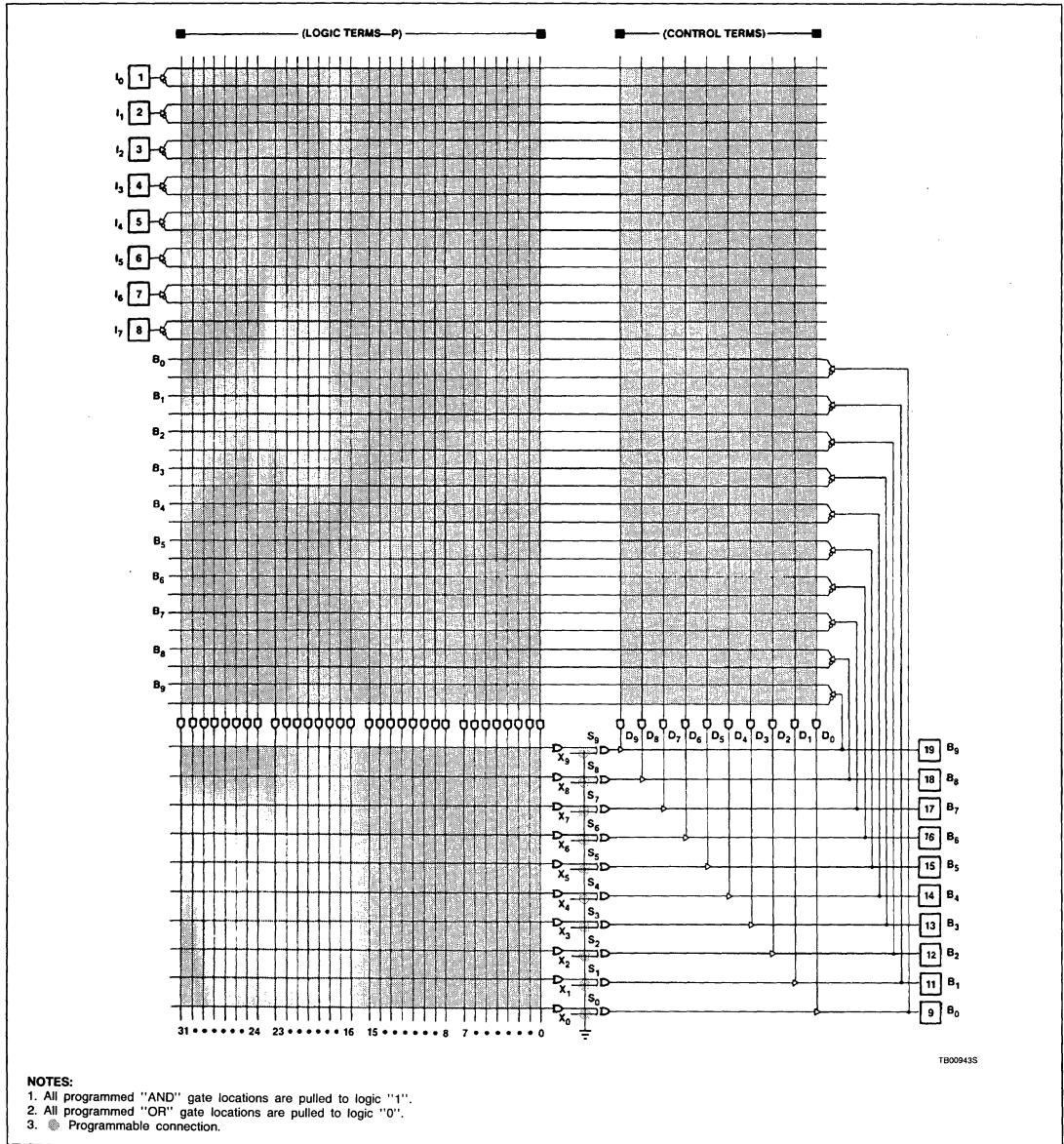
- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping
- Multiplexing



# Programmable Logic Array (18 × 42 × 10)

PLC153

## FPLA LOGIC DIAGRAM



## Programmable Logic Array (18 × 42 × 10)

PLC153

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
20-Pin Ceramic DIP with Window (300mil-wide)	PLC153-45FA
	PLC153-60FA
20-Pin Plastic DIP (300mil-wide)	PLC153-45N
	PLC153-60N
20-Pin Plastic Leaded Chip Carrier	PLC153-45A
	PLC153-60A

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	70°C
Allowable thermal rise ambient to junction	70°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	V <sub>CC</sub> + 0.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage	V <sub>CC</sub> + 0.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30 to +30	mA
I <sub>OUT</sub>	Output currents	+100	mA
T <sub>A</sub>	Operating temperature range	0 to +70	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ +70°C, 4.75 ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT	
			Min	Typ <sup>1</sup>	Max		
<b>Input voltage<sup>2</sup></b>							
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min	-0.3		0.8	V	
V <sub>IH</sub>	High	V <sub>CC</sub> = Max	2.0		V <sub>CC</sub> + 0.3	V	
<b>Output voltage<sup>2</sup></b>							
V <sub>OL</sub>	Low	V <sub>CC</sub> = Min I <sub>OL</sub> = 8mA			0.45	V	
V <sub>OH</sub>	High	I <sub>OH</sub> = -3mA	2.4			V	
<b>Input current<sup>10</sup></b>							
I <sub>IL</sub>	Low	V <sub>IN</sub> = GND			-10	μA	
I <sub>IH</sub>	High	V <sub>IN</sub> = V <sub>CC</sub>			10	μA	
<b>Output current</b>							
I <sub>O(OFF)</sub>	Hi-Z state <sup>7</sup>	V <sub>OUT</sub> = V <sub>CC</sub> V <sub>OUT</sub> = GND			10 -10	μA μA	
I <sub>OS</sub>	Short circuit <sup>3, 6</sup>	V <sub>OUT</sub> = GND	-15		-70	mA	
I <sub>CC</sub>	V <sub>CC</sub> supply current (Active) <sup>4, 5, 9</sup>	No load f = 15MHz		TTL inputs	48	60	mA
<b>Capacitance</b>							
C <sub>IN</sub>	Input I/O (bidirectional)	V <sub>CC</sub> = 5V			6	pF	
C <sub>B</sub>		V <sub>IN</sub> = 2.0V V <sub>B</sub> = 2.0V			12	pF	

Notes on following page.

# Programmable Logic Array (18 × 42 × 10)

PLC153

## AC ELECTRICAL CHARACTERISTICS $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ , $4.75 \leq V_{CC} \leq 5.25\text{V}$ , $R_1 = 470\Omega$ , $R_2 = 1\text{k}\Omega$

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	PLC153-45		PLC153-60		UNIT
					Min	Max	Min	Max	
$t_{PD}$	Propagation delay	Output $\pm$	Input $\pm$	$C_L = 30\text{pF}$		45		60	ns
$t_{OE}$	Output enable	Output -	Input $\pm$	$C_L = 30\text{pF}$		45		60	ns
$t_{OD}$	Output disable <sup>B</sup>	Output +	Input $\pm$	$C_L = 5\text{pF}$		45		60	ns

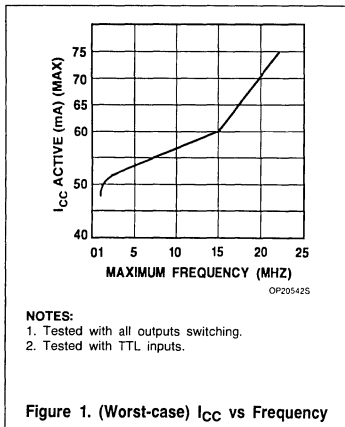
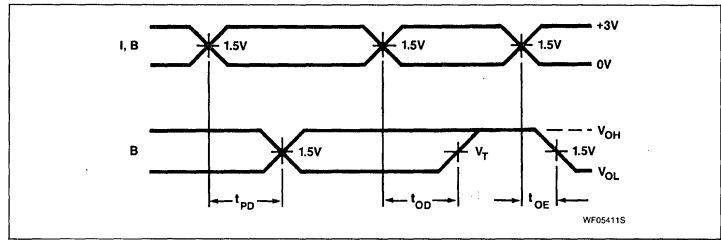
**NOTES:**

1. All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
2. All voltage values are with respect to network ground terminal.
3. Test one at a time.
4. TTL inputs:  $V_{IL} = 0.45\text{V}$ ,  $V_{IH} = 2.4\text{V}$
5. Measured with all inputs and outputs switching.
6. Duration of short circuit should not exceed 1 second.
7. Leakage values are a combination of input and output leakage.
8. Measured at  $V_T = V_{OL} + 0.5\text{V}$ .
9. Refer to Figure 1 for worst case  $I_{CC}$  vs frequency specifications.
10. Pin 1 ( $V_{pp}$ ) has an input leakage current of  $100\mu\text{A}$ .

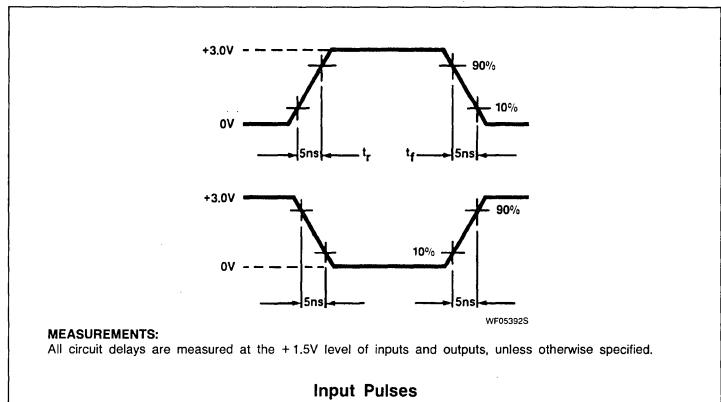
**TIMING DEFINITIONS**

SYMBOL	PARAMETER
$t_{PD}$	Propagation delay between input and output.
$t_{OD}$	Delay between input change and when output is off (Hi-Z or High).
$t_{OE}$	Delay between input change and when output reflects specified output level.

**TIMING DIAGRAM**



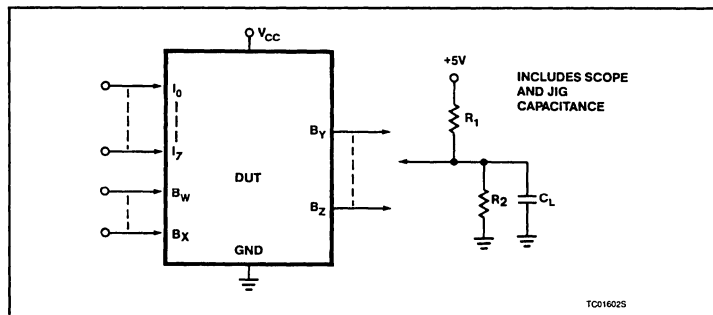
**VOLTAGE WAVEFORMS**



# Programmable Logic Array (18 × 42 × 10)

PLC153

## TEST LOAD CIRCUITS



## LOGIC PROGRAMMING

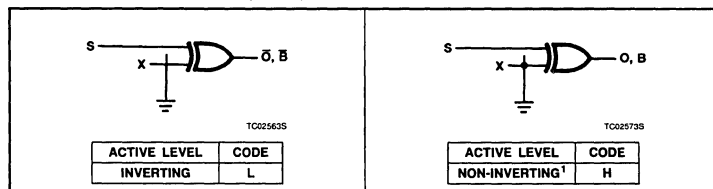
The EPLA can be programmed by means of Logic programming equipment.

With Logic programming, the AND/OR/EX-OR gate input connections necessary to implement the desired logic function are coded directly from logic equations using the Program Table on the following page.

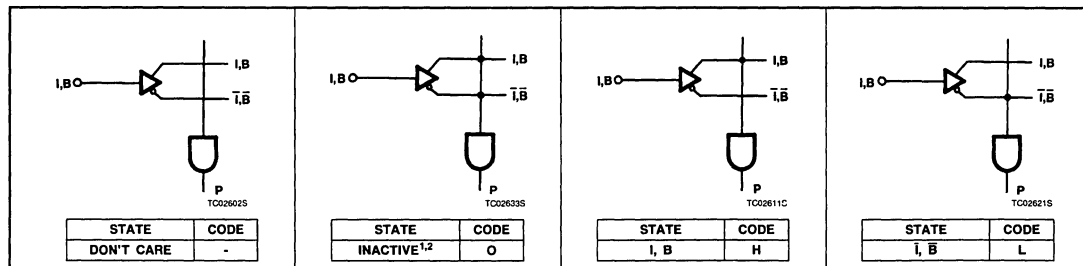
In this table, the logic state of variables I, P, and B associated with each Sum Term S is assigned a symbol which results in the proper fusing pattern of corresponding link pairs, defined as follows:

4

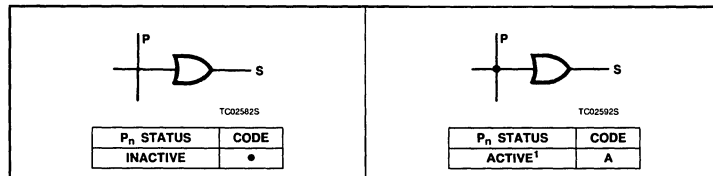
## OUTPUT POLARITY — (O, B)



## "AND" ARRAY — (I, B)



## "OR" ARRAY — (O, B)



## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

1. All outputs are at "H" polarity.
2. All P<sub>n</sub> terms are inactive.
3. All P<sub>n</sub> terms are active in the OR array.

### NOTES:

1. This is the initial unprogrammed state of all link pairs.
2. Any Product Term (P<sub>n</sub>) will always be inactive if one of its input pairs (I, B) is left unprogrammed as shown.

**Programmable Logic Array (18 × 42 × 10)****PLC153****ERASURE CHARACTERISTICS  
(For Quartz Window Packages  
Only)**

The erasure characteristics of the PLC153 Series devices are such that erasure begins to occur upon exposure to light with wavelengths shorter than approximately 4000 Angstroms (Å). It should be noted that sunlight and certain types of fluorescent lamps have wavelengths in the 3000 - 4000Å range. Data shows that constant exposure to room level fluorescent lighting could erase a typical PLC153 in approximately three years, while it

would take approximately one week to cause erasure when exposed to direct sunlight. If the PLC153 is to be exposed to these types of lighting conditions for extended periods of time, opaque labels should be placed over the window to prevent unintentional erasure.

The recommended erasure procedure for the PLC153 is exposure to shortwave ultraviolet light which has a wavelength of 2537 Angstroms (Å). The integrated dose (i.e., UV intensity × exposure time) for erasure should be a minimum of 15Wsec/cm<sup>2</sup>. The erasure time with this dosage is approximately 30 to

35 minutes using an ultraviolet lamp with a 12,000μW/cm<sup>2</sup> power rating. The device should be placed within one inch of the lamp tubes during erasure. The maximum integrated dose a CMOS EPLD can be exposed to without damage is 7258Wsec/cm<sup>2</sup> (1 week @ 12000μW/cm<sup>2</sup>). Exposure of these CMOS to high intensity UV light for longer periods may cause permanent damage.

The maximum number of guaranteed erase/write cycles is 50. Data retention exceeds 20 years.



# PLS153

## Field-Programmable Logic Array (18 × 42 × 10)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

- Series 20

### DESCRIPTION

The PLS153 is a two-level logic element, consisting of 42 AND gates and 10 OR gates with fusible link connections for programming I/O polarity and direction.

All AND gates are linked to 8 inputs (I) and 10 bidirectional I/O lines (B). These yield variable I/O gate configurations via 10 direction control gates (D), ranging from 18 inputs to 10 outputs.

On chip T/C buffers couple either True (I, B) or Complement (I, B) input polarities to all AND gates, whose outputs can be optionally linked to all OR gates. Their output polarity, in turn, is individually programmable through a set of EX-OR gates for implementing AND/OR or AND/NOR logic functions.

The PLS153 is field programmable, enabling the user to quickly generate custom patterns using standard programming equipment.

Order codes are listed in the Ordering Information Table.

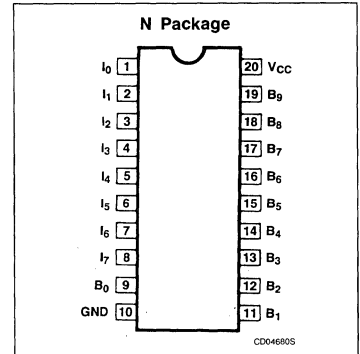
### FEATURES

- Field-Programmable (Ni-Cr links)
- 8 inputs
- 42 AND gates
- 10 OR gates
- 10 bidirectional I/O lines
- Active-High or -Low outputs
- 42 product terms:
  - 32 logic terms
  - 10 control terms
- I/O propagation delay: 40ns (max.)
- Input loading: -100µA (max.)
- Power dissipation: 650mW (typ.)
- 3-State outputs
- TTL compatible

### APPLICATIONS

- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping
- Multiplexing

### PIN CONFIGURATION



### LOGIC FUNCTION

**TYPICAL PRODUCT TERM:**  
 $P_n = A \cdot B \cdot C \cdot D \cdot \dots$

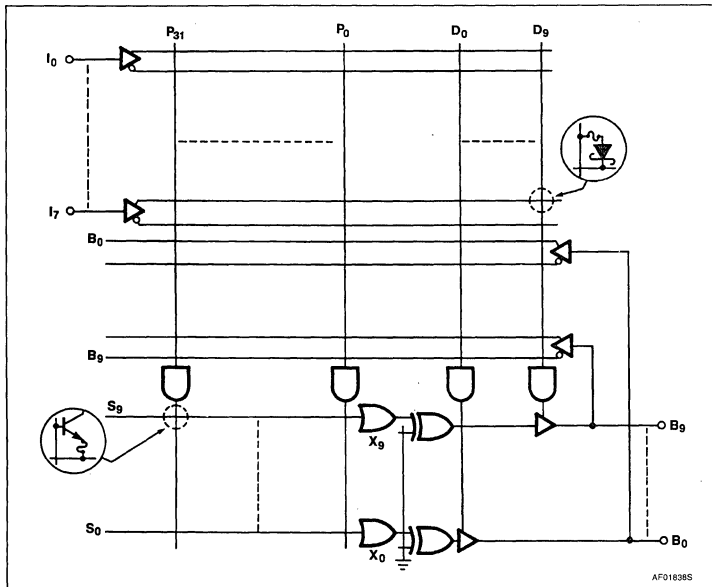
**TYPICAL LOGIC FUNCTION:**  
 AT OUTPUT POLARITY = H  
 $Z = P_0 + P_1 + P_2 \dots$

AT OUTPUT POLARITY = L  
 $Z = \bar{P}_0 + \bar{P}_1 + \bar{P}_2 \dots$   
 $Z = P_0 \cdot P_1 \cdot P_2 \dots$

**NOTES:**

1. For each of the 10 outputs, either function Z (Active-High) or  $\bar{Z}$  (Active-Low) is available, but not both. The desired output polarity is programmed via the EX-OR gates.
2. Z, A, B, C, etc. are user defined connections to fixed inputs (I) and bidirectional pins (B).

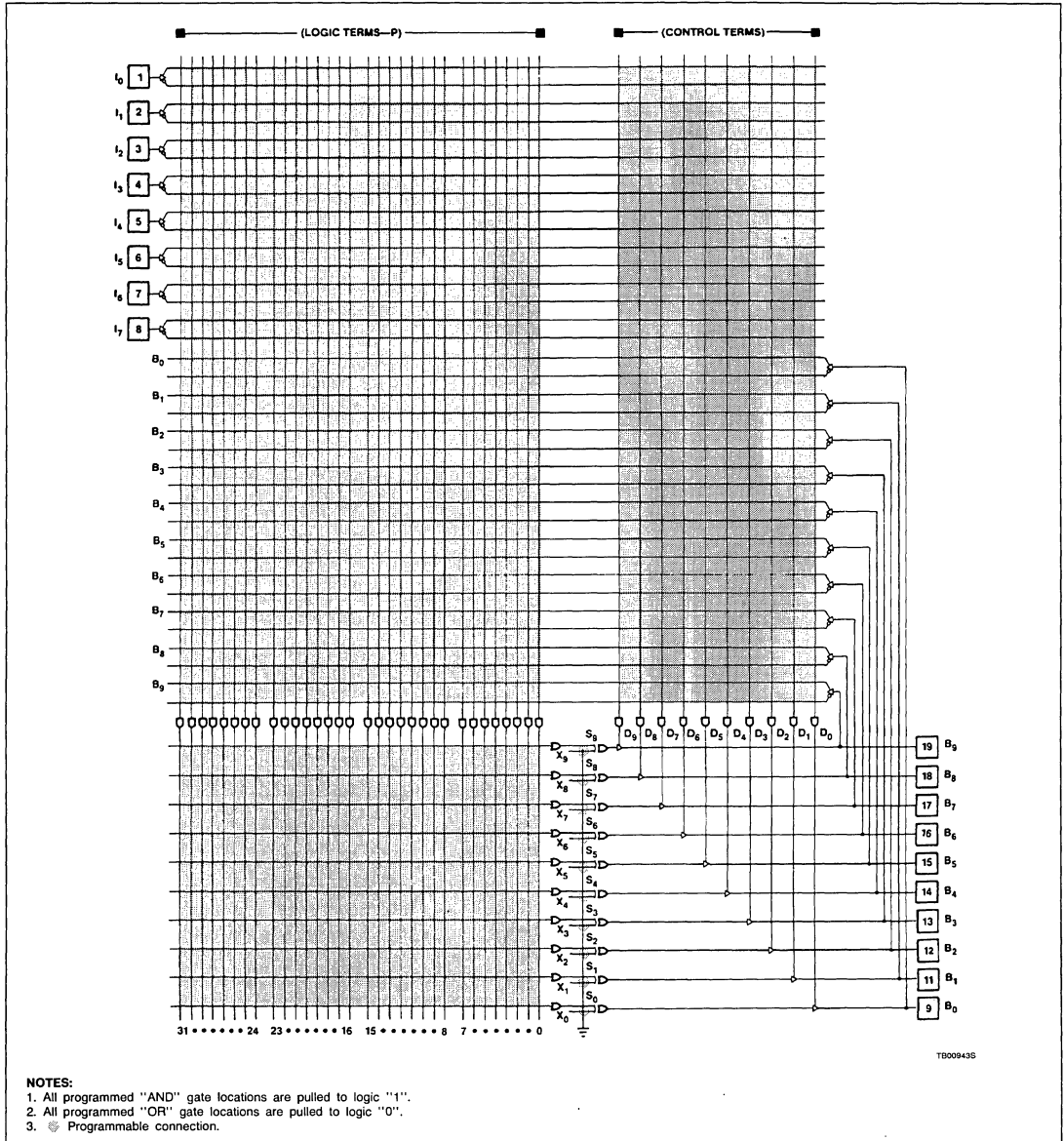
### FUNCTIONAL DIAGRAM



# Field-Programmable Logic Array (18 × 42 × 10)

PLS153

## FPLA LOGIC DIAGRAM



4



## Field-Programmable Logic Array (18 × 42 × 10)

PLS153

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
20-pin Plastic DIP 300mil-wide	PLS153N

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other conditions above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ 75°C, 4.75V ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IL</sub> V <sub>IH</sub> V <sub>IC</sub>	Low High Clamp <sup>2, 3</sup>	V <sub>CC</sub> = Min V <sub>CC</sub> = Max V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA	2.0		0.8 -0.8 -1.2	V V V
<b>Output voltage</b>						
V <sub>OL</sub> V <sub>OH</sub>	Low <sup>2, 4</sup> High <sup>2, 5</sup>	V <sub>CC</sub> = Min I <sub>OL</sub> = 15mA I <sub>OH</sub> = -2mA	2.4		0.5	V V
<b>Input current<sup>10</sup></b>						
I <sub>IL</sub> I <sub>IH</sub>	Low High	V <sub>CC</sub> = Max V <sub>IN</sub> = 0.45V V <sub>IN</sub> = 5.5V			-100 40	μA μA
<b>Output current</b>						
I <sub>O(OFF)</sub> I <sub>OS</sub> I <sub>CC</sub>	Hi-Z state <sup>9</sup> Short circuit <sup>3, 5, 6</sup> V <sub>CC</sub> supply current <sup>7</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V V <sub>OUT</sub> = 0.45V V <sub>OUT</sub> = 0V V <sub>CC</sub> = Max	-15		80 -140 -70 130 155	μA mA mA
<b>Capacitance</b>						
C <sub>IN</sub> C <sub>B</sub>	Input I/O	V <sub>CC</sub> = 5V V <sub>IN</sub> = 2.0V V <sub>B</sub> = 2.0V		8 15		pF pF

Notes on following page.

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

The PLS153 device is also processed to military requirements for operation over the military temperature range. For specifications and ordering information consult the Signetics Military Data Book.

# Field-Programmable Logic Array (18 × 42 × 10)

PLS153

## AC ELECTRICAL CHARACTERISTICS $R_1 = 470\Omega$ , $R_2 = 1k\Omega$ , $0^\circ C \leq T_A \leq +75^\circ C$ , $4.75V \leq V_{CC} \leq 5.25V$

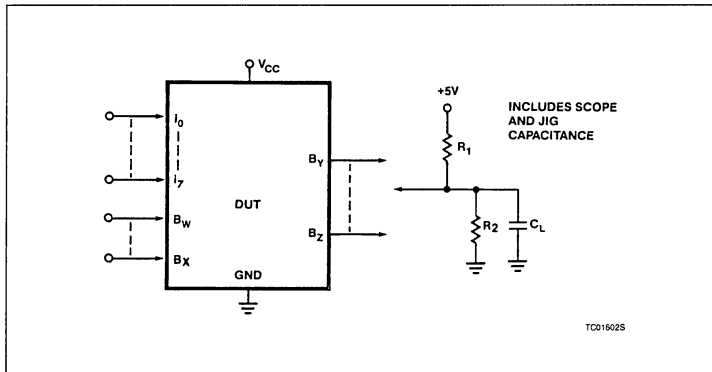
SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ <sup>1</sup>	Max	
$t_{PD}$	Propagation delay	Output $\pm$	Input $\pm$	$C_L = 30pF$		30	40	ns
$t_{OE}$	Output enable	Output -	Input $\pm$	$C_L = 30pF$		25	35	ns
$t_{OD}$	Output disable <sup>8</sup>	Output +	Input $\pm$	$C_L = 5pF$		25	35	ns

**NOTES:**

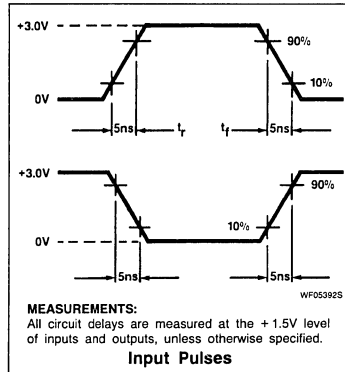
1. All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
2. All voltage values are with respect to network ground terminal.
3. Test one at a time.
4. Measured with +10V applied to  $I_7$ .
5. Measured with +10V applied to  $I_0-7$ . Output sink current is supplied through a resistor to  $V_{CC}$ .
6. Duration of short circuit should not exceed 1 second.
7.  $I_{CC}$  is measured with  $I_0, I_1$  at 0V,  $I_2-I_7$  and  $B_0-9$  at 4.5V.
8. Measured at  $V_T = V_{OL} + 0.5V$ .
9. Leakage values are a combination of input and output leakage.
10.  $I_{LH}$  and  $I_{HL}$  limits are for dedicated inputs only ( $I_0-I_7$ ).

4

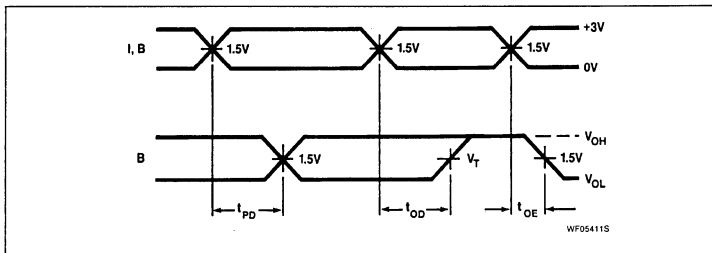
### TEST LOAD CIRCUITS



### VOLTAGE WAVEFORMS



### TIMING DIAGRAM



### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Propagation delay between input and output.
$t_{OD}$	Delay between input change and when output is off (Hi-Z or High).
$t_{OE}$	Delay between input change and when output reflects specified output level.

# Field-Programmable Logic Array (18 × 42 × 10)

PLS153

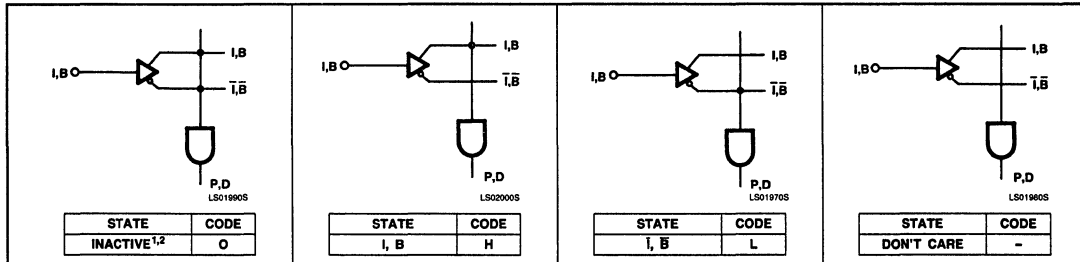
## LOGIC PROGRAMMING

PLS153 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

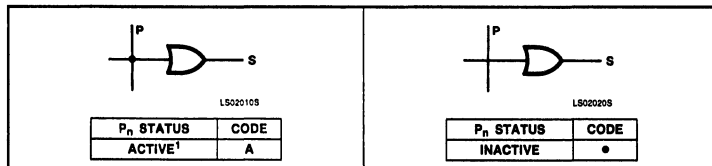
PLS153 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

## "AND" ARRAY - (I, B)



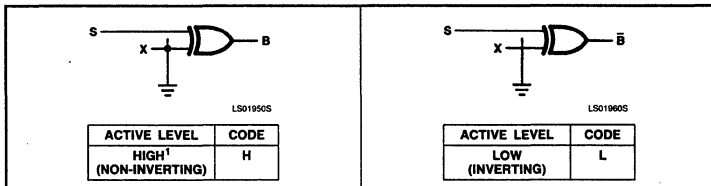
## OR ARRAY - (B)



### NOTES:

1. This is the initial unprogrammed state of all links.
2. Any gate P<sub>n</sub> will be unconditionally inhibited if both the True and Complement of an input (either I or B) are left intact.

## OUTPUT POLARITY - (B)



## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

1. All outputs are at "H" polarity.
2. All P<sub>n</sub> terms are disabled.
3. All P<sub>n</sub> terms are active on all outputs.



## PLS153A Field-Programmable Logic Array (18 × 42 × 10)

Signetics Programmable Logic  
Product Specification

### Application Specific Products • Series 20

#### DESCRIPTION

The PLS153A is a two-level logic element, consisting of 42 AND gates and 10 OR gates with fusible link connections for programming I/O polarity and direction.

All AND gates are linked to 8 inputs (I) and 10 bidirectional I/O lines (B). These yield variable I/O gate configurations via 10 direction control gates (D), ranging from 18 inputs to 10 outputs.

On chip T/C buffers couple either True (I, B) or Complement (I,  $\bar{B}$ ) input polarities to all AND gates, whose outputs can be optionally linked to all OR gates. Their output polarity, in turn, is individually programmable through a set of EX-OR gates for implementing AND/OR or AND/NOR logic functions.

The PLS153A is field programmable, enabling the user to quickly generate custom patterns using standard programming equipment.

Order codes are listed in the Ordering Information Table.

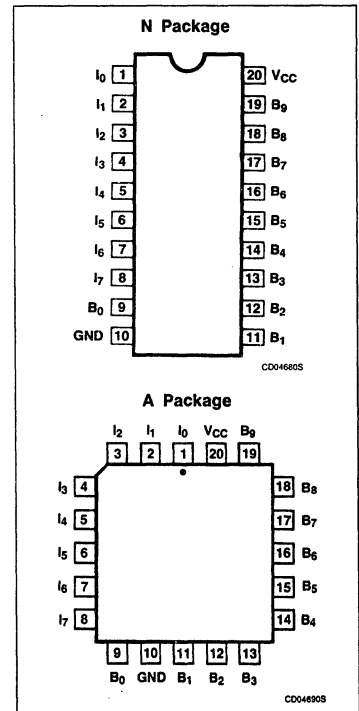
#### FEATURES

- Field-Programmable (Ni-Cr links)
- 8 inputs
- 42 AND gates
- 10 OR gates
- 10 bidirectional I/O lines
- Active-High or -Low outputs
- 42 product terms:
  - 32 logic terms
  - 10 control terms
- I/O propagation delay: 30ns (max.)
- Input loading: -100 $\mu$ A (max.)
- Power dissipation: 650mW (typ.)
- 3-State outputs
- TTL compatible

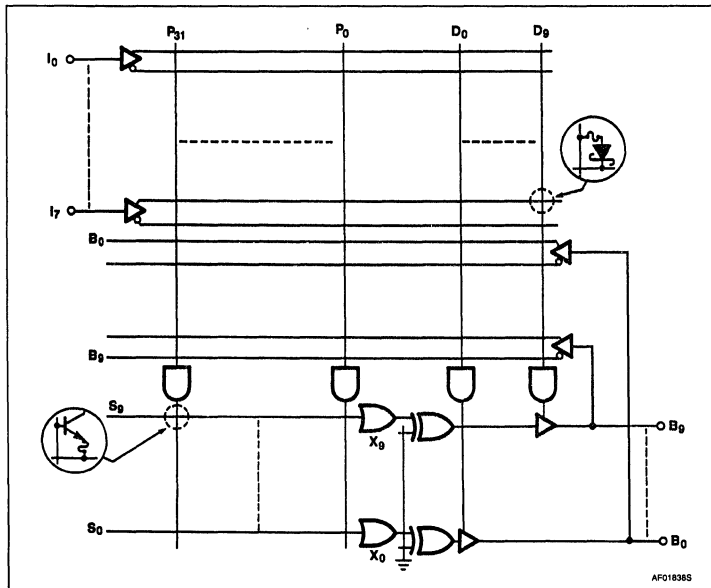
#### APPLICATIONS

- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping
- Multiplexing

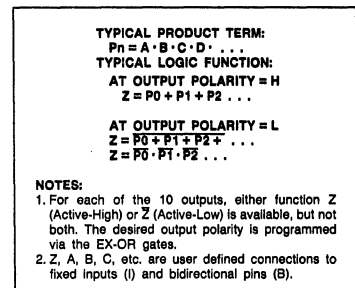
#### PIN CONFIGURATIONS



#### FUNCTIONAL DIAGRAM



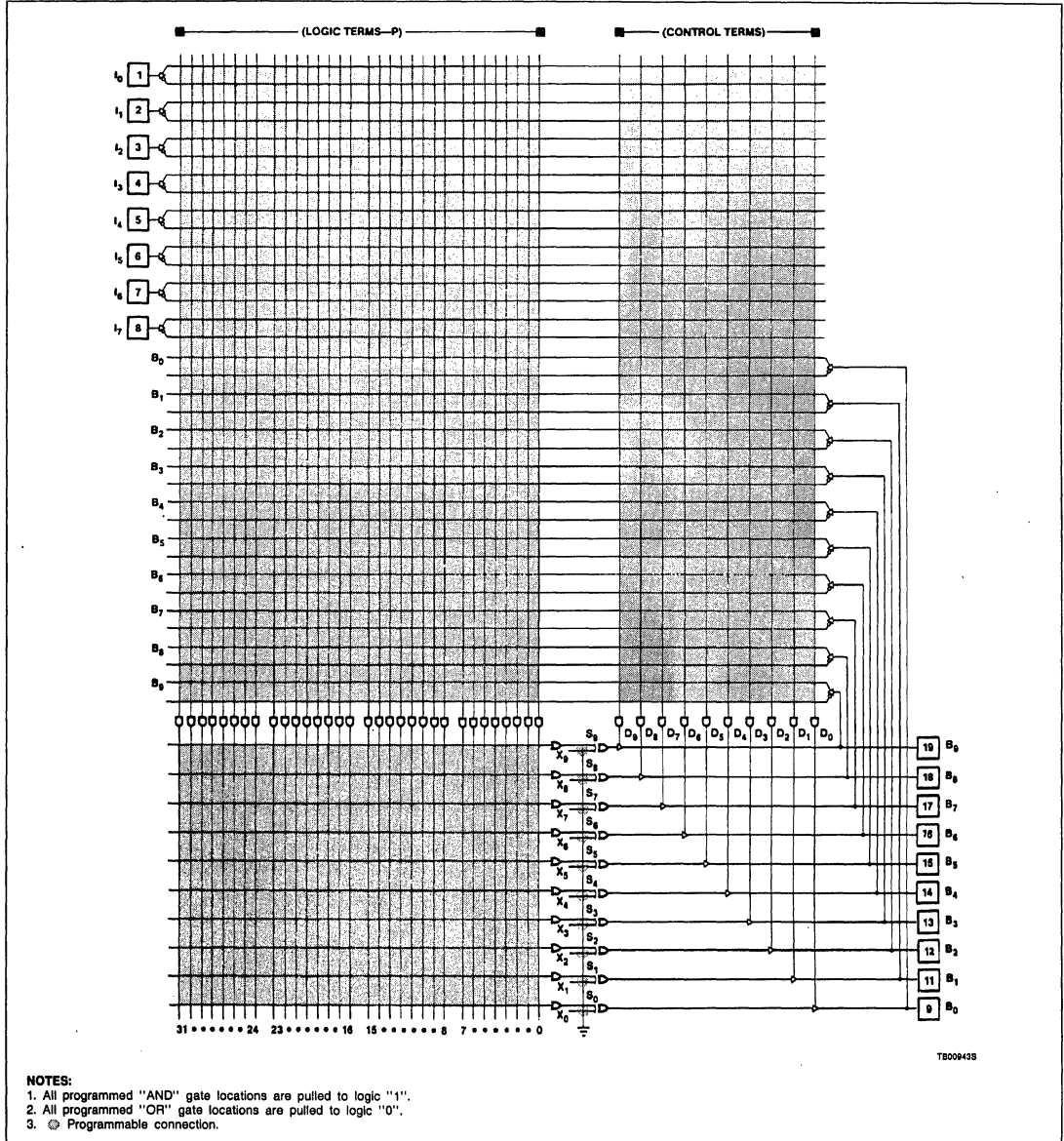
#### LOGIC FUNCTION



# Field-Programmable Logic Array (18 × 42 × 10)

PLS153A

## FPLA LOGIC DIAGRAM



4

## Field-Programmable Logic Array (18 × 42 × 10)

PLS153A

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
20-pin Plastic DIP 300mil-wide	PLS153AN
20-pin Plastic Leaded Chip Carrier	PLS153AA

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other conditions above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ 75°C, 4.75V ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IL</sub> V <sub>IH</sub> V <sub>IC</sub>	Low High Clamp <sup>2, 3</sup>	V <sub>CC</sub> = Min V <sub>CC</sub> = Max V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA	2.0		0.8 -0.8 -1.2	V V V
<b>Output voltage</b>						
V <sub>OL</sub> V <sub>OH</sub>	Low <sup>2, 4</sup> High <sup>2, 5</sup>	V <sub>CC</sub> = Min I <sub>OL</sub> = 15mA I <sub>OH</sub> = -2mA	2.4		0.5	V V
<b>Input current<sup>10</sup></b>						
I <sub>IL</sub> I <sub>IH</sub>	Low High	V <sub>CC</sub> = Max V <sub>IN</sub> = 0.45V V <sub>IN</sub> = 5.5V			-100 40	μA μA
<b>Output current</b>						
I <sub>O(OFF)</sub> I <sub>OS</sub>	Hi-Z state <sup>9</sup> Short circuit <sup>3, 5, 6</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V V <sub>OUT</sub> = 0.45V V <sub>OUT</sub> = 0V	-15		80 -140 -70	μA mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>7</sup>	V <sub>CC</sub> = Max		130	155	mA
<b>Capacitance</b>						
C <sub>IN</sub> C <sub>B</sub>	Input I/O	V <sub>CC</sub> = 5V V <sub>IN</sub> = 2.0V V <sub>B</sub> = 2.0V		8 15		pF pF

Notes on following page.

# Field-Programmable Logic Array (18 × 42 × 10)

PLS153A

## AC ELECTRICAL CHARACTERISTICS $R_1 = 470\Omega$ , $R_2 = 1k\Omega$ , $0^\circ C \leq T_A \leq +75^\circ C$ , $4.75V \leq V_{CC} \leq 5.25V$

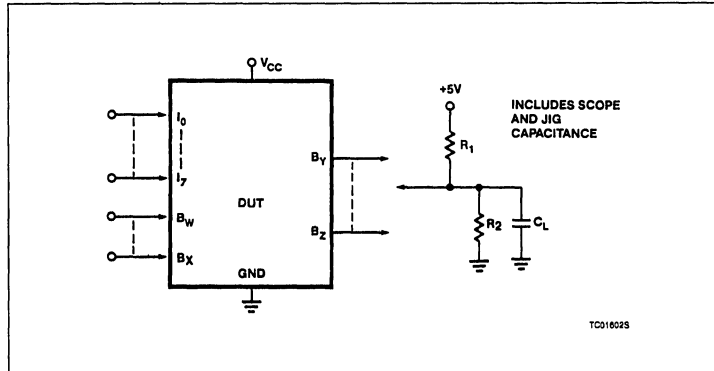
SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ <sup>1</sup>	Max	
$t_{PD}$	Propagation delay	Output $\pm$	Input $\pm$	$C_L = 30pF$		20	30	ns
$t_{OE}$	Output enable	Output $\pm$	Input $\pm$	$C_L = 30pF$		20	30	ns
$t_{OD}$	Output disable <sup>8</sup>	Output $\pm$	Input $\pm$	$C_L = 5pF$		20	30	ns

**NOTES:**

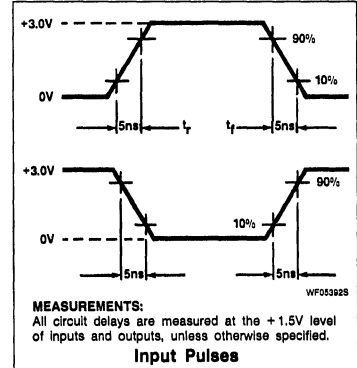
1. All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
2. All voltage values are with respect to network ground terminal.
3. Test one at a time.
4. Measured with +10V applied to  $I_7$ .
5. Measured with +10V applied to  $I_{0-7}$ . Output sink current is supplied through a resistor to  $V_{CC}$ .
6. Duration of short circuit should not exceed 1 second.
7.  $I_{CC}$  is measured with  $I_{0,1}$  at 0V and  $I_{2-7}$  and  $B_{0-9}$  at 4.5V.
8. Measured at  $V_T = V_{OL} + 0.5V$ .
9. Leakage values are a combination of input and output leakage.
10.  $I_{IH}$  and  $I_{IL}$  limits are for dedicated inputs only ( $I_{0-10}$ ).

4

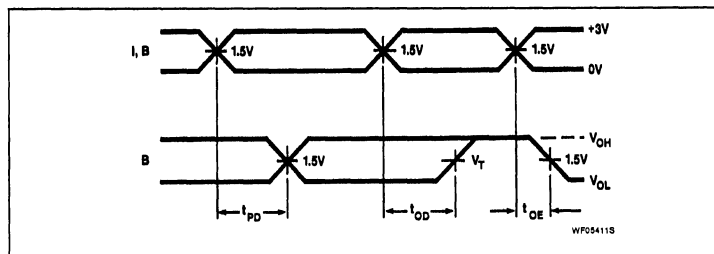
### TEST LOAD CIRCUITS



### VOLTAGE WAVEFORMS



### TIMING DIAGRAM



### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Propagation delay between input and output.
$t_{OD}$	Delay between input change and when output is off (Hi-Z or High).
$t_{OE}$	Delay between input change and when output reflects specified output level.



# Field-Programmable Logic Array (18 × 42 × 10)

# PLS153A

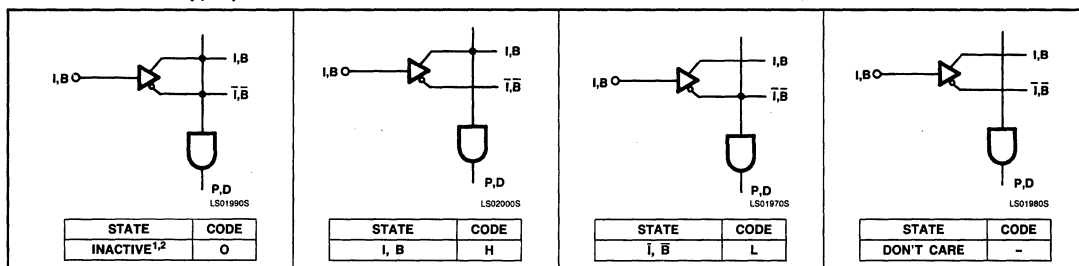
## LOGIC PROGRAMMING

PLS153A logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

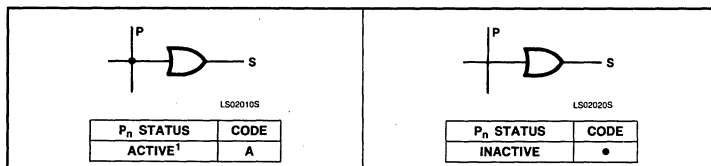
PLS153A logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

### "AND" ARRAY - (I, B)



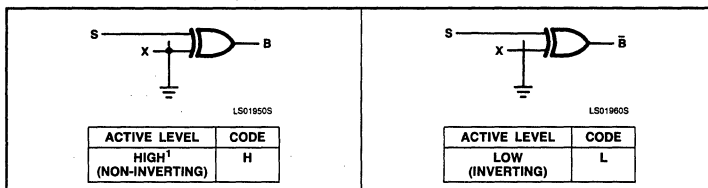
### OR ARRAY - (B)



#### NOTES:

1. This is the initial unprogrammed state of all links.
2. Any gate P<sub>n</sub> will be unconditionally inhibited if both the True and Complement of an input (either I or B) are left intact.

### OUTPUT POLARITY - (B)



### VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

1. All outputs are at "H" polarity.
2. All P<sub>n</sub> terms are disabled.
3. All P<sub>n</sub> terms are active on all outputs.

### CAUTION: PLS153A TEST COLUMNS

The PLS153A incorporates two columns not shown in the logic block diagram. These columns are used for in-house testing of the device in the unprogrammed state. These columns must be disabled prior to using the PLS153A in your application. If you are using a Signetics-approved programmer the disabling is accomplished during the device programming sequence. If these columns are not disabled, abnormal operation is possible.

Furthermore, because of these test columns, the PLS153A cannot be programmed using the programmer algorithm for the PLS153.



**Application Specific Products**  
• Series 20

**DESCRIPTION**

The PLHS153 is a high-speed version of the PLS153 and PLS153A FPLAs.

The PLHS153 is a two-level logic element, consisting of 42 AND gates and 10 OR gates with fusible link connections for programming I/O polarity and direction.

All AND gates are linked to 8 inputs (I) and 10 bidirectional I/O lines (B). These yield variable I/O gate configurations via 10 direction control gates (D), ranging from 18 inputs to 10 outputs.

On chip T/C buffers couple either True (I, B) or Complement (I, B) input polarities to all AND gates, whose outputs can be optionally linked to all OR gates. Their output polarity, in turn, is individually programmable through a set of EX-OR gates for implementing AND/OR or AND/NOR logic functions.

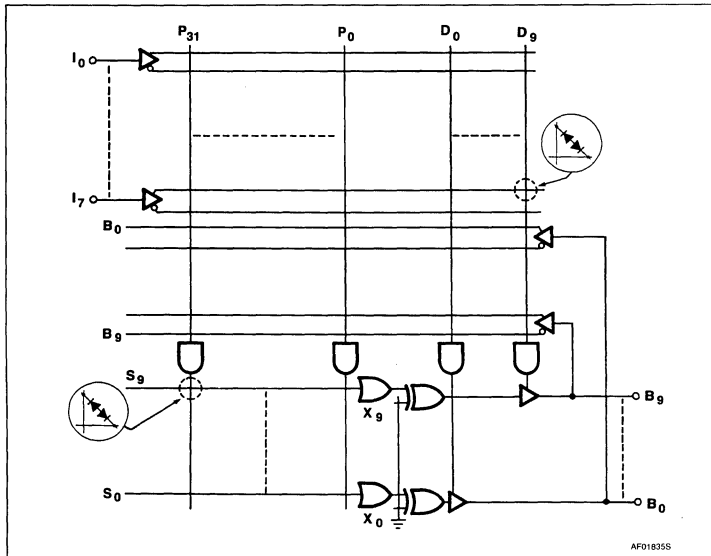
In the virgin state, the AND array fuses are back-to-back CB-EB diode pairs which will act as open connections. Current is avalanched across individual

diode pairs during fusing, which essentially short circuits the EB diode and provides the connection for the associated product term.

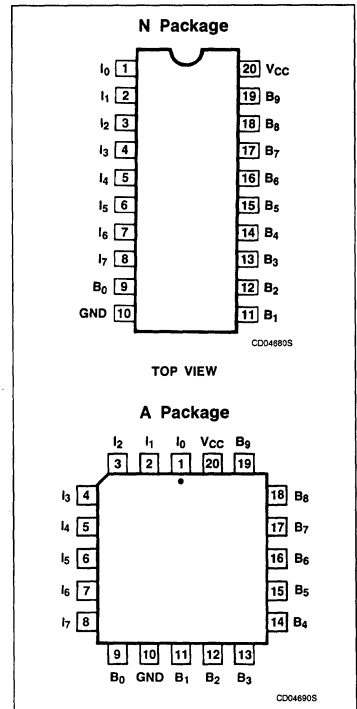
**FEATURES**

- **Field-Programmable**
- **Functionally identical to PLS153/153A**
- **8 inputs**
- **10 bidirectional I/O lines**
- **42 AND gates**
- **10 OR gates**
- **Programmable output polarity**
- **42 product terms:**
  - 32 logic terms
  - 10 control terms
- **I/O propagation delay: 20ns (max.)**
- **Input loading: -100µA (max.)**
- **Power dissipation: 650mW (typ.)**
- **3-State outputs**
- **TTL compatible**
- **Security fuse**

**FUNCTIONAL DIAGRAM**



**PIN CONFIGURATIONS**



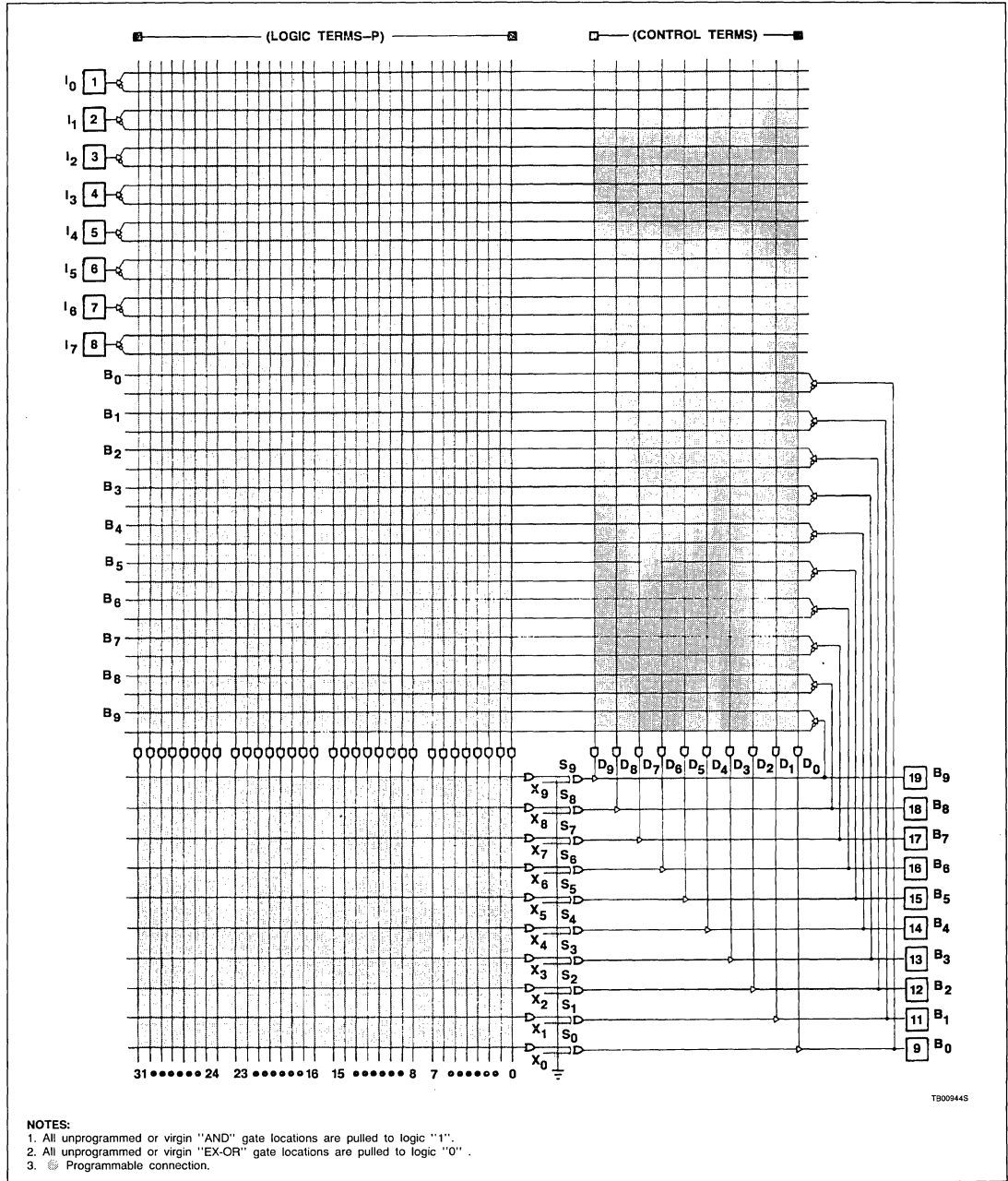
**APPLICATIONS**

- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping
- Multiplexing

# Field-Programmable Logic Array (18 × 42 × 10)

PLHS153

## FPLA LOGIC DIAGRAM



4

# Field-Programmable Logic Array (18 × 42 × 10)

# PLHS153

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
20-pin Plastic DIP 300mil-wide	PLHS153N
20-pin Plastic Leaded Chip Carrier	PLHS153A

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

## ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage	+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30 to +30	mA
I <sub>OUT</sub>	Output currents	+100	mA
T <sub>A</sub>	Operating free-air temperature range	0 to +75	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

The PLHS153 device is also processed to military requirements for operation over the military temperature range. For specifications and ordering information consult the Signetics Military Data Book.

### NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other conditions above those indicated in the operational and programming specification of the device is not implied.

## DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ 75°C, 4.75V ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min	2.0	-0.8	0.8	V
V <sub>IH</sub>	High	V <sub>CC</sub> = Max			V	
V <sub>IC</sub>	Clamp <sup>3</sup>	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA			-1.2	V
<b>Output voltage<sup>2</sup></b>						
V <sub>OL</sub>	Low <sup>4</sup>	V <sub>CC</sub> = Min	2.4		0.5	V
V <sub>OH</sub>	High <sup>5</sup>	I <sub>OL</sub> = 15mA I <sub>OH</sub> = -2mA				
<b>Input current<sup>10</sup></b>						
I <sub>IL</sub>	Low	V <sub>CC</sub> = Max			-100	μA
I <sub>IH</sub>	High	V <sub>IN</sub> = 0.45V V <sub>IN</sub> = 5.5V				
<b>Output current</b>						
I <sub>O(OFF)</sub>	Hi-Z state <sup>9</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V	-15		80	μA
I <sub>OS</sub>	Short circuit <sup>3, 5, 6</sup>	V <sub>OUT</sub> = 0.45V V <sub>OUT</sub> = 0.5V			-140	μA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>7</sup>	V <sub>CC</sub> = Max			-70	mA
<b>Capacitance</b>						
C <sub>IN</sub>	Input	V <sub>CC</sub> = 5V			8	pF
C <sub>B</sub>	I/O	V <sub>IN</sub> = 2.0V V <sub>B</sub> = 2.0V			15	pF

Notes on following page.

# Field-Programmable Logic Array (18 × 42 × 10)

PLHS153

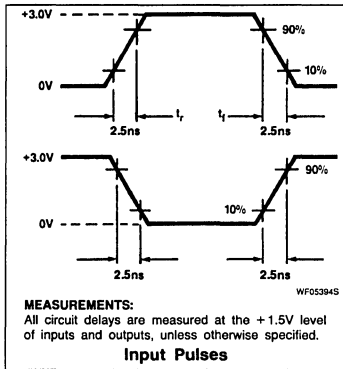
## AC ELECTRICAL CHARACTERISTICS $R_1 = 470\Omega$ , $R_2 = 1k\Omega$ , $0^\circ C \leq T_A \leq +75^\circ C$ , $4.75V \leq V_{CC} \leq 5.25V$

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ <sup>1</sup>	Max	
$t_{PD}$	Propagation delay	Output $\pm$	Input $\pm$	$C_L = 30pF$		14	20	ns
$t_{OE}$	Output enable	Output -	Input $\pm$	$C_L = 30pF$		16	20	ns
$t_{OD}$	Output disable <sup>B</sup>	Output +	Input $\pm$	$C_L = 5pF$		14	20	ns

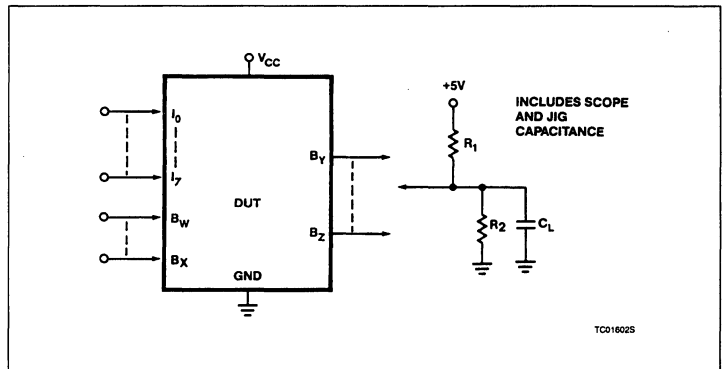
**NOTES:**

1. All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
2. All voltage values are with respect to network ground terminal.
3. Test one at a time.
4. Measured with +10V applied to  $I_5$ .
5. Output sink current is supplied through a resistor to  $V_{CC}$ .
6. Duration of short circuit should not exceed 1 second.
7.  $I_{CC}$  is measured with all pins = open or 4.5V.
8. Measured at  $V_T = V_{OL} + 0.5V$ .
9. Leakage values are a combination of input and output leakage.
10.  $I_{IL}$  and  $I_{IH}$  limits are for dedicated inputs only ( $I_0-I_7$ ).

### VOLTAGE WAVEFORMS



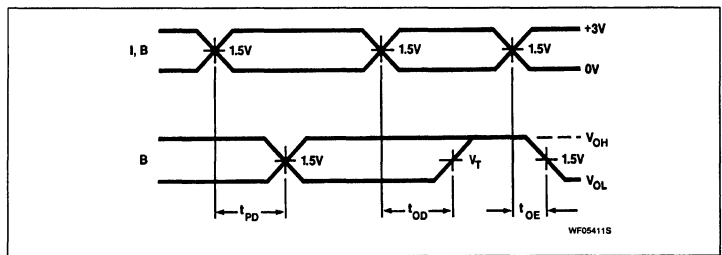
### TEST LOAD CIRCUITS



### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Propagation delay between input and output.
$t_{OD}$	Delay between input change and when output is off (Hi-Z or High).
$t_{OE}$	Delay between input change and when output reflects specified output level.

### TIMING DIAGRAM



4

# Field-Programmable Logic Array (18 × 42 × 10)

PLHS153

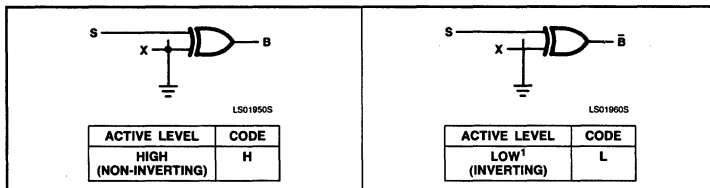
## LOGIC PROGRAMMING

PLHS153 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

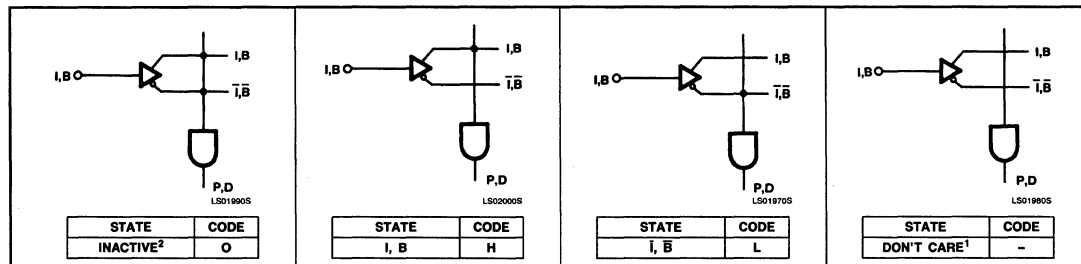
PLHS153 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

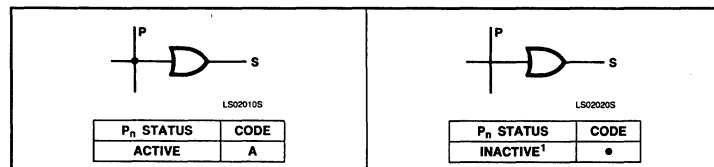
## OUTPUT POLARITY – (B)



## "AND" ARRAY – (I, B)



## OR ARRAY – (B)



## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

1. All outputs are at "L" polarity.
2. All P<sub>n</sub> terms are enabled in the AND array.
3. All P<sub>n</sub> terms are inactive in the OR array.

### NOTES:

1. This is the initial unprogrammed state of all links. All unused P<sub>n</sub> and D<sub>n</sub> terms must be programmed as INACTIVE.
2. Any gate P<sub>n</sub> will be unconditionally inhibited if both the True and Complement of an input (either I or B) are programmed for a connection.





# PLUS153B

## Field-Programmable Logic Array (18 × 42 × 10)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

- Series 20

### DESCRIPTION

The PLUS153B is a 15ns version of the Signetics PLS153 FPLA architecture. The Signetics state-of-the-art Oxide isolated Bipolar fabrication process is employed to produce performance levels not yet achieved in devices of this complexity.

The PLUS153B is a two-level logic element, consisting of 42 AND gates and 10 OR gates with fusible link connections for programming I/O polarity and direction.

All AND gates are linked to 8 inputs (I) and 10 bidirectional I/O lines (B). These yield variable I/O gate configurations via 10 direction control gates (D), ranging from 18 inputs to 10 outputs.

On-chip T/C buffers couple either True (I, B) or Complement (I, B) input polarities to all AND gates, whose outputs can be optionally linked to all OR gates. Their output polarity, in turn, is individually programmable through a set of Ex-OR gates for implementing AND/OR or AND/NOR logic functions.

The PLUS153B is field programmable, enabling the user to quickly generate

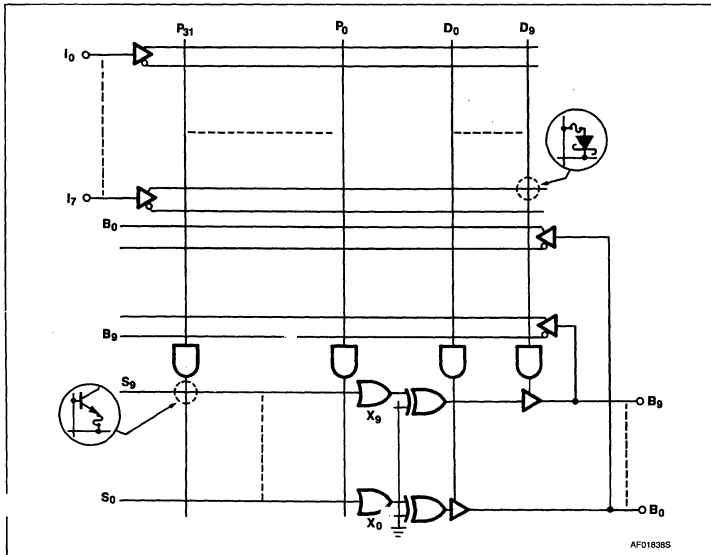
custom patterns using standard programming equipment.

Order codes are listed in the Ordering Information Table.

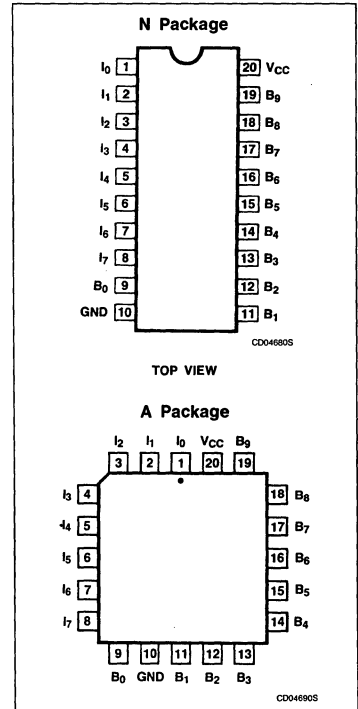
### FEATURES

- Field-Programmable (Ti-W links)
- Functionally identical to, and pin-for-pin compatible with, the PLS153/153A, PLHS153, and the PLUS153D
- 8 inputs
- 42 AND gates
- 10 OR gates
- 10 bidirectional I/O lines
- Programmable output polarity
  - active-High or -Low outputs
- 42 product terms:
  - 32 logic terms
  - 10 control terms
- I/O propagation delay: 15ns (max.)
- Input loading: -100μA (max.)
- Power dissipation: 750mW (typ.)
- 3-State outputs
- TTL compatible
- Security fuse

### FUNCTIONAL DIAGRAM



### PIN CONFIGURATIONS



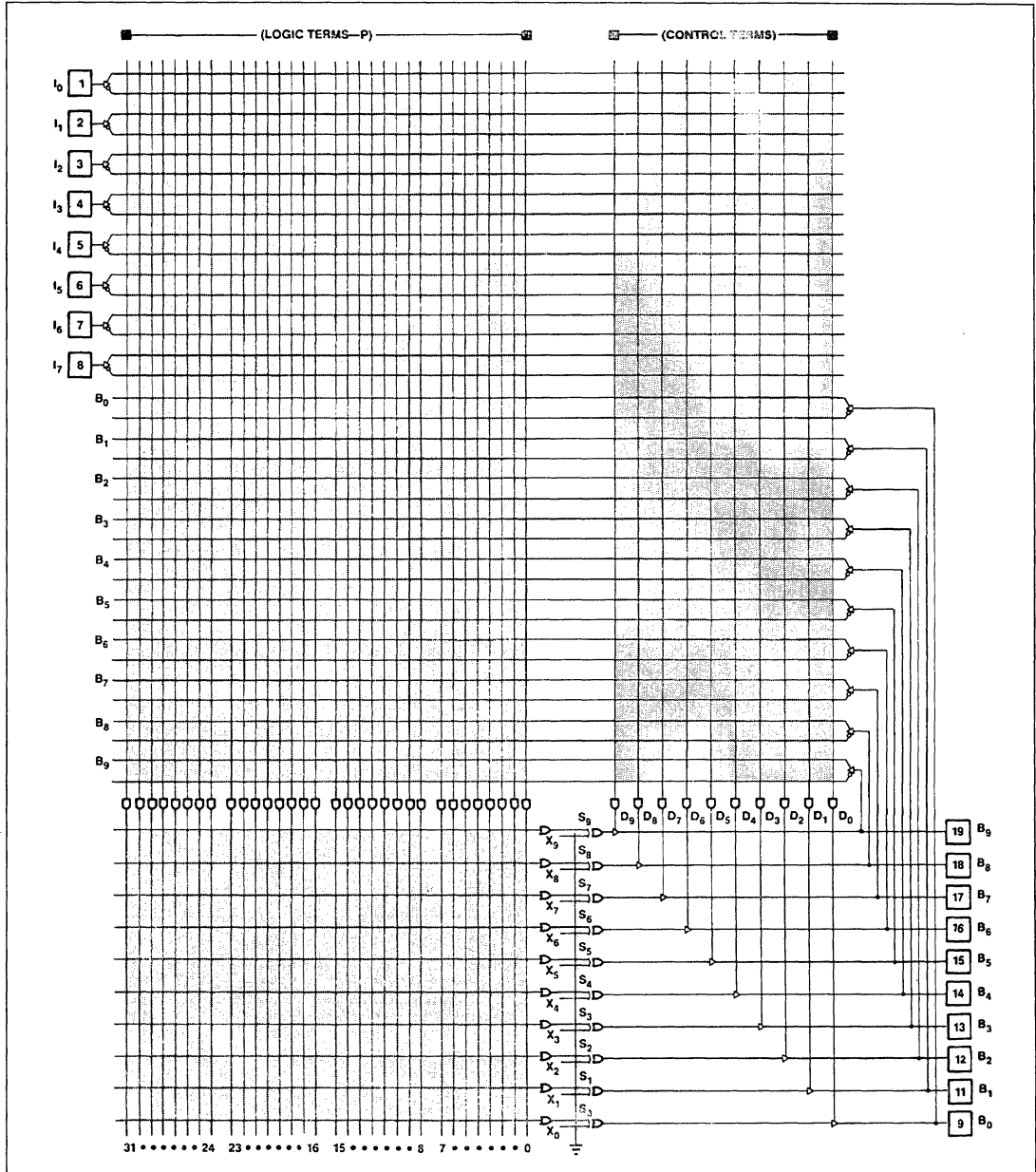
### APPLICATIONS

- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping
- Multiplexing

# Field-Programmable Logic Array (18 × 42 × 10)


PLUS153B

## FPLA LOGIC DIAGRAM



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**NOTES:**

1. All programmed "AND" gate locations are pulled to logic "1".
2. All programmed "OR" gate locations are pulled to logic "0".
3.  Programmable connection.

TB009435

## Field-Programmable Logic Array (18 × 42 × 10)

PLUS153B

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
20-pin Plastic DIP 300mil-wide	PLUS153BN
20-pin Plastic Leaded Chip Carrier	PLUS153BA

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating free-air temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

The PLUS153B device is also processed to military requirements for operation over the military temperature range. For specifications and ordering information consult the Signetics Military Data Book.

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other conditions above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ 75°C, 4.75V ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min	2.0	-0.8	0.8	V
V <sub>IH</sub>	High	V <sub>CC</sub> = Max			V	
V <sub>IC</sub>	Clamp	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA			-1.2	V
<b>Output voltage</b>						
V <sub>OL</sub>	Low <sup>4</sup>	V <sub>CC</sub> = Min	2.4		0.5	V
V <sub>OH</sub>	High <sup>5</sup>	I <sub>OL</sub> = 15mA I <sub>OH</sub> = -2mA				
<b>Input current<sup>10</sup></b>						
I <sub>IL</sub>	Low	V <sub>CC</sub> = Max			-100	μA
I <sub>IH</sub>	High	V <sub>IN</sub> = 0.45V V <sub>IN</sub> = 5.5V				
<b>Output current</b>						
I <sub>O(OFF)</sub>	Hi-Z state <sup>9</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V	-15		80	μA
I <sub>OS</sub>	Short circuit <sup>3, 5, 6</sup>	V <sub>OUT</sub> = 0.45V			-140	mA
		V <sub>OUT</sub> = 0V			-70	mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>7</sup>	V <sub>CC</sub> = Max		150	200	mA
<b>Capacitance</b>						
C <sub>IN</sub>	Input I/O	V <sub>CC</sub> = 5V			8	pF
C <sub>B</sub>		V <sub>IN</sub> = 2.0V V <sub>B</sub> = 2.0V				

Notes on following page.

# Field-Programmable Logic Array (18 × 42 × 10)

PLUS153B

## AC ELECTRICAL CHARACTERISTICS $R_1 = 470\Omega$ , $R_2 = 1k\Omega$ , $0^\circ C \leq T_A \leq +75^\circ C$ , $4.75V \leq V_{CC} \leq 5.25V$

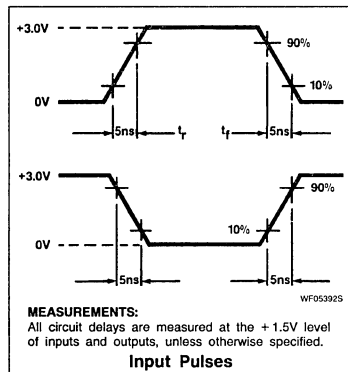
SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ <sup>1</sup>	Max	
$t_{PD}$	Propagation delay	Output $\pm$	Input $\pm$	$C_L = 30pF$		11	15	ns
$t_{OE}$	Output enable	Output -	Input $\pm$	$C_L = 30pF$		11	15	ns
$t_{OD}$	Output disable <sup>B</sup>	Output +	Input $\pm$	$C_L = 5pF$		11	15	ns

**NOTES:**

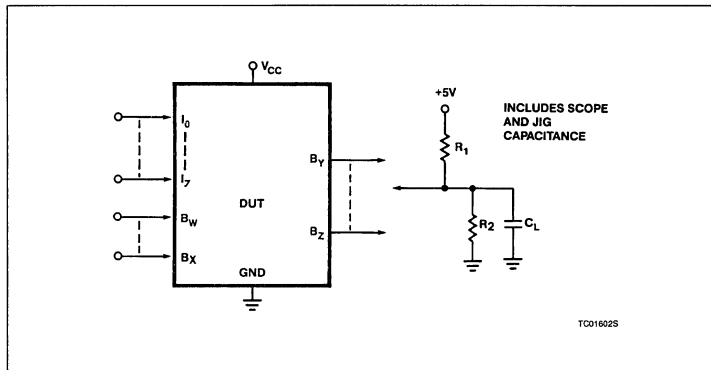
1. All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
2. All voltage values are with respect to network ground terminal.
3. Test one at a time.
4. Measured with inputs  $I_0-I_2 = 0V$ , inputs  $I_3-I_5 = 4.5V$ , inputs  $I_7 = 4.5V$  and  $I_6 = 10V$ . For outputs  $B_0-B_4$  and for outputs  $B_5-B_9$  apply the same conditions, except  $I_7 = 0V$ .
5. Same conditions as Note 5, except  $I_7 = +10V$ .
6. Duration of short circuit should not exceed 1 second.
7.  $I_{CC}$  is measured with inputs  $I_0-I_7$  and  $B_0-B_9 = 0V$ .
8. Measured at  $V_T = V_{OL} + 0.5V$ .
9. Leakage values are a combination of input and output leakage.
10.  $I_{L1}$  and  $I_{H1}$  limits are for dedicated inputs only ( $I_0-I_7$ ).

4

### VOLTAGE WAVEFORMS



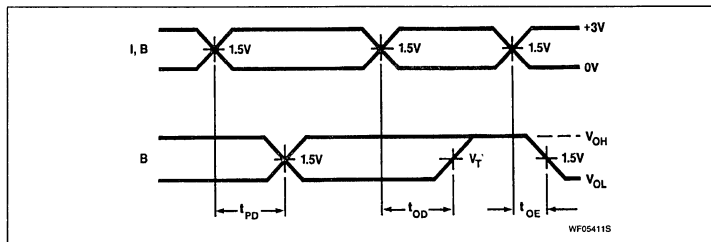
### TEST LOAD CIRCUITS



### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Propagation delay between input and output.
$t_{OD}$	Delay between input change and when output is off (Hi-Z or High).
$t_{OE}$	Delay between input change and when output reflects specified output level.

### TIMING DIAGRAM



# Field-Programmable Logic Array (18 × 42 × 10)

# PLUS153B

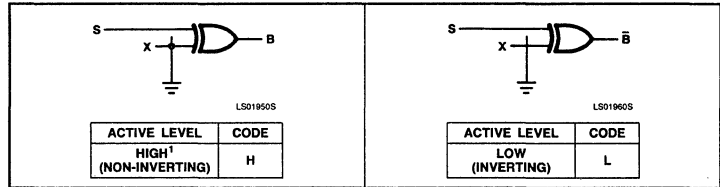
## LOGIC PROGRAMMING

PLUS153B logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

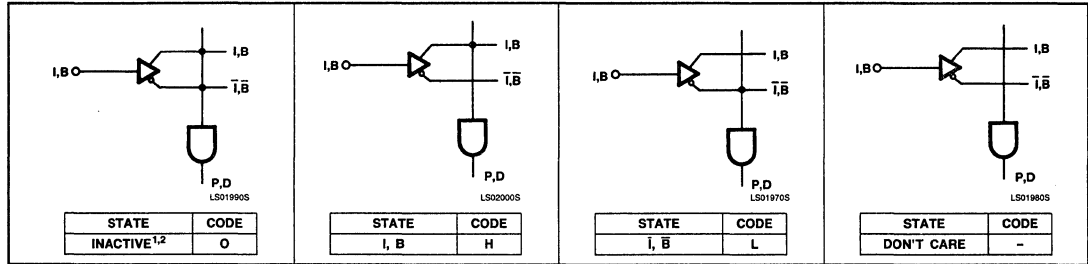
PLUS153B logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

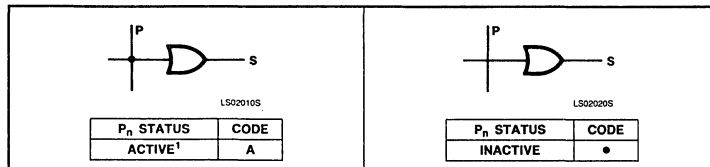
## OUTPUT POLARITY - (B)



## AND ARRAY - (I, B)



## OR ARRAY - (B)



### NOTES:

1. This is the initial unprogrammed state of all links.
2. Any gate P<sub>n</sub> will be unconditionally inhibited if both the true and complement of an input (either I or B) are left intact.

## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

1. All outputs are at "H" polarity.
2. All P<sub>n</sub> terms are disabled.
3. All P<sub>n</sub> terms are active on all outputs.



# PLUS153D

## Field-Programmable Logic Array (18 × 42 × 10)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

- Series 20

### DESCRIPTION

The PLUS153D is a 12ns version of the Signetics PLS153 FPLA architecture. The Signetics state-of-the-art Oxide Isolated Bipolar fabrication process is employed to produce performance levels not yet achieved in devices of this complexity.

The PLUS153D is a two-level logic element, consisting of 42 AND gates and 10 OR gates with fusible link connections for programming I/O polarity and direction.

All AND gates are linked to 8 inputs (I) and 10 bidirectional I/O lines (B). These yield variable I/O gate configurations via 10 direction control gates (D), ranging from 18 inputs to 10 outputs.

On-chip T/C buffers couple either True (I, B) or Complement (I, B) input polarities to all AND gates, whose outputs can be optionally linked to all OR gates. Their output polarity, in turn, is individually programmable through a set of Ex-OR gates for implementing AND/OR or AND/NOR logic functions.

The PLUS153D is field programmable, enabling the user to quickly generate

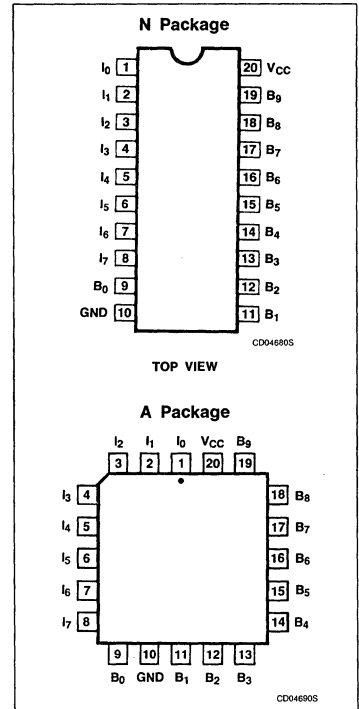
custom patterns using standard programming equipment.

Order codes are listed in the Ordering Information Table.

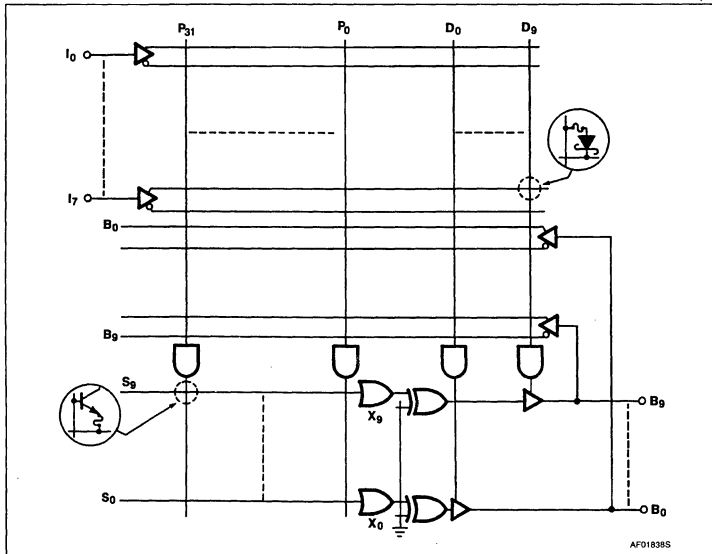
### FEATURES

- Field-Programmable (Ti-W links)
- Functionally identical to, and pin-for-pin compatible with, the PLS153/153A, PLHS153 and PLUS153B
- 8 inputs
- 42 AND gates
- 10 OR gates
- 10 bidirectional I/O lines
- Programmable output polarity - active-High or -Low outputs
- 42 product terms:
  - 32 logic terms
  - 10 control terms
- I/O propagation delay: 12ns (max.)
- Input loading: -100μA (max.)
- Power dissipation: 750mW (typ.)
- 3-State outputs
- TTL compatible
- Security fuse

### PIN CONFIGURATIONS



### FUNCTIONAL DIAGRAM



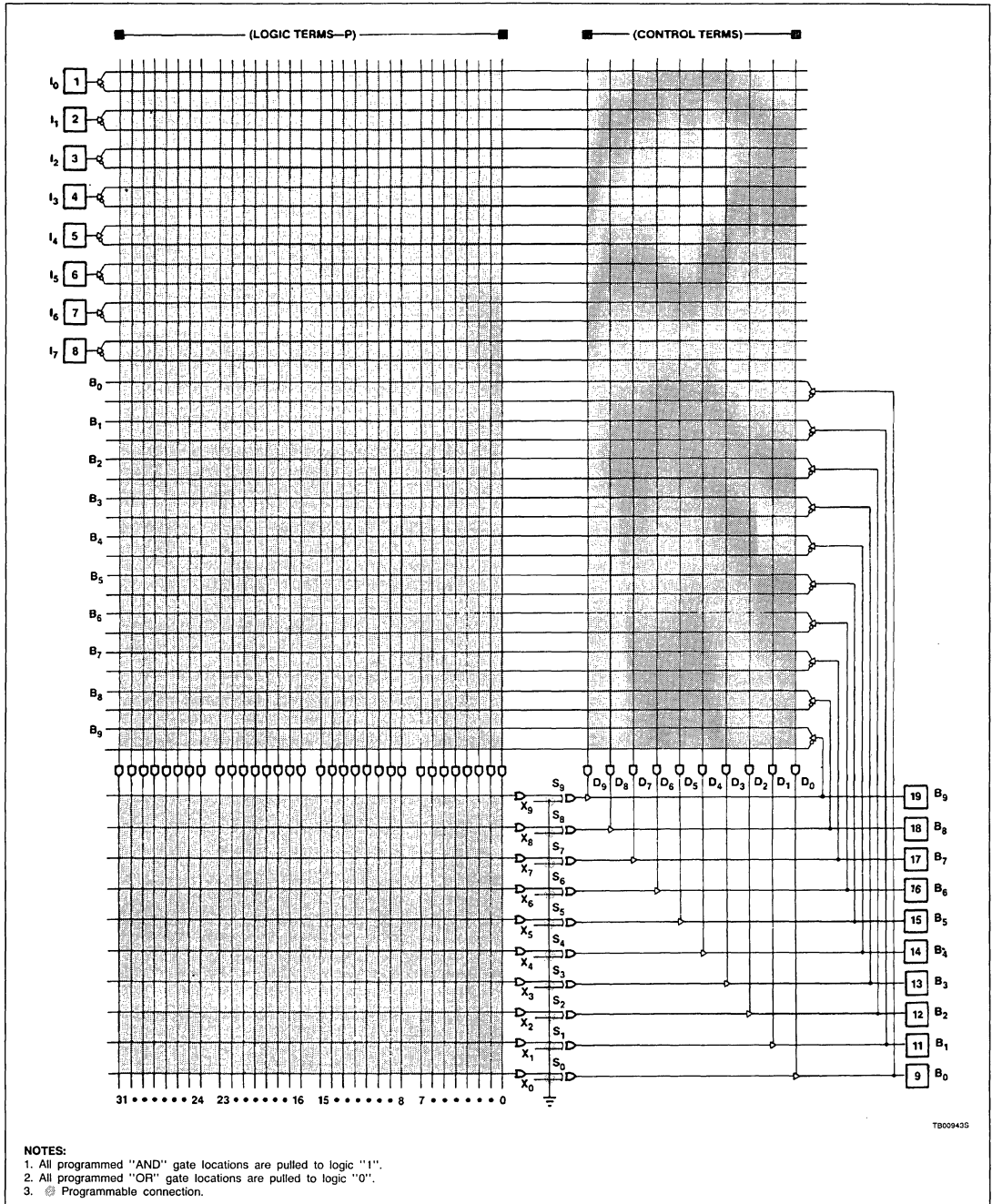
### APPLICATIONS

- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping
- Multiplexing

# Field-Programmable Logic Array (18 × 42 × 10)

# PLUS153D

## FPLA LOGIC DIAGRAM



4



## Field-Programmable Logic Array (18 × 42 × 10)

PLUS153D

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
20-pin Plastic DIP 300mil-wide	PLUS153DN
20-pin Plastic Leaded Chip Carrier	PLUS153DA

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating free-air temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other conditions above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ 75°C, 4.75V ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT	
			Min	Typ <sup>1</sup>	Max		
<b>Input voltage<sup>2</sup></b>							
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min	2.0	-0.8	0.8	V	
V <sub>IH</sub>	High	V <sub>CC</sub> = Max					
V <sub>IC</sub>	Clamp	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA				-1.2	V
<b>Output voltage<sup>2</sup></b>							
V <sub>OL</sub>	Low <sup>4</sup>	V <sub>CC</sub> = Min	2.4		0.5	V	
V <sub>OH</sub>	High <sup>5</sup>	I <sub>OL</sub> = 15mA I <sub>OH</sub> = -2mA				V	
<b>Input current<sup>11</sup></b>							
I <sub>IL</sub>	Low	V <sub>CC</sub> = Max			-100	μA	
I <sub>IH</sub>	High	V <sub>IN</sub> = 0.45V V <sub>IN</sub> = 5.5V				40	μA
<b>Output current</b>							
I <sub>O(OFF)</sub>	Hi-Z state <sup>9</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V	-15		80	μA	
I <sub>OS</sub>	Short circuit <sup>3, 5, 6</sup>	V <sub>OUT</sub> = 0.45V V <sub>OUT</sub> = 0V				-140	mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>7</sup>	V <sub>CC</sub> = Max				200	mA
<b>Capacitance</b>							
C <sub>IN</sub>	Input	V <sub>CC</sub> = 5V			8	pF	
C <sub>B</sub>	I/O	V <sub>IN</sub> = 2.0V V <sub>B</sub> = 2.0V				15	pF

Notes on following page.

# Field-Programmable Logic Array (18 × 42 × 10)

# PLUS153D

## AC ELECTRICAL CHARACTERISTICS $R_1 = 470\Omega$ , $R_2 = 1k\Omega$ , $0^\circ C \leq T_A \leq +75^\circ C$ , $4.75V \leq V_{CC} \leq 5.25V$

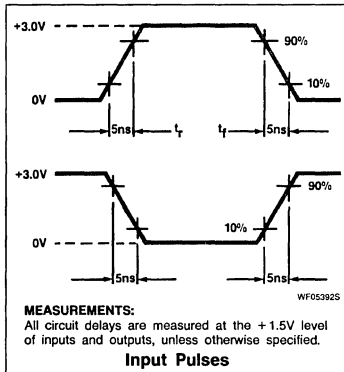
SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ <sup>1</sup>	Max	
$t_{PD}$	Propagation delay	Output ±	Input ±	$C_L = 30pF$		10	12	ns
$t_{OE}$	Output enable	Output -	Input ±	$C_L = 30pF$		10	12	ns
$t_{OD}$	Output disable <sup>B</sup>	Output +	Input ±	$C_L = 5pF$		10	12	ns

**NOTES:**

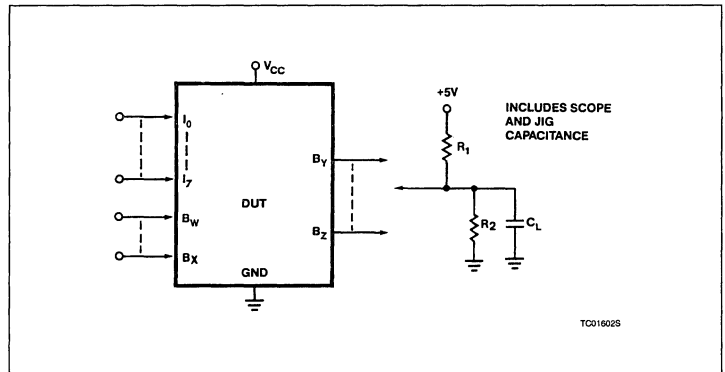
1. All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
2. All voltage values are with respect to network ground terminal.
3. Test one at a time.
4. Measured with inputs  $I_0-I_2 = 0V$ , inputs  $I_3-I_5 = 4.5V$ , inputs  $I_7 = 4.5V$  and  $I_6 = 10V$ . For outputs  $B_0-B_4$  and for outputs  $B_5-B_9$  apply the same conditions, except  $I_7 = 0V$ .
5. Same conditions as Note 4, except  $I_7 = +10V$ .
6. Duration of short circuit should not exceed 1 second.
7.  $I_{CC}$  is measured with inputs  $I_0-I_7$  and  $B_0-B_9 = 0V$ .
8. Measured at  $V_T = V_{OL} + 0.5V$ .
9. Leakage values are a combination of input and output leakage.
10.  $I_{IL}$  and  $I_{IH}$  limits are for dedicated inputs only ( $I_0-I_7$ ).



### VOLTAGE WAVEFORMS



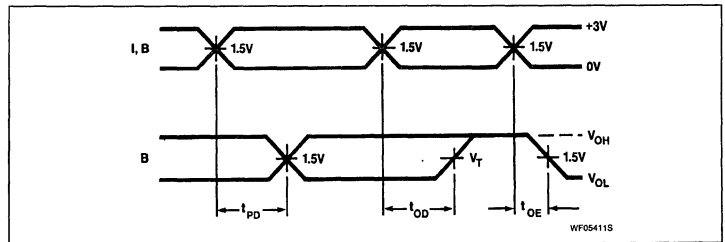
### TEST LOAD CIRCUITS



### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Propagation delay between input and output.
$t_{OD}$	Delay between input change and when output is off (Hi-Z or High).
$t_{OE}$	Delay between input change and when output reflects specified output level.

### TIMING DIAGRAM



# Field-Programmable Logic Array (18 × 42 × 10)

# PLUS153D

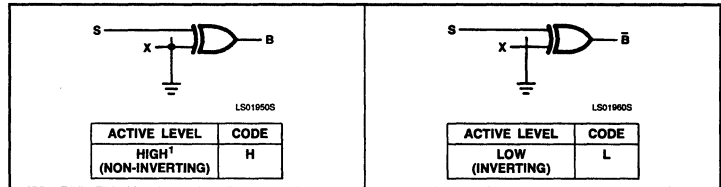
## LOGIC PROGRAMMING

PLUS153D logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

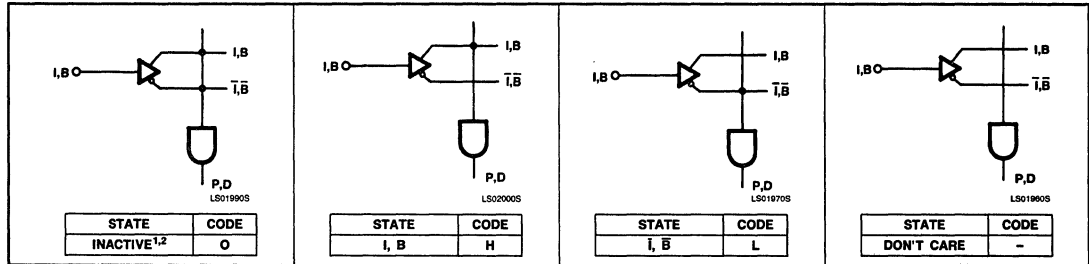
PLUS153D logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

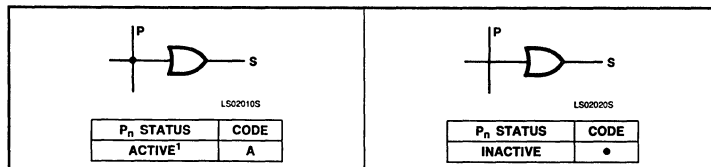
## OUTPUT POLARITY - (B)



## AND ARRAY - (I, B)



## OR ARRAY - (B)



## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

1. All outputs are at "H" polarity.
2. All P<sub>n</sub> terms are disabled.
3. All P<sub>n</sub> terms are active on all outputs.

### NOTES:

- \*1. This is the initial unprogrammed state of all links.
2. Any gate P<sub>n</sub> will be unconditionally inhibited if both the true and complement of an input (either I or B) are left intact.

# Field-Programmable Logic Array (18 × 42 × 10)

PLUS153D

## FPLA PROGRAM TABLE

	T E R M S	AND																		OR										POLARITY																																														
		A									B(1)									B(0)																																																								
		7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	1	0																																															
		0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31																																											
<p><b>CUSTOMER NAME</b> _____</p> <p><b>PURCHASE ORDER #</b> _____</p> <p><b>SIGNETICS DEVICE #</b> _____ <b>CF (XXXX)</b> _____</p> <p><b>CUSTOMER SYMBOLIZED PART #</b> _____</p> <p><b>TOTAL NUMBER OF PARTS</b> _____</p> <p><b>PROGRAM TABLE #</b> _____ <b>REV</b> _____ <b>DATE</b> _____</p>	<p><b>Notes</b></p> <p>1. The FPLA is shipped with all links intact. Thus a background of entries corresponding to states of virgin links exists in the LDR. (Shown BLANK for clarity)</p> <p>2. Unused I and B bits in the AND array must be programmed Don't Care (-).</p> <p>3. Unused product terms can be left blank.</p>																																																																											
<p><b>OR</b></p> <p>ACTIVE <input type="checkbox"/> A</p> <p>INACTIVE <input type="checkbox"/> B(0)</p> <p>CONTROL <input type="checkbox"/></p> <p>HIGH <input type="checkbox"/> H</p> <p>LOW <input type="checkbox"/> L</p>																																																																												
<p><b>AND</b></p> <p>INACTIVE <input type="checkbox"/> 0</p> <p>I.B. <input type="checkbox"/> H</p> <p>I.B. <input type="checkbox"/> L</p> <p>DONT CARE <input type="checkbox"/> -</p>																																																																												
<p><b>VARIABLE NAME</b></p>																																																																												
<p><b>PIN</b></p>																																																																												

4

# PLS161

## Field-Programmable Logic Array (12 × 48 × 8)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

- Series 24

### DESCRIPTION

The PLS161 is a bipolar, Field-Programmable Logic Array (FPLA). The device utilizes the standard AND/OR/Invert architecture to directly implement custom sum of product logic equations.

This device consists of 12 dedicated inputs and 8 dedicated outputs. Each output is capable of being actively controlled by any or all of the 48 product terms. The True, Complement, or Don't Care condition of each of the 12 inputs ANDed together comprise one P-term. All 48 P-terms are selectively ORed to each output. The user must then only select which P-terms will activate an output by disconnecting terms which do not affect the output. In addition each output can be fused as active-High (H) or active-Low (L).

The PLS161 is fully TTL compatible, and includes a chip enable input for output inhibit control and expansion of input variables.

Order codes are listed in the Ordering Information Table.

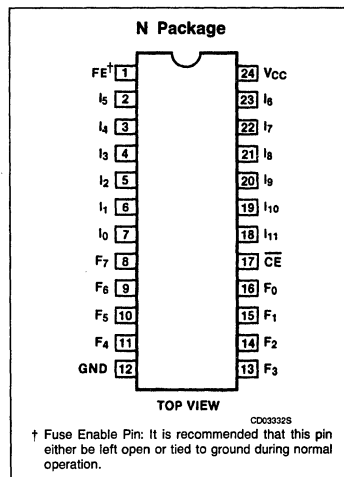
### FEATURES

- Field-Programmable (Ni-Cr Link)
- Input variables: 12
- Output functions: 8
- Product terms: 48
- I/O propagation delay: 50ns (max.)
- Power dissipation: 600mW (typ.)
- Input loading: -100µA (max.)
- Chip Enable input
- Output disable function
- Separate I/O architecture
- 3-State outputs

### APPLICATIONS

- CRT display systems
- Random logic
- Code conversion
- Peripheral controllers
- Function generators
- Look-up and decision tables
- Microprogramming
- Address mapping
- Character generators
- Sequential controllers
- Data security encoders
- Fault detectors
- Frequency synthesizers

### PIN CONFIGURATION



### LOGIC FUNCTION

#### TYPICAL PRODUCT TERM

$$P_0 = I_0 \cdot I_1 \cdot I_2 \cdot I_5 \cdot I_{11}$$

#### TYPICAL OUTPUT FUNCTIONS:

⊗ CE = 0:

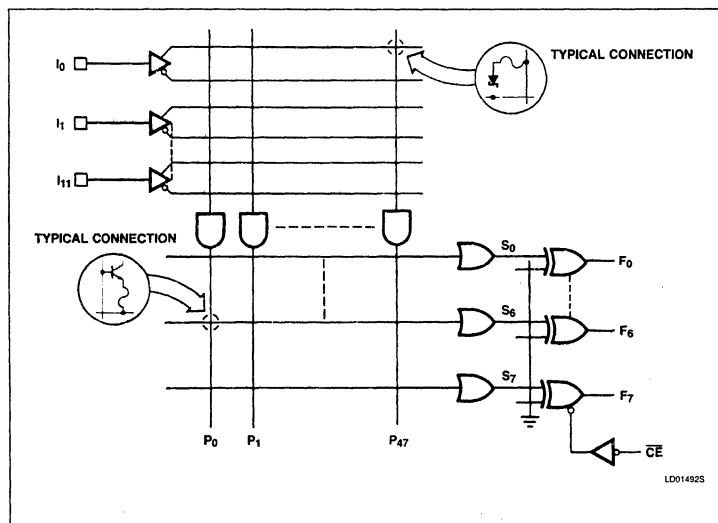
$$F_0 = (P_0 + P_1 + P_2) \text{ @ L = CLOSED}$$

$$F_0 = (P_0 \cdot P_1 \cdot P_2) \text{ @ L = OPEN}$$

#### NOTE:

For each of the 8 outputs either the function  $F_0$  (active-High) or  $F_0$  (active-Low) is available, but not both. The desired output polarity is programmed via the Ex-OR gates.

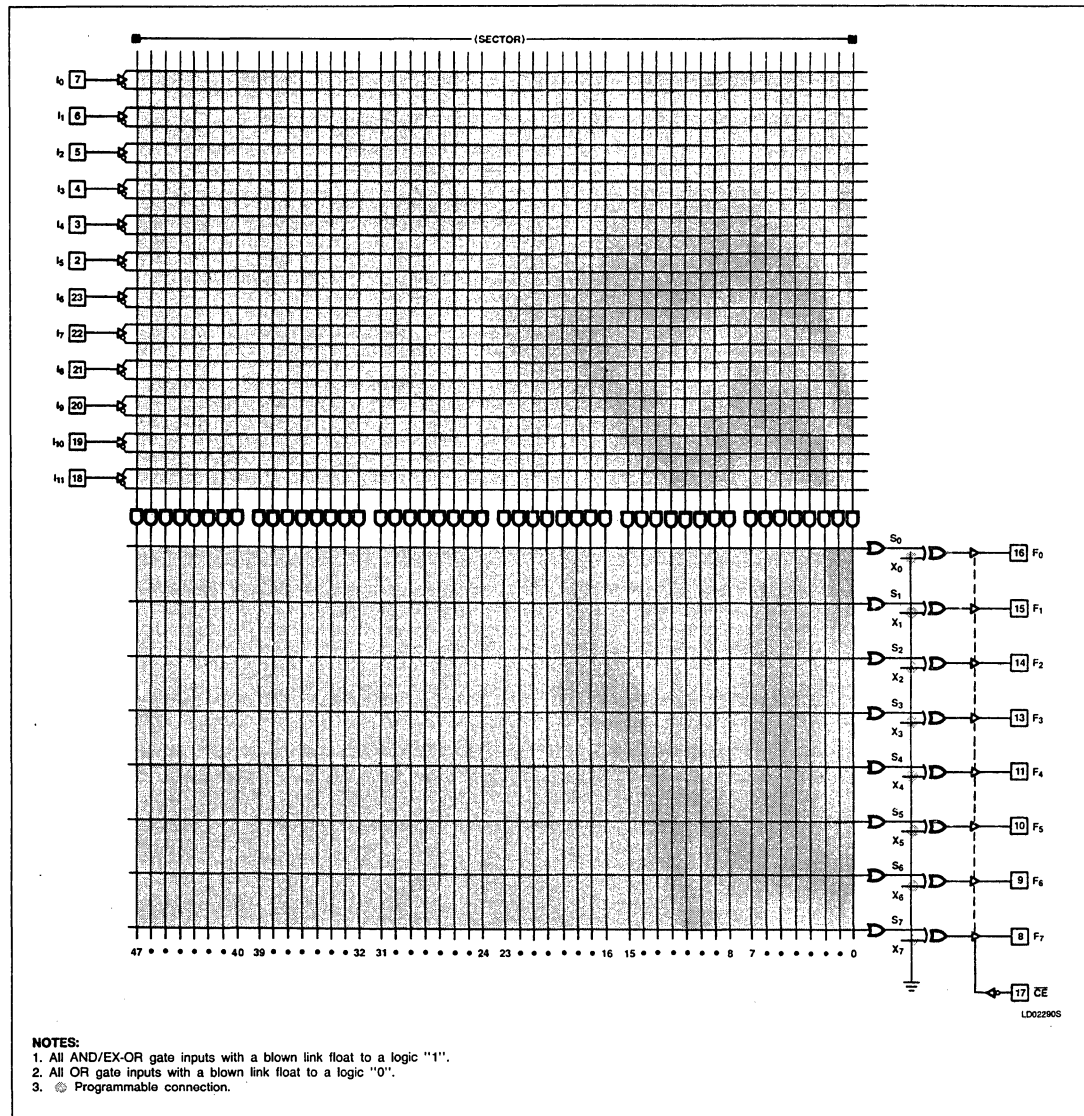
### FUNCTIONAL DIAGRAM



# Field-Programmable Logic Array (12 × 48 × 8)

PLS161

## FPLA LOGIC DIAGRAM



## Field-Programmable Logic Array (12 × 48 × 8)

PLS161

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
24-pin Plastic DIP 300mil-wide	PLS161N

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	+5.5	V <sub>DC</sub>
V <sub>O</sub>	Output voltage	+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input current	±30	mA
I <sub>OUT</sub>	Output current	+100	mA
T <sub>A</sub>	Operating temperature range	0 to +75	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other conditions above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ 75°C, 4.75V ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IH</sub> V <sub>IL</sub> V <sub>IC</sub>	High Low Clamp <sup>3</sup>	V <sub>CC</sub> = Max V <sub>CC</sub> = Min V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA	2		0.8 -1.2	V V V
<b>Output voltage<sup>2</sup></b>						
V <sub>OH</sub> V <sub>OL</sub>	High <sup>4</sup> Low <sup>5</sup>	V <sub>CC</sub> = Min I <sub>OH</sub> = -2mA I <sub>OL</sub> = 9.6mA	2.4	0.35	0.45	V V
<b>Input current</b>						
I <sub>IH</sub> I <sub>IL</sub>	High Low	V <sub>CC</sub> = Max V <sub>IN</sub> = 5.5V V <sub>IN</sub> = 0.45V		< 1 -10	40 -100	μA μA
<b>Output current</b>						
I <sub>O(OFF)</sub> I <sub>OS</sub>	Hi-Z state Short circuit <sup>3, 6</sup>	$\overline{CE}$ = High, V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V V <sub>OUT</sub> = 0.45V $\overline{CE}$ = Low, V <sub>OUT</sub> = 0V		1 -1	40 -40 -70	μA mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>7</sup>	V <sub>CC</sub> = Max		120	170	mA
<b>Capacitance</b>						
C <sub>IN</sub> C <sub>OUT</sub>	Input Output	$\overline{CE}$ = High, V <sub>CC</sub> = 5.0V V <sub>IN</sub> = 2V V <sub>OUT</sub> = 2V		8 17		pF pF

Notes on following page.

# Field-Programmable Logic Array (12 × 48 × 8)

PLS161

## AC ELECTRICAL CHARACTERISTICS $R_1 = 470\Omega$ , $R_2 = 1k\Omega$ , $C_L = 30pF$ , $0^\circ C \leq T_A \leq +75^\circ C$ , $4.75V \leq V_{CC} \leq 5.25V$

SYMBOL	PARAMETER	TO	FROM	LIMITS			UNIT
				Min	Typ <sup>1</sup>	Max	
<b>Propagation delay</b>							
$t_{PD}$	Input	Output	Input		35	50	ns
$t_{CE}$	Chip enable	Output	Chip enable		15	30	ns
<b>Disable time</b>							
$t_{CD}$	Chip disable	Output	Chip enable		15	30	ns

**NOTES:**

- All values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
- All voltage values are with respect to network ground terminal.
- Test one pin at a time.
- Measured with  $V_{IL}$  applied to  $\overline{CE}$  and a logic high stored.
- Measured with a programmed logic condition for which the output test is at a low logic level. Output sink current is applied through a resistor to  $V_{CC}$ .
- Duration of short circuit should not exceed 1 second.
- $I_{CC}$  is measured with the chip enable input grounded, all other inputs at 4.5V and the outputs open.

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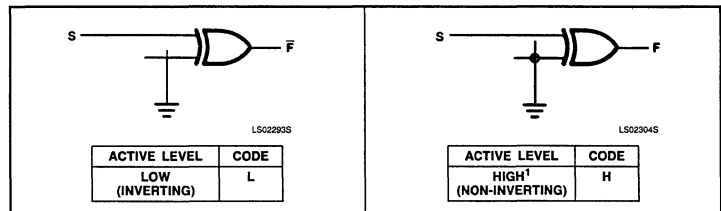
### LOGIC PROGRAMMING

PLS161 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

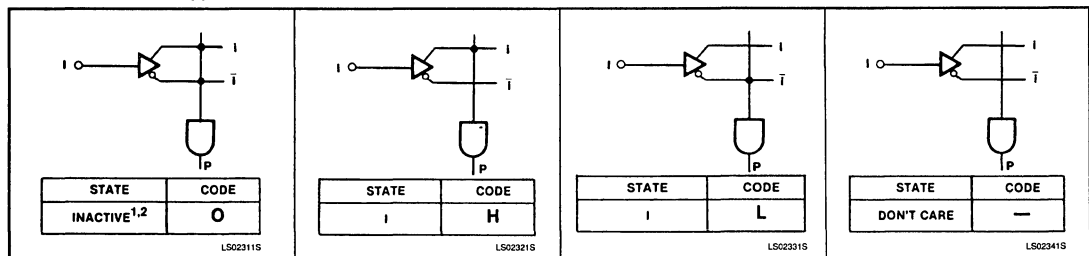
PLS161 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

### EX-OR ARRAY - (F)



### "AND" ARRAY - (I)

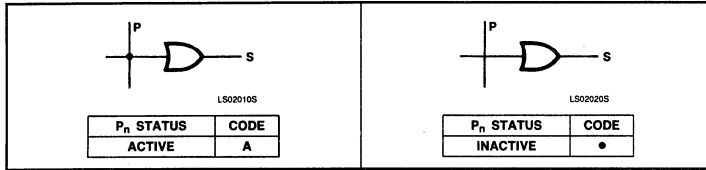




# Field-Programmable Logic Array (12 × 48 × 8)

PLS161

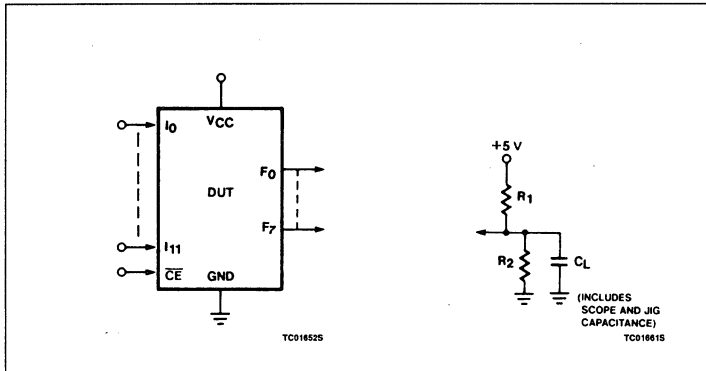
## "OR" ARRAY - (F)



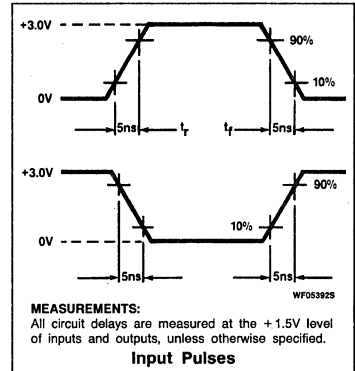
**NOTES:**

1. This is the initial unprogrammed state of all link pairs. It is normally associated with all unused (inactive) AND gates  $P_n$ .
2. Any gate  $P_n$  will be unconditionally inhibited if any one of its (I) link pairs is left intact.

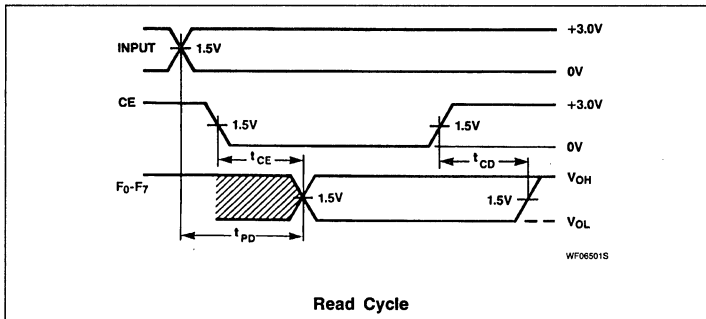
## TEST LOAD CIRCUITS



## VOLTAGE WAVEFORMS



## TIMING DIAGRAM



## TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{CE}$	Delay between beginning of Chip Enable Low (with Input valid) and when Data Output becomes valid.
$t_{CD}$	Delay between when Chip Enable becomes High and Data Output is in off state (Hi-Z or High).
$t_{PD}$	Delay between beginning of valid Input (with Chip Enable Low) and when Data Output becomes valid.

# Field-Programmable Logic Array (12 × 48 × 8)

PLS161

## FPLA PROGRAM TABLE

CUSTOMER NAME _____ PURCHASE ORDER # _____ SIGNETICS DEVICE # _____ CF (XXXX) CUSTOMER SYMBOLIZED PART # _____ TOTAL NUMBER OF PARTS _____ PROGRAM TABLE # _____ REV _____ DATE _____		<b>PROGRAM TABLE ENTRIES</b>																						
		<b>INPUT VARIABLE</b>		<b>OUTPUT FUNCTION</b>		<b>OUTPUT ACTIVE LEVEL</b>																		
		$I_m$	$I_m$	Don't Care	Prod Term Present in $F_p$	Prod Term Not Present in $F_p$	Active High	Active Low																
		H	L	—(dash)	A	• (period)	H	L																
		<b>NOTE</b> Enter (-) for unused inputs of used P-terms.		<b>NOTES</b> 1. Entries independent of output polarity. 2. Enter (A) for unused outputs of used P-terms.		<b>NOTES</b> 1. Polarity programmed once only. 2. Enter (H) for all unused outputs.																		
<b>VARIABLE NAME</b>	<b>PIN NO.</b>	1	2	3	4	5	6	7	<b>AND</b>								<b>POLARITY</b>							
		T E R M 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48								7 6 5 4 3 2 1 0														
		8 9 0 1 2 3 4 5 6 7								7 6 5 4 3 2 1 0														
		8 9 0 1 3 4 5 6								7 6 5 4 3 2 1 0														

780144S

# PLS162

## Field-Programmable Address Decoder (16 × 5)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

- Series 24

### DESCRIPTION

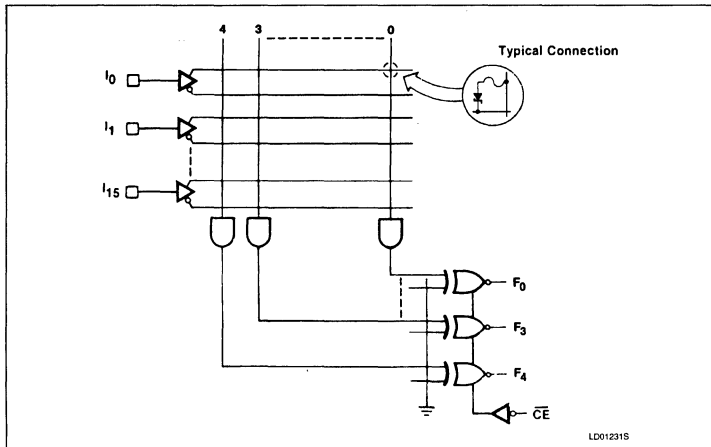
The PLS162 is a bipolar, Field-Programmable Address Decoder. The device consists of five AND/NAND gates which share 16 common inputs. The type of gate is selected by programming the output as active-High (H) or active-Low (L). Each of the 16 inputs  $I_0 - I_{15}$  can be programmed to provide the True (H), Complement (L), or Don't Care (—) state to each of the five AND/NAND gates. OR/NOR logic functions can also be implemented by complementing the inputs and outputs via on-chip inverting buffers.

The device is field programmable, which means that custom patterns are immediately available.

The PLS162 includes chip-enable control for output strobing and inhibit. It features 3-State outputs for ease of expansion of input variables and application in bus-organized systems.

Order codes are listed in the Ordering Information Table.

### FUNCTIONAL DIAGRAM



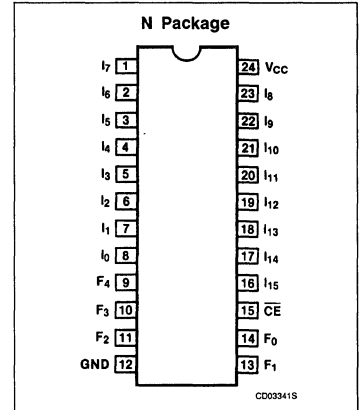
### FEATURES

- Field-Programmable (Ni-Cr link)
- 16 input variables
- 5 output functions
- Chip Enable input
- I/O propagation delay: 30ns (max.)
- Power dissipation: 500mW (typ.)
- Input loading:  $-100\mu A$  (max.)
- 3-State outputs
- Output disable function: Hi-Z
- Fully TTL compatible

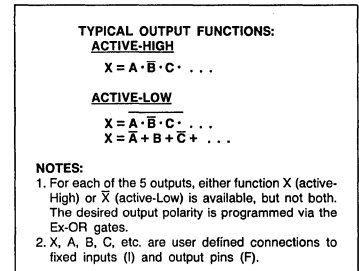
### APPLICATIONS

- Random logic
- Address decoders
- Code detectors
- Peripheral selectors
- Fault monitors
- Machine state decoders

### PIN CONFIGURATION



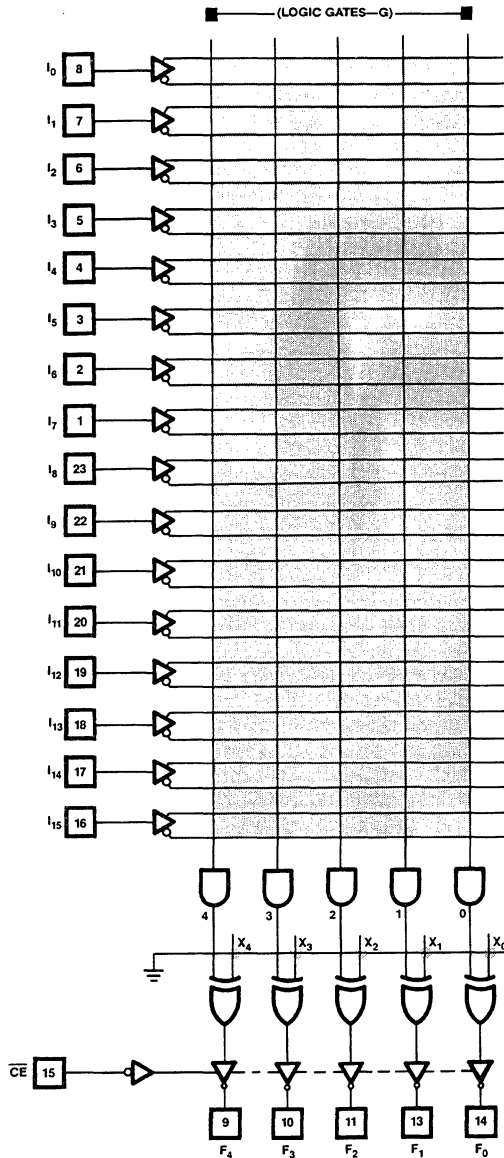
### LOGIC FUNCTION



# Field-Programmable Address Decoder (16 × 5)

PLS162

## FPAD LOGIC DIAGRAM



L0012405

**NOTE:**

1. All gate inputs with a blown link float to a logic "1".
2. ◊ Programmable connection.

4

## Field-Programmable Address Decoder (16 × 5)

PLS162

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
24-pin Plastic DIP 300mil-wide	PLS162N

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	+5.5	V <sub>DC</sub>
V <sub>O</sub>	Output voltage Off-State	+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input current	± 30	mA
I <sub>OUT</sub>	Output current	+ 100	mA
T <sub>A</sub>	Operating temperature range	0 to +75	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at those or any other conditions above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75 ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>2</sup>	Max	
<b>Input voltage<sup>1</sup></b>						
V <sub>IH</sub>	High	V <sub>CC</sub> = Max	2.0			V
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min			0.8	V
V <sub>IC</sub>	Clamp <sup>3</sup>	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA		-0.8	-1.2	V
<b>Output voltage<sup>1</sup></b>						
V <sub>OH</sub>	High <sup>5</sup>	V <sub>CC</sub> = Min I <sub>OH</sub> = -2mA	2.4			V
V <sub>OL</sub>	Low <sup>4</sup>	I <sub>OL</sub> = 15mA		0.35	0.5	V
<b>Input current</b>						
I <sub>IH</sub>	High	V <sub>CC</sub> = Max V <sub>IN</sub> = 5.5V		< 1	40	μA
I <sub>IL</sub>	Low	V <sub>IN</sub> = 0.45V		-10	-100	μA
<b>Output current</b>						
I <sub>O</sub> (OFF)	Hi-Z state <sup>6</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V		1	40	μA
I <sub>OS</sub>	Short circuit <sup>3, 7</sup>	V <sub>OUT</sub> = 0.45V V <sub>OUT</sub> = 0V		-1	-40	mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>8</sup>	V <sub>CC</sub> = Max		100	155	mA
<b>Capacitance</b>						
C <sub>IN</sub>	Input	V <sub>CC</sub> = 5.0V V <sub>IN</sub> = 2.0V		8		pF
C <sub>OUT</sub>	Output <sup>6</sup>	V <sub>OUT</sub> = 2.0V		15		pF

Notes on following page.

## Field-Programmable Address Decoder (16 × 5)

PLS162

**AC ELECTRICAL CHARACTERISTICS**  $0^{\circ}\text{C} \leq T_A \leq +75^{\circ}\text{C}$ ,  $4.75 \leq V_{CC} \leq 5.25\text{V}$ ,  $R_1 = 470\Omega$ ,  $R_2 = 1\text{k}\Omega$ 

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ <sup>1</sup>	Max	
$t_{PD}$	Propagation delay	Output	Input	$C_L = 30\text{pF}$		20	30	ns
$t_{CE}$	Chip enable	Output	Chip enable	$C_L = 30\text{pF}$		20	30	ns
$t_{CD}$	Chip disable	Output	Chip enable	$C_L = 5\text{pF}$		20	30	ns

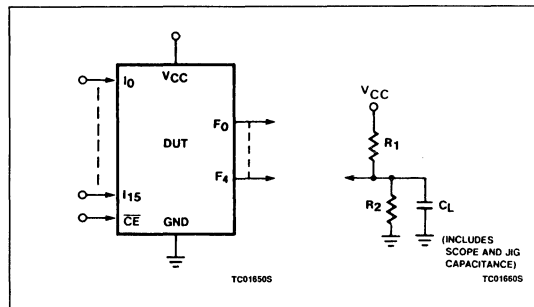
**NOTES:**

1. All voltage values are with respect to network ground terminal.
2. All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
3. Test each pin one at a time.
4. Measure with a programmed logic condition for which the output under test is at low logic level. Output sink current is supplied through a resistor to  $V_{CC}$ .
5. Measured with  $V_{IL}$  applied to  $\overline{CE}$  and logic high at the output.
6. Measured with  $V_{IH}$  applied to  $\overline{CE}$ .
7. Duration of short circuit should not exceed 1 second.
8.  $I_{CC}$  is measured with the outputs open.

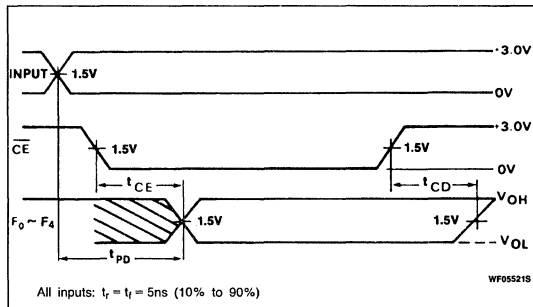
# Field-Programmable Address Decoder (16 × 5)

PLS162

## TEST LOAD CIRCUITS



## VOLTAGE WAVEFORMS



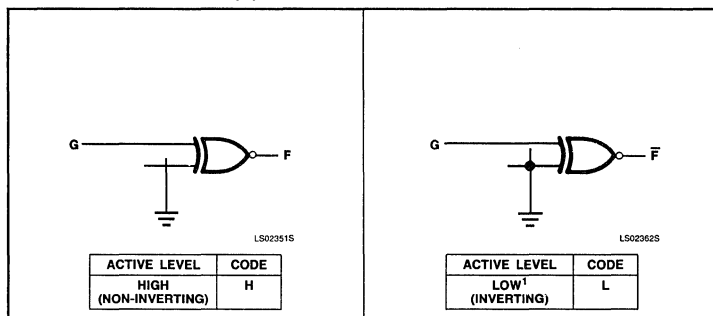
## LOGIC PROGRAMMING

PLS162 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

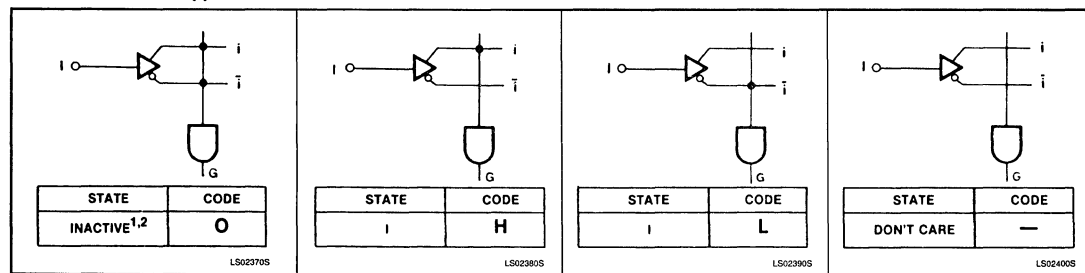
PLS162 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

## OUTPUT POLARITY - (F)



## "AND" ARRAY - (I)



### NOTES:

1. This is the initial unprogrammed state of all links.
2. Any gate  $G_n$  will be unconditionally inhibited if both the True and Complement of any input (either I or B) are left intact.

## VIRGIN DEVICE

The PLS162 is shipped in an unprogrammed state, in which:

1. All  $P_n$  terms are disabled. (Inactive).
2. All  $P_n$  terms are active on all outputs.
3. All outputs are active-Low.

# Field-Programmable Address Decoder (16 × 5)

PLS162

## FPAD PROGRAM TABLE

CUSTOMER NAME _____ PURCHASE ORDER # _____ SIGNETICS DEVICE # _____ TOTAL NUMBER OF PARTS _____ PROGRAM TABLE # _____	THIS PORTION TO BE COMPLETED BY SIGNETICS CF (XXXX) _____ CUSTOMER SYMBOLIZED PART # _____ DATE RECEIVED _____ COMMENTS _____
---	---

F<sub>0</sub> (14) \_\_\_\_\_ = \_\_\_\_\_  
 F<sub>1</sub> (13) \_\_\_\_\_ = \_\_\_\_\_  
 F<sub>2</sub> (11) \_\_\_\_\_ = \_\_\_\_\_  
 F<sub>3</sub> (10) \_\_\_\_\_ = \_\_\_\_\_  
 F<sub>4</sub> (9) \_\_\_\_\_ = \_\_\_\_\_

4

GATE	INPUT															
POLARITY	I <sub>15</sub>	I <sub>14</sub>	I <sub>13</sub>	I <sub>12</sub>	I <sub>11</sub>	I <sub>10</sub>	I <sub>9</sub>	I <sub>8</sub>	I <sub>7</sub>	I <sub>6</sub>	I <sub>5</sub>	I <sub>4</sub>	I <sub>3</sub>	I <sub>2</sub>	I <sub>1</sub>	I <sub>0</sub>
F <sub>0</sub>																
F <sub>1</sub>																
F <sub>2</sub>																
F <sub>3</sub>																
F <sub>4</sub>																
PIN NO.	16	17	18	19	20	21	22	23	1	2	3	4	5	6	7	8
VARIABLE NAME																

NOTES 1. The FPAD is shipped with all links intact. Thus a background of entries corresponding to states of virgin links exists in the table, shown BLANK for clarity. 2. Unused I bits are normally programmed Don't Care (—). 3. Unused Gates can be left blank.	PROGRAM TABLE ENTRIES  	AND <table border="1" style="width: 100%; border-collapse: collapse; text-align: center;"> <tr><td>INACTIVE</td><td>0</td></tr> <tr><td>I</td><td>H</td></tr> <tr><td>I</td><td>L</td></tr> <tr><td>Don't Care</td><td>—</td></tr> </table>	INACTIVE	0	I	H	I	L	Don't Care	—	CONTROL <table border="1" style="width: 100%; border-collapse: collapse; text-align: center;"> <tr><td>HIGH</td><td>H</td></tr> <tr><td>LOW</td><td>L</td></tr> </table> (POL.)	HIGH	H	LOW	L
INACTIVE	0														
I	H														
I	L														
Don't Care	—														
HIGH	H														
LOW	L														

TB01281S



**Application Specific Products**  
● Series 24

**DESCRIPTION**

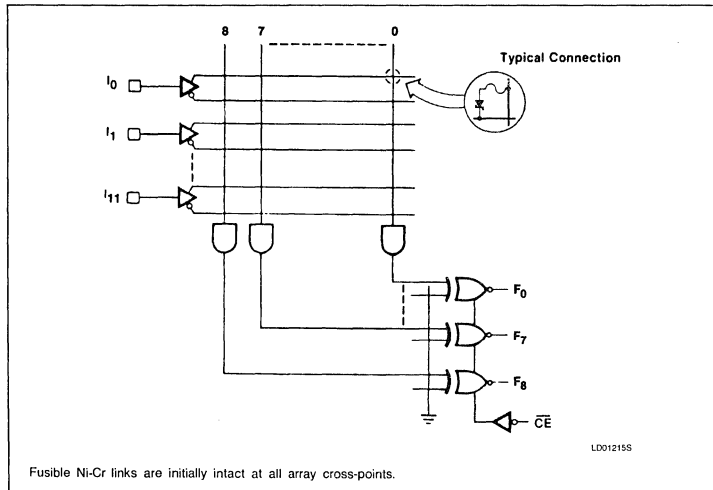
The PLS163 is a bipolar, Field-Programmable Address Decoder. The device consists of nine AND/NAND gates which share 12 common inputs. The type of gate is selected by programming the output as active-High (H) or active-Low (L). Each of the 12 inputs  $I_0 - I_{11}$  can be programmed to provide the True (H), Complement (L), or Don't Care (—) state to each of the nine AND/NAND gates. OR/NOR logic functions can also be implemented by complementing the inputs and outputs via on-chip inverting buffers.

The device is field programmable, which means that custom patterns are immediately available.

The PLS163 includes chip-enable control for output strobing and inhibit. It features 3-State outputs for ease of expansion of input variables and application in bus-organized systems.

Order codes are listed in the Ordering Information Table.

**FUNCTIONAL DIAGRAM**



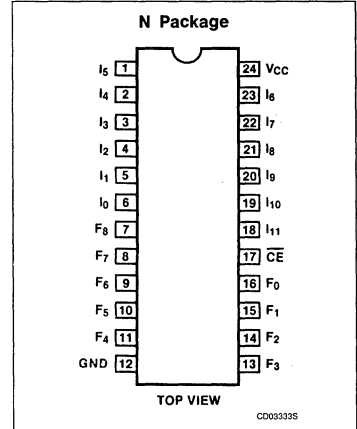
**FEATURES**

- Field-Programmable (Ni-Cr link)
- 12 input variables
- 9 output functions
- Chip Enable input
- I/O propagation delay: 30ns (max.)
- Power dissipation: 600mW (typ.)
- Input loading:  $-100\mu\text{A}$  (max.)
- 3-State outputs
- Output disable function: Hi-Z
- Fully TTL compatible

**APPLICATIONS**

- Random logic
- Address decoders
- Code detectors
- Peripheral selectors
- Fault monitors
- Machine state decoders

**PIN CONFIGURATION**



**LOGIC FUNCTION**

**TYPICAL OUTPUT FUNCTIONS:**  
ACTIVE-HIGH  
 $X = A \cdot \bar{B} \cdot C \dots$

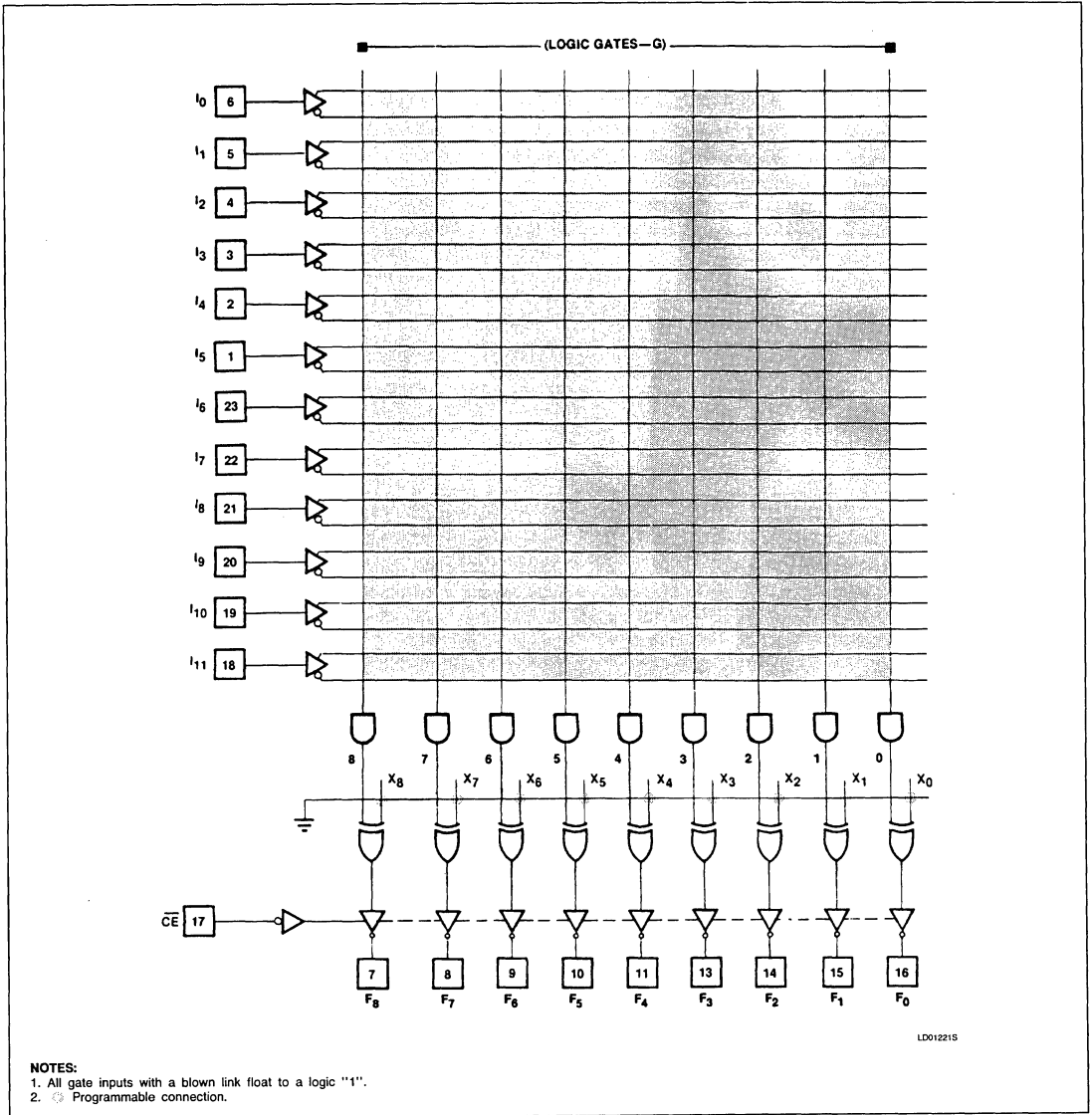
ACTIVE-LOW  
 $X = A \cdot \bar{B} \cdot C \dots$   
 $X = \bar{A} + B + C + \dots$

**NOTES:**  
 1. For each of the 9 outputs, either function X (active-High) or  $\bar{X}$  (active-Low) is available, but not both. The desired output polarity is programmed via the Ex-OR gates.  
 2. X, A, B, C, etc. are user defined connections to fixed inputs (I) and output pins (F).

# Field-Programmable Address Decoder (12 × 9)

PLS163

## FPAD LOGIC DIAGRAM



4

## Field-Programmable Address Decoder (12 × 9)

PLS163

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
24-pin Plastic DIP 300mil-wide	PLS163N

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	+5.5	V <sub>DC</sub>
V <sub>O</sub>	Output voltage Off-State	+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input current	±30	mA
I <sub>OUT</sub>	Output current	+100	mA
T <sub>A</sub>	Operating temperature range	0 to +75	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other conditions above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75 ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>2</sup>	Max	
<b>Input voltage</b>						
V <sub>IH</sub>	High <sup>1</sup>	V <sub>CC</sub> = Max	2.0			V
V <sub>IL</sub>	Low <sup>1</sup>	V <sub>CC</sub> = Min			0.8	V
V <sub>IC</sub>	Clamp <sup>1,3</sup>	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA		-0.8	-1.2	V
<b>Output voltage</b>						
V <sub>OH</sub>	High <sup>1,5</sup>	V <sub>CC</sub> = Min I <sub>OH</sub> = -2mA	2.4			V
V <sub>OL</sub>	Low <sup>1,4</sup>	I <sub>OL</sub> = 15mA		0.35	0.5	V
<b>Input current</b>						
I <sub>IH</sub>	High	V <sub>CC</sub> = Max V <sub>IN</sub> = 5.5V		< 1	40	μA
I <sub>IL</sub>	Low	V <sub>IN</sub> = 0.45V		-10	-100	μA
<b>Output current</b>						
I <sub>O (OFF)</sub>	Hi-Z state <sup>6</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V		1	40	μA
I <sub>OS</sub>	Short circuit <sup>3,7</sup>	V <sub>OUT</sub> = 0.45V V <sub>OUT</sub> = 0V		-1	-40	μA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>8</sup>	V <sub>CC</sub> = Max			-70	mA
<b>Capacitance</b>						
C <sub>IN</sub>	Input	V <sub>CC</sub> = 5.0V V <sub>IN</sub> = 2.0V		8		pF
C <sub>OUT</sub>	Output <sup>6</sup>	V <sub>OUT</sub> = 2.0V		15		pF

Notes on following page.

## Field-Programmable Address Decoder (12 × 9)

PLS163

**AC ELECTRICAL CHARACTERISTICS**  $0^{\circ}\text{C} \leq T_A \leq +75^{\circ}\text{C}$ ,  $4.75 \leq V_{CC} \leq 5.25\text{V}$ ,  $R_1 = 470\Omega$ ,  $R_2 = 1\text{k}\Omega$ 

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ <sup>2</sup>	Max	
$t_{PD}$	Propagation delay	Output	Input	$C_L = 30\text{pF}$		20	30	ns
$t_{CE}$	Chip enable	Output	Chip enable	$C_L = 30\text{pF}$		20	30	ns
$t_{CD}$	Chip disable	Output	Chip enable	$C_L = 5\text{pF}$		20	30	ns

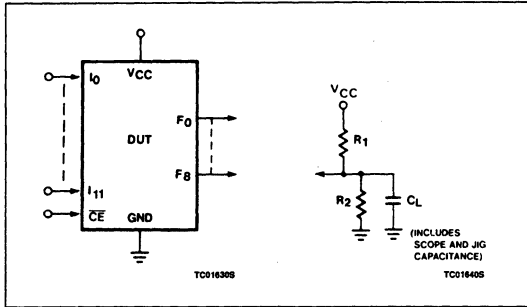
**NOTES:**

1. All voltage values are with respect to network ground terminal.
2. All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
3. Test each pin one at a time.
4. Measure with a programmed logic condition for which the output under test is at low logic level. Output sink current is supplied through a resistor to  $V_{CC}$ .
5. Measured with  $V_{IL}$  applied to  $\overline{CE}$  and logic high at the output.
6. Measured with  $V_{IH}$  applied to  $\overline{CE}$ .
7. Duration of short circuit should not exceed 1 second.
8.  $I_{CC}$  is measured with the outputs open.

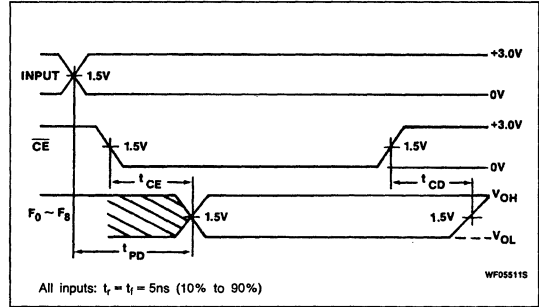
# Field-Programmable Address Decoder (12 × 9)

PLS163

## TEST LOAD CIRCUITS



## VOLTAGE WAVEFORMS



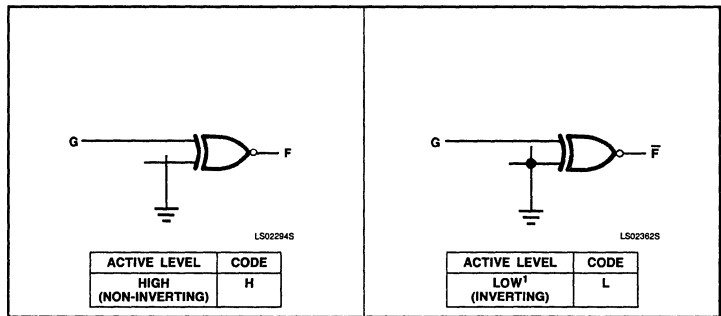
## LOGIC PROGRAMMING

PLS163 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

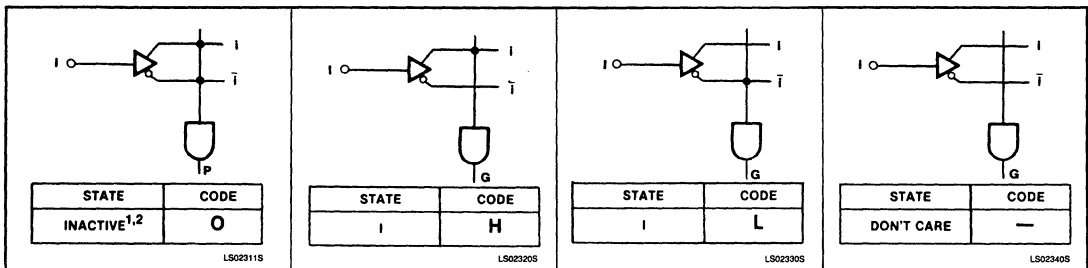
PLS163 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

## OUTPUT POLARITY - (F)



## "AND" ARRAY - (I)



### NOTES:

1. This is the initial unprogrammed state of all links.
2. Any gate  $G_n$  will be unconditionally inhibited if both the True and Complement fuses of any input (I) are left intact.

## VIRGIN DEVICE

The PLS163 is shipped in an unprogrammed state, in which:

1. All  $P_n$  terms are disabled. (Inactive).
2. All  $P_n$  terms are active on all outputs.
3. All outputs are active-Low.

# Field-Programmable Address Decoder (12 × 9)

PLS163

## FPAD PROGRAM TABLE

CUSTOMER NAME _____ PURCHASE ORDER # _____ SIGNETICS DEVICE # _____ TOTAL NUMBER OF PARTS _____ PROGRAM TABLE # _____	THIS PORTION TO BE COMPLETED BY SIGNETICS CF (XXXX) _____ CUSTOMER SYMBOLIZED PART # _____ DATE RECEIVED _____ COMMENTS _____
---	---

- F<sub>0</sub> (16) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>1</sub> (15) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>2</sub> (14) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>3</sub> (13) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>4</sub> (11) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>5</sub> (10) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>6</sub> (9) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>7</sub> (8) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>8</sub> (7) \_\_\_\_\_ = \_\_\_\_\_

GATE	INPUT												
	POLARITY	I <sub>11</sub>	I <sub>10</sub>	I <sub>9</sub>	I <sub>8</sub>	I <sub>7</sub>	I <sub>6</sub>	I <sub>5</sub>	I <sub>4</sub>	I <sub>3</sub>	I <sub>2</sub>	I <sub>1</sub>	I <sub>0</sub>
F <sub>0</sub>													
F <sub>1</sub>													
F <sub>2</sub>													
F <sub>3</sub>													
F <sub>4</sub>													
F <sub>5</sub>													
F <sub>6</sub>													
F <sub>7</sub>													
F <sub>8</sub>													
PIN NO.	18	19	20	21	22	23	1	2	3	4	5	6	
VARIABLE NAME													

**NOTES**

1. The FPAD is shipped with all links intact. Thus a background of entries corresponding to states of virgin links exists in the table, shown BLANK for clarity.
2. Unused I bits are normally programmed Don't Care (—).
3. Unused Gates can be left blank.

**PROGRAM TABLE ENTRIES**

AND	CONTROL												
<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><td>INACTIVE</td><td>0</td></tr> <tr><td>I</td><td>H</td></tr> <tr><td>T</td><td>L</td></tr> <tr><td>Don't Care</td><td>—</td></tr> </table>	INACTIVE	0	I	H	T	L	Don't Care	—	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><td>HIGH</td><td>H</td></tr> <tr><td>LOW</td><td>L</td></tr> </table>	HIGH	H	LOW	L
INACTIVE	0												
I	H												
T	L												
Don't Care	—												
HIGH	H												
LOW	L												
(I)	(POL.)												

4

# PLS173

## Field-Programmable Logic Array (22 × 42 × 10)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

- Series 24

### DESCRIPTION

The PLS173 is a two-level logic element consisting of 42 AND gates and 10 OR gates with fusible link connections for programming I/O polarity and direction.

All AND gates are linked to 12 inputs (I) and 10 bidirectional I/O lines (B). These yield variable I/O gate configurations via 10 direction control gates (D), ranging from 22 inputs to 10 outputs.

On chip T/C buffers couple either True (I, B) or Complement (I,  $\bar{B}$ ) input polarities to all AND gates, whose outputs can be optionally linked to all OR gates. Their output polarity, in turn, is individually programmable through a set of EX-OR gates for implementing AND/OR or AND/NOR logic functions.

The PLS173 is field programmable, enabling the user to quickly generate custom patterns using standard programming equipment.

Order codes are listed in the Ordering Information Table.

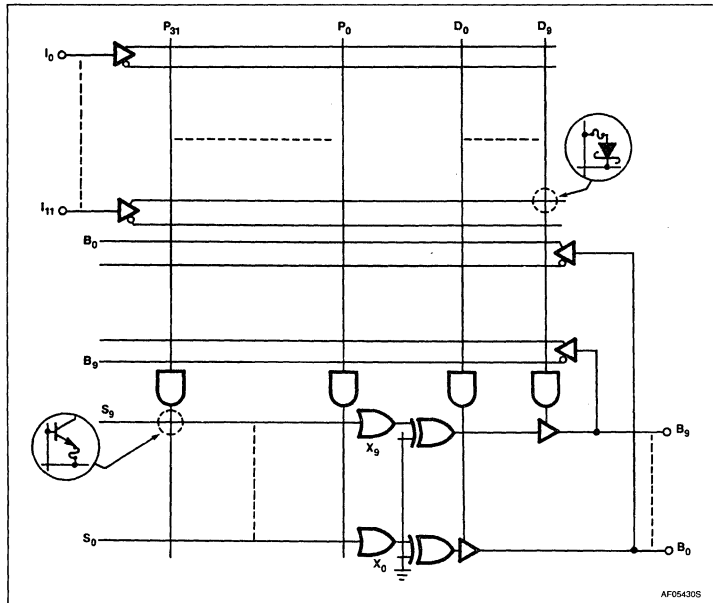
### FEATURES

- Field-Programmable (Ni-Cr links)
- 12 inputs
- 42 AND gates
- 10 OR gates
- 10 bidirectional I/O lines
- Active-High or -Low outputs
- 42 product terms:
  - 32 logic terms
  - 10 control terms
- I/O propagation delay: 30ns (max.)
- Input loading: -100 $\mu$ A (max.)
- Power dissipation: 750mW (typ.)
- 3-State outputs
- TTL compatible

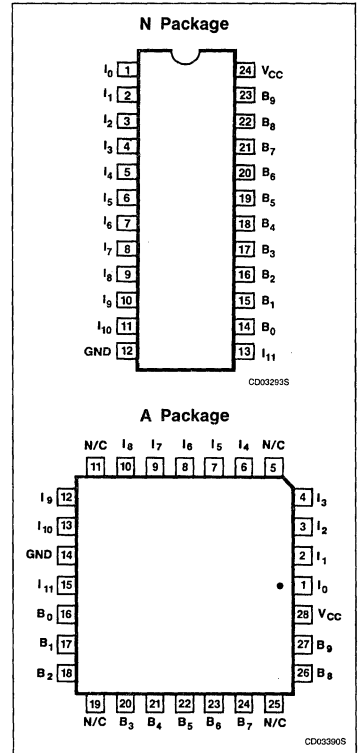
### APPLICATIONS

- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping
- Multiplexing

### FUNCTIONAL DIAGRAM



### PIN CONFIGURATIONS



### LOGIC FUNCTION

**TYPICAL PRODUCT TERM:**  
 $P_n = A \cdot \bar{B} \cdot C \cdot D \dots$

**TYPICAL LOGIC FUNCTION:**  
 AT OUTPUT POLARITY = H  
 $Z = P_0 + P_1 + P_2 \dots$

AT OUTPUT POLARITY = L  
 $Z = \bar{P}_0 \cdot \bar{P}_1 \cdot \bar{P}_2 \dots$

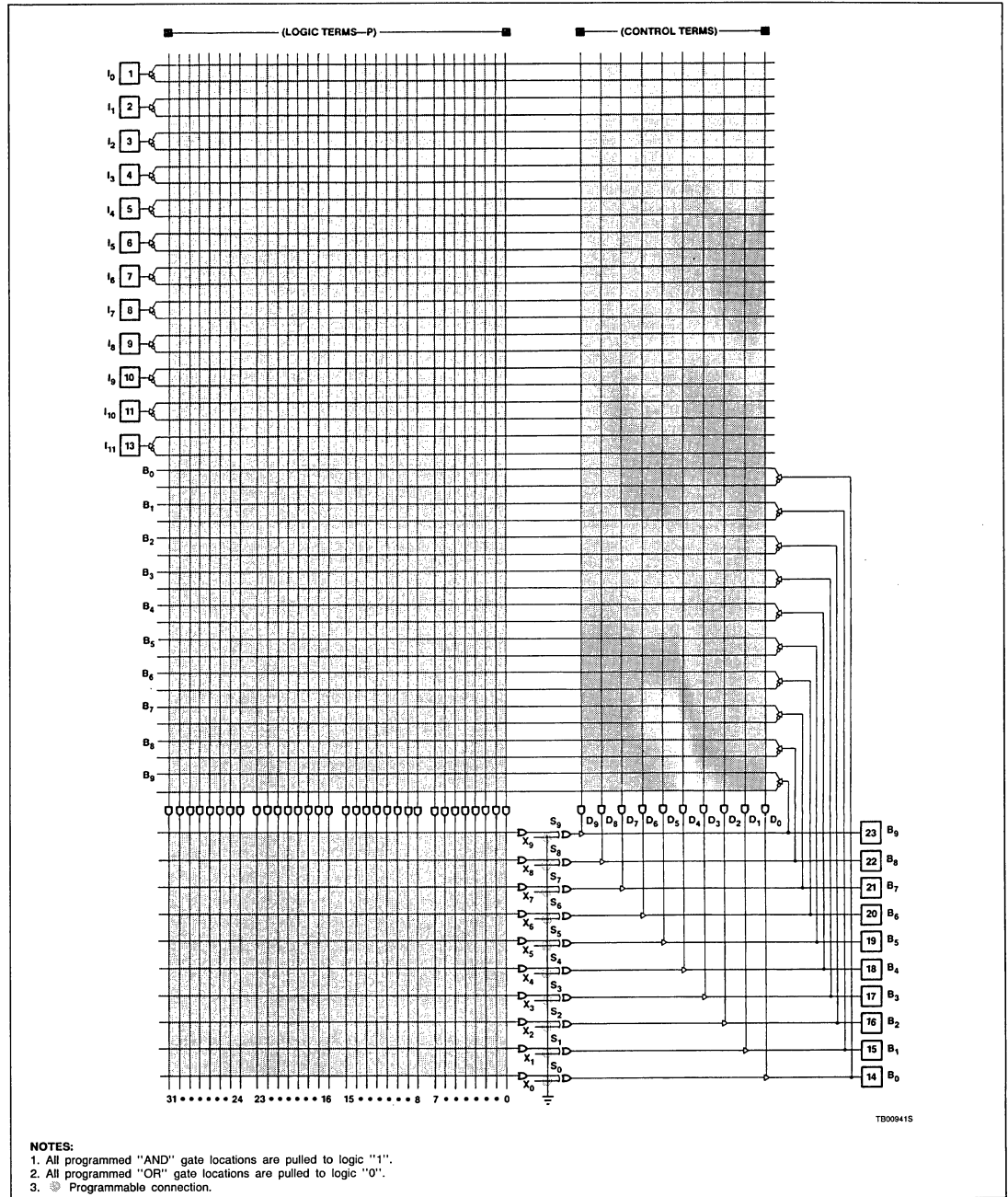
**NOTES:**

- For each of the 10 outputs, either function Z (Active-High) or  $\bar{Z}$  (Active-Low) is available, but not both. The desired output polarity is programmed via the EX-OR gates.
- Z, A, B, C, etc. are user defined connections to fixed inputs (I), and bidirectional pins (B).

# Field-Programmable Logic Array (22 × 42 × 10)

PLS173

## FPLA LOGIC DIAGRAM



4



## Field-Programmable Logic Array (22 × 42 × 10)

PLS173

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
24-pin Plastic DIP 300mil-wide	PLS173N
28-pin Plastic Leaded Chip Carrier	PLS173A

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75 ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IL</sub> V <sub>IH</sub> V <sub>IC</sub>	Low High Clamp <sup>2, 3</sup>	V <sub>CC</sub> = Min V <sub>CC</sub> = Max V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA	2.0	-0.8	0.8 -1.2	V V V
<b>Output voltage</b>						
V <sub>OL</sub> V <sub>OH</sub>	Low <sup>2, 4</sup> High <sup>2, 5</sup>	V <sub>CC</sub> = Min I <sub>OL</sub> = 15mA I <sub>OH</sub> = -2mA	2.4		0.5	V V
<b>Input current<sup>10</sup></b>						
I <sub>IL</sub> I <sub>IH</sub>	Low High	V <sub>CC</sub> = Max V <sub>IN</sub> = 0.45V V <sub>IN</sub> = 5.5V			-100 40	μA μA
<b>Output current</b>						
I <sub>O(OFF)</sub> I <sub>OS</sub>	Hi-Z state <sup>9</sup> Short circuit <sup>3, 5, 6</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V V <sub>OUT</sub> = 0.45V V <sub>OUT</sub> = 0V	-15		80 -140 -70	μA mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>7</sup>	V <sub>CC</sub> = Max		150	170	mA
<b>Capacitance</b>						
I <sub>IN</sub> C <sub>B</sub>	Input I/O	V <sub>CC</sub> = 5V V <sub>IN</sub> = 2.0V V <sub>B</sub> = 2.0V		8 15		pF pF

Notes on following page.

# Field-Programmable Logic Array (22 × 42 × 10)

PLS173

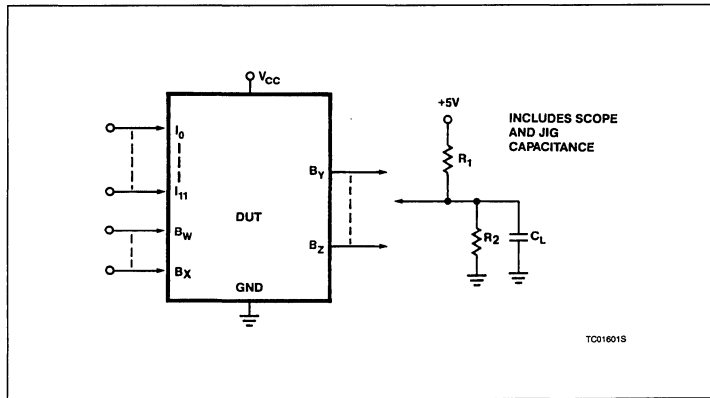
## AC ELECTRICAL CHARACTERISTICS $0^{\circ}\text{C} \leq T_A \leq +75^{\circ}\text{C}$ , $4.75 \leq V_{CC} \leq 5.25\text{V}$ , $R_1 = 470\Omega$ , $R_2 = 1\text{k}\Omega$

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ	Max	
$t_{PD}$	Propagation delay	Output $\pm$	Input $\pm$	$C_L = 30\text{pF}$		20	30	ns
$t_{OE}$	Output enable	Output -	Input $\pm$	$C_L = 30\text{pF}$		20	30	ns
$t_{OD}$	Output disable <sup>B</sup>	Output +	Input $\pm$	$C_L = 5\text{pF}$		20	30	ns

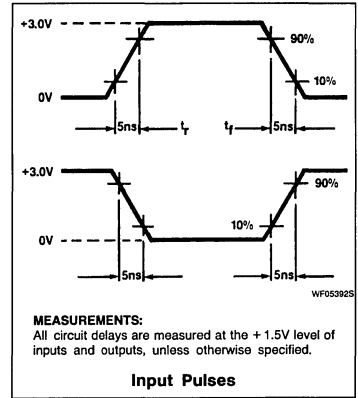
**NOTES:**

- All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- Measured with  $V_{IL}$  applied to  $I_{11}$ . Pins 1-5 = 0V, Pins 6-10 = 4.5V, Pin 11 = 0V and Pin 13 = 10V.
- Same conditions as Note 5 except Pin 11 = +10V.
- Duration of short circuit should not exceed 1 second.
- $I_{CC}$  is measured with  $I_0$  and  $I_1 = 0\text{V}$  and  $I_2 - I_{11}$  and  $B_0 - B_9 = 4.5\text{V}$ . Part in Virgin State.
- Measured at  $V_T = V_{OL} + 0.5\text{V}$ .
- Leakage values are a combination of input and output leakage.
- $I_{L}$  and  $I_{H}$  limits are for dedicated inputs only ( $I_0 - I_{11}$ ).

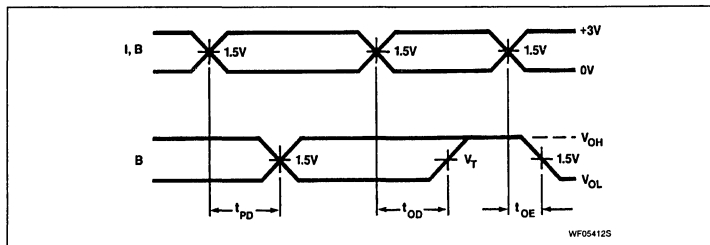
### TEST LOAD CIRCUITS



### VOLTAGE WAVEFORMS



### TIMING DIAGRAM



### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Propagation delay between input and output.
$t_{OD}$	Delay between input change and when output is off (Hi-Z or High).
$t_{OE}$	Delay between input change and when output reflects specified output level.

4

# Field-Programmable Logic Array (22 × 42 × 10)

PLS173

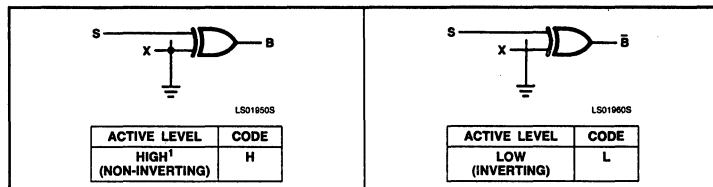
## LOGIC PROGRAMMING

PLS173 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

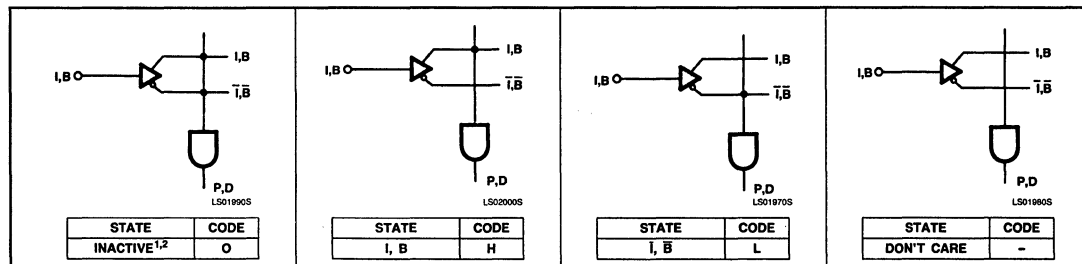
PLS173 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

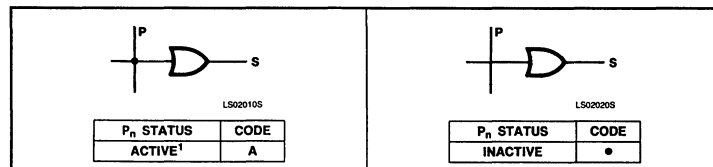
## OUTPUT POLARITY - (B)



## "AND" ARRAY - (I, B)



## OR ARRAY - (B)



## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

1. All outputs are at "H" polarity.
2. All P<sub>n</sub> terms are disabled.
3. All P<sub>n</sub> terms are active on all outputs.

## NOTES:

1. This is the initial unprogrammed state of all link pairs. It is normally associated with all unused (inactive) AND gates P<sub>n</sub>, D<sub>n</sub>.
2. Any gate P<sub>n</sub>, D<sub>n</sub> will be unconditionally inhibited if both the True and Complement of any input (I, B) are left intact.

# Field-Programmable Logic Array (22 × 42 × 10)

PLS173

## FPLA PROGRAM TABLE

POLARITY																							
OR		AND											OR										
B(0)		B(1)											B(0)										
9 8 7 6 5 4 3 2 1 0		11 10 9 8 7 6 5 4 3 2 1 0											9 8 7 6 5 4 3 2 1 0										
T E R M																							
1																							
2																							
3																							
4																							
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D9																							
D8																							
D7																							
D6																							
D5																							
D4																							
D3																							
D2																							
D1																							
D0																							
PIN		13 11 10 9 8 7 6 5 4 3 2 1											23 22 21 20 19 18 17 16 15 14										
VARIABLE NAME																							
AND																							
OR																							
I/O																							
CONTROL																							
HIGH I/O																							
LOW I/O																							
ACTIVE I/O																							
INACTIVE I/O																							
DON'T CARE I/O																							

CUSTOMER NAME \_\_\_\_\_

SIGNETICS DEVICE # \_\_\_\_\_

PROGRAM TABLE # \_\_\_\_\_ REV \_\_\_\_\_ DATE \_\_\_\_\_

**Notes**

- The FPLA is shipped with all fields intact. This a background of 1's and 0's in the AND array and 1's and 0's in the OR array. (Known BLANK for AND's)
- Unused 1 and 0 bits in the AND array must be programmed Don't Care (-).
- Unused product terms can be left blank.

# PLUS173B

## Field-Programmable Logic Array (22 × 42 × 10)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

- Series 24

### DESCRIPTION

The PLUS173B is a 15ns version of the PLS173 FPLA architecture. The Signetics state-of-the-art Oxide Isolated Bipolar fabrication process is employed to produce performance levels not yet achieved in devices of this complexity.

The PLUS173B is a two-level logic element consisting of 42 AND gates and 10 OR gates with fusible link connections for programming I/O polarity and direction.

All AND gates are linked to 12 inputs (I) and 10 bidirectional I/O lines (B). These yield variable I/O gate configurations via 10 direction control gates (D), ranging from 22 inputs to 10 outputs.

On chip T/C buffers couple either True (I, B) or Complement ( $\bar{I}$ ,  $\bar{B}$ ) input polarities to all AND gates, whose outputs can be optionally linked to all OR gates. Their output polarity, in turn, is individually programmable through a set of Ex-OR gates for implementing AND/OR or AND/NOR logic functions.

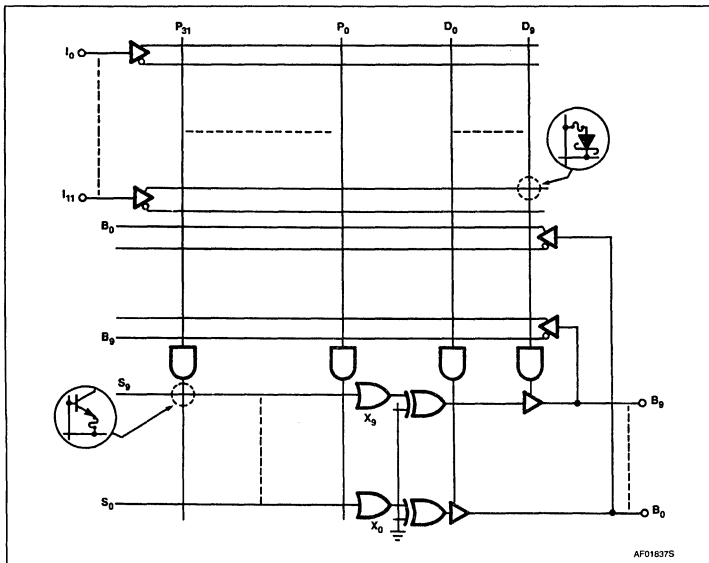
The PLUS173B is field-programmable, enabling the user to quickly generate

custom patterns using standard programming equipment.

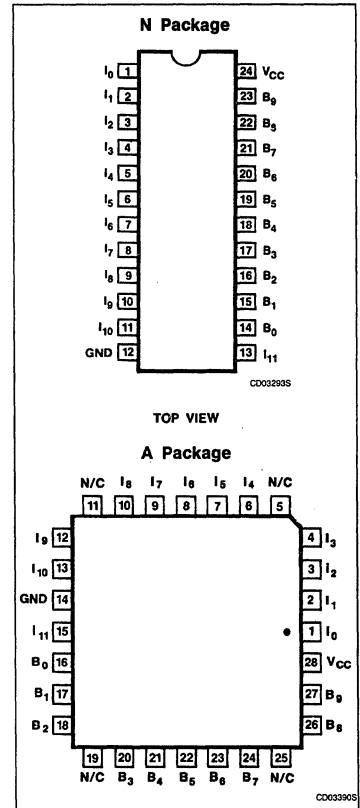
### FEATURES

- Field-Programmable (Ti-W links)
- Functionally identical to, and pin-for-pin compatible with, the PLS173 and the PLUS173D
- 12 inputs
- 42 AND gates
- 10 OR gates
- 10 bidirectional I/O lines
- Programmable output polarity
  - active-High or -Low outputs
- 42 product terms:
  - 32 logic terms
  - 10 control terms
- I/O propagation delay: 15ns (max.)
- Input loading: - 100 $\mu$ A (max.)
- Power dissipation: 750mW (typ.)
- 3-State outputs
- TTL compatible
- Security fuse

### FUNCTIONAL DIAGRAM



### PIN CONFIGURATIONS



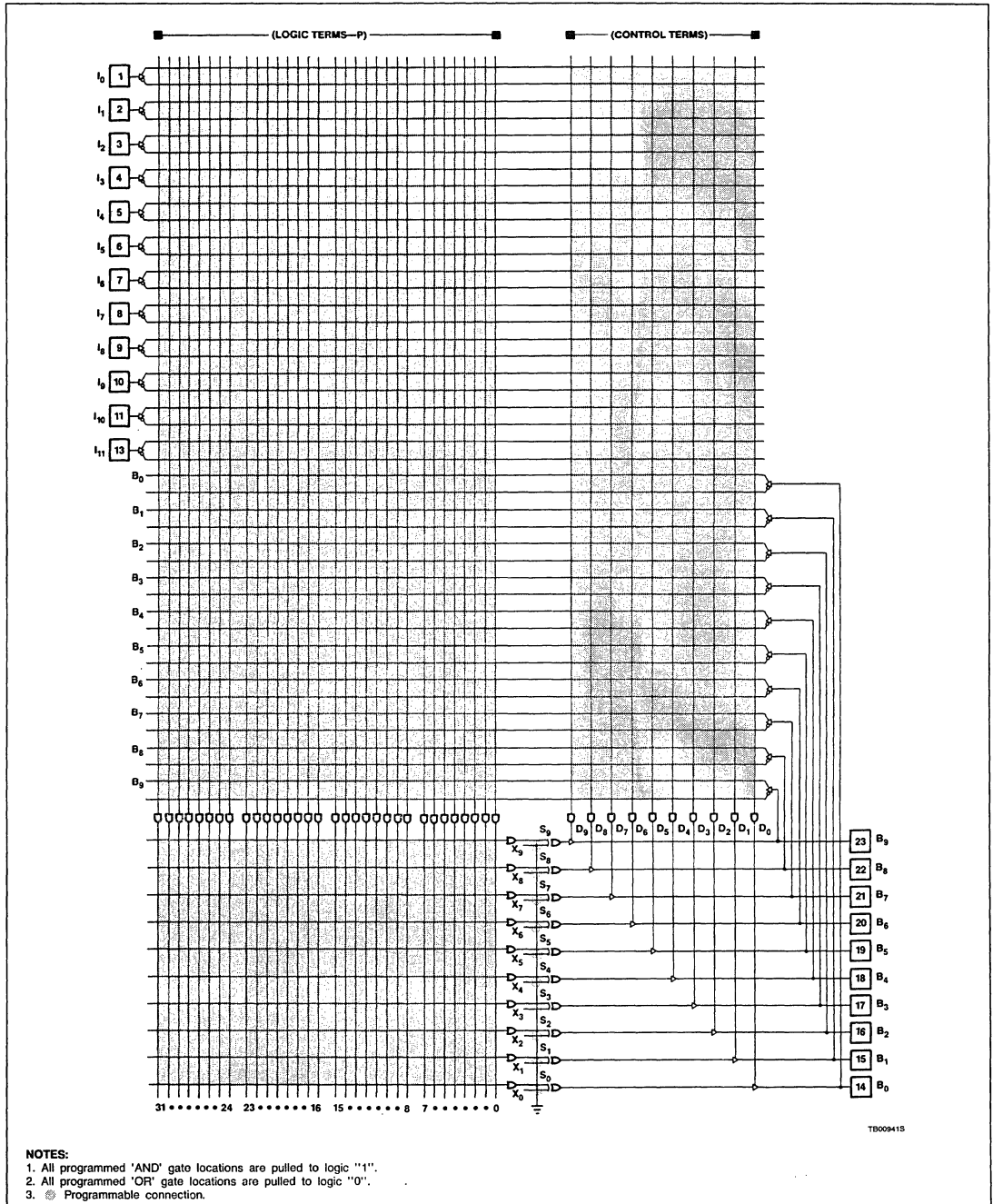
### APPLICATIONS

- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping
- Multiplexing

# Field-Programmable Logic Array (22 × 42 × 10)

PLUS173B

## FPLA LOGIC DIAGRAM



4

## Field-Programmable Logic Array (22 × 42 × 10)

PLUS173B

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
24-pin Plastic DIP 300mil-wide	PLUS173BN
28-pin Plastic Leaded Chip Carrier	PLUS173BA

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating free-air temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

The PLUS173B device is also processed to military requirements for operation over the military temperature range. For specifications and ordering information consult the Signetics Military Data Book.

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75 ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT	
			Min	Typ <sup>1</sup>	Max		
<b>Input voltage<sup>2</sup></b>							
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min	2.0		0.8	V	
V <sub>IH</sub>	High	V <sub>CC</sub> = Max					V
V <sub>IC</sub>	Clamp	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA			-0.8	-1.2	V
<b>Output voltage<sup>2</sup></b>							
V <sub>OL</sub>	Low <sup>4</sup>	V <sub>CC</sub> = Min	2.4		0.5	V	
V <sub>OH</sub>	High <sup>5</sup>	I <sub>OL</sub> = 15mA I <sub>OH</sub> = -2mA					
<b>Input current<sup>10</sup></b>							
I <sub>IL</sub>	Low	V <sub>CC</sub> = Max			-100	μA	
I <sub>IH</sub>	High	V <sub>IN</sub> = 0.45V V <sub>IN</sub> = 5.5V					
<b>Output current</b>							
I <sub>O(OFF)</sub>	Hi-Z state <sup>9</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V	-15		80	μA	
I <sub>OS</sub>	Short circuit <sup>3, 5, 6</sup>	V <sub>OUT</sub> = 0.45V V <sub>OUT</sub> = 0V					-140 -70
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>7</sup>	V <sub>CC</sub> = Max		150	200	mA	
<b>Capacitance</b>							
I <sub>IN</sub>	Input	V <sub>CC</sub> = 5V			8	pF	
C <sub>B</sub>	I/O	V <sub>IN</sub> = 2.0V V <sub>B</sub> = 2.0V			15		pF

Notes on following page.

# Field-Programmable Logic Array (22 × 42 × 10)

PLUS173B

## AC ELECTRICAL CHARACTERISTICS $0^{\circ}\text{C} \leq T_A \leq +75^{\circ}\text{C}$ , $4.75 \leq V_{CC} \leq 5.25\text{V}$ , $R_1 = 470\Omega$ , $R_2 = 1\text{k}\Omega$

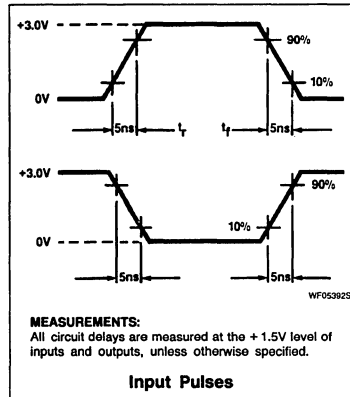
SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ	Max	
$t_{PD}$	Propagation delay	Output $\pm$	Input $\pm$	$C_L = 30\text{pF}$		11	15	ns
$t_{OE}$	Output enable	Output -	Input $\pm$	$C_L = 30\text{pF}$		11	15	ns
$t_{OD}$	Output disable <sup>6</sup>	Output +	Input $\pm$	$C_L = 5\text{pF}$		11	15	ns

**NOTES:**

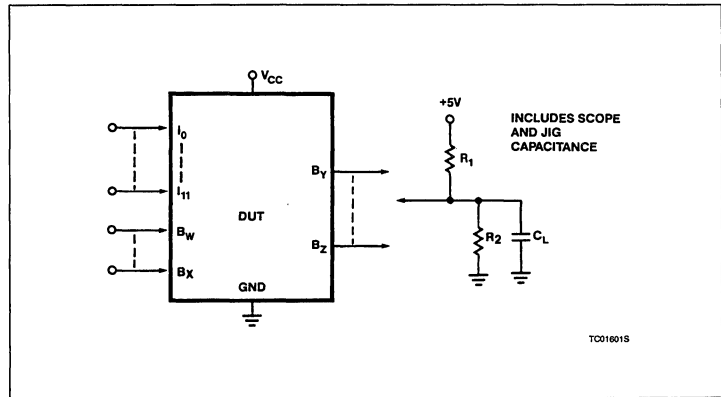
1. All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
2. All voltage values are with respect to network ground terminal.
3. Test one at a time.
4. Measured with inputs  $I_0 - I_4 = 0\text{V}$ , inputs  $I_5 - I_9 = 4.5\text{V}$ ,  $I_{11} = 4.5\text{V}$  and  $I_{10} = 10\text{V}$ . For outputs  $B_0 - B_4$  and for outputs  $B_5 - B_9$  apply the same conditions except  $I_{11} = 0\text{V}$ .
5. Same conditions as Note 4 except input  $I_{11} = +10\text{V}$ .
6. Duration of short circuit should not exceed 1 second.
7.  $I_{CC}$  is measured with inputs  $I_0 - I_{11}$  and  $B_0 - B_9 = 0\text{V}$ . Part in Virgin State.
8. Measured at  $V_T = V_{OL} + 0.5\text{V}$ .
9. Leakage values are a combination of input and output leakage.
10.  $I_{IL}$  and  $I_{IH}$  limits are for dedicated inputs only ( $I_0 - I_{11}$ ).

4

### VOLTAGE WAVEFORMS



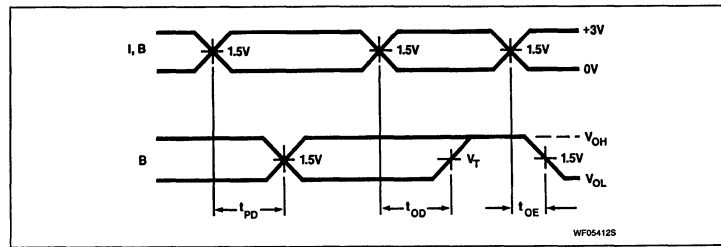
### TEST LOAD CIRCUITS



### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Propagation delay between input and output.
$t_{OD}$	Delay between input change and when output is off (Hi-Z or High).
$t_{OE}$	Delay between input change and when output reflects specified output level.

### TIMING DIAGRAM





# Field-Programmable Logic Array (22 × 42 × 10)

# PLUS173B

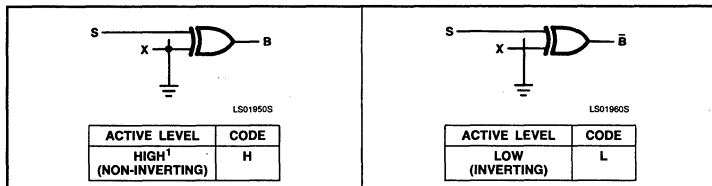
## LOGIC PROGRAMMING

PLUS173B logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

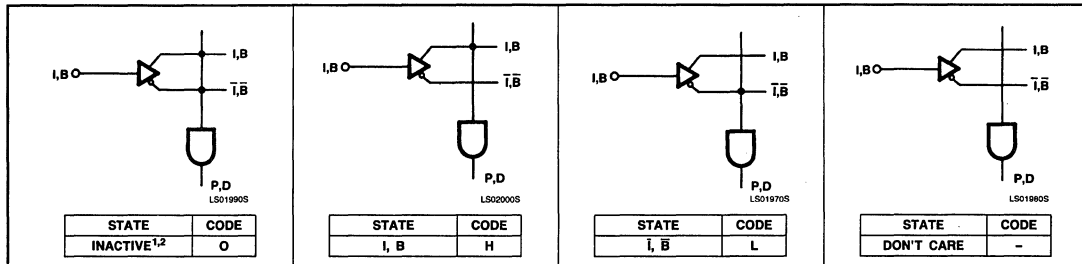
PLUS173B logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

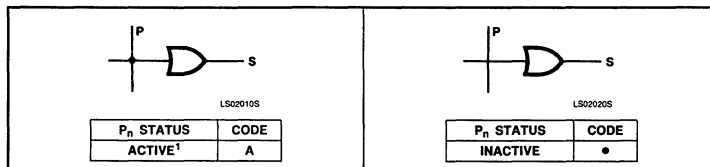
## OUTPUT POLARITY - (B)



## AND ARRAY - (I, B)



## OR ARRAY - (B)



## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

1. All outputs are at "H" polarity.
2. All P<sub>n</sub> terms are disabled.
3. All P<sub>n</sub> terms are active on all outputs.

### NOTES:

1. This is the initial unprogrammed state of all link pairs. It is normally associated with all unused (inactive) AND gates P<sub>n</sub>, D<sub>n</sub>.
2. Any gate P<sub>n</sub>, D<sub>n</sub> will be unconditionally inhibited if both the True and Complement of any input (I, B) are left intact.

# Field-Programmable Logic Array (22 × 42 × 10)

PLUS173B

## FPLA PROGRAM TABLE

POLARITY		AND											OR										
		B(1)											B(0)										
		11	10	9	8	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	1	0
CUSTOMER NAME _____																							
SIGNETICS DEVICE # _____																							
PROGRAM TABLE # _____ REV _____ DATE _____																							
Notes																							
1. The FPLA is shipped with all lines intact. Thus a background of																							
inactive bits of origin exists in the table.																							
(Shown Blank for clarity)																							
2. Unused 1 and 0 bits in the AND array must be programmed Don't																							
Care (-).																							
3. Unused product terms can be left blank.																							
OR																							
ACTIVE (A) B(0)																							
INACTIVE (-)																							
CONTROL																							
HIGH (H) (POL)																							
LOW (L)																							
AND																							
INACTIVE (0)																							
L(B) H																							
L(B) L																							
DON'T CARE (-)																							
VARIABLE NAME																							
		PIN 13 11 10 9 8 7 6 5 4 3 2 1 23 22											21 20 19 18 17 16 15 14 23 22 21 20 19 18 17 16 15 14										
		1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31																					

# PLUS173D

## Field-Programmable Logic Array (22 × 42 × 10)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

- Series 24

### DESCRIPTION

The PLUS173D is a 12ns version of the PLS173 FPLA architecture. The Signetics state-of-the-art Oxide Isolated Bipolar fabrication process is employed to produce performance levels not yet achieved in devices of this complexity.

The PLUS173D is a two-level logic element consisting of 42 AND gates and 10 OR gates with fusible link connections for programming I/O polarity and direction.

All AND gates are linked to 12 inputs (I) and 10 bidirectional I/O lines (B). These yield variable I/O gate configurations via 10 direction control gates (D), ranging from 22 inputs to 10 outputs.

On chip T/C buffers couple either True (I, B) or Complement ( $\bar{I}$ ,  $\bar{B}$ ) input polarities to all AND gates, whose outputs can be optionally linked to all OR gates. Their output polarity, in turn, is individually programmable through a set of Ex-OR gates for implementing AND/OR or AND/NOR logic functions.

The PLUS173D is field-programmable, enabling the user to quickly generate

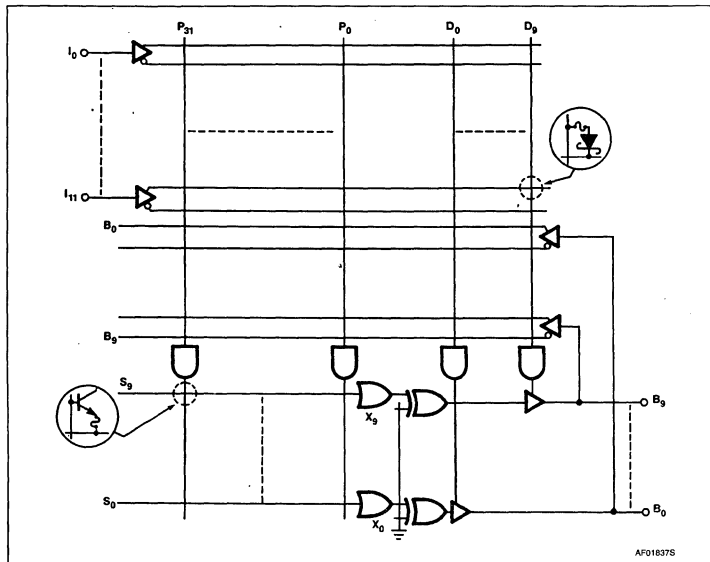
custom patterns using standard programming equipment.

Order codes are listed in the Ordering Information Table.

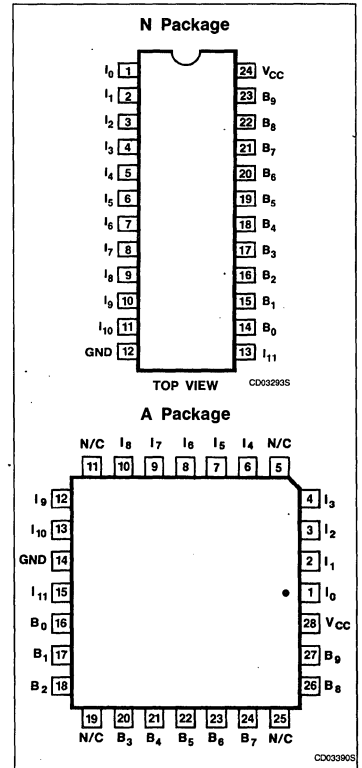
### FEATURES

- Field-Programmable (Ti-W links)
- Functionally identical to, and pin-for-pin compatible with, the PLS173 and the PLUS173B
- 12 inputs
- 42 AND gates
- 10 OR gates
- 10 bidirectional I/O lines
- Programmable output polarity
  - active-High or -Low outputs
- 42 product terms:
  - 32 logic terms
  - 10 control terms
- I/O propagation delay: 12ns (max.)
- Input loading: - 100 $\mu$ A (max.)
- Power dissipation: 750mW (typ.)
- 3-State outputs
- TTL compatible
- Security fuse

### FUNCTIONAL DIAGRAM



### PIN CONFIGURATIONS



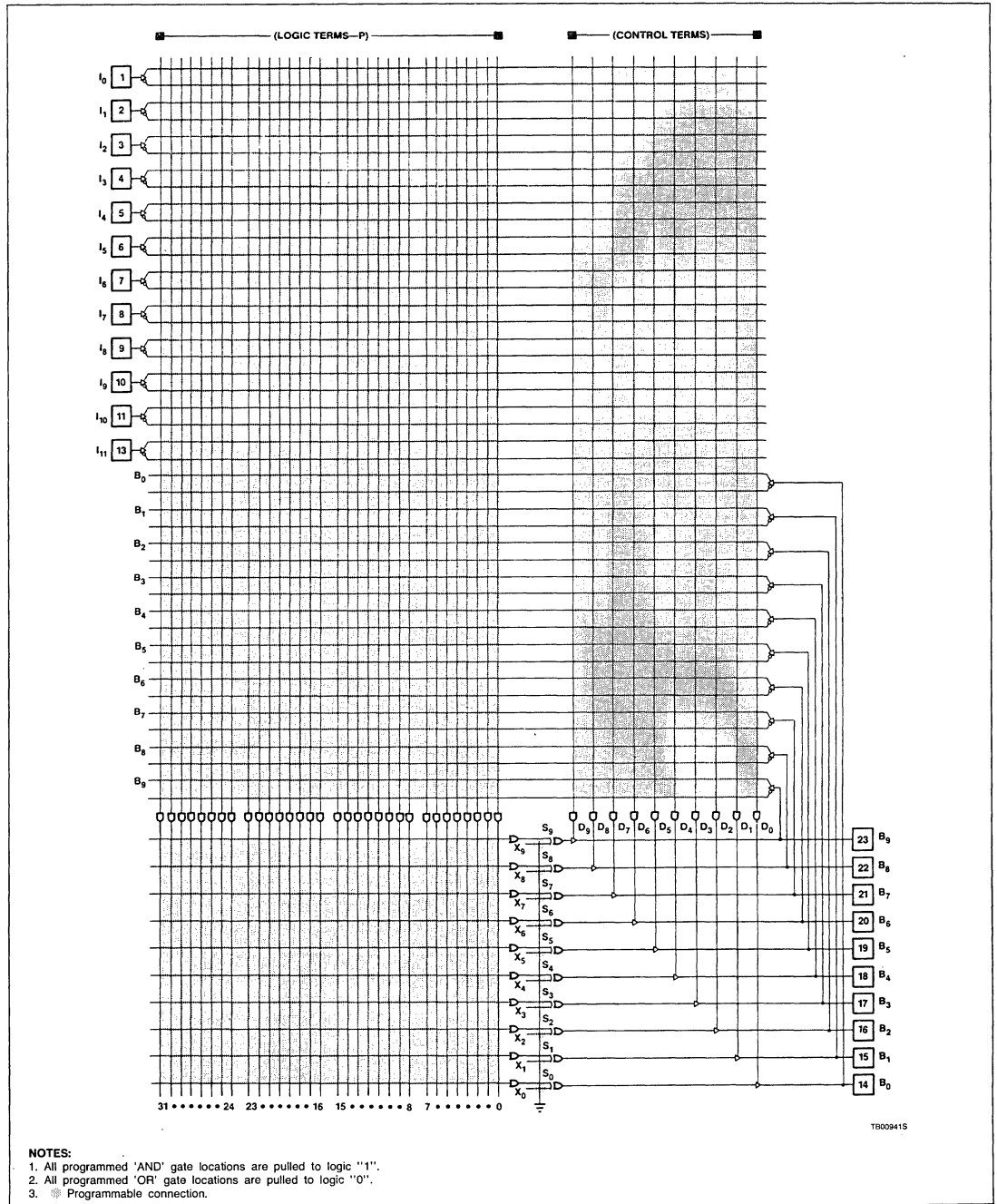
### APPLICATIONS

- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping
- Multiplexing

# Field-Programmable Logic Array (22 × 42 × 10)

## PLUS173D

### FPLA LOGIC DIAGRAM



4

# Field-Programmable Logic Array (22 × 42 × 10)

# PLUS173D

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
24-pin Plastic DIP 300mil-wide	PLUS173DN
28-pin Plastic Leaded Chip Carrier	PLUS173DA

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

## ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating free-air temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

**NOTE:**

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

## DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75 ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IL</sub> V <sub>IH</sub> V <sub>IC</sub>	Low High Clamp	V <sub>CC</sub> = Min V <sub>CC</sub> = Max V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA	2.0	-0.8	0.8 -1.2	V V V
<b>Output voltage<sup>2</sup></b>						
V <sub>OL</sub> V <sub>OH</sub>	Low <sup>4</sup> High <sup>5</sup>	V <sub>CC</sub> = Min I <sub>OL</sub> = 15mA I <sub>OH</sub> = -2mA	2.4		0.5	V V
<b>Input current<sup>10</sup></b>						
I <sub>IL</sub> I <sub>IH</sub>	Low High	V <sub>CC</sub> = Max V <sub>IN</sub> = 0.45V V <sub>IN</sub> = 5.5V			-100 40	μA μA
<b>Output current</b>						
I <sub>O(OFF)</sub> I <sub>OS</sub>	Hi-Z state <sup>9</sup> Short circuit <sup>3, 5, 6</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V V <sub>OUT</sub> = 0.45V V <sub>OUT</sub> = 0V	-15		80 -140 -70	μA mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>7</sup>	V <sub>CC</sub> = Max		150	200	mA
<b>Capacitance</b>						
I <sub>IN</sub> C <sub>B</sub>	Input I/O	V <sub>CC</sub> = 5V V <sub>IN</sub> = 2.0V V <sub>B</sub> = 2.0V		8 15		pF pF

Notes on following page.

# Field-Programmable Logic Array (22 × 42 × 10)

PLUS173D

## AC ELECTRICAL CHARACTERISTICS $0^{\circ}\text{C} \leq T_A \leq +75^{\circ}\text{C}$ , $4.75 \leq V_{CC} \leq 5.25\text{V}$ , $R_1 = 470\Omega$ , $R_2 = 1\text{k}\Omega$

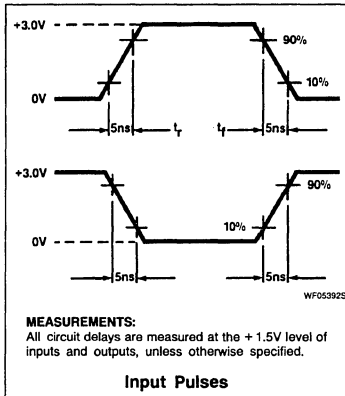
SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ	Max	
$t_{PD}$	Propagation delay	Output $\pm$	Input $\pm$	$C_L = 30\text{pF}$		10	12	ns
$t_{OE}$	Output enable	Output $-$	Input $\pm$	$C_L = 30\text{pF}$		10	12	ns
$t_{OD}$	Output disable <sup>9</sup>	Output $+$	Input $\pm$	$C_L = 5\text{pF}$		10	12	ns

**NOTES:**

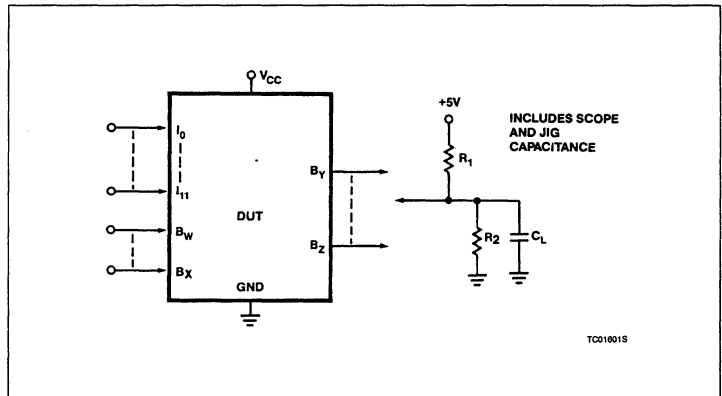
1. All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
2. All voltage values are with respect to network ground terminal.
3. Test one at a time.
4. Measured with inputs  $I_0 - I_4 = 0\text{V}$ , inputs  $I_5 - I_9 = 4.5\text{V}$ ,  $I_{11} = 4.5\text{V}$  and  $I_{10} = 10\text{V}$ . For outputs  $B_0 - B_4$  and for outputs  $B_5 - B_9$  apply the same conditions except  $I_{11} = 0\text{V}$ .
5. Same conditions as Note 4 except input  $I_{11} = +10\text{V}$ .
6. Duration of short circuit should not exceed 1 second.
7.  $I_{CC}$  is measured with inputs  $I_0 - I_{11}$  and  $B_0 - B_9 = 0\text{V}$ . Part in Virgin State.
8. Measured at  $V_T = V_{OL} + 0.5\text{V}$ .
9. Leakage values are a combination of input and output leakage.
10.  $I_{IL}$  and  $I_{IH}$  limits are for dedicated inputs only ( $I_0 - I_{11}$ ).

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### VOLTAGE WAVEFORMS



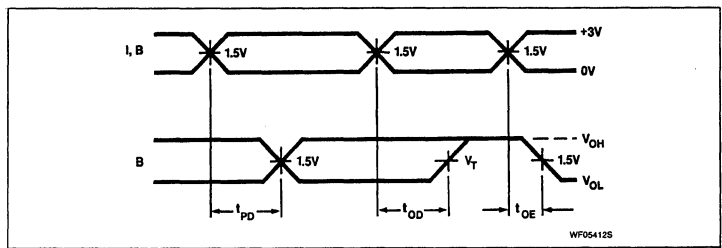
### TEST LOAD CIRCUITS



### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Propagation delay between input and output.
$t_{OD}$	Delay between input change and when output is off (Hi-Z or High).
$t_{OE}$	Delay between input change and when output reflects specified output level.

### TIMING DIAGRAM



# Field-Programmable Logic Array (22 × 42 × 10)

# PLUS173D

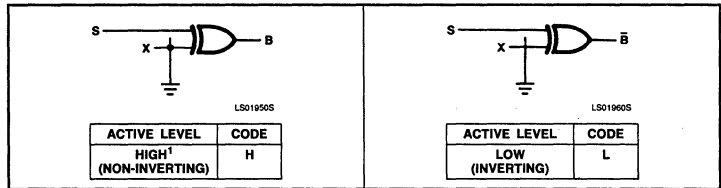
## LOGIC PROGRAMMING

PLUS173D logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

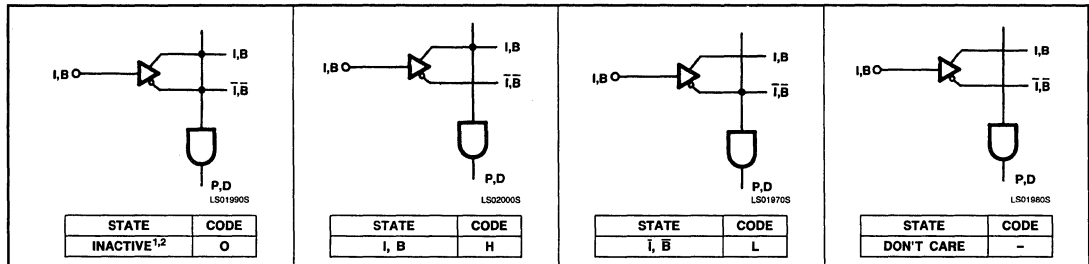
PLUS173D logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

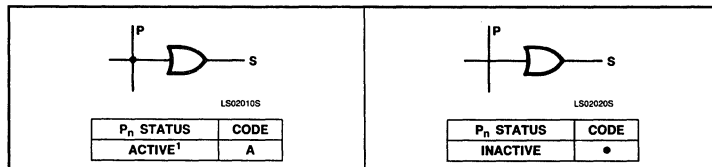
## OUTPUT POLARITY - (B)



## AND ARRAY - (I, B)



## OR ARRAY - (B)



## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

1. All outputs are at "H" polarity.
2. All P<sub>n</sub> terms are disabled.
3. All P<sub>n</sub> terms are active on all outputs.

### NOTES:

1. This is the initial unprogrammed state of all link pairs. It is normally associated with all unused (inactive) AND gates P<sub>n</sub>, D<sub>n</sub>.
2. Any gate P<sub>n</sub>, D<sub>n</sub> will be unconditionally inhibited if both the True and Complement of any input (I, B) are left intact.





## PLC473-60 Erasable and O.T.P. Programmable Logic Array (20 × 24 × 11)

**Application Specific Products**  
● Series 24

**Signetics Programmable Logic**  
*Product Specification*

### DESCRIPTION

The PLC473-60 is a two-level logic CMOS Erasable Programmable Logic Device (EPLD) consisting of 24 AND gates and 22 OR gates with EPROM cell connections for programming I/O polarity and direction. The Signetics state-of-the-art Floating-Gate CMOS process is used to produce UV erasable and One Time Programmable (O.T.P.) versions of the PLC473.

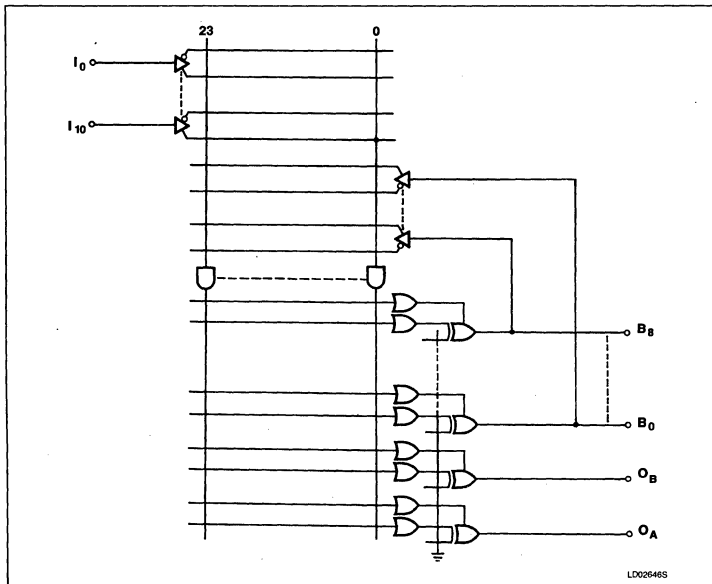
All AND gate inputs are linked to 11 dedicated input pins ( $I_0 - I_{10}$ ) and 9 bi-directional I/O pins ( $B_0 - B_8$ ). These bi-directional pins are controlled via the OR array. Employing the 2 dedicated outputs ( $O_A - O_B$ ) and the programmable I/O direction feature, the PLC473 can be configured with up to 20 inputs — and as many as 11 outputs.

The AND array input buffers provide both the True and Complement of the inputs ( $I_X$ ) and the bidirectional signals ( $B_X$ ) as programmable connections to

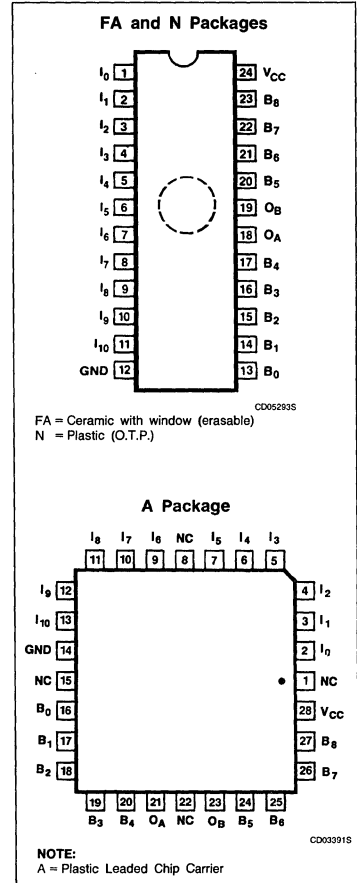
### FEATURES

- Electrically Programmable; UV erasable and One Time Programmable (O.T.P.) versions available
- 11 dedicated inputs
- 2 dedicated outputs
- 9 bidirectional I/O lines
- 24 product terms
- I/O direction decoded in OR array
- I/O propagation delay: 60ns (max.)
- Input loading:  $-10\mu\text{A}$  (max.)
- Power dissipation:
  - CMOS inputs: 53mA max at 15MHz
  - TTL inputs: 60mA max at 15MHz
- Output: 3-State condition decoded in OR array
- TTL and CMOS compatible

### FUNCTIONAL DIAGRAM



### PIN CONFIGURATIONS



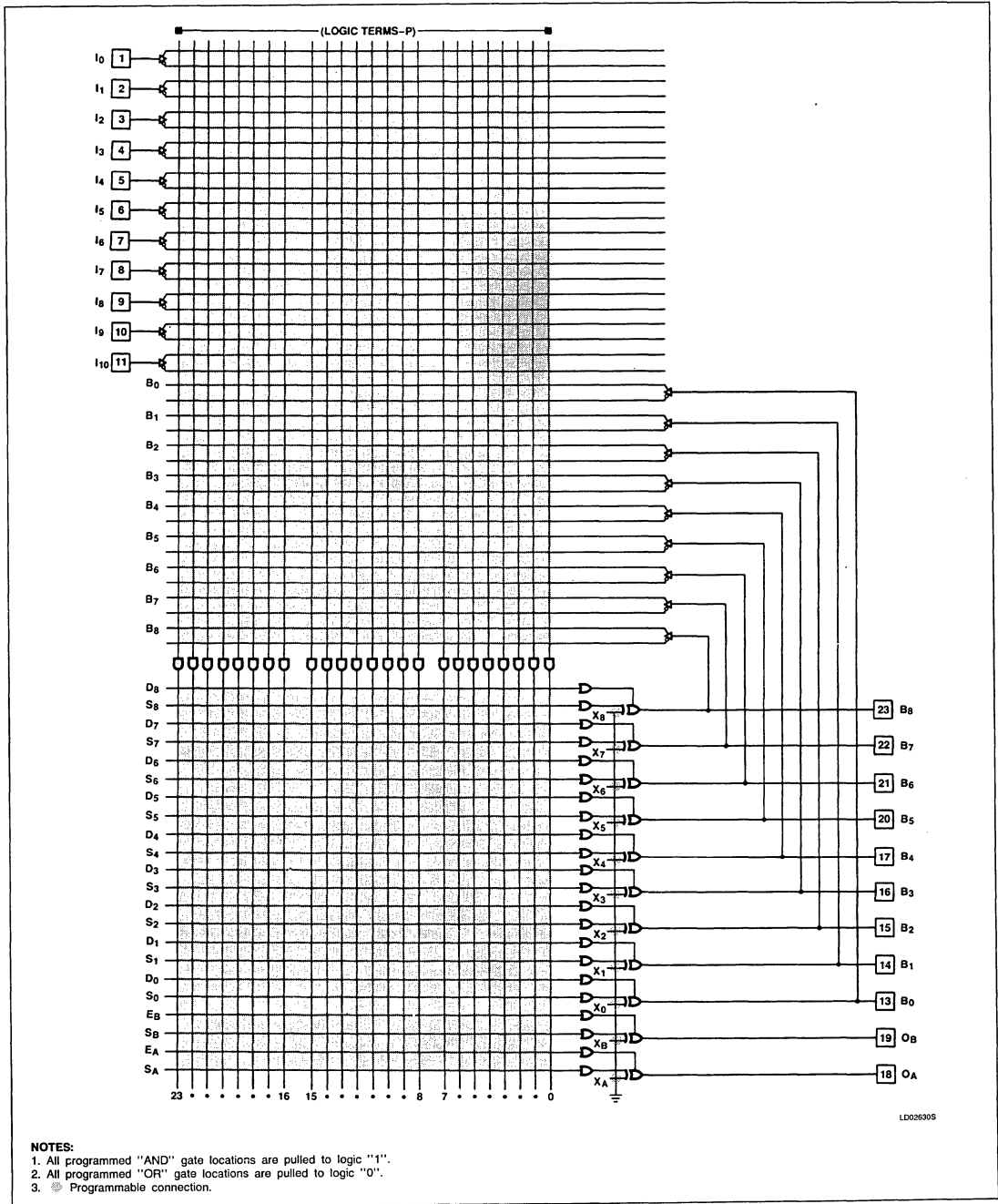
### APPLICATIONS

- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping
- Multiplexing

# Erasable and O.T.P. Programmable Logic Array (20 × 24 × 11)

PLC473-60

## FPLA LOGIC DIAGRAM



4

LD028305

# Erasable and O.T.P. Programmable Logic Array (20 × 24 × 11)

## PLC473-60

the AND gates. All 24 AND gates can then be optionally linked to all 22 OR gates (a feature known as Product Term sharing not found in PALs<sup>1</sup> or most macrocell architectures). The OR array drives 11 output buffers which can be programmed as active-High for AND-OR functions or active-Low for AND-NOR func-

tions. In addition, the I/O configuration of each bidirectional pin is individually controlled by a sum-of-products (AND-OR) function which may also contain any of the 24 AND gate outputs. This allows dynamic I/O configuration of all 9 bidirectional pins.

The PLC473-60 is field programmable using Floating-Gate Ultraviolet Erasable Cells. The UV erasable version is available in a ceramic DIP (300mil-wide) with a quartz window. One Time Programmable versions are available in plastic DIP and PLCC.

### ORDERING INFORMATION

DESCRIPTION	ORDER CODE
24-pin Ceramic DIP with Window (300mil-wide)	PLC473-60FA
24-pin Plastic DIP (300mil-wide)	PLC473-60N
28-pin Plastic Leaded Chip Carrier (PLCC)	PLC473-60A

### ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	V <sub>CC</sub> + 0.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage	V <sub>CC</sub> + 0.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30 to +30	mA
I <sub>OUT</sub>	Output currents	+100	mA
T <sub>A</sub>	Operating temperature range	0 to +70	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

#### NOTE:

- Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

### LOGIC FUNCTION

**TYPICAL PRODUCT TERM:**  
P<sub>n</sub> = A · B · C · D · . . .

**TYPICAL LOGIC FUNCTION:**  
AT OUTPUT POLARITY = H  
Z = P<sub>0</sub> + P<sub>1</sub> + P<sub>2</sub> . . .

**AT OUTPUT POLARITY = L**  
Z =  $\overline{P_0 + P_1 + P_2 + \dots}$   
Z = P<sub>0</sub> · P<sub>1</sub> · P<sub>2</sub> · . . .

#### NOTES:

- For each of the 11 outputs, either function Z (Active-High) or  $\bar{Z}$  (Active-Low) is available, but not both. The desired output polarity is programmed via the EX-OR gates.
- Z, A, B, C, etc. are user defined connections to fixed inputs (I), fixed output pins (O) and bidirectional pins (B).

# Erasable and O.T.P. Programmable Logic Array (20 × 24 × 11)

PLC473-60

## DC ELECTRICAL CHARACTERISTICS $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ , $4.75 \leq V_{CC} \leq 5.25\text{V}$

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
$V_{IL}$ $V_{IH}$	Low High	$V_{CC} = \text{Min}$ $V_{CC} = \text{Max}$	-0.3 2.0		0.8 $V_{CC} + 0.3$	V
<b>Output voltage<sup>2</sup></b>						
$V_{OL}$ $V_{OH}$	Low High	$V_{CC} = \text{Min}$ $I_{OL} = 8\text{mA}$ $I_{OH} = -3\text{mA}$	2.4		0.45	V
<b>Input current<sup>9</sup></b>						
$I_{IL}$ $I_{IH}$	Low High	$V_{IN} = \text{GND}$ $V_{IN} = V_{CC}$			-10 10	$\mu\text{A}$
<b>Output current</b>						
$I_{O(\text{OFF})}$ $I_{OS}$	Hi-Z state <sup>7</sup> Short circuit <sup>3, 6</sup>	$V_{OUT} = V_{CC}$ $V_{OUT} = \text{GND}$ $V_{OUT} = \text{GND}$	-15		10 -10 -70	$\mu\text{A}$ $\mu\text{A}$ mA
$I_{CC}$	$V_{CC}$ supply current (Active) <sup>4, 5, 8</sup>	No load, $f = 15\text{MHz}$ , $V_{CC} = \text{Max}$	CMOS inputs		53	mA
			TTL inputs		60	mA
<b>Capacitance</b>						
$C_{IN}$ $C_B$	Input I/O (bidirectional)	$V_{CC} = 5\text{V}$ $V_{IN} = 2.0\text{V}$ $V_B = 2.0\text{V}$			6 12	pF

**NOTES:**

- All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- CMOS inputs:  $V_{IL} = \text{GND}$ ,  $V_{IH} = V_{CC}$   
TTL inputs:  $V_{IL} = 0.45\text{V}$ ,  $V_{IH} = 2.4\text{V}$
- Measured with all inputs and outputs switching.
- Duration of short circuit should not exceed 1 second.
- Leakage values are a combination of input and output leakage.
- Refer to Figure 1 for  $I_{CC}$  vs frequency specifications (worst case).
- Pin 1 ( $V_{PP}$ ) has a leakage current of  $\pm 100\mu\text{A}$ .

## AC ELECTRICAL CHARACTERISTICS $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ , $4.75 \leq V_{CC} \leq 5.25\text{V}$ , $R_1 = 470\Omega$ , $R_2 = 1\text{k}\Omega$

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS		UNIT
					Min	Max	
$t_{PD}$	Propagation delay	Output $\pm$	Input $\pm$	$C_L = 30\text{pF}$		60	ns
$t_{OE}$	Output enable	Output -	Input $\pm$	$C_L = 30\text{pF}$		60	ns
$t_{OD}$	Output disable <sup>1</sup>	Output +	Input $\pm$	$C_L = 5\text{pF}$		60	ns

**NOTE:**

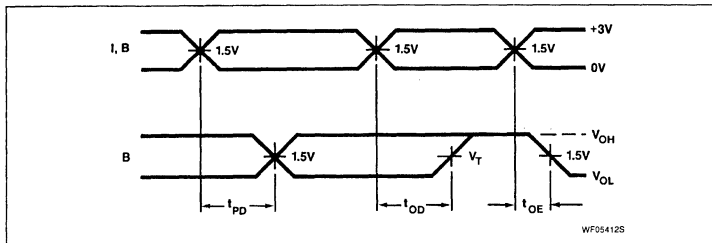
- Measured at  $V_T = V_{OL} + 0.5\text{V}$ .

4

# Erasable and O.T.P. Programmable Logic Array (20 X 24 X 11)

PLC473-60

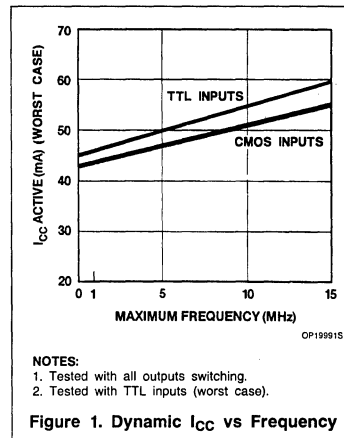
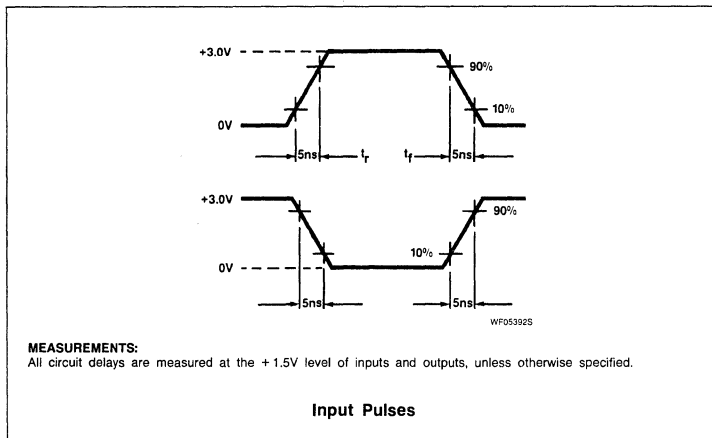
## TIMING DIAGRAM



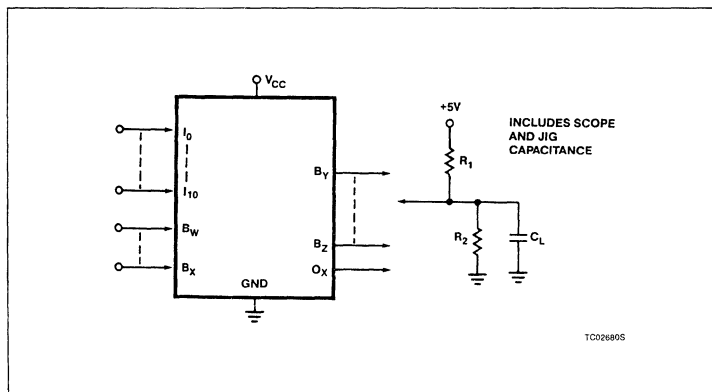
## TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Propagation delay between input and output.
$t_{OD}$	Delay between input change and when output is off (Hi-Z or High).
$t_{OE}$	Delay between input change and when output reflects specified output level.

## VOLTAGE WAVEFORMS



## TEST LOAD CIRCUITS



## LOGIC PROGRAMMING

PLC473-60 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

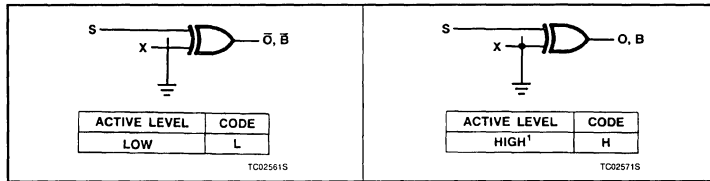
PLC473-60 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

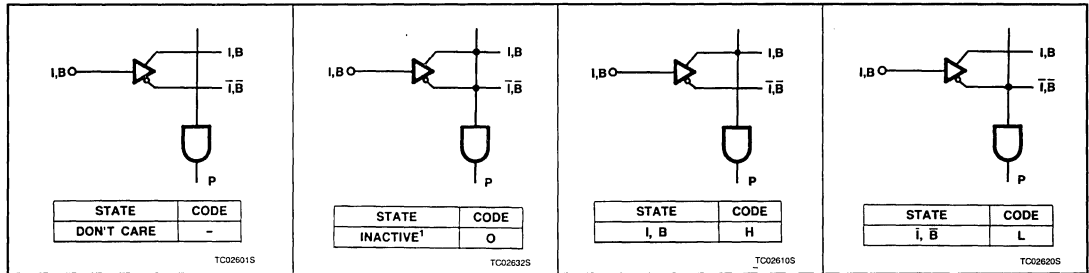
# Erasable and O.T.P. Programmable Logic Array (20 × 24 × 11)

PLC473-60

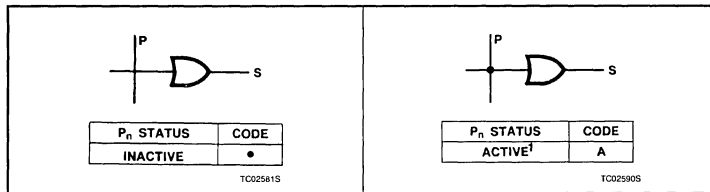
## OUTPUT POLARITY - (O, B)



## "AND" ARRAY - (I, B)



## "OR" ARRAY - (O, B)



## VIRGIN STATE

A factory shipped virgin device is configured such that:

1. All outputs are at "H" polarity.
2. All P<sub>n</sub> terms are inactive in the AND array.
3. All P<sub>n</sub> terms are active in the OR array.

### NOTES:

1. This is the initial unprogrammed state of all link pairs.
2. Any Product Term (P<sub>n</sub>) will always be False (logic low) if at least one of its (I, B) link pairs is unprogrammed as shown.

## ERASURE CHARACTERISTICS (FOR FA PACKAGE ONLY)

The PLC473 is erased by exposure to ultraviolet light. The recommended erasure procedure is exposure to short-wave ultraviolet light which has a wavelength of 2537 Angstroms (Å). The integrated dose (i.e., UV intensity × exposure time) for erasure should be a minimum of 15Wsec/cm<sup>2</sup>.

The erasure time with this dosage is approximately 15 to 20 minutes using an ultraviolet lamp with 12,000μW/cm<sup>2</sup> power rating.

The PLC473 should be placed within one inch of the lamp tubes during erasure. The maximum integrated dose a PLC473 can be exposed to without damage is 7258Wsec/cm<sup>2</sup> (1week @ 12,000μW/cm<sup>2</sup>).

Exposure of this CMOS EPROM to high-intensity UV light for longer periods may cause permanent damage. Some erasure may occur with exposure to light sources having wavelengths shorter than 4,000Å such as sunlight or fluorescent light. For maximum system reliability, precautions should be taken by placing opaque labels over the quartz window when used in these environments.

4



## PLHS473

### Field-Programmable Logic Array (20 × 24 × 11)

Signetics Programmable Logic  
Product Specification

#### Application Specific Products • Series 24

#### DESCRIPTION

The PLHS473 is a two level logic device consisting of 24 AND gates and 22 OR gates with fusible link connections for programming I/O polarity and direction. The Signetics state of the art Oxide-Isolated Bipolar process is used to produce performance not yet achieved in devices of this complexity.

All AND gates are linked to 11 input pins, 9 bidirectional I/O pins, and 2 dedicated output pins. The bidirectional pins are controlled via the OR array. Using these features, the PLHS473 can be configured with up to 20 inputs and as many as 11 outputs.

The AND array input buffers provide both the True and Complement of the inputs ( $I_x$ ) and the bidirectional signals ( $B_x$ ) as programmable connections to the AND gates. All 24 AND gates can then be optionally linked to all 22 OR gates (a feature known as Product Term sharing not found in PAL<sup>®</sup> device architectures or most macrocell architectures). The OR array drives 11 output buffers which can be programmed as active-High for AND-OR functions or active-Low for AND-NOR functions. In addition, the I/O configuration of each bidirectional pin is individually controlled by a sum-of-products (AND-OR) function which may also contain any of the 24 AND gate outputs. This allows dynamic

I/O configuration of all 9 bidirectional pins.

The PLHS473 contains two new features of significance. A code verification lock has been incorporated to improve user security. The addition of three test columns and one test row enables the user to test the device in an unprogrammed state.

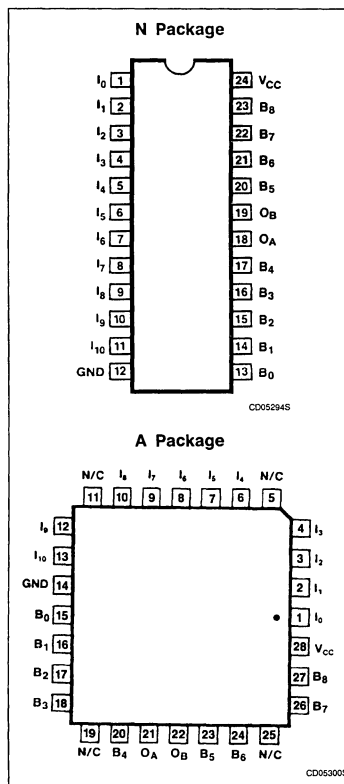
The PLHS473 is field programmable using Vertical Avalanche Migration Programmed (VAMP<sup>™</sup>) fuses to program the cells. This enables the generation of custom logic patterns using standard programming equipment.

Order codes are listed in the Ordering Information Table.

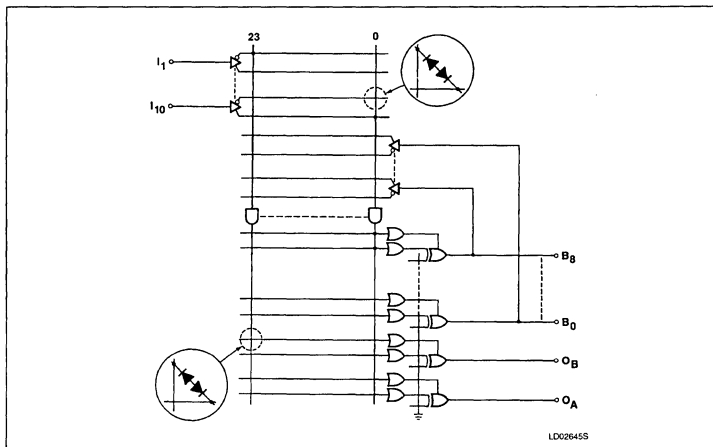
#### FEATURES

- Field-Programmable
- 11 dedicated inputs
- 2 dedicated outputs
- 9 bidirectional I/O lines
- 24 product terms
- 22 OR gates
- I/O direction decoded in OR array
- Output Enable decoded in OR array
- Security fuse
- I/O propagation delay: 22ns (max.)

#### PIN CONFIGURATIONS



#### FUNCTIONAL DIAGRAM



- Input loading: -100 $\mu$ A (max.)
- Power dissipation: 700mW (typ.)
- Security fuse
- Testable in unprogrammed state
- Programmable as 3-State or Open-Collector outputs
- TTL compatible
- Programmable output polarity

#### APPLICATIONS

- Random logic
- Code converters
- Fault detectors
- Function generators
- Address mapping
- Multiplexing

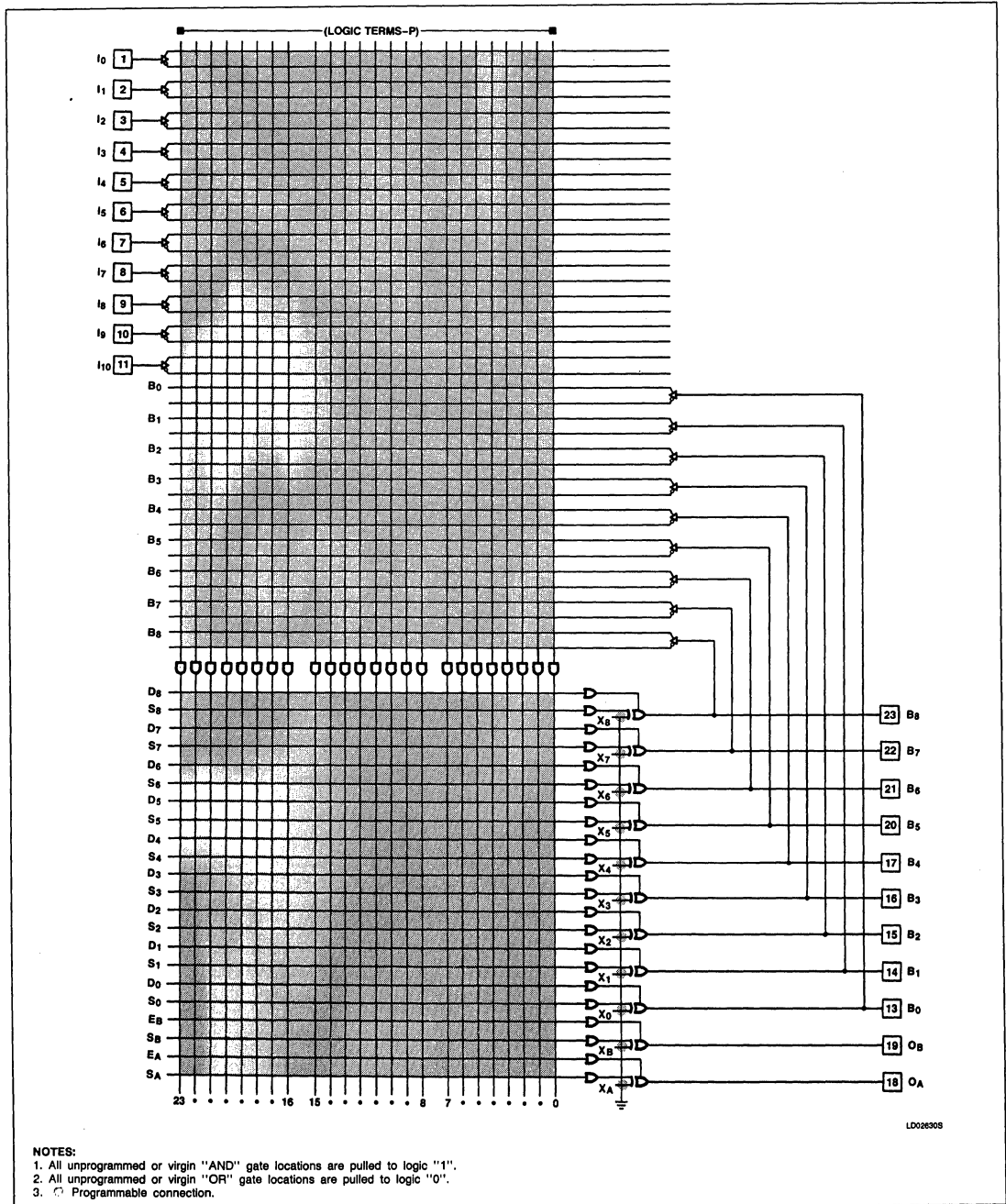
PAL is a trademark of Monolithic Memories, Inc., a wholly owned subsidiary of Advanced Micro Devices, Inc.



# Field-Programmable Logic Array (20 × 24 × 11)

PLHS473

## FPLA LOGIC DIAGRAM



## Field-Programmable Logic Array (20 × 24 × 11)

PLHS473

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
24-pin Plastic DIP 300mil-wide	PLHS473N
28-pin Plastic Leaded Chip Carrier	PLHS473A

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage	+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30 to +30	mA
I <sub>OUT</sub>	Output currents	+100	mA
T <sub>A</sub>	Operating free-air temperature range	0 to +75	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other conditions above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75 ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min	2.0		0.8	V
V <sub>IH</sub>	High	V <sub>CC</sub> = Max				
V <sub>IC</sub>	Clamp <sup>3</sup>	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA				
<b>Output voltage<sup>3</sup></b>						
V <sub>OL</sub>	Low <sup>4</sup>	V <sub>CC</sub> = Min	2.4		0.5	V
V <sub>OH</sub>	High <sup>5</sup>	I <sub>OL</sub> = 15mA I <sub>OH</sub> = -2mA				
<b>Input current</b>						
I <sub>IL</sub>	Low	V <sub>CC</sub> = Max			-100	μA
I <sub>IH</sub>	High	V <sub>IN</sub> = 0.45V V <sub>IN</sub> = 5.5V				
<b>Output current</b>						
I <sub>O(OFF)</sub>	Hi-Z state <sup>9</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V	-15		40	μA
I <sub>OS</sub>	Short circuit <sup>3, 5, 6</sup>	V <sub>OUT</sub> = 0.45V				
		V <sub>OUT</sub> = 0.5V				
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>7</sup>	V <sub>CC</sub> = Max		140	155	mA
<b>Capacitance</b>						
I <sub>IN</sub>	Input	V <sub>CC</sub> = 5V		8		pF
C <sub>B</sub>	I/O	V <sub>IN</sub> = 2.0V V <sub>B</sub> = 2.0V				

Notes on the following page.

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

## LOGIC FUNCTION

<p><b>TYPICAL PRODUCT TERM:</b> P<sub>n</sub> = A · B · C · D · . . .</p> <p><b>TYPICAL LOGIC FUNCTION:</b> AT OUTPUT POLARITY = H Z = P<sub>0</sub> + P<sub>1</sub> + P<sub>2</sub> . . .</p> <p>AT OUTPUT POLARITY = L Z = P<sub>0</sub> + P<sub>1</sub> + P<sub>2</sub> + . . . Z = P<sub>0</sub> · P<sub>1</sub> · P<sub>2</sub> . . .</p> <p><b>NOTES:</b></p> <p>1. For each of the 11 outputs, either function Z (Active-High) or Z̄ (Active-Low) is available, but not both. The desired output polarity is programmed via the Ex-OR gates.</p> <p>2. Z, A, B, C, etc. are user defined connections to fixed inputs (I), fixed output pins (O) and bidirectional pins (B).</p>
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4

# Field-Programmable Logic Array (20 × 24 × 11)

PLHS473

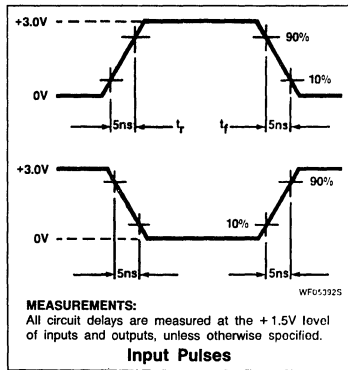
## AC ELECTRICAL CHARACTERISTICS $0^{\circ}\text{C} \leq T_A \leq +75^{\circ}\text{C}$ , $4.75 \leq V_{CC} \leq 5.25\text{V}$ , $R_1 = 470\Omega$ , $R_2 = 1\text{k}\Omega$

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min	Typ	Max	
$t_{PD}$	Propagation delay	Output $\pm$	Input $\pm$	$C_L = 30\text{pF}$		15	22	ns
$t_{OE}$	Output enable	Output -	Input $\pm$	$C_L = 30\text{pF}$		15	22	ns
$t_{OD}$	Output disable <sup>8</sup>	Output +	Input $\pm$	$C_L = 5\text{pF}$		15	22	ns

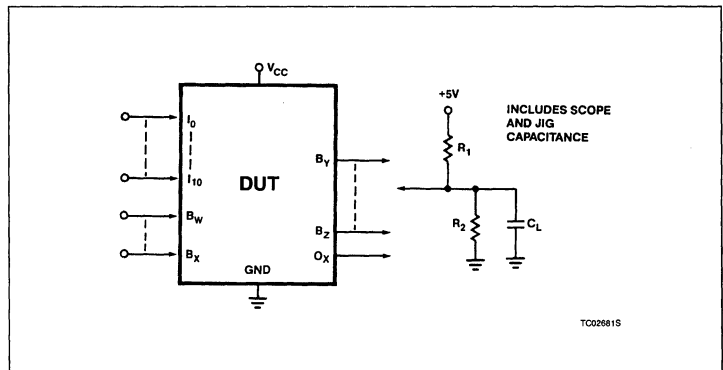
**NOTES:**

1. All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
2. All voltage values are with respect to network ground terminal.
3. Test one at a time.
4. Measured with inputs 0 - 4 = 0V, inputs 5, 7 = 4.5V, and inputs 6, 8 - 10 = 10V.
5. Same conditions as Note 5 except input 8 = 4.5V.
6. Duration of short circuit should not exceed 1 second.
7.  $I_{CC}$  is measured with all inputs and bidirectional pins at 4.5V. Part in Virgin State.
8. Measured at  $V_T = V_{OL} + 0.5\text{V}$ .
9. Leakage values are a combination of input and output leakage.

### VOLTAGE WAVEFORMS



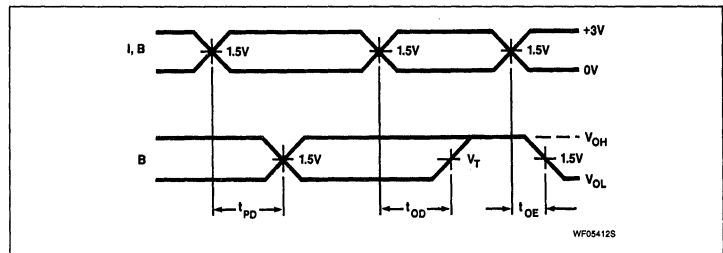
### TEST LOAD CIRCUITS



### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD}$	Propagation delay between input and output.
$t_{OD}$	Delay between input change and when output is off (Hi-Z or High).
$t_{OE}$	Delay between input change and when output reflects specified output level.

### TIMING DIAGRAM



# Field-Programmable Logic Array (20 × 24 × 11)

PLHS473

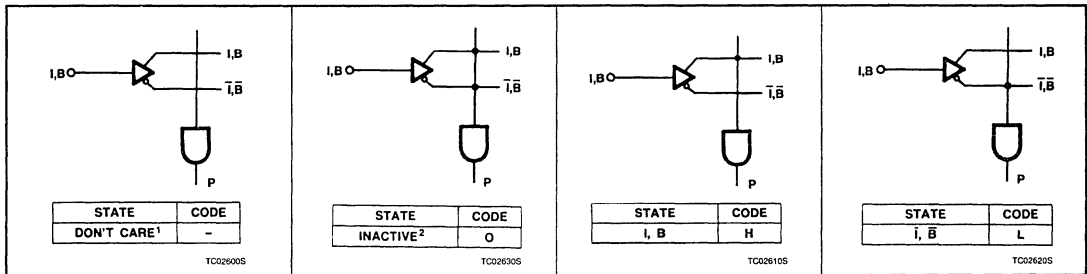
## LOGIC PROGRAMMING

PLHS473 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

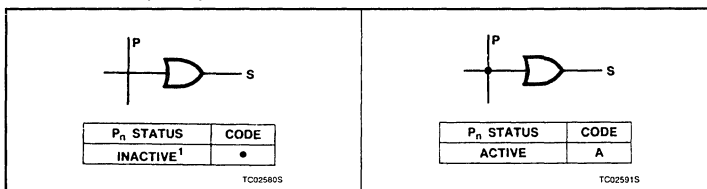
PLHS473 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

### 'AND' ARRAY - (I, B)



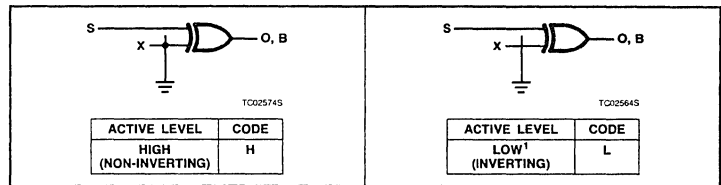
### OR ARRAY - (O, B)



**NOTES:**

1. This is the initial unprogrammed state of all links. All unused P<sub>n</sub> and D<sub>n</sub> terms must be programmed as INACTIVE.
2. Any gate P<sub>n</sub> will be unconditionally inhibited if the True and Complement of either input (I or B) are both programmed for a connection.

### OUTPUT POLARITY - (O, B)



4

### VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

1. All outputs are at "L" polarity.
2. All P<sub>n</sub> terms are enabled in the AND array. (Don't Cares)
3. All P<sub>n</sub> terms are inactive in the OR array.



# PLS100/PLS101 Field-Programmable Logic Array (16 × 48 × 8)

Signetics Programmable Logic  
Product Specification

## Application Specific Products • Series 28

### DESCRIPTION

The PLS100 (3-state) and PLS101 (Open-Collector) are bipolar, fuse Programmable Logic Arrays (FPLAs). Each device utilizes the standard AND/OR/Invert architecture to directly implement custom sum of product logic equations.

Each device consists of 16 dedicated inputs and 8 dedicated outputs. Each output is capable of being actively controlled by any or all of the 48 product terms. The True, Complement, or Don't Care condition of each of the 16 inputs can be ANDed together to comprise one P-term. All 48 P-terms can be selectively ORed to each output.

The PLS100 and PLS101 are fully TTL compatible, and chip enable control for expansion of input variables and output inhibit. They feature either Open-Collector or 3-state outputs for ease of expansion of product terms and application in bus-organized systems.

Order codes are listed in the Ordering Information Table.

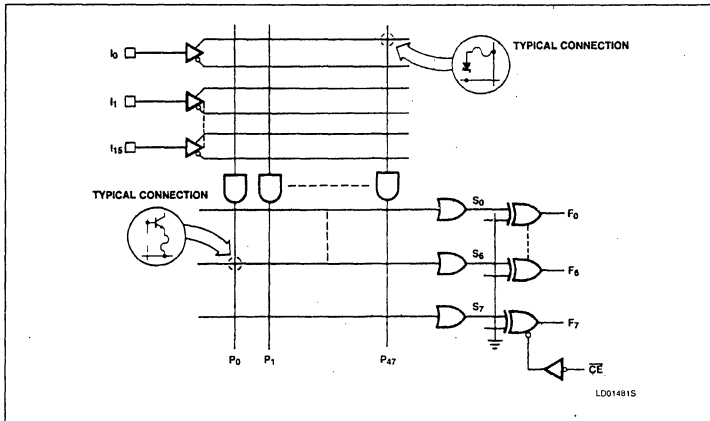
### FEATURES

- Field-Programmable (Ni-Cr link)
- Input variables: 16
- Output functions: 8
- Product terms: 48
- I/O propagation delay: 50ns (max.)
- Power dissipation: 600mW (typ.)
- Input loading: -100µA (max.)
- Chip Enable input
- Output option:
  - PLS100: 3-State
  - PLS101: Open-Collector
- Output disable function:
  - 3-State: Hi-Z
  - Open-Collector: High

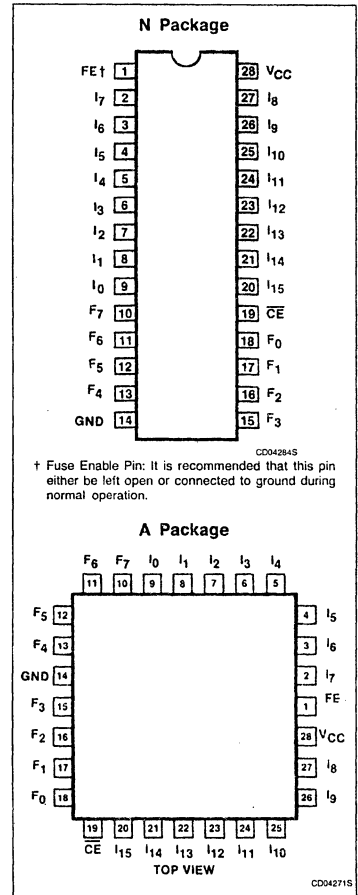
### APPLICATIONS

- CRT display systems
- Code conversion
- Peripheral controllers
- Function generators
- Look-up and decision tables
- Microprogramming
- Address mapping
- Character generators
- Data security encoders
- Fault detectors
- Frequency synthesizers
- 16-bit to 8-bit bus interface
- Random logic replacement

### FUNCTIONAL DIAGRAM



### PIN CONFIGURATIONS

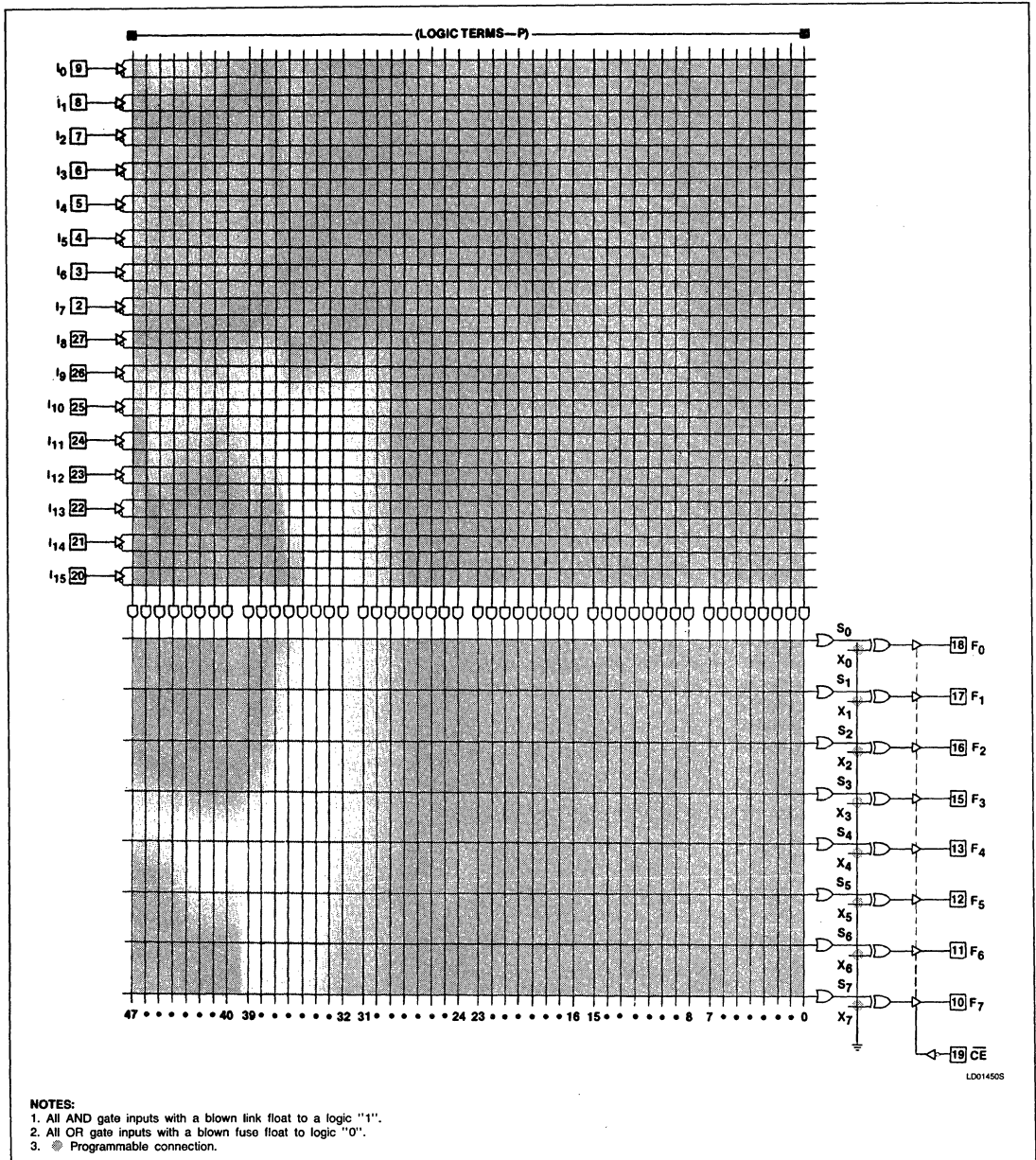


† Fuse Enable Pin: It is recommended that this pin either be left open or connected to ground during normal operation.

# Field-Programmable Logic Array (16 × 48 × 8)

PLS100/PLS101

## FPLA LOGIC DIAGRAM



# Field-Programmable Logic Array (16 × 48 × 8)

PLS100/PLS101

## ORDERING INFORMATION

DESCRIPTION	TRI-STATE	OPEN-COLLECTOR
28-pin Plastic DIP 600mil-wide	PLS100N	PLS101N
28-pin Plastic Leaded Chip Carrier	PLS100A	PLS101A

The PLS100 device is also processed to military requirements for operation over the military temperature range. For specifications and ordering information consult the Signetics Military Data Book.

## ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	+5.5	V <sub>DC</sub>
V <sub>O</sub>	Output voltage	+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input current	±30	mA
I <sub>OUT</sub>	Output current	+100	mA
T <sub>A</sub>	Operating temperature range	0 to +75	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

### NOTE:

- Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other conditions above those indicated in the operational and programming specification of the device is not implied.

## DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75V ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IH</sub>	High	V <sub>CC</sub> = Max	2			V
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min			0.8	V
V <sub>IC</sub>	Clamp <sup>2, 3</sup>	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA		-0.8	-1.2	V
<b>Output voltage<sup>2</sup></b>						
V <sub>OH</sub>	High (PLS100) <sup>4</sup>	V <sub>CC</sub> = Min	2.4			V
V <sub>OL</sub>	Low <sup>5</sup>	I <sub>OH</sub> = -2mA I <sub>OL</sub> = 9.6mA		0.35	0.45	V
<b>Input current</b>						
I <sub>IH</sub>	High	V <sub>IN</sub> = 5.5V		< 1	25	μA
I <sub>IL</sub>	Low	V <sub>IN</sub> = 0.45V		-10	-100	μA
<b>Output current</b>						
I <sub>O(OFF)</sub>	Hi-Z state (PLS100)	$\overline{CE}$ = High, V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V V <sub>OUT</sub> = 0.45V		1 -1	40 -40	μA
I <sub>OS</sub>	Short circuit (PLS100) <sup>3, 6</sup>	$\overline{CE}$ = Low, V <sub>OUT</sub> = 0V	-15		-70	mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>7</sup>	V <sub>CC</sub> = Max		120	170	mA
<b>Capacitance</b>						
C <sub>IN</sub>	Input	$\overline{CE}$ = High, V <sub>CC</sub> = 5.0V V <sub>IN</sub> = 2.0V		8		pF
C <sub>OUT</sub>	Output	V <sub>OUT</sub> = 2.0V		17		pF

Notes on following page.



# Field-Programmable Logic Array (16 × 48 × 8)

## PLS100/PLS101

### AC ELECTRICAL CHARACTERISTICS $R_1 = 470\Omega$ , $R_2 = 1k\Omega$ , $C_L = 30pF$ , $0^\circ C \leq T_A \leq +75^\circ C$ , $4.75V \leq V_{CC} \leq 5.25V$

SYMBOL	PARAMETER	TO	FROM	LIMITS			UNIT
				Min	Typ <sup>1</sup>	Max	
<b>Propagation delay</b>							
$t_{PD}$	Input	Output	Input		35	50	ns
$t_{CE}$	Chip enable	Output	Chip enable		15	30	ns
<b>Disable time</b>							
$t_{CD}$	Chip disable	Output	Chip enable		15	30	ns

#### NOTES:

1. All values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
2. All voltage values are with respect to network ground terminal.
3. Test one pin at a time.
4. Measured with  $V_{IL}$  applied to  $\overline{CE}$  and a logic high stored.
5. Measured with a programmed logic condition for which the output test is at a low logic level. Output sink current is applied through a resistor to  $V_{CC}$ .
6. Duration of short circuit should not exceed 1 second.
7.  $I_{CC}$  is measured with the chip enable input grounded, all other inputs at 4.5V and the outputs open.

# Field-Programmable Logic Array (16 × 48 × 8)

PLS100/PLS101

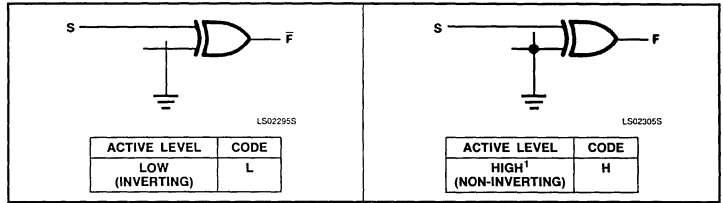
## LOGIC PROGRAMMING

PLS100/PLS101 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

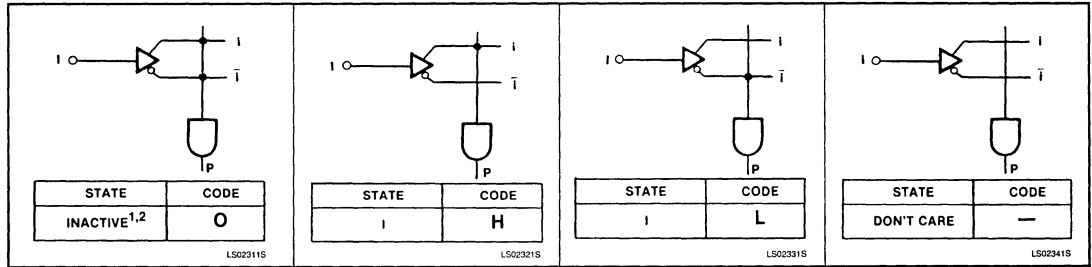
PLS100/PLS101 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

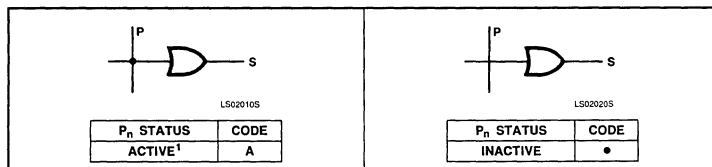
## OUTPUT POLARITY - (F)



## "AND" ARRAY - (I)



## "OR" ARRAY - (F)



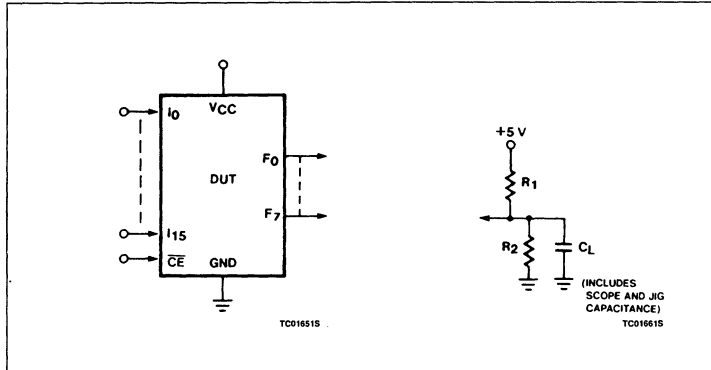
### NOTES:

- This is the initial unprogrammed state of all link pairs. It is normally associated with all unused (inactive) AND gates P<sub>n</sub>.
- Any gate P<sub>n</sub> will be unconditionally inhibited if any one of its (I) link pairs is left intact.

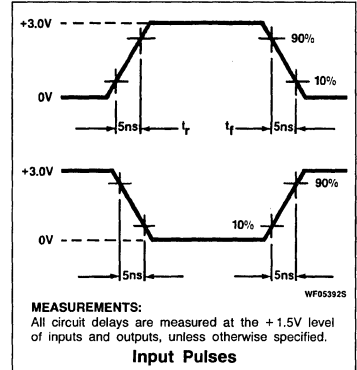
# Field-Programmable Logic Array (16 × 48 × 8)

PLS100/PLS101

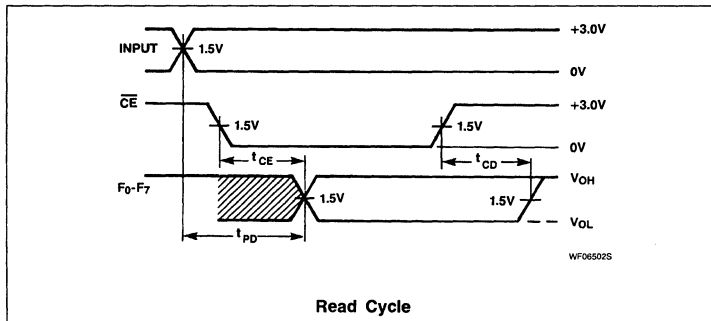
### TEST LOAD CIRCUITS



### VOLTAGE WAVEFORMS



### TIMING DIAGRAM



### TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{CE}$	Delay between beginning of Chip Enable low (with Input valid) and when Data Output becomes valid.
$t_{CD}$	Delay between when Chip Enable becomes High and Data Output is in off state (Hi-Z or High).
$t_{PD}$	Delay between beginning of valid Input (with Chip Enable Low) and when Data Output becomes valid.

### VIRGIN STATE

The PLS100/101 virgin devices are factory shipped in an unprogrammed state, with all fuses intact, such that:

1. All  $P_n$  terms are disabled (inactive), in the AND array.
2. All  $P_n$  terms are active in the OR array.
3. All outputs are active-High.



# PLS103

## Field-Programmable Gate Array (16 × 9 × 9)

Signetics Programmable Logic  
Product Specification

Application Specific Products  
• Series 28

### DESCRIPTION

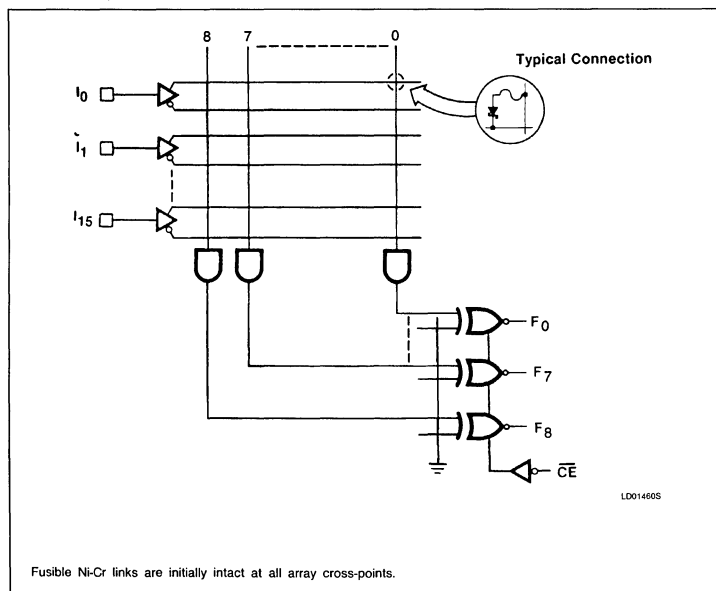
The PLS103 is a bipolar, fuse Programmable Gate Array. The device consists of nine AND/NAND gates which share 16 common inputs. The type of gate is selected by programming the output as active-High (H) or active-Low (L). Each of the 16 inputs  $I_0$ – $I_{15}$  can be programmed to provide the True (H), Complement (L), or Don't Care (—) state to each of the nine AND/NAND gates. OR/NOR logic functions can also be implemented by complementing the inputs and outputs via on-chip inverting buffers.

The device is field programmable, which means that custom patterns are immediately available.

The PLS103 includes chip-enable control for output strobing and inhibit. It features 3-State outputs for ease of expansion of input variables and application in bus-organized systems.

Order codes are listed in the Ordering Information Table.

### FUNCTIONAL DIAGRAM



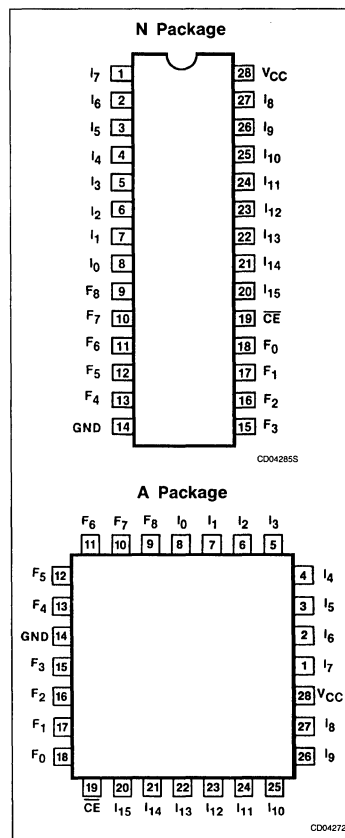
### FEATURES

- Field-Programmable (Ni-Cr link)
- 16 input variables
- 9 output functions
- Chip Enable input
- I/O propagation delay: 35ns (max.)
- Power dissipation: 600mW (typ.)
- Input loading:  $-100\mu\text{A}$  (max.)
- 3-State outputs
- Output disable function: Hi-Z
- Fully TTL compatible

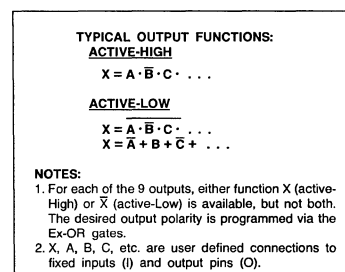
### APPLICATIONS

- Random logic
- Address decoders
- Code detectors
- Peripheral selectors
- Fault monitors
- Machine state decoders

### PIN CONFIGURATIONS



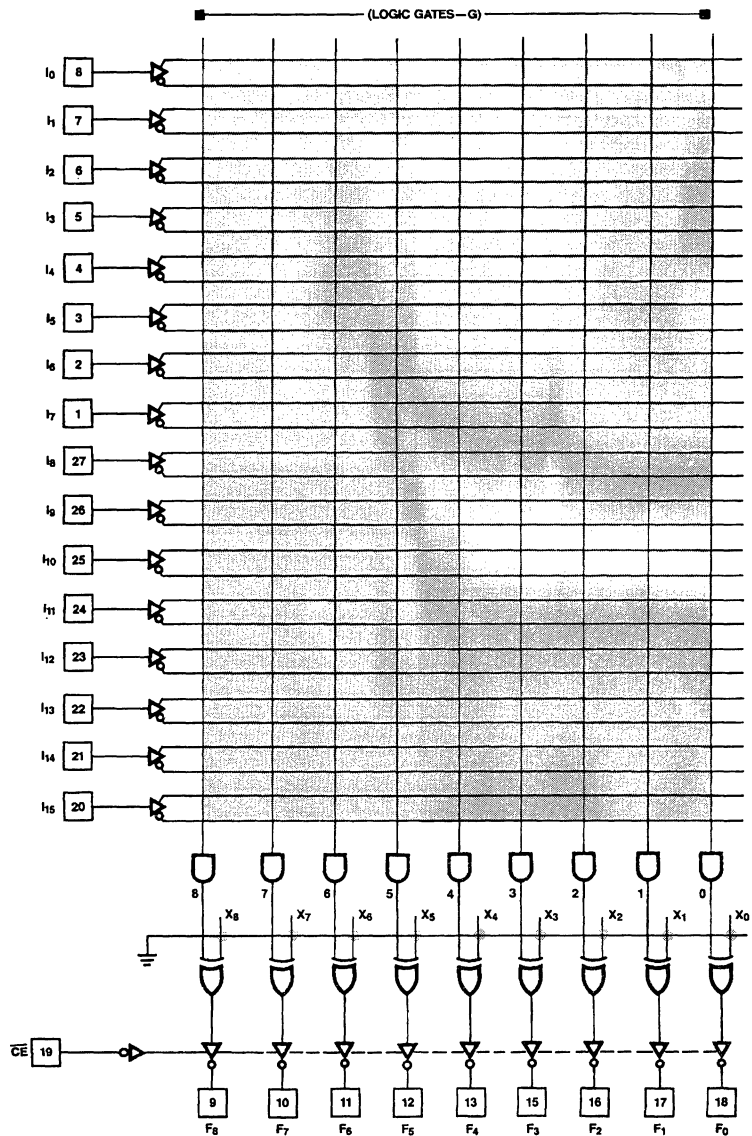
### LOGIC FUNCTION



# Field-Programmable Gate Array (16 × 9 × 9)

PLS103

## FPGA LOGIC DIAGRAM



- NOTES:**
1. All gate inputs when a blown link float to a logic "1".
  2. ⊗ Programmable connection.

LD014715

4

# Field-Programmable Gate Array (16 × 9 × 9)

PLS103

**ORDERING INFORMATION**

DESCRIPTION	ORDER CODE
28-pin Plastic DIP 600mil-wide	PLS103N
28-pin Plastic Leaded Chip Carrier	PLS103A

**THERMAL RATINGS**

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

**ABSOLUTE MAXIMUM RATINGS<sup>1</sup>**

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	+5.5	V <sub>DC</sub>
V <sub>O</sub>	Output voltage	+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input current	±30	mA
I <sub>OUT</sub>	Output current	+100	mA
T <sub>A</sub>	Operating temperature range	0 to +75	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

**NOTE:**

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other conditions above those indicated in the operational and programming specification of the device is not implied.

**DC ELECTRICAL CHARACTERISTICS** 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75V ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>2</sup>	Max	
<b>Input voltage<sup>1</sup></b>						
V <sub>IH</sub>	High	V <sub>CC</sub> = Max	2.0			V
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min			0.8	V
V <sub>IC</sub>	Clamp <sup>3</sup>	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA		-0.8	-1.2	V
<b>Output voltage<sup>1</sup></b>						
V <sub>OH</sub>	High <sup>5</sup>	V <sub>CC</sub> = Min	2.4			V
V <sub>OL</sub>	Low <sup>4</sup>	I <sub>OH</sub> = -2mA I <sub>OL</sub> = 9.6mA		0.35	0.45	V
<b>Input current</b>						
I <sub>IH</sub>	High	V <sub>IN</sub> = 5.5V		< 1	25	μA
I <sub>IL</sub>	Low	V <sub>IN</sub> = 0.45V		-10	-100	μA
<b>Output current</b>						
I <sub>O(OFF)</sub>	Hi-Z state	$\overline{CE}$ = High, V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V		1	40	μA
I <sub>OS</sub>	Short circuit <sup>3,6</sup>	V <sub>OUT</sub> = 0.45V $\overline{CE}$ = Low, V <sub>OUT</sub> = 0V	-15	-1	-40	mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>7</sup>	V <sub>CC</sub> = Max		120	170	mA
<b>Capacitance</b>						
C <sub>IN</sub>	Input	V <sub>CC</sub> = 5.0V V <sub>IN</sub> = 2.0V		8		pF
C <sub>OUT</sub>	Output	V <sub>OUT</sub> = 2.0V		15		pF

Notes on following page.

# Field-Programmable Gate Array (16 × 9 × 9)

PLS103

**AC ELECTRICAL CHARACTERISTICS**  $R_1 = 470\Omega$ ,  $R_2 = 1k\Omega$ ,  $C_L = 30pF$ ,  $0^\circ C \leq T_A \leq +75^\circ C$ ,  $4.75V \leq V_{CC} \leq 5.25V$ 

SYMBOL	PARAMETER	TO	FROM	LIMITS			UNIT
				Min	Typ <sup>2</sup>	Max	
<b>Propagation delay</b>							
$t_{PD}$	Input	Output	Input		20	35	ns
$t_{CE}$	Chip enable	Output	Chip enable		15	30	ns
<b>Disable time</b>							
$t_{CD}$	Chip disable	Output	Chip enable		15	30	ns

**NOTES:**

1. All voltage values are with respect to network ground terminal.
2. All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
3. Test one pin at a time.
4. Measure with a programmed logic condition for which the output under test is at a low logic level. Output sink current is supplied through a resistor to  $V_{CC}$ .
5. Measured with  $V_{IL}$  applied to  $\overline{CE}$  and a logic high at the output.
6. Duration of short circuit should not exceed 1 second.
7.  $I_{CC}$  is measured with the outputs open.

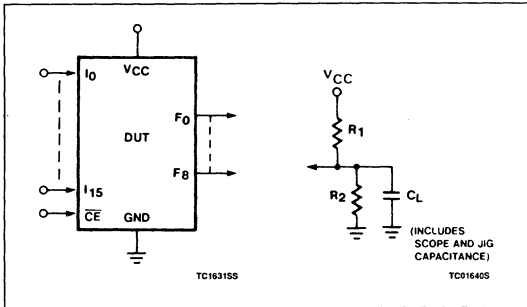
4



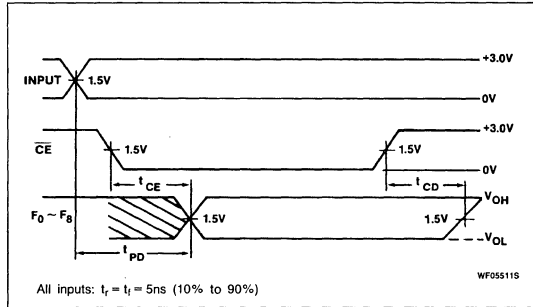
# Field-Programmable Gate Array (16 × 9 × 9)

PLS103

## TEST LOAD CIRCUITS



## VOLTAGE WAVEFORMS



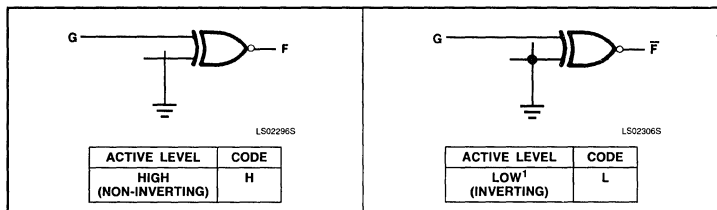
## LOGIC PROGRAMMING

In a virgin device all Ni-Cr links are intact. PLS013 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

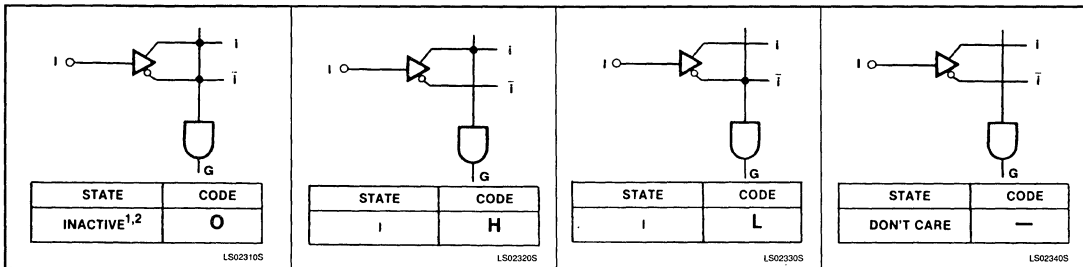
PLS013 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

## OUTPUT POLARITY - (F)



## 'AND' ARRAY - (I), (P)



### NOTES:

- This is the initial unprogrammed state of all links.
- Any gate  $G_n$  will be unconditionally inhibited if both the True and Complement fuses of any input (I) are left intact.

## VIRGIN STATE

The PLS103 virgin device is factory shipped in an unprogrammed state, with all fuses intact, such that:

- All  $P_n$  terms are disabled (inactive).
- All  $P_n$  terms are active on all outputs.
- All outputs are active-Low.

# Field-Programmable Gate Array (16 × 9 × 9)

PLS103

## FPGA PROGRAM TABLE

CUSTOMER NAME _____ PURCHASE ORDER # _____ SIGNETICS DEVICE # _____ TOTAL NUMBER OF PARTS _____ PROGRAM TABLE # _____	THIS PORTION TO BE COMPLETED BY SIGNETICS CF (XXXX) _____ CUSTOMER SYMBOLIZED PART # _____ DATE RECEIVED _____ COMMENTS _____
---	---

- F<sub>0</sub> (18) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>1</sub> (17) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>2</sub> (16) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>3</sub> (15) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>4</sub> (13) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>5</sub> (12) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>6</sub> (11) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>7</sub> (10) \_\_\_\_\_ = \_\_\_\_\_
- F<sub>8</sub> (9) \_\_\_\_\_ = \_\_\_\_\_

4

GATE	INPUT															
	I <sub>15</sub>	I <sub>14</sub>	I <sub>13</sub>	I <sub>12</sub>	I <sub>11</sub>	I <sub>10</sub>	I <sub>9</sub>	I <sub>8</sub>	I <sub>7</sub>	I <sub>6</sub>	I <sub>5</sub>	I <sub>4</sub>	I <sub>3</sub>	I <sub>2</sub>	I <sub>1</sub>	I <sub>0</sub>
F <sub>0</sub>																
F <sub>1</sub>																
F <sub>2</sub>																
F <sub>3</sub>																
F <sub>4</sub>																
F <sub>5</sub>																
F <sub>6</sub>																
F <sub>7</sub>																
F <sub>8</sub>																
PIN NO.	20	21	22	23	24	25	26	27	1	2	3	4	5	6	7	8
VARIABLE NAME																

<b>NOTES:</b> 1. The FPGA is shipped with all links intact. Thus a background of entries corresponding to states of virgin links exists in the table, shown BLANK for clarity. 2. Unused inputs are normally programmed Don't Care (—). 3. Unused Gates can be left blank.	<b>PROGRAM TABLE ENTRIES</b>	<b>AND</b> <table border="1" style="margin: auto; border-collapse: collapse;"> <tr><td>INACTIVE</td><td>0</td></tr> <tr><td>I</td><td>H</td></tr> <tr><td>I</td><td>L</td></tr> <tr><td>Don't Care</td><td>—</td></tr> </table> (I)	INACTIVE	0	I	H	I	L	Don't Care	—	<b>CONTROL</b> <table border="1" style="margin: auto; border-collapse: collapse;"> <tr><td>HIGH</td><td>H</td></tr> <tr><td>LOW</td><td>L</td></tr> </table> (POL.)	HIGH	H	LOW	L
INACTIVE	0														
I	H														
I	L														
Don't Care	—														
HIGH	H														
LOW	L														

LD022605



## Section 5 Programmable Logic Sequencer Device Data Sheets

### INDEX

#### Series 20

PLS155	Field-Programmable Logic Sequencer (16 × 45 × 12); 18.2MHz .	5-3
PLS157	Field-Programmable Logic Sequencer (16 × 45 × 12); 18.2MHz .	5-14
PLS159A	Field-Programmable Logic Sequencer (16 × 45 × 12); 25MHz ...	5-25

#### Series 24

PLS167	Field-Programmable Logic Sequencer (14 × 48 × 6); 20MHz .....	5-35
PLS167A	Field-Programmable Logic Sequencer (14 × 48 × 6); 25MHz .....	5-47
PLS168	Field-Programmable Logic Sequencer (12 × 48 × 8); 20MHz .....	5-59
PLS168A	Field-Programmable Logic Sequencer (12 × 48 × 8); 25MHz .....	5-71
PLS179	Field-Programmable Logic Sequencer (20 × 45 × 12); 25MHz ...	5-83

#### Series 28

PLS105	Field-Programmable Logic Sequencer (16 × 48 × 8); 20MHz .....	5-93
PLS105A	Field-Programmable Logic Sequencer (16 × 48 × 8); 25MHz .....	5-105
PLUS405	Field-Programmable Logic Sequencer (16 × 64 × 8); 50MHz .....	5-117



# PLS155

## Field-Programmable Logic Sequencer (16 × 45 × 12)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

- Series 20

### DESCRIPTION

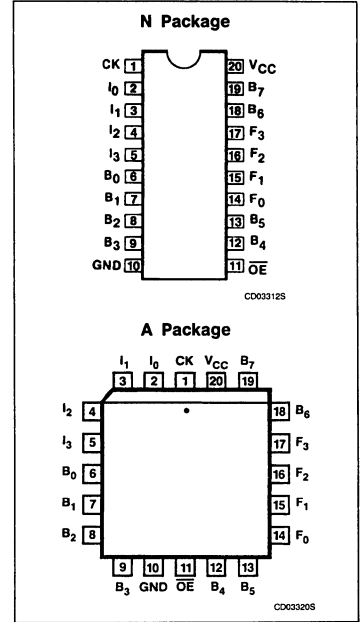
The PLS155 is a 3-State output, registered logic element combining AND/OR gate arrays with clocked J-K flip-flops. These J-K flip-flops are dynamically convertible to D-type via a "fold-back" inverting buffer and control gate  $F_C$ . It features 4 registered I/O outputs (F) in conjunction with 8 bidirectional I/O lines (B). These yield variable I/O gate and register configurations via control gates (D, L) ranging from 16 inputs to 12 outputs.

The AND/OR arrays consist of 32 logic AND gates, 13 control AND gates, and 21 OR gates with fusible link connections for programming I/O polarity and direction. All AND gates are linked to 4 inputs (I), bidirectional I/O lines (B), internal flip-flop outputs (Q), and Complement Array output (C). The Complement Array consists of a NOR gate optionally linked to all AND gates for generating and propagating complementary AND terms.

### FEATURES

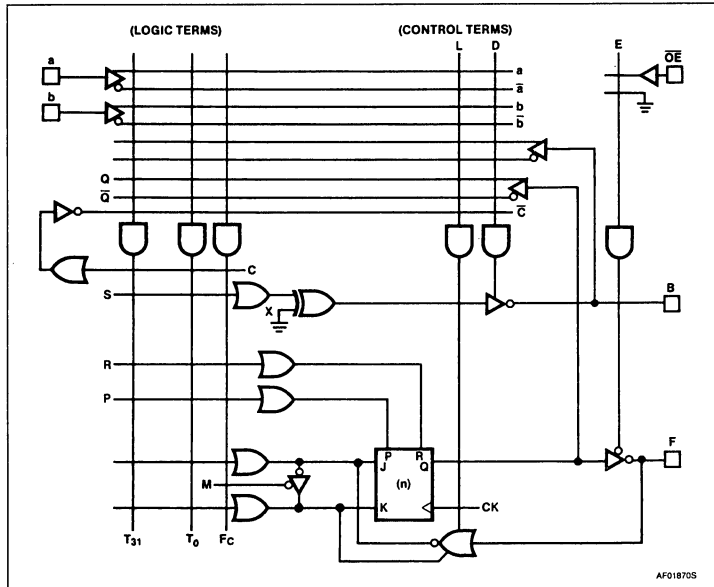
- $f_{MAX} = 14\text{MHz}$
- - 18.2MHz clock rate
- Field-Programmable (Ni-Cr link)
- 4 dedicated inputs
- 13 control gates
- 32 AND gates
- 21 OR gates
- 45 product terms:
  - 32 logic terms
  - 13 control terms
- 8 bidirectional I/O lines
- 4 bidirectional registers
- J-K, T, or D-type flip-flops
- Asynchronous Preset/Reset
- Complement Array
- Active-High or -Low outputs
- Programmable  $\overline{OE}$  control
- Positive edge-triggered clock
- Input loading: -100 $\mu\text{A}$  (max.)
- Power dissipation: 750mW (typ.)
- TTL compatible
- 3-State outputs

### PIN CONFIGURATIONS



5

### FUNCTIONAL DIAGRAM



### APPLICATIONS

- Random sequential logic
- Synchronous up/down counters
- Shift registers
- Bidirectional data buffers
- Timing function generators
- System controllers/synchronizers
- Priority encoder/registers

# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS155

On-chip T/C buffers couple either True (I, B, Q) or Complement ( $\bar{I}$ ,  $\bar{B}$ ,  $\bar{Q}$ ,  $\bar{C}$ ) input polarities to all AND gates, whose outputs can be optionally linked to all OR gates. One group of AND gates drives bidirectional I/O lines (B), whose output polarity is individually programmable through a set of EX-OR gates for implementing AND-OR or AND-NOR logic functions. Another group drives the J-K inputs of all flip-flops. The Asynchronous Preset and Reset lines (P, R), are driven from the OR matrix.

All flip-flops are positive edge-triggered and can be used as input, output or I/O (for interfacing with a bidirectional data bus) in conjunction with load control gates (L), steering inputs (I), (B), (Q) and programmable output select lines (E).

The PLS155 is field programmable, enabling the user to quickly generate custom patterns using standard programming equipment.

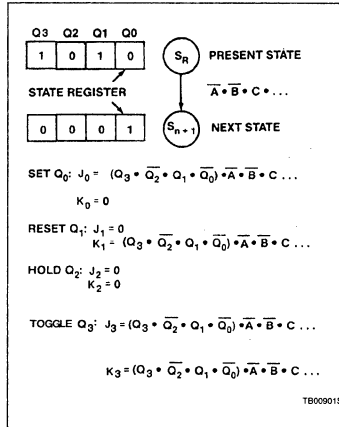
Order codes are listed in the Ordering Information Table.

### VIRGIN STATE

The factory shipped virgin device contains all fusible links intact, such that:

1.  $\bar{OE}$  is always enabled.
2. Preset and Reset are always disabled.
3. All transition terms are disabled.
4. All flip-flops are in D-mode unless otherwise programmed to J/K only or J/K or D (controlled).
5. All B pins, are inputs and all F pins are outputs unless otherwise programmed.

### LOGIC FUNCTION



**NOTES:**  
 Similar logic functions are applicable for D and T mode flip-flops.

### FLIP-FLOP TRUTH TABLE

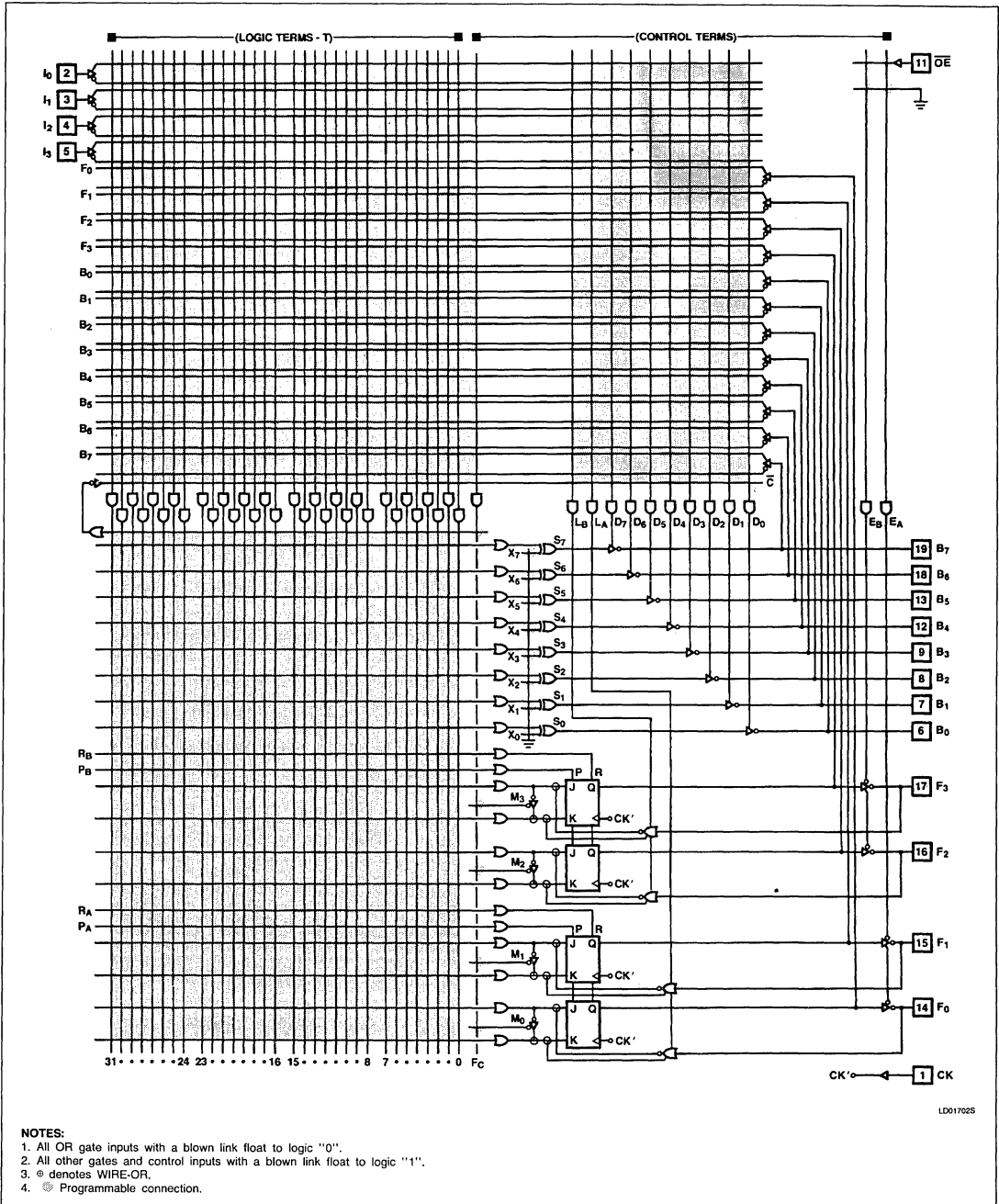
$\bar{OE}$	L	CK	P	R	J	K	Q	F
H								HI-Z
L	X	X	H	L	X	X	H	L
L	X	X	L	H	X	X	L	H
L	L	↑	L	L	L	L	Q	$\bar{Q}$
L	L	↑	L	L	L	H	L	H
L	L	↑	L	L	H	L	H	L
L	L	↑	L	L	H	H	$\bar{Q}$	Q
H	H	↑	L	L	L	H	L	H*
H	H	↑	L	L	H	L	H	L*
+10V	X	↑	X	X	L	H	L	H**
	X	↑	X	X	H	L	H	L**

**NOTES:**  
 1. Positive Logic:  
 $J/K = T_0 + T_1 + T_2 \dots T_{31}$   
 $T_n = \bar{C} \cdot (I_0 \cdot I_1 \cdot I_2 \dots) \cdot (Q_0 \cdot Q_1 \dots) \cdot (B_0 \cdot B_1 \dots)$   
 2. ↑ denotes transition from Low to High level.  
 3. X = Don't care  
 4. \* = Forced at  $F_n$  pin for loading J/K flip-flop in I/O mode. L must be enabled, and other active  $T_n$  disabled via steering input(s) I, B, or Q.  
 5. At  $P = R = H$ ,  $Q = H$ . The final state of Q depends on which is released first.  
 6. \*\* = Forced at  $F_n$  pin to load J/K flip-flop independent of program code (Diagnostic mode), 3-State B outputs.

# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS155

## FPLS LOGIC DIAGRAM



5



## Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS155

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
20-pin Plastic DIP 300mil-wide	PLS155N
20-pin Plastic Leaded Chip Carrier	PLS155A

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

## Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS155

**DC ELECTRICAL CHARACTERISTICS**  $0^{\circ}\text{C} \leq T_A \leq +75^{\circ}\text{C}$ ,  $4.75 \leq V_{CC} \leq 5.25\text{V}$ 

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
$V_{IH}$	High	$V_{CC} = \text{Max}$	2			V
$V_{IL}$	Low	$V_{CC} = \text{Min}$			0.8	V
$V_{IC}$	Clamp	$V_{CC} = \text{Min}$ , $I_{IN} = -12\text{mA}$		-0.8	-1.2	V
<b>Output voltage<sup>2</sup></b>						
$V_{OH}$	High	$V_{CC} = \text{Min}$	2.4			V
$V_{OL}$	Low	$I_{OH} = -2\text{mA}$ $I_{OL} = 10\text{mA}$		0.35	0.5	V
<b>Input current<sup>5</sup></b>						
$I_{IH}$	High	$V_{CC} = \text{Max}$		< 1	80	$\mu\text{A}$
$I_{IL}$	Low	$V_{IN} = 5.5\text{V}$ $V_{IN} = 0.45\text{V}$		-10	-100	$\mu\text{A}$
<b>Output current</b>						
$I_{O(\text{OFF})}$	Hi-Z state <sup>5, 6</sup>	$V_{CC} = \text{Max}$ $V_{OUT} = 5.5\text{V}$ $V_{OUT} = 0.45\text{V}$		1 -1	80 -140	$\mu\text{A}$ $\mu\text{A}$
$I_{OS}$	Short circuit <sup>3, 7</sup>	$V_{OUT} = 0\text{V}$	-15		-70	$\text{mA}$
$I_{CC}$	$V_{CC}$ supply current <sup>4</sup>	$V_{CC} = \text{Max}$		150	190	$\text{mA}$
<b>Capacitance</b>						
$C_{IN}$	Input	$V_{CC} = 5.0\text{V}$ $V_{IN} = 2.0\text{V}$		8		pF
$C_{OUT}$	Output	$V_{OUT} = 2.0\text{V}$		15		pF

**NOTES:**

- All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- $I_{CC}$  is measured with the  $\overline{OE}$  input grounded, all other inputs at 4.5V, and the outputs open.
- Leakage values are a combination of input and output leakage.
- Measured with  $V_{IH}$  applied to  $\overline{OE}$ .
- Duration of short circuit should not exceed 1 second.

5

## Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS155

**AC ELECTRICAL CHARACTERISTICS** 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75 ≤ V<sub>CC</sub> ≤ 5.25V, R<sub>1</sub> = 470Ω, R<sub>2</sub> = 1kΩ

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min <sup>5</sup>	Typ <sup>1</sup>	Max	
<b>Pulse width</b>								
t <sub>CKH</sub>	Clock <sup>2</sup> High	CK -	CK +	C <sub>L</sub> = 30pF	25	20		ns
t <sub>CKL</sub>	Clock Low	CK +	CK -		30	20		
t <sub>CKP</sub>	Period	CK +	CK +		70	50		
t <sub>PRH</sub>	Preset/Reset pulse	(I,B) +	(I,B) -		40	30		
<b>Setup time</b>								
t <sub>S1</sub>	Input	CK +	(I,B) ±	C <sub>L</sub> = 30pF	40	30		ns
t <sub>S2</sub>	Input (through F <sub>n</sub> )	CK +	F ±		20	10		
t <sub>S3</sub>	Input (through Complement Array) <sup>4</sup>	CK +	(I,B) ±		65	40		
<b>Hold time</b>								
t <sub>IH1</sub>	Input	CK +	(I,B) ±	C <sub>L</sub> = 30pF	0	-10		ns
t <sub>IH2</sub>		CK +	F ±		15	10		
<b>Propagation delays</b>								
t <sub>CKO</sub>	Clock	F ±	CK +	C <sub>L</sub> = 30pF		25	30	ns
t <sub>OE1</sub>	Output enable	F -	$\overline{OE}$ -	C <sub>L</sub> = 30pF		20	30	
t <sub>OD1</sub>	Output disable <sup>3</sup>	F +	$\overline{OE}$ +	C <sub>L</sub> = 5pF		20	30	
t <sub>PD</sub>	Output	B ±	(I,B) ±	C <sub>L</sub> = 30pF		40	50	
t <sub>OE2</sub>	Output enable	B ±	(I,B) +	C <sub>L</sub> = 30pF		35	55	
t <sub>OD2</sub>	Output disable <sup>3</sup>	B +	(I,B) -	C <sub>L</sub> = 5pF		30	35	
t <sub>PRO</sub>	Preset/Reset	F ±	(I,B) +	C <sub>L</sub> = 30pF		50	55	

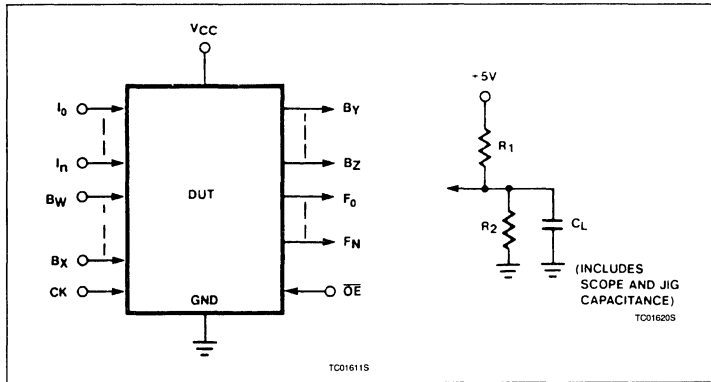
**NOTES:**

1. All typical values are at V<sub>CC</sub> = 5V, T<sub>A</sub> = +25°C.
2. To prevent spurious clocking, clock rise time (10% - 90%) ≤ 10ns.
3. Measured at V<sub>T</sub> = V<sub>OL</sub> + 0.5V.
4. When using the Complement Array T<sub>CKP</sub> = 95ns (min).
5. Limits are guaranteed with 12 product terms maximum connected to each sum term line.
6. For test circuits, waveforms and timing diagrams see the following pages.

# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS155

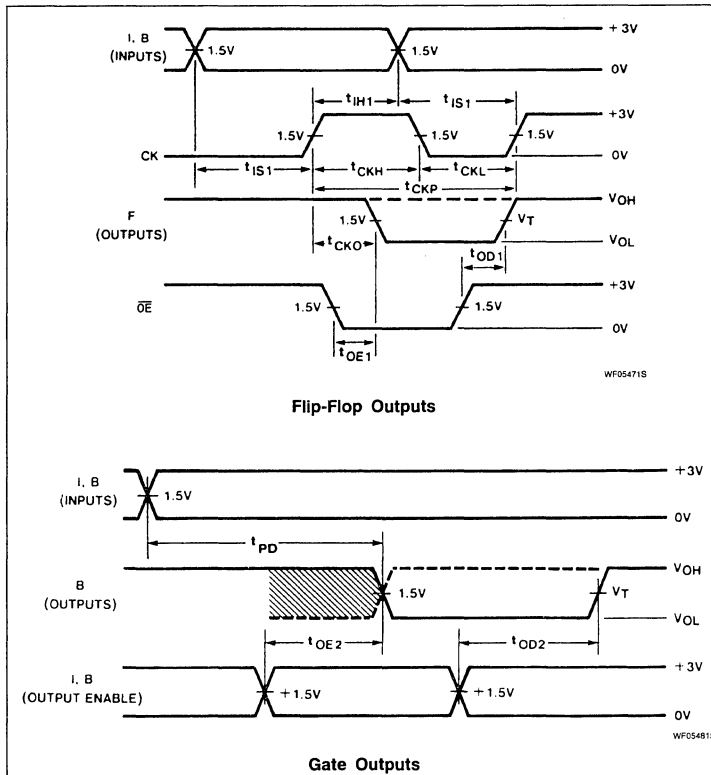
## TEST LOAD CIRCUITS



## TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{CKH}$	Width of input clock pulse.
$t_{CKL}$	Interval between clock pulses.
$t_{CKP}$	Clock period.
$t_{PRH}$	Width of preset input pulse.
$t_{IS1}$	Required delay between beginning of valid input and positive transition of clock.
$t_{IS2}$	Required delay between beginning of valid input forced at flip-flop output pins, and positive transition of clock.
$t_{IH1}$	Required delay between positive transition of clock and end of valid input data.
$t_{IH2}$	Required delay between positive transition of clock and end of valid input data forced at flip-flop output pins.
$t_{CKO}$	Delay between positive transition of clock and when Outputs become valid (with $\overline{OE}$ Low).
$t_{OE1}$	Delay between beginning of Output Enable Low and when Outputs become valid.
$t_{OD1}$	Delay between beginning of Output Enable High and when Outputs are in the OFF-state.
$t_{PD}$	Propagation delay between combinational inputs and outputs.
$t_{OE2}$	Delay between predefined Output Enable High, and when combinational Outputs become valid.
$t_{OD2}$	Delay between predefined Output Enable Low, and when combinational Outputs are in the OFF-state.
$t_{PRO}$	Delay between positive transition of predefined Preset/Reset input, and when flip-flop outputs become valid.

## TIMING DIAGRAMS

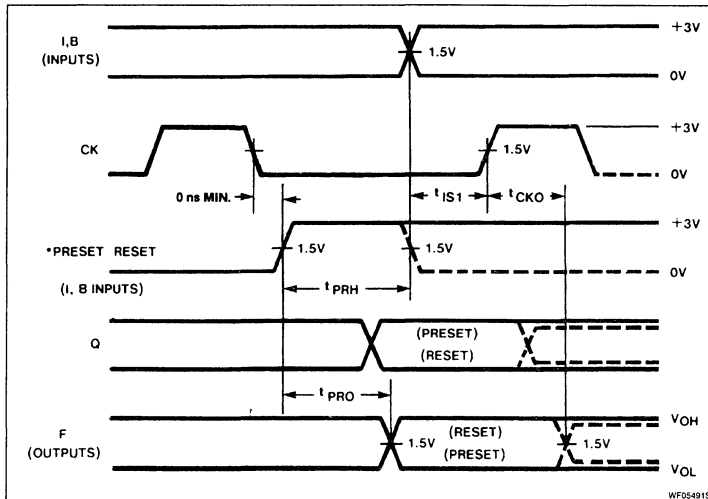


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# Field-Programmable Logic Sequencer (16 × 45 × 12)

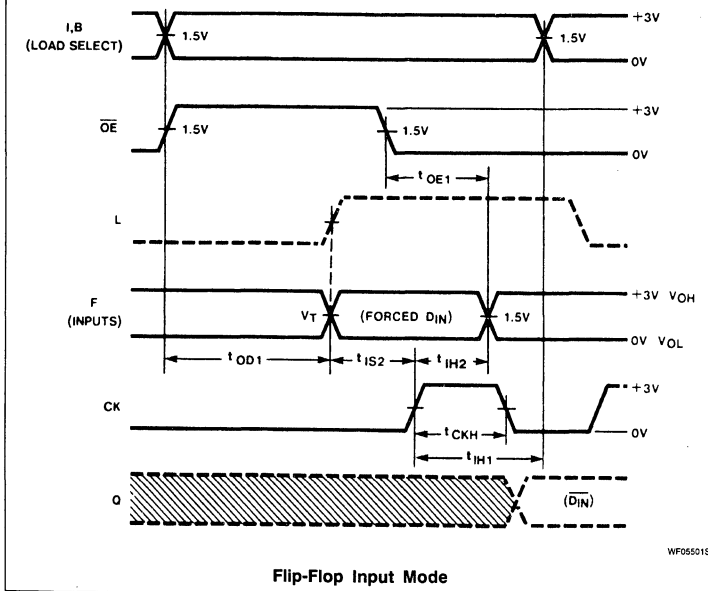
PLS155

## TIMING DIAGRAMS (Continued)



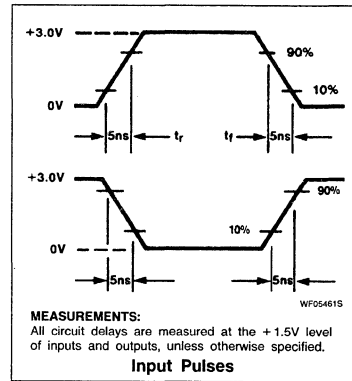
\* The leading edge of preset/reset must occur only when the input clock is "low", and must remain "high" as long as required to override clock. The falling edge of preset/reset can never go "low" when the input clock is "high".

### Asynchronous Preset/Reset



### Flip-Flop Input Mode

## VOLTAGE WAVEFORMS



# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS155

## LOGIC PROGRAMMING

PLS155 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

PLS155 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

### "AND" ARRAY - (I), (B), (Q<sub>p</sub>)

<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>INACTIVE<sup>1,2</sup></td><td>O</td></tr> </table> <p style="font-size: small; text-align: center;">LS02030S</p>	STATE	CODE	INACTIVE <sup>1,2</sup>	O	<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>I, B, Q</td><td>H</td></tr> </table> <p style="font-size: small; text-align: center;">LS02040S</p>	STATE	CODE	I, B, Q	H	<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>I, B, Q</td><td>L</td></tr> </table> <p style="font-size: small; text-align: center;">LS02050S</p>	STATE	CODE	I, B, Q	L	<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>DON'T CARE</td><td>-</td></tr> </table> <p style="font-size: small; text-align: center;">LS02060S</p>	STATE	CODE	DON'T CARE	-
STATE	CODE																		
INACTIVE <sup>1,2</sup>	O																		
STATE	CODE																		
I, B, Q	H																		
STATE	CODE																		
I, B, Q	L																		
STATE	CODE																		
DON'T CARE	-																		

### "COMPLEMENT" ARRAY - (C)

<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>INACTIVE<sup>1,3,5</sup></td><td>O</td></tr> </table> <p style="font-size: small; text-align: center;">LS02070S</p>	ACTION	CODE	INACTIVE <sup>1,3,5</sup>	O	<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>GENERATE<sup>5</sup></td><td>A</td></tr> </table> <p style="font-size: small; text-align: center;">LS02080S</p>	ACTION	CODE	GENERATE <sup>5</sup>	A	<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>PROPAGATE</td><td>•</td></tr> </table> <p style="font-size: small; text-align: center;">LS02090S</p>	ACTION	CODE	PROPAGATE	•	<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>TRANSPARENT</td><td>-</td></tr> </table> <p style="font-size: small; text-align: center;">LS02100S</p>	ACTION	CODE	TRANSPARENT	-
ACTION	CODE																		
INACTIVE <sup>1,3,5</sup>	O																		
ACTION	CODE																		
GENERATE <sup>5</sup>	A																		
ACTION	CODE																		
PROPAGATE	•																		
ACTION	CODE																		
TRANSPARENT	-																		

### "OR" ARRAY - (F-F CONTROL MODE)

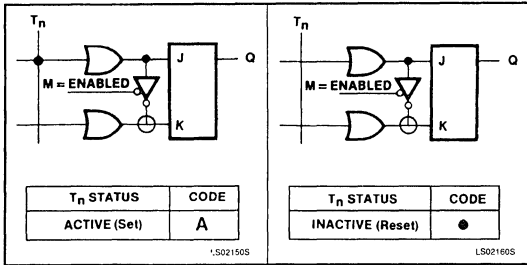
<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>J/K OR D (CONTROLLED)</td><td>A</td></tr> </table> <p style="font-size: small; text-align: center;">LS02130S</p>	ACTION	CODE	J/K OR D (CONTROLLED)	A	<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>J-K</td><td>•</td></tr> </table> <p style="font-size: small; text-align: center;">LS02140S</p>	ACTION	CODE	J-K	•
ACTION	CODE								
J/K OR D (CONTROLLED)	A								
ACTION	CODE								
J-K	•								

Notes on following page.

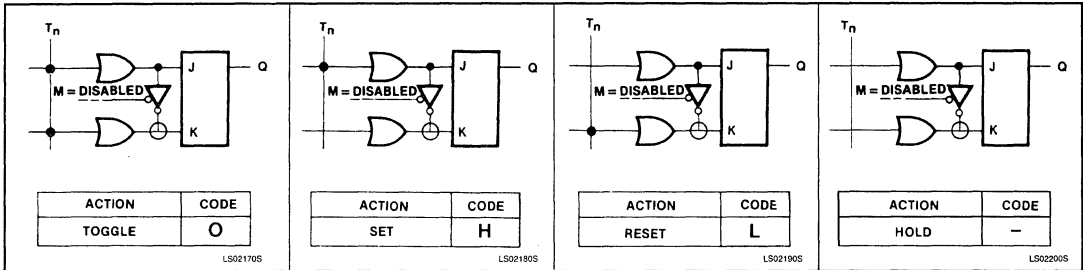
# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS155

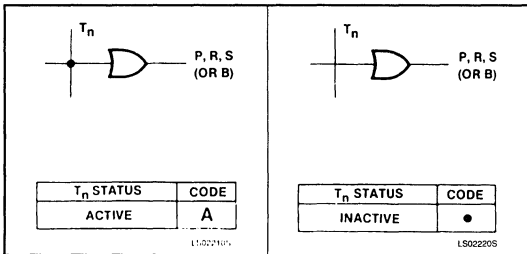
## "OR" ARRAY - ( $Q_n = D$ -Type)



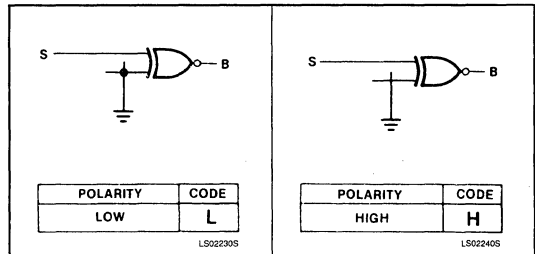
## "OR" ARRAY - ( $Q_n = J$ -K Type)



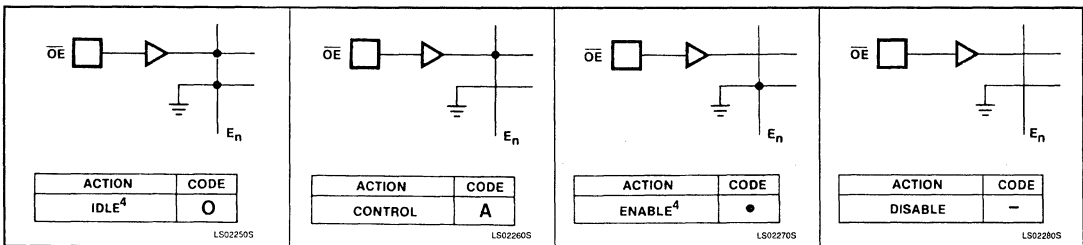
## "OR" ARRAY - (S or B), (P), (R)



## "EX-OR" ARRAY - (B)



## "OE" ARRAY - (E)



**NOTES:**

1. This is the initial unprogrammed state of all link pairs. It is normally associated with all unused (inactive) AND gates.
2. Any gate ( $T, F_c, L, P, R, D$ )<sub>n</sub> will be unconditionally inhibited if both of the I, B, or Q links are left intact.
3. To prevent oscillations, this state is not allowed for C link pairs coupled to active gates  $T_n, F_c$ .
4.  $E_n = \bar{O}$  and  $E_n = \bullet$  are logically equivalent states, since both cause  $F_n$  outputs to be unconditionally enabled.
5. These states are not allowed for control gates ( $L, P, R, D$ )<sub>n</sub> due to their lack of "OR" array links.

# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS155

## FPLS PROGRAM TABLE

AND				OR				CONTROL				NOTES																																																
INACTIVE	O	I, B, Q	H	ACTIVE	A	P, R, B (O)	(Q = D)	J/K	*	FIF MODE	IDLE		O																																															
I, B, Q	L	I, B, Q	L	INACTIVE	*	(Q = J/K)	(Q = D)	J/K or D (controlled)	A	CONTROL	A		E <sub>A</sub> , B																																															
DON'T CARE	-	I, B (I), Q (P)	C	TOGGLE	O	HIGH	H	LOW	L	ENABLE	*		<p>1. The FPLS is shipped with all links intact. Thus a background of entries corresponding to states of virgin links exists in the table, shown BLANK for clarity.</p> <p>2. Program unused C, I, B, and Q bits in the AND array as (-). Program unused Q, B, P, and R bits in the OR array as (-) or (A), as applicable.</p> <p>3. Unused Terms can be left blank.</p> <p>4. Q (P) and Q (N) are respectively the present and next states of flip-flops Q.</p>																																															
GENERATE	A	TRANSPARENT	-	RESET	L	(POL)	H	DISABLE	-	E <sub>B</sub>	E <sub>A</sub>																																																	
				HOLD	-					POLARITY																																																		
								FIF MODE																																																				
<p style="text-align: center;">THIS PORTION TO BE COMPLETED BY SIGNETICS</p> <p>CF (XXXX) _____</p> <p>CUSTOMER SYMBOLIZED PART # _____</p> <p>DATE RECEIVED _____</p> <p>COMMENTS _____</p> <hr/> <p>CUSTOMER NAME _____</p> <p>PURCHASE ORDER # _____</p> <p>SIGNETICS DEVICE # _____</p> <p>TOTAL NUMBER OF PARTS _____</p> <p>PROGRAM TABLE # _____</p> <p>REV _____</p> <p>DATE _____</p>	T E R M	C	AND												OR												E <sub>B</sub>	E <sub>A</sub>	POLARITY																															
	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	F <sub>C</sub>	L <sub>B</sub>	L <sub>A</sub>	D <sub>7</sub>	D <sub>6</sub>	D <sub>5</sub>	D <sub>4</sub>	D <sub>3</sub>	D <sub>2</sub>	D <sub>1</sub>	D <sub>0</sub>	PIN	5	4	3	2	19	18	13	12	9	8	7	6	17	16	15	14
	3	2	1	0	7	6	5	4	3	2	1	0	3	2	1	0	3	2	1	0	3	2	1	0	3	2	1	0	B	A	B	A	7	6	5	4	3	2	1	0	Q(N)	P	R	B(O)																

5



# PLS157

## Field-Programmable Logic Sequencer (16 × 45 × 12)

Signetics Programmable Logic  
Product Specification

Application Specific Products  
• Series 20

### DESCRIPTION

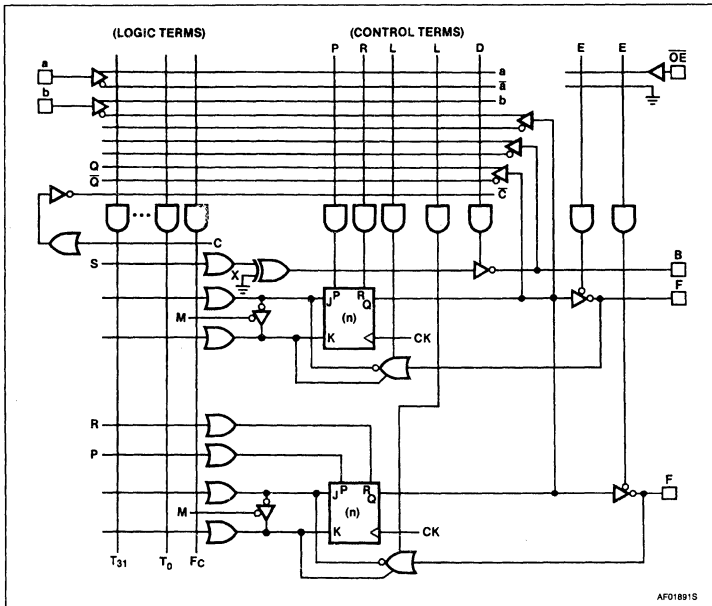
The PLS157 is a 3-State output, registered logic element combining AND/OR gate arrays with clocked J-K flip-flops. These J-K flip-flops are dynamically convertible to D-type via a "fold-back" inverting buffer and control gate  $F_C$ . It features 6 registered I/O outputs (F) in conjunction with 6 bidirectional I/O lines (B). These yield variable I/O gate and register configurations via control gates (D, L) ranging from 16 inputs to 12 outputs.

The AND/OR arrays consist of 32 logic AND gates, 13 control AND gates, and 21 OR gates with fusible link connections for programming I/O polarity and direction. All AND gates are linked to 4 inputs (I), bidirectional I/O lines (B), internal flip-flop outputs (Q), and Complement Array output ( $\bar{C}$ ). The Complement Array consists of a NOR gate optionally linked to all AND gates for generating and propagating complementary AND terms.

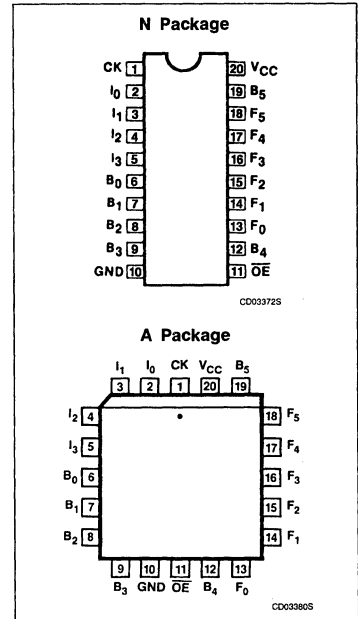
### FEATURES

- $f_{MAX} = 14\text{MHz}$
- 18.2MHz clock rate
- Field-Programmable (Ni-Cr link)
- 4 dedicated inputs
- 13 control gates
- 32 AND gates
- 21 OR gates
- 45 product terms:
  - 32 logic terms
  - 13 control terms
- 6 bidirectional I/O lines
- 6 bidirectional registers
- J-K, T, or D-type flip-flops
- 3-State outputs
- Asynchronous Preset/Reset
- Complement Array
- Active-High or -Low outputs
- Programmable  $\bar{O}E$  control
- Positive edge-triggered clock
- Input loading:  $-100\mu\text{A}$  (max.)
- Power dissipation: 750mW (typ.)
- TTL compatible

### FUNCTIONAL DIAGRAM



### PIN CONFIGURATIONS



### APPLICATIONS

- Random sequential logic
- Synchronous up/down counters
- Shift registers
- Bidirectional data buffers
- Timing function generators
- System controllers/synchronizers
- Priority encoder/registers

# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS157

On-chip T/C buffers couple either True (I, B, Q) or Complement (I, B, Q, C) input polarities to all AND gates, whose outputs can be optionally linked to all OR gates. One group of AND gates drives bidirectional I/O lines (B), whose output polarity is individually programmable through a set of EX-OR gates for implementing AND-OR or AND-NOR logic functions. Another group drives the J-K inputs of all flip-flops. The Asynchronous Preset and Reset lines (P, R), for two of the registers are driven from the AND matrix. The Preset and Reset lines (P, R) controlling the lower four registers are driven from the OR matrix.

All flip-flops are positive edge-triggered and can be used as input, output or I/O (for interfacing with a bidirectional data bus) in conjunction with load control gates (L), steering inputs (I), (B), (Q) and programmable output select lines (E).

The PLS157 is field programmable, enabling the user to quickly generate custom patterns using standard programming equipment.

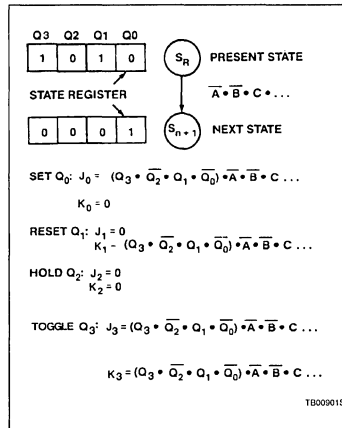
Order codes are listed in the Ordering Information Table.

### VIRGIN STATE

The factory shipped virgin device contains all fusible links intact, such that:

1.  $\overline{OE}$  is always enabled.
2. Preset and Reset are always disabled.
3. All transition terms are disabled.
4. All flip-flops are in D-mode unless otherwise programmed to J/K only or J/K or D (controlled).
5. All B pins are inputs and all F pins are outputs unless otherwise programmed.

### LOGIC FUNCTION



### NOTES:

Similar logic functions are applicable for D and T mode flip-flops.

### FLIP-FLOP TRUTH TABLE

$\overline{OE}$	L	CK	P	R	J	K	Q	F
H								Hi-Z
L	X	X	H	L	X	X	H	L
L	X	X	L	H	X	X	L	H
L	L	↑	L	L	L	L	Q	$\overline{Q}$
L	L	↑	L	L	L	H	L	H
L	L	↑	L	L	H	L	H	L
L	L	↑	L	L	H	H	L	Q
H	H	↑	L	L	L	H	L	H*
H	H	↑	L	L	H	L	H	L*
+10V	X	↑	X	X	L	H	L	H**
	X	↑	X	X	H	L	H	L**

### NOTES:

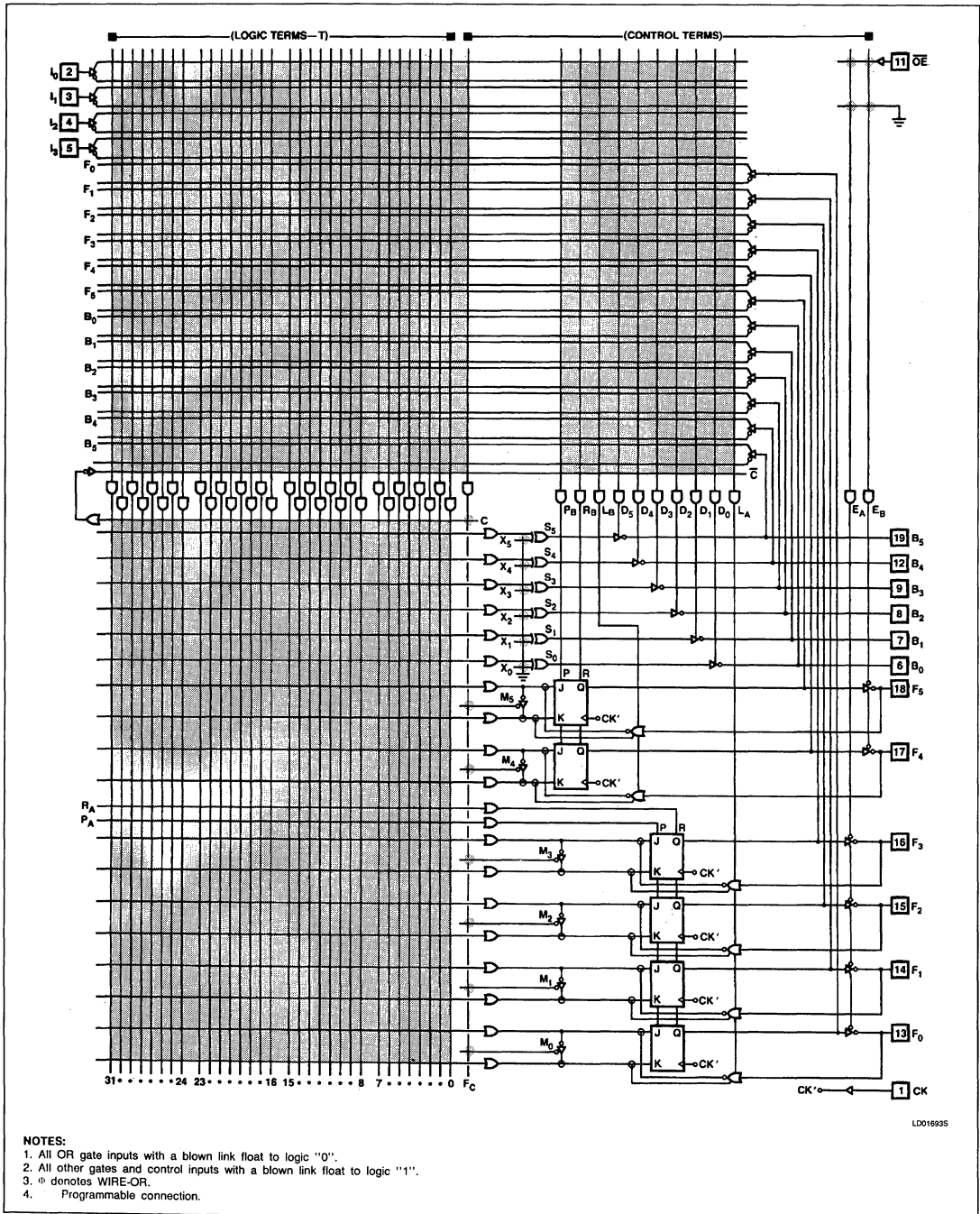
1. Positive Logic:  
 $J/K = T_0 + T_1 + T_2 \dots T_{31}$   
 $T_n = \overline{C} \cdot (I_0 \cdot I_1 \cdot I_2 \dots) \cdot (Q_0 \cdot Q_1 \dots) \cdot (B_0 \cdot B_1 \dots)$
2. ↑ denotes transition from Low to High level.
3. X = Don't care
4. \* = Forced at  $F_n$  pin for loading J/K flip-flop in I/O mode. L must be enabled, and other active  $T_n$  disabled via steering input(s) I, B, or Q.
5. At  $P = R = H$ ,  $Q = H$ . The final state of Q depends on which is released first.
6. \* \* = Forced at  $F_n$  pin to load J/K flip-flop independent of program code (Diagnostic mode), 3-State B outputs.

5

# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS157

## FPLS LOGIC DIAGRAM



LD01693S

**NOTES:**

1. All OR gate inputs with a blown link float to logic "0".
2. All other gates and control inputs with a blown link float to logic "1".
3. ⊕ denotes WIRE-OR.
4. • Programmable connection.

## Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS157

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
20-pin Plastic DIP 300mil-wide	PLS157N
20-pin Plastic Leaded Chip Carrier	PLS157A

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

## Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS157

**DC ELECTRICAL CHARACTERISTICS** 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75 ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IH</sub>	High	V <sub>CC</sub> = Max	2			V
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min			0.8	V
V <sub>IC</sub>	Clamp	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA		-0.8	-1.2	V
<b>Output voltage<sup>2</sup></b>						
V <sub>OH</sub>	High	V <sub>CC</sub> = Min	2.4			V
V <sub>OL</sub>	Low	I <sub>OH</sub> = -2mA I <sub>OL</sub> = 10mA		0.35	0.5	V
<b>Input current</b>						
I <sub>IH</sub>	High	V <sub>IN</sub> = 5.5V		< 1	80	μA
I <sub>IL</sub>	Low	V <sub>IN</sub> = 0.45V		-10	-100	μA
<b>Output current</b>						
I <sub>O</sub> (OFF)	Hi-Z state <sup>5, 6</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V		1	80	μA
I <sub>OS</sub>	Short circuit <sup>3, 7</sup>	V <sub>OUT</sub> = 0.45V V <sub>OUT</sub> = 0V	-15	-1	-140 -70	μA mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>4</sup>	V <sub>CC</sub> = Max		150	190	mA
<b>Capacitance</b>						
C <sub>IN</sub>	Input	V <sub>CC</sub> = 5.0V V <sub>IN</sub> = 2.0V		8		pF
C <sub>OUT</sub>	Output	V <sub>OUT</sub> = 2.0V		15		pF

**NOTES:**

- All typical values are at V<sub>CC</sub> = 5V, T<sub>A</sub> = +25°C.
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- I<sub>CC</sub> is measured with the  $\overline{OE}$  input grounded, all other inputs at 4.5V, and the outputs open.
- Leakage values are a combination of input and output leakage.
- Measured with V<sub>IH</sub> applied to  $\overline{OE}$ .
- Duration of short circuit should not exceed 1 second.

## Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS157

**AC ELECTRICAL CHARACTERISTICS** 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75 ≤ V<sub>CC</sub> ≤ 5.25V, R<sub>1</sub> = 470Ω, R<sub>2</sub> = 1kΩ

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min <sup>5</sup>	Typ <sup>1</sup>	Max	
<b>Pulse width</b>								
t <sub>CKH</sub>	Clock <sup>2</sup> High	CK -	CK +	C <sub>L</sub> = 30pF	25	20		ns
t <sub>CKL</sub>	Clock Low	CK +	CK -		30	20		
t <sub>CKP</sub>	Period	CK +	CK +		70	50		
t <sub>PRH</sub>	Preset/Reset pulse	(I,B) +	(I,B) -		40	30		
<b>Setup time</b>								
t <sub>IS1</sub>	Input	CK +	(I,B) ±	C <sub>L</sub> = 30pF	40	30		ns
t <sub>IS2</sub>	Input (through F <sub>N</sub> )	CK +	F ±		20	10		
t <sub>IS3</sub>	Input (through Complement Array) <sup>4</sup>	CK +	(I,B) ±		65	40		
<b>Hold time</b>								
t <sub>IH1</sub>	Input	CK +	(I,B) ±	C <sub>L</sub> = 30pF	0	-10		ns
t <sub>IH2</sub>		CK +	F ±		15	10		
<b>Propagation delays</b>								
t <sub>CKO</sub>	Clock	F ±	CK +	C <sub>L</sub> = 30pF		25	30	ns
t <sub>OE1</sub>	Output enable	F -	$\overline{OE}$ -	C <sub>L</sub> = 30pF		20	30	
t <sub>OD1</sub>	Output disable <sup>3</sup>	F +	$\overline{OE}$ +	C <sub>L</sub> = 5pF		20	30	
t <sub>PD</sub>	Output	B ±	(I,B) ±	C <sub>L</sub> = 30pF		40	50	
t <sub>OE2</sub>	Output enable	B ±	(I,B) +	C <sub>L</sub> = 30pF		35	55	
t <sub>OD2</sub>	Output disable <sup>3</sup>	B +	(I,B) -	C <sub>L</sub> = 5pF		30	35	
t <sub>PRO</sub>	Preset/Reset	F ±	(I,B) +	C <sub>L</sub> = 30pF		50	55	

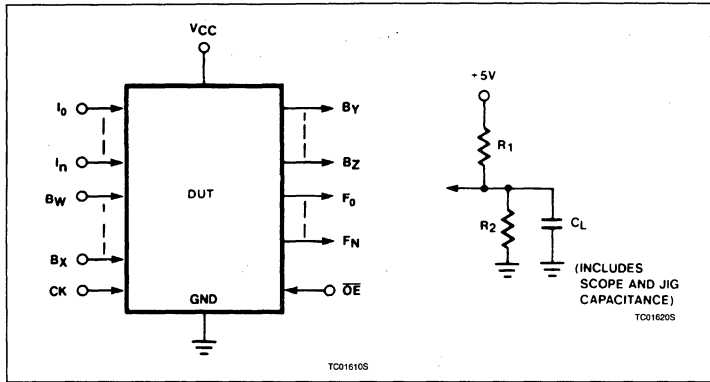
**NOTES:**

- All typical values are at V<sub>CC</sub> = 5V, T<sub>A</sub> = +25°C.
- To prevent spurious clocking, clock rise time (10% - 90%) ≤ 10ns.
- Measured at V<sub>T</sub> = V<sub>OL</sub> + 0.5V.
- When using the Complement Array T<sub>CKP</sub> = 95ns (min).
- Limits are guaranteed with 12 product terms maximum connected to each sum term line.
- For test circuits, waveforms and timing diagrams see the following pages.

# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS157

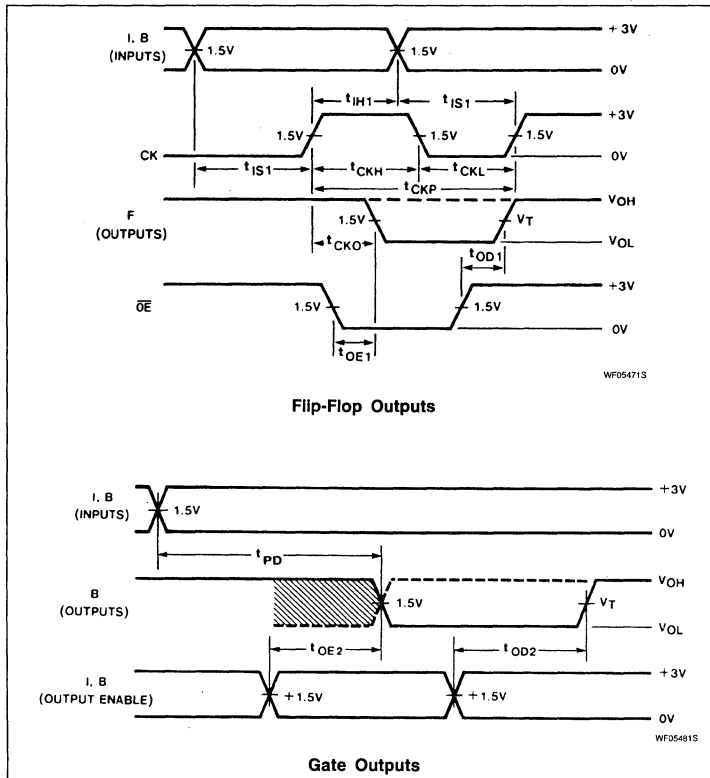
## TEST LOAD CIRCUITS



## TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{CKH}$	Width of input clock pulse.
$t_{CKL}$	Interval between clock pulses.
$t_{CKP}$	Clock period.
$t_{PRH}$	Width of preset input pulse.
$t_{IS1}$	Required delay between beginning of valid input and positive transition of clock.
$t_{IS2}$	Required delay between beginning of valid input forced at flip-flop output pins, and positive transition of clock.
$t_{IH1}$	Required delay between positive transition of clock and end of valid input data.
$t_{IH2}$	Required delay between positive transition of clock and end of valid input data forced at flip-flop output pins.
$t_{CKO}$	Delay between positive transition of clock and when Outputs become valid (with $\overline{OE}$ Low).
$t_{OE1}$	Delay between beginning of Output Enable Low and when Outputs become valid.
$t_{OD1}$	Delay between beginning of Output Enable High and when Outputs are in the OFF-state.
$t_{PD}$	Propagation delay between combinational inputs and outputs.
$t_{OE2}$	Delay between predefined Output Enable High, and when combinational Outputs become valid.
$t_{OD2}$	Delay between predefined Output Enable Low, and when combinational Outputs are in the OFF-state.
$t_{PRO}$	Delay between positive transition of predefined Preset/Reset input, and when flip-flop outputs become valid.

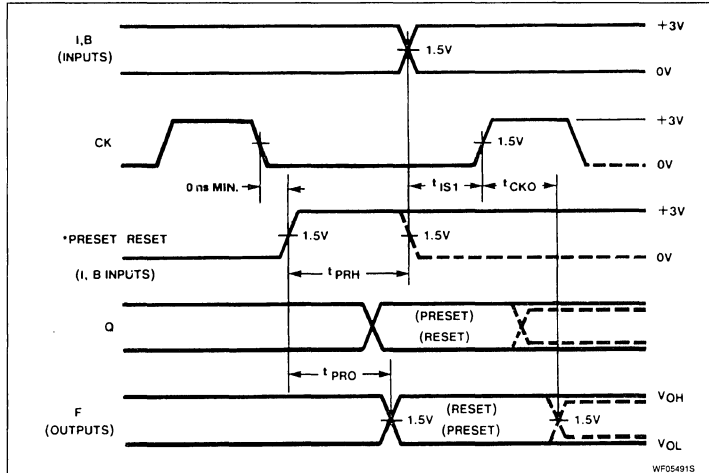
## TIMING DIAGRAMS



# Field-Programmable Logic Sequencer (16 × 45 × 12)

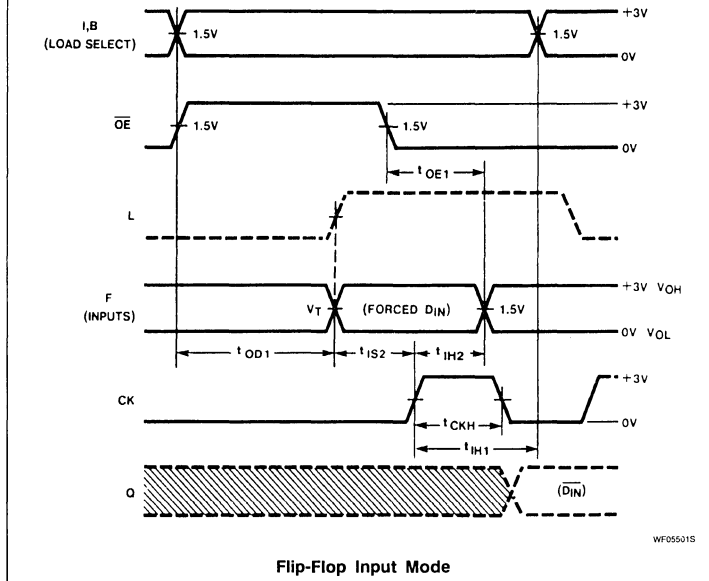
PLS157

## TIMING DIAGRAMS (Continued)



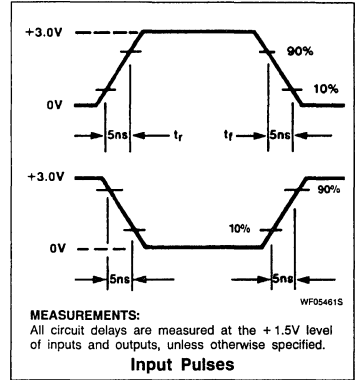
\* The leading edge of preset/reset must occur only when the input clock is "low", and must remain "high" as long as required to override clock. The falling edge of preset/reset can never go "low" when the input clock is "high".

**Asynchronous Preset/Reset**



**Flip-Flop Input Mode**

## VOLTAGE WAVEFORMS





# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS157

## LOGIC PROGRAMMING

PLS157 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

PLS157 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

### "AND" ARRAY - (I), (B), (Q<sub>p</sub>)

<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1"> <thead> <tr> <th>STATE</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>INACTIVE<sup>1,2</sup></td> <td>O</td> </tr> </tbody> </table> <p>LS020305</p>	STATE	CODE	INACTIVE <sup>1,2</sup>	O	<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1"> <thead> <tr> <th>STATE</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>I, B, Q</td> <td>H</td> </tr> </tbody> </table> <p>LS020405</p>	STATE	CODE	I, B, Q	H	<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1"> <thead> <tr> <th>STATE</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>I-bar, B-bar, Q-bar</td> <td>L</td> </tr> </tbody> </table> <p>LS020505</p>	STATE	CODE	I-bar, B-bar, Q-bar	L	<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1"> <thead> <tr> <th>STATE</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>DON'T CARE</td> <td>-</td> </tr> </tbody> </table> <p>LS020605</p>	STATE	CODE	DON'T CARE	-
STATE	CODE																		
INACTIVE <sup>1,2</sup>	O																		
STATE	CODE																		
I, B, Q	H																		
STATE	CODE																		
I-bar, B-bar, Q-bar	L																		
STATE	CODE																		
DON'T CARE	-																		

### "COMPLEMENT" ARRAY - (C)

<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1"> <thead> <tr> <th>ACTION</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>INACTIVE<sup>1,3,5</sup></td> <td>O</td> </tr> </tbody> </table> <p>LS020705</p>	ACTION	CODE	INACTIVE <sup>1,3,5</sup>	O	<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1"> <thead> <tr> <th>ACTION</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>GENERATE<sup>5</sup></td> <td>A</td> </tr> </tbody> </table> <p>LS020805</p>	ACTION	CODE	GENERATE <sup>5</sup>	A	<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1"> <thead> <tr> <th>ACTION</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>PROPAGATE</td> <td>•</td> </tr> </tbody> </table> <p>LS020905</p>	ACTION	CODE	PROPAGATE	•	<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1"> <thead> <tr> <th>ACTION</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>TRANSPARENT</td> <td>-</td> </tr> </tbody> </table> <p>LS021005</p>	ACTION	CODE	TRANSPARENT	-
ACTION	CODE																		
INACTIVE <sup>1,3,5</sup>	O																		
ACTION	CODE																		
GENERATE <sup>5</sup>	A																		
ACTION	CODE																		
PROPAGATE	•																		
ACTION	CODE																		
TRANSPARENT	-																		

### "OR" ARRAY - (F-F CONTROL MODE)

<p>LS021105</p>	<p>LS021405</p>
-----------------	-----------------

ACTION	CODE
J/K OR D (CONTROLLED)	A

ACTION	CODE
J-K	•

### "OR" ARRAY - (Q<sub>n</sub> = D-Type)

<p>LS021505</p>	<p>LS021605</p>
-----------------	-----------------

T <sub>n</sub> STATUS	CODE
ACTIVE (Set)	A

T <sub>n</sub> STATUS	CODE
INACTIVE (Reset)	•

Notes on following page.

# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS157

## "OR" ARRAY - (Q<sub>n</sub> = J-K Type)

<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>TOGGLE</td><td>O</td></tr> </table>	ACTION	CODE	TOGGLE	O	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>SET</td><td>H</td></tr> </table>	ACTION	CODE	SET	H	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>RESET</td><td>L</td></tr> </table>	ACTION	CODE	RESET	L	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>HOLD</td><td>-</td></tr> </table>	ACTION	CODE	HOLD	-
ACTION	CODE																		
TOGGLE	O																		
ACTION	CODE																		
SET	H																		
ACTION	CODE																		
RESET	L																		
ACTION	CODE																		
HOLD	-																		
<small>LS02170S</small>	<small>LS02180S</small>	<small>LS02190S</small>	<small>LS02200S</small>																

## "OR" ARRAY - (S or B), (P), (R)

<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>T<sub>n</sub> STATUS</th><th>CODE</th></tr> <tr><td>ACTIVE</td><td>A</td></tr> </table>	T <sub>n</sub> STATUS	CODE	ACTIVE	A	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>T<sub>n</sub> STATUS</th><th>CODE</th></tr> <tr><td>INACTIVE</td><td>•</td></tr> </table>	T <sub>n</sub> STATUS	CODE	INACTIVE	•
T <sub>n</sub> STATUS	CODE								
ACTIVE	A								
T <sub>n</sub> STATUS	CODE								
INACTIVE	•								
<small>LS02210S</small>	<small>LS02220S</small>								

## "EX-OR" ARRAY - (B)

<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>POLARITY</th><th>CODE</th></tr> <tr><td>LOW</td><td>L</td></tr> </table>	POLARITY	CODE	LOW	L	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>POLARITY</th><th>CODE</th></tr> <tr><td>HIGH</td><td>H</td></tr> </table>	POLARITY	CODE	HIGH	H
POLARITY	CODE								
LOW	L								
POLARITY	CODE								
HIGH	H								
<small>LS02230S</small>	<small>LS02240S</small>								

## "OE" ARRAY - (E)

<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>IDLE<sup>4</sup></td><td>O</td></tr> </table>	ACTION	CODE	IDLE <sup>4</sup>	O	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>CONTROL</td><td>A</td></tr> </table>	ACTION	CODE	CONTROL	A	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>ENABLE<sup>4</sup></td><td>•</td></tr> </table>	ACTION	CODE	ENABLE <sup>4</sup>	•	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>DISABLE</td><td>-</td></tr> </table>	ACTION	CODE	DISABLE	-
ACTION	CODE																		
IDLE <sup>4</sup>	O																		
ACTION	CODE																		
CONTROL	A																		
ACTION	CODE																		
ENABLE <sup>4</sup>	•																		
ACTION	CODE																		
DISABLE	-																		
<small>LS02250S</small>	<small>LS02260S</small>	<small>LS02270S</small>	<small>LS02280S</small>																

**NOTES:**

1. This is the initial unprogrammed state of all link pairs. It is normally associated with all unused (inactive) AND gates.
2. Any gate (T, F<sub>C</sub>, L, P, R, D<sub>n</sub>) will be unconditionally inhibited if both of the I, B, or Q links are left intact.
3. To prevent oscillations, this state is not allowed for C link pairs coupled to active gates T<sub>n</sub>, F<sub>C</sub>.
4. E<sub>n</sub> = O and E<sub>n</sub> = • are logically equivalent states, since both cause F<sub>n</sub> outputs to be unconditionally enabled.
5. These states are not allowed for control gates (L, P, R, D<sub>n</sub>) due to their lack of "OR" array links.

5



# PLS159A

## Field-Programmable Logic Sequencer (16 × 45 × 12)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

- Series 20

### DESCRIPTION

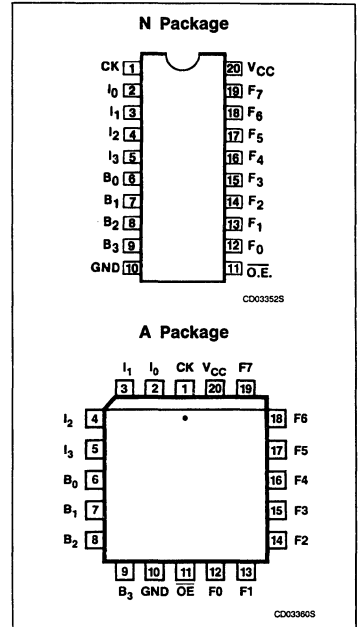
The PLS159A is a 3-State output, registered logic element combining AND/OR gate arrays with clocked J-K flip-flops. These J-K flip-flops are dynamically convertible to D-type via a "fold-back" inverting buffer and control gate  $F_C$ . It features 8 registered I/O outputs (F) in conjunction with 4 bidirectional I/O lines (B). These yield variable I/O gate and register configurations via control gates (D, L) ranging from 16 inputs to 12 outputs.

The AND/OR arrays consist of 32 logic AND gates, 13 control AND gates, and 21 OR gates with fusible link connections for programming I/O polarity and direction. All AND gates are linked to 4 inputs (I), bidirectional I/O lines (B), internal flip-flop outputs (Q), and Complement Array output ( $\bar{C}$ ). The Complement Array consists of a NOR gate optionally linked to all AND gates for generating and propagating complementary AND terms.

### FEATURES

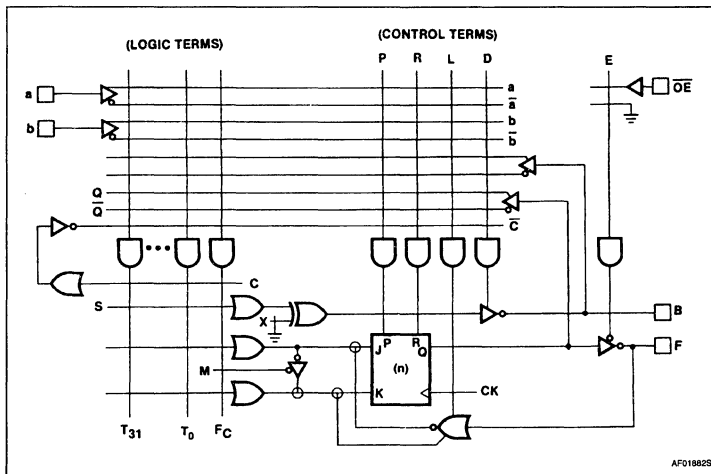
- High-speed version of PLS159
- $f_{MAX} = 18\text{MHz}$ 
  - 25MHz clock rate
- Field-Programmable (Ni-Cr link)
- 4 dedicated inputs
- 13 control gates
- 32 AND gates
- 21 OR gates
- 45 product terms:
  - 32 logic terms
  - 13 control terms
- 4 bidirectional I/O lines
- 8 bidirectional registers
- J-K, T, or D-type flip-flops
- Power-on reset feature on all flip-flops ( $F_n = 1$ )
- Asynchronous Preset/Reset
- Complement Array
- Active-High or -Low outputs
- Programmable  $\bar{O}E$  control
- Positive edge-triggered clock
- Input loading:  $-100\mu\text{A}$  (max.)
- Power dissipation: 750mW (typ.)
- TTL compatible
- 3-State outputs

### PIN CONFIGURATIONS



5

### FUNCTIONAL DIAGRAM



### APPLICATIONS

- Random sequential logic
- Synchronous up/down counters
- Shift registers
- Bidirectional data buffers
- Timing function generators
- System controllers/synchronizers
- Priority encoder/registers

# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS159A

On-chip T/C buffers couple either True (I, B, Q) or Complement (Ī, B̄, Q̄, C̄) input polarities to all AND gates, whose outputs can be optionally linked to all OR gates. One group of AND gates drives bidirectional I/O lines (B), whose output polarity is individually programmable through a set of Ex-OR gates for implementing AND-OR or AND-NOR logic functions. Another group drives the J-K inputs of all flip-flops, as well as asynchronous Preset and Reset lines (P, R).

All flip-flops are positive edge-triggered and can be used as input, output or I/O (for interfacing with a bidirectional data bus) in conjunction with load control gates (L), steering inputs (I), (B), (Q) and programmable output select lines (E).

The PLS159A is field-programmable, enabling the user to quickly generate custom patterns using standard programming equipment.

### VIRGIN STATE

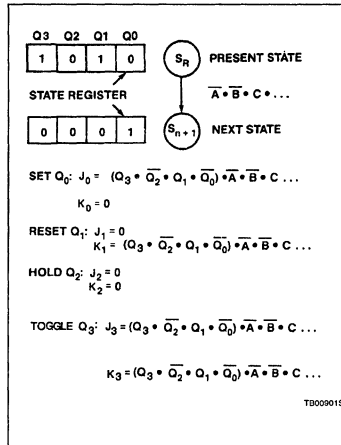
The factory shipped virgin device contains all fusible links intact, such that:

1.  $\overline{OE}$  is always enabled.
2. Preset and Reset are always disabled.
3. All transition terms are disabled.
4. All flip-flops are in D-mode unless otherwise programmed to J-K only or J-K or D (controlled).
5. All B pins are inputs and all F pins are outputs unless otherwise programmed.

### CAUTION: PLS159A PROGRAMMING ALGORITHM

The programming voltage required to program the PLS159A is higher (17.5V) than that required to program the PLS159 (14.5V). Consequently, the PLS159 programming algorithm will not program the PLS159A. Please exercise caution when accessing programmer device codes to insure that the correct algorithm is used.

### LOGIC FUNCTION



**NOTE:** Similar logic functions are applicable for D and T mode flip-flops.

### FLIP-FLOP TRUTH TABLE

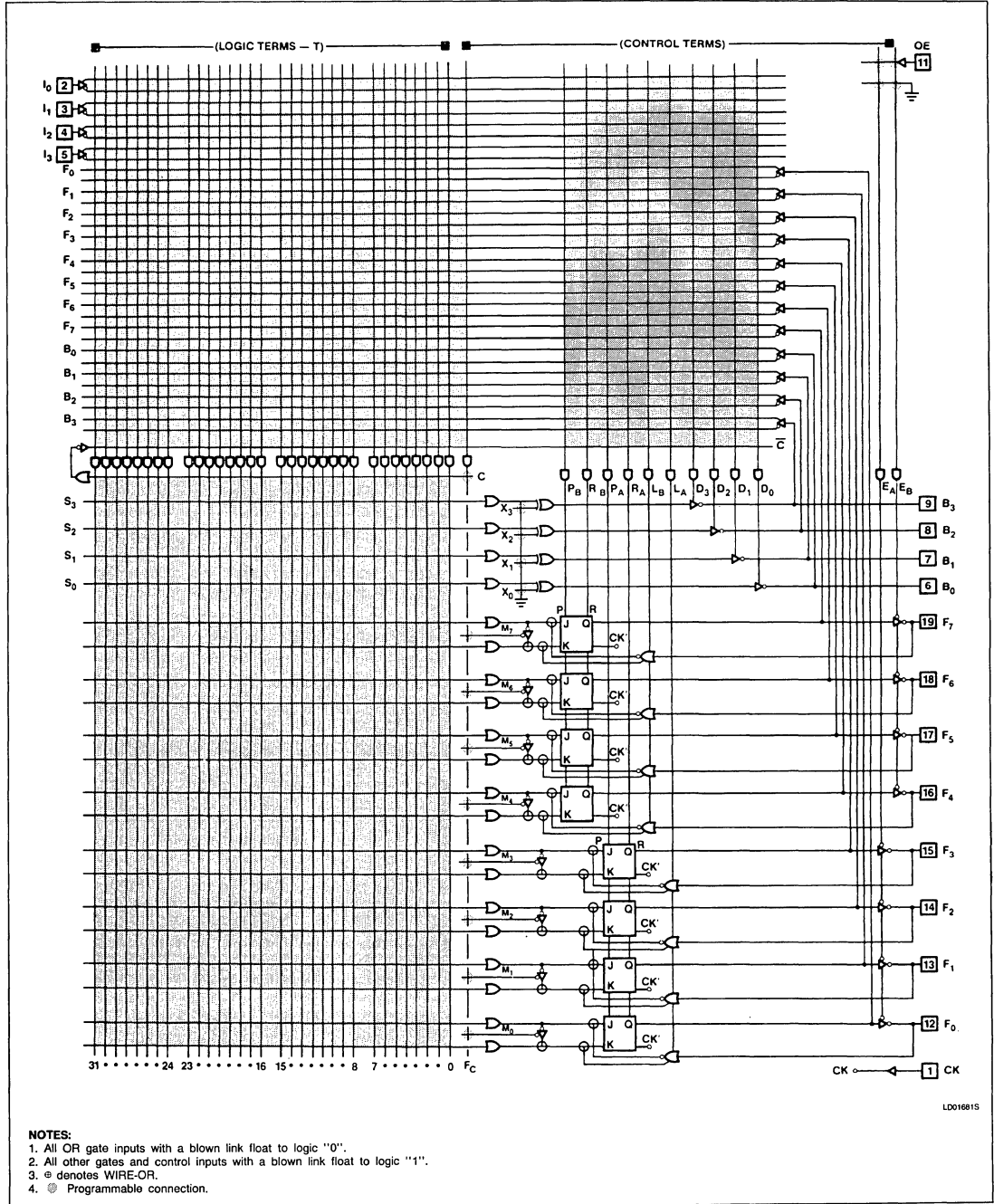
$\overline{OE}$	L	C	P	R	J	K	Q	F
H								HI-Z
L	X	X	L	X	X	X	L	H
L	X	X	H	L	X	X	H	L
L	X	X	L	H	X	X	L	H
L	L	↑	L	L	L	L	Q	$\overline{Q}$
L	L	↑	L	L	L	H	L	H
L	L	↑	L	L	H	L	H	L
L	L	↑	L	L	H	H	L	Q
H	H	↑	L	L	L	H	L	H*
H	H	↑	L	L	H	L	H	L*
+10V	X	↑	X	X	L	H	L	H**
	X	↑	X	X	H	L	H	L**

- NOTES:**
1. Positive Logic:  
 $J \cdot K = T_0 + T_1 + T_2 \dots T_{31}$   
 $T_n = \overline{C} \cdot (I_0 \cdot I_1 \cdot I_2 \dots) \cdot (Q_0 \cdot Q_1 \dots) \cdot (B_0 \cdot B_1 \dots)$
  2. ↑ denotes transition from Low to High level.
  3. X = Don't Care
  4. \* = Forced at  $F_n$  pin for loading J-K flip-flop in I/O mode. L must be enabled, and other active  $T_n$  disabled via steering input(s) I, B, or Q.
  5. At  $P = R = H$ ,  $Q = H$ . The final state of Q depends on which is released first.
  6. \*\* = Forced at  $F_n$  pin to load J-K flip-flop independent of program code (Diagnostic mode), 3-State B outputs.

# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS159A

## FPLS LOGIC DIAGRAM



5

**NOTES:**

1. All OR gate inputs with a blown link float to logic "0".
2. All other gates and control inputs with a blown link float to logic "1".
3. ⊕ denotes WIRE-OR.
4. ● Programmable connection.

LD01681S

## Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS159A

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
20-pin Plastic DIP 300mil-wide	PLS159AN
20-pin Plastic Leaded Chip Carrier	PLS159AA

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at those or any other condition above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ 75°C, 4.75V ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IH</sub>	High	V <sub>CC</sub> = Max	2			V
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min			0.8	V
V <sub>IC</sub>	Clamp	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA		-0.8	-1.2	V
<b>Output voltage<sup>2</sup></b>						
V <sub>OH</sub>	High	V <sub>CC</sub> = Min, I <sub>OH</sub> = -2mA	2.4			V
V <sub>OL</sub>	Low	I <sub>OL</sub> = 10mA		0.35	0.5	V
<b>Input current</b>						
I <sub>IH</sub>	High	V <sub>CC</sub> = Max, V <sub>IN</sub> = 5.5V		< 1	40	μA
I <sub>IL</sub>	Low	V <sub>IN</sub> = 0.45V		-10	-100	μA
<b>Output current</b>						
I <sub>O(OFF)</sub>	Hi-Z state <sup>4, 7</sup>	V <sub>CC</sub> = Max, V <sub>OUT</sub> = 5.5V		1	80	μA
I <sub>OS</sub>	Short circuit <sup>3, 5</sup>	V <sub>OUT</sub> = 0.45V	-15	-1	-140	μA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>6</sup>	V <sub>OUT</sub> = 0V			-70	mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>6</sup>	V <sub>CC</sub> = Max		150	190	mA
<b>Capacitance</b>						
C <sub>IN</sub>	Input	V <sub>CC</sub> = 5.0V, V <sub>IN</sub> = 2.0V		8		pF
C <sub>OUT</sub>	Output	V <sub>OUT</sub> = 2.0V		15		pF

## NOTES:

- All typical values are at V<sub>CC</sub> = 5V, T<sub>A</sub> = +25°C.
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- Measured with V<sub>IH</sub> applied to  $\overline{OE}$ .
- Duration of short circuit should not exceed 1 second.
- I<sub>CC</sub> is measured with the  $\overline{OE}$  input grounded, all other inputs at 4.5V, and the outputs open.
- Leakage values are a combination of input and output leakage.

# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS159A

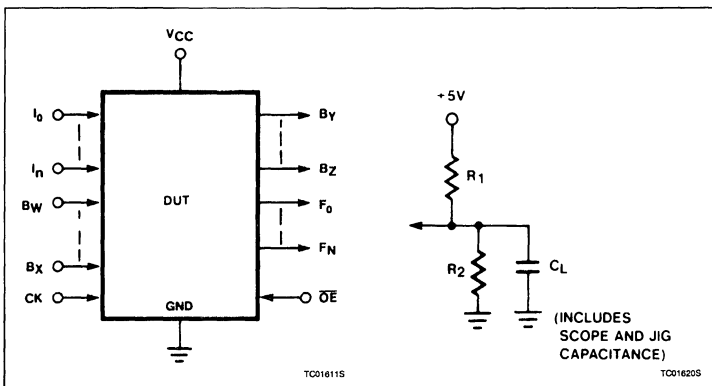
## AC ELECTRICAL CHARACTERISTICS $R_1 = 470\Omega$ , $R_2 = 1k\Omega$ , $0^\circ C \leq T_A \leq +75^\circ C$ , $4.75V \leq V_{CC} \leq 5.25V$

SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min <sup>5</sup>	Typ <sup>1</sup>	Max	
<b>Pulse width</b>								
$t_{CKH}$	Clock <sup>2</sup> High	CK -	CK +	$C_L = 30pF$	20	15		ns
$t_{CKL}$	Clock Low	CK +	CK -	$C_L = 30pF$	20	15		
$t_{CKP}$	Period	CK +	CK +	$C_L = 30pF$	55	45		
$t_{PRH}$	Preset/Reset pulse	(I, B) +	(I, B) -	$C_L = 30pF$	35	30		
<b>Setup time</b>								
$t_{S1}$	Input	CK +	(I, B) $\pm$	$C_L = 30pF$	35	30		ns
$t_{S2}$	Input (through $F_n$ )	CK +	F $\pm$	$C_L = 30pF$	15	10		
$t_{S3}$	Input (through Complement Array) <sup>4</sup>	CK +	(I, B) $\pm$	$C_L = 30pF$	55	45		
<b>Hold time</b>								
$t_{H1}$	Input	CK +	(I, B) $\pm$	$C_L = 30pF$	0	-5		ns
$t_{H2}$	Input (through $F_n$ )	CK +	F $\pm$	$C_L = 30pF$	15	10		
<b>Propagation delay</b>								
$t_{CKO}$	Clock	F $\pm$	CK +	$C_L = 30pF$		15	20	ns
$t_{OE1}$	Output enable	F -	$\overline{OE}$ -	$C_L = 30pF$		20	30	
$t_{OD1}$	Output disable <sup>3</sup>	F +	$\overline{OE}$ +	$C_L = 5pF$		20	30	
$t_{PD}$	Output	B $\pm$	(I, B) $\pm$	$C_L = 30pF$		25	35	
$t_{OE2}$	Output enable	B $\pm$	(I, B) +	$C_L = 30pF$		20	30	
$t_{OD2}$	Output disable <sup>3</sup>	B +	(I, B) -	$C_L = 5pF$		20	30	
$t_{PRO}$	Preset/Reset	F $\pm$	(I, B) +	$C_L = 30pF$		35	45	
$t_{PPR}$	Power-on/preset	F -	$V_{CC}$ +	$C_L = 30pF$		0	10	

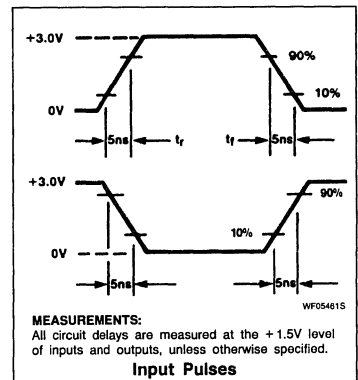
**NOTES:**

1. All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
2. To prevent spurious clocking, clock rise time (10% - 90%)  $\leq 10ns$ .
3. Measured at  $V_T = V_{OL} + 0.5V$ .
4. When using the Complement Array  $T_{CKP} = 75ns$  (min).
5. Limits are guaranteed with 12 product terms maximum connected to each sum term line.

**TEST LOAD CIRCUITS**



**VOLTAGE WAVEFORMS**

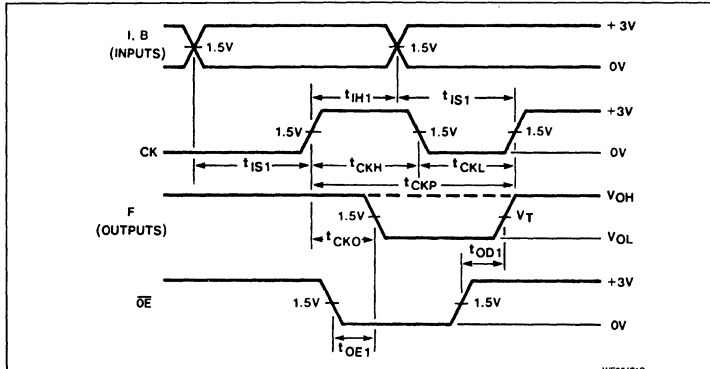




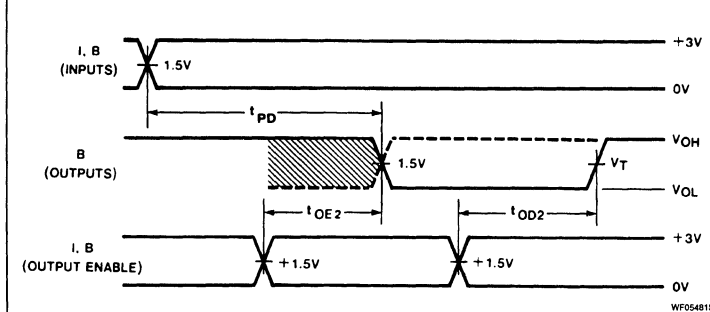
# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS159A

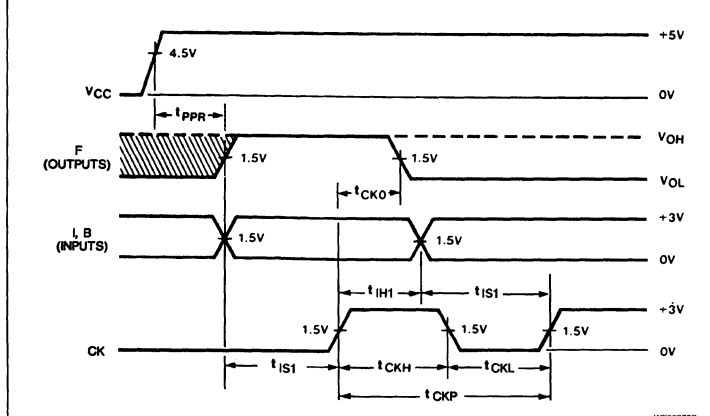
## TIMING DIAGRAMS



Flip-Flop Outputs



Gate Outputs



Power-On Reset

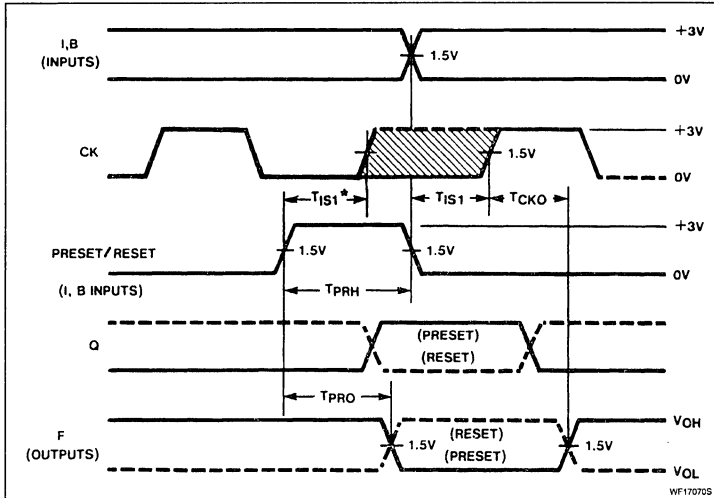
## TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{CKH}$	Width of input clock pulse.
$t_{CKL}$	Interval between clock pulses.
$t_{CKP}$	Clock period.
$t_{PRH}$	Width of preset input pulse.
$t_{IS1}$	Required delay between beginning of valid input data and positive transition of clock.
$t_{IS2}$	Required delay between beginning of valid input forced at flip-flop output pins, and positive transition of clock.
$t_{IH1}$	Required delay between positive transition of clock and end of valid input data.
$t_{IH2}$	Required delay between positive transition of clock and end of valid input data forced at flip-flop output pins.
$t_{CKO}$	Delay between positive transition of clock and when outputs become valid (with OE Low).
$t_{OE1}$	Delay between beginning of Output Enable Low and when outputs become valid.
$t_{OD1}$	Delay between beginning of Output Enable High and when outputs are in the OFF-state.
$t_{PPR}$	Delay between $V_{CC}$ (after power-on) and when flip-flop outputs become preset at "1" (internal Q outputs at "0").
$t_{PD}$	Propagation delay between combinational inputs and outputs.
$t_{OE2}$	Delay between predefined Output Enable High, and when combinational outputs become valid.
$t_{OD2}$	Delay between predefined Output Enable Low and when combinational outputs are in the OFF-state.
$t_{PRO}$	Delay between positive transition of predefined Preset/Reset input, and when flip-flop outputs become valid.

# Field-Programmable Logic Sequencer (16 × 45 × 12)

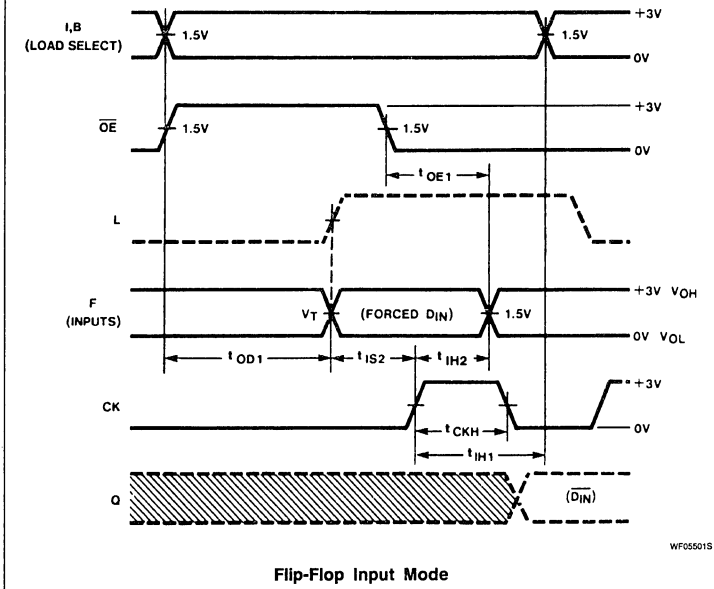
PLS159A

## TIMING DIAGRAMS (Continued)



\* Preset and Reset functions override Clock. However, F outputs may glitch with the first positive Clock Edge if  $T_{IS1}$  cannot be guaranteed by the user.

### Asynchronous Preset/Reset



### Flip-Flop Input Mode

5

# Field-Programmable Logic Sequencer (16 × 45 × 12)

# PLS159A

## LOGIC PROGRAMMING

PLS159A logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

PLS159A logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

### "AND" ARRAY — (I), (B), (Qp)

<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1"> <thead> <tr> <th>STATE</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>INACTIVE<sup>1, 2</sup></td> <td>O</td> </tr> </tbody> </table> <p>LS020325</p>	STATE	CODE	INACTIVE <sup>1, 2</sup>	O	<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1"> <thead> <tr> <th>STATE</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>I, B, Q</td> <td>H</td> </tr> </tbody> </table> <p>LS020405</p>	STATE	CODE	I, B, Q	H	<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1"> <thead> <tr> <th>STATE</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>I-bar, B-bar, Q-bar</td> <td>L</td> </tr> </tbody> </table> <p>LS020505</p>	STATE	CODE	I-bar, B-bar, Q-bar	L	<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1"> <thead> <tr> <th>STATE</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>DON'T CARE</td> <td>-</td> </tr> </tbody> </table> <p>LS020605</p>	STATE	CODE	DON'T CARE	-
STATE	CODE																		
INACTIVE <sup>1, 2</sup>	O																		
STATE	CODE																		
I, B, Q	H																		
STATE	CODE																		
I-bar, B-bar, Q-bar	L																		
STATE	CODE																		
DON'T CARE	-																		

### "COMPLEMENT" ARRAY — (C)

<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1"> <thead> <tr> <th>ACTION</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>INACTIVE<sup>1, 3, 5</sup></td> <td>O</td> </tr> </tbody> </table> <p>LS020725</p>	ACTION	CODE	INACTIVE <sup>1, 3, 5</sup>	O	<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1"> <thead> <tr> <th>ACTION</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>GENERATE<sup>5</sup></td> <td>A</td> </tr> </tbody> </table> <p>LS020805</p>	ACTION	CODE	GENERATE <sup>5</sup>	A	<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1"> <thead> <tr> <th>ACTION</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>PROPAGATE</td> <td>•</td> </tr> </tbody> </table> <p>LS020905</p>	ACTION	CODE	PROPAGATE	•	<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1"> <thead> <tr> <th>ACTION</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>TRANSPARENT</td> <td>-</td> </tr> </tbody> </table> <p>LS021005</p>	ACTION	CODE	TRANSPARENT	-
ACTION	CODE																		
INACTIVE <sup>1, 3, 5</sup>	O																		
ACTION	CODE																		
GENERATE <sup>5</sup>	A																		
ACTION	CODE																		
PROPAGATE	•																		
ACTION	CODE																		
TRANSPARENT	-																		

### "OR" ARRAY — (F-F CONTROL MODE)

<p>ENABLED</p> <table border="1"> <thead> <tr> <th>ACTION</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>J-K OR D (CONTROLLED)<sup>1</sup></td> <td>A</td> </tr> </tbody> </table> <p>LS021315</p>	ACTION	CODE	J-K OR D (CONTROLLED) <sup>1</sup>	A	<p>DISABLED</p> <table border="1"> <thead> <tr> <th>ACTION</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>J-K ONLY</td> <td>•</td> </tr> </tbody> </table> <p>LS021415</p>	ACTION	CODE	J-K ONLY	•
ACTION	CODE								
J-K OR D (CONTROLLED) <sup>1</sup>	A								
ACTION	CODE								
J-K ONLY	•								

### "OR" ARRAY — (Q<sub>n</sub> = D - Type)

<p>M = ENABLED</p> <table border="1"> <thead> <tr> <th>T<sub>n</sub> STATUS</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>ACTIVE (Set)<sup>1</sup></td> <td>A</td> </tr> </tbody> </table> <p>LS021515</p>	T <sub>n</sub> STATUS	CODE	ACTIVE (Set) <sup>1</sup>	A	<p>M = ENABLED</p> <table border="1"> <thead> <tr> <th>T<sub>n</sub> STATUS</th> <th>CODE</th> </tr> </thead> <tbody> <tr> <td>INACTIVE (Reset)</td> <td>•</td> </tr> </tbody> </table> <p>LS021605</p>	T <sub>n</sub> STATUS	CODE	INACTIVE (Reset)	•
T <sub>n</sub> STATUS	CODE								
ACTIVE (Set) <sup>1</sup>	A								
T <sub>n</sub> STATUS	CODE								
INACTIVE (Reset)	•								

**CAUTION:**

The PLS159A Programming Algorithm is different from the PLS159.

# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS159A

## "OR" ARRAY — (Q<sub>n</sub> = J - K Type)

<p style="text-align: center;"><math>M = \text{DISABLED}</math></p>	<p style="text-align: center;"><math>M = \text{DISABLED}</math></p>	<p style="text-align: center;"><math>M = \text{DISABLED}</math></p>	<p style="text-align: center;"><math>M = \text{DISABLED}</math></p>																
<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>TOGGLE</td><td>O</td></tr> </table> <p style="text-align: center; font-size: small;">LS02170S</p>	ACTION	CODE	TOGGLE	O	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>SET</td><td>H</td></tr> </table> <p style="text-align: center; font-size: small;">LS02190S</p>	ACTION	CODE	SET	H	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>RESET</td><td>L</td></tr> </table> <p style="text-align: center; font-size: small;">LS02190S</p>	ACTION	CODE	RESET	L	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>HOLD</td><td>-</td></tr> </table> <p style="text-align: center; font-size: small;">LS02200S</p>	ACTION	CODE	HOLD	-
ACTION	CODE																		
TOGGLE	O																		
ACTION	CODE																		
SET	H																		
ACTION	CODE																		
RESET	L																		
ACTION	CODE																		
HOLD	-																		

## "OR" ARRAY — (S or B)

<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>T<sub>n</sub> STATUS</th><th>CODE</th></tr> <tr><td>ACTIVE<sup>1</sup></td><td>A</td></tr> </table> <p style="text-align: center; font-size: small;">LS02211S</p>	T <sub>n</sub> STATUS	CODE	ACTIVE <sup>1</sup>	A	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>T<sub>n</sub> STATUS</th><th>CODE</th></tr> <tr><td>INACTIVE</td><td>•</td></tr> </table> <p style="text-align: center; font-size: small;">LS02221S</p>	T <sub>n</sub> STATUS	CODE	INACTIVE	•
T <sub>n</sub> STATUS	CODE								
ACTIVE <sup>1</sup>	A								
T <sub>n</sub> STATUS	CODE								
INACTIVE	•								

## "EX-OR" ARRAY — (B)

<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>POLARITY</th><th>CODE</th></tr> <tr><td>LOW</td><td>L</td></tr> </table> <p style="text-align: center; font-size: small;">LS02230S</p>	POLARITY	CODE	LOW	L	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>POLARITY</th><th>CODE</th></tr> <tr><td>HIGH</td><td>H</td></tr> </table> <p style="text-align: center; font-size: small;">LS02240S</p>	POLARITY	CODE	HIGH	H
POLARITY	CODE								
LOW	L								
POLARITY	CODE								
HIGH	H								

## "OE" ARRAY — (E)

<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>IDLE<sup>1, 4</sup></td><td>O</td></tr> </table> <p style="text-align: center; font-size: small;">LS02252S</p>	ACTION	CODE	IDLE <sup>1, 4</sup>	O	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>CONTROL</td><td>A</td></tr> </table> <p style="text-align: center; font-size: small;">LS02260S</p>	ACTION	CODE	CONTROL	A	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>ENABLE<sup>4</sup></td><td>•</td></tr> </table> <p style="text-align: center; font-size: small;">LS02270S</p>	ACTION	CODE	ENABLE <sup>4</sup>	•	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>DISABLE</td><td>-</td></tr> </table> <p style="text-align: center; font-size: small;">LS02290S</p>	ACTION	CODE	DISABLE	-
ACTION	CODE																		
IDLE <sup>1, 4</sup>	O																		
ACTION	CODE																		
CONTROL	A																		
ACTION	CODE																		
ENABLE <sup>4</sup>	•																		
ACTION	CODE																		
DISABLE	-																		

**NOTES:**

1. This is the initial unprogrammed state of all link pairs. It is normally associated with all unused (inactive) AND gates.
2. Any gate (T, F<sub>C</sub>, L, P, R, D)<sub>n</sub> will be unconditionally inhibited if both of the I, B, or Q links are left intact.
3. To prevent oscillations, this state is not allowed for C link, pairs coupled to active gates T<sub>n</sub>, F<sub>C</sub>.
4. E<sub>n</sub> = O and E<sub>n</sub> = • are logically equivalent states, since both cause F<sub>n</sub> outputs to be unconditionally enabled.
5. These states are not allowed for control gates (L, P, R, D)<sub>n</sub> due to their lack of "OR" array links.

5

# Field-Programmable Logic Sequencer (16 × 45 × 12)

PLS159A

## FPLS PROGRAM TABLE

AND		OR		CONTROL		<b>NOTES</b> 1. The FPLS is shipped with all links intact. Thus a background of entries corresponding to states of virgin links exists in the table, shown BLANK for clarity. 2. Program unused C, I, B, and Q bits in the AND array as (-). Program unused Q, B, P, and R bits in the OR array as (-) or (A), as applicable. 3. Unused Terms can be left blank. 4. Q (P) and Q (N) are respectively the present and next states of flip-flops Q.																							
INACTIVE <input type="checkbox"/> O I, B, Q <input type="checkbox"/> H I, B, Q <input type="checkbox"/> L DON'T CARE <input type="checkbox"/> -	I, B (I), Q (P)	ACTIVE <input type="checkbox"/> A INACTIVE <input type="checkbox"/> -	P, R, B (O), (Q = D)	J/K <input type="checkbox"/> * J/K or D (controlled) <input type="checkbox"/> A	FIF MODE		IDLE <input type="checkbox"/> O CONTROL <input type="checkbox"/> A ENABLE <input type="checkbox"/> * DISABLE <input type="checkbox"/> -																						
INACTIVE <input type="checkbox"/> O GENERATE <input type="checkbox"/> A PROPAGATE <input type="checkbox"/> * TRANSPARENT <input type="checkbox"/> -	C	TOGGLE <input type="checkbox"/> O SET <input type="checkbox"/> H RESET <input type="checkbox"/> L HOLD <input type="checkbox"/> -	(Q = J/K)	HIGH <input type="checkbox"/> H LOW <input type="checkbox"/> L	(POL.)	E <sub>B</sub>   E <sub>A</sub>   POLARITY																							
THIS PORTION TO BE COMPLETED BY SIGNETICS  CF (XXXX) _____ CUSTOMER SYMBOLIZED PART # _____ DATE RECEIVED _____ COMMENTS _____		T E R M C'	<b>AND</b>												<b>(OR)</b>														
		0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 F <sub>C</sub> P <sub>B</sub> R <sub>B</sub> L <sub>B</sub> P <sub>A</sub> R <sub>A</sub> L <sub>A</sub> D <sub>3</sub> D <sub>2</sub> D <sub>1</sub> D <sub>0</sub> P <sub>W</sub>	I 3 2 1 0	B(I) 3 2 1 0	Q (P) 7 6 5 4 3 2 1 0	Q (N) 7 6 5 4 3 2 1 0	B(O) 3 2 1 0																						
		5	4	3	2	9	8	7	6	19	18	17	16	15	14	13	12												

TB012915

# PLS167

## Field-Programmable Logic Sequencer (14 × 48 × 6)

Signetics Programmable Logic  
Product Specification

Application Specific Products  
• Series 24

### DESCRIPTION

The PLS167 is a bipolar, programmable state machine of the Mealy type. The Field Programmable Logic Sequencer (FPLS) contains logic AND-OR gate arrays with user programmable connections which control the inputs of on-chip State and Output Registers. These consist respectively of 8  $Q_p$ , and 4  $Q_f$  edge-triggered, clocked S/R flip-flops, with an asynchronous preset option.

All flip-flops are unconditionally preset to "1" during power turn-on.

The AND Array combines 14 external inputs,  $I_0-13$ , with 8 internal inputs,  $P_0-7$ , fed back from the State Register to form up to 48 transition terms (AND terms). In addition,  $P_0$  and  $P_1$  of the internal State Register are brought off-chip to allow extending the Output Register to 6 bits, if so desired.

All transition terms can include True, False, or Don't Care states of the controlling variables, and are merged in the OR Array to issue next-state and next-output commands to their respective registers on the Low-to-High transition of the Clock pulse.

Both True and Complement transition terms can be generated by optional use of the internal variable (C) from the Complement Array. Also, if desired, the Preset input can be converted to Output-

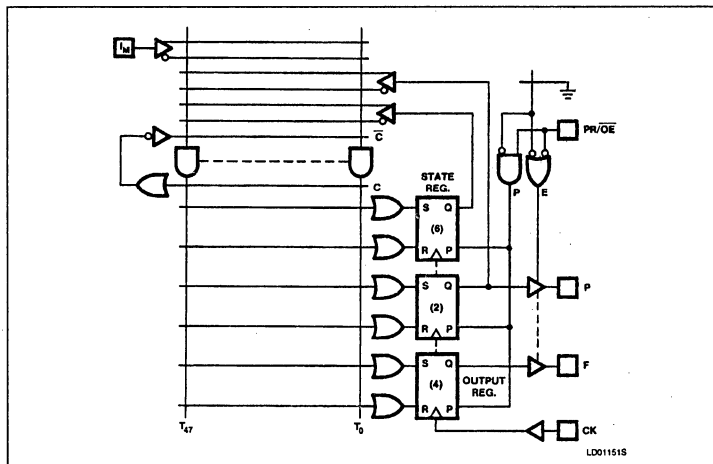
Enable function, as an additional user programmable option.

Order codes are listed in the Ordering Information Table.

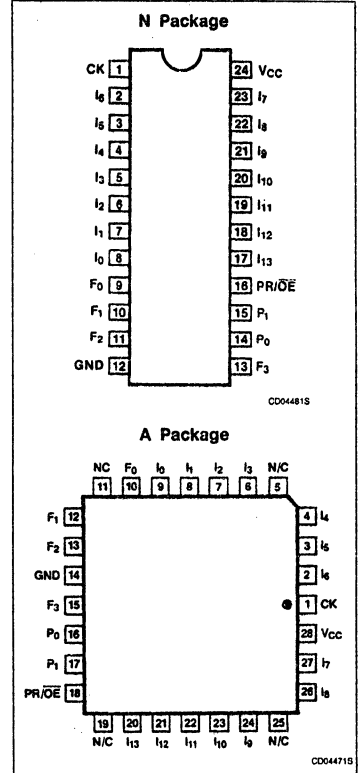
### FEATURES

- $f_{MAX}$ : 13.9MHz
- 20MHz clock rate
- Field-Programmable (Ni-Cr link)
- 14 True/Complement buffered Inputs
- 48 programmable AND gates
- 25 programmable OR gates
- 8-bit State Register
- 2-bit shared State/Output Register
- 4-bit Output Register
- Transition Complement Array
- Programmable Asynchronous Preset/Output Enable
- Positive edge-triggered clock
- Power-on preset to logic "1" of all registers
- Automatic logic "HOLD" state via S/R flip-flops
- On-chip Test Array
- Power: 600mW (typ.)
- TTL compatible
- 3-State outputs
- Single +5V supply
- 300mil-wide 24-pin DIP

### FUNCTIONAL DIAGRAM



### PIN CONFIGURATIONS



### APPLICATIONS

- Interface protocols
- Sequence detectors
- Peripheral controllers
- Timing generators
- Sequential circuits
- Security locking systems

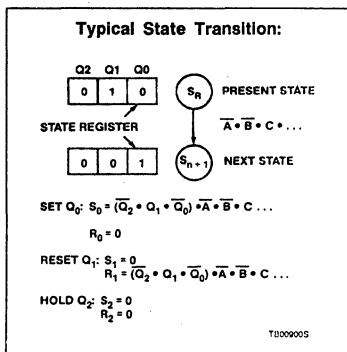
# Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167

## PIN DESCRIPTION

PIN NO.	SYMBOL	NAME AND FUNCTION	POLARITY
1	CK	<b>Clock:</b> The Clock input to the State and Output Registers. A Low-to-High transition on this line is necessary to update the contents of both registers.	Active-High
2-7 17-23	I <sub>1-13</sub>	<b>Logic Inputs:</b> The 13 external inputs to the AND array used to program jump conditions between machine states, as determined by a given logic sequence.	Active-High/Low
8	I <sub>0</sub>	<b>Logic/Diagnostic Input:</b> A 14th external logic input to the AND array, as above, when exercised with standard TTL levels. When I <sub>0</sub> is held at +10V, device outputs F <sub>0-3</sub> and P <sub>0-1</sub> reflect the contents of State Register bits P <sub>2-7</sub> (see Diagnostic Output Mode diagram). The contents of flip-flops P <sub>0-1</sub> and F <sub>0-3</sub> remain unaltered.	Active-High/Low
9-11 13	F <sub>0-3</sub>	<b>Logic/Diagnostic Outputs:</b> Four device outputs which normally reflect the contents of Output Register bits Q <sub>0-3</sub> , when enabled. When I <sub>0</sub> is held at +10V, F <sub>0-3</sub> = (P <sub>2-5</sub> ).	Active-High
14-15	P <sub>0-1</sub>	<b>Logic/Diagnostic Outputs:</b> Two register bits with shared function as least significant State Register bits, or most significant Output Register bits. When I <sub>0</sub> is held at +10V, P <sub>0-1</sub> = (P <sub>6-7</sub> ).	Active-High
16	PR/ $\overline{OE}$	<b>Preset or Output Enable Input:</b> A user programmable function: • <b>Preset:</b> Provides an asynchronous preset to logic "1" of all State and Output Register bits. Preset overrides Clock, and when held High, clocking is inhibited and P <sub>0-1</sub> and F <sub>0-3</sub> are High. Normal clocking resumes with the first full clock pulse following a High-to-Low clock transition, after Preset goes Low. • <b>Output Enable:</b> Provides an Output Enable function to all output buffers.	Active-High (H)  Active-Low (L)

## LOGIC FUNCTION



## TRUTH TABLE 1, 2, 3, 4, 5, 6

V <sub>cc</sub>	OPTION		I <sub>0</sub>	CK	S	R	Q <sub>P/F</sub>	F	
	PR	$\overline{OE}$							
+5V	H		*	X	X	X	H	H	
	L		+10V	X	X	X	Q <sub>n</sub>	(Q <sub>P</sub> ) <sub>n</sub>	
	L		X	X	X	X	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>	
		H	*	X	X	X	Q <sub>n</sub>	Hi-Z	
		L	+10V	X	X	X	Q <sub>n</sub>	(Q <sub>P</sub> ) <sub>n</sub>	
		L	X	X	X	X	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>	
		L	X	↑	L	L	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>	
		L	X	↑	L	H	L	L	
		L	X	↑	H	L	H	H	
		L	X	↑	H	H	IND.	IND.	
	↑	X	X	X	X	X	X	H	

### NOTES:

- Positive Logic:  
 $S/R = T_0 + T_1 + T_2 + \dots + T_{47}$   
 $T_n = C(I_0 I_1 I_2 \dots) (P_0 P_1 \dots P_7)$
- Either Preset (Active-High) or Output Enable (Active-Low) are available, but not both. The desired function is a user programmable option.
- ↑ denotes transition from Low to High level.
- R = S = High is an illegal input condition.
- \* = H/L/+10V
- X = Don't Care ( $\leq 5.5V$ )

## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

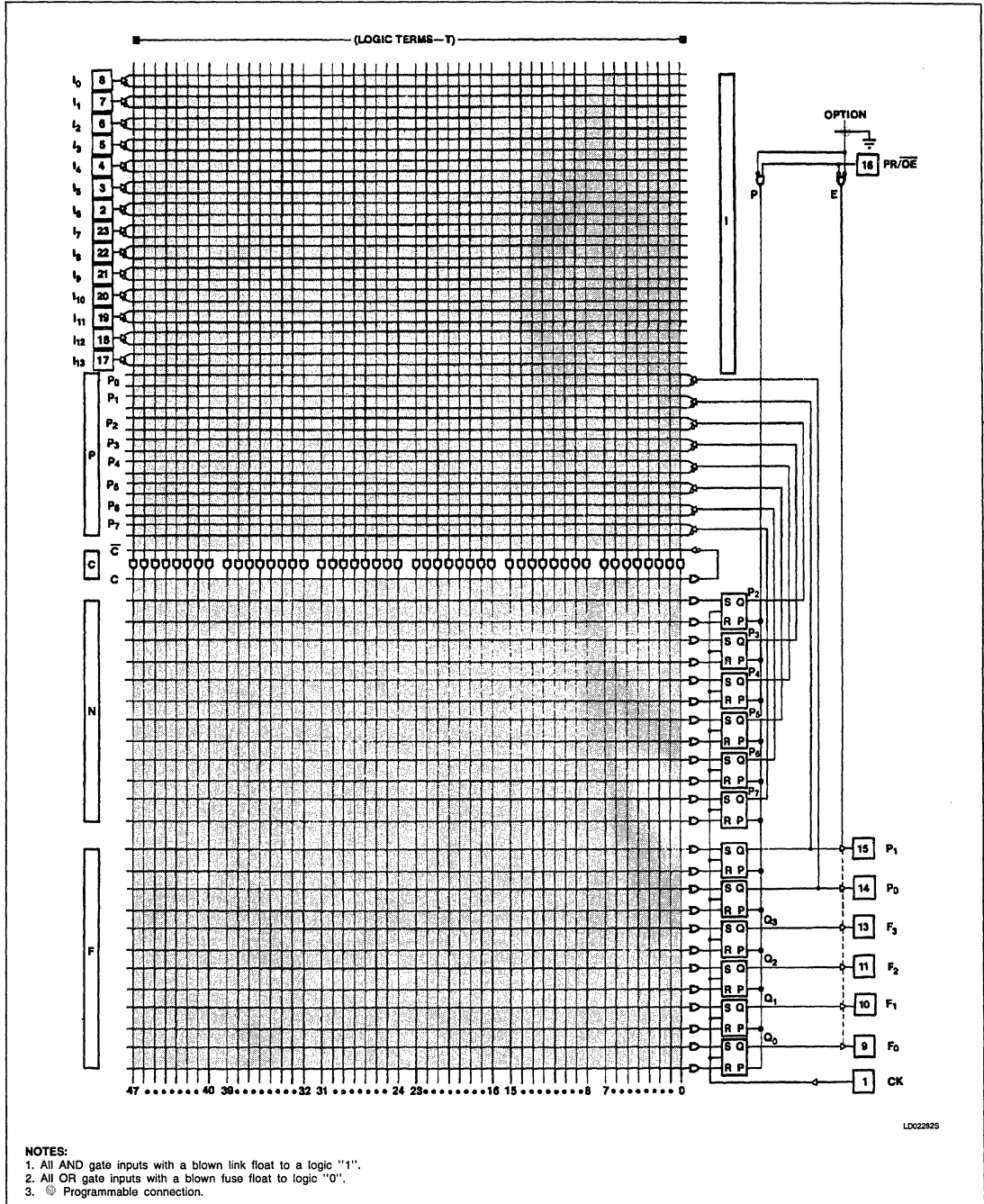
- PR/ $\overline{OE}$  option is set to PR. Thus, all outputs will be at "1", as preset by initial power-up procedure.
- All transition terms are disabled (0).
- All S/R flip-flop inputs are disabled (0).
- The device can be clocked via a Test Array pre-programmed with a standard test pattern.

NOTE: The Test Array pattern MUST be deleted before incorporating a user program. This is accomplished automatically by any Signetics qualified programming equipment.

# Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167

## FPLS LOGIC DIAGRAM



5



## Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
24-pin Plastic DIP 300mil-wide	PLS167N
28-pin Plastic Leaded Chip Carrier	PLS167A

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

## Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167

**DC ELECTRICAL CHARACTERISTICS** 0°C ≤ T<sub>A</sub> ≤ 75°C, 4.75V ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IH</sub>	High	V <sub>CC</sub> = Max	2			V
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min			0.8	V
V <sub>IC</sub>	Clamp <sup>3</sup>	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA		-0.8	-1.2	V
<b>Output voltage<sup>2</sup></b>						
V <sub>OH</sub>	High <sup>4</sup>	V <sub>CC</sub> = Min	2.4			V
V <sub>OL</sub>	Low <sup>5</sup>	I <sub>OH</sub> = -2mA I <sub>OL</sub> = 9.6mA		0.35	0.45	V
<b>Input current</b>						
I <sub>IH</sub>	High	V <sub>IN</sub> = 5.5V		< 1	25	μA
I <sub>IL</sub>	Low	V <sub>IN</sub> = 0.45V		-10	-100	μA
I <sub>IL</sub>	Low (CK input)	V <sub>IN</sub> = 0.45V		-50	-250	μA
<b>Output current</b>						
I <sub>O(OFF)</sub>	Hi-Z state <sup>6</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V		1	40	μA
I <sub>OS</sub>	Short circuit <sup>3, 7</sup>	V <sub>OUT</sub> = 0.45V V <sub>OUT</sub> = 0V	-15	-1	-40 -70	μA mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>8</sup>	V <sub>CC</sub> = Max		120	180	mA
<b>Capacitance<sup>6</sup></b>						
C <sub>IN</sub>	Input	V <sub>CC</sub> = 5.0V V <sub>IN</sub> = 2.0V		8		pF
C <sub>OUT</sub>	Output	V <sub>OUT</sub> = 2.0V		10		pF

**NOTES:**

- All typical values are at V<sub>CC</sub> = 5V, T<sub>A</sub> = +25°C.
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- Measured with V<sub>IL</sub> applied to  $\overline{OE}$  and a logic high stored, or with V<sub>IH</sub> applied to PR.
- Measured with a programmed logic condition for which the output is at a low logic level, and V<sub>IL</sub> applied to PR/ $\overline{OE}$ . Output sink current is supplied through a resistor to V<sub>CC</sub>.
- Measured with V<sub>IH</sub> applied to PR/ $\overline{OE}$ .
- Duration of short circuit should not exceed 1 second.
- I<sub>CC</sub> is measured with the PR/ $\overline{OE}$  input grounded, all other inputs at 4.5V and the outputs open.

5

## Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167

**AC ELECTRICAL CHARACTERISTICS**  $R_1 = 470\Omega$ ,  $R_2 = 1k\Omega$ ,  $C_L = 30pF$ ,  $0^\circ C \leq T_A \leq +75^\circ C$ ,  $4.75V \leq V_{CC} \leq 5.25V$ 

SYMBOL	PARAMETER	TO	FROM	LIMITS			UNIT
				Min	Typ <sup>1</sup>	Max	
<b>Pulse width<sup>3</sup></b>							
$t_{CKH}$	Clock <sup>2</sup> High	CK -	CK +	25	15		ns
$t_{CKL}$	Clock Low	CK +	CK -	25	15		
$t_{CKP1B}$	Period (without Complement Array)	CK +	CK +	80	40		
$t_{CKP2B}$	Period (with Complement Array)	CK +	CK +	120	60		
$t_{PRH}$	Preset pulse	PR -	PR +	25	15		
<b>Setup time<sup>3</sup></b>							
$t_{S1A}$	Input	CK +	Input ±	60			ns
$t_{S1B}$	Input	CK +	Input ±	50			
$t_{S1C}$	Input	CK +	Input ±	42			
$t_{S2A}$	Input (through Complement Array)	CK +	Input ±	90			
$t_{S2B}$	Input (through Complement Array)	CK +	Input	80			
$t_{S2C}$	Input (through Complement Array)	CK +	Input	72			
$t_{VS}$	Power-on preset	CK -	$V_{CC} +$	0	-10		
$t_{PRS}$	Preset	CK -	PR -	0	-10		
<b>Hold time</b>							
$t_{IH}$	Input	Input ±	CK +	5	-10		ns
<b>Propagation delay</b>							
$t_{CKO}$	Clock	Output ±	CK +		15	30	ns
$t_{OE}$	Output enable	Output -	OE -		20	30	
$t_{OD}$	Output disable	Output +	OE +		20	30	
$t_{PR}$	Preset	Output +	PR +		18	30	
$t_{PPR}$	Power-on preset	Output +	$V_{CC} +$		0	10	
<b>Frequency of operation<sup>3</sup></b>							
$f_{MAXC}$	Without Complement Array					13.9	MHz
$f_{MAXC}$	With Complement Array					9.8	

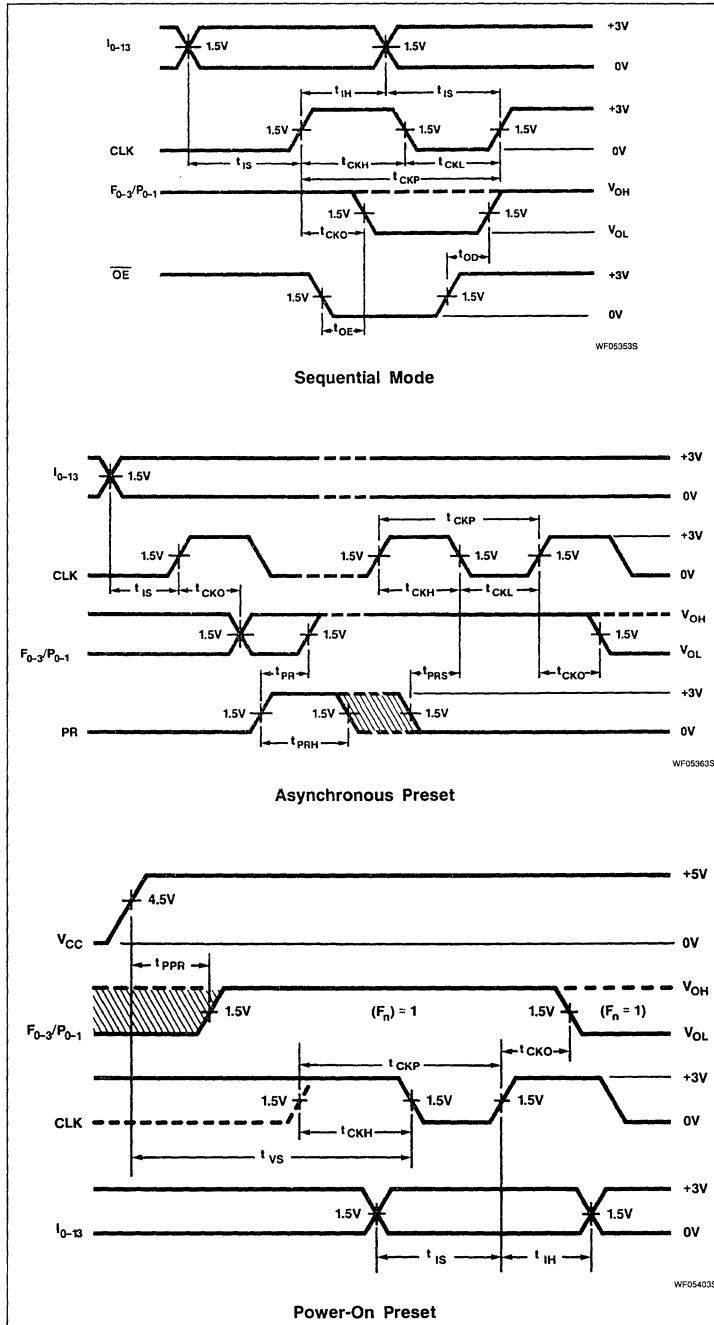
**NOTES:**

1. All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
2. To prevent spurious clocking, clock rise time (10% - 90%)  $\leq 30ns$ .
3. See "Speed vs. OR Loading" diagrams.

# Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167

## TIMING DIAGRAMS



## TIMING DEFINITIONS

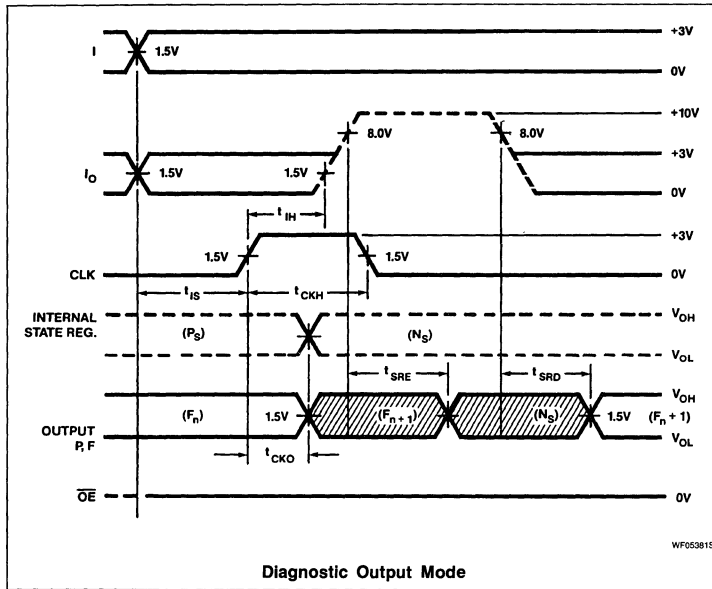
SYMBOL	PARAMETER
$t_{CKH}$	Width of input clock pulse.
$t_{CKL}$	Interval between clock pulses.
$t_{CKP1}$	Clock period – when not using Complement array.
$t_{IS1}$	Required delay between beginning of valid input and positive transition of clock.
$t_{CKP2}$	Clock period – when using complement array.
$t_{IS2}$	Required delay between beginning of valid input and positive transition of clock, when using optional Complement Array (two passes necessary through the AND array).
$t_{VS}$	Required delay between $V_{CC}$ (after power-on) and negative transition of clock preceding first reliable clock pulse.
$t_{PRS}$	Required delay between negative transition of asynchronous Preset and negative transition of clock preceding first reliable clock pulse.
$t_{IH}$	Required delay between positive transition of clock and end of valid Input data.
$t_{CKO}$	Delay between positive transition of clock and when Outputs become valid (with PR/OE Low).
$t_{OE}$	Delay between beginning of Output Enable Low and when Outputs become valid.
$t_{OD}$	Delay between beginning of Output Enable High and when Outputs are in the OFF-state.
$t_{SRE}$	Delay between input $I_0$ transition to Diagnostic mode and when the Outputs reflect the contents of the State Register.
$t_{SRD}$	Delay between input $I_0$ transition to Logic mode and when the Outputs reflect the contents of the Output Register.
$t_{PR}$	Delay between positive transition of Preset and when Outputs become valid at "1".
$t_{PPR}$	Delay between $V_{CC}$ (after power-on) and when Outputs become preset at "1".
$t_{PRH}$	Width of preset input pulse.
$f_{MAX}$	Maximum clock frequency.

5

# Field-Programmable Logic Sequencer (14 × 48 × 6)

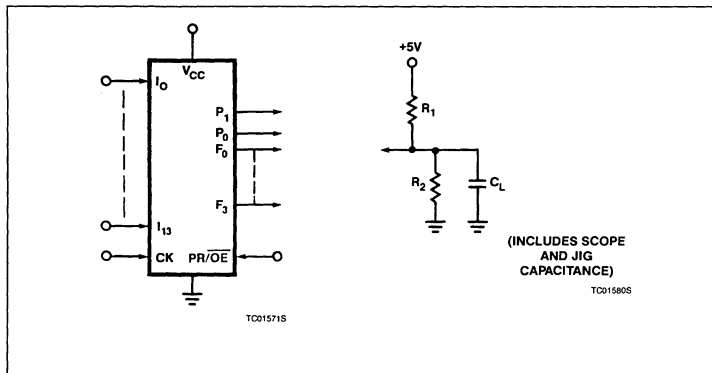
PLS167

## TIMING DIAGRAMS (Continued)



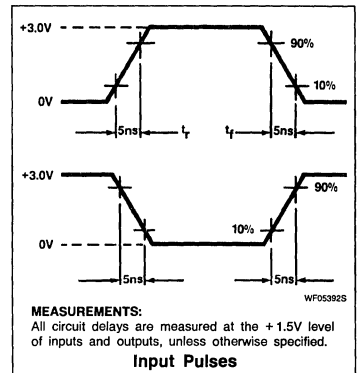
Diagnostic Output Mode

## TEST LOAD CIRCUITS



(INCLUDES SCOPE AND JIG CAPACITANCE)

## VOLTAGE WAVEFORMS



### MEASUREMENTS:

All circuit delays are measured at the +1.5V level of inputs and outputs, unless otherwise specified.

### Input Pulses

# Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167

## SPEED VS. "OR" LOADING

The maximum frequency at which the FPLS can be clocked while operating in *sequential mode* is given by:

$$(1/f_{MAX}) = t_{CY} = t_{IS} + t_{CKO}$$

This frequency depends on the number of transition terms  $T_n$  used. Having all 48 terms connected in the AND array does not appreciably impact performance; but the number of terms connected to each OR line affects  $t_{IS}$ , due to capacitive loading. The effect of this loading can be seen in Figure 1, showing the variation of  $t_{IS1}$  with the number of terms connected per OR.

The AC electrical characteristics contain three limits for the parameters  $t_{IS1}$  and  $t_{IS2}$ . The first,  $t_{IS1A}$  is guaranteed for a device with 48 terms connected to any OR line.  $t_{IS1B}$  is guaranteed for a device with 32 terms connected to any OR line.  $t_{IS1C}$  is guaranteed for a device with 24 terms connected to any OR line.

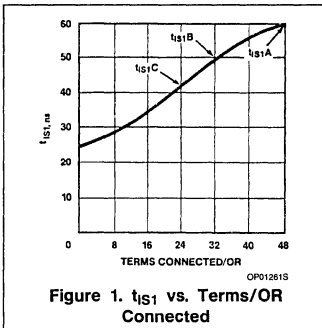


Figure 1.  $t_{IS1}$  vs. Terms/OR Connected

The Three other entries in the AC table,  $t_{IS2}$  A, B, and C are corresponding 48, 32, and 24 term limits when using the on-chip Complement Array.

The worst case  $t_{IS}$  for a given application can be determined by identifying the OR line with the maximum number of  $T_n$  connections. This can be done by referring to

the interconnect pattern in the FPLS logic diagram, typically illustrated in Figure 2, or by counting the maximum number of "H" or "L" entries in one of the columns of the device Program Table.

This number plotted on the curve in Figure 1 will yield the worst case  $t_{IS}$  and, by implication, the maximum clocking frequency for reliable operation.

*Note that for maximum speed all UNUSED transition terms should be disconnected from the OR array.*

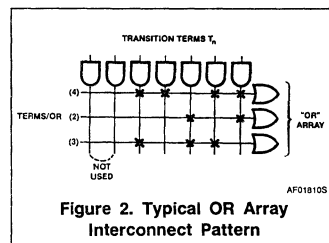


Figure 2. Typical OR Array Interconnect Pattern

5

# Field-Programmable Logic Sequencer (14 × 48 × 6)

# PLS167

## LOGIC PROGRAMMING

PLS167 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

PLS167 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

### "AND" ARRAY - (I), (P)

<p style="text-align: center;">LS018145</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>OPTION</th><th>CODE</th></tr> </thead> <tbody> <tr><td>PRESET<sup>1</sup></td><td>H</td></tr> </tbody> </table>	OPTION	CODE	PRESET <sup>1</sup>	H	<p style="text-align: center;">LS018255</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>OPTION</th><th>CODE</th></tr> </thead> <tbody> <tr><td>OE</td><td>L</td></tr> </tbody> </table>	OPTION	CODE	OE	L	<p style="text-align: center;">LS018605</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>STATE</th><th>CODE</th></tr> </thead> <tbody> <tr><td>I, P</td><td>H</td></tr> </tbody> </table>	STATE	CODE	I, P	H	<p style="text-align: center;">LS018305</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>STATE</th><th>CODE</th></tr> </thead> <tbody> <tr><td>I-bar, P-bar</td><td>L</td></tr> </tbody> </table>	STATE	CODE	I-bar, P-bar	L	<p style="text-align: center;">LS018505</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>STATE</th><th>CODE</th></tr> </thead> <tbody> <tr><td>INACTIVE<sup>1,2</sup></td><td>O</td></tr> </tbody> </table>	STATE	CODE	INACTIVE <sup>1,2</sup>	O	<p style="text-align: center;">LS018405</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>STATE</th><th>CODE</th></tr> </thead> <tbody> <tr><td>DON'T CARE</td><td>-</td></tr> </tbody> </table>	STATE	CODE	DON'T CARE	-
OPTION	CODE																												
PRESET <sup>1</sup>	H																												
OPTION	CODE																												
OE	L																												
STATE	CODE																												
I, P	H																												
STATE	CODE																												
I-bar, P-bar	L																												
STATE	CODE																												
INACTIVE <sup>1,2</sup>	O																												
STATE	CODE																												
DON'T CARE	-																												

### PROGRAMMING:

The PLS167 has a power-up preset feature. This feature insures that the device will power-up in a known state with all register elements (state and output register) at a logic High (H). When programming the device it is important to realize this is the initial state of the device. You *must* provide a next state jump if you do not wish to use all Highs (H) as the present state.

### "OR" ARRAY - (N), (F)

<p style="text-align: center;">LS019005</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>ACTION</th><th>CODE</th></tr> </thead> <tbody> <tr><td>SET</td><td>H</td></tr> </tbody> </table>	ACTION	CODE	SET	H	<p style="text-align: center;">LS018705</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>ACTION</th><th>CODE</th></tr> </thead> <tbody> <tr><td>RESET</td><td>L</td></tr> </tbody> </table>	ACTION	CODE	RESET	L	<p style="text-align: center;">LS019005</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>ACTION</th><th>CODE</th></tr> </thead> <tbody> <tr><td>INACTIVE<sup>1,3</sup></td><td>O</td></tr> </tbody> </table>	ACTION	CODE	INACTIVE <sup>1,3</sup>	O	<p style="text-align: center;">LS018605</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>ACTION</th><th>CODE</th></tr> </thead> <tbody> <tr><td>NO CHANGE</td><td>-</td></tr> </tbody> </table>	ACTION	CODE	NO CHANGE	-
ACTION	CODE																		
SET	H																		
ACTION	CODE																		
RESET	L																		
ACTION	CODE																		
INACTIVE <sup>1,3</sup>	O																		
ACTION	CODE																		
NO CHANGE	-																		

### "COMPLEMENT" ARRAY - (C)

<p style="text-align: center;">LS019305</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>ACTION</th><th>CODE</th></tr> </thead> <tbody> <tr><td>INACTIVE<sup>1,4</sup></td><td>O</td></tr> </tbody> </table>	ACTION	CODE	INACTIVE <sup>1,4</sup>	O	<p style="text-align: center;">LS019405</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>ACTION</th><th>CODE</th></tr> </thead> <tbody> <tr><td>GENERATE</td><td>A</td></tr> </tbody> </table>	ACTION	CODE	GENERATE	A	<p style="text-align: center;">LS019105</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>ACTION</th><th>CODE</th></tr> </thead> <tbody> <tr><td>PROPAGATE</td><td>•</td></tr> </tbody> </table>	ACTION	CODE	PROPAGATE	•	<p style="text-align: center;">LS019205</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr><th>ACTION</th><th>CODE</th></tr> </thead> <tbody> <tr><td>TRANSPARENT</td><td>-</td></tr> </tbody> </table>	ACTION	CODE	TRANSPARENT	-
ACTION	CODE																		
INACTIVE <sup>1,4</sup>	O																		
ACTION	CODE																		
GENERATE	A																		
ACTION	CODE																		
PROPAGATE	•																		
ACTION	CODE																		
TRANSPARENT	-																		

### NOTES:

1. This is the initial unprogrammed state of all links.
2. Any gate T<sub>n</sub> will be unconditionally inhibited if both the true and complement of any input (I, P) are left intact.
3. To prevent simultaneous Set and Reset flip-flop commands, this state is not allowed for N and F link pairs coupled to active gates T<sub>n</sub> (see flip-flop truth tables).
4. To prevent oscillations, this state is not allowed for C link pairs coupled to active gates T<sub>n</sub>.





# Field-Programmable Logic Sequencer (14 × 48 × 6)

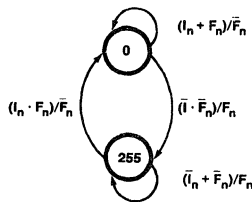
PLS167

## TEST ARRAY

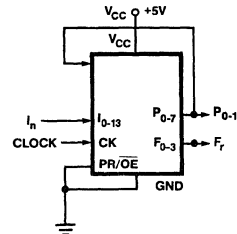
The FPLS may be subjected to AC and DC parametric tests prior to programming via an on-chip test array.

The array consists of test transition terms 48 and 49, factory programmed as shown below.

Testing is accomplished by clocking the FPLS and applying the proper input sequence to  $I_{0-13}$  as shown in the test circuit timing diagram.



State Diagram



FPLS Under Test

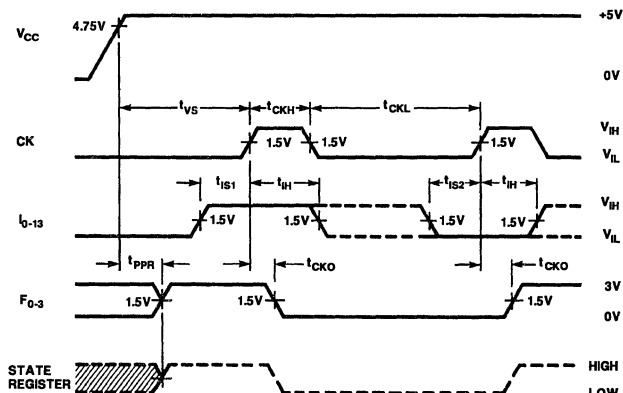
TERM	AND																						
	C	INPUT (I <sub>n</sub> )								PRESENT STATE (P <sub>n</sub> )													
48	A	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H
49	●	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L

OPTION (P/E)																H			
OR																			
NEXT STATE (N <sub>s</sub> )								OUTPUT (F <sub>r</sub> )											
7	6	5	4	3	2	1	0	3	2	1	0	7	6	5	4	3	2	1	0
L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L
H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H

Test Array Program

TB016005

Both terms 48 and 49 must be deleted during user programming to avoid interfering with the desired logic function. This is accomplished automatically by any of Signetics' qualified programming equipment.



Test Circuit Timing Diagram

WF053755

TERM	AND																					
	C	INPUT (I <sub>n</sub> )								PRESENT STATE (P <sub>n</sub> )												
48	—	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H
49	●	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L

OPTION (P/E)																H			
OR																			
NEXT STATE (N <sub>s</sub> )								OUTPUT (F <sub>r</sub> )											
7	6	5	4	3	2	1	0	3	2	1	0	7	6	5	4	3	2	1	0
—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—
—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—

Test Array Deleted

TR016105

## PLS167A

### Field-Programmable Logic Sequencer (14 × 48 × 6)

Signetics Programmable Logic  
Product Specification

Application Specific Products  
• Series 24

#### DESCRIPTION

The PLS167A is a bipolar, programmable state machine of the Mealy type. The Field-Programmable Logic Sequencer (FPLS) contains logic AND-OR gate arrays with user programmable connections which control the inputs of on-chip State and Output Registers. These consist respectively of 8  $Q_p$  and 4  $Q_f$  edge-triggered, clocked S/R flip-flops, with an Asynchronous Preset Option.

All flip-flops are unconditionally preset to "1" during power turn-on.

The AND array combines 14 external inputs,  $I_0$ - $I_{13}$ , with 8 internal inputs,  $P_0$ - $P_7$ , fed back from the State Register to form up to 48 transition terms (AND terms). In addition,  $P_0$  and  $P_1$  of the internal State Register are brought off-chip to allow extending the Output Register to 6 bits, if so desired.

All transition terms can include True, False, or Don't Care states of the controlling variables, and are merged in the OR array to issue next-state and next-output commands to their respective registers on the Low-to-High transition of the Clock pulse.

Both True and Complement transition terms can be generated by optional use of the internal variable (C) from the Complement Array. Also, if desired, the Preset input can be converted to output-

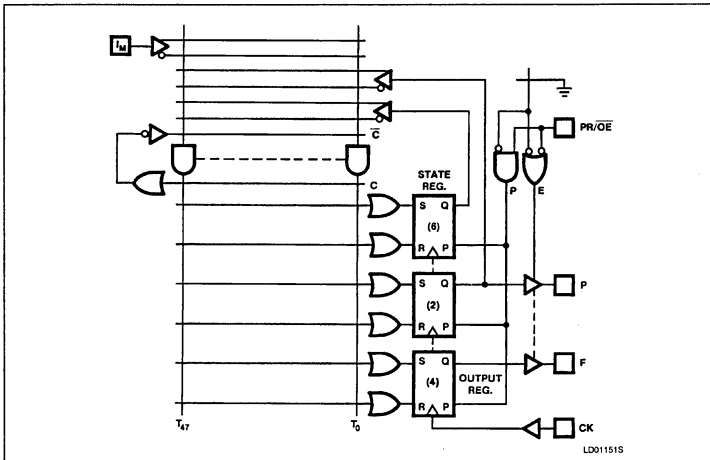
enable function, as an additional user programmable option.

Order codes are listed in the Ordering Information Table.

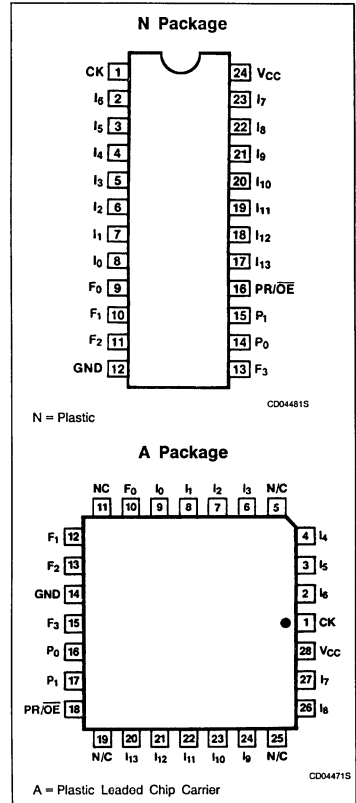
#### FEATURES

- $f_{MAX}$ : 20MHz  
- 25MHz clock rate
- Field-Programmable (Ni-Cr link)
- 14 True/Complement buffered inputs
- 48 programmable AND gates
- 25 programmable OR gates
- 8-bit State Register
- 2-bit shared State/Output Register
- 4-bit Output Register
- Transition Complement Array
- Programmable Asynchronous Preset/Output Enable
- Positive edge-triggered clock
- Power-on preset to logic "1" of all registers
- Automatic logic "HOLD" state via S/R flip-flops
- On-chip Test Array
- Power: 600mW (typ.)
- TTL compatible
- 3-State outputs
- Single +5V supply
- 300mil-wide 24-pin DIP

#### FUNCTIONAL DIAGRAM



#### PIN CONFIGURATIONS



#### APPLICATIONS

- Interface protocols
- Sequence detectors
- Peripheral controllers
- Timing generators
- Sequential circuits
- Security locking systems

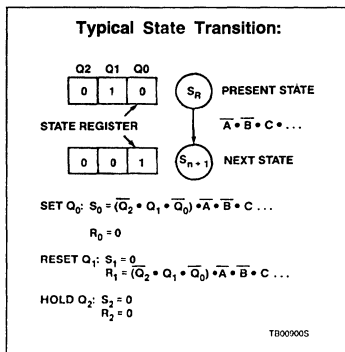
## Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167A

## PIN DESCRIPTION

PIN NO.	SYMBOL	NAME AND FUNCTION	POLARITY
1	CK	<b>Clock:</b> The Clock input to the State and Output Registers. A low-to-high transition on this line is necessary to update the contents of both registers.	Active-High
2-7 17-23	I <sub>1-13</sub>	<b>Logic Inputs:</b> The 13 external inputs to the AND array used to program jump conditions between machine states, as determined by a given logic sequence.	Active-High/Low
8	I <sub>0</sub>	<b>Logic/Diagnostic Input:</b> A 14th external logic input to the AND array, as above, when exercised with standard TTL levels. When I <sub>0</sub> is held at +10V, device outputs F <sub>0-3</sub> and P <sub>0-1</sub> reflect the contents of state register bits P <sub>2-7</sub> (see Diagnostic Output Mode diagram). The contents of flip-flops P <sub>0-1</sub> and F <sub>0-3</sub> remain unaltered.	Active-High/Low
9-11 13	F <sub>0-3</sub>	<b>Logic/Diagnostic Outputs:</b> Four device outputs which normally reflect the contents of Output Register bits Q <sub>0-3</sub> , when enabled. When I <sub>0</sub> is held at +10V, F <sub>0-3</sub> = (P <sub>2-5</sub> ).	Active-High
14-15	P <sub>0-1</sub>	<b>Logic/Diagnostic Outputs:</b> Two register bits with shared function as least significant State Register bits, or most significant Output Register bits. When I <sub>0</sub> is held at +10V, P <sub>0-1</sub> = (P <sub>6-7</sub> ).	Active-High
16	PR/ $\overline{OE}$	<b>Preset or Output Enable Input:</b> A user programmable function: <ul style="list-style-type: none"> <li><b>Preset:</b> Provides an Asynchronous Preset to logic "1" of all State and Output Register bits. Preset overrides Clock, and when held High, clocking is inhibited and P<sub>0-1</sub> and F<sub>0-3</sub> are High. Normal clocking resumes with the first full clock pulse following a High-to-Low clock transition, after Preset goes Low.</li> <li><b>Output Enable:</b> Provides an Output Enable function to all output buffers.</li> </ul>	Active High (H)  Active-Low (L)

## LOGIC FUNCTION



## TRUTH TABLE 1, 2, 3, 4, 5, 6

V <sub>CC</sub>	OPTION		I <sub>0</sub>	CK	S	R	Q <sub>P/F</sub>	F	
	PR	$\overline{OE}$							
+5V	H		*	X	X	X	H	H	
	L		+10V	X	X	X	Q <sub>n</sub>	(Q <sub>P</sub> ) <sub>n</sub>	
	L		X	X	X	X	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>	
		H	*	X	X	X	Q <sub>n</sub>	Hi-Z	
		L	+10V	X	X	X	Q <sub>n</sub>	(Q <sub>P</sub> ) <sub>n</sub>	
		L	X	X	X	X	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>	
		L	X	↑	L	L	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>	
		L	X	↑	L	H	L	L	
		L	X	↑	H	L	H	H	
		L	X	↑	H	H	IND.	IND.	
	↑	X	X	X	X	X	X	H	

## NOTES:

1. Positive Logic:

$$S/R = T_0 + T_1 + T_2 + \dots + T_{47}$$

$$T_n = C(I_0 I_1 I_2 \dots) (P_0 P_1 \dots P_7)$$

2. Either Preset (Active-High) or Output Enable (Active-Low) are available, but not both. The desired function is a user programmable option.

3. ↑ denotes transition from Low-to-High level.

4. R = S = High is an illegal input condition.

5. \* = H/L/+10V

6. X = Don't care (≤ 5.5V)

## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

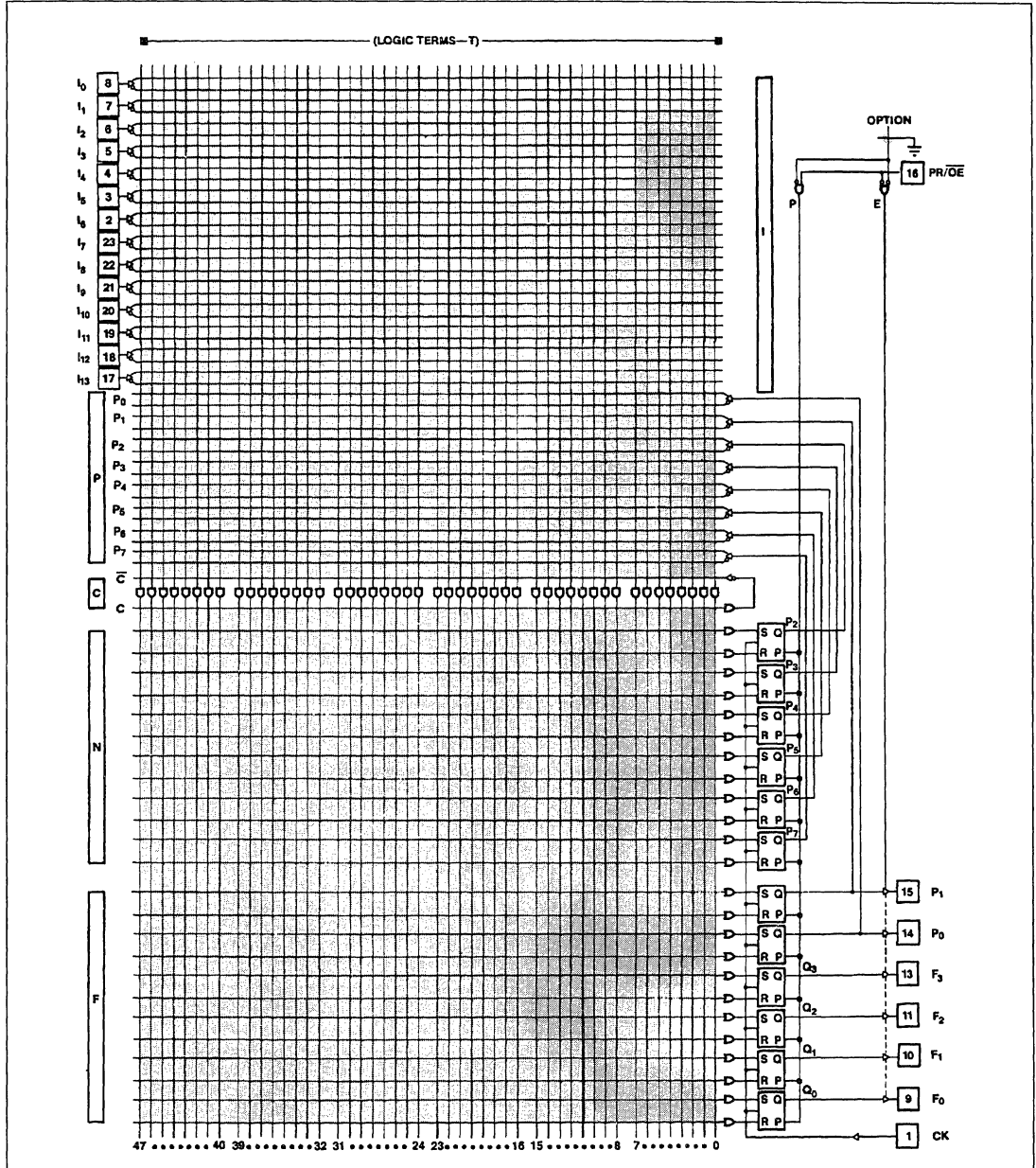
1. PR/ $\overline{OE}$  option is set to PR. Thus, all outputs will be at "1", as preset by initial power-up procedure.
2. All transition terms are disabled (0).
3. All S/R flip-flop inputs are disabled (0).
4. The device can be clocked via a Test Array pre-programmed with a standard test pattern.

NOTE: The Test Array pattern MUST be deleted before incorporating a user program. This is accomplished automatically by any Signetics qualified programming equipment.

# Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167A

## FPLS LOGIC DIAGRAM



5

**NOTES:**

1. All AND gate inputs with a blown link float to a logic "1".
2. All OR gate inputs with a blown link float to a logic "0".
3. ⊙ Programmable connection.

LD02282S

## Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167A

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
24-pin Plastic DIP 300mil-wide	PLS167AN
28-pin Plastic Leaded Chip Carrier	PLS167AA

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

## Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167A

DC ELECTRICAL CHARACTERISTICS  $0^{\circ}\text{C} \leq T_A \leq 75^{\circ}\text{C}$ ,  $4.75\text{V} \leq V_{\text{CC}} \leq 5.25\text{V}$ 

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
$V_{\text{IH}}$	High	$V_{\text{CC}} = \text{Max}$	2			V
$V_{\text{IL}}$	Low	$V_{\text{CC}} = \text{Min}$			0.8	V
$V_{\text{IC}}$	Clamp <sup>3</sup>	$V_{\text{CC}} = \text{Min}$ , $I_{\text{IN}} = -12\text{mA}$		-0.8	-1.2	V
<b>Output voltage<sup>2</sup></b>						
$V_{\text{OH}}$	High <sup>4</sup>	$V_{\text{CC}} = \text{Min}$	2.4			V
$V_{\text{OL}}$	Low <sup>5</sup>	$I_{\text{OH}} = -2\text{mA}$ $I_{\text{OL}} = 9.6\text{mA}$		0.35	0.45	V
<b>Input current</b>						
$I_{\text{IH}}$	High	$V_{\text{IN}} = 5.5\text{V}$		< 1	25	$\mu\text{A}$
$I_{\text{IL}}$	Low	$V_{\text{IN}} = 0.45\text{V}$		-10	-100	$\mu\text{A}$
$I_{\text{IL}}$	Low (CK input)	$V_{\text{IN}} = 0.45\text{V}$		-50	-250	$\mu\text{A}$
<b>Output current</b>						
$I_{\text{O(OFF)}}$	Hi-Z state <sup>6</sup>	$V_{\text{CC}} = \text{Max}$ $V_{\text{OUT}} = 5.5\text{V}$		1	40	$\mu\text{A}$
$I_{\text{OS}}$	Short circuit <sup>3, 7</sup>	$V_{\text{OUT}} = 0.45\text{V}$ $V_{\text{OUT}} = 0\text{V}$	-15	-1	-40 -70	$\mu\text{A}$ mA
$I_{\text{CC}}$	$V_{\text{CC}}$ supply current <sup>8</sup>	$V_{\text{CC}} = \text{Max}$		120	180	mA
<b>Capacitance<sup>6</sup></b>						
$C_{\text{IN}}$	Input	$V_{\text{CC}} = 5.0\text{V}$ $V_{\text{IN}} = 2.0\text{V}$		8		pF
$C_{\text{OUT}}$	Output	$V_{\text{OUT}} = 2.0\text{V}$		10		pF

## NOTES:

- All typical values are at  $V_{\text{CC}} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- Measured with  $V_{\text{IL}}$  applied to  $\overline{\text{OE}}$  and a logic high stored, or with  $V_{\text{IH}}$  applied to PR.
- Measured with a programmed logic condition for which the output is at a low logic level, and  $V_{\text{IL}}$  applied to PR/ $\overline{\text{OE}}$ . Output sink current is supplied through a resistor to  $V_{\text{CC}}$ .
- Measured with  $V_{\text{IH}}$  applied to PR/ $\overline{\text{OE}}$ .
- Duration of short circuit should not exceed 1 second.
- $I_{\text{CC}}$  is measured with the PR/ $\overline{\text{OE}}$  input grounded, all other inputs at 4.5V and the outputs open.

5

Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167A

**AC ELECTRICAL CHARACTERISTICS**  $R_1 = 470\Omega$ ,  $R_2 = 1k\Omega$ ,  $C_L = 30pF$ ,  $0^\circ C \leq T_A \leq +75^\circ C$ ,  $4.75V \leq V_{CC} \leq 5.25V$

SYMBOL	PARAMETER	TO	FROM	LIMITS			UNIT
				Min	Typ <sup>1</sup>	Max	
<b>Pulse width<sup>3</sup></b>							
t <sub>CKH</sub>	Clock <sup>2</sup> High	CK -	CK +	20	15		ns
t <sub>CKL</sub>	Clock Low	CK +	CK -	20	15		
t <sub>CKP1B</sub>	Period (without Complement Array)	CK +	CK +	50	40		
t <sub>CKP2B</sub>	Period (with Complement Array)	CK +	CK +	80	50		
t <sub>PRH</sub>	Preset pulse	PR -	PR +	25	15		
<b>Setup time<sup>3</sup></b>							
t <sub>IS1A</sub>	Input	CK +	Input ±	40			ns
t <sub>IS1B</sub>	Input	CK +	Input ±	30			
t <sub>IS2A</sub>	Input (through Complement Array)	CK +	Input ±	70			
t <sub>IS2B</sub>	Input (through Complement Array)	CK +	Input	60			
t <sub>VS</sub>	Power-on preset	CK -	V <sub>CC</sub> +	0	-10		
t <sub>PRS</sub>	Preset	CK -	PR -	0	-10		
<b>Hold time</b>							
t <sub>IH</sub>	Input	Input ±	CK +	5	-10		ns
<b>Propagation delay</b>							
t <sub>CKO</sub>	Clock	Output ±	CK +		15	20	ns
t <sub>OE</sub>	Output enable	Output -	OE -		20	30	
t <sub>OD</sub>	Output disable	Output +	OE +		20	30	
t <sub>PR</sub>	Preset	Output +	PR +		18	30	
t <sub>PPR</sub>	Power-on preset	Output +	V <sub>CC</sub> +		0	10	
<b>Frequency of operation<sup>3</sup></b>							
f <sub>MaxB</sub>	Without Complement Array					20.0	MHz
f <sub>MaxB</sub>	With Complement Array					12.5	

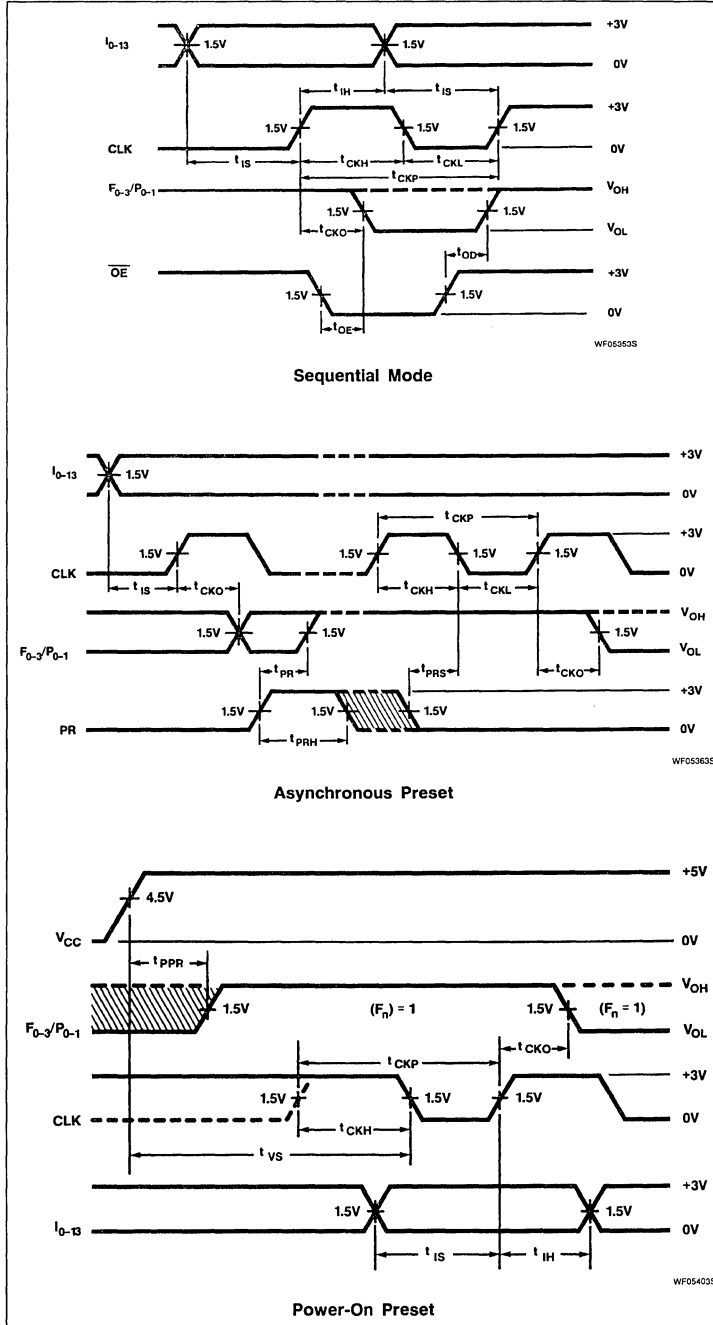
**NOTES:**

1. All typical values are at V<sub>CC</sub> = 5V, T<sub>A</sub> = +25°C.
2. To prevent spurious clocking, clock rise time (10% - 90%) ≤ 30ns.
3. See "Speed vs. OR Loading" diagrams.

# Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167A

## TIMING DIAGRAMS



## TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{CKH}$	Width of input clock pulse.
$t_{CKL}$	Interval between clock pulses.
$t_{CKP1}$	Clock period – when not using Complement array.
$t_{IS1}$	Required delay between beginning of valid input and positive transition of clock.
$t_{CKP2}$	Clock period – when using complement array.
$t_{IS2}$	Required delay between beginning of valid input and positive transition of clock, when using optional Complement Array (two passes necessary through the AND array).
$t_{VS}$	Required delay between $V_{CC}$ (after power-on) and negative transition of clock preceding first reliable clock pulse.
$t_{PRS}$	Required delay between negative transition of asynchronous Preset and negative transition of clock preceding first reliable clock pulse.
$t_{IH}$	Required delay between positive transition of clock and end of valid Input data.
$t_{CKO}$	Delay between positive transition of clock and when Outputs become valid (with PR/OE Low).
$t_{OE}$	Delay between beginning of Output Enable Low and when Outputs become valid.
$t_{OD}$	Delay between beginning of Output Enable High and when Outputs are in the OFF-state.
$t_{SRE}$	Delay between input $I_0$ transition to Diagnostic mode and when the Outputs reflect the contents of the State Register.
$t_{SRD}$	Delay between input $I_0$ transition to Logic mode and when the Outputs reflect the contents of the Output Register.
$t_{PR}$	Delay between positive transition of Preset and when Outputs become valid at "1".
$t_{PPR}$	Delay between $V_{CC}$ (after power-on) and when Outputs become preset at "1".
$t_{PRH}$	Width of preset input pulse.
$f_{MAX}$	Maximum clock frequency.

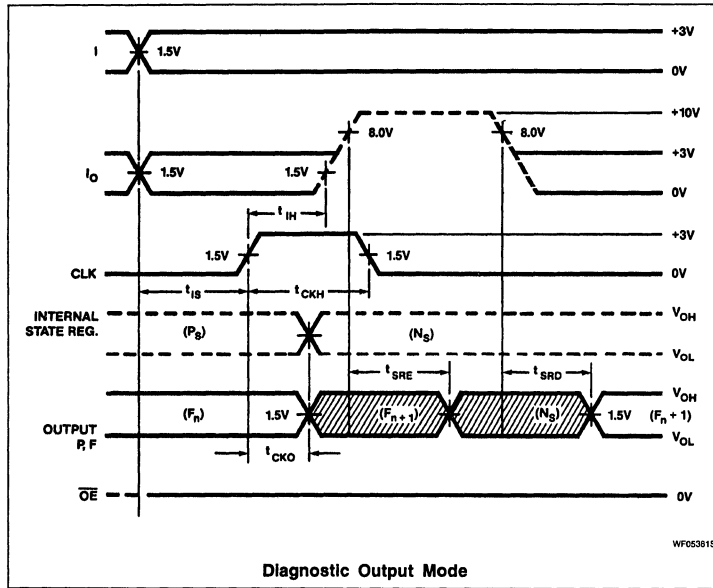
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# Field-Programmable Logic Sequencer (14 × 48 × 6)

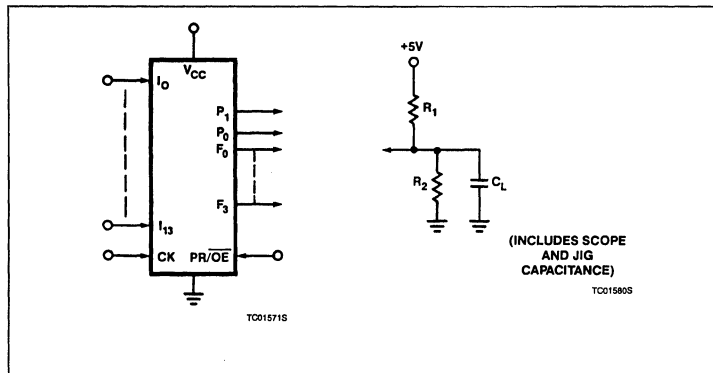
PLS167A

## TIMING DIAGRAMS (Continued)



Diagnostic Output Mode

## TEST LOAD CIRCUITS

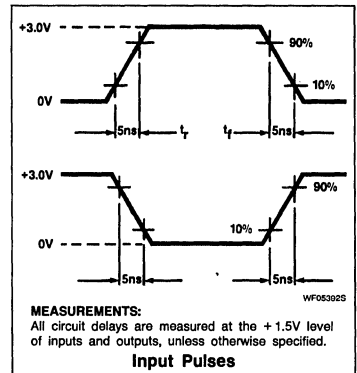


TC015715

(INCLUDES SCOPE AND JIG CAPACITANCE)

TC015905

## VOLTAGE WAVEFORMS



### MEASUREMENTS:

All circuit delays are measured at the +1.5V level of inputs and outputs, unless otherwise specified.

### Input Pulses

# Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167A

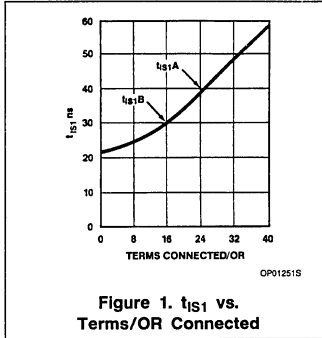
## SPEED VS. "OR" LOADING

The maximum frequency at which the FPLS can be clocked while operating in *sequential mode* is given by:

$$(1/f_{MAX}) = t_{CY} = t_{IS} + t_{CKO}$$

This frequency depends on the number of transition terms  $T_n$  used. Having all 48 terms connected in the AND array does not appreciably impact performance; but the number of terms connected to each OR line affects  $t_{IS}$ , due to capacitive loading. The effect of this loading can be seen in Figure 1, showing the variation of  $t_{IS1}$  with the number of terms connected per OR.

The AC electrical characteristics contain two limits for the parameters  $t_{IS1}$  and  $t_{IS2}$ . The first,  $t_{IS1A}$  is guaranteed for a device with 24 terms connected to any OR line.  $t_{IS1B}$  is guaranteed for a device with 16 terms connected to any OR line.



**Figure 1.  $t_{IS1}$  vs. Terms/OR Connected**

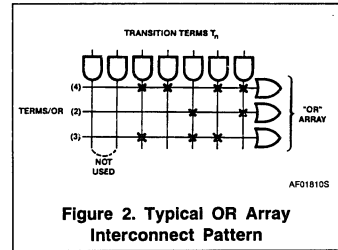
The three other entries in the AC table,  $t_{IS2}$  A and B are corresponding 24 and 16 term limits when using the on-chip Complement Array.

The worst case of  $t_{IS}$  for a given application can be determined by identifying the OR line with the maximum number of  $T_n$  connections. This can be done by referring to the interconnect pattern in the FPLS logic

diagram, typically illustrated in Figure 2, or by counting the maximum number of "H" or "L" entries in one of the columns of the device Program Table.

This number plotted on the curve in Figure 1 will yield the worst case  $t_{IS}$  and, by implication, the maximum clocking frequency for reliable operation.

*Note that for maximum speed all UNUSED transition terms should be disconnected from the OR array.*



**Figure 2. Typical OR Array Interconnect Pattern**

# Field-Programmable Logic Sequencer (14 × 48 × 6)

PLS167A

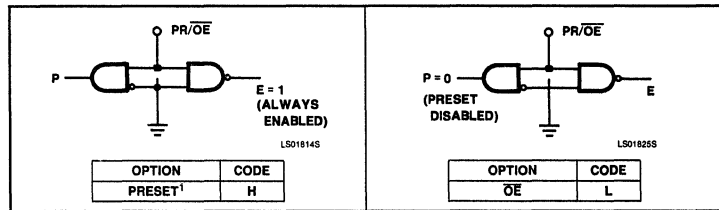
## LOGIC PROGRAMMING

PLS167A logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

PLS167A logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

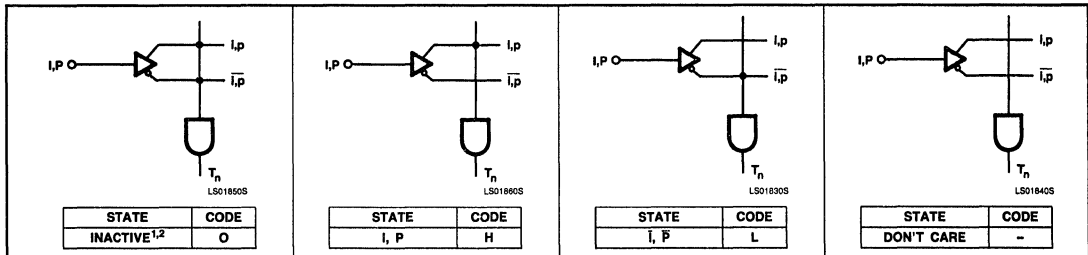
## PRESET/OE OPTION - (P/E)



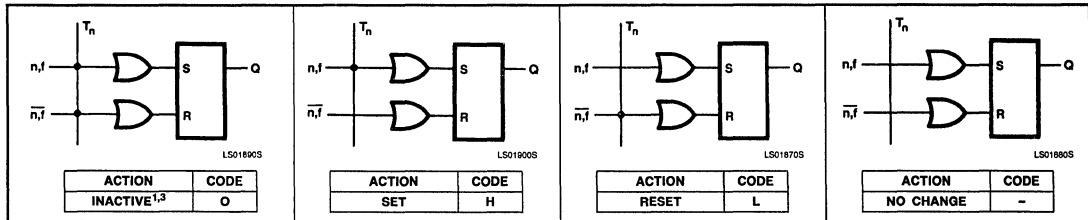
### PROGRAMMING:

The PLS167A has a power-up preset feature. This feature insures that the device will power-up in a known state with all register elements (state and output register) at a logic High (H). When programming the device it is important to realize this is the initial state of the device. You *must* provide a next state jump if you do not wish to use all Highs (H) as the present state.

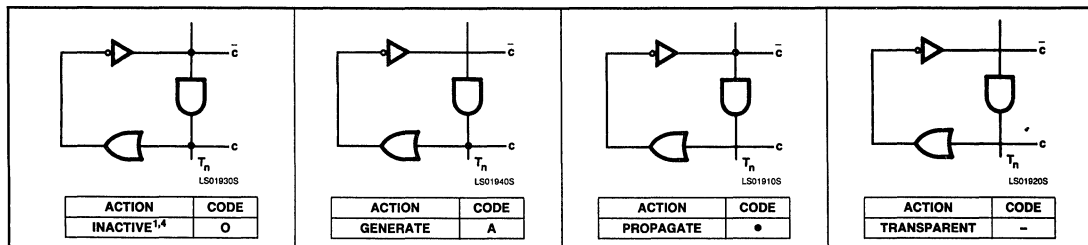
## "AND" ARRAY - (I), (P)



## "OR" ARRAY - (N), (F)



## "COMPLEMENT" ARRAY - (C)



### NOTES:

- This is the initial unprogrammed state of all links.
- Any gate  $T_n$  will be unconditionally inhibited if both the true and complement of any input (I, P) are left intact.
- To prevent simultaneous Set and Reset flip-flop commands, this state is not allowed for N and F link pairs coupled to active gates  $T_n$  (see flip-flop truth tables).
- To prevent oscillations, this state is not allowed for C link pairs coupled to active gates  $T_n$ .



# Field-Programmable Logic Sequencer (14 × 48 × 6)

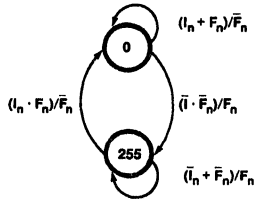
PLS167A

## TEST ARRAY

The FPLS may be subjected to AC and DC parametric tests prior to programming via an on-chip test array.

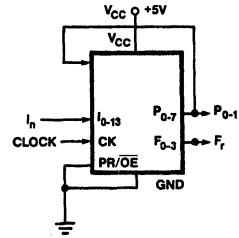
The array consists of test transition terms 48 and 49, factory programmed as shown below.

Testing is accomplished by clocking the FPLS and applying the proper input sequence to  $I_{0-13}$  as shown in the test circuit timing diagram.



State Diagram

AF018215



FPLS Under Test

TC015925

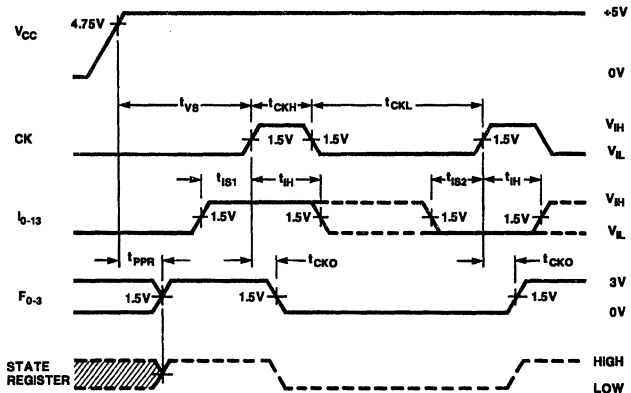
TERM	AND																						
	C	INPUT (I <sub>m</sub> )								PRESENT STATE (P <sub>n</sub> )													
		1	1	1	1	9	8	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
48	A	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H
49	●	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L

OPTION (P/E)																H
OR																
NEXT STATE (N <sub>n</sub> )								OUTPUT (F <sub>r</sub> )								
7	6	5	4	3	2	1	0	3	2	1	0	3	2	1	0	
L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	
H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	

Test Array Program

TB016005

Both terms 48 and 49 must be deleted during user programming to avoid interfering with the desired logic function. This is accomplished automatically by any of Signetics' qualified programming equipment.



Test Circuit Timing Diagram

WF053755

TERM	AND																						
	C	INPUT (I <sub>m</sub> )								PRESENT STATE (P <sub>n</sub> )													
		1	1	1	1	9	8	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
48	—	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H
49	●	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L

OPTION (P/E)																H
OR																
NEXT STATE (N <sub>n</sub> )								OUTPUT (F <sub>r</sub> )								
7	6	5	4	3	2	1	0	3	2	1	0	3	2	1	0	
—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	
—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	

Test Array Deleted

TB016105

# PLS168

## Field-Programmable Logic Sequencer (12 × 48 × 8)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

- Series 24

### DESCRIPTION

The PLS168 is a bipolar, programmable state machine of the Mealy type. It contains logic AND-OR gate arrays with user programmable connections which control the inputs of on-chip State and Output Registers. These consist respectively of 10 Q<sub>p</sub>, and 4 Q<sub>f</sub> edge-triggered, clocked S/R flip-flops, with an Asynchronous Preset option.

All flip-flops are unconditionally preset to "1" during power turn-on.

The AND array combines 12 external inputs, I<sub>0-11</sub>, with 10 internal inputs, P<sub>0-9</sub>, fed back from the State Register to form up to 48 transition terms (AND terms). In addition, P<sub>0-P3</sub> of the internal State Register are brought off-chip to allow extending the Output Register to 8 bits, if so desired.

All transition terms can include True, False, or Don't Care states of the controlling variables, and are merged in the OR array to issue next-state and next-output commands to their respective registers on the Low-to-High transition of the Clock pulse.

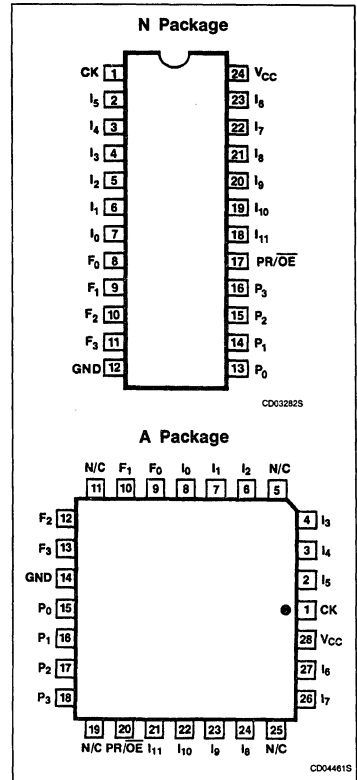
Both True and Complement transition terms can be generated by optional use of the internal variable (C) from the Complement Array. Also, if desired, the Preset input can be converted to output-enable function, as an additional user programmable option.

Order codes are listed in the Ordering Information Table.

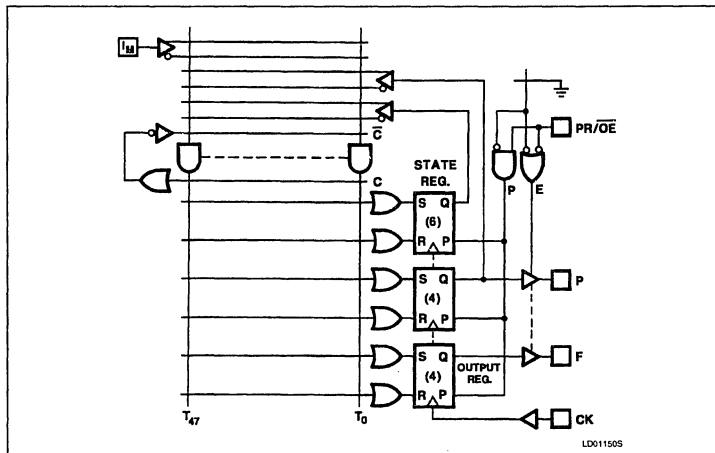
### FEATURES

- f<sub>MAX</sub>: 13.9MHz  
- 20MHz clock rate
- Field-Programmable (Ni-Cr link)
- 12 True/Complement buffered inputs
- 48 programmable AND gates
- 29 programmable OR gates
- 10-bit State Register
- 4-bit shared State/Output Register
- 4-bit Output Register
- Transition Complement Array
- Programmable Asynchronous Preset/Output Enable
- Positive edge-triggered clock
- Power-on preset to logic "1" of all registers
- Automatic logic "HOLD" state via S/R flip-flops
- On-chip Test Array
- Power: 600mW (typ.)
- TTL compatible
- 3-State outputs
- Single +5V supply
- 300mil-wide 24-pin DIP

### PIN CONFIGURATIONS



### FUNCTIONAL DIAGRAM



### APPLICATIONS

- Interface protocols
- Sequence detectors
- Peripheral controllers
- Timing generators
- Sequential circuits
- Elevator controllers
- Security locking systems
- Counters
- Shift registers

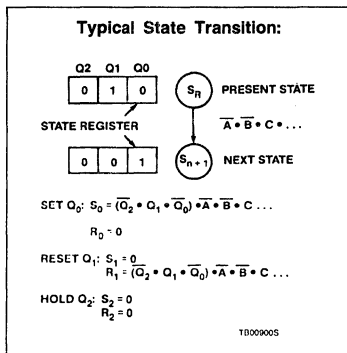
# Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168

## PIN DESCRIPTION

PIN NO.	SYMBOL	NAME AND FUNCTION	POLARITY
1	CK	<b>Clock:</b> The Clock input to the State and Output Registers. A Low-to-High transition on this line is necessary to update the contents of both registers.	Active-High
2-6 18-23	I <sub>1-11</sub>	<b>Logic Inputs:</b> The 11 external inputs to the AND array used to program jump conditions between machine states, as determined by a given logic sequence.	Active-High/Low
7	I <sub>0</sub>	<b>Logic/Diagnostic Input:</b> A 12th external logic input to the AND array, as above, when exercised with standard TTL levels. When I <sub>0</sub> is held at +10V, device outputs F <sub>2-3</sub> and P <sub>0-3</sub> reflect the contents of State Register bits P <sub>4-9</sub> (see Diagnostic Output Mode diagram). The contents of flip-flops P <sub>0-1</sub> and F <sub>0-3</sub> remain unaltered.	Active-High/Low
13-16	P <sub>0-3</sub>	<b>Logic/Diagnostic Outputs:</b> Four device outputs which normally reflect the contents of State Register bits P <sub>0-3</sub> . When I <sub>0</sub> is held at +10V these pins reflect (P <sub>6-9</sub> ).	Active-High
10-11	F <sub>2-F3</sub>	<b>Logic/Diagnostic Outputs:</b> Two register bits (F <sub>2-F3</sub> ) which normally reflect Output Register bits (Q <sub>2-Q3</sub> ). When I <sub>0</sub> is held at +10V these pins reflect (P <sub>4-P5</sub> ).	Active-High
17	PR/ŌE	<b>Preset or Output Enable Input:</b> A user programmable function: <ul style="list-style-type: none"> <li><b>Preset:</b> Provides an Asynchronous Preset to logic "1" of all State and Output Register bits. Preset overrides Clock, and when held high, clocking is inhibited and P<sub>0-9</sub> and F<sub>0-3</sub> are high. Normal clocking resumes with the first full clock pulse following a High-to-Low clock transition, after Preset goes low.</li> <li><b>Output Enable:</b> Provides an Output Enable function to all output buffers.</li> </ul>	Active-High (H)  Active-Low (L)
8, 9	F <sub>0-F1</sub>	<b>Logic Output:</b> Two device outputs which reflect Output Registers Q <sub>0-Q1</sub> . When I <sub>0</sub> is held at +10V F <sub>0-F1</sub> = Logic "1".	

## LOGIC FUNCTION



## TRUTH TABLE<sup>1, 2, 3, 4, 5, 6</sup>

V <sub>CC</sub>	OPTION		I <sub>0</sub>	CK	S	R	Q <sub>P/F</sub>	F
	PR	ŌE						
+5V	H		*	X	X	X	H	H
	L		+10V	X	X	X	Q <sub>n</sub>	(Q <sub>P</sub> ) <sub>n</sub>
	L		X	X	X	X	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>
	H		*	X	X	X	Q <sub>n</sub>	Hi-Z
	L		+10V	X	X	X	Q <sub>n</sub>	(Q <sub>P</sub> ) <sub>n</sub>
	L		X	X	X	X	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>
+5V	L		X	↑	L	L	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>
	L		X	↑	L	H	L	L
	L		X	↑	H	L	H	H
+5V	L		X	↑	H	H	IND.	IND.
	L		X	↑	H	H	IND.	IND.
	L		X	↑	H	H	IND.	IND.
↑	X	X	X	X	X	X	H	

### NOTES:

- Positive Logic:  
 $S/R = T_0 + T_1 + T_2 + \dots + T_{47}$   
 $T_n = C(I_0 I_1 I_2 \dots) (P_0 P_1 \dots P_9)$
- Either Preset (Active-High) or Output Enable (Active-Low) are available, but not both. The desired function is a user programmable option.
- ↑ denotes transition from Low to High level.
- R = S = High is an illegal input condition.
- \* = H/L/+10V
- X = Don't care (≤ 5.5V)

## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

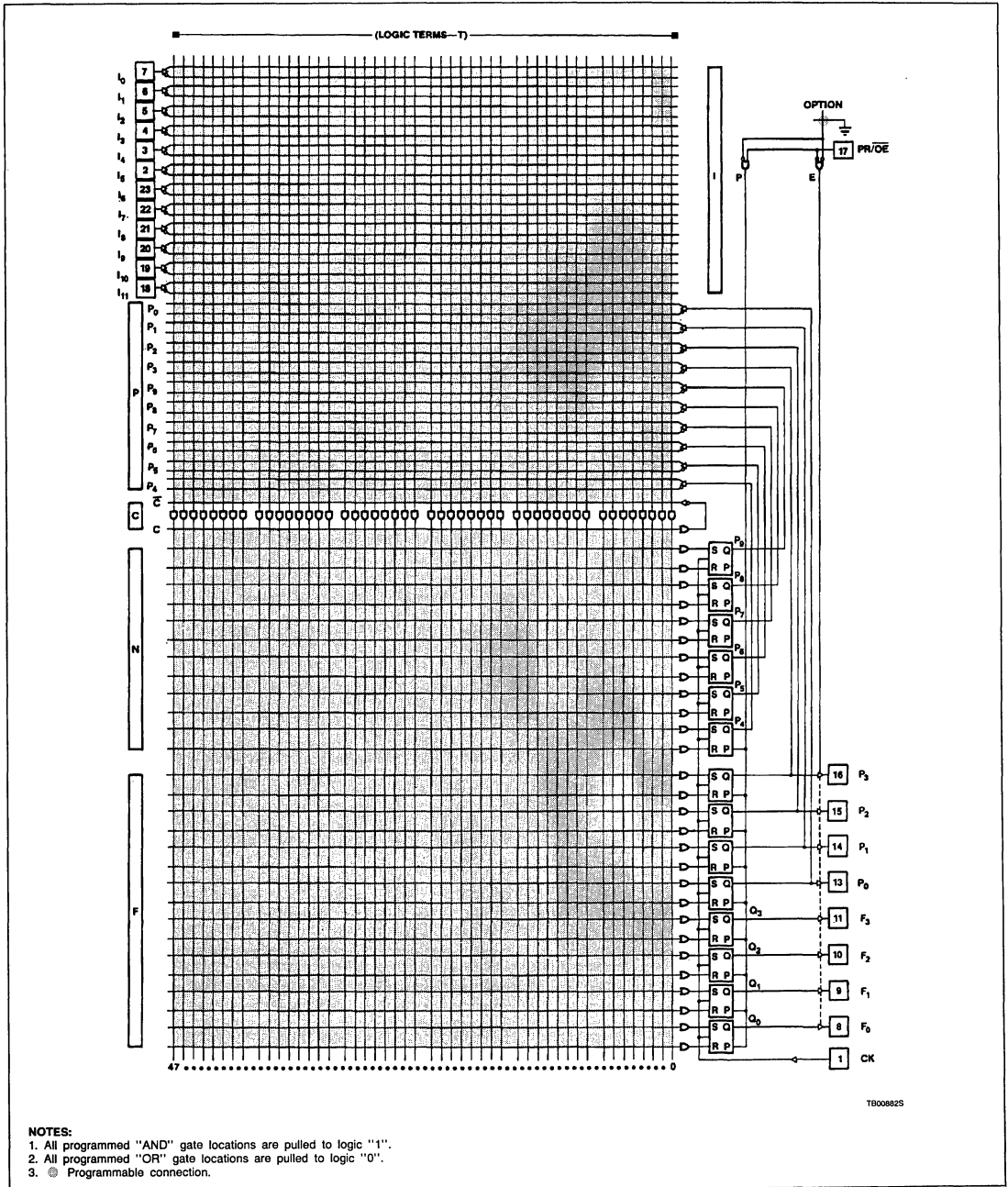
- PR/ŌE option is set to PR. Thus, all outputs will be at "1", as preset by initial power-up procedure.
- All transition terms are disabled (0).
- All S/R flip-flop inputs are disabled (0).
- The device can be clocked via a Test Array pre-programmed with a standard test pattern.

NOTE: The Test Array pattern MUST be deleted before incorporating a user program. This is accomplished automatically by any Signetics qualified programming equipment.

# Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168

## FPLS LOGIC DIAGRAM



5



## Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
24-pin Plastic DIP 300mil-wide	PLS168N
28-pin Plastic Leaded Chip Carrier	PLS168A

## THERMAL RATING

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>IN</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

## Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168

DC ELECTRICAL CHARACTERISTICS  $0^{\circ}\text{C} \leq T_A \leq 75^{\circ}\text{C}$ ,  $4.75\text{V} \leq V_{CC} \leq 5.25\text{V}$ 

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
$V_{IH}$	High	$V_{CC} = \text{Max}$	2			V
$V_{IL}$	Low	$V_{CC} = \text{Min}$			0.8	V
$V_{IC}$	Clamp <sup>3</sup>	$V_{CC} = \text{Min}$ , $I_{IN} = -12\text{mA}$		-0.8	-1.2	V
<b>Output voltage<sup>2</sup></b>						
$V_{OH}$	High <sup>4</sup>	$V_{CC} = \text{Min}$	2.4			V
$V_{OL}$	Low <sup>5</sup>	$I_{OH} = -2\text{mA}$ $I_{OL} = 9.6\text{mA}$		0.35	0.45	V
<b>Input current</b>						
$I_{IH}$	High	$V_{IN} = 5.5\text{V}$		< 1	25	$\mu\text{A}$
$I_{IL}$	Low	$V_{IN} = 0.45\text{V}$		-10	-100	$\mu\text{A}$
$I_{IL}$	Low (CK input)	$V_{IN} = 0.45\text{V}$		-50	-250	$\mu\text{A}$
<b>Output current</b>						
$I_{O(\text{OFF})}$	Hi-Z state <sup>6</sup>	$V_{CC} = \text{Max}$ $V_{OUT} = 5.5\text{V}$		1	40	$\mu\text{A}$
$I_{OS}$	Short circuit <sup>3, 7</sup>	$V_{OUT} = 0.45\text{V}$ $V_{OUT} = 0\text{V}$	-15	-1	-40 -70	mA
$I_{CC}$	$V_{CC}$ supply current <sup>8</sup>	$V_{CC} = \text{Max}$		120	180	mA
<b>Capacitance<sup>6</sup></b>						
$C_{IN}$	Input	$V_{CC} = 5.0\text{V}$ $V_{IN} = 2.0\text{V}$		8		pF
$C_{OUT}$	Output	$V_{OUT} = 2.0\text{V}$		10		pF

## NOTES:

- All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- Measured with  $V_{IL}$  applied to  $\overline{\text{OE}}$  and a logic high stored, or with  $V_{IH}$  applied to PR.
- Measured with a programmed logic condition for which the output is at a low logic level, and  $V_{IL}$  applied to PR/ $\overline{\text{OE}}$ . Output sink current is supplied through a resistor to  $V_{CC}$ .
- Measured with  $V_{IH}$  applied to PR/ $\overline{\text{OE}}$ .
- Duration of short circuit should not exceed 1 second.
- $I_{CC}$  is measured with the PR/ $\overline{\text{OE}}$  input grounded, all other inputs at 4.5V and the outputs open.

5

## Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168

**AC ELECTRICAL CHARACTERISTICS**  $R_1 = 470\Omega$ ,  $R_2 = 1k\Omega$ ,  $C_L = 30pF$ ,  $0^\circ C \leq T_A \leq +75^\circ C$ ,  $4.75V \leq V_{CC} \leq 5.25V$ 

SYMBOL	PARAMETER	TO	FROM	LIMITS			UNIT
				Min	Typ <sup>1</sup>	Max	
<b>Pulse width<sup>3</sup></b>							
t <sub>CKH</sub>	Clock <sup>2</sup> High	CK -	CK +	25	15		ns
t <sub>CKL</sub>	Clock Low	CK +	CK -	25	15		
t <sub>CKP1B</sub>	Period (without Complement Array)	CK +	CK +	80	40		
t <sub>CKP2B</sub>	Period (with Complement Array)	CK +	CK +	120	60		
t <sub>PRH</sub>	Preset pulse	PR -	PR +	25	15		
<b>Setup time<sup>3</sup></b>							
t <sub>IS1A</sub>	Input	CK +	Input ±	60			ns
t <sub>IS1B</sub>	Input	CK +	Input ±	50			
t <sub>IS1C</sub>	Input	CK +	Input ±	42			
t <sub>IS2A</sub>	Input (through Complement Array)	CK +	Input ±	90			
t <sub>IS2B</sub>	Input (through Complement Array)	CK +	Input	80			
t <sub>IS2C</sub>	Input (through Complement Array)	CK +	Input	72			
t <sub>VS</sub>	Power-on preset	CK -	V <sub>CC</sub> +	0	-10		
t <sub>PRS</sub>	Preset	CK -	PR -	0	-10		
<b>Hold time</b>							
t <sub>IH</sub>	Input	Input ±	CK +	5	-10		ns
<b>Propagation delay</b>							
t <sub>CKO</sub>	Clock	Output ±	CK +		15	30	ns
t <sub>OE</sub>	Output enable	Output -	OE -		20	30	
t <sub>OD</sub>	Output disable	Output +	OE +		20	30	
t <sub>PR</sub>	Preset	Output +	PR +		18	30	
t <sub>PPR</sub>	Power-on preset	Output +	V <sub>CC</sub> +		0	10	
<b>Frequency of operation<sup>3</sup></b>							
f <sub>MAXC</sub>	Without Complement Array					13.9	MHz
f <sub>MAXC</sub>	With Complement Array					9.8	

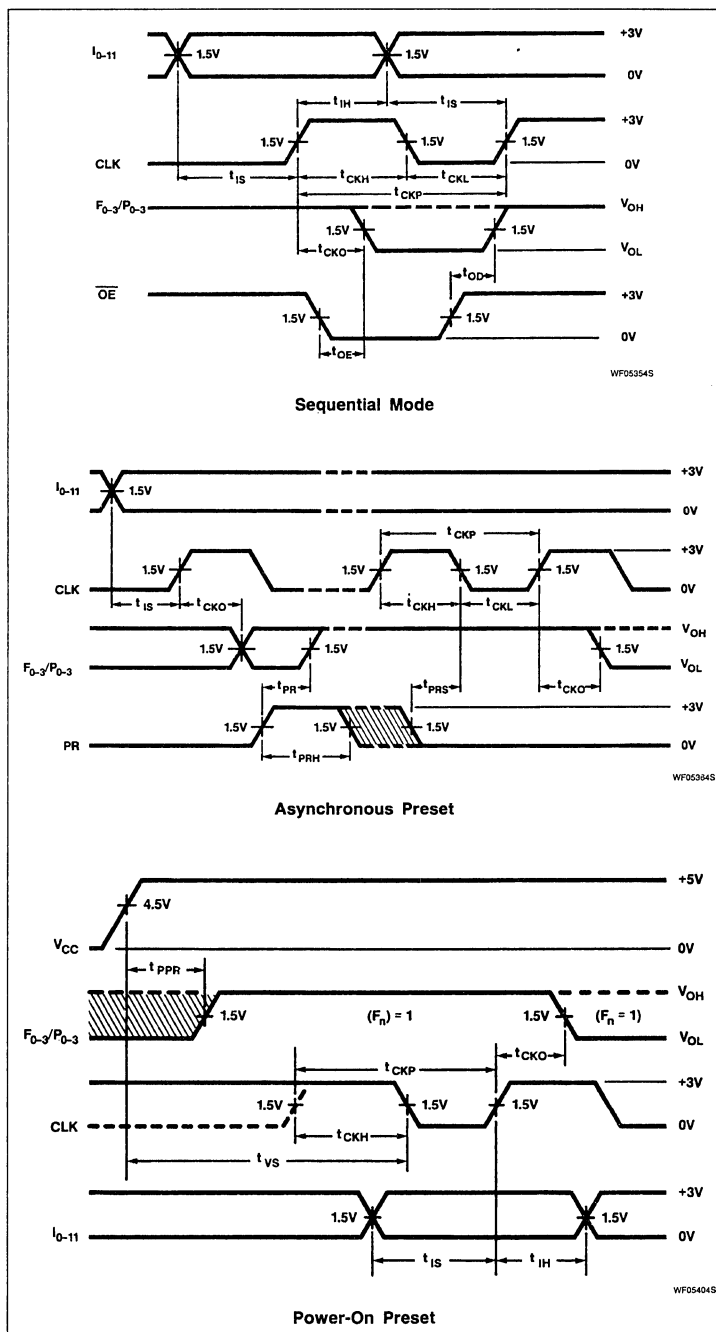
**NOTES:**

- All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
- To prevent spurious clocking, clock rise time (10% - 90%)  $\leq 30ns$ .
- See "Speed vs. OR Loading" diagrams.

## Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168

## TIMING DIAGRAMS



## TIMING DEFINITIONS

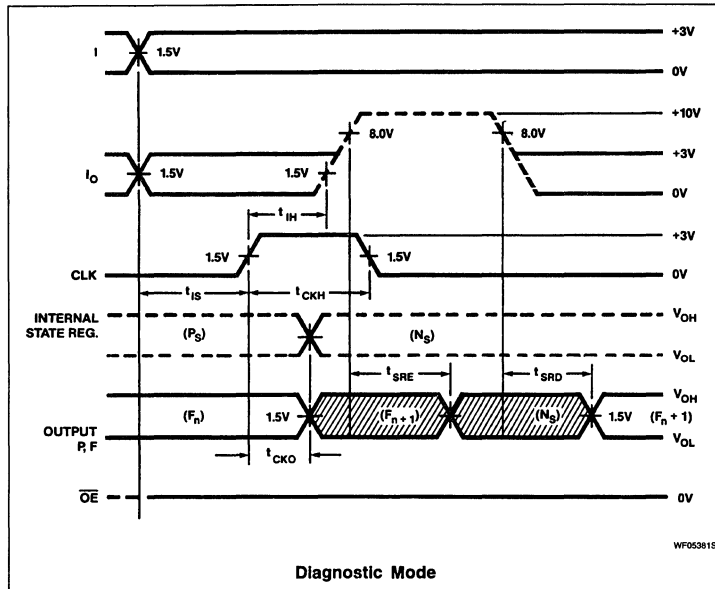
SYMBOL	PARAMETER
$t_{CKH}$	Width of input clock pulse.
$t_{CKL}$	Interval between clock pulses.
$t_{CKP1}$	Clock period – when not using Complement array.
$t_{IS1}$	Required delay between beginning of valid input and positive transition of clock.
$t_{CKP2}$	Clock period – when using complement array.
$t_{IS2}$	Required delay between beginning of valid input and positive transition of clock, when using optional Complement Array (two passes necessary through the AND array).
$t_{VS}$	Required delay between $V_{CC}$ (after power-on) and negative transition of clock preceding first reliable clock pulse.
$t_{PRS}$	Required delay between negative transition of asynchronous Preset and negative transition of clock preceding first reliable clock pulse.
$t_{IH}$	Required delay between positive transition of clock and end of valid input data.
$t_{CKO}$	Delay between positive transition of clock and when Outputs become valid (with PR/OE Low).
$t_{OE}$	Delay between beginning of Output Enable Low and when Outputs become valid.
$t_{OD}$	Delay between beginning of Output Enable High and when Outputs are in the OFF-state.
$t_{SRE}$	Delay between input $I_0$ transition to Diagnostic mode and when the Outputs reflect the contents of the State Register.
$t_{SRD}$	Delay between input $I_0$ transition to Logic mode and when the Outputs reflect the contents of the Output Register.
$t_{PR}$	Delay between positive transition of Preset and when Outputs become valid "1".
$t_{PPR}$	Delay between $V_{CC}$ (after power-on) and when Outputs become preset at "1".
$t_{PRH}$	Width of preset input pulse.
$f_{MAX}$	Maximum clock frequency.

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# Field-Programmable Logic Sequencer (12 × 48 × 8)

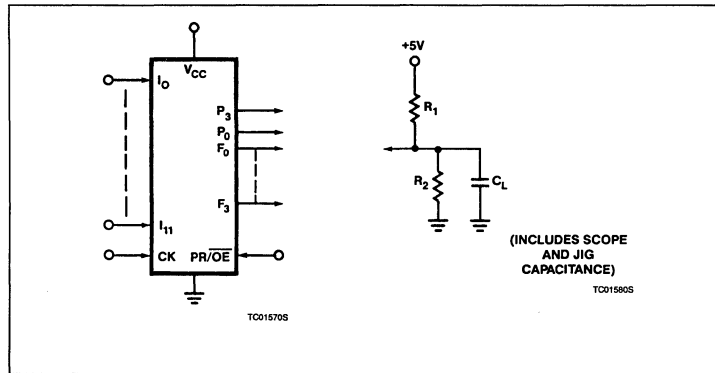
PLS168

## TIMING DIAGRAMS (Continued)

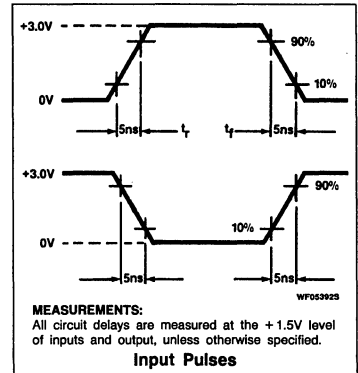


Diagnostic Mode

## TEST LOAD CIRCUITS



## VOLTAGE WAVEFORMS



## Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168

## SPEED VS. "OR" LOADING

The maximum frequency at which the FPLS can be clocked while operating in *sequential mode* is given by:

$$(1/f_{MAX}) = t_{CY} = t_{IS} + t_{CKO}$$

This frequency depends on the number of transition terms  $T_n$  used. Having all 48 terms connected in the AND array does not appreciably impact performance; but the number of terms connected to each OR line affects  $t_{IS}$ , due to capacitive loading. The effect of this loading can be seen in Figure 1, showing the variation of  $t_{IS1}$  with the number of terms connected per OR.

The AC electrical characteristics contain three limits for the parameters  $t_{IS1}$  and  $t_{IS2}$ . The first,  $t_{IS1A}$  is guaranteed for a device with 48 terms connected to any OR line.  $t_{IS1B}$  is guaranteed for a device with 32 terms connected to any OR line. And  $t_{IS1C}$  is guaranteed for a device with 24 terms connected to any OR line.

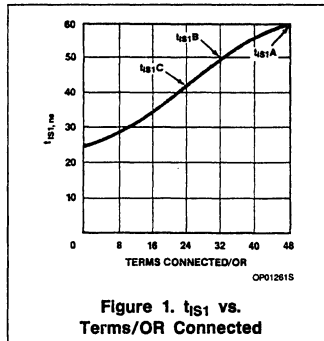


Figure 1.  $t_{IS1}$  vs. Terms/OR Connected

The three other entries in the AC table,  $t_{IS2}$  A, B and C are corresponding 48, 32 and 24 term limits when using the on-chip Complement Array.

The worst case of  $t_{IS}$  for a given application can be determined by identifying the OR line with the maximum number of  $T_n$  connections. This can be done by referring to the interconnect pattern in the FPLS logic

diagram, typically illustrated in Figure 2, or by counting the maximum number of "H" or "L" entries in one of the columns of the device Program Table.

This number plotted on the curve in Figure 1 will yield the worst case  $t_{IS}$  and, by implication, the maximum clocking frequency for reliable operation.

*Note that for maximum speed all UNUSED transition terms should be disconnected from the OR array.*

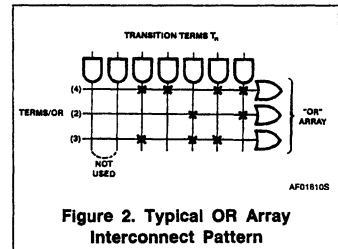


Figure 2. Typical OR Array Interconnect Pattern

# Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168

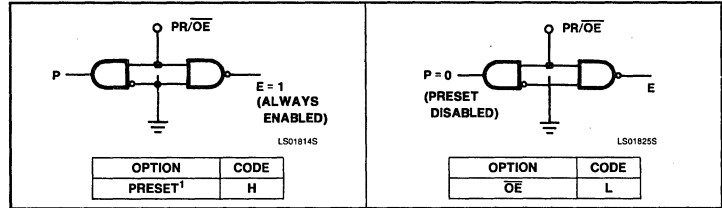
## LOGIC PROGRAMMING

PLS168 logic designs can be generated using Sigmetrics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

PLS168 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Sigmetrics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

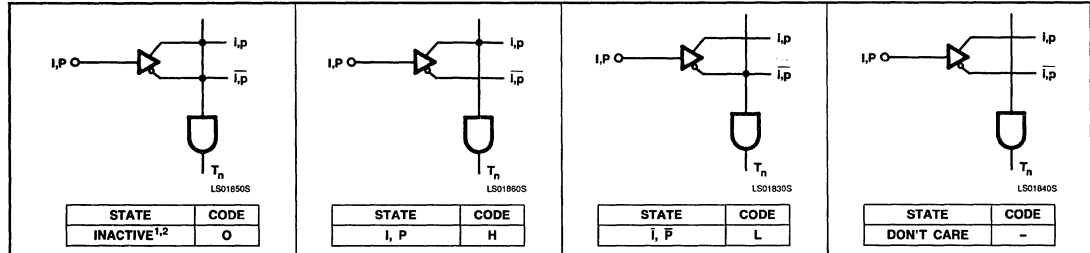
## PRESET/ÖE OPTION - (P/E)



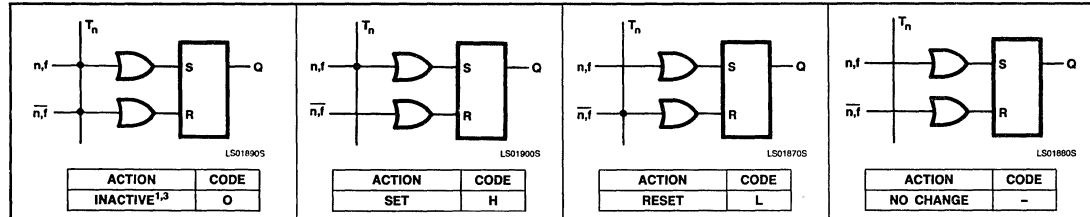
### PROGRAMMING:

The PLS168 has a power-up preset feature. This feature insures that the device will power-up in a known state with all register elements (state and output register) at a logic High (H). When programming the device it is important to realize this is the initial state of the device. You *must* provide a next state jump if you do not wish to use all Highs (H) as the present state.

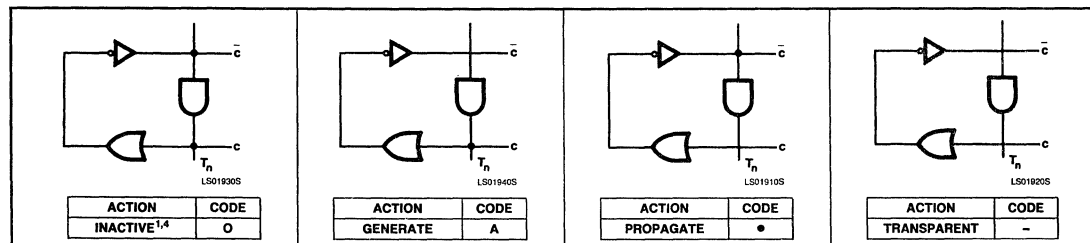
## "AND" ARRAY - (I), (P)



## "OR" ARRAY - (N), (F)



## "COMPLEMENT" ARRAY - (C)



### NOTES:

1. This is the initial unprogrammed state of all links.
2. Any gate  $T_n$  will be unconditionally inhibited if both the true and complement of any input (I or P) are left intact.
3. To prevent simultaneous Set and Reset flip-flop commands, this state is not allowed for N and F link pairs coupled to active gates  $T_n$  (see flip-flop truth tables).
4. To prevent oscillations, this state is not allowed for C link pairs coupled to active gates  $T_n$ .







## PLS168A Field-Programmable Logic Sequencer (12 × 48 × 8)

Signetics Programmable Logic  
Product Specification

### Application Specific Products • Series 24

#### DESCRIPTION

The PLS168A is a bipolar, programmable state machine of the Mealy type. It contains logic AND-OR gate arrays with user programmable connections which control the inputs of on-chip State and Output Registers. These consist respectively of 10  $Q_p$ , and 4  $Q_f$  edge-triggered, clocked S/R flip-flops, with an Asynchronous Preset option.

All flip-flops are unconditionally preset to "1" during power turn-on.

The AND array combines 12 external inputs,  $I_{0-11}$ , with 10 internal inputs,  $P_{0-9}$ , fed back from the State Register to form up to 48 transition terms (AND terms). In addition,  $P_0-P_3$  of the internal State Register are brought off-chip to allow extending the Output Register to 8 bits, if so desired.

All transition terms can include True, False, or Don't Care states of the controlling variables, and are merged in the OR array to issue next-state and next-output commands to their respective registers on the Low-to-High transition of the Clock pulse.

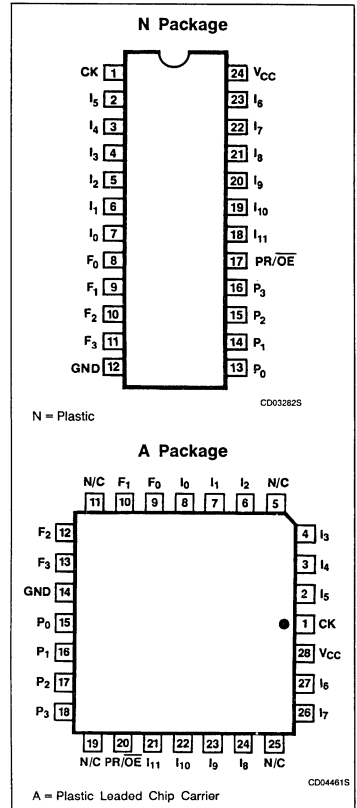
Both True and Complement transition terms can be generated by optional use of the internal variable (C) from the Complement Array. Also, if desired, the Preset input can be converted to output-enable function, as an additional user programmable option.

Order codes are listed in the Ordering Information Table.

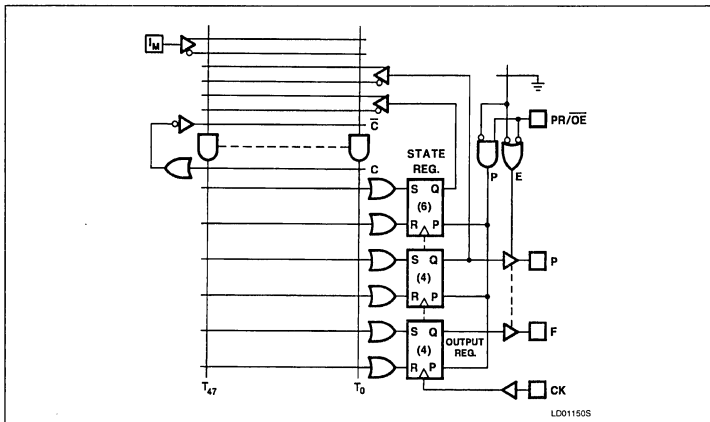
#### FEATURES

- **f<sub>MAX</sub>: 20MHz**  
- 25MHz clock rate
- **Field-Programmable (Ni-Cr link)**
- **12 True/Complement buffered inputs**
- **48 programmable AND gates**
- **29 programmable OR gates**
- **10-bit State Register**
- **4-bit shared State/Output Register**
- **4-bit Output Register**
- **Transition Complement Array**
- **Programmable Asynchronous Preset/Output Enable**
- **Positive edge-triggered clock**
- **Power-on preset to logic "1" of all registers**
- **Automatic logic "HOLD" state via S/R flip-flops**
- **On-chip Test Array**
- **Power: 600mW (typ.)**
- **TTL compatible**
- **3-State outputs**
- **Single +5V supply**
- **300mil-wide 24-pin DIP**

#### PIN CONFIGURATIONS



#### FUNCTIONAL DIAGRAM



#### APPLICATIONS

- Interface protocols
- Sequence detectors
- Peripheral controllers
- Timing generators
- Sequential circuits
- Elevator controllers
- Security locking systems
- Counters
- Shift registers

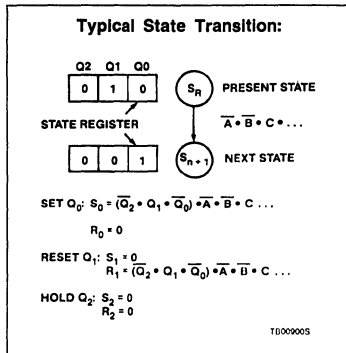
# Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168A

## PIN DESCRIPTION

PIN NO.	SYMBOL	NAME AND FUNCTION	POLARITY
1	CK	<b>Clock:</b> The Clock input to the State and Output Registers. A Low-to-High transition on this line is necessary to update the contents of both registers.	Active-High
2-6 18-23	I <sub>1-11</sub>	<b>Logic Inputs:</b> The 11 external inputs to the AND array used to program jump conditions between machine states, as determined by a given logic sequence.	Active-High/Low
7	I <sub>0</sub>	<b>Logic/Diagnostic Input:</b> A 12th external logic input to the AND array, as above, when exercised with standard TTL levels. When I <sub>0</sub> is held at +10V, device outputs F <sub>2-F3</sub> and P <sub>0-P3</sub> reflect the contents of State Register bits P <sub>4-9</sub> (see Diagnostic Output Mode diagram). The contents of flip-flops P <sub>0-1</sub> and F <sub>0-3</sub> remain unaltered.	Active-High/Low
13-16	P <sub>0-3</sub>	<b>Logic/Diagnostic Outputs:</b> Four device outputs which normally reflect the contents of State Register bits P <sub>0-3</sub> . When I <sub>0</sub> is held at +10V these pins reflect (P <sub>6-P9</sub> ).	Active-High
10-11	F <sub>2-F3</sub>	<b>Logic/Diagnostic Outputs:</b> Two register bits (F <sub>2-F3</sub> ) which reflect Output Register bits (Q <sub>2-Q3</sub> ). When I <sub>0</sub> is held at +10V these pins reflect (P <sub>4-P5</sub> ).	Active-High
17	PR/ŌE	<b>Preset or Output Enable Input:</b> A user programmable function: <ul style="list-style-type: none"> <li><b>Preset:</b> Provides an Asynchronous Preset to logic "1" of all State and Output Register bits. Preset overrides Clock, and when held high, clocking is inhibited and P<sub>0-9</sub> and F<sub>0-3</sub> are high. Normal clocking resumes with the first full clock pulse following a High-to-Low clock transition, after Preset goes low.</li> <li><b>Output Enable:</b> Provides an Output Enable function to all output buffers.</li> </ul>	Active-High (H)  Active-Low (L)
8, 9	F <sub>0-F1</sub>	<b>Logic Output:</b> Two device outputs which reflect Output Registers Q <sub>0-Q1</sub> . When I <sub>0</sub> is held at +10V F <sub>0-F1</sub> = Logic "1"	

## LOGIC FUNCTION



## TRUTH TABLE<sup>1, 2, 3, 4, 5, 6</sup>

V <sub>CC</sub>	OPTION		I <sub>0</sub>	CK	S	R	Q <sub>P/F</sub>	F
	PR	ŌE						
+5V	H		*	X	X	X	H	H
	L		+10V	X	X	X	Q <sub>n</sub>	(Q <sub>P</sub> ) <sub>n</sub>
	L		X	X	X	X	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>
		H	*	X	X	X	Q <sub>n</sub>	Hi-Z
		L	+10V	X	X	X	Q <sub>n</sub>	(Q <sub>P</sub> ) <sub>n</sub>
		L	X	X	X	X	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>
			L	X	↑	L	L	Q <sub>n</sub>
			L	X	↑	L	H	L
			L	X	↑	H	L	H
			L	X	↑	H	H	H
			L	X	↑	H	H	IND.
			L	X	↑	H	H	IND.
↑	X	X	X	X	X	X	H	

### NOTES:

- Positive Logic:  
 $S/R = T_0 + T_1 + T_2 + \dots + T_{47}$   
 $T_n = C(I_0 I_1 I_2 \dots) (P_0 P_1 \dots P_9)$
- Either Preset (Active-High) or Output Enable (Active-Low) are available, but not both. The desired function is a user programmable option.
- ↑ denotes transition from Low to High level.
- R = S = High is an illegal input condition.
- \* = H/L/+10V
- X = Don't Care ( $\leq 5.5V$ )

## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

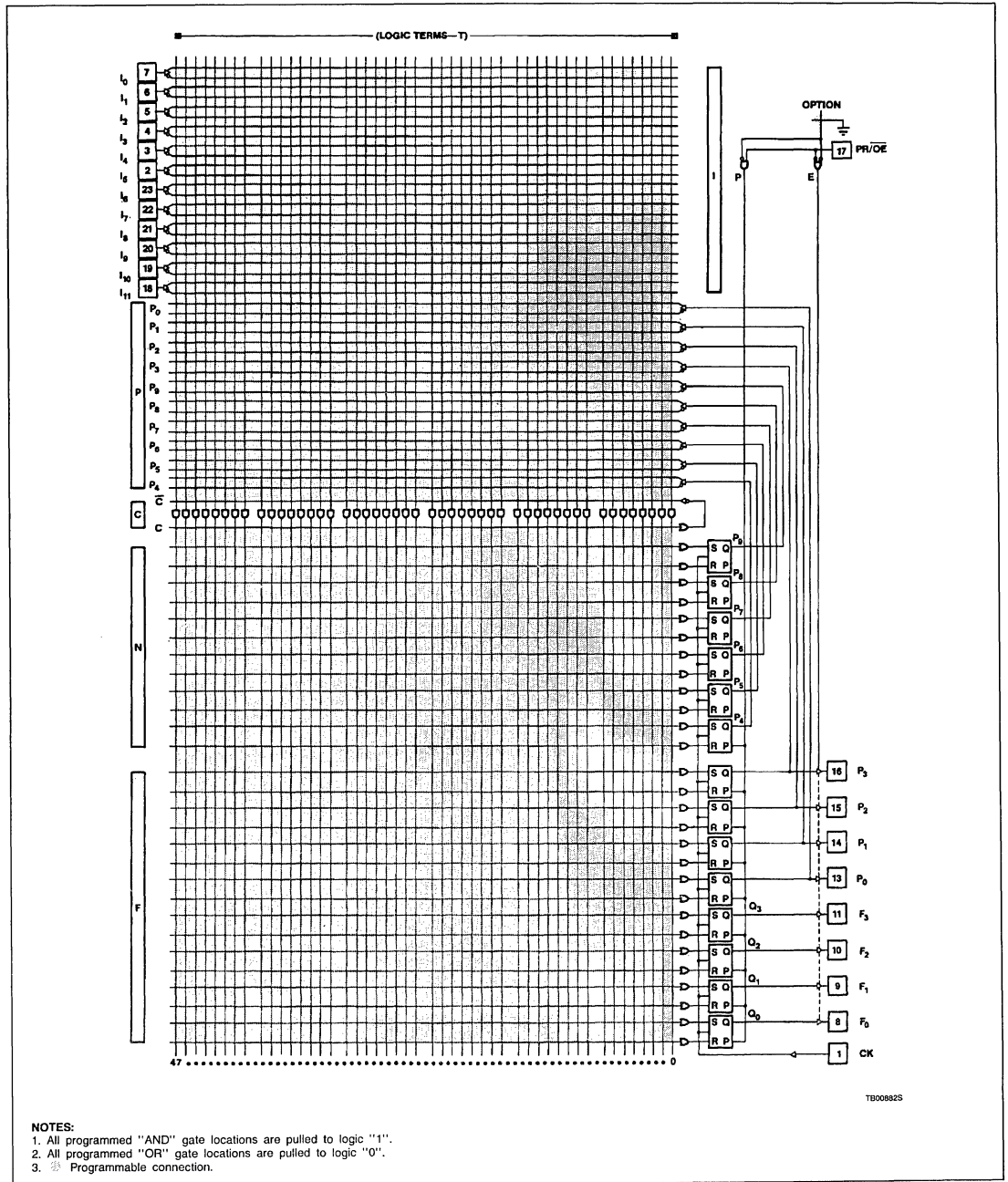
- PR/ŌE option is set to PR. Thus, all outputs will be at "1", as preset by initial power-up procedure.
- All transition terms are disabled (0).
- All S/R flip-flop inputs are disabled (0).
- The device can be clocked via a Test Array pre-programmed with a standard test pattern.

NOTE: The Test Array pattern MUST be deleted before incorporating a user program.

# Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168A

## FPLS LOGIC DIAGRAM



5

## Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168A

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
24-pin Plastic DIP 300mil-wide	PLS168AN
28-pin Plastic Leaded Chip Carrier	PLS168AA

## THERMAL RATING

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+ 7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+ 5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+ 5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+ 30	mA
I <sub>IN</sub>	Output currents		+ 100	mA
T <sub>A</sub>	Operating temperature range	0	+ 75	°C
T <sub>STG</sub>	Storage temperature range	-65	+ 150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

# Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168A

## DC ELECTRICAL CHARACTERISTICS $0^{\circ}\text{C} \leq T_A \leq 75^{\circ}\text{C}$ , $4.75\text{V} \leq V_{CC} \leq 5.25\text{V}$

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
$V_{IH}$	High	$V_{CC} = \text{Max}$	2			V
$V_{IL}$	Low	$V_{CC} = \text{Min}$			0.8	V
$V_{IC}$	Clamp <sup>3</sup>	$V_{CC} = \text{Min}$ , $I_{IN} = -12\text{mA}$		-0.8	-1.2	V
<b>Output voltage<sup>2</sup></b>						
$V_{OH}$	High <sup>4</sup>	$V_{CC} = \text{Min}$ $I_{OH} = -2\text{mA}$	2.4			V
$V_{OL}$	Low <sup>5</sup>	$I_{OL} = 9.6\text{mA}$		0.35	0.45	V
<b>Input current</b>						
$I_{IH}$	High	$V_{IN} = 5.5\text{V}$		< 1	25	$\mu\text{A}$
$I_{IL}$	Low	$V_{IN} = 0.45\text{V}$		-10	-100	$\mu\text{A}$
$I_{IL}$	Low (CK input)	$V_{IN} = 0.45\text{V}$		-50	-250	$\mu\text{A}$
<b>Output current</b>						
$I_{O(\text{OFF})}$	Hi-Z state <sup>6</sup>	$V_{CC} = \text{Max}$ $V_{OUT} = 5.5\text{V}$		1	40	$\mu\text{A}$
$I_{OS}$	Short circuit <sup>3, 7</sup>	$V_{OUT} = 0.45\text{V}$ $V_{OUT} = 0\text{V}$	-15	-1	-40 -70	$\mu\text{A}$ $\text{mA}$
$I_{CC}$	$V_{CC}$ supply current <sup>8</sup>	$V_{CC} = \text{Max}$		120	180	$\text{mA}$
<b>Capacitance<sup>6</sup></b>						
$C_{IN}$	Input	$V_{CC} = 5.0\text{V}$ $V_{IN} = 2.0\text{V}$		8		$\text{pF}$
$C_{OUT}$	Output	$V_{OUT} = 2.0\text{V}$		10		$\text{pF}$

**NOTES:**

- All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- Measured with  $V_{IL}$  applied to  $\overline{OE}$  and a logic high stored, or with  $V_{IH}$  applied to PR.
- Measured with a programmed logic condition for which the output is at a low logic level, and  $V_{IL}$  applied to PR/ $\overline{OE}$ . Output sink current is supplied through a resistor to  $V_{CC}$ .
- Measured with  $V_{IH}$  applied to PR/ $\overline{OE}$ .
- Duration of short circuit should not exceed 1 second.
- $I_{CC}$  is measured with the PR/ $\overline{OE}$  input grounded, all other inputs at 4.5V and the outputs open.

5

## Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168A

**AC ELECTRICAL CHARACTERISTICS**  $R_1 = 470\Omega$ ,  $R_2 = 1k\Omega$ ,  $C_L = 30pF$ ,  $0^\circ C \leq T_A \leq +75^\circ C$ ,  $4.75V \leq V_{CC} \leq 5.25V$ 

SYMBOL	PARAMETER	TO	FROM	LIMITS			UNIT
				Min	Typ <sup>1</sup>	Max	
<b>Pulse width<sup>3</sup></b>							
$t_{CKH}$	Clock <sup>2</sup> High	CK -	CK +	20	15		ns
$t_{CKL}$	Clock Low	CK +	CK -	20	15		
$t_{CKP1B}$	Period (without Complement Array)	CK +	CK +	50	40		
$t_{CKP2B}$	Period (with Complement Array)	CK +	CK +	80	50		
$t_{PRH}$	Preset pulse	PR -	PR +	25	15		
<b>Setup time<sup>3</sup></b>							
$t_{IS1A}$	Input	CK +	Input $\pm$	40			ns
$t_{IS1B}$	Input	CK +	Input $\pm$	30			
$t_{IS2A}$	Input (through Complement Array)	CK +	Input $\pm$	70			
$t_{IS2B}$	Input (through Complement Array)	CK +	Input	60			
$t_{VS}$	Power-on preset	CK -	$V_{CC} +$	0	-10		
$t_{PRS}$	Preset	CK -	PR -	0	-10		
<b>Hold time</b>							
$t_{IH}$	Input	Input $\pm$	CK +	5	-10		ns
<b>Propagation delay</b>							
$t_{CKO}$	Clock	Output $\pm$	CK +		15	20	ns
$t_{OE}$	Output enable	Output -	OE -		20	30	
$t_{OD}$	Output disable	Output +	OE +		20	30	
$t_{PR}$	Preset	Output +	PR +		18	30	
$t_{PPR}$	Power-on preset	Output +	$V_{CC} +$		0	10	
<b>Frequency of operation<sup>3</sup></b>							
$f_{MAXB}$	Without Complement Array					20	MHz
$f_{MAXB}$	With Complement Array					12.5	

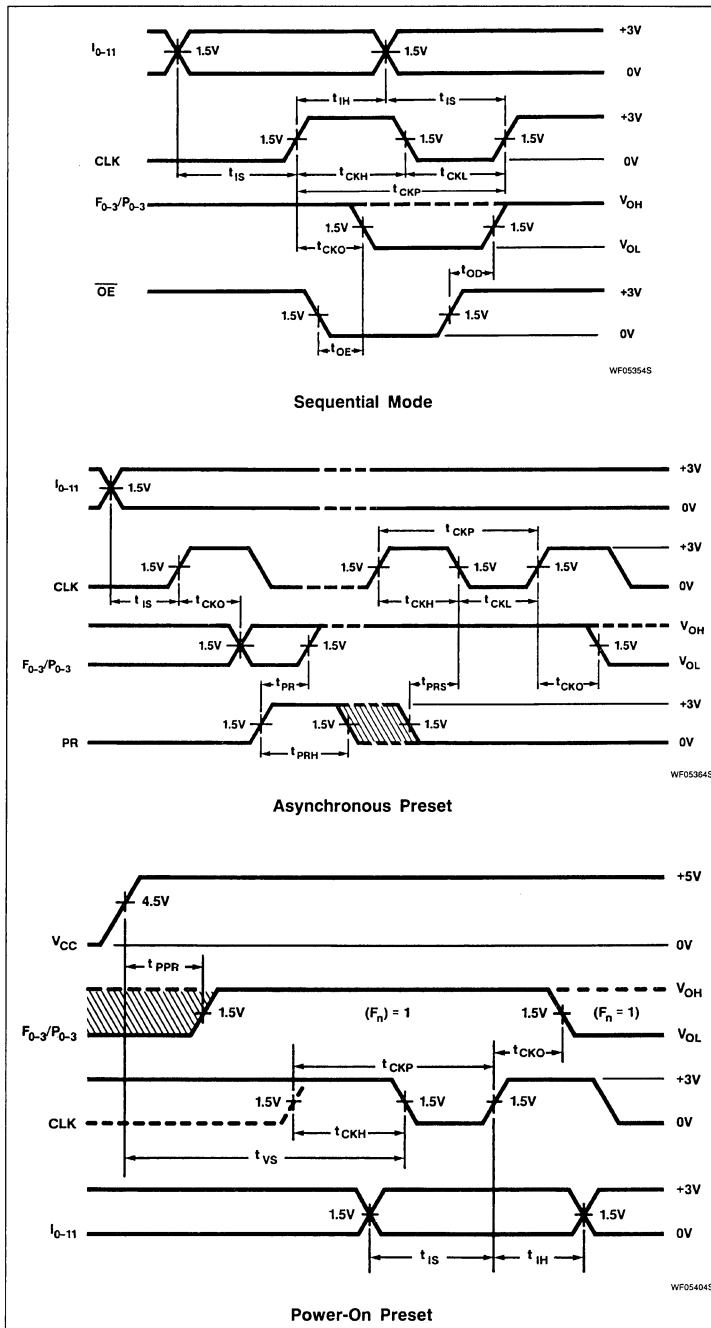
**NOTES:**

1. All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
2. To prevent spurious clocking, clock rise time (10% - 90%)  $\leq 30ns$ .
3. See "Speed vs. OR Loading" diagrams.

# Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168A

## TIMING DIAGRAMS



## TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{CKH}$	Width of input clock pulse.
$t_{CKL}$	Interval between clock pulses.
$t_{CKP1}$	Clock period – when not using Complement array.
$t_{IS1}$	Required delay between beginning of valid input and positive transition of clock.
$t_{CKP2}$	Clock period – when using complement array.
$t_{IS2}$	Required delay between beginning of valid input and positive transition of clock, when using optional Complement Array (two passes necessary through the AND array).
$t_{VS}$	Required delay between $V_{CC}$ (after power-on) and negative transition of clock preceding first reliable clock pulse.
$t_{PRS}$	Required delay between negative transition of asynchronous Preset and negative transition of clock preceding first reliable clock pulse.
$t_{IH}$	Required delay between positive transition of clock and end of valid input data.
$t_{CKO}$	Delay between positive transition of clock and when Outputs become valid (with PR/ $\overline{OE}$ Low).
$t_{OE}$	Delay between beginning of Output Enable Low and when Outputs become valid.
$t_{OD}$	Delay between beginning of Output Enable High and when Outputs are in the OFF-state.
$t_{SRE}$	Delay between input $I_0$ transition to Diagnostic mode and when the Outputs reflect the contents of the State Register.
$t_{SRD}$	Delay between input $I_0$ transition to Logic mode and when the Outputs reflect the contents of the Output Register.
$t_{PR}$	Delay between positive transition of Preset and when Outputs become valid "1".
$t_{PPR}$	Delay between $V_{CC}$ (after power-on) and when Outputs become preset at "1".
$t_{PRH}$	Width of preset input pulse.
$f_{MAX}$	Maximum clock frequency.

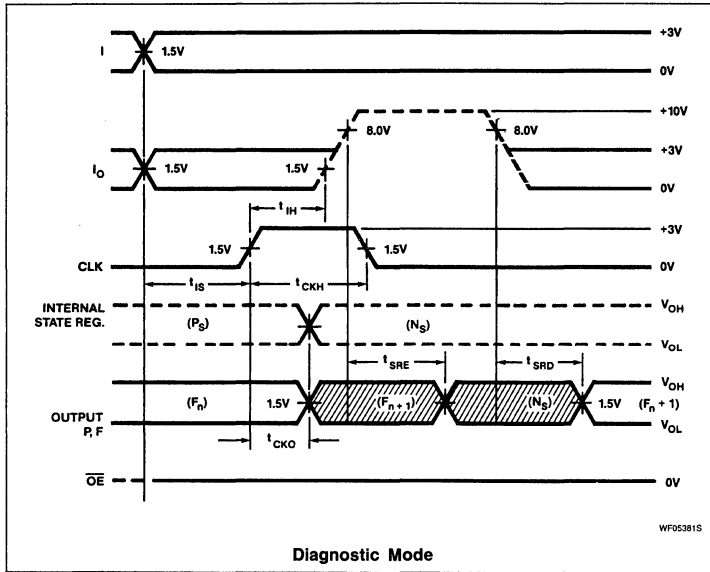
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# Field-Programmable Logic Sequencer (12 × 48 × 8)

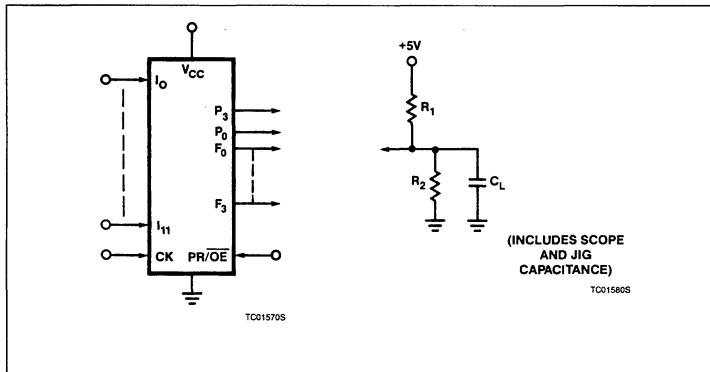
PLS168A

## TIMING DIAGRAMS (Continued)

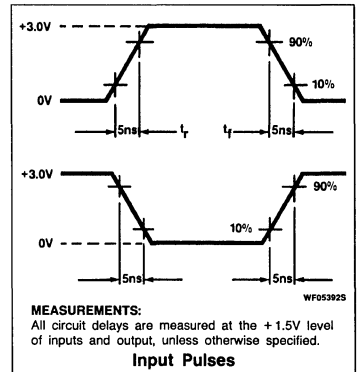


Diagnostic Mode

## TEST LOAD CIRCUITS



## VOLTAGE WAVEFORMS



# Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168A

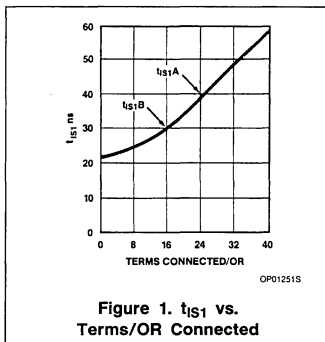
## SPEED VS. "OR" LOADING

The maximum frequency at which the FPLS can be clocked while operating in *sequential mode* is given by:

$$(1/f_{MAX}) = t_{CY} = t_{IS} + t_{CKO}$$

This frequency depends on the number of transition terms  $T_n$  used. Having all 48 terms connected in the AND array does not appreciably impact performance; but the number of terms connected to each OR line affects  $t_{IS}$ , due to capacitive loading. The effect of this loading can be seen in Figure 1, showing the variation of  $t_{IS1}$  with the number of terms connected per OR.

The AC electrical characteristics contain two limits for the parameters  $t_{IS1}$  and  $t_{IS2}$ . The first,  $t_{IS1A}$  is guaranteed for a device with 24 terms connected to any OR line.  $t_{IS1B}$  is guaranteed for a device with 16 terms connected to any OR line.



**Figure 1.  $t_{IS1}$  vs. Terms/OR Connected**

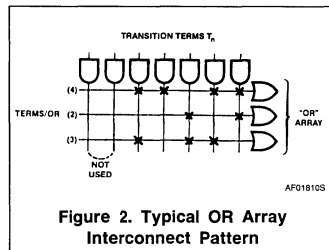
The three other entries in the AC table,  $t_{IS2}$  A and B are corresponding 24 and 16 term limits when using the on-chip Complement Array.

The worst case of  $t_{IS}$  for a given application can be determined by identifying the OR line with the maximum number of  $T_n$  connections. This can be done by referring to the interconnect pattern in the FPLS logic

diagram, typically illustrated in Figure 2, or by counting the maximum number of "H" or "L" entries in one of the columns of the device Program Table.

This number plotted on the curve in Figure 1 will yield the worst case  $t_{IS}$  and, by implication, the maximum clocking frequency for reliable operation.

*Note that for maximum speed all UNUSED transition terms should be disconnected from the OR array.*



**Figure 2. Typical OR Array Interconnect Pattern**

# Field-Programmable Logic Sequencer (12 × 48 × 8)

PLS168A

## LOGIC PROGRAMMING

PLS168A logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

PLS168A logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

### "AND" ARRAY - (I), (P)

<p style="text-align: center;">LS01860S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>INACTIVE<sup>1,2</sup></td><td>O</td></tr> </table>	STATE	CODE	INACTIVE <sup>1,2</sup>	O	<p style="text-align: center;">LS01860S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>I, P</td><td>H</td></tr> </table>	STATE	CODE	I, P	H	<p style="text-align: center;">LS01830S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>I, P-bar</td><td>L</td></tr> </table>	STATE	CODE	I, P-bar	L	<p style="text-align: center;">LS01840S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>DON'T CARE</td><td>-</td></tr> </table>	STATE	CODE	DON'T CARE	-
STATE	CODE																		
INACTIVE <sup>1,2</sup>	O																		
STATE	CODE																		
I, P	H																		
STATE	CODE																		
I, P-bar	L																		
STATE	CODE																		
DON'T CARE	-																		

### "OR" ARRAY - (N), (F)

<p style="text-align: center;">LS01990S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>INACTIVE<sup>1,3</sup></td><td>O</td></tr> </table>	ACTION	CODE	INACTIVE <sup>1,3</sup>	O	<p style="text-align: center;">LS01900S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>SET</td><td>H</td></tr> </table>	ACTION	CODE	SET	H	<p style="text-align: center;">LS01870S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>RESET</td><td>L</td></tr> </table>	ACTION	CODE	RESET	L	<p style="text-align: center;">LS01880S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>NO CHANGE</td><td>-</td></tr> </table>	ACTION	CODE	NO CHANGE	-
ACTION	CODE																		
INACTIVE <sup>1,3</sup>	O																		
ACTION	CODE																		
SET	H																		
ACTION	CODE																		
RESET	L																		
ACTION	CODE																		
NO CHANGE	-																		

### "COMPLEMENT" ARRAY - (C)

<p style="text-align: center;">LS01930S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>INACTIVE<sup>1,4</sup></td><td>O</td></tr> </table>	ACTION	CODE	INACTIVE <sup>1,4</sup>	O	<p style="text-align: center;">LS01940S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>GENERATE</td><td>A</td></tr> </table>	ACTION	CODE	GENERATE	A	<p style="text-align: center;">LS01910S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>PROPAGATE</td><td>•</td></tr> </table>	ACTION	CODE	PROPAGATE	•	<p style="text-align: center;">LS01920S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>TRANSPARENT</td><td>-</td></tr> </table>	ACTION	CODE	TRANSPARENT	-
ACTION	CODE																		
INACTIVE <sup>1,4</sup>	O																		
ACTION	CODE																		
GENERATE	A																		
ACTION	CODE																		
PROPAGATE	•																		
ACTION	CODE																		
TRANSPARENT	-																		

**NOTES:**

1. This is the initial unprogrammed state of all link pairs. It is normally associated with all unused (inactive) AND gates  $T_n$ .
2. Any gate  $T_n$  will be unconditionally inhibited if any one of its I or P link pairs is left intact.
3. To prevent simultaneous Set and Reset flip-flop commands, this state is not allowed for N and F link pairs coupled to active gates  $T_n$  (see flip-flop truth tables).
4. To prevent oscillations, this state is not allowed for C link pairs coupled to active gates  $T_n$ .

## PRESET/OE OPTION - (P/E)

<p style="text-align: center;">LS01814S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>OPTION</th><th>CODE</th></tr> <tr><td>PRESET<sup>1</sup></td><td>H</td></tr> </table>	OPTION	CODE	PRESET <sup>1</sup>	H	<p style="text-align: center;">LS01825S</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>OPTION</th><th>CODE</th></tr> <tr><td>OE</td><td>L</td></tr> </table>	OPTION	CODE	OE	L
OPTION	CODE								
PRESET <sup>1</sup>	H								
OPTION	CODE								
OE	L								

**PROGRAMMING:**

The PLS168A has a power-up preset feature. This feature insures that the device will power-up in a known state with all register elements (state and output register) at a logic High (H). When programming the device it is important to realize this is the initial state of the device. You *must* provide a next state jump if you do not wish to use all Highs (H) as the present state.





# PLS179

## Field-Programmable Logic Sequencer (20 X 45 X 12)

Signetics Programmable Logic  
Product Specification

Application Specific Products  
• Series 24

### DESCRIPTION

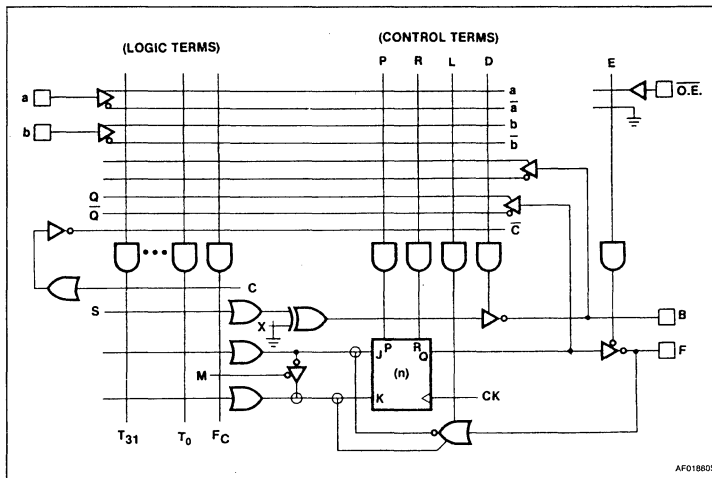
The PLS179 is a 3-State output, registered logic element combining AND/OR gate arrays with clocked J-K flip-flops. These J-K flip-flops are dynamically convertible to D-type via a "foldback" inverting buffer and control gate  $F_C$ . It features 8 registered I/O outputs (F) in conjunction with 4 bidirectional I/O lines (B). There are 8 dedicated inputs. These yield variable I/O gate and register configurations via control gates (D, L) ranging from 20 inputs to 12 outputs.

The AND/OR arrays consist of 32 logic AND gates, 13 control AND gates, and 21 OR gates with fusible link connections for programming I/O polarity and direction. All AND gates are linked to 8 inputs (I), bidirectional I/O lines (B), internal flip-flop outputs (Q), and Complement Array output ( $\bar{C}$ ). The Complement Array consists of a NOR gate optionally linked to all AND gates for generating and propagating complementary AND terms.

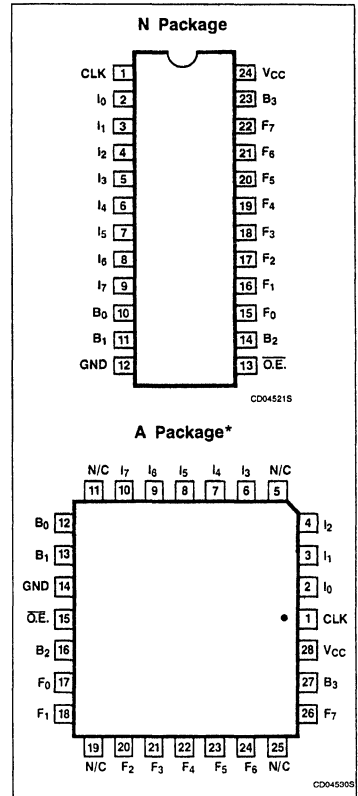
### FEATURES

- $f_{MAX} = 18.2\text{MHz}$   
- 25MHz clock rate
- Field-Programmable (Ni-Cr link)
- 8 dedicated inputs
- 13 control gates
- 32 AND gates
- 21 OR gates
- 45 product terms:
  - 32 logic terms
  - 13 control terms
- 4 bidirectional I/O lines
- 8 bidirectional registers
- J/K, T, or D-type flip-flops
- Asynchronous Preset/Reset
- Complement Array
- Active-High or -Low outputs
- Programmable  $\bar{O}E$  control
- Positive edge-triggered clock
- Power-on reset on flip-flop ( $F_n = "1"$ )
- Input loading: PLS179: - 100 $\mu$ A (max.)
- Power dissipation: 750mW (typ.)
- TTL compatible
- 3-State option

### FUNCTIONAL DIAGRAM



### PIN CONFIGURATIONS



### APPLICATIONS

- Random sequential logic
- Synchronous up/down counters
- Shift registers
- Bidirectional data buffers
- Timing function generators
- System controllers/synchronizers
- Priority encoder/registers

# Field-Programmable Logic Sequencer (20 X 45 X 12)

PLS179

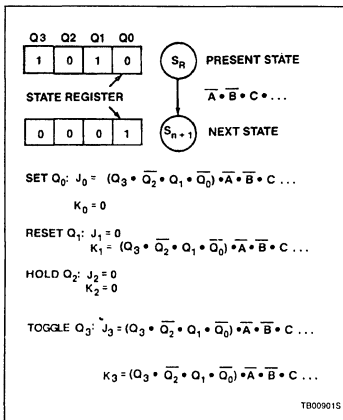
On-chip T/C buffers couple either True (I, B, Q) or Complement ( $\bar{I}$ ,  $\bar{B}$ ,  $\bar{Q}$ ,  $\bar{C}$ ) input polarities to all AND gates, whose outputs can be optionally linked to all OR gates. One group of AND gates drives bidirectional I/O lines (B), whose output polarity is individually programmable through a set of EX-OR gates for implementing AND-OR or AND-NOR logic functions. Another group drives the J-K inputs of all flip-flops, as well as asynchronous Preset and Reset lines (P, R).

All flip-flops are positive edge-triggered and can be used as input, output or I/O (for interfacing with a bidirectional data bus) in conjunction with load control gates (L), steering inputs (I), (B), (Q) and programmable output select lines (E).

The PLS179 is field programmable, enabling the user to quickly generate custom patterns using standard programming equipment.

Order codes are listed in the Ordering Information Table.

## LOGIC FUNCTION



**NOTES:**

Similar logic functions are applicable for D and T mode flip-flops.

## FLIP-FLOP TRUTH TABLE

OE	L	CK	P	R	J	K	Q	F
H								H/Hi-Z
L	X	X	X	X	X	X	L	H
L	X	X	H	L	X	X	H	L
L	X	X	L	H	X	X	L	H
L	L	↑	L	L	L	L	Q	$\bar{Q}$
L	L	↑	L	L	L	H	L	H
L	L	↑	L	L	H	L	H	L
L	L	↑	L	L	H	H	$\bar{Q}$	Q
H	H	↑	L	L	L	H	L	H*
H	H	↑	L	L	H	L	H	L*
+10V	X	↑	X	X	L	H	L	H**
	X	↑	X	X	H	L	H	L**

**NOTES:**

- Positive Logic:  
 $J/K = T_0 + T_1 + T_2 + \dots + T_{31}$   
 $T_n = \bar{C} \cdot (I_0 \cdot I_1 \cdot I_2 \dots) \cdot (Q_0 \cdot Q_1 \dots) \cdot (B_0 \cdot B_1 \dots)$
- ↑ denotes transition from Low to High level.
- X = Don't Care
- \* = Forced at F<sub>n</sub> pin for loading J/K flip-flop in I/O mode. L must be enabled, and other active T<sub>n</sub> disabled via steering input(s) I, B, or Q.
- At P = R = H, Q = H. The final state of Q depends on which is released first.
- \*\* = Forced at F<sub>n</sub> pin to load J/K flip-flop independent of program code (Diagnostic mode), 3-State B outputs.

## VIRGIN STATE

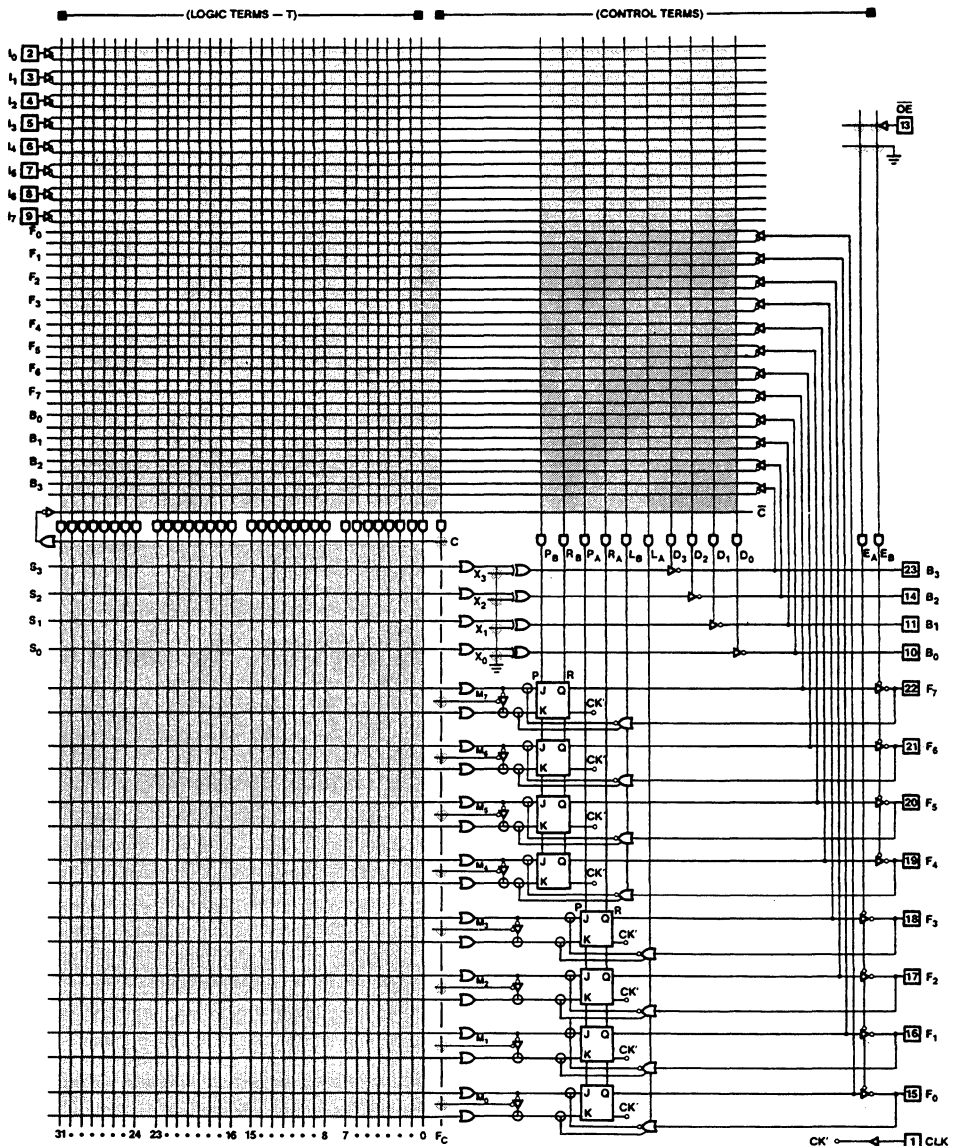
The factory shipped virgin device contains all fusible links intact, such that:

- $\bar{OE}$  is always enabled.
- Preset and Reset are always disabled.
- All transition terms are disabled.
- All flip-flops are in D-mode unless otherwise programmed to J/K only or J/K or D (controlled).
- All B pins are inputs and all F pins are outputs unless otherwise programmed.

# Field-Programmable Logic Sequencer (20 X 45 X 12)

## PLS179

### FPLS LOGIC DIAGRAM



5

1. All OR gate inputs with a blown link float to logic "0".
2. All other gates and control inputs with a blown link float to logic "1".
3. ⊕ denotes WIRE-OR.
4. ⊗ Programmable connection.

LD01672S



## Field-Programmable Logic Sequencer (20 × 45 × 12)

PLS179

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
24-pin Plastic DIP 300mil-wide	PLS179N
28-pin Plastic Leaded Chip Carrier	PLS179A

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ 75°C, 4.75V ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IH</sub>	High	V <sub>CC</sub> = Max	2			V
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min			0.8	V
V <sub>IC</sub>	Clamp	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA		-0.8	-1.2	V
<b>Output voltage<sup>2</sup></b>						
V <sub>OH</sub>	High	V <sub>CC</sub> = Min, I <sub>OH</sub> = -2mA	2.4			V
V <sub>OL</sub>	Low	I <sub>OL</sub> = 10mA		0.35	0.5	V
<b>Input current</b>						
I <sub>IH</sub>	High	V <sub>CC</sub> = Max, V <sub>IN</sub> = 5.5V		< 1	40	μA
I <sub>IL</sub>	Low	V <sub>IN</sub> = 0.45V		-10	-100	μA
<b>Output current</b>						
I <sub>O(OFF)</sub>	Hi-Z state <sup>4, 7</sup>	V <sub>CC</sub> = Max, V <sub>OUT</sub> = 5.5V		1	80	μA
I <sub>OS</sub>	Short circuit <sup>3, 5</sup>	V <sub>OUT</sub> = 0.45V			-140	μA
		V <sub>OUT</sub> = 0V	-15		-70	mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>6</sup>	V <sub>CC</sub> = Max		150	210	mA
<b>Capacitance</b>						
C <sub>IN</sub>	Input	V <sub>CC</sub> = 5.0V, V <sub>IN</sub> = 2.0V		8		pF
C <sub>OUT</sub>	Output	V <sub>OUT</sub> = 2.0V		15		pF

## NOTES:

- All typical values are at V<sub>CC</sub> = 5V, T<sub>A</sub> = +25°C.
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- Measured with V<sub>IH</sub> applied to  $\overline{OE}$ .
- Duration of short circuit should not exceed 1 second.
- I<sub>CC</sub> is measured with the  $\overline{OE}$  input grounded, all other inputs at 4.5V, and the outputs open.
- Leakage values are a combination of input and output leakage.

# Field-Programmable Logic Sequencer (20 X 45 X 12)

PLS179

## AC ELECTRICAL CHARACTERISTICS $R_1 = 470\Omega, R_2 = 1k\Omega, 0^\circ C \leq T_A \leq +75^\circ C, 4.75V \leq V_{CC} \leq 5.25V$

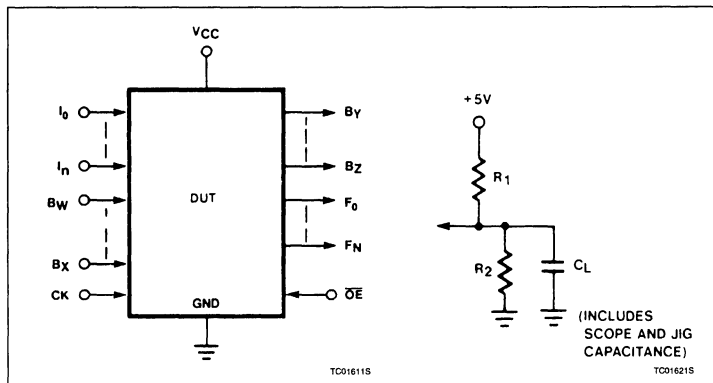
SYMBOL	PARAMETER	TO	FROM	TEST CONDITION	LIMITS			UNIT
					Min <sup>5</sup>	Typ <sup>1</sup>	Max	
<b>Pulse width</b>								
$t_{CKH}$	Clock <sup>2</sup> High	CK -	CK +	$C_L = 30pF$	20	15		ns
$t_{CKL}$	Clock Low	CK +	CK -		20	15		
$t_{CKP}$	Period	CK +	CK +		55	45		
$t_{PRH}$	Preset/Reset pulse	(I,B) +	(I,B) -		35	30		
<b>Setup time</b>								
$t_{IS1}$	Input	CK +	(I,B) $\pm$	$C_L = 30pF$	35	30		ns
$t_{IS2}$	Input (through $F_n$ )	CK +	$F \pm$		15	10		
$t_{IS3}$	Input (through Complement Array) <sup>4</sup>	CK +	(I,B) $\pm$		55	45		
<b>Hold time</b>								
$t_{IH1}$	Input	CK +	(I,B) $\pm$	$C_L = 30pF$	0	-5		ns
$t_{IH2}$	Input (through $F_n$ )	CK +	$F \pm$		15	10		
<b>Propagation delay</b>								
$t_{CKO}$	Clock	$F \pm$	CK $\pm$	$C_L = 5pF$		15	20	ns
$t_{OE1}$	Output enable	$F -$	$\overline{OE} -$	$C_L = 30pF$		20	30	
$t_{OD1}$	Output disable <sup>3</sup>	$F +$	$\overline{OE} +$	$C_L = 5pF$		20	30	
$t_{PD}$	Output	$B \pm$	(I,B) $\pm$	$C_L = 30pF$		25	35	
$t_{OE2}$	Output enable	$B \pm$	(I,B) +	$C_L = 5pF$		20	30	
$t_{OD2}$	Output disable <sup>3</sup>	$B +$	(I,B) -	$C_L = 30pF$		20	30	
$t_{PRO}$	Preset/Reset	$F \pm$	(I,B) +			35	45	
$t_{PPR}$	Power-on preset	$F -$	$V_{CC} +$			0	10	

5

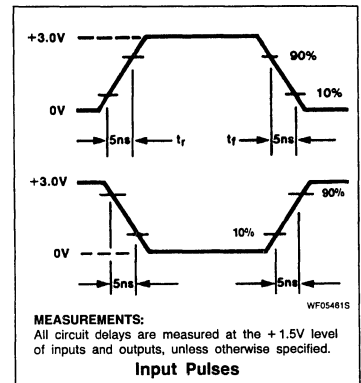
**NOTES:**

1. All typical values are at  $V_{CC} = 5V, T_A = +25^\circ C$ .
2. To prevent spurious clocking, clock rise time (10% - 90%)  $\leq 10ns$ .
3. Measured at  $V_T = V_{OL} + 0.5V$ .
4. When using the Complement Array  $T_{CKP} = 75ns$  (min).
5. Limits are guaranteed with 12 product terms maximum connected to each sum term line.

**TEST LOAD CIRCUITS**



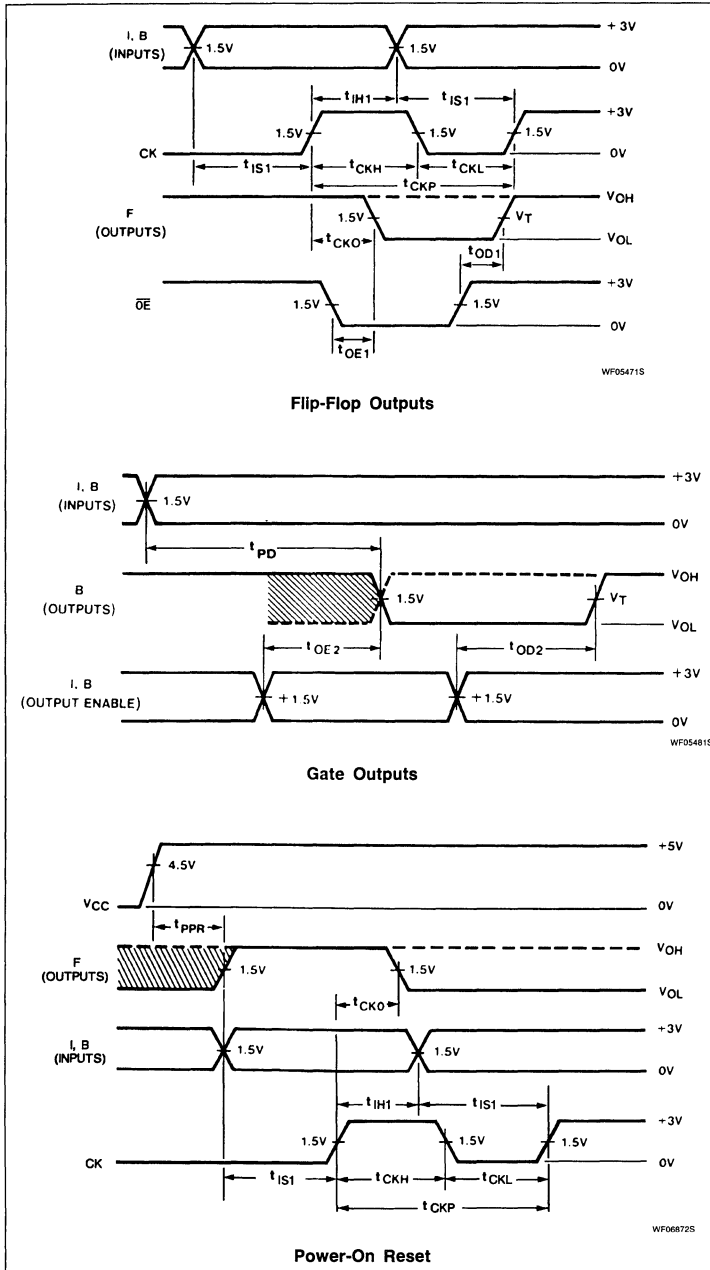
**VOLTAGE WAVEFORMS**



# Field-Programmable Logic Sequencer (20 × 45 × 12)

PLS179

## TIMING DIAGRAMS



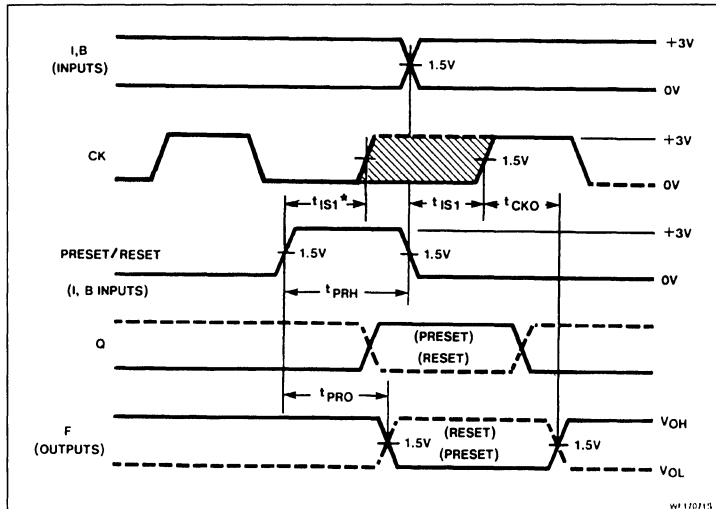
## TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{CKH}$	Width of input clock pulse.
$t_{CKL}$	Interval between clock pulses.
$t_{CKP}$	Clock period.
$t_{PRH}$	Width of preset input pulse.
$t_{IS1}$	Required delay between beginning of valid input and positive transition of clock.
$t_{IS2}$	Required delay between beginning of valid input forced at flip-flop output pins, and positive transition of clock.
$t_{IH1}$	Required delay between positive transition of clock and end of valid input data.
$t_{IH2}$	Required delay between positive transition of clock and end of valid input data forced at flip-flop output pins.
$t_{CKO}$	Delay between positive transition of clock and when Outputs become valid (with OE Low).
$t_{OE1}$	Delay between beginning of Output Enable Low and when Outputs become valid.
$t_{OD1}$	Delay between beginning of Output Enable High and when Outputs are in the OFF-state.
$t_{PPR}$	Delay between $V_{CC}$ (after power-on) and when flip-flop outputs become preset at "1" (internal Q outputs at "0").
$t_{PD}$	Propagation delay between combinational inputs and outputs.
$t_{OE2}$	Delay between predefined Output Enable High, and when combinational Outputs become valid.
$t_{OD2}$	Delay between predefined Output Enable Low and when combinational Outputs are in the off state.
$t_{PRO}$	Delay between positive transition of predefined Preset/Reset input, and when flip-flop outputs become valid.

# Field-Programmable Logic Sequencer (20 × 45 × 12)

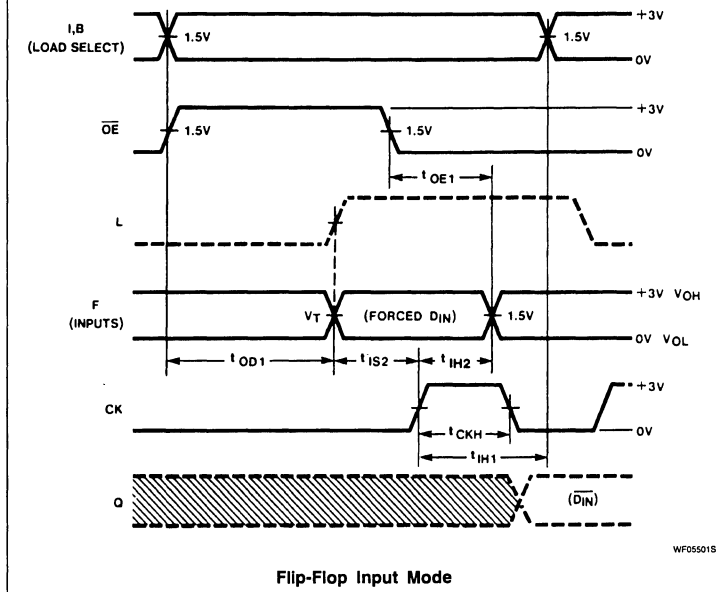
PLS179

## TIMING DIAGRAMS (Continued)



\*Preset and Reset functions override Clock. However, F outputs may glitch with the first positive Clock Edge if  $T_{111}$  cannot be guaranteed by the user.

### Asynchronous Preset/Reset



### Flip-Flop Input Mode

5

# Field-Programmable Logic Sequencer (20 × 45 × 12)

PLS179

## LOGIC PROGRAMMING

PLS179 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

PLS179 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

### "AND" ARRAY - (I), (B), (Qp)

<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>INACTIVE<sup>1,2</sup></td><td>O</td></tr> </table> <p style="font-size: small;">LS020305</p>	STATE	CODE	INACTIVE <sup>1,2</sup>	O	<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>I, B, Q</td><td>H</td></tr> </table> <p style="font-size: small;">LS020405</p>	STATE	CODE	I, B, Q	H	<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>I, B, Q</td><td>L</td></tr> </table> <p style="font-size: small;">LS020505</p>	STATE	CODE	I, B, Q	L	<p>(T, F<sub>C</sub>, L, P, R, D)<sub>n</sub></p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>STATE</th><th>CODE</th></tr> <tr><td>DON'T CARE</td><td>-</td></tr> </table> <p style="font-size: small;">LS020605</p>	STATE	CODE	DON'T CARE	-
STATE	CODE																		
INACTIVE <sup>1,2</sup>	O																		
STATE	CODE																		
I, B, Q	H																		
STATE	CODE																		
I, B, Q	L																		
STATE	CODE																		
DON'T CARE	-																		

### "COMPLEMENT" ARRAY - (C)

<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>INACTIVE<sup>1,3,5</sup></td><td>O</td></tr> </table> <p style="font-size: small;">LS020705</p>	ACTION	CODE	INACTIVE <sup>1,3,5</sup>	O	<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>GENERATE<sup>5</sup></td><td>A</td></tr> </table> <p style="font-size: small;">LS020805</p>	ACTION	CODE	GENERATE <sup>5</sup>	A	<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>PROPAGATE</td><td>•</td></tr> </table> <p style="font-size: small;">LS020905</p>	ACTION	CODE	PROPAGATE	•	<p>(T<sub>n</sub>, F<sub>C</sub>)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>TRANSPARENT</td><td>-</td></tr> </table> <p style="font-size: small;">LS021005</p>	ACTION	CODE	TRANSPARENT	-
ACTION	CODE																		
INACTIVE <sup>1,3,5</sup>	O																		
ACTION	CODE																		
GENERATE <sup>5</sup>	A																		
ACTION	CODE																		
PROPAGATE	•																		
ACTION	CODE																		
TRANSPARENT	-																		

### "OR" ARRAY - (Q<sub>N</sub> = D - Type)

<p>M = ENABLE</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>T<sub>n</sub> STATUS</th><th>CODE</th></tr> <tr><td>ACTIVE (Set)</td><td>A</td></tr> </table> <p style="font-size: small;">LS021105</p>	T <sub>n</sub> STATUS	CODE	ACTIVE (Set)	A	<p>M = ENABLE</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>T<sub>n</sub> STATUS</th><th>CODE</th></tr> <tr><td>INACTIVE (Reset)</td><td>•</td></tr> </table> <p style="font-size: small;">LS021605</p>	T <sub>n</sub> STATUS	CODE	INACTIVE (Reset)	•
T <sub>n</sub> STATUS	CODE								
ACTIVE (Set)	A								
T <sub>n</sub> STATUS	CODE								
INACTIVE (Reset)	•								

### "OR" ARRAY - (F-F CONTROL MODE)

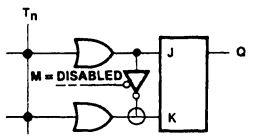
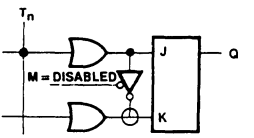
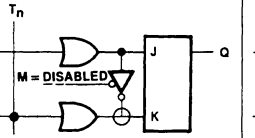
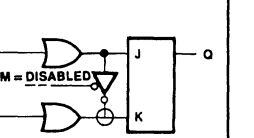
<p>Fc, M</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>JIK OR D (CONTROLLED)</td><td>A</td></tr> </table> <p style="font-size: small;">LS021305</p>	ACTION	CODE	JIK OR D (CONTROLLED)	A	<p>Fc, M</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>J-K</td><td>•</td></tr> </table> <p style="font-size: small;">LS021405</p>	ACTION	CODE	J-K	•
ACTION	CODE								
JIK OR D (CONTROLLED)	A								
ACTION	CODE								
J-K	•								

Notes on following page.

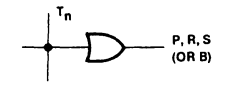
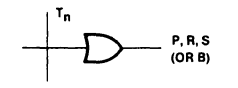
# Field-Programmable Logic Sequencer (20 × 45 × 12)

PLS179

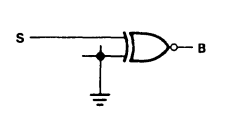
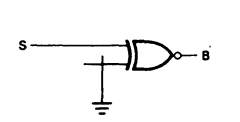
## "AND" ARRAY — ( $Q_n = J - K$ Type)

																			
<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>TOGGLE</td><td>O</td></tr> </table>	ACTION	CODE	TOGGLE	O	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>SET</td><td>H</td></tr> </table>	ACTION	CODE	SET	H	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>RESET</td><td>L</td></tr> </table>	ACTION	CODE	RESET	L	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>HOLD</td><td>-</td></tr> </table>	ACTION	CODE	HOLD	-
ACTION	CODE																		
TOGGLE	O																		
ACTION	CODE																		
SET	H																		
ACTION	CODE																		
RESET	L																		
ACTION	CODE																		
HOLD	-																		
<small>LS02170S</small>	<small>LS02180S</small>	<small>LS02190S</small>	<small>LS02200S</small>																

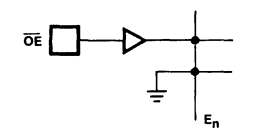
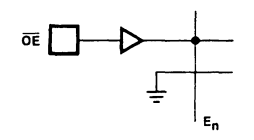
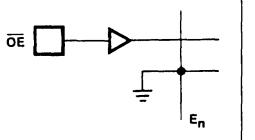
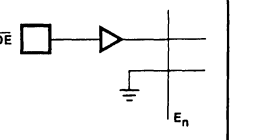
## "OR" ARRAY — (S or B)

									
<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th><math>T_n</math> STATUS</th><th>CODE</th></tr> <tr><td>ACTIVE</td><td>A</td></tr> </table>	$T_n$ STATUS	CODE	ACTIVE	A	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th><math>T_n</math> STATUS</th><th>CODE</th></tr> <tr><td>INACTIVE</td><td>•</td></tr> </table>	$T_n$ STATUS	CODE	INACTIVE	•
$T_n$ STATUS	CODE								
ACTIVE	A								
$T_n$ STATUS	CODE								
INACTIVE	•								
<small>LS02210S</small>	<small>LS02220S</small>								

## "EX-OR" ARRAY — (B)

									
<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>POLARITY</th><th>CODE</th></tr> <tr><td>LOW</td><td>L</td></tr> </table>	POLARITY	CODE	LOW	L	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>POLARITY</th><th>CODE</th></tr> <tr><td>HIGH</td><td>H</td></tr> </table>	POLARITY	CODE	HIGH	H
POLARITY	CODE								
LOW	L								
POLARITY	CODE								
HIGH	H								
<small>LS02230S</small>	<small>LS02240S</small>								

## "OE" ARRAY — (E)

																			
<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>IDLE<sup>4</sup></td><td>O</td></tr> </table>	ACTION	CODE	IDLE <sup>4</sup>	O	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>CONTROL</td><td>A</td></tr> </table>	ACTION	CODE	CONTROL	A	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>ENABLE<sup>4</sup></td><td>•</td></tr> </table>	ACTION	CODE	ENABLE <sup>4</sup>	•	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr><th>ACTION</th><th>CODE</th></tr> <tr><td>DISABLE</td><td>-</td></tr> </table>	ACTION	CODE	DISABLE	-
ACTION	CODE																		
IDLE <sup>4</sup>	O																		
ACTION	CODE																		
CONTROL	A																		
ACTION	CODE																		
ENABLE <sup>4</sup>	•																		
ACTION	CODE																		
DISABLE	-																		
<small>LS02250S</small>	<small>LS02260S</small>	<small>LS02270S</small>	<small>LS02280S</small>																

**NOTES:**

1. This is the initial unprogrammed state of all link pairs. It is normally associated with all unused (inactive) AND gates.
2. Any gate ( $T, F_C, L, P, R, D$ )<sub>n</sub> will be unconditionally inhibited if any one of the I, B, or Q link pairs is left intact.
3. To prevent oscillations, this state is not allowed for C link, pairs coupled to active gates  $T_n, F_C$ .
4.  $E_n = O$  and  $E_n = \cdot$  are logically equivalent states, since both cause  $F_n$  outputs to be unconditionally enabled.
5. These states are not allowed for control gates ( $L, P, R, D$ )<sub>n</sub> due to their lack of "OR" array links.

5

# Field-Programmable Logic Sequencer (20 × 45 × 12)

PLS179

## FPLS PROGRAM TABLE

AND		OR		CONTROL		NOTES																
INACTIVE <input type="checkbox"/> 0	I, B, Q <input type="checkbox"/> H	ACTIVE <input type="checkbox"/> A	R, R, B (O) <input type="checkbox"/> H	J/K <input type="checkbox"/> *	F/F MODE <input type="checkbox"/> 0			IDLE <input type="checkbox"/> 0	1. The FPLS is shipped with all links intact. Thus a background of entries corresponding to states of virgin links exists in the table, shown BLANK for clarity. 2. Program unused C, I, B, and O bits in the AND array as (-). Program unused Q, B, R, and P bits in the OR array as (-) or (A), as applicable. 3. Unused Terms can be left blank. 4. Q (P) and Q (N) are respectively the present and next states of flip-flops Q.													
I, B, Q <input type="checkbox"/> L	I, B, Q (P) <input type="checkbox"/> Q	INACTIVE <input type="checkbox"/> *	(Q = D)	J/K or D (CONTROLLED) <input type="checkbox"/> A	CONTROL <input type="checkbox"/> A	CONTROL <input type="checkbox"/> A																
DON'T CARE <input type="checkbox"/> -					ENABLE <input type="checkbox"/> *	ENABLE <input type="checkbox"/> *	EA, B															
INACTIVE <input type="checkbox"/> 0	GENERATE <input type="checkbox"/> A	TOGGLE <input type="checkbox"/> 0	SET <input type="checkbox"/> H	HIGH <input type="checkbox"/> H																		
PROPAGATE <input type="checkbox"/> *	TRANSPARENT <input type="checkbox"/> -	RESET <input type="checkbox"/> L	(Q = J/K)	LOW <input type="checkbox"/> L																		
TRANSPARENT <input type="checkbox"/> -	C	HOLD <input type="checkbox"/> -		(POL.)																		
THIS PORTION TO BE COMPLETED BY SIGNETICS CF (XXXX) _____ CUSTOMER SYMBOLIZED PART # _____ DATE RECEIVED _____ COMMENTS _____		F/F MODE		EB		EA		POLARITY														
		AND		OR																		
		B (I)	Q (P)																			
		7 6 5 4 3 2 1 0	7 6 5 4 3 2 1 0																			
CUSTOMER NAME _____ PURCHASE ORDER # _____ SIGNETICS DEVICE # _____ TOTAL NUMBER OF PARTS _____ PROGRAM TABLE # _____ REV _____ DATE _____		T																				
		E																				
		R																				
		M																				
		0																				
		1																				
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R <sub>A</sub>																						
L <sub>A</sub>																						
D <sub>3</sub>																						
D <sub>2</sub>																						
D <sub>1</sub>																						
D <sub>0</sub>																						
PIN	9	8	7	6	5	4	3	2	14	11	10	22	21	20	19	18	17	16	15			

T801711S

# PLS105

## Field-Programmable Logic Sequencer (16 × 48 × 8)

Signetics Programmable Logic  
Product Specification

Application Specific Products  
• Series 28

### DESCRIPTION

The PLS105 is a bipolar programmable state machine of the Mealy type. It contains logic AND-OR gate arrays with user programmable connections which control the inputs of on-chip State and Output Registers. These consist respectively of 6  $Q_P$ , and 8  $Q_F$  edge-triggered, clocked S/R flip-flops, with an Asynchronous Preset option. All flip-flops are unconditionally preset to "1" during power turn on.

The AND array combines 16 external inputs  $I_0-15$  with six internal inputs  $P_0-5$ , which are fed back from the State Registers to form up to 48 transition terms (AND terms). All transition terms can include True, False, or Don't Care states of the controlling variables, and are merged in the OR array to issue next-state and next-output commands to their respective registers on the Low-to-High transition of the Clock pulse. Both True and Complement transition terms can be generated by optional use of the internal input variable (C) from the Complement Array. Also, if desired, the Preset input can be converted to Output Enable function, as an additional user-programmable option.

Order codes are listed in the Ordering Information Table.

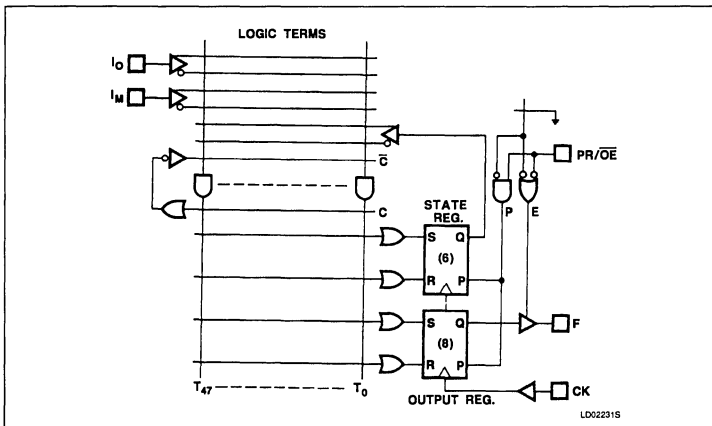
### FEATURES

- $f_{MAX} = 13.9\text{MHz}$
- 20MHz clock rate
- Field-Programmable (Ni-Cr link)
- 16 input variables
- 8 output functions
- 48 transition terms
- 6-bit State Register
- 8-bit Output Register
- Transition Complement Array
- Positive edge-triggered clocked flip-flops
- Programmable Asynchronous Preset or Output Enable
- Power-on preset to all "1" of internal registers
- Power dissipation: 600mW (typ.)
- TTL compatible
- Single +5V supply
- 3-State outputs

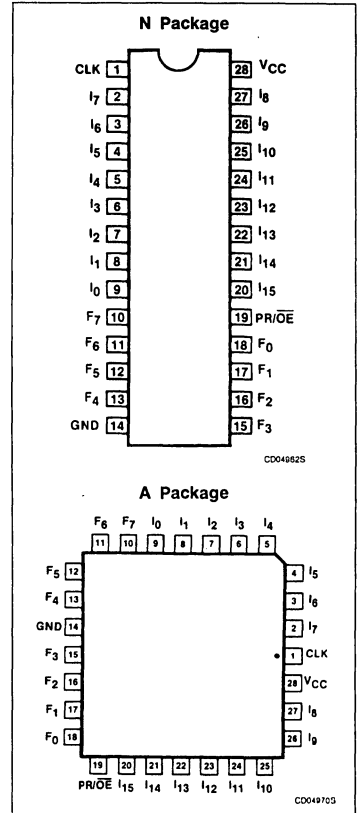
### APPLICATIONS

- Interface protocols
- Sequence detectors
- Peripheral controllers
- Timing generators
- Sequential circuits
- Elevator controllers
- Security locking systems
- Counters
- Shift registers

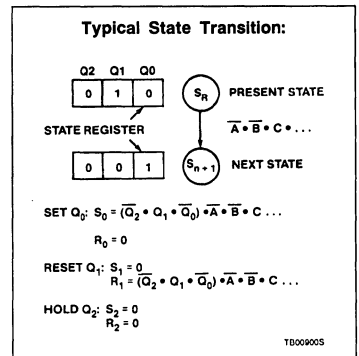
### FUNCTIONAL DIAGRAM



### PIN CONFIGURATIONS



### LOGIC FUNCTION





## Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105

## PIN DESCRIPTION

PIN NO.	SYMBOL	NAME AND FUNCTION	POLARITY
1	CK	<b>Clock:</b> The Clock input to the State and Output Registers. A Low-to-High transition on this line is necessary to update the contents of both registers.	Active-High
2-8 20-27	I <sub>1-15</sub>	<b>Logic Inputs:</b> The 15 external inputs to the AND array used to program jump conditions between machine states, as determined by a given logic sequence.	Active-High/Low
9	I <sub>0</sub>	<b>Logic/Diagnostic Input:</b> A 16th external logic input to the AND array, as above, when exercised with standard TTL levels. When I <sub>0</sub> is held at +10V, device outputs F <sub>0-5</sub> reflect the contents of State Register bits P <sub>0-5</sub> . The contents of each Output Register remains unaltered.	Active-High/Low
10-13 15-18	F <sub>0-7</sub>	<b>Logic/Diagnostic Outputs:</b> Eight device outputs which normally reflect the contents of Output Register bits Q <sub>0-7</sub> , when enabled. When I <sub>0</sub> is held at +10V, F <sub>0-5</sub> = (P <sub>0-5</sub> ), and F <sub>6,7</sub> = Logic "1".	Active-High
19	PR/ŌE	<b>Preset or Output Enable Input:</b> A user programmable function: <ul style="list-style-type: none"> <li>• <b>Preset:</b> Provides an Asynchronous Preset to logic "1" of all State and Output Register bits. Preset overrides Clock, and when held High, clocking is inhibited and F<sub>0-7</sub> are High. Normal clocking resumes with the first full clock pulse following a High-to-Low clock transition, after Preset goes Low.</li> <li>• <b>Output Enable:</b> Provides an Output Enable function to all output buffers F<sub>0-7</sub> from the Output Register.</li> </ul>	Active-High (H)  Active-Low (L)

## TRUTH TABLE 1, 2, 3, 4, 5, 6

V <sub>CC</sub>	OPTION		I <sub>0</sub>	CK	S	R	Q <sub>P/F</sub>	F	
	PR	ŌE							
+5V	H		*	X	X	X	H	H	
	L		+10V	X	X	X	Q <sub>n</sub>	(Q <sub>P</sub> ) <sub>n</sub>	
	L		X	X	X	X	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>	
		H	L	*	X	X	X	Q <sub>n</sub>	Hi-Z
				+10V	X	X	X	Q <sub>n</sub>	(Q <sub>P</sub> ) <sub>n</sub>
				X	X	X	X	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>
		L	L	X	↑	L	L	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>
				X	↑	L	H	L	L
				X	↑	H	L	H	H
		L	L	X	↑	H	H	IND.	IND.
				X	↑	H	H	IND.	IND.
	↑	X	X	X	X	X	X	H	

## NOTES:

- Positive Logic:  
 $S/R = T_0 + T_1 + T_2 + \dots + T_{47}$   
 $T_n = C(I_0 I_1 I_2 \dots) (P_0 P_1 \dots P_5)$
- Either Preset (Active-High) or Output Enable (Active-Low) are available, but not both. The desired function is a user-programmable option.
- ↑ denotes transition from Low to High level.
- R = S = High is an illegal input condition.
- \* = H/L/+10V
- X = Don't Care ( $\leq 5.5V$ )

## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

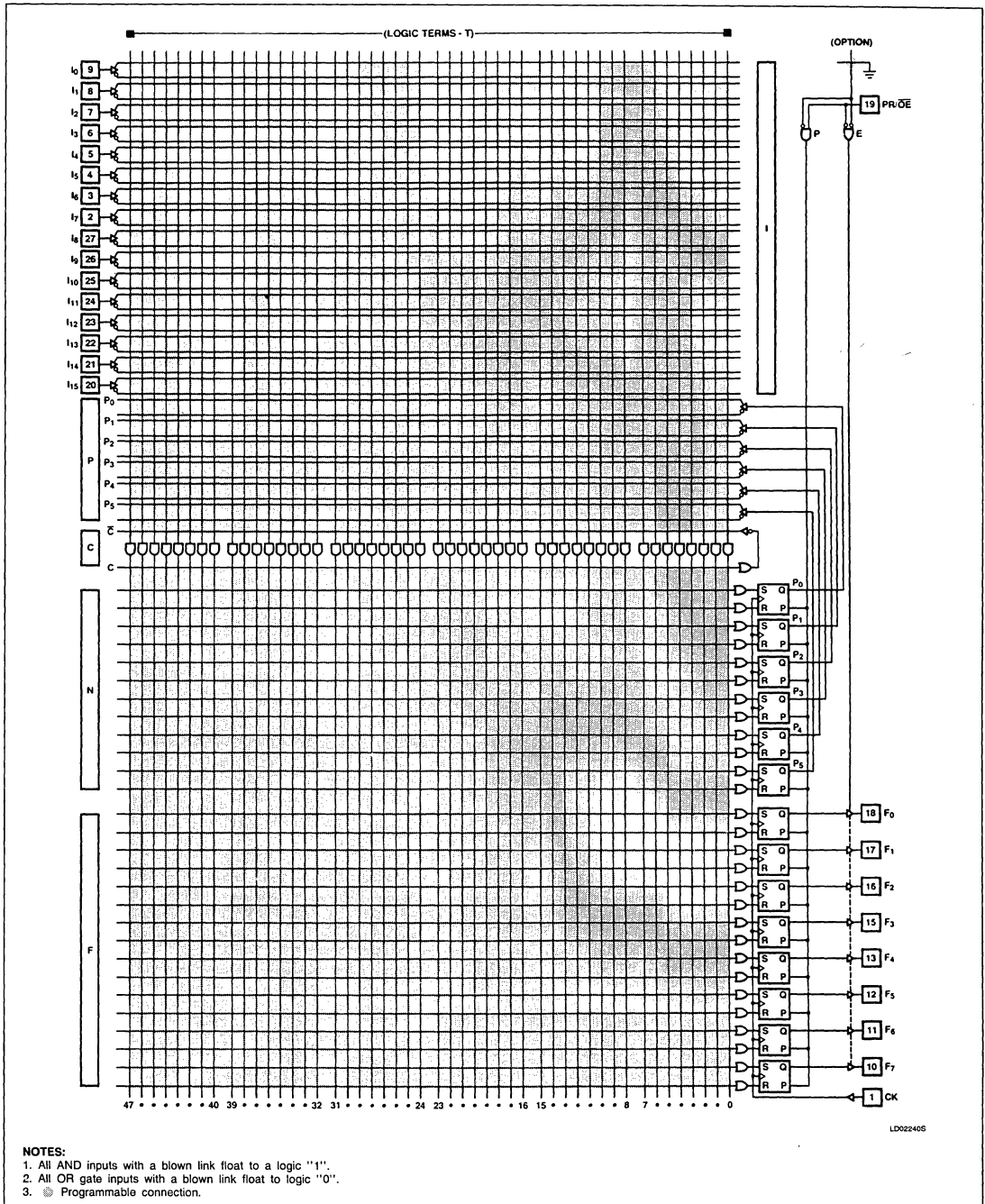
- PR/ŌE option is set to PR. Thus, all outputs will be at "1", as preset by initial power-up procedure.
- All transition terms are disabled (0).
- All S/R flip-flop inputs are disabled (0).
- The device can be clocked via a Test Array pre-programmed with a standard test pattern.

NOTE: The Test Array pattern MUST be deleted before incorporating a user program. This is accomplished automatically when using Signetics qualified programming equipment.

# Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105

## FPLS LOGIC DIAGRAM



5

## Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
28-pin Plastic DIP 600mil-wide	PLS105N
28-pin Plastic Leaded Chip Carrier	PLS105A

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

## Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105

**DC ELECTRICAL CHARACTERISTICS**  $0^{\circ}\text{C} \leq T_A \leq 75^{\circ}\text{C}$ ,  $4.75\text{V} \leq V_{CC} \leq 5.25\text{V}$ 

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
$V_{IH}$	High	$V_{CC} = \text{Max}$	2			V
$V_{IL}$	Low	$V_{CC} = \text{Min}$			0.8	V
$V_{IC}$	Clamp <sup>3</sup>	$V_{CC} = \text{Min}$ , $I_{IN} = -12\text{mA}$		-0.8	-1.2	V
<b>Output voltage<sup>2</sup></b>						
$V_{OH}$	High <sup>4</sup>	$V_{CC} = \text{Min}$	2.4			V
$V_{OL}$	Low <sup>5</sup>	$I_{OH} = -2\text{mA}$ $I_{OL} = 9.6\text{mA}$		0.35	0.45	V
<b>Input current</b>						
$I_{IH}$	High	$V_{IN} = 5.5\text{V}$		< 1	25	$\mu\text{A}$
$I_{IL}$	Low	$V_{IN} = 0.45\text{V}$		-10	-100	$\mu\text{A}$
$I_{IL}$	Low (CK input)	$V_{IN} = 0.45\text{V}$		-50	-250	$\mu\text{A}$
<b>Output current</b>						
$I_{O(\text{OFF})}$	Hi-Z state <sup>6</sup>	$V_{CC} = \text{Max}$ $V_{OUT} = 5.5\text{V}$		1	40	$\mu\text{A}$
$I_{OS}$	Short circuit <sup>3, 7</sup>	$V_{OUT} = 0.45\text{V}$ $V_{OUT} = 0\text{V}$	-15	-1	-40 -70	$\text{mA}$
$I_{CC}$	$V_{CC}$ supply current <sup>8</sup>	$V_{CC} = \text{Max}$		120	180	$\text{mA}$
<b>Capacitance<sup>6</sup></b>						
$C_{IN}$	Input	$V_{CC} = 5.0\text{V}$ $V_{IN} = 2.0\text{V}$		8		$\text{pF}$
$C_{OUT}$	Output	$V_{OUT} = 2.0\text{V}$		10		$\text{pF}$

**NOTES:**

- All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- Measured with  $V_{IL}$  applied to  $\overline{OE}$  and a logic high stored, or with  $V_{IH}$  applied to PR.
- Measured with a programmed logic condition for which the output is at a low logic level, and  $V_{IL}$  applied to PR/ $\overline{OE}$ . Output sink current is supplied through a resistor to  $V_{CC}$ .
- Measured with  $V_{IH}$  applied to PR/ $\overline{OE}$ .
- Duration of short circuit should not exceed 1 second.
- $I_{CC}$  is measured with the PR/ $\overline{OE}$  input grounded, all other inputs at 4.5V and the outputs open.

5

## Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105

**AC ELECTRICAL CHARACTERISTICS**  $R_1 = 470\Omega$ ,  $R_2 = 1k\Omega$ ,  $C_L = 30pF$ ,  $0^\circ C \leq T_A \leq +75^\circ C$ ,  $4.75V \leq V_{CC} \leq 5.25V$ 

SYMBOL	PARAMETER	TO	FROM	LIMITS			UNIT
				Min	Typ <sup>1</sup>	Max	
<b>Pulse width</b>							
$t_{CKH}$	Clock <sup>2</sup> High	CK -	CK +	25	15		ns
$t_{CKL}$	Clock Low	CK +	CK -	25	15		
$t_{CKP1B}$	Period (without Complement Array)	CK +	CK +	80	40		
$t_{CKP2B}$	Period (with Complement Array)	CK +	CK +	120	60		
$t_{PRH}$	Preset pulse	PR -	PR +	25	15		
<b>Setup time<sup>3</sup></b>							
$t_{IS1A}$	Input	CK +	Input $\pm$	60			ns
$t_{IS1B}$	Input	CK +	Input $\pm$	50			
$t_{IS1C}$	Input	CK +	Input $\pm$	42			
$t_{IS2A}$	Input (through Complement Array)	CK +	Input $\pm$	90			
$t_{IS2B}$	Input (through Complement Array)	CK +	Input	80			
$t_{IS2C}$	Input (through Complement Array)	CK +	Input	72			
$t_{VS}$	Power-on preset	CK -	$V_{CC} +$	0	-10		
$t_{PRS}$	Preset	CK -	PR -	0	-10		
<b>Hold time</b>							
$t_{IH}$	Input	Input $\pm$	CK +	5	-10		ns
<b>Propagation delay</b>							
$t_{CKO}$	Clock	Output $\pm$	CK +		15	30	ns
$t_{OE}$	Output enable	Output -	OE -		20	30	
$t_{OD}$	Output disable	Output +	OE +		20	30	
$t_{PR}$	Preset	Output +	PR +		18	30	
$t_{PPR}$	Power-on preset	Output +	$V_{CC} +$		0	10	
<b>Frequency of operation<sup>3</sup></b>							
$f_{MAXC}$	Without Complement Array					13.9	MHz
$f_{MAXC}$	With Complement Array					9.8	

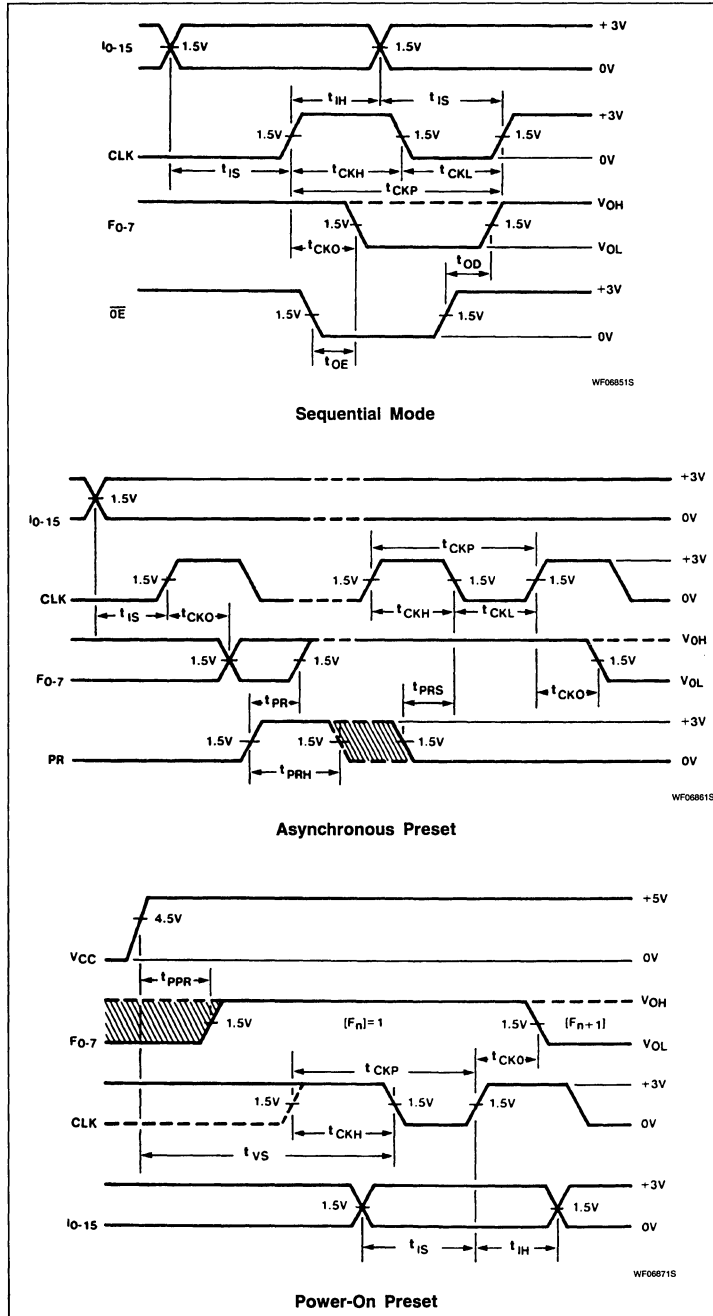
**NOTES:**

- All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
- To prevent spurious clocking, clock rise time (10% - 90%)  $\leq 30ns$ .
- See "Speed vs. OR Loading" diagrams.

# Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105

## TIMING DIAGRAMS



## TIMING DEFINITIONS

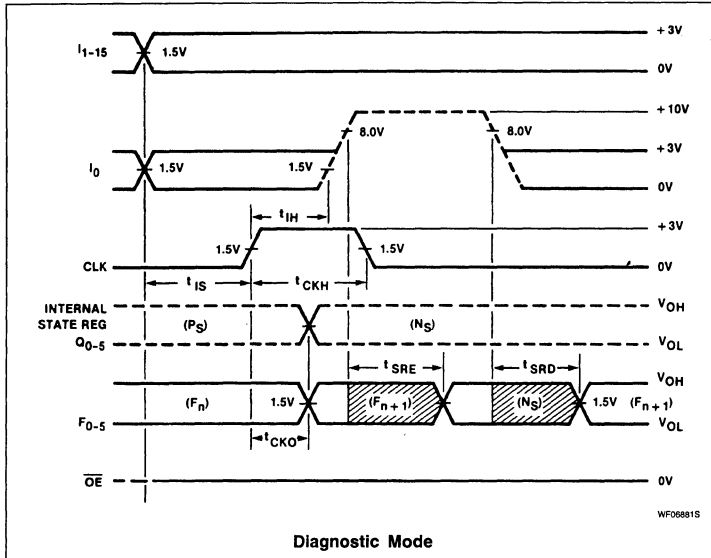
SYMBOL	PARAMETER
$t_{CKH}$	Width of input clock pulse.
$t_{CKL}$	Interval between clock pulses.
$t_{CKP1}$	Clock period - when not using Complement Array.
$t_{IS1}$	Required delay between beginning of valid input and positive transition of Clock.
$t_{CKP2}$	Clock period - when using Complement Array.
$t_{IS2}$	Required delay between beginning of valid input and positive transition of Clock, when using optional Complement Array (two passes necessary through the AND Array).
$t_{VS}$	Required delay between $V_{CC}$ (after power-on) and negative transition of Clock preceding first reliable clock pulse.
$t_{PRS}$	Required delay between negative transition of Asynchronous Preset and negative transition of Clock preceding first reliable clock pulse.
$t_{IH}$	Required delay between positive transition of Clock and end of valid Input data.
$t_{CKO}$	Delay between positive transition of clock and when outputs become valid (with $\overline{PR}/\overline{OE}$ Low).
$t_{OE}$	Delay between beginning of Output Enable Low and when Outputs become valid.
$t_{OD}$	Delay between beginning of Output Enable High and when Outputs are in the OFF-state.
$t_{SRE}$	Delay between input $I_0$ transition to Diagnostic Mode and when the Outputs reflect the contents of the State Register.
$t_{SRD}$	Delay between input $I_0$ transition to Logic mode and when the Outputs reflect the contents of the Output Register.
$t_{PR}$	Delay between positive transition of Preset and when Outputs become valid at "1".
$t_{PPR}$	Delay between $V_{CC}$ (after power-on) and when Outputs become preset at "1".
$t_{PRH}$	Width of preset input pulse.
$f_{MAX}$	Maximum clock frequency.

5

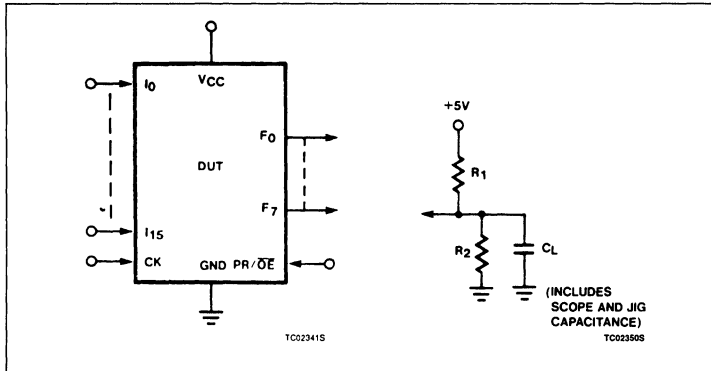
# Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105

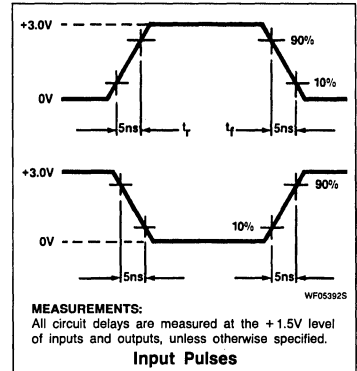
## TIMING DIAGRAMS (Continued)



## TEST LOAD CIRCUITS



## VOLTAGE WAVEFORMS



# Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105

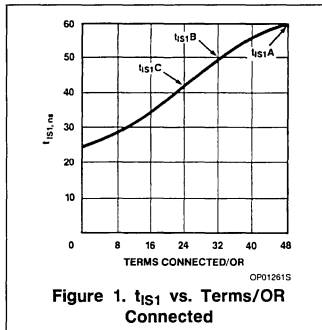
## SPEED VS. "OR" LOADING

The maximum frequency at which the FPLS can be clocked while operating in *sequential mode* is given by:

$$(1/f_{MAX}) = t_{CY} = t_{IS} + t_{CKO}$$

This frequency depends on the number of transition terms  $T_n$  used. Having all 48 terms connected in the AND array does not appreciably impact performance; but the number of terms connected to each OR line affects  $t_{IS}$ , due to capacitive loading. The effect of this loading can be seen in Figure 1, showing the variation of  $t_{IS1}$  with the number of terms connected per OR.

The AC electrical characteristics contain three limits for the parameters  $t_{IS1}$  and  $t_{IS2}$ . The first,  $t_{IS1A}$  is guaranteed for a device with 48 terms connected to any OR line.  $t_{IS1B}$  is guaranteed for a device with 32 terms connected to any OR line. And  $t_{IS1C}$  is guaranteed for a device with 24 terms connected to any OR line.



**Figure 1.  $t_{IS1}$  vs. Terms/OR Connected**

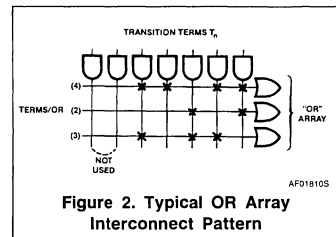
The three other entries in the AC table,  $t_{IS2}$  A, B, and C are corresponding 48, 32, and 24 term limits when using the on-chip Complement Array.

The worst case  $t_{IS}$  for a given application can be determined by identifying the OR line with the maximum number of  $t_n$  connections. This can be done by referring to

the interconnect pattern in the FPLS logic diagram, typically illustrated in Figure 2, or by counting the maximum number of "H" or "L" entries in one of the columns of the device Program Table.

This number plotted on the curve in Figure 1 will yield the worst case  $t_{IS}$  and, by implication, the maximum clocking frequency for reliable operation.

*Note that for maximum speed all UNUSED transition terms should be disconnected from the OR array.*



**Figure 2. Typical OR Array Interconnect Pattern**

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# Field-Programmable Logic Sequencer (16 × 48 × 8)

# PLS105

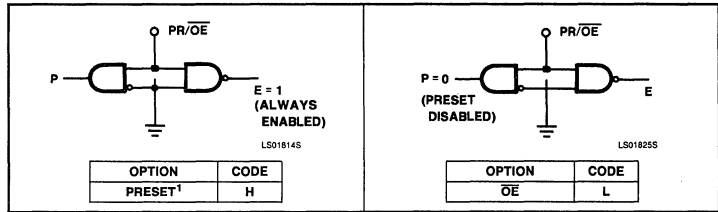
## LOGIC PROGRAMMING

PLS105 logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

PLS105 logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

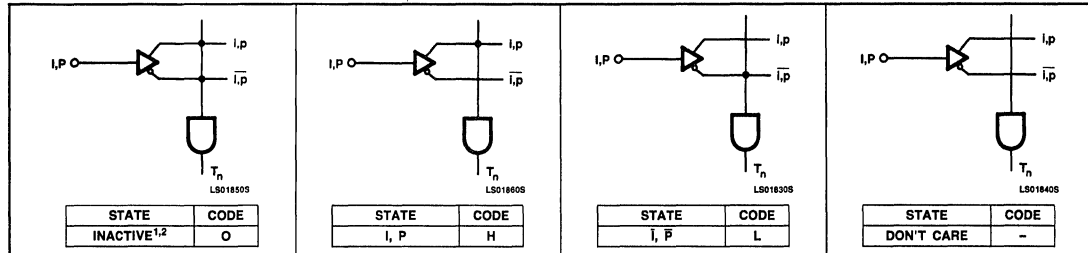
## PRESET/OE OPTION - (P/E)



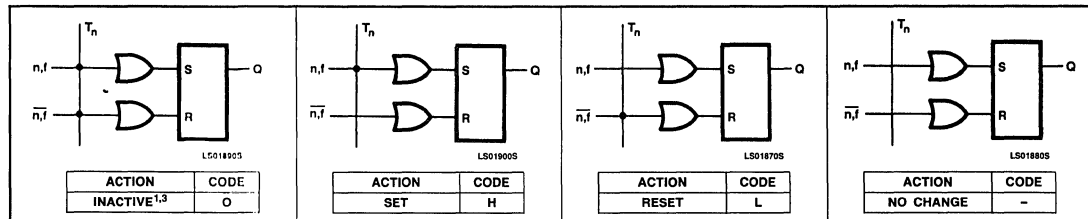
## PROGRAMMING THE PLS105:

The PLS105 has a power-up preset feature. This feature insures that the device will power-up in a known state with all register elements (state and output register) at a logic High (H). When programming the device it is important to realize this is the initial state of the device. You must provide a next state jump if you do not wish to use all Highs (H) as the present state.

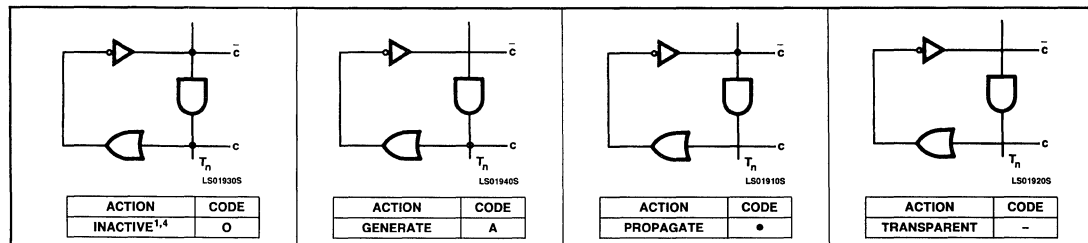
## "AND" ARRAY - (I), (P)



## "OR" ARRAY - (N), (F)



## "COMPLEMENT" ARRAY - (C)



### NOTES:

1. This is the initial unprogrammed state of all links.
2. Any gate  $T_n$  will be unconditionally inhibited if both the true and complement fuses of any input (I,P) are left intact.
3. To prevent simultaneous Set and Reset flip-flop commands, this state is not allowed for N and F link pairs coupled to active gates  $T_n$  (see flip-flop truth tables).
4. To prevent oscillations, this state is not allowed for C link pairs coupled to active gates  $T_n$ .





# PLS105A

## Field-Programmable Logic Sequencer (16 × 48 × 8)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

• Series 28

### DESCRIPTION

The PLS105A is a bipolar programmable state machine of the Mealy type. It contains logic AND-OR gate arrays with user programmable connections which control the inputs of on-chip State and Output Registers. These consist respectively of 6  $Q_p$ , and 8  $Q_f$  edge-triggered, clocked S/R flip-flops, with an Asynchronous Preset option. All flip-flops are unconditionally preset to "1" during power turn on.

The AND array combines 16 external inputs  $I_0$ – $I_{15}$  with 6 internal inputs  $P_0$ – $P_5$ , which are fed back from the State Registers to form up to 48 Transition terms (AND terms). All Transition terms can include True, False, or Don't Care states of the controlling variables, and are merged in the OR array to issue next-state and next-output commands to their respective registers on the Low-to-High transition of the Clock pulse. Both True and Complement Transition terms can be generated by optional use of the internal input variable (C) from the Complement Array. Also, if desired, the Preset input can be converted to Output-Enable function, as an additional user programmable option.

Order codes are listed in the Ordering Information Table.

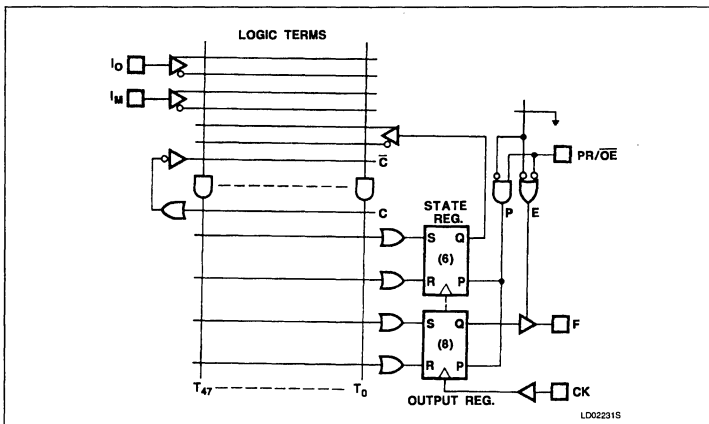
### FEATURES

- $f_{MAX} = 20\text{MHz}$
- - 25MHz clock rate
- Field-Programmable (Ni-Cr link)
- 16 input variables
- 8 output functions
- 48 transition terms
- 6-bit State Register
- 8-bit Output Register
- Transition complement array
- Positive edge-triggered clocked flip-flops
- Programmable Asynchronous Preset or Output Enable
- Power-on preset to all "1" of internal registers
- Power dissipation: 600mW (typ.)
- TTL compatible
- Single +5V supply
- 3-State outputs

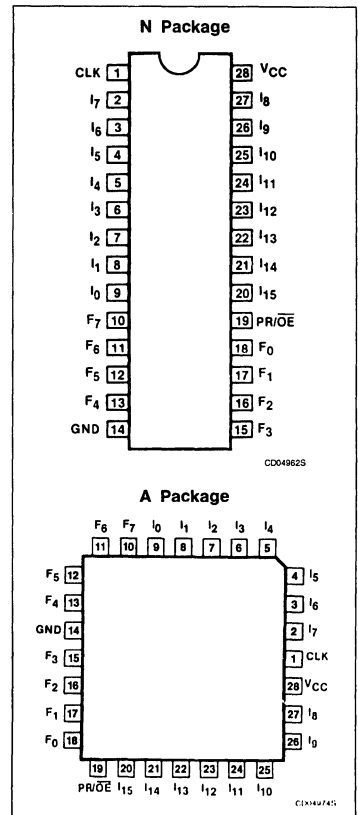
### APPLICATIONS

- Interface protocols
- Sequence detectors
- Peripheral controllers
- Timing generators
- Sequential circuits
- Elevator controllers
- Security locking systems
- Counters
- Shift registers

### FUNCTIONAL DIAGRAM



### PIN CONFIGURATIONS



5

# Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105A

## PIN DESCRIPTION

PIN NO.	SYMBOL	NAME AND FUNCTION	POLARITY
1	CK	<b>Clock:</b> The Clock input to the State and Output Registers. A Low-to-High transition on this line is necessary to update the contents of both registers.	Active-High
2-8 20-27	I <sub>1-15</sub>	<b>Logic Inputs:</b> The 15 external inputs to the AND array used to program jump conditions between machine states, as determined by a given logic sequence.	Active-High/Low
9	I <sub>0</sub>	<b>Logic/Diagnostic Input:</b> A 16th external logic input to the AND array, as above, when exercised with standard TTL levels. When I <sub>0</sub> is held at +10V, device outputs F <sub>0-5</sub> reflect the contents of State Register bits P <sub>0-5</sub> . The contents of each Output Register remains unaltered.	Active-High/Low
10-13 15-18	F <sub>0-7</sub>	<b>Logic/Diagnostic Outputs:</b> Eight device outputs which normally reflect the contents of Output Register bits Q <sub>0-7</sub> , when enabled. When I <sub>0</sub> is held at +10V, F <sub>0-5</sub> = (P <sub>0-5</sub> ), and F <sub>6, 7</sub> = Logic "1".	Active-High
19	PR/ $\overline{OE}$	<b>Preset or Output Enable Input:</b> A user programmable function: <ul style="list-style-type: none"> <li>• <b>Preset:</b> Provides an Asynchronous Preset to logic "1" of all State and Output Register bits. Preset overrides Clock, and when held High, clocking is inhibited and F<sub>0-7</sub> are High. Normal clocking resumes with the first full clock pulse following a High-to-Low clock transition, after Preset goes Low.</li> <li>• <b>Output Enable:</b> Provides an output enable function to buffers F<sub>0-7</sub> from the Output Register.</li> </ul>	Active-High (H)  Active-Low (L)

## TRUTH TABLE 1, 2, 3, 4, 5, 6

V <sub>cc</sub>	OPTION		I <sub>0</sub>	CK	S	R	Q <sub>P/F</sub>	F	
	PR	$\overline{OE}$							
+5V	H		*	X	X	X	H	H	
	L		+10V	X	X	X	Q <sub>n</sub>	(Q <sub>P</sub> ) <sub>n</sub>	
	L		X	X	X	X	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>	
		H	*	X	X	X	Q <sub>n</sub>	Hi-Z	
		L	+10V	X	X	X	Q <sub>n</sub>	(Q <sub>P</sub> ) <sub>n</sub>	
		L	X	X	X	X	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>	
		L	X	↑	L	L	Q <sub>n</sub>	(Q <sub>F</sub> ) <sub>n</sub>	
		L	X	↑	L	H	L	L	
		L	X	↑	H	L	H	H	
		L	X	↑	H	H	IND.	IND.	
	↑	X	X	X	X	X	X	H	

## VIRGIN STATE

A factory shipped virgin device contains all fusible links intact, such that:

1. PR/ $\overline{OE}$  option is set to PR. Thus, all outputs will be at "1", as preset by initial power-up procedure.
2. All transition terms are disabled (0).
3. All S/R flip-flop inputs are disabled (0).
4. The device can be clocked via a Test Array pre-programmed with a standard test pattern.

NOTE: The Test Array pattern MUST be deleted before incorporating a user program. This is accomplished automatically when using any of Signetics' qualified programming equipment.

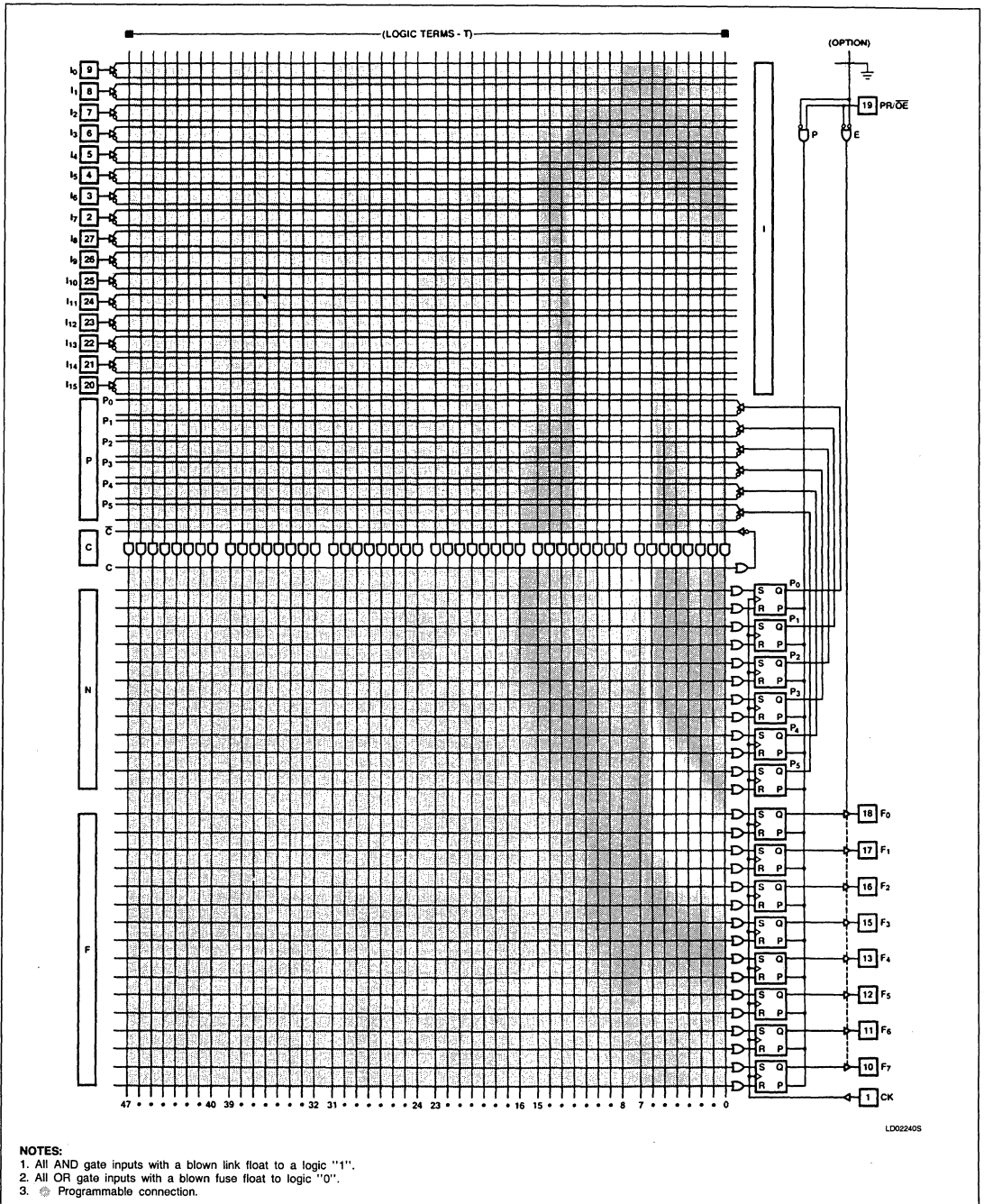
### NOTES:

1. Positive Logic:  
 $S/R = T_0 + T_1 + T_2 + \dots + T_{47}$   
 $T_n = C(I_0 I_1 I_2 \dots) (P_0 P_1 \dots P_5)$
2. Either Preset (Active-High) or Output Enable (Active-Low) are available, but not both. The desired function is a user-programmable option.
3. ↑ denotes transition from Low to High level.
4. R = S = High is an illegal input condition.
5. \* = H/L/+10V
6. X = Don't Care (<=5.5V)

# Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105A

## FPLS LOGIC DIAGRAM



5

## Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105A

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
28-pin Plastic DIP 600mil-wide	PLS105AN
28-pin Plastic Leaded Chip Carrier	PLS105AA

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

## Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105A

**DC ELECTRICAL CHARACTERISTICS** 0°C ≤ T<sub>A</sub> ≤ 75°C, 4.75V ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IH</sub>	High	V <sub>CC</sub> = Max	2			V
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min			0.8	V
V <sub>IC</sub>	Clamp <sup>3</sup>	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA		-0.8	-1.2	V
<b>Output voltage<sup>2</sup></b>						
V <sub>OH</sub>	High <sup>4</sup>	V <sub>CC</sub> = Min	2.4			V
V <sub>OL</sub>	Low <sup>5</sup>	I <sub>OH</sub> = -2mA I <sub>OL</sub> = 9.6mA		0.35	0.45	V
<b>Input current</b>						
I <sub>IH</sub>	High	V <sub>IN</sub> = 5.5V		< 1	25	μA
I <sub>IL</sub>	Low	V <sub>IN</sub> = 0.45V		-10	-100	μA
I <sub>IL</sub>	Low (CK input)	V <sub>IN</sub> = 0.45V		-50	-250	μA
<b>Output current</b>						
I <sub>O(OFF)</sub>	Hi-Z state <sup>6</sup>	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V		1	40	μA
I <sub>OS</sub>	Short circuit <sup>3, 7</sup>	V <sub>OUT</sub> = 0.45V V <sub>OUT</sub> = 0V	-15	-1	-40 -70	μA mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>8</sup>	V <sub>CC</sub> = Max		120	180	mA
<b>Capacitance<sup>6</sup></b>						
C <sub>IN</sub>	Input	V <sub>CC</sub> = 5.0V V <sub>IN</sub> = 2.0V		8		pF
C <sub>OUT</sub>	Output	V <sub>OUT</sub> = 2.0V		10		pF

**NOTES:**

- All typical values are at V<sub>CC</sub> = 5V, T<sub>A</sub> = +25°C.
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- Measured with V<sub>IL</sub> applied to  $\overline{OE}$  and a logic high stored, or with V<sub>IH</sub> applied to PR.
- Measured with a programmed logic condition for which the output is at a low logic level, and V<sub>IL</sub> applied to PR/ $\overline{OE}$ . Output sink current is supplied through a resistor to V<sub>CC</sub>.
- Measured with V<sub>IH</sub> applied to PR/ $\overline{OE}$ .
- Duration of short circuit should not exceed 1 second.
- I<sub>CC</sub> is measured with the PR/ $\overline{OE}$  input grounded, all other inputs at 4.5V and the outputs open.

5



## Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105A

**AC ELECTRICAL CHARACTERISTICS**  $R_1 = 470\Omega$ ,  $R_2 = 1k\Omega$ ,  $C_L = 30pF$ ,  $0^\circ C \leq T_A \leq +75^\circ C$ ,  $4.75V \leq V_{CC} \leq 5.25V$ 

SYMBOL	PARAMETER	TO	FROM	LIMITS			UNIT
				Min	Typ <sup>1</sup>	Max	
<b>Pulse width</b>							
t <sub>CKH</sub>	Clock <sup>2</sup> High	CK -	CK +	20	15		ns
t <sub>CKL</sub>	Clock Low	CK +	CK -	20	15		
t <sub>CKP1B</sub>	Period (without Complement Array)	CK +	CK +	50	40		
t <sub>CKP2B</sub>	Period (with Complement Array)	CK +	CK +	80	50		
t <sub>PRH</sub>	Preset pulse	PR -	PR +	25	15		
<b>Setup time<sup>3</sup></b>							
t <sub>IS1A</sub>	Input	CK +	Input ±	40			ns
t <sub>IS1B</sub>	Input	CK +	Input ±	30			
t <sub>IS2A</sub>	Input (through Complement Array)	CK +	Input ±	70			
t <sub>IS2B</sub>	Input (through Complement Array)	CK +	Input	60			
t <sub>VS</sub>	Power-on preset	CK -	V <sub>CC</sub> +	0	-10		
t <sub>PRS</sub>	Preset	CK -	PR -	0	-10		
<b>Hold time</b>							
t <sub>H</sub>	Input	Input ±	CK +	5	-10		ns
<b>Propagation delay</b>							
t <sub>CKO</sub>	Clock	Output ±	CK +		15	20	ns
t <sub>OE</sub>	Output enable	Output -	OE -		20	30	
t <sub>OD</sub>	Output disable	Output +	OE +		20	30	
t <sub>PR</sub>	Preset	Output +	PR +		18	30	
t <sub>PPR</sub>	Power-on preset	Output +	V <sub>CC</sub> +		0	10	
<b>Frequency of operation</b>							
f <sub>MAXB</sub>	Without Complement Array					20	MHz
f <sub>MAXB</sub>	With Complement Array					12.5	

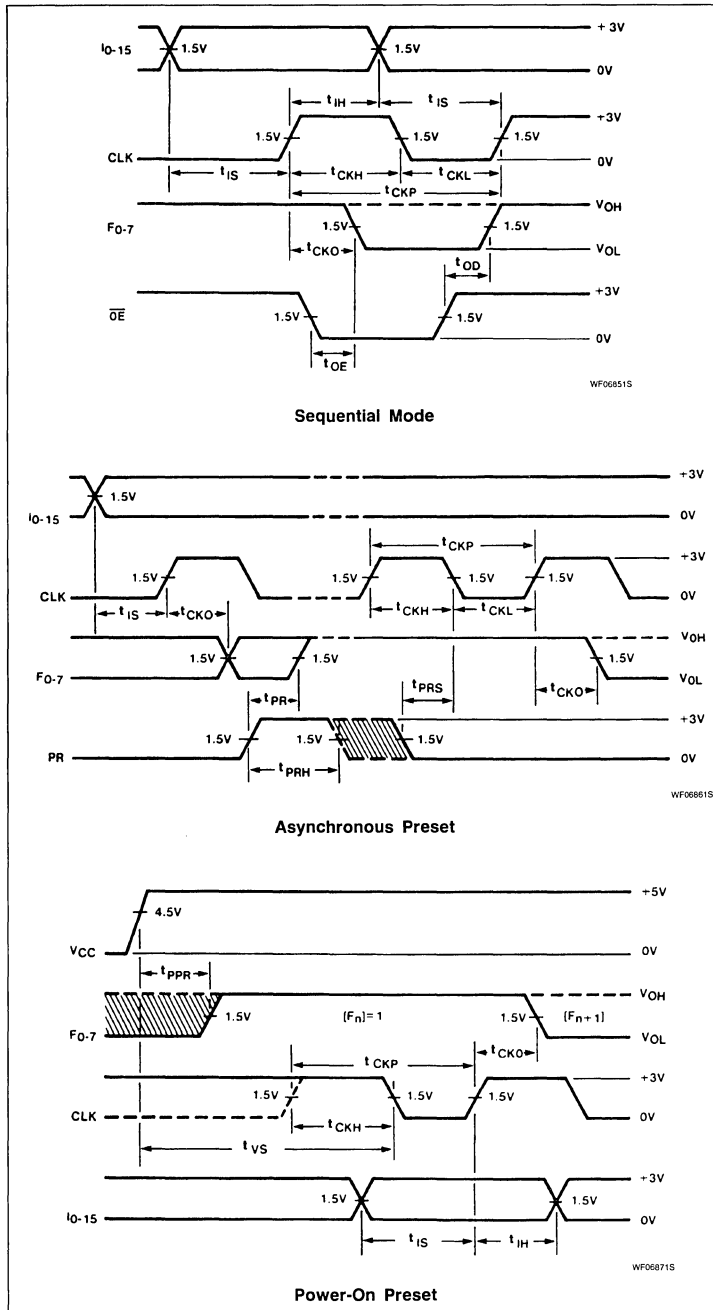
**NOTES:**

- All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
- To prevent spurious clocking, clock rise time (10% - 90%)  $\leq 30ns$ .
- See "Speed vs. OR Loading" diagrams.

# Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105A

## TIMING DIAGRAMS



## TIMING DEFINITIONS

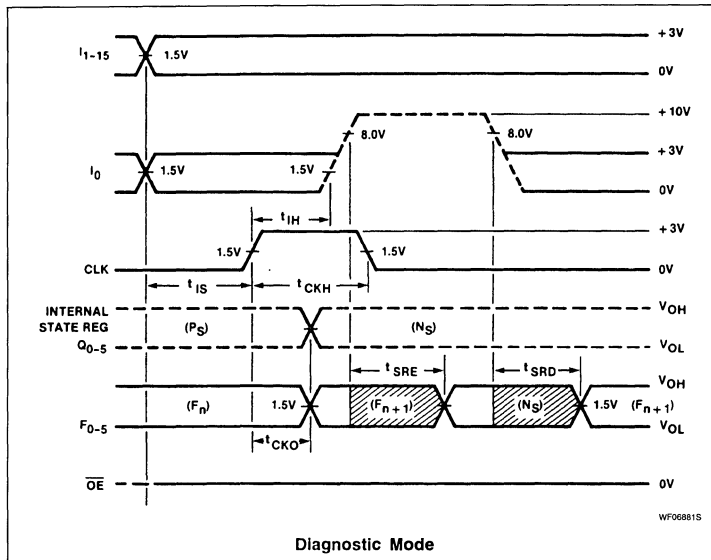
SYMBOL	PARAMETER
$t_{CKH}$	Width of input clock pulse.
$t_{CKL}$	Interval between clock pulses.
$t_{CKP}$	Clock period — when not using Complement Array.
$t_{IS1}$	Required delay between beginning of valid input and positive transition of Clock.
$t_{CKP2}$	Clock period — when using Complement Array.
$t_{IS2}$	Required delay between beginning of valid Input and positive transition of Clock, when using optional Complement Array (two passes necessary through the AND Array).
$t_{VS}$	Required delay between $V_{CC}$ (after power-on) and negative transition of Clock preceding first reliable clock pulse.
$t_{PRS}$	Required delay between negative transition of Asynchronous Preset and negative transition of Clock preceding first reliable clock pulse.
$t_{IH}$	Required delay between positive transition of Clock and end of valid Input data.
$t_{CKO}$	Delay between positive transition of Clock and when Outputs become valid (with PR/ $\overline{OE}$ Low).
$t_{OE}$	Delay between beginning of Output Enable Low and when Outputs become valid.
$t_{OD}$	Delay between beginning of Output Enable High and when Outputs are in the OFF-state.
$t_{SRE}$	Delay between input $I_0$ transition to Diagnostic Mode and when the Outputs reflect the contents of the State Register.
$t_{SRD}$	Delay between input $I_0$ transition to Logic mode and when the Outputs reflect the contents of the Output Register.
$t_{PR}$	Delay between positive transition of Preset and when Outputs become valid at "1".
$t_{PPR}$	Delay between $V_{CC}$ (after power-on) and when Outputs
$t_{PRH}$	Width of preset input pulse.
$f_{MAX}$	Maximum clock frequency.

5

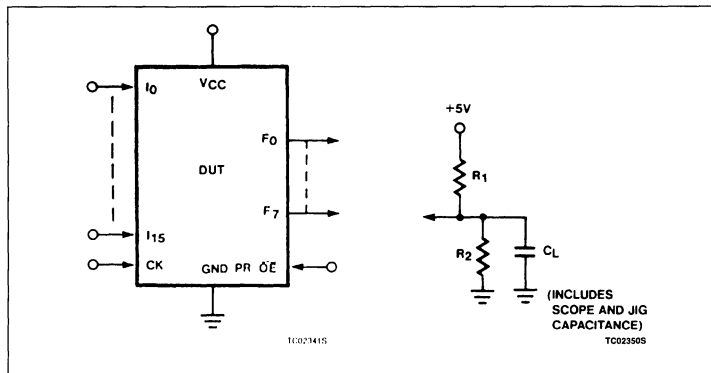
# Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105A

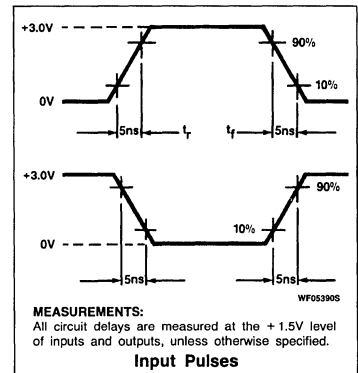
## TIMING DIAGRAMS (Continued)



## TEST LOAD CIRCUITS



## VOLTAGE WAVEFORMS



# Field-Programmable Logic Sequencer (16 × 48 × 8)

PLS105A

## SPEED VS. "OR" LOADING

The maximum frequency at which the FPLS can be clocked while operating in *sequential mode* is given by:

$$(1/t_{MAX}) = t_{CY} = t_{IS} + t_{CKO}$$

This frequency depends on the number of transition terms  $T_n$  used. Having all 48 terms connected in the AND array does not appreciably impact performance; but the number of terms connected to each OR line affects  $t_{IS}$ , due to capacitive loading. The effect of this loading can be seen in Figure 1, showing the variation of  $t_{IS1}$  with the number of terms connected per OR.

The AC electrical characteristics contain two limits for the parameters  $t_{IS1}$  and  $t_{IS2}$ . The first,  $t_{IS1A}$  is guaranteed for a device with 24 terms connected to any OR line.  $t_{IS1B}$  is guaranteed for a device with 16 terms connected to any OR line.

The two other entries in the AC table,  $t_{IS2A}$  and B are corresponding 24 and 16 term limits when using the on-chip Complement array.

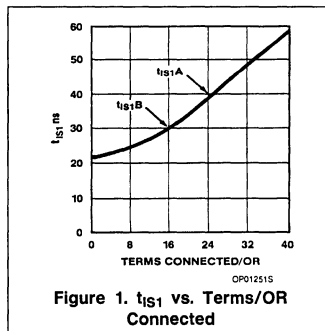


Figure 1.  $t_{IS1}$  vs. Terms/OR Connected

The worst case of  $t_{IS}$  for a given application can be determined by identifying the OR line with the maximum number of  $T_n$  connections. This can be done by referring to

the interconnect pattern in the FPLS logic diagram, typically illustrated in Figure 2, or by counting the maximum number of "H" or "L" entries in one of the columns of the device Program Table.

This number plotted on the curve in Figure 1 will yield the worst case  $t_{IS}$  and, by implication, the maximum clocking frequency for reliable operation.

Note that for maximum speed all UNUSED transition terms should be disconnected from the OR array.

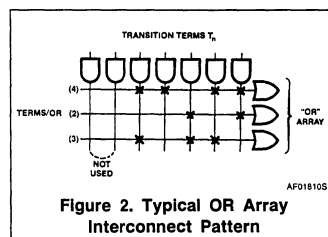


Figure 2. Typical OR Array Interconnect Pattern

# Field-Programmable Logic Sequencer (16 × 48 × 8)

# PLS105A

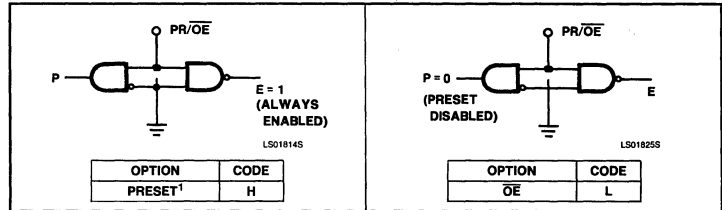
## LOGIC PROGRAMMING

PLS105A logic designs can be generated using Signetics' AMAZE PLD design software or one of several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry is accepted.

PLS105A logic designs can also be generated using the program table entry format detailed on the following pages. This program table entry format is supported by the Signetics' AMAZE PLD design software (PTP module). AMAZE is available free of charge to qualified users.

To implement the desired logic functions, the state of each logic variable from logic equations (I, B, O, P, etc.) is assigned a symbol. The symbols for TRUE, COMPLEMENT, INACTIVE, PRESET, etc., are defined below.

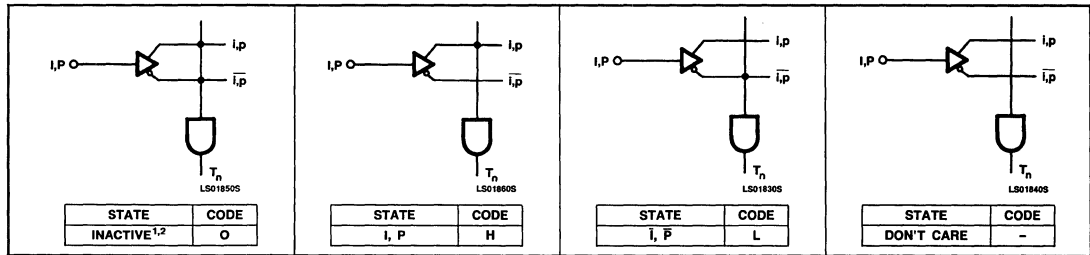
## PRESET/ $\overline{OE}$ OPTION - (P/E)



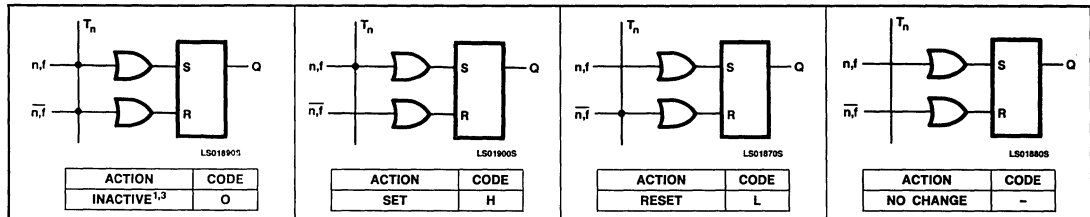
### PROGRAMMING THE PLS105A:

The PLS105A has a power-up preset feature. This feature insures that the device will power-up in a known state with all register elements (state and output register) at a logic High (H). When programming the device it is important to realize this is the initial state of the device. You *must* provide a next state jump if you do not wish to use all Highs (H) as the present state.

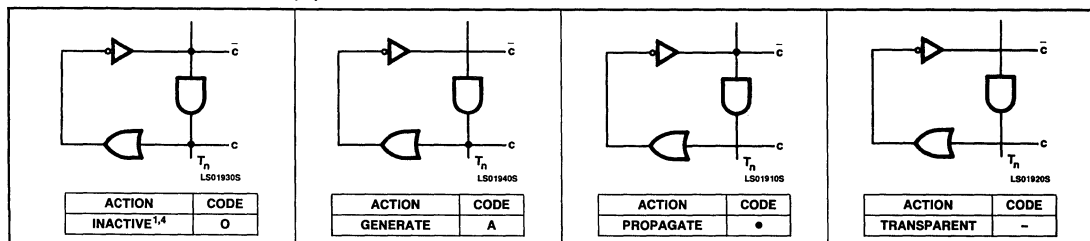
## "AND" ARRAY - (I), (P)



## "OR" ARRAY - (N), (F)



## "COMPLEMENT" ARRAY - (C)



### NOTES:

1. This is the initial unprogrammed state of all link pairs. It is normally associated with all unused (inactive) AND gates  $T_n$ .
2. Any gate  $T_n$  will be unconditionally inhibited if both the true and complement fuses of any input (I,P) are left intact.
3. To prevent simultaneous Set and Reset flip-flop commands, this state is not allowed for N and F link pairs coupled to active gates  $T_n$  (see flip-flop truth tables).
4. To prevent oscillations, this state is not allowed for C link pairs coupled to active gates  $T_n$ .





# PLUS405

## Field-Programmable Logic Sequencer (16 × 64 × 8)

Signetics Programmable Logic  
Product Specification

### Application Specific Products

- Series 28

### DESCRIPTION

The PLUS405 is a bipolar, programmable state machine of the Mealy type. Both the AND and the OR array are user-programmable. All 64 AND gates are connected to the 16 external dedicated inputs ( $I_0 - I_{15}$ ) and to the feedback paths of the 8 on-chip State Registers ( $Q_{P0} - Q_{P7}$ ). Complement transition terms can be generated via optional use of the two internal Complement Arrays (input variables  $C_0, C_1$ ).

All state transition terms can include True, False and Don't Care states of the controlling state variables. All AND gates are merged into the programmable OR array to issue the next-state and next-output commands to their respective registers. Because the OR array is programmable, any one or all of the 64 transition terms can be connected to any or all of the State and Output Registers.

All state ( $Q_{P0} - Q_{P7}$ ) and output ( $Q_{F0} - Q_{F7}$ ) registers are edge-triggered, clocked J-K flip-flops, with Asynchronous Preset and Reset options. The PLUS405 architecture provides the added flexibility of the J-K toggle function which is indeterminate on S-R flip-flops. Each register may be individually programmed such that a specific Preset-Reset pattern is initialized when the initialization pin is raised to a logic level "1". This feature allows the state machine to be asynchronously initialized to known internal state and output conditions prior to proceeding through a sequence of state transitions. Upon power-up, all registers are unconditionally preset to "1". If desired, the initialization input pin (INIT) can be converted to an Output Enable ( $\overline{OE}$ ) function as an additional user-programmable feature.

Availability of two user-programmable clocks allows the user to design two independently clocked state machine functions consisting of four state and four output bits each.

Order codes are listed in the Ordering Information Table.

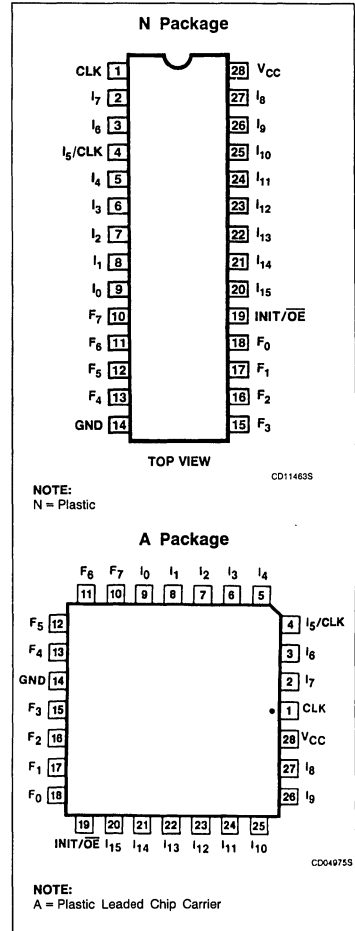
### FEATURES

- Functional superset of PLS105/105A
- 50MHz clock rate
- $f_{MAX} = 33\text{MHz}$   
( $1/(t_{IS} + t_{CKO}) = f_{MAX}$ )
- Field-programmable (Ti-W fusible link)
- 16 input variables
- 8 output functions
- 64 transition terms
- 8-bit State Register
- 8-bit Output Register
- 2 transition Complement Array terms
- Multiple clocks
- Programmable Asynchronous Initialization or Output Enable
- Power-on preset of all registers to "1"
- 950mW power dissipation (typ.)
- TTL compatible
- J-K or S-R flip-flop functions
- 3-State outputs

### APPLICATIONS

- Interface protocols
- Sequence detectors
- Peripheral controllers
- Timing generators
- Sequential circuits
- Elevator controllers
- Security locking systems
- Counters
- Shift registers

### PIN CONFIGURATIONS





# Field-Programmable Logic Sequencer (16 × 64 × 8)

PLUS405

## PIN DESCRIPTION

PIN NO.	SYMBOL	NAME AND FUNCTION	POLARITY
1	CLK	<b>Clock:</b> The Clock input to the State and Output Registers. A Low-to-High transition on this line is necessary to update the contents of both registers. Pin 1 only clocks P <sub>0-3</sub> and F <sub>0-3</sub> if Pin 4 is also being used as a clock.	Active-High (H)
2, 3, 5-9, 26-27 20-22	I <sub>0-I<sub>4</sub></sub> , I <sub>7</sub> , I <sub>6</sub> I <sub>8-I<sub>9</sub></sub> I <sub>13-I<sub>15</sub></sub>	<b>Logic Inputs:</b> The 12 external inputs to the AND array used to program jump conditions between machine states, as determined by a given logic sequence. True and complement signals are generated via use of "H" and "L".	Active-High/Low (H/L)
4	I <sub>5</sub> /CLK	<b>Logic Input/Clock:</b> A user programmable function: • <b>Logic Input:</b> A 13th external logic input to the AND array, as above.  • <b>Clock:</b> A 2nd clock for the State Registers P <sub>4-7</sub> and Output Registers F <sub>4-7</sub> , as above. Note that input buffer I <sub>5</sub> must be deleted from the AND array (i.e., all fuse locations "Don't Care") when using Pin 4 as a Clock.	Active-High/Low (H/L)  Active-High (H)
23	I <sub>12</sub>	<b>Logic/Diagnostic Input:</b> A 14th external logic input to the AND array, as above, when exercising standard TTL levels. When I <sub>12</sub> is held at +10V, device outputs F <sub>0-F<sub>7</sub></sub> reflect the contents of State Register bits P <sub>0-P<sub>7</sub></sub> . The contents of each Output Register remains unaltered.	Active-High/Low (H/L)
24	I <sub>11</sub>	<b>Logic/Diagnostic Input:</b> A 15th external logic input to the AND array, as above, when exercising standard TTL levels. When I <sub>11</sub> is held at +10V, device outputs F <sub>0-F<sub>7</sub></sub> become direct inputs for State Register bits P <sub>0-P<sub>7</sub></sub> ; a Low-to-High transition on the appropriate clock line loads the values on pins F <sub>0-F<sub>7</sub></sub> into the State Register bits P <sub>0-P<sub>7</sub></sub> . The contents of each Output Register remains unaltered.	Active-High/Low (H/L)
25	I <sub>10</sub>	<b>Logic/Diagnostic Input:</b> A 16th external logic input to the AND array, as above, when exercising standard TTL levels. When I <sub>10</sub> is held at +10V, device outputs F <sub>0-F<sub>7</sub></sub> become direct inputs for Output Register bits Q <sub>0-Q<sub>7</sub></sub> ; a Low-to-High transition on the appropriate clock line loads the values on pins F <sub>0-F<sub>7</sub></sub> into the Output Register bits Q <sub>0-Q<sub>7</sub></sub> . The contents of each State Register remains unaltered.	Active-High/Low (H/L)
10-13 15-18	F <sub>0-F<sub>7</sub></sub>	<b>Logic Outputs/Diagnostic Outputs/Diagnostic Inputs:</b> Eight device outputs which normally reflect the contents of Output Register Bits Q <sub>0-Q<sub>7</sub></sub> , when enabled. When I <sub>12</sub> is held at +10V, F <sub>0-F<sub>7</sub></sub> = (P <sub>0-P<sub>7</sub></sub> ). When I <sub>11</sub> is held at +10V, F <sub>0-F<sub>7</sub></sub> become inputs to State Register bits P <sub>0-P<sub>7</sub></sub> . When I <sub>10</sub> is held at +10V, F <sub>0-F<sub>7</sub></sub> become inputs to Output Register bits Q <sub>0-Q<sub>7</sub></sub> .	Active-High (H)
19	INIT/ $\overline{OE}$	<b>Initialization or Output Enable Input:</b> <b>A user-programmable function:</b> • <b>Initialization:</b> Provides an asynchronous preset to logic "1" or reset to logic "0" of all State and Output Register bits, determined individually for each register bit through user programming. INIT overrides Clock, and when held High, clocking is inhibited and F <sub>0-F<sub>7</sub></sub> are in their initialization state. Normal clocking resumes with the first full clock pulse following a High-to-Low clock transition, after INIT goes Low. See timing definition for t <sub>VCK</sub> and t <sub>NVCK</sub> . • <b>Output Enable:</b> Provides an output enable function to buffers F <sub>0-F<sub>7</sub></sub> from the Output Registers.	Active-High (H)  Active-Low (L)

# Field-Programmable Logic Sequencer (16 × 64 × 8)

PLUS405

TRUTH TABLE 1, 2, 3, 4, 5, 6, 7

V <sub>CC</sub>	OPTION		I <sub>10</sub>	I <sub>11</sub>	I <sub>12</sub>	CK	J	K	Q <sub>P</sub>	Q <sub>F</sub>	F	
	INIT	OE										
+5V	H		*	*	*	X	X	X	H/L	H/L	Q <sub>F</sub>	
	L		+10V	X	X	↑	X	X	Q <sub>P</sub>	L	L <sup>9</sup>	
	L		+10V	X	X	↑	X	X	Q <sub>P</sub>	H	H <sup>9</sup>	
	L		X	+10V	X	↑	X	X	L	Q <sub>F</sub>	L <sup>9</sup>	
	L		X	+10V	X	↑	X	X	H	Q <sub>F</sub>	H <sup>9</sup>	
	L		X	X	+10V	X	X	X	Q <sub>P</sub>	Q <sub>F</sub>	Q <sub>P</sub>	
	L		X	X	X	X	X	X	Q <sub>P</sub>	Q <sub>F</sub>	Q <sub>F</sub>	
	H		H	X	X	*	X	X	X	Q <sub>P</sub>	Q <sub>F</sub>	Hi-Z
	X		X	+10V	X	X	↑	X	X	Q <sub>P</sub>	L	L <sup>9</sup>
	X		X	+10V	X	X	↑	X	X	Q <sub>P</sub>	H	H <sup>9</sup>
	X		X	X	+10V	X	↑	X	X	L	Q <sub>F</sub>	L <sup>9</sup>
	X		X	X	+10V	X	↑	X	X	H	Q <sub>F</sub>	H <sup>9</sup>
	L	X	X	X	+10V	X	X	X	Q <sub>P</sub>	Q <sub>F</sub>	Q <sub>P</sub>	
	L	X	X	X	X	X	X	X	Q <sub>P</sub>	Q <sub>F</sub>	Q <sub>F</sub>	
	L	L	X	X	X	↑	L	L	Q <sub>P</sub>	Q <sub>F</sub>	Q <sub>F</sub>	
	L	L	X	X	X	↑	L	H	L	L	L	
	L	L	X	X	X	↑	H	L	H	H	H	
	L	L	X	X	X	↑	H	H	Q <sub>P</sub>	Q <sub>F</sub>	Q <sub>F</sub>	
	↑	X	X	X	X	X	X	X	X	X	H	

**NOTES:**

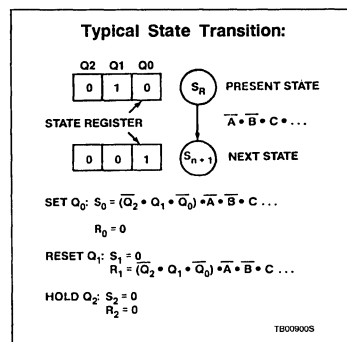
- Positive Logic:  
S/R (or J/K) = T<sub>0</sub> + T<sub>1</sub> + T<sub>2</sub> + ...T<sub>63</sub>  
T<sub>n</sub> = (C<sub>0</sub>, C<sub>1</sub>)(I<sub>0</sub>, I<sub>1</sub>, I<sub>2</sub>,...) (P<sub>0</sub>, P<sub>1</sub>,...P<sub>7</sub>)
- Either Initialization (Active-High) or Output Enable (Active-Low) are available, but not both. The desired function is a user-programmable option.
- ↑ denotes transition from Low-to-High level.
- \* = H/L/+10V
- X = Don't Care (≤ 5.5V)
- H/L implies that either a High or a Low can occur, depending upon user-programmed selection (each State and Output Register individually programmable).
- When using the F<sub>n</sub> pins as inputs to the State and Output Registers in diagnostic mode, the F buffers are 3-stated and the indicated levels on the output pins are forced by the user.

**VIRGIN STATE**

A factory-shipped virgin device contains all fusible links intact, such that:

- INIT/OE option is set to INIT. In order to use the INIT function, the user must select either the PRESET or the RESET option for each flip-flop. Note that regardless of the user-programmed initialization, or even if the INIT function is not used, all registers are preset to "1" by the power-up procedure.
- All transition terms are inactive (0).
- All S/R (or J/K) flip-flop inputs are disabled (0).
- The device can be clocked via a Test Array preprogrammed with a standard test pattern.

**LOGIC FUNCTION**

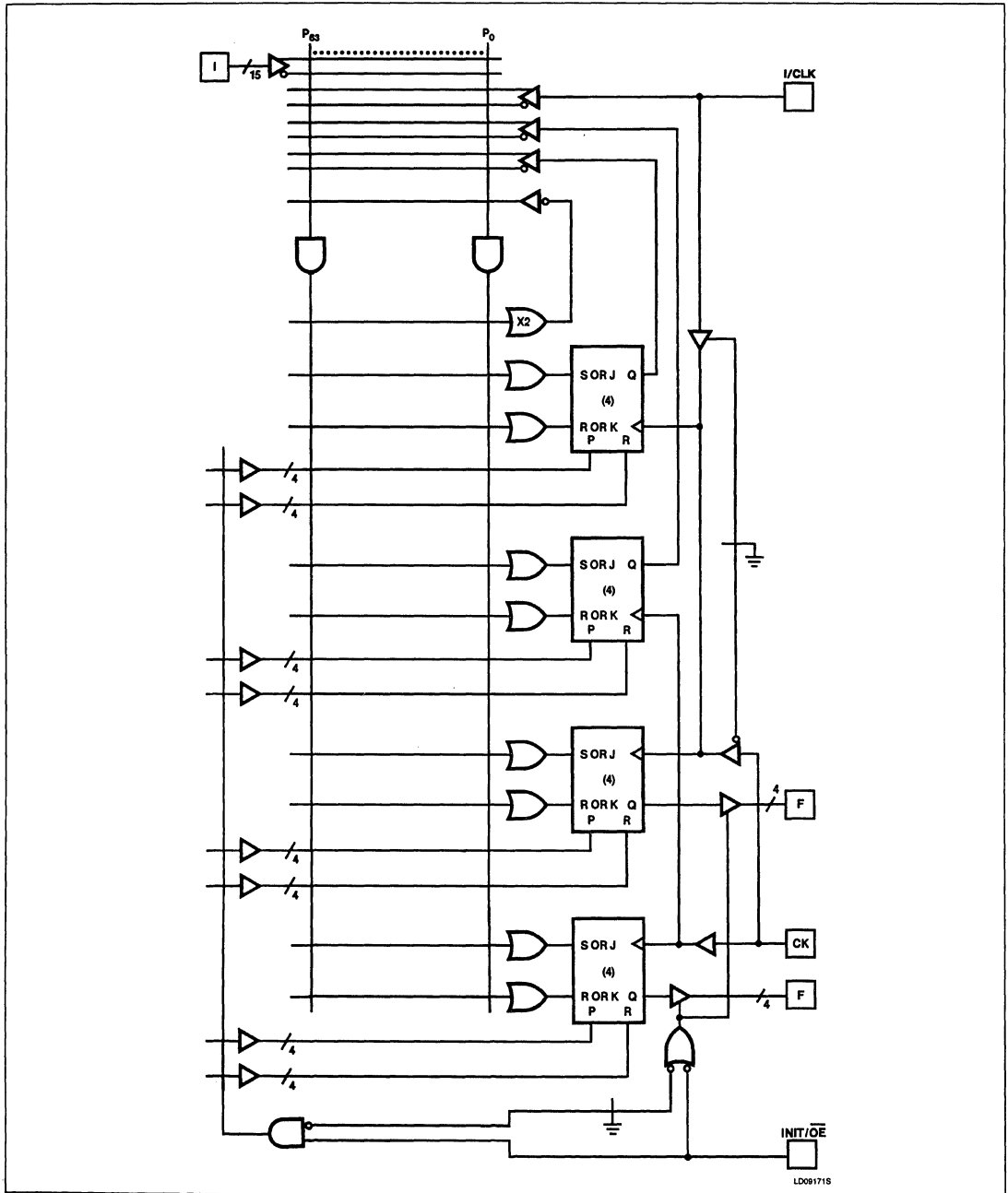


5

# Field-Programmable Logic Sequencer (16 × 64 × 8)

PLUS405

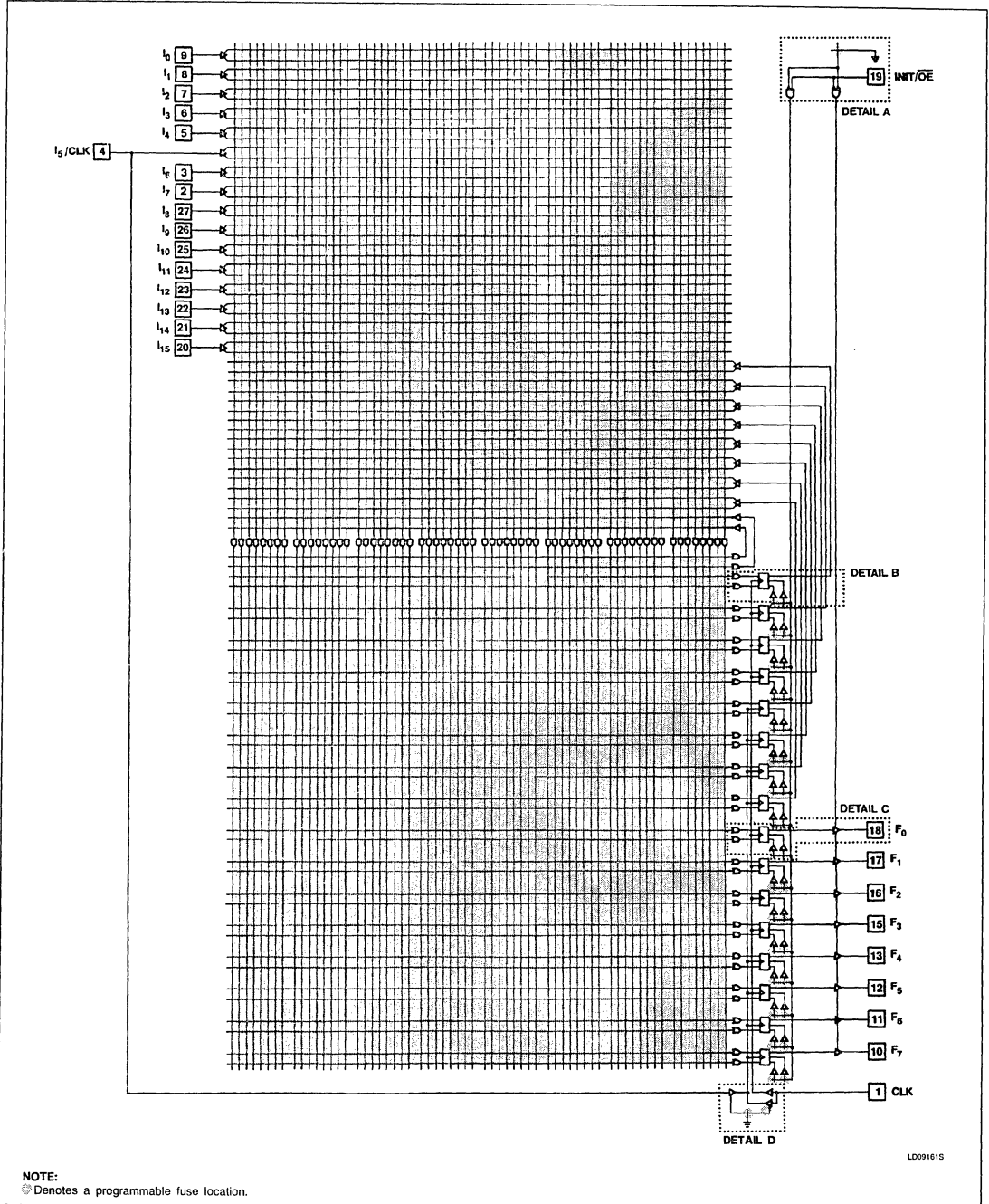
## FUNCTIONAL DIAGRAM



# Field-Programmable Logic Sequencer (16 × 64 × 8)

PLUS405

## FPLS LOGIC DIAGRAM

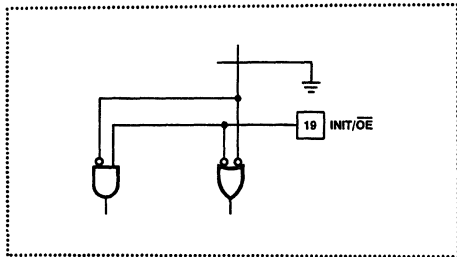


5

# Field-Programmable Logic Sequencer (16 × 64 × 8)

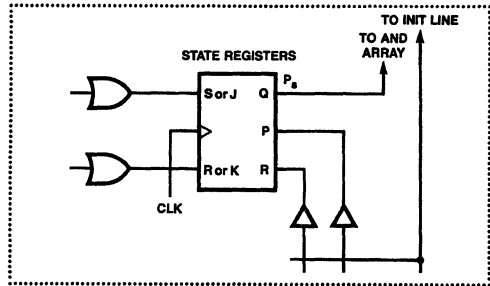
PLUS405

## DETAILS FOR REGISTERS FOR PLUS405



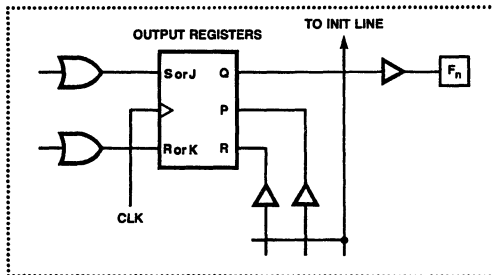
LD068805

Detail A



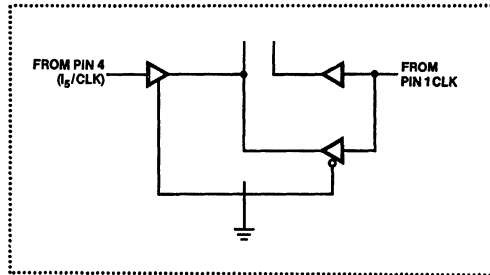
LD068925

Detail B



LD069025

Detail C



LD091515

Detail D

# Field-Programmable Logic Sequencer (16 × 64 × 8)

PLUS405

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
28-Pin Plastic DIP (600mil-wide)	PLUS405N
28-Pin Plastic Leaded Chip Carrier	PLUS405A

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS	UNIT
V <sub>CC</sub>	Supply voltage	+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage	+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage	+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30 to +30	mA
I <sub>OUT</sub>	Output currents	+100	mA
T <sub>A</sub>	Operating temperature range	0 to +75	°C
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C

## NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75 ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
V <sub>IH</sub>	High	V <sub>CC</sub> = Max	2			V
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min			0.8	V
V <sub>IC</sub>	Clamp <sup>3</sup>	V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA		-0.8	-1.2	V
<b>Output voltage<sup>2</sup></b>						
V <sub>OH</sub>	High	V <sub>CC</sub> = Min, I <sub>OH</sub> = -2mA	2.4			V
V <sub>OL</sub>	Low	V <sub>CC</sub> = Min, I <sub>OL</sub> = 9.6mA		0.35	0.45	V
<b>Input current</b>						
I <sub>IH</sub>	High	V <sub>IN</sub> = 5.5V		< 1	25	μA
I <sub>IL</sub>	Low	V <sub>IN</sub> = 0.45V		-20	-250	μA
<b>Output current</b>						
I <sub>O(OFF)</sub>	Hi-Z state	V <sub>CC</sub> = Max, V <sub>OUT</sub> = 5.5V		1	40	μA
		V <sub>CC</sub> = Max, V <sub>OUT</sub> = 0.45V		-1	-40	μA
I <sub>OS</sub>	Short circuit <sup>3, 4</sup>	V <sub>OUT</sub> = 0V	-15		-70	mA
I <sub>CC</sub>	V <sub>CC</sub> supply current <sup>5</sup>	V <sub>CC</sub> = Max		190	225	mA
<b>Capacitance</b>						
C <sub>IN</sub>	Input	V <sub>CC</sub> = 5.0V, V <sub>IN</sub> = 2.0V		8		pF
C <sub>OUT</sub>	Output	V <sub>CC</sub> = 5.0V, V <sub>OUT</sub> = 2.0V		10		pF

## NOTES:

- All typical values are at V<sub>CC</sub> = 5V, T<sub>A</sub> = +25°C.
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- Duration of short circuit should not exceed 1 second.
- I<sub>CC</sub> is measured with the INIT/ŌE input grounded, all other inputs at 4.5V and the outputs open.

# Field-Programmable Logic Sequencer (16 × 64 × 8)

**PLUS405**

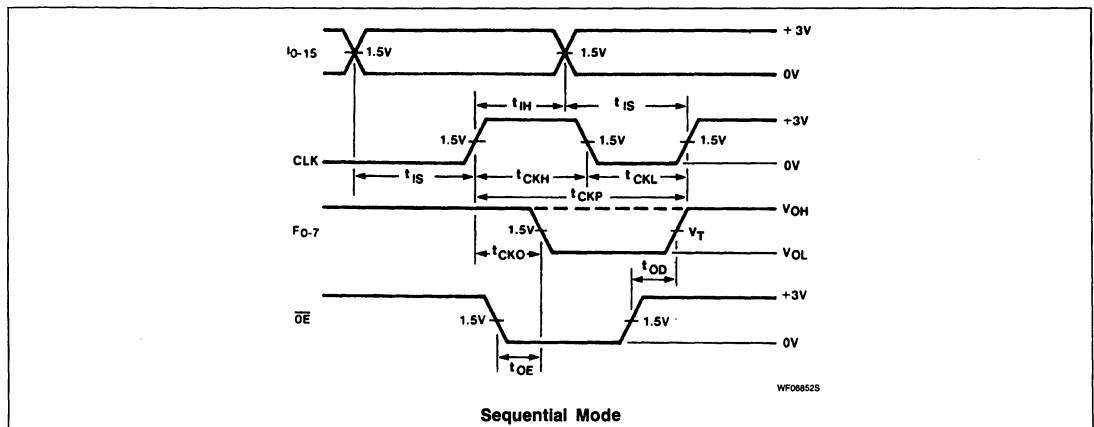
**AC ELECTRICAL CHARACTERISTICS**  $R_1 = 470\Omega$ ,  $R_2 = 1k\Omega$ ,  $C_L = 30pF$ ,  $0^\circ C \leq T_A \leq +75^\circ C$ ,  $4.75V \leq V_{CC} \leq 5.25V$

SYMBOL	PARAMETER	TO	FROM	LIMITS			UNIT
				Min	Typ <sup>1</sup>	Max	
<b>Pulse width</b>							
$t_{CKH}$	Clock High	CK -	CK +	10	8		ns
$t_{CKL}$	Clock Low	CK +	CK -	10	8		ns
$t_{CKP1}$	Period (without Complement Array)	CK +	CK +	30	25		ns
$t_{CKP2}$	Period (with Complement Array)	CK +	CK +	40	35		ns
$t_{INITH}$	Initialization pulse	INIT +	INIT -	15	8		ns
<b>Setup time<sup>2</sup></b>							
$t_{IS1}$	Input	CK +	Input ±	15	12		ns
$t_{IS2}$	Input (through Complement Array)	CK +	Input ±	25	20		ns
$t_{VS}$	Power-on preset	CK -	$V_{CC} +$	0	-10		ns
$t_{VCK}$	Clock resume (after initialization)	CK -	INIT -	0	-5		ns
$t_{NVCK}$	Clock lockout (before Initialization)	INIT -	CK -	15	5		ns
<b>Hold time</b>							
$t_{IH}$	Input	Input ±	CK +	0	-5		ns
<b>Propagation delay</b>							
$t_{CKO}$	Clock	Output ±	CK +		10	15	ns
$t_{OE}$	Output enable	Output -	OE -		12	15	ns
$t_{OD}$	Output disable <sup>3</sup>	Output +	OE +		12	15	ns
$t_{INIT}$	Initialization	Output +	INIT +		15	20	ns
$t_{PPR}$	Power-on preset	Output +	$V_{CC} +$		0	10	ns
<b>Frequency of operation</b>							
$f_{MAX}$	Without Complement Array					33	MHz
	With Complement Array					25	

**NOTES:**

1. All typical values are at  $V_{CC} = 5V$ ,  $T_A = +25^\circ C$ .
2. Product term loading considerations: Connecting more than 8 toggle mode registers to only one product term by itself may compromise the setup time performance. This restriction does not apply if toggle mode function is not used.
3.  $C_L = 5pF$ ;  $V_T = V_{OL} + 0.5V$ .

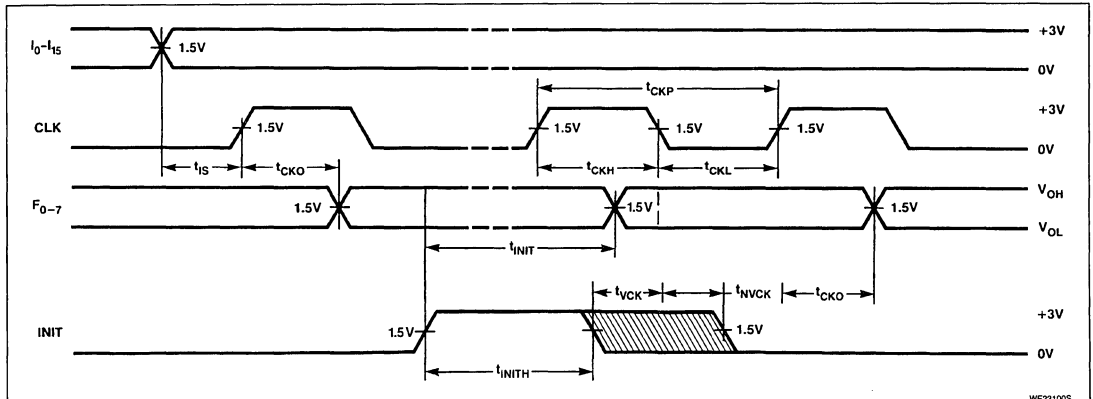
**TIMING DIAGRAMS**



# Field-Programmable Logic Sequencer (16 × 64 × 8)

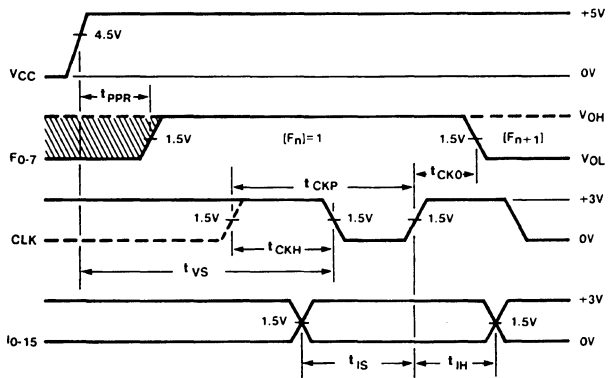
PLUS405

## TIMING DIAGRAMS (Continued)



WF231005

Asynchronous Initialization



WF068715

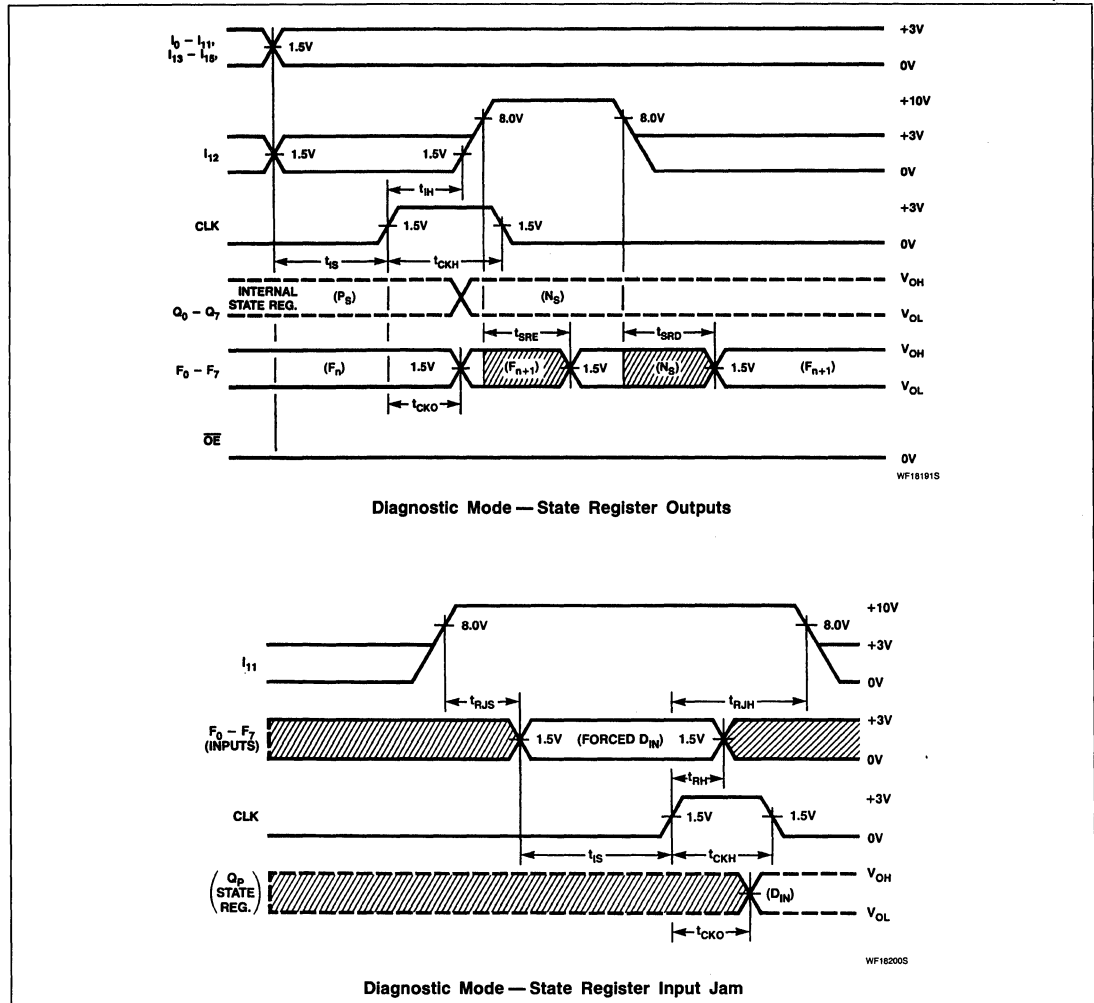
Power-On Preset



# Field-Programmable Logic Sequencer (16 × 64 × 8)

PLUS405

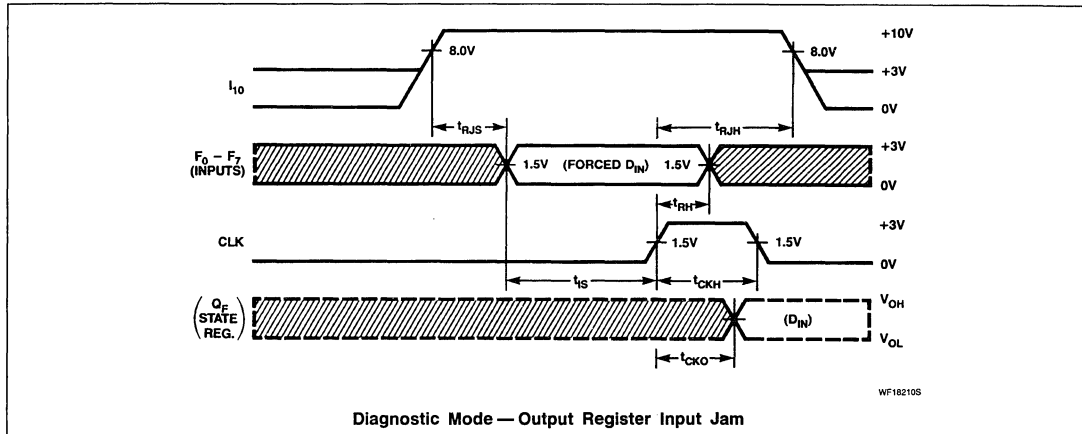
## TIMING DIAGRAMS (Continued)



# Field-Programmable Logic Sequencer (16 × 64 × 8)

PLUS405

## TIMING DIAGRAMS (Continued)



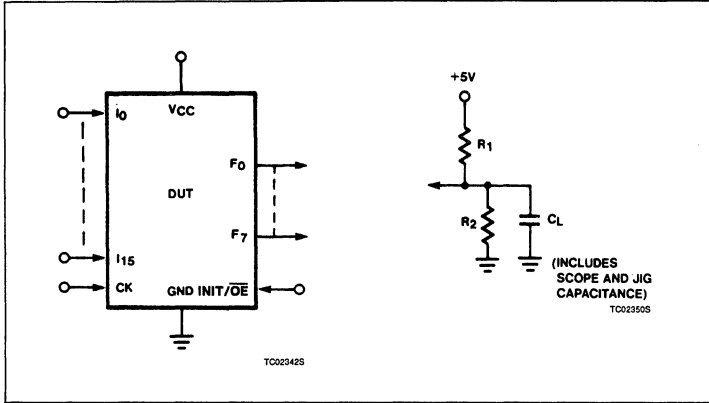
## TIMING DEFINITIONS

SYMBOL	PARAMETER	SYMBOL	PARAMETER	SYMBOL	PARAMETER
t <sub>CKH</sub>	Width of input clock pulse.	t <sub>CKL</sub>	Interval between clock pulses.	t <sub>INITH</sub>	Width of initialization input pulse.
t <sub>CKP</sub>	Clock period — when not using Complement Array.	t <sub>CKP2</sub>	Clock period — when using Complement Array.	t <sub>VS</sub>	Required delay between V <sub>CC</sub> (after power-on) and negative transition of Clock preceding first reliable clock pulse.
t <sub>IS1</sub>	Required delay between beginning of valid input and positive transition of Clock.	t <sub>IH</sub>	Required delay between positive transition of Clock and end of valid Input data.	t <sub>OD</sub>	Delay between beginning of Output Enable High and when Outputs are in the OFF-state.
t <sub>CKO</sub>	Delay between positive transition of Clock and when Outputs become valid (with INIT/OE Low).	t <sub>OE</sub>	Delay between beginning of Output Enable Low and when Outputs become valid.	t <sub>INIT</sub>	Delay between positive transition of Initialization and when Outputs become valid.
t <sub>PPR</sub>	Delay between V <sub>CC</sub> (after power-on) and when Outputs become preset at "1".	t <sub>SRE</sub>	Delay between input I <sub>12</sub> transition to Diagnostic Mode and when the Outputs reflect the contents of the State Register.	t <sub>SRD</sub>	Delay between input I <sub>12</sub> transition to Logic mode and when the Outputs reflect the contents of the Output Register.
t <sub>IS2</sub>	Required delay between beginning of valid input and positive transition of Clock, when using optional Complement Array (two passes necessary through the AND Array).	t <sub>RJS</sub>	Required delay between inputs I <sub>11</sub> or I <sub>10</sub> transition to State and Output Register Input Jam Diagnostic Modes, respectively, and when the output pins become available as inputs.	t <sub>RH</sub>	Required delay between positive transition of Clock and end of valid Input data when jamming data into State or Output Registers in diagnostic mode.
t <sub>RJH</sub>	Required delay between positive transition of Clock and end of inputs I <sub>11</sub> or I <sub>10</sub> transition to State and Output Register Input Jam Diagnostic Modes, respectively.	t <sub>NVCK</sub>	Required delay between the negative transition of the clock and the negative transition of the Asynchronous Initialization to guarantee that the clock edge is not detected as a valid negative transition.	t <sub>VCK</sub>	Required delay between negative transition of Asynchronous Initialization and negative transition of Clock preceding first reliable clock pulse.
t <sub>MAX</sub>	Maximum clock frequency.				

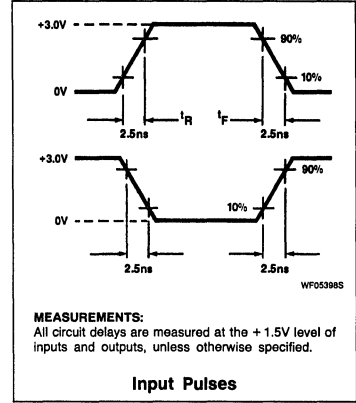
# Field-Programmable Logic Sequencer (16 × 64 × 8)

## PLUS405

### TEST LOAD CIRCUIT



### VOLTAGE WAVEFORMS



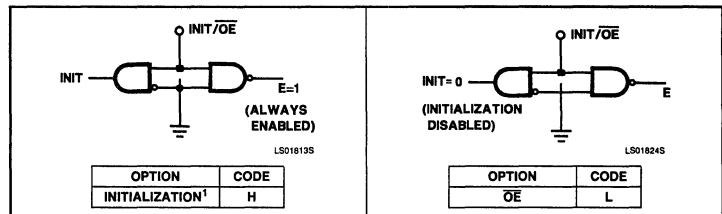
### LOGIC PROGRAMMING

PLUS405 Logic designs can be generated using Signetics' AMAZE design software or several other commercially available, JEDEC standard PLD design software packages. Boolean and/or state equation entry format is accepted.

PLUS405 logic designs can also be generated using the program table format detailed on the following page(s). This Program Table Entry Format (PTE) is supported by the Signetics' AMAZE PLD design software. AMAZE is available free of charge to qualified users.

To implement the desired logic functions, each logic variable (I, B, P, S, T, etc.) from the logic equations is assigned a symbol. TRUE, COMPLEMENT, PRESET, RESET, OUTPUT ENABLE, INACTIVE, etc., symbols are defined below.

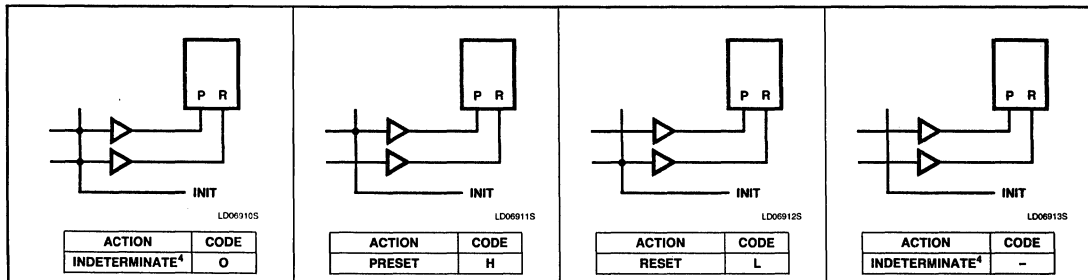
### INITIALIZATION/ $\overline{OE}$ OPTION — (INIT/ $\overline{OE}$ )



### PROGRAMMING THE PLUS405:

The PLUS405 has a power-up preset feature. This feature insures that the device will power-up in a known state with all register elements (State and Output Register) at a logic High (H). When programming the device it is important to realize this is the initial state of the device. You *must* provide a next state jump if you do not wish to use all Highs (H) as the present state.

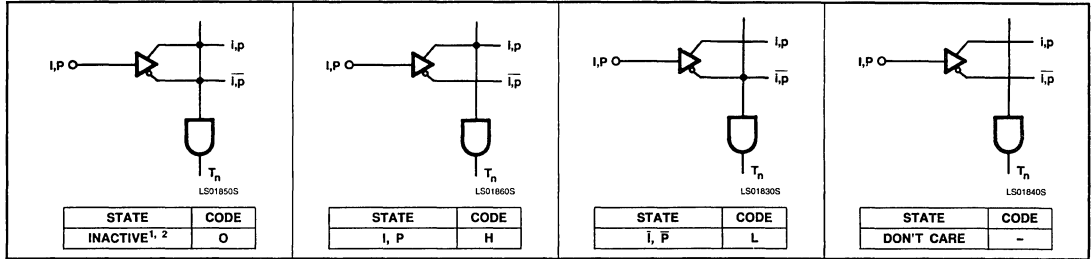
### PRESET/RESET OPTION — (P/R)



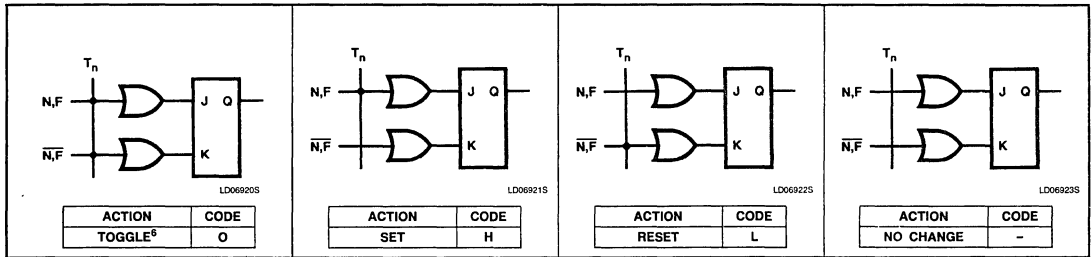
# Field-Programmable Logic Sequencer (16 × 64 × 8)

PLUS405

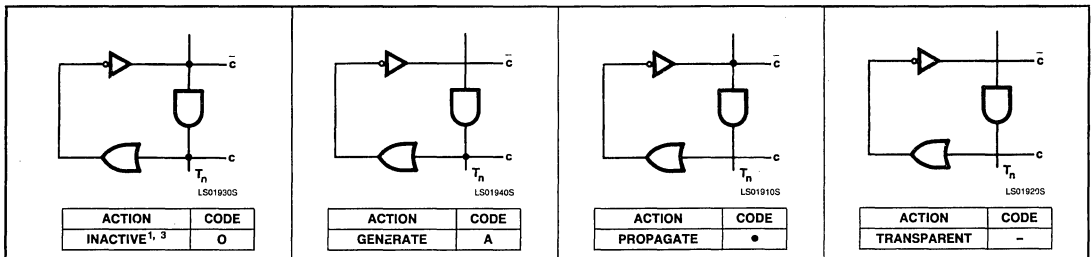
## "AND" ARRAY — (I), (P)



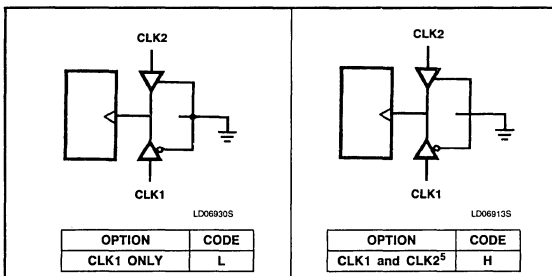
## "OR" ARRAY — J-K FUNCTION — (N), (F)



## "COMPLEMENT" ARRAY — (C)



## CLOCK OPTION — (CLK1/CLK2)



**NOTES:**

1. This is the initial unprogrammed state of all links.
2. Any gate  $T_n$  will be unconditionally inhibited if any one of its I or P link pairs is left intact.
3. To prevent oscillations, this state is not allowed for C link pairs coupled to active gates  $T_n$ .
4. These states are not allowed when using PRESET/RESET option.
5. Input buffer  $I_5$  must be deleted from the AND array (i.e., all fuse locations "Don't Care") when using second clock option.
6. A single product term cannot drive more than 8 registers by itself when used in TOGGLE mode.





Application Specific Products

PLHS501  
PLHS502

### INDEX

Programmable Macro Logic ..... 6-3  
Programmable Macro Logic ..... 6-13



# PLHS501

## Programmable Macro Logic

### Product Specification

Applied Specific Application  
Products • PML Series

#### FEATURES

- Programmable instant gate array
- SNAP development system:
  - Supports third-party schematic entry formats
  - Macro library
  - Versatile netlist format for design portability
  - Logic, timing, and fault simulation
- AMAZE development system:
  - Supports third-party schematic entry formats
  - Boolean equation entry
  - Logic, timing, and fault simulation
- TTL compatible
- Power dissipation = 1.12W (typ.)

#### PROPAGATION DELAYS

- Single level (excluding the internal core) = 22ns (max)
- Two level (through the internal core) = 30ns (max)
- Delay per internal NAND function = 8ns (max)

#### STRUCTURE

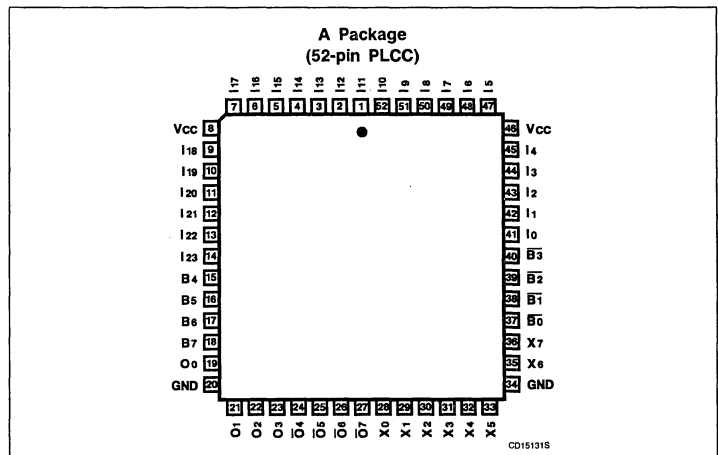
- NAND gate based architecture:
  - 72 foldback NAND terms
- 24 dedicated inputs (I0 - I23)
- 8 bidirectional I/Os with individual 3-State enable:
  - 4 active-High (B4 - B7)
  - 4 active-Low (/B0 - /B3)
- 16 dedicated outputs:
  - 4 active-High outputs:
    - O0, O1 with common 3-State enable
    - O2, O3 with common 3-State enable
  - 4 active-Low outputs:
    - O4, O5 with common 3-State enable
    - O6, O7 with common 3-State enable
  - 8 Exclusive-OR outputs:
    - X0 - X3 with common 3-State enable
    - X4 - X7 with common 3-State enable
- Security fuse allows protection of proprietary designs
- Testable in unprogrammed state

#### DESCRIPTION

The PLHS501 is a high-density Bipolar Programmable Macro Logic device. PML incorporates a programmable NAND structure. The NAND architecture is an efficient method for implementing any logic function. The SNAP software development system provides a user friendly environment for design entry. SNAP eliminates the need for a detailed understanding of the PLHS501 architecture and makes it transparent to the user. PLHS501 is also supported on the Signetics AMAZE software development system.

6

#### PIN CONFIGURATION





# Programmable Macro Logic

**PLHS501**

## ARCHITECTURE

The core of the PLHS501 is a programmable fuse array of 72 NAND gates. The output of each gate folds back upon itself and all other NAND gates. In this manner total interconnectivity of all logic functions is achieved in the PLHS501. Any logic function can be created within the core of the device without wasting valuable I/O pins. Furthermore, a speed advantage is acquired by implementing multi-level logic within a fast internal core without incurring any delays from the I/O buffers.

## DESIGN DEVELOPMENT TOOLS

### SNAP

The SNAP Software Development System provides the necessary tools for designing with PML. SNAP provides the following:

- Schematic entry netlist generation from third party schematic design packages such as OrCAD/STD™ and FutureNet™.
- Macro library for standard PLHS501 functions and user defined functions
- Boolean equation entry
- State equation entry
- Syntax and design entry checking
- Simulator includes logic simulation, fault simulation, automatic test vector generation, and timing simulation.

SNAP operates on an IBM® PC/XT, PC/AT, PS/2, or any compatible system with DOS 2.1 or higher. The minimum system configuration for SNAP is 640K bytes of RAM and a hard disk.

SNAP provides primitive PML function libraries for third-party schematic design packages. Custom macro function libraries can be defined in schematic or equation form.

After the completion of a design, the software compiles the design for syntax and completeness. Complete simulation can be carried out using the different simulation tools available.

The programming data is generated in JEDEC format. Using the Device Programmer Interface (DPI) module of SNAP, the JEDEC fusemap is sent from the host computer to the device programmer.

### AMAZE

The AMAZE PLD Design Software development system also supports the PLHS501. AMAZE provides the following capabilities for the PLHS501:

- Schematic entry netlist conversion from third-party schematic software
- Boolean equation entry
- Logic and timing simulation
- Automatic test vector generation

AMAZE operates on an IBM PC/XT, PC/AT, PS/2, or any compatible system with DOS 2.0 or higher. The minimum system configuration for AMAZE is 640K bytes of RAM and a hard disk.

AMAZE compiles the design after completion for syntax and completeness. Programming data is generated in JEDEC format.

## DESIGN SECURITY

The PLHS501 has a programmable security fuse that controls the access to the data programmed in the device. By using this programmable feature, proprietary designs implemented in the device cannot be copied or retrieved.

FutureNet is a trademark of FutureNet Corporation.

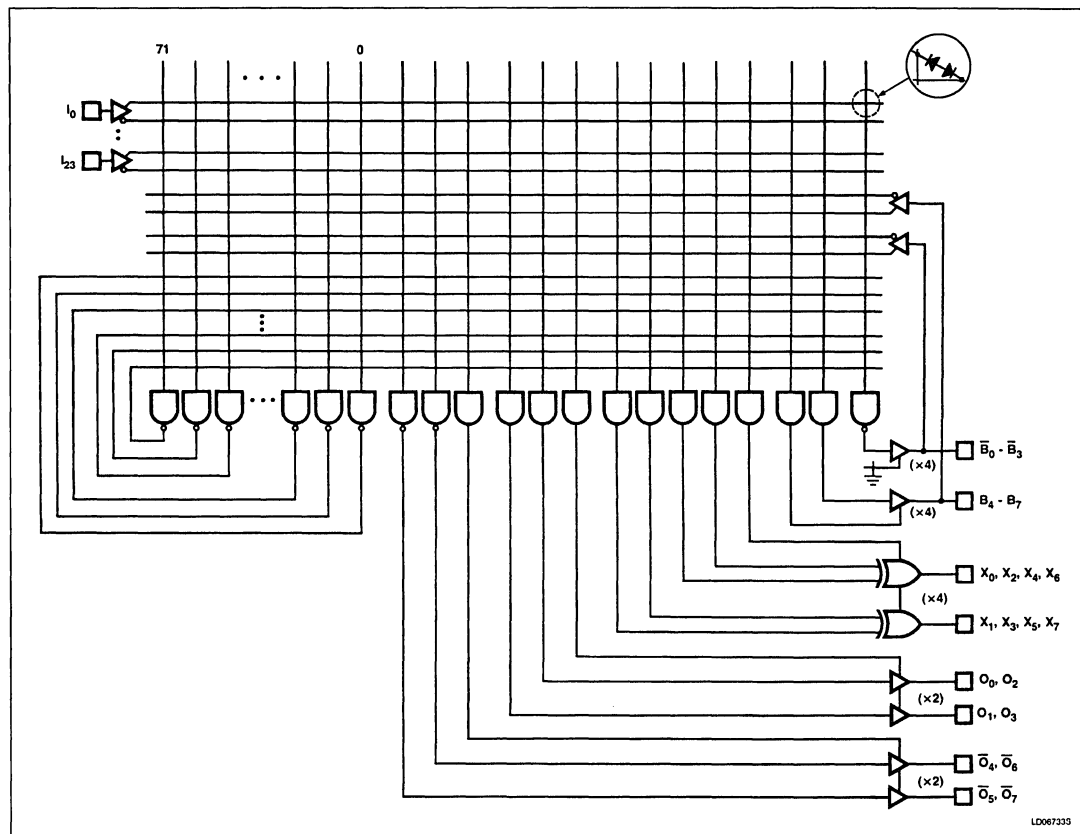
OrCAD/STD is a trademark of OrCAD, Inc.

IBM is a registered trademark of International Business Machines Corporation.

# Programmable Macro Logic

PLHS501

## FUNCTIONAL DIAGRAM



6

### ORDERING INFORMATION

DESCRIPTION	ORDER CODE
52-Pin Plastic Leaded Chip Carrier	PLHS501A

### ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+150	°C

**NOTE:**

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

### THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

### VIRGIN STATE

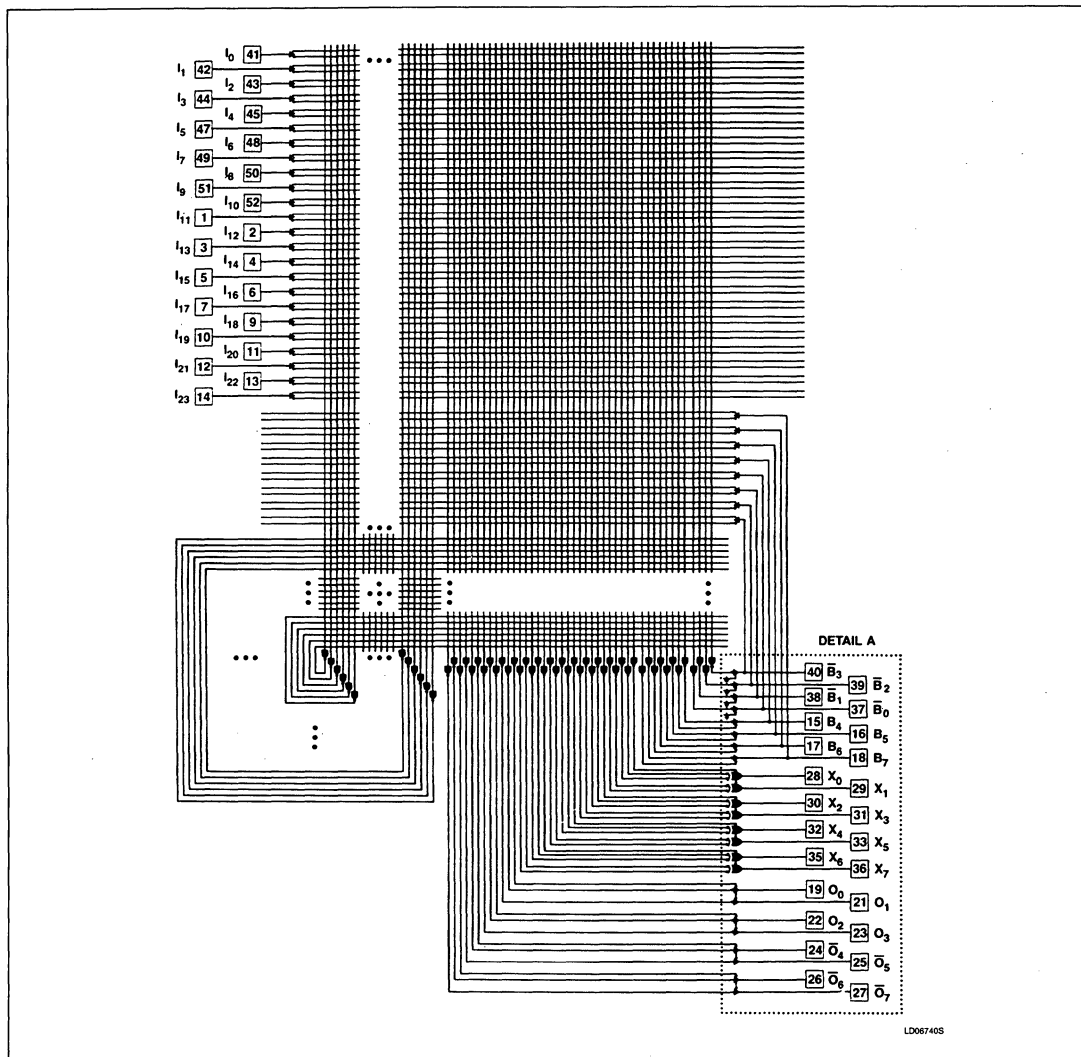
A factory shipped virgin device contains all fusible links open, such that:

1. All product terms are enabled.
2. All bidirectional (B) pins are outputs.
3. All outputs are enabled.
4. All outputs are active-High **except**  $\bar{B}_0 - \bar{B}_3$  (fusible I/O) and  $\bar{O}_4 - \bar{O}_7$  which are active-Low.

# Programmable Macro Logic

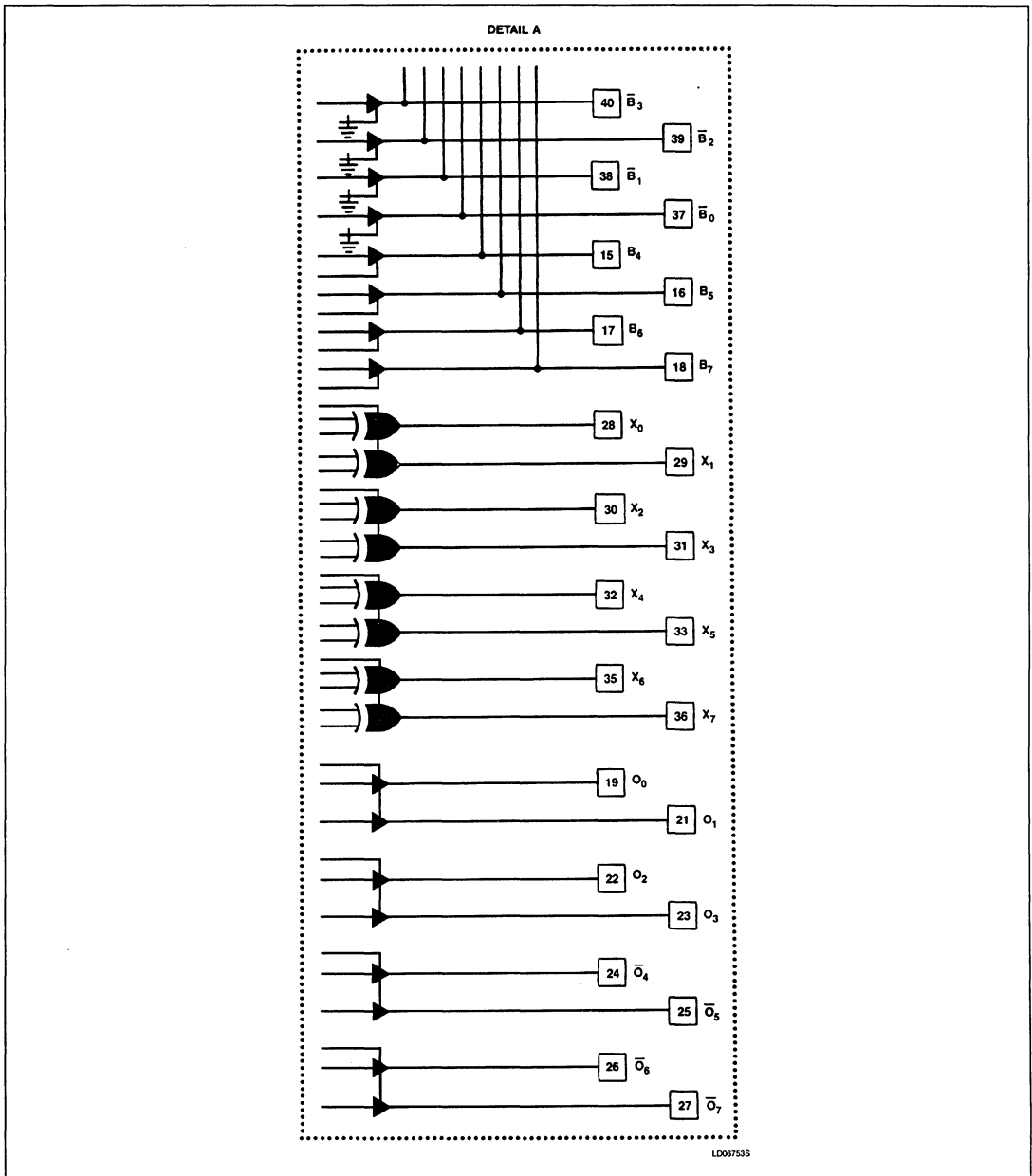
PLHS501

## LOGIC DIAGRAM



# Programmable Macro Logic

# PLHS501



6

## Programmable Macro Logic

PLHS501

DC ELECTRICAL CHARACTERISTICS  $0^{\circ}\text{C} \leq T_A \leq +75^{\circ}\text{C}$ ,  $4.75 \leq V_{CC} \leq 5.25\text{V}$ 

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT
			Min	Typ <sup>1</sup>	Max	
<b>Input voltage<sup>2</sup></b>						
$V_{IL}$	Low	$V_{CC} = \text{Min}$	2.0	-0.8	0.8	V
$V_{IH}$	High	$V_{CC} = \text{Max}$				
$V_{IC}$	Clamp <sup>2, 3</sup>	$V_{CC} = \text{Min}, I_{IN} = -12\text{mA}$				
<b>Output voltage</b>						
$V_{OL}$	Low <sup>2, 4</sup>	$V_{CC} = \text{Min}$	2.4		0.45	V
$V_{OH}$	High <sup>2, 5</sup>	$I_{OL} = 10\text{mA}$ $I_{OH} = -2\text{mA}$				
<b>Input current</b>						
$I_{IL}$	Low	$V_{CC} = \text{Max}$			-100	$\mu\text{A}$
$I_{IH}$	High	$V_{IN} = 0.45\text{V}$ $V_{IN} = 5.5\text{V}$				
<b>Output current</b>						
$I_{O(\text{OFF})}$	Hi-Z state <sup>9</sup>	$V_{CC} = \text{Max}$ $V_{OUT} = 5.5\text{V}$	-15		80	$\mu\text{A}$
$I_{OS}$	Short circuit <sup>3, 5, 6</sup>	$V_{OUT} = 0.45\text{V}$ $V_{OUT} = 0\text{V}$			-140	-70
$I_{CC}$	$V_{CC}$ supply current <sup>8</sup>	$V_{CC} = \text{Max}$		225	295	mA
<b>Capacitance</b>						
$C_{IN}$	Input I/O	$V_{CC} = 5\text{V}$			8	pF
$C_B$		$V_{IN} = 2.0\text{V}$ $V_{OUT} = 2.0\text{V}$				

AC ELECTRICAL CHARACTERISTICS  $T_A = 0^{\circ}\text{C}$  to  $+75^{\circ}\text{C}$ ,  $4.75 < V_{CC} < 5.25\text{V}$ ,  $R_1 = 470\Omega$ ,  $R_2 = 1000\Omega$ 

SYMBOL	PARAMETER		TEST CONDITION	LIMITS			UNIT
	TO	FROM		Min	Typ	Max	
$t_{PD1}$	Output $\pm$	Input $\pm$	$C_L = 30\text{pF}$			25	ns
$t_{PD2}$	Output $\pm$	Input $\pm$				25	ns
$t_{PD3}$	Output $\pm$	Input $\pm$				22	ns
$t_{PD4}^{10}$	Output $\pm$	Input $\pm$				30	ns
$t_{PD5}^{10}$	Output $\pm$	Input $\pm$				30	ns
$t_{PD6}^{10}$	Output $\pm$	Input $\pm$				28	ns
$t_{PD7}$	Internal						
$t_{OE}$	Output -	Input $\pm$	$C_L = 5\text{pF}$			26	ns
$t_{OD}^8$	Output +	Input $\pm$				26	ns

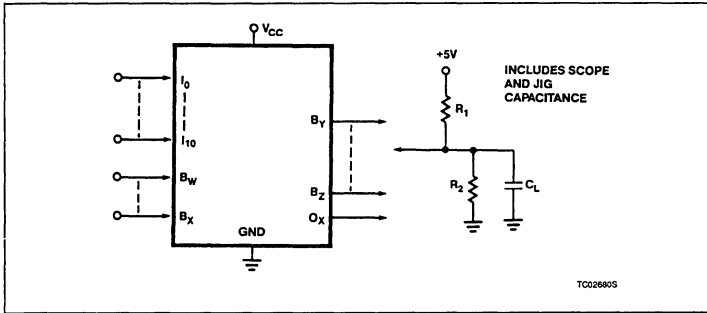
## NOTES:

- All typical values are at  $V_{CC} = 5\text{V}$ ,  $T_A = +25^{\circ}\text{C}$ .
- All voltage values are with respect to network ground terminal.
- Test one at a time.
- For Pins 15 - 19, 21 - 27 and 37 - 40,  $V_{OL}$  is measured with Pins 5 and 41 = 8.75V, Pin 43 = 0V and Pins 42 and 44 = 4.5V.  
For Pins 28 - 33 and 35 - 36,  $V_{OL}$  is measured under same conditions EXCEPT Pin 44 = 0V.
- $V_{OH}$  is measured with Pins 5 and 41 = 8.75V, Pins 42 and 43 = 4.5V and Pin 44 = 0V.
- Duration of short circuit should not exceed 1 second.
- $I_{CC}$  is measured with all dedicated inputs at 0V and bidirectional and output pins open.
- Measured at  $V_T = V_{OL} + 0.5\text{V}$ .
- Leakage values are a combination of input and output leakage.
- Limits are guaranteed with internal feedback buffers simultaneously switching cumulative maximum of eight outputs.

# Programmable Macro Logic

# PLHS501

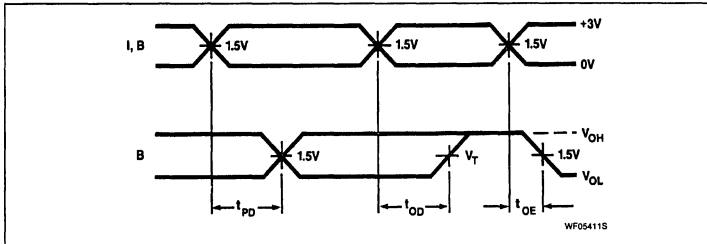
## TEST LOAD CIRCUITS



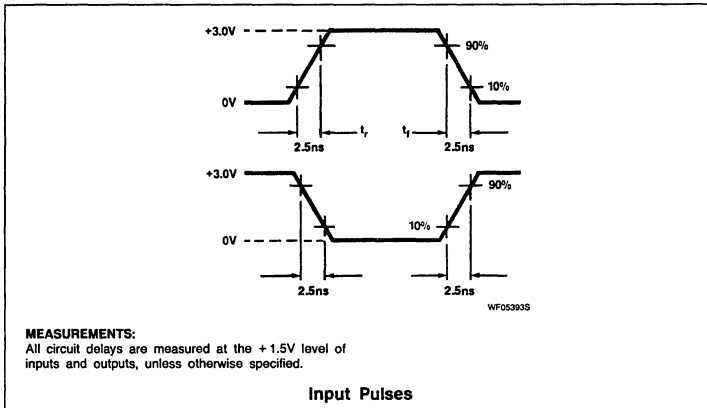
## TIMING DEFINITIONS

SYMBOL	PARAMETER
$t_{PD1}$	Input to Output delay, one pass, through X outputs.
$t_{PD2}$	Input to Output delay, one pass, through $\bar{B}$ outputs.
$t_{PD3}$	Input to Output delay, one pass, through O, $\bar{O}$ and B outputs.
$t_{PD4}$	Input to Output delay, two passes, through X outputs.
$t_{PD5}$	Input to Output delay, two passes, through $\bar{B}$ outputs.
$t_{PD6}$	Input to Output delay, two passes, through O, $\bar{O}$ and B outputs.
$t_{PD7}$	Feedback delay per internal NAND function performed.
$t_{OD}$	Delay between output change and when output is off (Hi-Z or High).
$t_{OE}$	Delay between input change and when the output reflects specified output level.

## TIMING DIAGRAMS



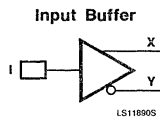
## VOLTAGE WAVEFORMS



## Programmable Macro Logic

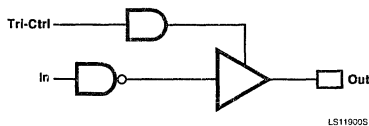
PLHS501

## MACRO CELL SPECIFICATIONS



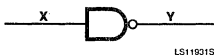
SYMBOL	PARAMETER		LIMITS			UNIT
	To (Output)	From (Input)	Min	Typ	Max	
t <sub>PHL</sub>	X	I		6		ns
t <sub>PLH</sub>	X	I		7		
t <sub>PHL</sub>	Y	I		4.5		ns
t <sub>PLH</sub>	Y	I		6		

Input Pins: 1 - 7, 9 - 14, 41 - 45, 48 - 52  
 Bidirectional Pins: 15 - 18, 37 - 40

**NAND Output Buffer with 3-State Control**

SYMBOL	PARAMETER		LIMITS			UNIT
	To (Output)	From (Input)	Min	Typ	Max	
t <sub>PHL</sub>	Out	In		10.5		ns
t <sub>PLH</sub>	Out	In		9.0		
t <sub>OE</sub>	Out	Tri-Ctrl		9.5		ns
t <sub>OD</sub>	Out	Tri-Ctrl		9.5		

Output Pins: 24 - 27

**Internal Fold Back NAND**

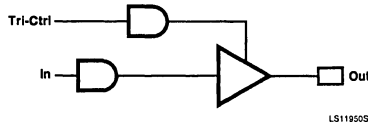
SYMBOL	PARAMETER		LIMITS			UNIT
	To (Output)	From (Input)	Min	Typ	Max	
t <sub>PHL</sub>	Y	X		5.5		ns
t <sub>PLH</sub>	Y	X		6.5		

# Programmable Macro Logic

PLHS501

## MACRO CELL SPECIFICATIONS (Continued)

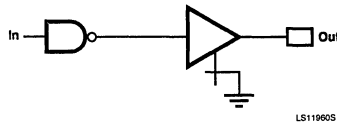
AND Output Buffer with 3-State Control



SYMBOL	PARAMETER		LIMITS			UNIT
	To (Output)	From (Input)	Min	Typ	Max	
$t_{PHL}$	Output	In		10		ns
$t_{PLH}$	Output	In		8.5		
$t_{OE}$	Out	Tri-Ctrl		9.5		ns
$t_{OD}$	Out	Tri-Ctrl		9.5		

Bidirectional and Output Pins: 19, 21, 22, 23, 15 - 18

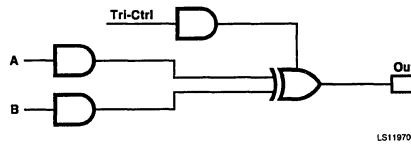
NAND Output Buffer



SYMBOL	PARAMETER		LIMITS			UNIT
	To (Output)	From (Input)	Min	Typ	Max	
$t_{PHL}$				10.5		
$t_{PLH}$				9		

Bidirectional Pins: 37 - 40

Ex-OR Output Buffer



SYMBOL	PARAMETER		LIMITS			UNIT
	To (Output)	From (Input)	Min	Typ	Max	
$t_{PHL}$	Out	A or B		10		ns
$t_{PLH}$	Out	A or B		12		
$t_{OE}$	Out	Tri-Ctrl		9.5		ns
$t_{OD}$	Out	Tri-Ctrl		9.5		

Ex-OR Output Pins: 28 - 33

6



## Programmable Macro Logic

PLHS501

## PLHS501 GATE COUNT EQUIVALENTS

FUNCTION	PLHS501 INTERNAL NAND EQUIVALENT	COMMENTS
Gates: NANDs ANDs NORs ORs	1 1 1 1	For 1 to 32 input variables. For 1 to 32 input variables. For 1 to 32 input variables. For 1 to 32 input variables.
Decoders: 3 to 8 4 to 16 5 to 32	8 16 32	Inverted inputs available. Inverted inputs available. Inverted inputs available (24 chip outputs only).
Encoders: 8 to 3 16 to 4 32 to 5	15 32 41	Inverted inputs, 2 logic levels. Inverted inputs, 2 logic levels. Inverted inputs, 2 logic levels, factored solution.
Multiplexers: 4 to 1 8 to 1 16 to 1 27 to 1	5 9 17 28	Inverted inputs available.  Can address only 27 external inputs – more if internal.
Flip-Flops: D – FF T – FF J – K – FF	6 6 10	With asynch S – R. With asynch S – R. With asynch S – R.
Adders: 8-bit	45	Full carry-lookahead (four levels of logic).
Barrel Shifters: 8-bit	72	2 levels of logic.
Latches D-latch	3	2 levels of logic with one shared gate.

# PLHS502 Programmable Macro Logic

*Preliminary Specification*

## Application Specific Products

### FEATURES

- Programmable instant gate array
- SNAP development system
  - Supports third-party schematic entry formats
  - Macro library
  - Versatile netlist format for design portability
  - Logic, timing, and fault simulation
- TTL compatible
- Power dissipation = 1.25W (typ.)

### PROPAGATION DELAYS

- Single level (excluding the internal core) = 22ns (max)
- Two level (through the internal core) = 30ns (max)
- Delay per internal NAND function = 8ns (max)
- Maximum operating frequency = 50MHz (internal flip-flop)

### STRUCTURE

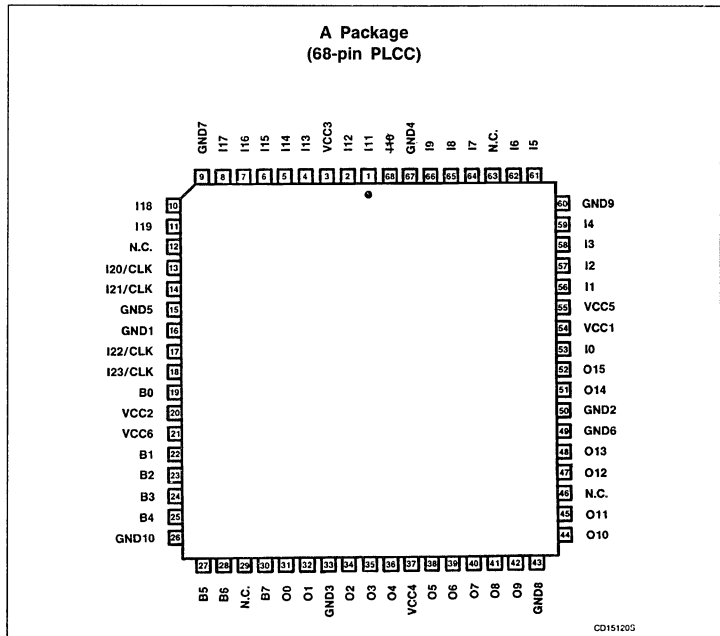
- NAND gate based architecture
  - 64 foldback NAND terms
- 20 dedicated inputs
- 4 programmable input/clock inputs
- 8 independent clocks
  - 4 from input/clock pins
  - 4 from NAND array
- 8 bidirectional I/Os
- 16 dedicated outputs
  - 8 active-High outputs
  - 4 outputs with programmable polarity
  - 4 3-State outputs with programmable polarity
- 16 buried flip-flops
  - 8 D type
  - 8 S-R type
- Security fuse allows protection of proprietary designs
- Testable in unprogrammed state

### DESCRIPTION

The PLHS502 is a high-density Bipolar Programmable Macro Logic device. PML incorporates a programmable NAND structure. The NAND architecture is an efficient method for implementing any logic function. The SNAP software development system provides a user friendly environment for design entry. SNAP eliminates the need for a detailed understanding of the PLHS502 architecture and makes it transparent to the user.

6

### PIN CONFIGURATION



# Programmable Macro Logic

# PLHS502

## ARCHITECTURE

The core of the PLHS502 is a programmable fuse array of 64 NAND gates and 16 buried flip-flops. The output of each gate and flip-flop folds back upon itself and all other NAND gates and flip-flops. In this manner, total interconnectivity of all logic functions is achieved in the PLHS502. Any logic function can be created within the core of the device without wasting valuable I/O pins. Furthermore, a speed advantage is acquired by implementing multi-level logic within a fast internal core without incurring any delays from the I/O buffers.

### ● Buried Flip-Flops

The 16 buried flip-flops can be connected to the input or output structures through the NAND array. Intricate state machine designs can be implemented within the core without any unnecessary delays from the input or output buffers. Each flip-flop can be realized as an input or output register with no constraints.

### ● The Clock Array

The 16 buried flip-flops (8-D and 8 S-R) can be clocked individually through the 'Clock Array'. The Clock Array consists of 8 individual clocks, 4 directly from the input pins and 4 from the NAND array. The clock inputs from the NAND array enable the user to create different functions for clocking the flip-flops. This, together with the fully interconnectivity of the device, offers the capability to implement a variety of synchronous and asynchronous state machines as well as multi-phase design, such as pipelined processing.

## DESIGN DEVELOPMENT TOOLS

The SNAP Software Development System provides the necessary tools for designing with PML. SNAP provides the following:

- Schematic entry netlist generation from third-party schematic design packages such as OrCAD/STD™ and FutureNet™.
- Macro library for standard PLHS502 functions and user defined functions
- Boolean equation entry
- State equation entry
- Syntax and design entry checking
- Simulator includes logic simulation, fault simulation, automatic test generation, and timing simulation.

SNAP operates on an IBM® PC/XT, PC/AT, PS/2, or any compatible system with DOS 2.1 or higher. A minimum of 640K bytes of RAM is required together with a hard disk.

SNAP provides primitive PML function libraries for third party schematic design packages. Custom macro function libraries can be defined in schematic or equation form.

After the completion of a design, the software compiles the design for syntax and completeness. Complete simulation can be carried out using the different simulation tools available.

The programming data is generated in JEDEC format. Using the Device Programmer Interface (DPI) module of SNAP, the JEDEC fusemap is sent from the host computer to the device programmer.

## DESIGN SECURITY

The PLHS502 has a programmable security fuse that controls the access to the data programmed in the device. By using this programmable feature, proprietary designs implemented in the device cannot be copied or retrieved.

FutureNet is a trademark of FutureNet Corporation.

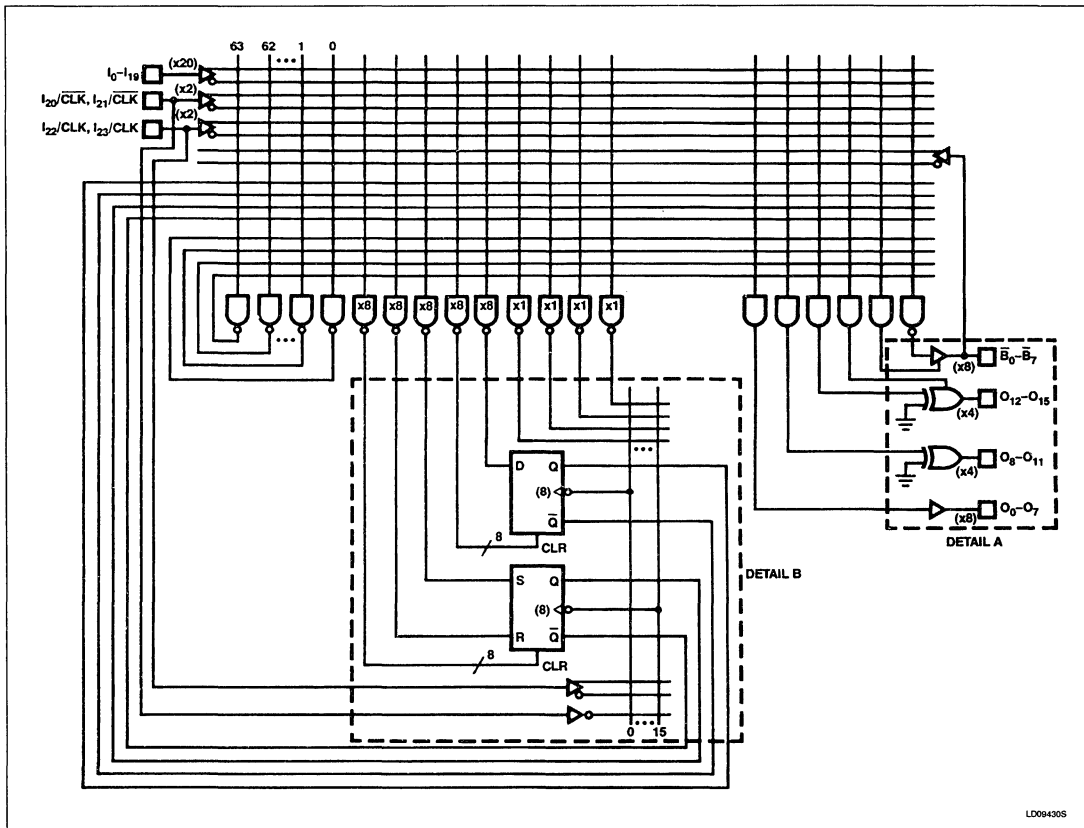
OrCAD/STD is a trademark of OrCAD, Inc.

IBM is a registered trademark of International Business Machines Corporation.

# Programmable Macro Logic

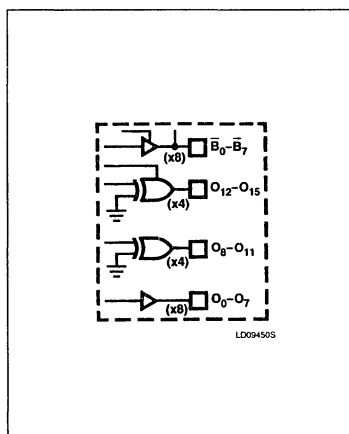
# PLHS502

## FUNCTIONAL DIAGRAM

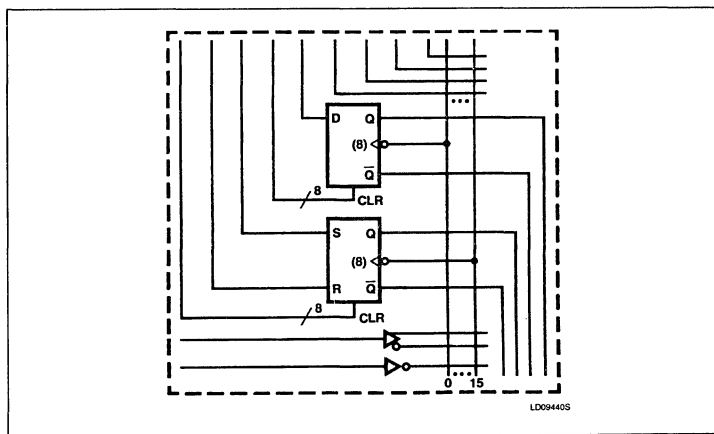


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LD09430S



LD09450S



LD09440S

# Programmable Macro Logic

PLHS502

## ORDERING INFORMATION

DESCRIPTION	ORDER CODE
68-Pin Plastic Leaded Chip Carrier	PLHS502A

## THERMAL RATINGS

TEMPERATURE	
Maximum junction	150°C
Maximum ambient	75°C
Allowable thermal rise ambient to junction	75°C

## ABSOLUTE MAXIMUM RATINGS<sup>1</sup>

SYMBOL	PARAMETER	RATINGS		UNIT
		Min	Max	
V <sub>CC</sub>	Supply voltage		+ 7	V <sub>DC</sub>
V <sub>IN</sub>	Input voltage		+ 5.5	V <sub>DC</sub>
V <sub>OUT</sub>	Output voltage		+ 5.5	V <sub>DC</sub>
I <sub>IN</sub>	Input currents	-30	+30	mA
I <sub>OUT</sub>	Output currents		+ 100	mA
T <sub>A</sub>	Operating temperature range	0	+75	°C
T <sub>STG</sub>	Storage temperature range	-65	+ 150	°C

## VIRGIN STATE

A factory shipped virgin device contains all fusible links open, such that:

1. All bidirectional (B) pins are outputs.
2. All outputs are enabled.
3. All outputs are active-Low **except** O<sub>0</sub>-O<sub>7</sub>, which are active-High.

### NOTE:

1. Stresses above those listed may cause malfunction or permanent damage to the device. This is a stress rating only. Functional operation at these or any other condition above those indicated in the operational and programming specification of the device is not implied.

## DC ELECTRICAL CHARACTERISTICS 0°C ≤ T<sub>A</sub> ≤ +75°C, 4.75 ≤ V<sub>CC</sub> ≤ 5.25V

SYMBOL	PARAMETER	TEST CONDITION	LIMITS			UNIT	
			Min	Typ <sup>1</sup>	Max		
<b>Input voltage<sup>2</sup></b>							
V <sub>IL</sub>	Low	V <sub>CC</sub> = Min V <sub>CC</sub> = Max V <sub>CC</sub> = Min, I <sub>IN</sub> = -12mA	2.0		0.8	V	
V <sub>IH</sub>	High				-0.8		V
V <sub>IC</sub>	Clamp <sup>2</sup>					-1.2	V
<b>Output voltage</b>							
V <sub>OL</sub>	Low <sup>2</sup> High <sup>2</sup>	V <sub>CC</sub> = Min I <sub>OL</sub> = 10mA I <sub>OH</sub> = -2mA	2.4		0.45	V	
V <sub>OH</sub>							V
<b>Input current</b>							
I <sub>IL</sub>	Low High	V <sub>CC</sub> = Max V <sub>IN</sub> = 0.45V V <sub>IN</sub> = 5.5V			-100	μA	
I <sub>IH</sub>						40	μA
<b>Output current</b>							
I <sub>O(OFF)</sub>	Hi-Z state	V <sub>CC</sub> = Max V <sub>OUT</sub> = 5.5V V <sub>OUT</sub> = 0.45V			80	μA	
I <sub>OS</sub>	Short circuit	V <sub>OUT</sub> = 0V	-15		-140	mA	
I <sub>CC</sub>	V <sub>CC</sub> supply current	V <sub>CC</sub> = Max			375	mA	
<b>Capacitance</b>							
C <sub>IN</sub>	Input I/O	V <sub>CC</sub> = 5V V <sub>IN</sub> = 2.0V V <sub>OUT</sub> = 2.0V		8		pF	
C <sub>B</sub>				15		pF	

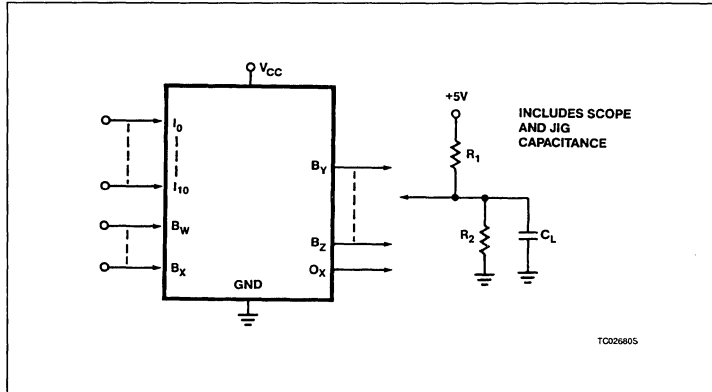
### NOTES:

1. All typical values are at V<sub>CC</sub> = 5V, T<sub>A</sub> = +25°C.
2. All voltage values are with respect to network ground terminal.

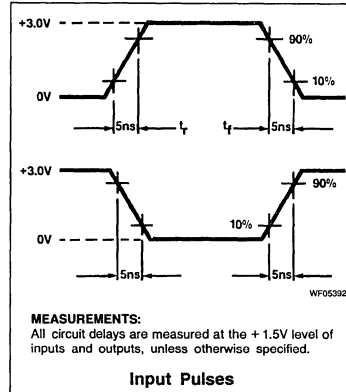
# Programmable Macro Logic

PLHS502

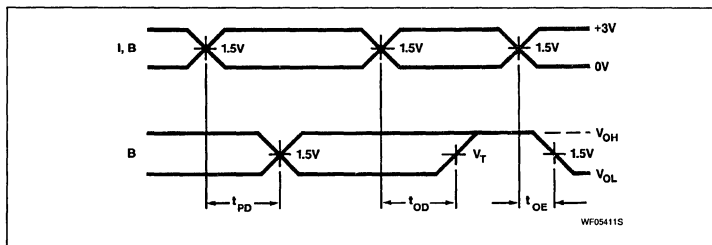
## TEST LOAD CIRCUITS



## VOLTAGE WAVEFORMS



## TIMING DIAGRAMS



## AC ELECTRICAL CHARACTERISTICS $T_A = 0^{\circ}\text{C}$ to $+75^{\circ}\text{C}$ , $4.75 < V_{CC} < 5.25\text{V}$ , $R_1 = 470\Omega$ , $R_2 = 1000\Omega$

SYMBOL	PARAMETER	LIMITS		
		Min	Typ	Max
<b>Non registered operations</b>				
$t_{PD1}$	Input to output delay — no NAND feedback w/Ex-OR buffer		17ns	22ns
$t_{PD2}$	Input to output delay — no NAND feedback w/NAND buffer		15ns	20ns
$t_{PD3}$	Input to output delay — no NAND feedback w/AND buffer		15ns	20ns
$t_{PD4}$	Input to output delay — w/1 NAND feedback w/Ex-OR buffer		22ns	30ns
$t_{PD5}$	Input to output delay — w/1 NAND feedback w/NAND buffer		20ns	28ns
$t_{PD6}$	Input to output delay — w/1 NAND feedback w/AND buffer		20ns	28ns
$t_{PD7}$	Feedback delay per internal NAND function performed		5ns	8ns
$t_{OE}$	Output enable time — no NAND feedback		20ns	25ns
$t_{OD}$	Output disable time — no NAND feedback		18ns	22ns

## Programmable Macro Logic

PLHS502

**AC ELECTRICAL CHARACTERISTICS** (Continued)  $T_A = 0^\circ\text{C}$  to  $+75^\circ\text{C}$ ,  $4.75 < V_{CC} < 5.25\text{V}$ ,  $R_1 = 470\Omega$ ,  $R_2 = 1000\Omega$ 

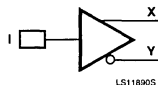
SYMBOL	PARAMETER	LIMITS		
		Min	Typ	Max
<b>Registered operations from dedicated clock inputs</b>				
$t_{IS1}$	Input to clock setup time	10ns	6ns	
$t_{IS2}$	NAND feedback to clock setup time (not including $t_{D7}$ )	5ns	3ns	
$t_{IH1}$	Input hold time	4ns	3ns	
$t_{IH2}$	NAND feedback to clock hold time	7ns	5ns	
$t_{CK0}$	Clock to output (includes NAND output buffer delay)		20ns	25ns
$t_{CK1}$	Clock to output (includes AND output buffer delay)		20ns	25ns
$t_{CK2}$	Clock to output (includes Ex-OR output buffer delay)		22ns	27ns
$t_{CK3}$	Clock to output (includes NAND output buffer delay + 1 feedback)		23ns	30ns
$t_{CK4}$	Clock to output (includes AND output buffer delay + 1 feedback)		23ns	30ns
$t_{CK5}$	Clock to output (includes Ex-OR output buffer delay + 1 feedback)		25ns	32ns
$t_{CK6}$	Clock to feedback matrix (not including buffer delay)		15ns	20ns
$t_{CKH1}$	Width of input clock pulse	15ns	10ns	
$t_{CKL1}$	Interval between clock pulses	15ns	10ns	
$t_{CLR1}$	Clear input to output (includes NAND output buffer delay)		23ns	30ns
$t_{CLR2}$	Clear input to output (includes AND output buffer delay)		23ns	30ns
$t_{CLR3}$	Clear input to output (includes Ex-OR output buffer delay)		25ns	32ns
$t_{CLRQ}$	Clear input to register output		15ns	20ns
$t_{CLH}$		20ns	15ns	
$t_{PPR}$			0ns	10ns
<b>Operations from P-term clocks (abbreviated as P-CK)</b>				
$t_{IS4}$	Input to P-CK setup time	8ns	6ns	
$t_{IS5}$	NAND feedback to P-CK setup time	5ns	3ns	
$t_{HOLD3}$	Input hold time for P-CK	13ns	8ns	
$t_{HOLD4}$	NAND feedback hold time for P-CK	18ns	11ns	
$t_{CK7}$	P-CK to output (includes NAND output buffer delay)		25ns	35ns
$t_{CK8}$	P-CK to output (includes AND output buffer delay)		25ns	35ns
$t_{CK9}$	P-CK to output (includes Ex-OR output buffer delay)		27ns	38ns
$t_{CK10}$	P-CK to output (includes NAND output buffer delay + 1 feedback)		32ns	42ns
$t_{CK11}$	P-CK to output (includes AND output buffer delay + 1 feedback)		32ns	42ns
$t_{CK12}$	P-CK to output (includes Ex-OR output buffer delay + 1 feedback)		34ns	44ns
$t_{CK13}$	P-CK to feedback matrix (not including output buffer delay)		18ns	25ns
$t_{CKH2}$	Width of P-CK pulse	20ns	15ns	
$t_{CKL2}$	Interval between P-CK pulses	20ns	15ns	

# Programmable Macro Logic

PLHS502

## MACRO CELL A.C. SPECIFICATIONS

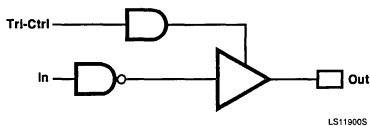
Input Buffer



SYMBOL	PARAMETER		LIMITS			UNIT
	To (Output)	From (Input)	Min	Typ	Max	
$t_{HL}$	X	I			TBD	ns
$t_{LH}$	X	I			TBD	ns
$t_{HL}$	Y	I			TBD	ns
$t_{LH}$	Y	I			TBD	ns

Input Pins: 1, 2, 4-8, 10, 11, 13, 14, 17, 18, 53, 56-59, 61, 62, 64-66, 68  
 Bidirectional Pins: 19, 22-25, 27, 28, 30

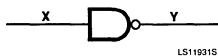
NAND Output Buffer with 3-State Control



SYMBOL	PARAMETER		LIMITS			UNIT
	To (Output)	From (Input)	Min	Typ	Max	
$t_{PHL}$	Out	In			TBD	ns
$t_{PLH}$	Out	In			TBD	ns
$t_{OE}$	Out	Tri-Ctrl			TBD	ns
$t_{OD}$	Out	Tri-Ctrl			TBD	ns

Bidirectional and Output Pins: 19, 22-25, 27, 28, 30

Internal Foldback NAND



SYMBOL	PARAMETER		LIMITS			UNIT
	To (Output)	From (Input)	Min	Typ	Max	
$t_{PHL}$	Y	X			TBD	ns
$t_{PLH}$	Y	X			TBD	ns

6

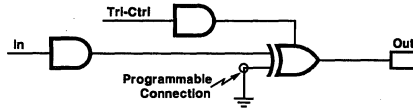


# Programmable Macro Logic

# PLHS502

## MACRO CELL A.C. SPECIFICATIONS (Continued)

### 3-State Output with Programmable Polarity

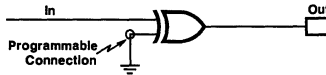


LS11940S

SYMBOL	PARAMETER		LIMITS			UNIT
	To (Output)	From (Input)	Min	Typ	Max	
$t_{PHL}$ $t_{PLH}$	Out Out	In In			TBD	ns
$t_{OE}$ $t_{OD}$	Out Out	Tri-Ctrl Tri-Ctrl			TBD	ns

Output Pins: 47, 48, 51, 52

### Output with Programmable Polarity



LS11910S

SYMBOL	PARAMETER		LIMITS			UNIT
	To (Output)	From (Input)	Min	Typ	Max	
$t_{PHL}$ $t_{PLH}$	Out Out	In In			TBD	ns

Output Pins: 41, 42, 44, 45

### Output Buffer



LS11920S

SYMBOL	PARAMETER		LIMITS			UNIT
	To (Output)	From (Input)	Min	Typ	Max	
$t_{PHL}$ $t_{PLH}$	Out Out	In In			TBD	ns

Output Pins: 31, 32, 34 - 36, 38 - 40

# Programmable Macro Logic

# PLHS502

## D FLIP-FLOP

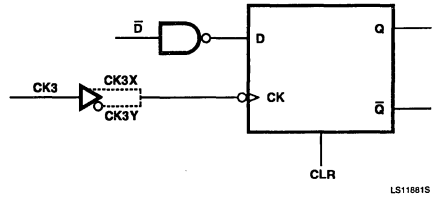
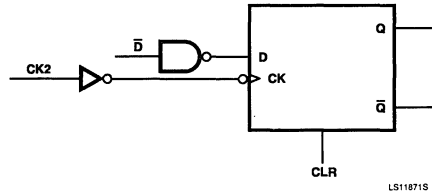
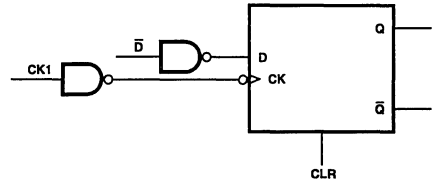
INPUTS			OUTPUTS	
CLR	CK	$\bar{D}$	Q	$\bar{Q}$
H	X	X	H	L
L	L	$Q_0$	$Q_0$	$\bar{Q}_0$
L	$\uparrow$	H	H	L
L	$\uparrow$	L	L	H

**NOTE:**

$Q_0, \bar{Q}_0$  represent previous stable condition of Q,  $\bar{Q}$

SYMBOL	LIMITS			UNIT
	Min	Typ	Max	
f <sub>CK1</sub>			TBD	MHz
f <sub>CK2</sub>			TBD	MHz
f <sub>CK3X</sub>			TBD	MHz
f <sub>CK3Y</sub>			TBD	MHz
t <sub>w</sub> CK1 High			TBD	ns
t <sub>w</sub> CK1 Low			TBD	ns
t <sub>w</sub> CK2 High			TBD	ns
t <sub>w</sub> CK2 Low			TBD	ns
t <sub>w</sub> CK3X High			TBD	ns
t <sub>w</sub> CK3Y Low			TBD	ns
t <sub>SETUP</sub> D			TBD	ns
t <sub>HOLD</sub> D			TBD	ns
t <sub>w</sub> CLR High			TBD	ns

SYMBOL	FROM (INPUT)	TO (OUTPUT)	LIMITS			UNIT
			Min	Typ	Max	
t <sub>PLH</sub>	CK1	Q, $\bar{Q}$			TBD	ns
t <sub>PHL</sub>	CK1	Q, $\bar{Q}$			TBD	ns
t <sub>PLH</sub>	CK2	Q, $\bar{Q}$			TBD	ns
t <sub>PHL</sub>	CK2	Q, $\bar{Q}$			TBD	ns
t <sub>PLH</sub>	CK3X	Q, $\bar{Q}$			TBD	ns
t <sub>PHL</sub>	CK3X	Q, $\bar{Q}$			TBD	ns
t <sub>PLH</sub>	CK3Y	Q, $\bar{Q}$			TBD	ns
t <sub>PHL</sub>	CK3Y	Q, $\bar{Q}$			TBD	ns
t <sub>PLH</sub>	CLR	Q, $\bar{Q}$			TBD	ns
t <sub>PHL</sub>	CLR	Q, $\bar{Q}$			TBD	ns



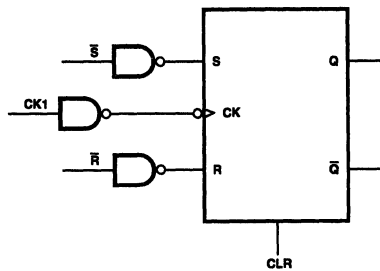
# Programmable Macro Logic

PLHS502

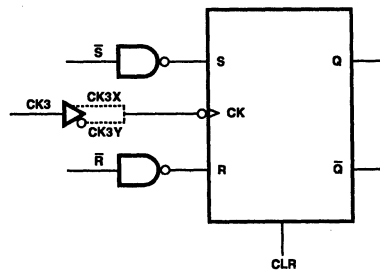
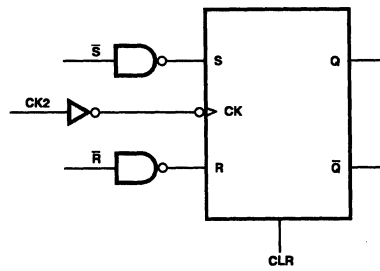
## S-R FLIP-FLOP

INPUTS				OUTPUTS	
CLR	CK	$\bar{S}$	$\bar{R}$	Q	$\bar{Q}$
H	X	X	X	H	L
L	L	X	X	Q <sub>0</sub>	$\bar{Q}$ <sub>0</sub>
L	↑	H	L	L	H
L	↑	L	H	H	L
L	↑	L	L	Q <sub>0</sub>	$\bar{Q}$ <sub>0</sub>
L	↑	H	H	Not allowed	

**NOTE:**  
Q<sub>0</sub>,  $\bar{Q}$ <sub>0</sub> represent previous stable condition of Q,  $\bar{Q}$



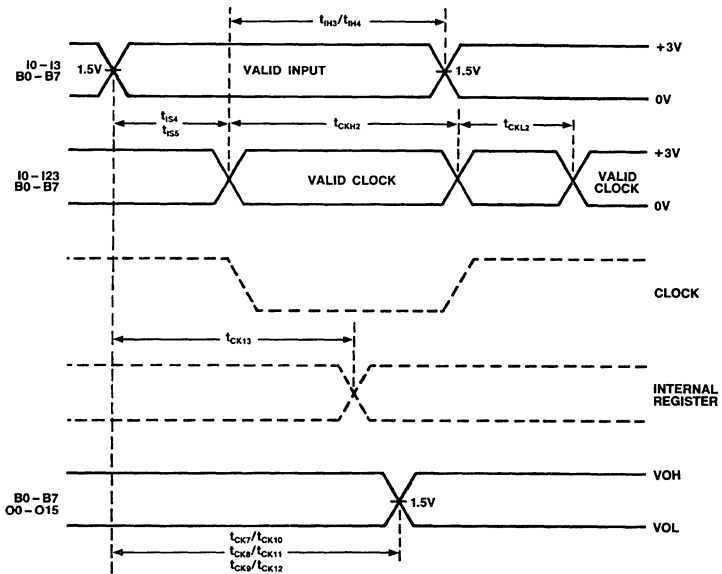
SYMBOL	LIMITS			UNIT
	Min	Typ	Max	
f <sub>CK1</sub>			TBD	MHz
f <sub>CK2</sub>			TBD	MHz
f <sub>CK3X</sub>			TBD	MHz
f <sub>CK3Y</sub>			TBD	MHz
t <sub>w CK1</sub> High			TBD	ns
t <sub>w CK1</sub> Low			TBD	ns
t <sub>w CK2</sub> High			TBD	ns
t <sub>w CK2</sub> Low			TBD	ns
t <sub>w CK3X</sub> High			TBD	ns
t <sub>w CK3X</sub> Low			TBD	ns
t <sub>w CK3Y</sub> High			TBD	ns
t <sub>w CK3Y</sub> Low			TBD	ns
t <sub>SETUP S, R</sub>			TBD	ns
t <sub>HOLD S, R</sub>			TBD	ns
t <sub>w CLR</sub> High			TBD	ns



SYMBOL	FROM (INPUT)	TO (OUTPUT)	LIMITS			UNIT
			Min	Typ	Max	
t <sub>PLH</sub>	CK1	Q, $\bar{Q}$			TBD	ns
t <sub>PHL</sub>	CK1	Q, $\bar{Q}$			TBD	ns
t <sub>PLH</sub>	CK2	Q, $\bar{Q}$			TBD	ns
t <sub>PHL</sub>	CK2	Q, $\bar{Q}$			TBD	ns
t <sub>PLH</sub>	CK3X	Q, $\bar{Q}$			TBD	ns
t <sub>PHL</sub>	CK3X	Q, $\bar{Q}$			TBD	ns
t <sub>PLH</sub>	CK3Y	Q, $\bar{Q}$			TBD	ns
t <sub>PHL</sub>	CK3Y	Q, $\bar{Q}$			TBD	ns
t <sub>PLH</sub>	CLR	Q, $\bar{Q}$			TBD	ns
t <sub>PHL</sub>	CLR	Q, $\bar{Q}$			TBD	ns

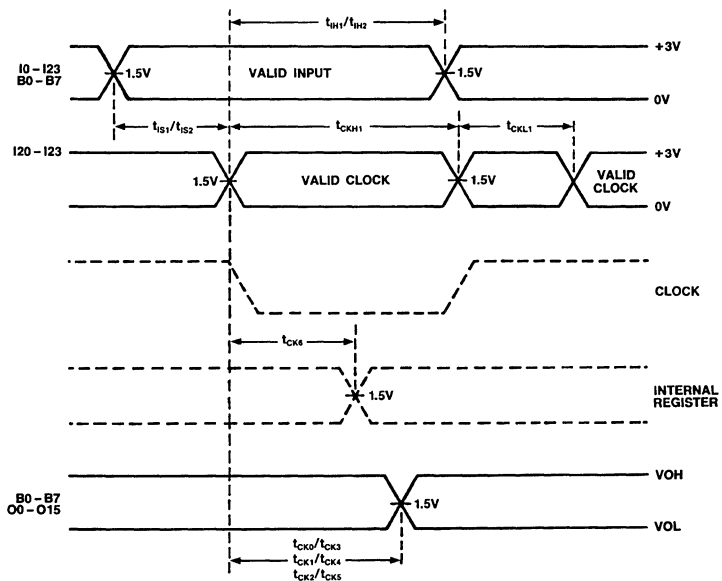
# Programmable Macro Logic

PLHS502



WF231305

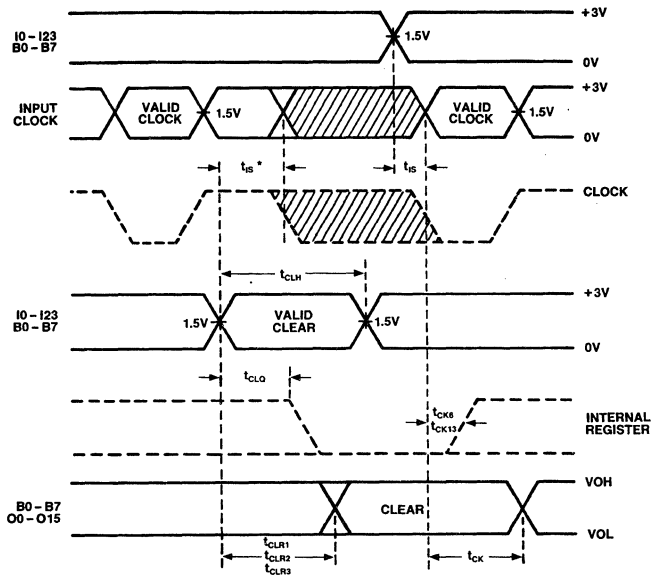
Register Output — P-Term Clock Inputs



WF231405

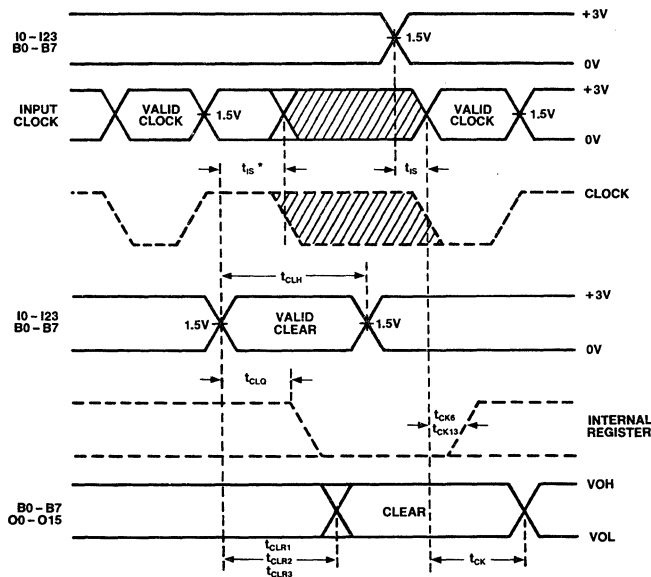
Register Outputs — Dedicated Clock Inputs





WF23150S

Asynchronous Clear



WF23150S

Asynchronous Clear

Effective October 1986, this section has been superseded by the Military Products Data Manual. Information regarding this manual can be obtained from the Military Division in Sacramento, (916) 925-6700. Electrical specifications herein do not necessarily describe the performance characterization of military processed products.



### INDEX

AMAZE – Automatic Map and Zap Equations Design Software .....	8-3
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### Application Specific Products

#### SOFTWARE SUPPORT FOR USER PROGRAMMABLE LOGIC

Computer Aided Design (CAD) support is becoming necessary to address the time-consuming details required by the more complex programmable logic devices available today. The design effort can include the manipulation of Boolean equations, truth tables, state diagrams, flowcharts etc, to create the binary fuse map required to program such devices.

For many years, design engineers have used programmable read-only memories (PROMs) to replace conventional logic. The architecture of the PROM can be described as a programmable logic device containing a **fixed** AND array followed by a **programmable** OR array. The fixed structure of the PROM requires a full assignment of output words to be programmed for every input combination. Therefore, little use can be made of programmable logic software programs for logic minimization or other compiling efforts when using PROMs.

Signetics Programmable Logic Devices are the most advanced approach to solving the inherent limitations of PROMs. Their architecture consists of a **programmable** AND array, followed by a **programmable** OR array - with the addition of a **programmable** invert function for flexible output control.

A Signetics PLD device can implement any set of Boolean expressions, provided that they are first put into the standard sum of products form. The logical ANDs are implemented at the first gate level of the programmable logic device and the logical ORs are implemented by the second gate level within the PLD. The only limitations on the expressions are those imposed by the number of inputs, outputs, and internal product terms provided by the particular PLD circuit selected. The efficiency of implementing the set of equations can be increased significantly by applying DeMorgan's theorem, and utilizing the programmable invert function on each output.

If there seems to be too few product terms to handle a relatively large equation set, one of several minimization methods can be pursued.

The probability of reducing such equations to manageable size is enhanced through the flexibility of shared AND terms for each output function, the accessibility of all AND terms to each output, and having a programmable invert function on each output. All of these features can be utilized by applying the manual manipulation of Venn Diagrams or Karnaugh Maps. However, the time and effort to accomplish these tasks as well as document the effort for procurement specification purposes increase

the need and desire to have software programs to automatically perform such manipulations.

Many types of software programs are being developed to provide this assistance for operation on a wide range of computer hardware. This list of software is expanding rapidly, consisting of both Signetics generated software and some independent software houses' contributions.

This discussion is intended to outline the Signetics developed software program called AMAZE (**A**utomatic **M**ap **A**nd **Z**ap **E**quation **E**ntry) The AMAZE software program currently consists of five modules, BLAST (**B**oolean **L**ogic **A**nd **S**tate **T**ransfer' entry program), PTP (**P**AL **T**o **P**LD' conversion program), DPI (**D**evice **P**rogrammer **I**nterface' program), PLD SIM (**P**LD **S**imulator'' program) and the PTE (**P**rogram **T**able **E**ditor' program). Other modules will be added when product developments require additional software tools.

It must be noted that the AMAZE program is not by any means the total extent of software available for use in designing with PLD (Programmable Logic Devices). Several other commercially available PLD Design Software packages support Signetics' PLD product line. Please contact your local Signetics representative for the latest word on the most currently available software.

# Programmable Logic Development Software

# AMAZE

## AMAZE Version 1.65

### Description

The AMAZE software program, Automatic Map And Zap Equation Entry software, consists of the following five modules:

- **BLAST** ('Boolean Logic And State Transfer' entry program)
- **PTE** ('Program Table Editor')
- **PTP** ('PAL To PLD' conversion program)
- **DPI** ('Device Programmer Interface' program)
- **PLD SIM** ('PLD Simulator' program)

Each module performs specific tasks as outlined in the following section.

### Features

- Multiple modules allowing expansion for future requirements
- Each module designed to be user friendly
- Both **HELP** and **ERROR** messages
- **Document printout: Header, Pin diagram, Boolean equation and Fuse map**
- Interface with most commercial programmers
- **SIMULATOR** programs provide applications assistance and Automatic Test Vector Generation

### Equipment Requirements (for Version 1.65)

- **Platform 1: IBM-PC, XT, AT, PS-2 and compatibles**
  - **Memory: Minimum of 640K bytes**
  - **Operating system: PC-DOS version 2.0 or higher**
  - **Disk Drive: One hard disk drive and one double sided floppy disk drive**
- **Platform 2: DEC VAX/VMS**
  - **Version 4.0 or higher**

Please contact your Signetics Sales Representative for availability and ordering information.

### Products Supported

AMAZE Version 1.65 supports the following products:

<b>20-Pin PLDs</b> PLS151 PLS153 PLS153A PLHS153 PLUS153B PLUS153D PLC153 PLS155 PLS157 PLS159 PLS159A PLC16V8 Series PLHS18P8A PLHS18P8B
<b>24-Pin PLDs</b> PLS161 PLS162 PLS163 PLS167 PLS167A PLS168 PLS168A PLS173 PLUS173B PLUS173D PLS179 PLHS473 PLC473 PLC20V8 Series
<b>28-Pin PLDs</b> PLS100 PLS101 PLS103 PLS105 PLS105A PLUS405
<b>52-pin PLDs</b> PLHS501 <sup>1</sup>

#### NOTE:

1. The PLHS501 and other Programmable Macro Logic devices will also be supported on a separate PML Development System (scheduled to be available in 1989).

**BLAST**

Boolean Logic And State Transfer program is a menu driven software package that supports the engineer in implementing logic designs into Signetics Programmable Logic Devices. It checks design data and automatically compiles a program table from Boolean and State Machine equations. Data from the program table is then used to produce a Standard File which contains the fusing codes in a form acceptable to all the AMAZE modules (i.e. PLD-SIM and DPI).

BLAST reports the logic and syntax errors, and lists the equations in a Sum of Products form, which can help the user to minimize the entered logic equations. It will automatically partition State machine designs into specified devices, and then delete redundant terms during compilation.

BLAST also provides the capability of modifying a current logic set programmed into a device by overlaying new data onto unused fuses.

**BOOLEAN LOGIC AND STATE TRANSFER FEATURES**

- User friendly interactive pinlist editor
- Boolean equation or state vector entry
- Schematic entry (with external schematic capture package)\*\*
- On-line error checking, minimization, and design overlay
- Capable of partitioning single designs into multiple PLDs
- Generates standard PLD fusemap files
- Supports all Signetics' PLDs and PLEs
- User definable device files for support of PALs and other PLD devices

**PTE**

Program Table Entry is an interactive editor which allows the logic designer to enter data into AMAZE in the form of SIGNETICS APPROVED PROGRAM TABLES. Each Signetics PLD data sheet has the program table format which applies to that device. In addition, PTE can be used to document completed designs and to make changes in logic functions which have been previously defined in the BLAST module.

**PROGRAM TABLE EDITOR FEATURES**

- Allows easy creation and editing of new and existing PLD designs
- Truth-table representation of PLD fusemap in High/Low format
- On-line editor provides automatic cursor control and prevents syntax errors
- On-line help screen and print facility
- Operates on standard PLD fusemap files

**PTP**

PAL To PLD is a conversion program to allow easy transfer of the various PAL 20 and 24 pin circuits to the Signetics PLD 20 and 24 pin series devices.

PTP can automatically upload the PAL pattern from a Commercial programmer, convert the pattern into a PLD pattern, and then download the PLD pattern into the programmer. The PAL pattern and it's corresponding PLD pattern can be directed to other AMAZE modules.

PTP can also convert the PAL fuse file in a HEXPLOT format.

**PAL-TO-PLD CONVERSION FEATURES**

- Menu-driven fusemap conversion of 20- and 24-pin PAL devices to pin and functional equivalent Signetics' PLDs and PAL-type devices
- Automatic assembler removes duplicated p-terms providing efficient PLD mapping (PLD conversions only)
- Accepts JEDEC, fuseplot files or direct PAL master input via commercial PLD programmer
- User selectable RS-232 programmable interface parameters
- Provides fusemap conversion documentation
- Generates standard PLD fusemap files compatible with other AMAZE modules

The PTP module supports the conversion of the following device types:

PLS153 PLHS18P8 PLC16V8	10H8, 10L8, 12H6, 12L6, 14H4, 14L4, 16H2, 16L2, 16C1, 16H8, 16L8, 16P8
PLC16V8	18P8, 16RP8
PLS155 PLC16V8	16R4
PLS157 PLC16V8	16R6
PLS159 PLC16V8	16R8
PLS173 PLC20V8	14L8, 16L6, 18L4, 20C1, 20L2, 20L8
PLS173	12L10, 20L10
PLS179 PLC20V8	20R8
PLC20V8	20R4, 20R6

Signetics also provides a stand-alone version of the PTP module, SimPal, which supports the conversion of PAL device fuse maps into equivalent Signetics PAL-type PLDs.

SimPal operates on an IBM-PC/AT/XT/PS-2 or compatible platform (PC-DOS Version 2.0 or higher). SimPal supports the conversion of the following PAL JEDEC fuse maps:

PLC16V8 PLHS18P8	10H8, 10L8, 12H6, 12L6, 14H4, 14L4, 16H2, 16L2, 16C1, 16H8, 16L8, 16P8
PLC16V8	16R4, 16R6, 16R8, 16RP8, 18P8
PLC20V8	14L8, 16L6, 18L4, 20C1, 20L2, 20L8, 20R8, 20R4, 20R6

**DPI**

Device Programmer Interface is the software module that provides the interface between the Standard File created by the AMAZE modules and a commercial programmer. This module allows both download (sending from host to programmer) and upload (sending from programmer into the host) operations.

DPI supports both JEDEC and Signetics High/Low formats to convey fusing information to and from several commercial programmers.

(\*\* AMAZE accepts TTL schematics generated with DATA-I/O FUTURENET DASH and OrCAD's OrCAD STD design software packages).

**DEVICE PROGRAMMER  
INTERFACE FEATURES**

- Supports standard JEDEC and Signetics High/Low fusemap file formats
- RS-232 interface to commercial PLD programmers
- Screen menus for easy upload and download of fusemaps
- User selectable RS-232 parameters for programmer flexibility
- Test vectors automatically transferred to programmer along with fusemap file
- Operates with standard PLD fusemap files

**PLD SIMULATOR**

The **PLD Simulator** program is a software package that simulates the operation of the logic that has been defined for Signetics PLD products. The input to the program is the Standard File generated by other AMAZE modules. The simulator has the capability of running manually or automatically. In the automatic mode the simulator creates a file of test vectors that can be used to test the programmed devices. In the manual mode the program will allow the operator to assign an input vector and observe the resultant output.

**PLD FUNCTIONAL SIMULATOR  
FEATURES**

- Functional simulation of designs created from equations, program tables, or existing programmed devices
- Automatic test vector generation from standard or JEDEC PLD fusemap files
- Interactive keyboard entry or batch file input of test vectors
- Detects Illegal State Machine transitions and flags affected p-terms
- On-line help screen

### INDEX

#### Application Notes

AN7	Single Chip Multiprocessor Arbiter .....	9-3
AN8	Introduction to Signetics Programmable Logic .....	9-15
AN10	4-Bit Binary-To-7 Segment Decoder .....	9-27
AN11	PLD Programmable Retriggerable One-Shot .....	9-51
AN13	Oscillator With PLS159 .....	9-55
AN14	Latches and Flip-Flops With PLS153 .....	9-60
AN15	PLS159 Primer .....	9-73
AN16	PLS159 as Modulo Counters .....	9-84
AN17	Electronic Combination Lock .....	9-91
AN18	Schmitt Trigger Using PLS153 and PLS159 .....	9-94
AN19	Electronic Dice .....	9-102
AN21	9-Bit Parity Generator/Checker With PLS153/153A .....	9-106
AN22	PLS151 Toolkit .....	9-112
AN23	PLS168/168A Primer .....	9-120
AN24	PLS173 as a 10-Bit Comparator, 74LS460 .....	9-133
AN25	A Simple Entry/Exit Meeting Device (PLS157) .....	9-139
AN26	PLHS18P8A Primer .....	9-145
AN27	PLHS473 Primer .....	9-154
AN28	High-Speed 12-Bit Tracking A/D Converter Using PLS179 .....	9-162

#### PML Application Notes

AN29	PLHS501 Programmable Macro Logic Primer .....	9-172
------	---	-------

#### Designing with Programmable Macro Logic

Chapter 1	Introduction to PML Design Concepts .....	9-187
	Performance .....	9-187
	NAND Gate Flip-Flops .....	9-194
Chapter 2	Functional Fit .....	9-197
Chapter 3	Design Examples .....	9-200
Chapter 4	Successor Architectures .....	9-205
Chapter 5	Support Issues .....	9-206
Chapter 6	PLHS501 Examples Using AMAZE Revision 1.6 .....	9-207
	Simple Gate Implementations .....	9-207
	8-Bit Barrel Shifter .....	9-210
	12-Bit Comparator with Dual 1-of-8 Decoders .....	9-216
	8-Bit Carry Look-Ahead Adder .....	9-219
	32-to-5-Bit Priority Encoder .....	9-222
	8-Bit Shift Register with Sequence Detector .....	9-227
	4-Bit Synchronous Counter .....	9-233

#### List of Figures

1.1	PML Basic Functions .....	9-187
1.2	PLHS501 Logic Diagram .....	9-189
1.3	tpd3 - 22ns max .....	9-190
1.4	tpd4 - 30ns max .....	9-191
1.5	tpd1 - 25ns max .....	9-192
1.6	tpd7 - 8ns max .....	9-193
1.7	Edge-Triggered D Flip-Flop .....	9-194
1.8	PLHS501 Test Flip-Flop .....	9-195

**List of Figures (Continues)**

1.9	Partial PLHS501 Fusemap Showing Test Flip-Flop Fusing .....	9-195
1.10	Waveforms of Test Flip-Flop .....	9-196
2.1	16 Input NAND Formed From 2 Input Gates.....	9-198
3.1	Decoder Implementation in NAND Foldback Structure .....	9-200
3.2	Two Flip-Flops Implemented in the NAND Foldback Structure .....	9-201
3.3	68000 Microprocessor Address Decoder .....	9-201
3.4	8-Bit Barrel Shifter Implemented with the PLHS501 .....	9-202
3.5	Partial NAND Gate Equivalence of the 8-Bit Look-Ahead Adder....	9-203
3.6	12-Bit Ripple Counter .....	9-204
3.7	Encoder .....	9-204
4.1	PLHS502 Diagram .....	9-205
6.1	Gates Pin List .....	9-207
6.2	Gates Boolean Equations .....	9-208
6.3	Gates Simulation Input File.....	9-208
6.4	Gates Simulation Log File .....	9-209
6.5	Barrel Shifter Pin List .....	9-210
6.6	8-Bit Barrel Shifter Schematic .....	9-210
6.7	Barrel Shifter Boolean Equations .....	9-211
6.8	Barrel Shifter Simulation Input File .....	9-214
6.9	Barrel Shifter Simulation Log File .....	9-215
6.10	12-Bit Comparator Pin List .....	9-216
6.11	12-Bit Comparator with Dual 1 – 8 Decoders Block Diagram ...	9-216
6.12	12-Bit Comparator Boolean Equations .....	9-217
6.13	12-Bit Comparator Simulation Input File .....	9-218
6.14	12-Bit Comparator Simulation Log File .....	9-218
6.15	8-Bit Adder Pin List .....	9-219
6.16	8-Bit Carry Look-Ahead Adder Block Diagram and Equations..	9-219
6.17	8-Bit Adder Boolean Equations.....	9-220
6.18	8-Bit Adder Simulation Input File .....	9-220
6.19	8-Bit Adder Simulation Log File .....	9-221
6.20	Encoder Pin List .....	9-222
6.21	32 to 5 Priority Encoder Block Diagram .....	9-222
6.22	Encoder Boolean Equations .....	9-223
6.23	Encoder Simulation Input File.....	9-225
6.24	Encoder Simulation Log File .....	9-226
6.25	8-Bit Shifter Pin List.....	9-227
6.26	Shift Register with Sequence Detector Block Diagram .....	9-227
6.27	8-Bit Shifter Boolean Equations .....	9-228
6.28	Portion of STD Files .....	9-230
6.29	8-Bit Shifter Simulation Input File .....	9-231
6.30	8-Bit Shifter Simulation Log File .....	9-232
6.31	4-Bit Counter Pin List.....	9-233
6.32	4-Bit Counter Boolean Equations .....	9-234
6.33	4-Bit Counter Simulation Input File .....	9-235
6.34	4-Bit Counter Simulation Log File.....	9-236

**List of Tables**

1.1	Example Demonstration .....	9-188
2.1	Equivalency Ratio .....	9-198
2.2	PLHS501 Gate Count Equivalents .....	9-199

# AN7 Single Chip Multiprocessor Arbiter

## Application Note

### Application Specific Products

#### INTRODUCTION

In multiprocessor environments there is considerable savings to be made through sharing system resources. If each processor must support its own bus structure, I/O devices, and bulk storage medium, system cost could be very high. In the configuration shown in Figure 1, all processors share a common communication bus, and a number of system resources.

Since every processor must use the common system bus to communicate with its peripherals, a priority structure that resolves simultaneous processor bus requests into a single bus grant must be integrated into the system. In addition to making request-grant transactions, transient bus contention due to grant switching must be removed by inserting precise guard band times between bus grants.

Signetics' Field Programmable Logic Sequencer provides a convenient and cost-effective means for implementing a synchronous arbiter to perform these tasks within a single chip.

#### ARBITER STRUCTURE

Within a multiprocessor system, two general classes of processors can be recognized: Priority A and Priority b. Priority A processors have the highest request priority and must only compete with other Priority A processors for bus control. The arbiter must issue "A" grants in manner that prevents any high priority "A" processor from locking out another Priority A processor. To enable this, the Priority A rules implemented here use a Last Granted Lowest Priority (LGLP) ring structure. After an "A" processor has completed a bus-related task, its next arbitrated request priority will be lowest in the "A" request group. The previously second highest priority "A" processor will then become highest priority requester. The net effect of the "round robin" exchange is that every Priority A processor will have a turn at being highest priority processor. Priority A processors are typically ones that perform real-time operations or vital system tasks.

Priority b processors are lower in priority than the "A's" and may only be granted system control when no "A" requests are pending. "b" processors usually perform background tasks. Within the Priority b group, further priority ordering exists such that each "b" processor has a fixed priority position.

Plumber<sup>1</sup>, Pearce<sup>2</sup>, and Hojberg<sup>3</sup> present asynchronous techniques of arbiter implementation. These methods all have hard-wired priority rules and imprecise guard band times during grant switching. As pointed out by Hojberg, a synchronous state machine can be configured as a Mealy-type controller to provide not only precise guard band times and programmable priority rules, but also programmable input/output polarity. The state machine in Figure 2 is made from a control PROM array and an edge-triggered latch. The "A" and "b" requests and the machine's present state are used by the control PROM to determine the next "A" and "b" grants and the next state.

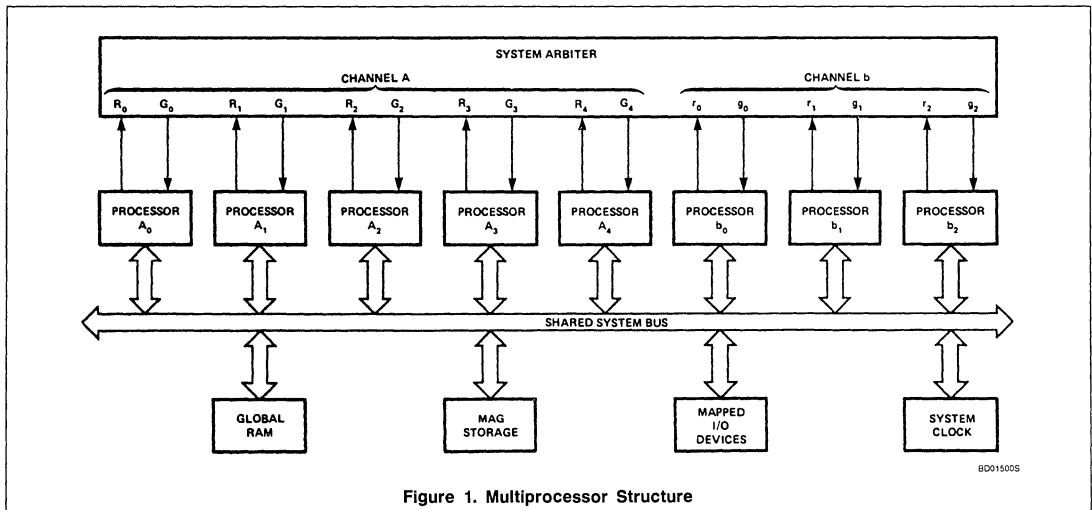
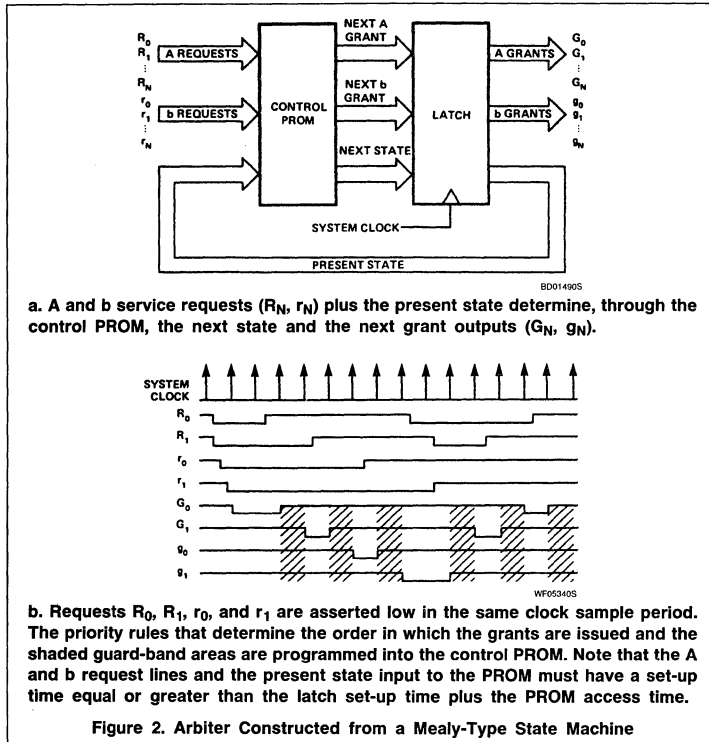


Figure 1. Multiprocessor Structure



# Single Chip Multiprocessor Arbiter

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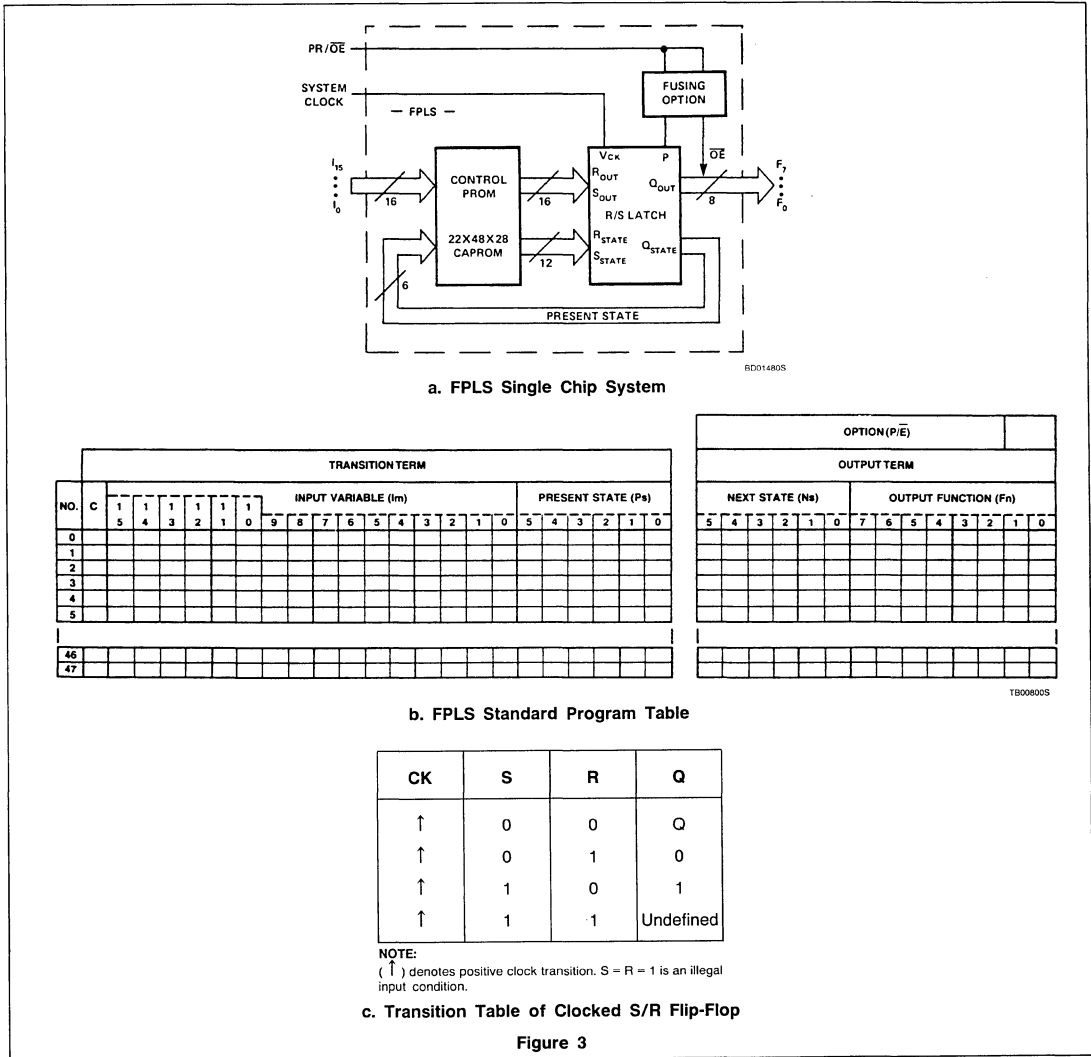


## SYSTEM OPERATION

Two machine states can be identified by inspection: a wait state and a grant state. The state machine enters a grant state as a response to a system request on either  $R_N$  or  $r_N$ . The machine will remain in this state with a single grant line asserted as long as the request remains asserted. Upon releasing the request line, the machine will pass through a single wait state before considering other pending requests. This provides a single state guard band time. The requests received must meet the set-up requirement of the edge-triggered latch after propagating through the control PROM. If these time considerations do not fit within a given multiprocessor structure, an input latch may be added such that the  $R_N$  and  $r_N$  lines are clocked through the latch by the system clock, thereby removing asynchronous set-up time considerations. On the basis of a state machine approach, two techniques of implementation are feasible: 1) using an architecturally advanced single IC controller, the FPLS, and, 2) a traditional PROM/LATCH configuration.

# Single Chip Multiprocessor Arbiter

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## FPLS ARBITER IMPLEMENTATION

A five Priority "A" and three Priority "b" arbiter will be constructed such that all grant outputs will be asserted low for grants and all request inputs will be asserted low for system requests.

### Brief FPLS Description

The FPLS block diagram shown in Figure 3(a) consists of a control PLA and 14 clocked S/R flip-flops. The control PLA is actually an AND-OR logic array that functions as a Content Addressable PROM. The PLA is organized as 48 words of 28 bits with 16 external input

lines, and six internal inputs fed back from the State Register. The 28 PLA outputs drive the S/R inputs of the six-bit State Register and eight-bit Output Register. Note that the state feedback path is made inside the FPLS.

$I_N$  and present state inputs,  $P_S$ , represent  $2^{22}$  possible input codes; 48 of these codes may be mapped in the PLA to provide a 14 bit register control word. As shown in Figure 3(b) each input code may be specified by assigning to the variables either Low "L", High "H", or Don't Care "-" logic states. If any input code falls logically outside the programmed codes, the PLA asserts a Low on all its 28

internal outputs, thereby issuing a "no change" command to the R/S flip-flops.

This is an important architectural feature because it requires that only state or output transition terms be programmed. Looping terms that change neither state nor output need not be programmed in the FPLS, owing to the functional characteristics of S/R flip-flops tabulated in Figure 3(c). An example of this is shown in Figure 4.

The S/R inputs of both state and output registers are specified by using PLA outputs ("AND" functions of request inputs and present state) in the program table of Figure 3(c).

# Single Chip Multiprocessor Arbiter

AN7

The corresponding next state of each bit will be set to 0 for "L", 1 for "H", and No Change for "-". The FPLS's PR/OE line may be assigned either Asynchronous Preset or Output Enable functions, via a user programmable option.

The entire function is integrated into a single 28-pin package designated as PLS105.

## State Algorithm

Figure 5(a) displays the circular state form and all possible state transitions of the LGLP priority structure. Hex states 3F, 3E, 3D, 3C, and 3B are arbiter wait states  $W_{0-4}$ . In these states, processor "A" and "b" requests are monitored. Figure 5(b) illustrates a typical grant to processor  $A_1$  in hex state 07. As long as  $A_1$  asserts its request line low, the next state will be 07<sub>16</sub> and the next output will remain with  $G_1$  asserted low and all the other grant outputs asserted high. Since no change in state or grant output results from this transition, no PLA resources are required.

As soon as processor  $A_1$  returns its request line,  $R_1$ , to 1, a state transition is made to 3D, and an output transition is made to set all grant outputs to 1. Since processor  $A_1$  was the last to be granted system resources, it will now have the lowest A level request priority (LGLP). In wait state  $W_2$ , the highest priority processor will be  $A_2$ , second  $A_3$ , third  $A_4$ , and fourth  $A_0$ . To maintain the LGLP rule, grant transitions must follow the state rule  $G_N \rightarrow W_{(N+1)}$ , and wait states,  $W_M$ , must set their "A" priorities so that processor  $A_M$  is highest priority. Priority decreases as one proceeds clockwise around the state ring to the lowest priority processor,  $A_{(m-1)}$ .

When no "A" requests are pending, "b" requests may be granted. To avoid upsetting the LGLP priority rule, a "b" grant must leave and return to the same wait state. Since the "b" priority structure is the same regardless of the wait state, only a single set of "b" transition terms are required.

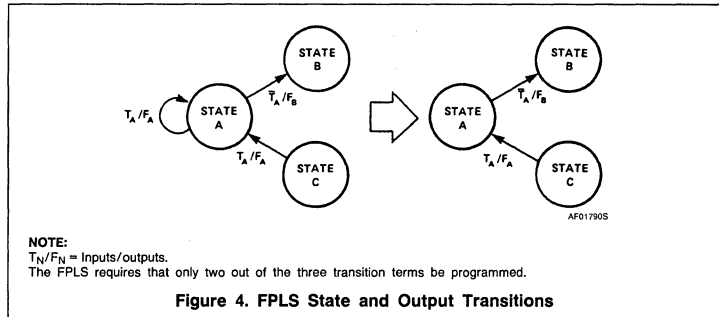


Figure 4. FPLS State and Output Transitions

For example, a grant transition to  $g_2$  (Hex 20-25) can be issued only if there are no "A", "b<sub>0</sub>", or "b<sub>1</sub>" requests pending. Given the binary wait state code 111XXX, where "X"s represent Don't Cares, a request code of 01111111 will transfer the arbiter to the grant state  $g_2$  from any of the wait states,  $W_{0-4}$ .

It is important to realize that in making this transition, the lower three-state bits will not be changed—they provide the wait state return address. When  $r_2$  returns high, 1XXXXXXX, a transition back to the previously exited wait state is made by forcing a "1" in the three most significant state bits and leaving the lower three-state bits unchanged.

All output and state bits are initially preset to "1" through the use of the optional preset function. Grant output lines are only forced low when transitions are made to grant states and are returned to "1" when jumping back to a wait state.

Table 1 provides the complete arbiter program. The complete arbiter circuit diagram is shown in Figure 6. The AMAZE equations are shown in Figure 7.

## PROM/LATCH IMPLEMENTATION

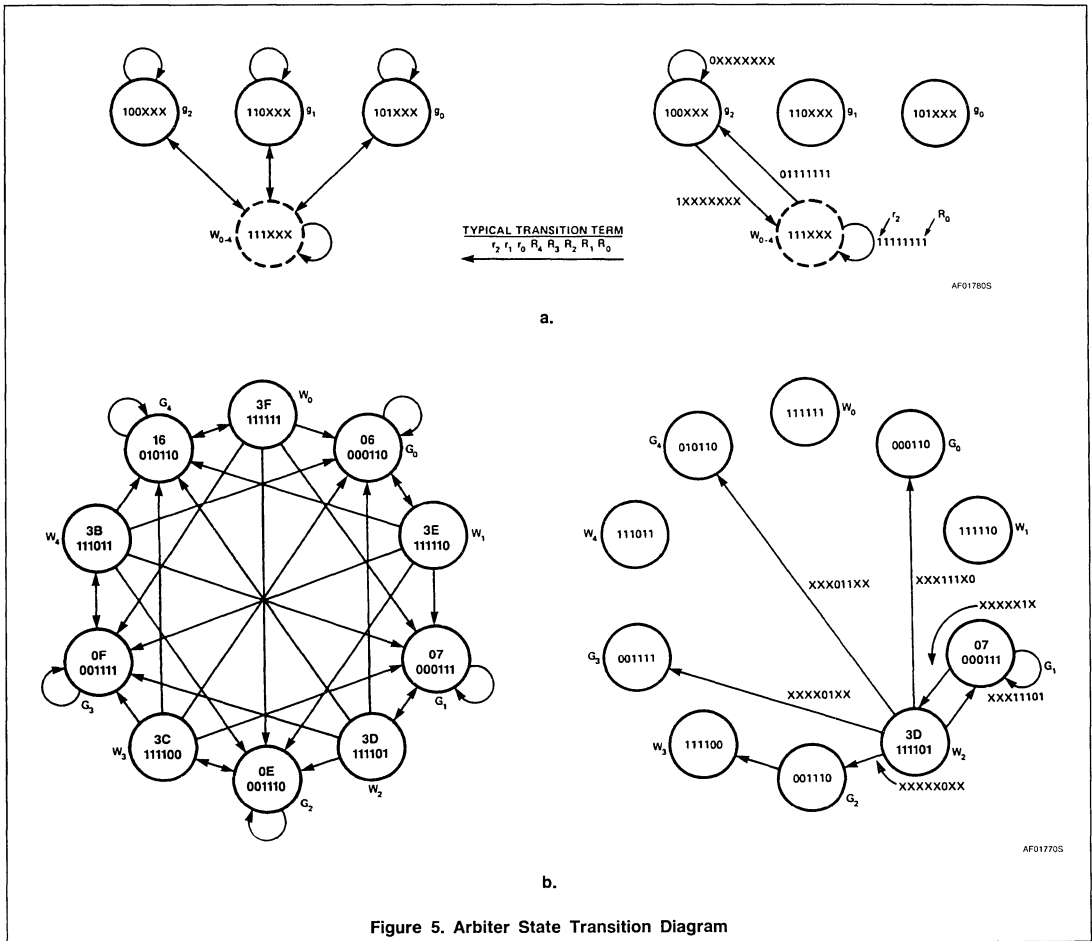
The same five "A" processor and three "b" processor arbiter can be implemented with discrete PROM's and Latches using the same state diagrams for the FPLS, except that now looping transition terms must be programmed. Coding of all state and output transitions requires programming of two memory fields: the "A" request PROM's (2KX6) and the "b" request PROM (64 X 3). The complete circuit diagram is shown in Figure 6(b).

The "A" request PROM's determine the next machine state ( $N_{0-5}$ ) at all times, except when there are no "A" requests pending and there is a "b" request, or if the machine is presently in a "b" grant state. In these cases, the "b" request PROM controls the machine's next state.

The grant control lines are decoded from the next state lines and latched in two quad output latches. This PROM/LATCH organization is conceptually the same as that shown in Figure 2.

# Single Chip Multiprocessor Arbiter

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# Single Chip Multiprocessor Arbiter

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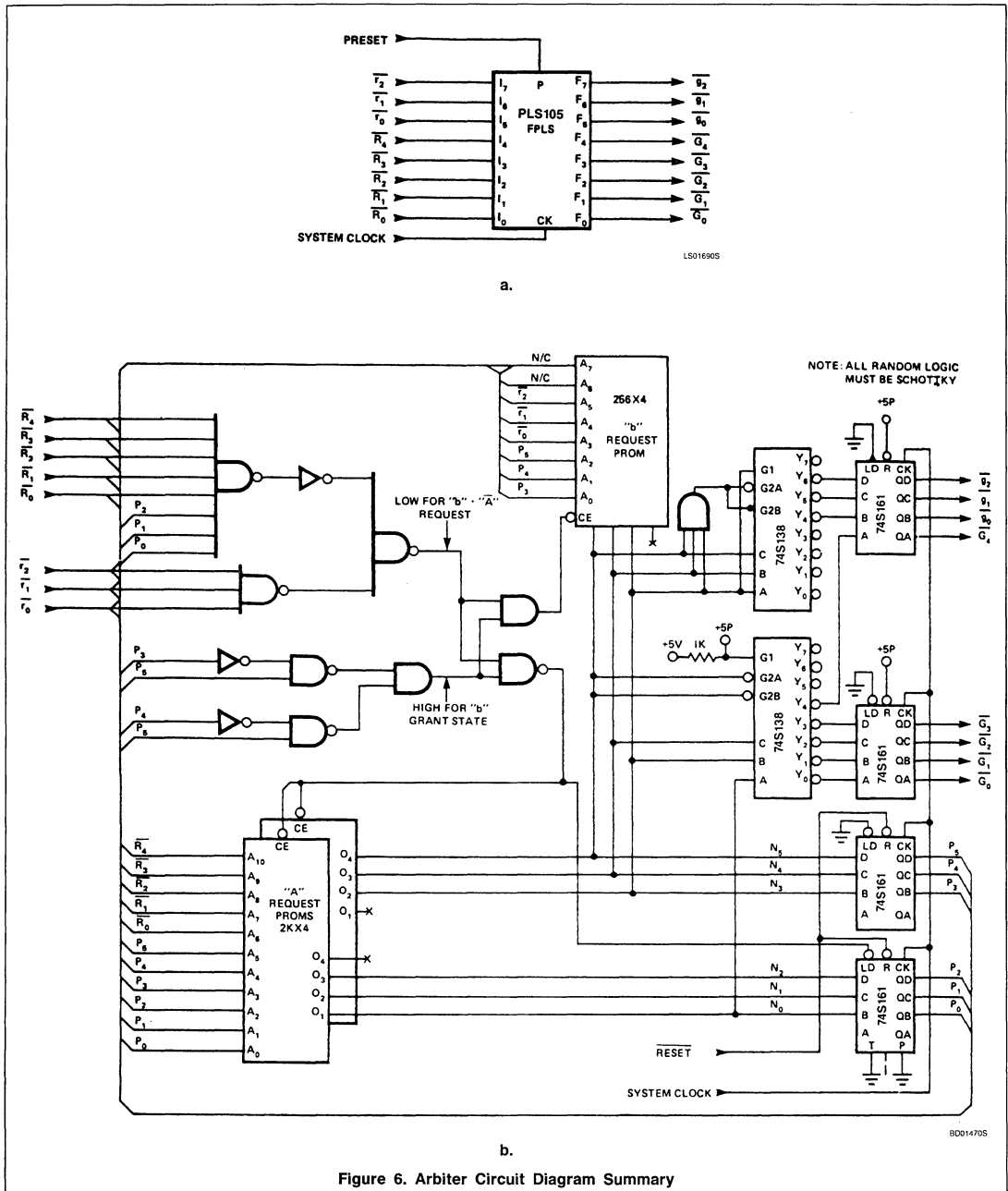


Figure 6. Arbiter Circuit Diagram Summary



## Single Chip Multiprocessor Arbiter

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```

***** ARBITERS *****
@DEVICE SELECTION
ARBITERB/82S105
@STATE VECTORS
[ FF5, FF4, FF3, FF2, FF1, FF0 ]
W0 = 03Fh ;
W1 = 03Eh ;
W2 = 03Dh ;
W3 = 03Ch ;
W4 = 03Bh ;
W04 = 111---b ;
GA0 = 06h ;
GA1 = 07h ;
GA2 = 0Eh ;
GA3 = 0Fh ;
GA4 = 16h ;
GB0 = 101---b ;
GB1 = 110---b ;
GB2 = 100---b ;

@INPUT VECTORS
@OUTPUT VECTORS
[OB2, OB1, OB0, OA4, OA3, OA2, OA1, OA0]
QA0' = FEh ;
QA1' = FDh ;
QA2' = FBh ;
QA3' = F7h ;
QA4' = EFh ;
QB0' = DFh ;
QB1' = BFh ;
QB2' = 7Fh ;
NOGRANT' = FFh ;

@TRANSITIONS
WHILE [W0]
CASE
  [/RA0] :: [GA0] WITH [QA0']
  [/RA1 * RA0] :: [GA1] WITH [QA1']
  [/RA2 * RA1 * RA0] :: [GA2] WITH [QA2']
  [/RA3 * RA2 * RA1 * RA0] :: [GA3] WITH [QA3']
  [/RA4 * RA3 * RA2 * RA1 * RA0] :: [GA4] WITH [QA4']
ENDCASE

WHILE [W1]
CASE
  [/RA1] :: [GA1] WITH [QA1']
  [/RA2 * RA1] :: [GA2] WITH [QA2']
  [/RA3 * RA2 * RA1] :: [GA3] WITH [QA3']
  [/RA4 * RA3 * RA2 * RA1] :: [GA4] WITH [QA4']
  [/RA0 * RA4 * RA3 * RA2 * RA1] :: [GA0] WITH [QA0']
ENDCASE

```

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## a. Arbiter State Equations

Figure 7

## Single Chip Multiprocessor Arbiter

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```

WHILE [W2]
CASE
[/RA2] :: [GA2] WITH [QA2']
[/RA3 * RA2] :: [GA3] WITH [QA3']
[/RA4 * RA3 * RA2] :: [GA4] WITH [QA4']
[/RA0 * RA4 * RA3 * RA2] :: [GA0] WITH [QA0']
[/RA1 * RA0 * RA4 * RA3 * RA2] :: [GA1] WITH [QA1']
ENDCASE

WHILE [W3]
CASE
[/RA3] :: [GA3] WITH [QA3']
[/RA4 * RA3] :: [GA4] WITH [QA4']
[/RA0 * RA4 * RA3] :: [GA0] WITH [QA0']
[/RA1 * RA0 * RA4 * RA3] :: [GA1] WITH [QA1']
[/RA2 * RA1 * RA0 * RA4 * RA3] :: [GA2] WITH [QA2']
ENDCASE

WHILE [W4]
CASE
[/RA4] :: [GA4] WITH [QA4']
[/RA0 * RA4] :: [GA0] WITH [QA0']
[/RA1 * RA0 * RA4] :: [GA1] WITH [QA1']
[/RA2 * RA1 * RA0 * RA4] :: [GA2] WITH [QA2']
[/RA3 * RA2 * RA1 * RA0 * RA4] :: [GA3] WITH [QA3']
ENDCASE

WHILE [W04]
CASE
[/RB0 * RA4 * RA3 * RA2 * RA1 * RA0] :: [GB0] WITH [QB0']
[/RB1 * RB0 * RA4 * RA3 * RA2 * RA1 * RA0] :: [GB1] WITH [QB1']
[/RB2 * RB1 * RB0 * RA4 * RA3 * RA2 * RA1 * RA0] :: [GB2] WITH [QB2']
ENDCASE

WHILE [GA0]
IF [RA0] THEN [W1] WITH [NOGRANT']

WHILE [GA1]
IF [RA1] THEN [W2] WITH [NOGRANT']

WHILE [GA2]
IF [RA2] THEN [W3] WITH [NOGRANT']

WHILE [GA3]
IF [RA3] THEN [W4] WITH [NOGRANT']

WHILE [GA4]
IF [RA4] THEN [W0] WITH [NOGRANT']

WHILE [GB0]
IF [RB0] THEN [GB1] WITH [NOGRANT']

WHILE [GB1]
IF [RB1] THEN [GB2] WITH [NOGRANT']

WHILE [GB2]
IF [RB2] THEN [GB0] WITH [NOGRANT']

```

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a. Arbiter State Equations (Continued)

Figure 7 (Continued)

9



# Single Chip Multiprocessor Arbiter

# AN7

```

***** ARBITERB *****
##### P I N   L I S T #####

```

LABEL	** FNC	**PIN	-----	PIN**	FNC **	LABEL
CLOCK	** CK	** 1-		1-28	** +5V	**VCC
RB2	** I	** 2-		1-27	** I	**N/C
RB1	** I	** 3-		1-26	** I	**N/C
RB0	** I	** 4-	8	1-25	** I	**N/C
RA4	** I	** 5-	2	1-24	** I	**N/C
RA3	** I	** 6-	S	1-23	** I	**N/C
RA2	** I	** 7-	1	1-22	** I	**N/C
RA1	** I	** 8-	0	1-21	** I	**N/C
RA0	** I	** 9-	5	1-20	** I	**N/C
OB2	** 0	** 10-		1-19	** PR	**PRESET
OB1	** 0	** 11-		1-18	** 0	**OA0
OB0	** 0	** 12-		1-17	** 0	**OA1
OA4	** 0	** 13-		1-16	** 0	**OA2
GND	** 0V	** 14-		1-15	** 0	**OA3

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### b. Arbiter Pin List

```

***** ARBITERB *****
@DEVICE TYPE
@2S105
@DRAWING
***** MULTI-PROCESSOR BUS ARBITOR
@REVISION
***** ARBITERB REV. 0
@DATE
***** JULY 26, 1985
@SYMBOL
***** ARBITERB
@COMPANY
***** SIGNETICS
@NAME
***** DAVID K. WONG
@DESCRIPTION
@INTERNAL SR FLIP FLOP LABELS
FF0 FF1 FF2 FF3 FF4 FF5

@COMMON PRODUCT TERM
@COMPLEMENT ARRAY
@LOGIC EQUATION

```

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### c. Arbiter Boolean Equations

Figure 7 (Continued)



## Single Chip Multiprocessor Arbiter

AN7

**SUMMARY**

As can be seen from the circuit diagrams, the FPLS can offer significant advantages over discrete MSI arrays in the design of state machines. The tradeoff in both design alternatives for the Priority Arbiter is shown in Table 2. Clearly, the FPLS approach uses fewer parts, with savings in PC board space and power requirements.

**REFERENCES**

1. W.W. Plumber: "Asynchronous Arbiters"; *IEEE Transactions on Computers*, January 1972, pp. 37 - 42.

**Table 3. Design Alternatives for the Priority Arbiter**

PARAMETER	F.P.L.S.	PROM/LATCH
Parts count	1 IC	≈19IC's
PCB space	.84 in <sup>2</sup>	7.92 in <sup>2</sup>
Power	.65W	2.85W
Voltage	+5V	+5V

2. R.C. Pearce, J.A. Field, and W.D. Little: "Asynchronous Arbiter Module"; *IEEE Transactions on Computers*, September 1975, pp. 931 - 933.
3. K. Soe Hojberg: "An Asynchronous Arbiter Resolves Resource Allocation Conflicts on a Random Priority Basis"; *Computer Design*, August 1977, pp. 120 - 123.
4. K. Soe Hojberg: "One-Step Programmable Arbiter for Multiprocessors"; *Computer Design*, April 1978, pp. 154 - 158.

### Application Specific Products

Author: K. A. H. Noach

### INTRODUCTION

Custom logic is expensive – too expensive if your production run is short. 'Random logic' is cheaper but occupies more sockets and board space. Signetics Programmable Logic bridges the gap. Using PLD, you can configure an off-the-shelf chip to perform just the logic functions you need. Design and development times are much shorter, and risk much lower than for custom logic. Connections are fewer than for random logic, and, for all but the simplest functions, propagation delay is usually shorter. Yet another advantage that PLD has over custom logic is that it allows you to redesign the functions without redesigning the chip – giving you an invaluable margin not only for cut-and-try during system development, but also for later revision of system design. You're not tied down by the need to recover capital invested in a custom chip.

A PLD chip is an array of logic elements – gates, inverters, and flip-flops, for instance. In the virgin state, everything is connected to everything else by nichrome fuses, and although the chip has the capacity to perform an extensive variety of logic functions, it doesn't have the ability to. What gives it that is programming: selectively blowing undesired fuses so that those that remain provide the interconnections necessary for the required functions.

Signetics Series 20 PLD, named for the number of pins, supplements the well-known Series 28. The package is smaller – little more than a third the size, in fact – but the improved architecture, with user-programmable shared I/O, compensates for the fewer pins. The series comprises the following members, in order of increasing complexity:

- PLS151 – field-programmable gate array
- PLS153 – field-programmable logic array

- PLS155 – field-programmable logic sequencer
- PLS157 – field-programmable logic sequencer
- PLS159 – field-programmable logic sequencer

Entry to all the devices is via a product matrix, an array of input and shared I/O lines fuse-connected to the multiple inputs of an array of AND gates (see Figures 1, 2 and 5). To exploit the capacity of any device, it is important to make the most economical use of the AND gates it has available. Application of de Morgan's theorem can help in this. For example, inputs for the function

$$F = A + B + C + D$$

would occupy four of the AND gates of the product matrix. However, the same function rewritten as

$$\bar{F} = \bar{A} \bar{B} \bar{C} \bar{D}$$

would occupy only one. Moreover, the second function could be done on the simplest of the Series 20 devices (and leave eleven gates over for other functions), whereas the first could not. The fact that all inputs of the Series 20 devices, including the shared ones, incorporate double buffers that make the true and complement forms of all input variables equally accessible, greatly facilitates the use of de Morgan's theorem for logic minimization.

To convert the minimized logic equations to the pattern of fuses to be blown, you can use either a programming sheet (see e.g. Table 1) or Boolean equation program-entry software that lets you enter the equations via the keyboard of a terminal. The direct programmability of logic equations makes system design with PLD simple and sure. Functional changes can be made by replacing one PLD chip by another differently programmed. In many cases you can even remove the original one, reprogram it on the spot, and re-insert it. Programming machines qualified for the Se-

ries 20 are at present available from DATA I/O, KONTRON, and STAG.

### FPGA PLS151

The field-programmable gate array is the simplest of the Series 20 PLD devices; Figure 1 shows the functional diagram. The array can accept up to 18 inputs. There are six dedicated input pins (A) and twelve (A') that can be programmed as inputs, outputs, or bidirectional I/O. All input variables, whether on dedicated or programmed input pins, are available in both, true and complement form in the product matrix (B), and both forms are buffered: either form can drive all 12 product lines if required. In the virgin state, all the input variables and their complements are connected to all the product lines via a diode and a fuse (C), and the product matrix is effectively inoperative. To enable it to generate the required functions, unrequired connections between individual input lines and product lines are severed by blowing the connecting fuses.

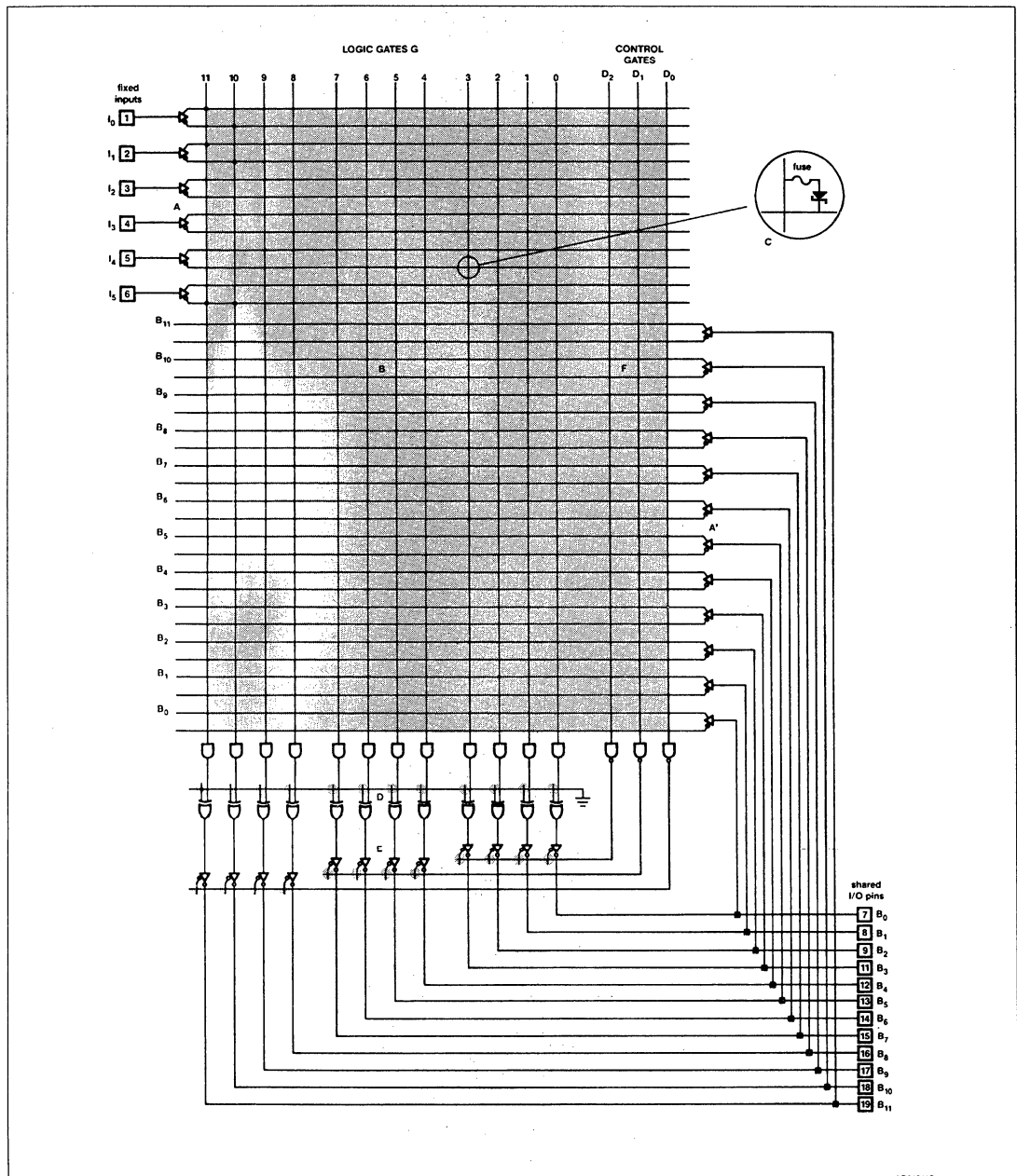
At the output of the product matrix are 12 NAND gates, each with 36 inputs to accommodate the 18 possible input variables and their complements. Each of the product terms is normally active-Low, but a unique feature of Signetics PLD is that any or all of them can be independently programmed active-High. This is done by means of an array of exclusive-OR gates (D) at the NAND-gate outputs; when the fuse that grounds the second input of each OR gate is blown, the output of that gate is inverted.

The product matrix and exclusive OR-gate connections shown in Figure 1 illustrate the flexibility conferred by having buffered complements of all input variables internally available, together with independently programmable output polarities. Output B<sub>11</sub>, shown with its exclusive OR-gate fuse intact, is programmed

$$\bar{B}_{11} = I_0 I_1 \bar{I}_5$$

# Introduction To Signetics Programmable Logic

AN8



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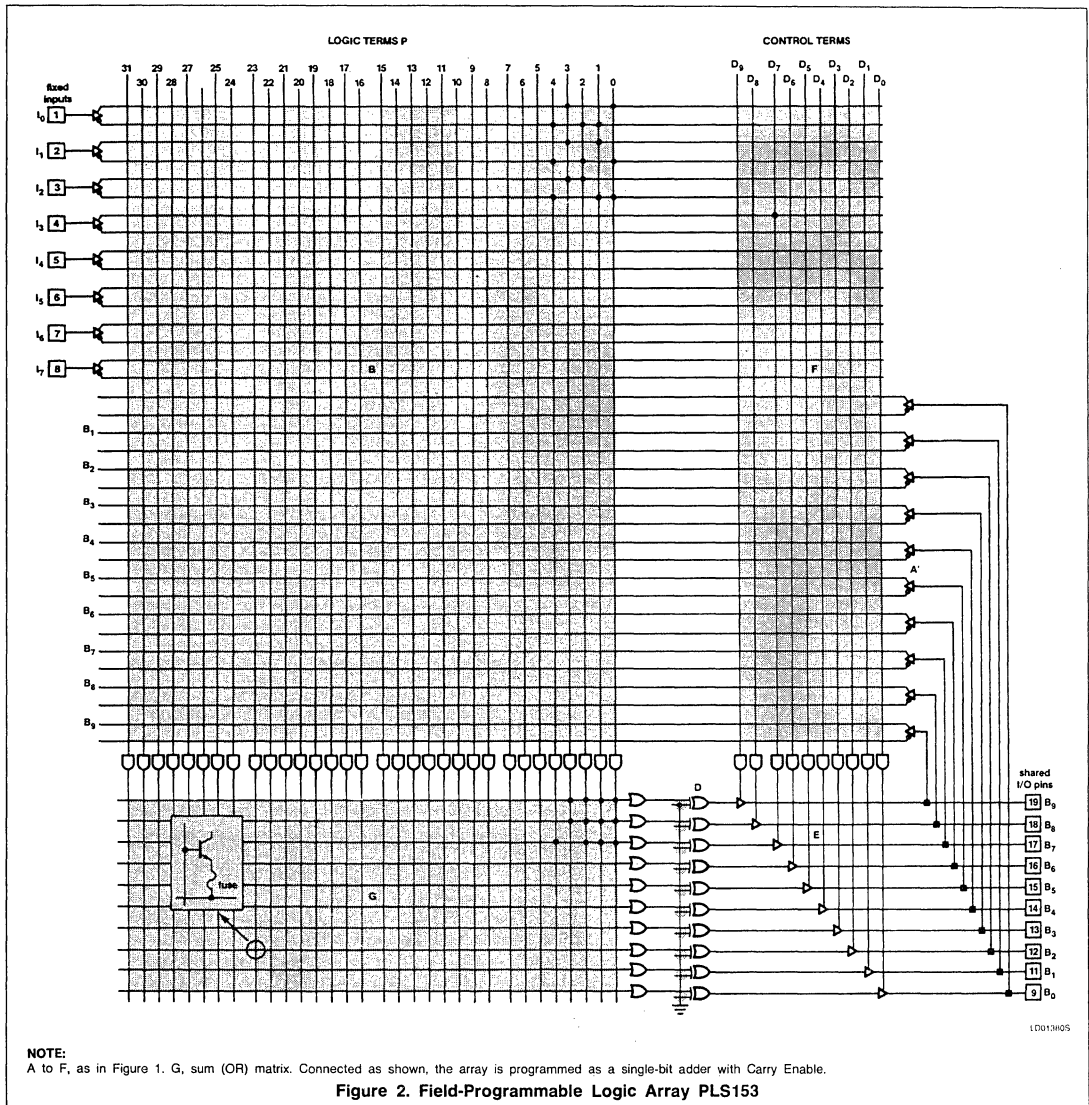
**NOTE:**

A, dedicated inputs; A', programmable I/O. B, product (NAND) matrix with fused connections C; each of the vertical lines in the matrix represents 36 inputs to the terminating NAND gated. D, exclusive-OR array with inputs grounded via fuses for polarity control. E, programmable Tri-state output buffers. F, fuse-programmable control matrix. Square dots (■) represent permanent connections; round dots (●) intact fuse connections. Connected as shown, the array is programmed for the functions  $B_{11} = I_0 I_1 I_5$  and  $B_{10} = I_0 I_1 I_5$ .

**Figure 1. Field-Programmable Gate Array PLS151A**

# Introduction To Signetics Programmable Logic

AN8



At the same time, and without using any additional inputs, output B<sub>10</sub> (fuse blown) is programmed

$$B_{10} = \overline{I_0} \overline{I_1} \overline{I_5}$$

Each of the exclusive-OR gates drives a three-state output buffer. In the virgin state all the buffers (E) are disabled and therefore in the high-impedance state. The function of the programmable I/O pins (A') is then determined by the I/O control matrix (F). The three AND gates at the control-matrix output are

Active-High, and when one of them is in the High state, the four output buffers it controls are enabled; the corresponding I/O pins then act as outputs. Conversely, when a control-matrix AND-gate output is Low and the control fuse for the corresponding Tri-state buffer is intact, the pins controlled by that gate act as inputs. Thus, these pins can be programmed in groups of up to four to act as inputs or outputs according to the state of selected input variables. If required, any of the programmable I/O pins can be made a

dedicated output by blowing the control fuse of the output buffer associated with it.

The speed of the FPGA compares favorably with TTL, although its propagation delay is longer than the individual gate delay of TTL. When the number of inputs required is large, however, the FPGA more than makes up for this. When more than eight inputs are required, for example, the FPGA has a distinct advantage. Then, the overall propagation de-

# Introduction To Signetics Programmable Logic

AN8

lay of TTL often amounts to two or three gate delays, but that of the FPGA to only one.

## FPLA PLS153

### Architecture

With two levels of logic embodied in a product matrix terminating in 32 AND gates coupled to a ten-output OR matrix (Figure 2), the FPLA is a step up in complexity from the FPGA. Again, there is provision for 18 input variables, internally complemented and buffered, but here divided between eight dedicated input pins and ten individually programmable I/O pins. As before, exclusive-OR gates grounded by fuses provide output polarity control, and any of the programmable I/O pins can be made a dedicated output by blowing the control fuse of the output buffer associated with it.

### Programming

When the required functions have been defined, corresponding programming instructions are entered in a programming table, the layout of which reflects the FPLA architecture. (A Signetics computer program named AMAZE, which accepts Boolean equations as input and generates an FPLA programming table as output, is also available.) The programming machine blows the FPLA fuses in the pattern prescribed by the table.

As an illustration of FPLA programming, consider a full adder. Figure 3 shows a TTL version (74LS80) and the corresponding logic equations. Note that the feedback of  $\bar{C}_{n+1}$  introduces a second propagation delay. In the FPLA this is eliminated by redefining  $\Sigma$  in terms of A, B, and  $C_n$ , as shown in Figure 4, and using the right side of the equation for  $\bar{C}_{n+1}$  instead of the term itself. At first glance this would appear to require a minimum of three product terms for  $\bar{C}_{n+1}$  plus four for  $\Sigma$ , or a total of seven. The Karnaugh maps, however, show considerable overlap between the two functions: the map for  $\bar{C}_{n+1}$  differs from that for  $\Sigma$  only by having A B  $C_n$  instead of  $\bar{A} \bar{B} \bar{C}_n$ . Rewriting the equation for  $\bar{C}_{n+1}$  to introduce  $\bar{A} \bar{B} \bar{C}_n$  and eliminate A B  $C_n$ ,

$$\bar{C}_{n+1} = A \bar{B} \bar{C}_n + \bar{A} B \bar{C}_n + \bar{A} \bar{B} C_n + \bar{A} \bar{B} \bar{C}_n$$

increases the number of product terms by one, but now  $\bar{C}_{n+1}$  and  $\Sigma$  have three terms in common. Therefore, since the FPLA allows multiple use of product terms, it is sufficient to program each of the common terms only once; thus, the original seven product terms are effectively reduced to five.

To fill in the programming table (Table 1), first allocate inputs and outputs.

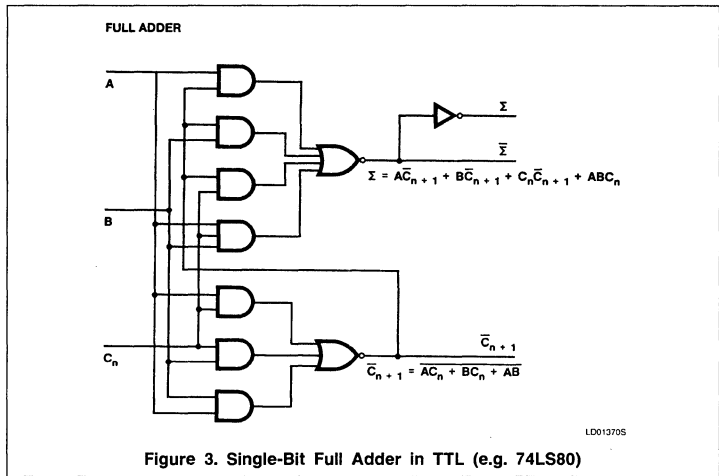


Figure 3. Single-Bit Full Adder in TTL (e.g. 74LS80)

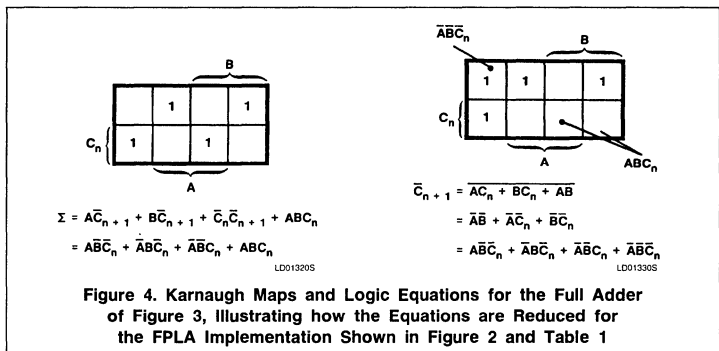


Figure 4. Karnaugh Maps and Logic Equations for the Full Adder of Figure 3, Illustrating how the Equations are Reduced for the FPLA Implementation Shown in Figure 2 and Table 1

Inputs: A = I<sub>0</sub>      Outputs:  $\bar{C}_{n+1}$  = B<sub>7</sub>  
 B = I<sub>1</sub>               $\Sigma$  = B<sub>8</sub>  
 C<sub>n</sub> = I<sub>2</sub>               $\Sigma$  = B<sub>9</sub>

Next, enter the product terms of  $\Sigma$  in the product-matrix (AND) part of the table, using H to indicate a true input and L a false one.

- Term 0 is  $\bar{A} \bar{B} \bar{C}_n$ : mark H, L, L in columns I<sub>0</sub>, I<sub>1</sub>, I<sub>2</sub> of row 0
- Term 1 is  $\bar{A} B \bar{C}_n$ : mark L, H, L in columns I<sub>0</sub>, I<sub>1</sub>, I<sub>2</sub> of row 1
- Term 2 is  $\bar{A} \bar{B} C_n$ : mark L, L, H in columns I<sub>0</sub>, I<sub>1</sub>, I<sub>2</sub> of row 2
- Term 3 is  $A B C_n$ : mark H, H, H in columns I<sub>0</sub>, I<sub>1</sub>, I<sub>2</sub> of row 3.

Fill the rest of rows 0, 1, 2, and 3 with dashes to indicate that all other inputs are to be disconnected from Terms 0, 1, 2, and 3 (fuses blown).

The product terms of  $\Sigma$  must be added to form the sum-of-products required at output

B<sub>9</sub>. Indicate the required addition by putting an A (for Attached, i.e. fuse unblown) in the Term 0, 1, 2, and 3 spaces of column B(O)<sub>9</sub>; Term 4 is not required for  $\Sigma$ , so put a dot in the Term 4 space to indicate that it is to be disconnected (fuse blown). To indicate that the output is to be Active-High, put an H in the polarity square above the B(O)<sub>9</sub> column. Finally, fill row D<sub>9</sub> with dashes to indicate that all fuses on line D<sub>9</sub> of the control matrix are to be blown and B<sub>9</sub> is to be a dedicated output. This completes the programming of  $\Sigma$ .

The  $\Sigma$  output on B<sub>8</sub> is programmed in just the same way, except that the polarity square above the B(O)<sub>8</sub> column is marked L to indicate Active-Low. (Note that in the FPLA, the  $\Sigma$  and  $\bar{\Sigma}$  outputs change simultaneously, because all output signals traverse the exclusive-OR array (D), whether they are Active-High or Active-Low. In the TTL full adder shown in Figure 3, the output inverter delays the change of  $\Sigma$  with respect to  $\bar{\Sigma}$ .)

# Introduction To Signetics Programmable Logic

AN8

Table 1. FPLA Programming Table Filled in for the Full Adder of Figure 2

		POLARITY																																											
		AND										OR																																	
		I										B(I)										B(O)																							
		TERM	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	1	0															
<p>PROGRAM TABLE ENTRIES:</p> <p>I, B(I)</p> <table border="1"> <tr><td>INACTIVE</td><td>0</td></tr> <tr><td>I</td><td>B</td></tr> <tr><td>B</td><td>DONT CARE</td></tr> <tr><td>DONT CARE</td><td>-</td></tr> </table> <p>(AND)</p> <p>B(O)</p> <table border="1"> <tr><td>HIGH</td><td>A</td></tr> <tr><td>LOW</td><td>L</td></tr> </table> <p>(POL)</p> <p>B(O)</p> <table border="1"> <tr><td>ACTIVE</td><td>A</td></tr> <tr><td>INACTIVE</td><td>•</td></tr> </table>	INACTIVE	0	I	B	B	DONT CARE	DONT CARE	-	HIGH	A	LOW	L	ACTIVE	A	INACTIVE	•	0	-	-	-	-	L	L	H	-	-	-	-	-	-	-	-	-	-	-	A	A	A							
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	2	-	-	-	-	-	H	L	L	-	-	-	-	-	-	-	-	-	-	-	A	A	A																						
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	4	-	-	-	-	-	L	L	L	-	-	-	-	-	-	-	-	-	-	-	•	•	A																						
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D0																																													
PIN NO.	8	7	6	5	4	3	2	1	19	18	17	16	15	14	13	12	11	9																											
VARIABLE NAME					ENABLE	C <sub>n</sub>	B	A	Σ	Σ	C <sub>n+1</sub>																																		

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# Introduction To Signetics Programmable Logic

AN8

The output  $C_{n+1}$  on  $B_7$  contains three of the same terms as  $\Sigma$ , plus the term  $\bar{A} \bar{B} \bar{C}_n$ . Only this last term needs to be additionally programmed in the product matrix: mark L, L, L in columns  $l_0, l_1, l_2$  of the Term 4 row. Indicate the addition

$$A \bar{B} \bar{C}_n + \bar{A} B \bar{C}_n + \bar{A} \bar{B} C_n + \bar{A} \bar{B} \bar{C}_n$$

by putting an A in rows 0, 1, 2, and 4 of column  $B(O)_7$ , and show that Term 3 ( $A B C_n$ ) is not required by putting a dot in the Term 3 row to indicate disconnection (fuse blown). Put an L in the  $B(O)_7$  polarity square to indicate Active-Low.

Identifying  $B_7$  as a dedicated output by indicating that all the fuses to control term  $D_7$  are to be blown, would now complete the programming of the full adder. However, a useful supplementary feature would be a Carry Enable function to keep the  $B_7$  output buffer in the high-impedance state except when the enable input  $I_3$  is true. The output buffer is enabled when both the fuses of a control term are blown, or when one is blown and the term that controls the output buffer is true. Thus, a Carry Enable can be provided via the  $I_3$  input by leaving intact the fuse for Active-High operation of the enable signal to control term  $D_7$ . To indicate this, put an H in the  $I_3$  column of row  $D_7$  and fill the rest of the row with dashes.

The full adder with output Carry Enable uses only four of the eight dedicated inputs, three of the ten programmable I/O pins, and five of the 32 AND gates. The remaining capacity can be used for programming other functions which may, if required, also make use of AND-gate outputs already programmed for the full adder.

All fuses not indicated as blown in the programming table are normally left intact to preserve capacity for later program revisions or the addition of supplementary functions. If it is essential to minimize propagation delay, however, the finalized program should include instructions for blowing all unused fuses to minimize load capacitance.

## FPLS PLS155 – PLS157 – PLS159

### Architecture

The FPLS (Figure 5) is the most complex of the Series 20 PLD devices. Like the FPLA, it has a 32-term product matrix followed by an OR matrix. In the FPLS, however, the OR matrix is larger and comprises three distinct parts, with architecture differing in detail from type to type. In the PLS155, for instance, the first part consists of eight 32-input gates coupled, like those of the FPLA, to an output-polarity-controlling exclusive-OR array. The

second consists of twelve additional gates which control four flip-flops. These are what give the FPLS its sequential character, enabling it to dictate its next state as a function of its present state. The third part is the deceptively simple Complement Array (I in Figure 5): a single OR gate with its output inverted and fed back into the product matrix. This enables a chosen sum-of-products to become a common factor of any or all the product terms and makes it possible to work factored sum-of-products equations. It is also useful for handshaking control when interfacing with a processor and for altering the sequence of a state machine without resorting to a large number of product terms.

PLS155 has four dedicated inputs and eight programmable I/O pins that can be allocated in the same way as in the FPLA. It also has four shared I/O pins (L) whereby the flip-flops can be interfaced with a bidirectional data bus. Two product terms,  $L_A$  and  $L_B$  in the control matrix F, control the loading of the flip-flops, in pairs, synchronized with the clock.

Figure 6 shows the architecture of the flip-flop circuitry in the PLS155. The flip-flops are positive-edge-triggered and can be dynamically changed to J-K, T, or D types according to the requirements of the function being performed; this considerably lessens the demands on the logic. The Tri-state inverter between the J and K inputs governs the mode of operation, under the control of the product term F:

- When the inverter is in the high-impedance state, the flip-flop is a J-K type, or a T type when  $J = K$ .
- When the inverter is active,  $K = \bar{J}$  and the flip-flop is a D type; the K input must then be disconnected from the OR matrix.

All the product terms from the product matrix ( $T_0$  to  $T_{31}$  in Figure 5) are fuse-connected to the J and K input OR gates. If both fuses of any one product term are left intact,  $J = K$  and the flip-flop is a T type.

The flip-flops of the PLS155 have asynchronous Preset and Reset controlled by terms in the OR matrix that take priority over the clock. Their three-state output buffers can be controlled from the enable pin OE or permanently enabled or disabled by blowing fuses or leaving them intact in the enable array (K in Figure 5).

The PLS157 and PLS159 sequencers have, respectively, six and eight flip-flops. The architecture differs in detail but is similar in principle to that of PLS155.

### Programming

The FPLS is programmed in much the same way as the FPLA, using a table to instruct the machine that blows the undesired fuses. It is not necessary to work with a circuit diagram; in fact, it is even undesirable to do so, since applying the necessary logic reduction techniques would in most cases make the diagram difficult to read and more a hindrance than a help. An example of how to program the FPLS as a universal counter/shift-register is given in the Appendix.

## DEVELOPMENT AND PRODUCTION ECONOMY WITH PLD

Underlying the design philosophy of the Signetics Series 20 PLD is the concept of programmable arrays whose architecture emulates logic equation formats rather than mere aggregations of gates. The unique combination of features which support this philosophy includes:

- double-buffered true and complement inputs
- programmable-polarity outputs
- programmable I/O for internal feedback and maximum freedom in allocating inputs and outputs
- truth-table programming format

These features are common to all the PLD devices. In the field-programmable logic sequencers they are further supported by:

- flip-flops with dynamically alterable operating modes
- a complement array for simplified handshaking control

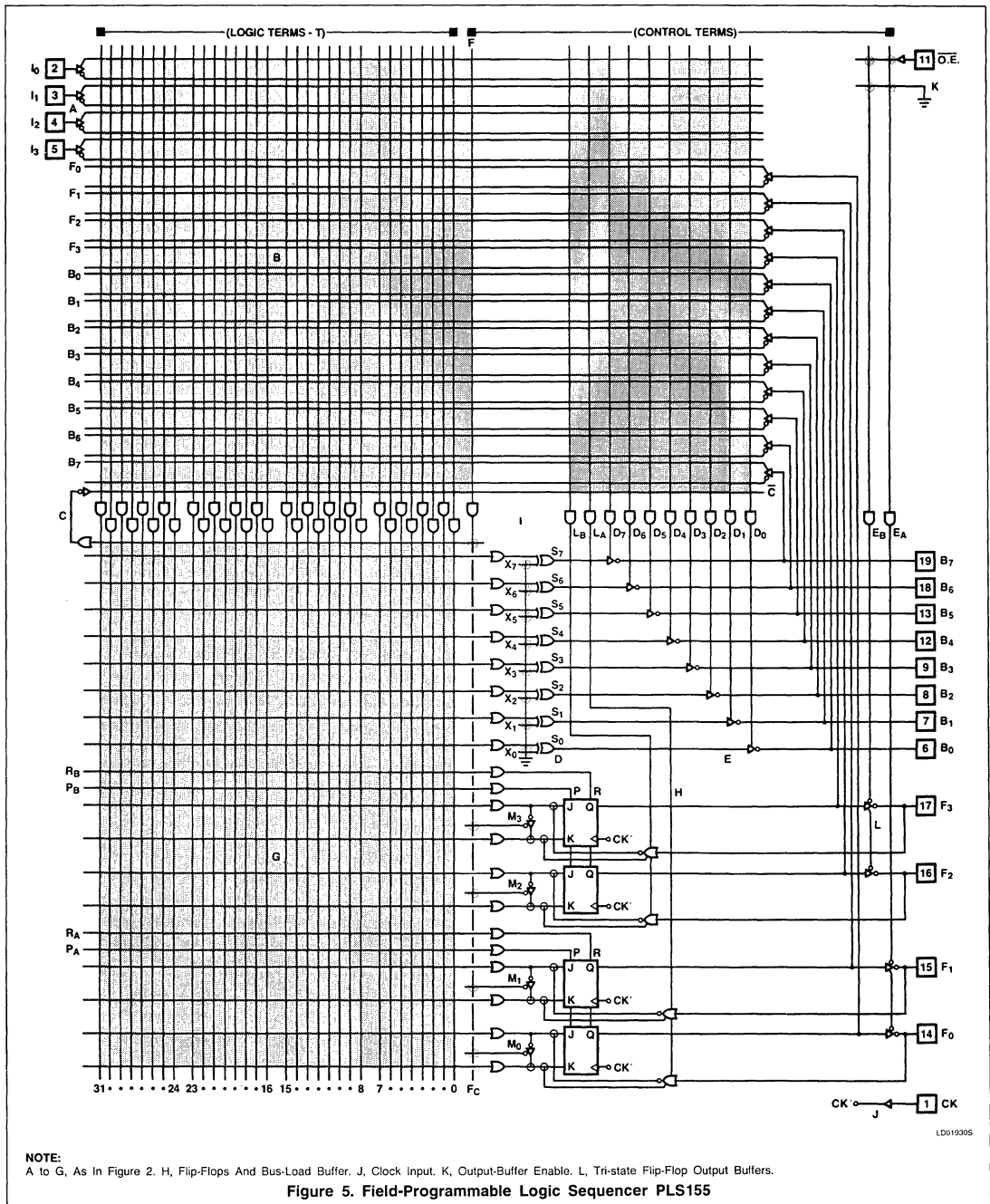
From the development engineer's point of view an important advantage of PLD is that it eliminates breadboarding. Once the functions required in terms of minimized logic equations are worked out, a PLD can be programmed accordingly. Once programmed, it will perform those functions.

Loading the instructions into the programming machine usually takes no more than a couple of hours; after that, the machine can program the devices at a rate of 100 an hour. Moreover, since any PLD can be programmed in many different ways, PLD has considerable potential for simplifying purchasing and stock control. One type of device can be programmed to perform a diversity of tasks for which it would otherwise be necessary to purchase and stock many different devices.

Series 20 PLD is second-sourced by Harris Semiconductor.

# Introduction To Signetics Programmable Logic

AN8



# Introduction To Signetics Programmable Logic

# AN8

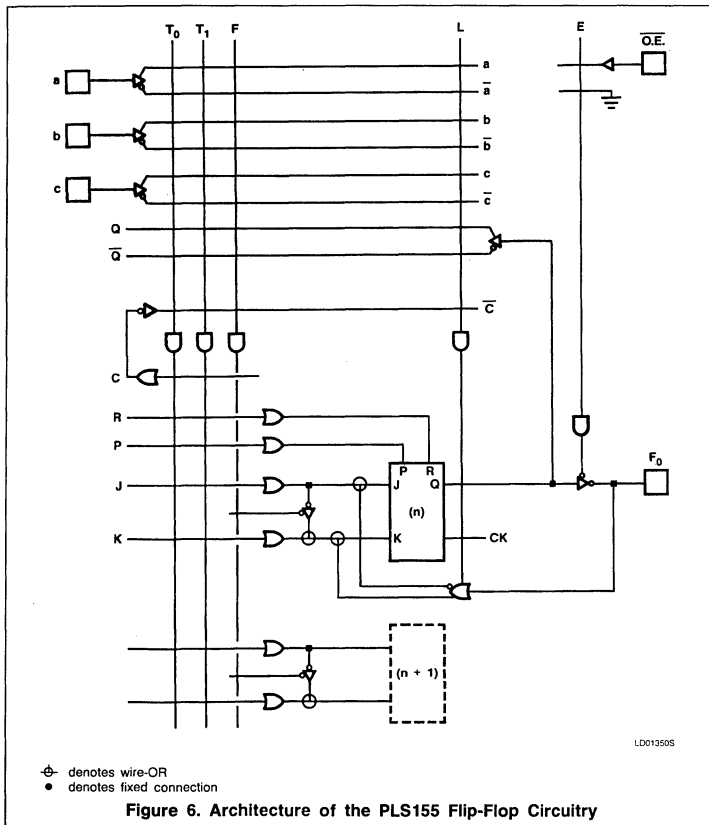


Figure 6. Architecture of the PLS155 Flip-Flop Circuitry

Table A-2, derive the excitation equations for the different types of flip-flops (the examples shown in Figure A-1 omit the T type because it is the same as the J-K type when J = K). In deciding which types of flip-flop to use, remember that logic minimization with PLD is different from logic minimization with 'random logic': with random logic you seek to reduce the number of standard packages required; with PLD you seek to reduce the number of product terms.

From Figure A-1 it is evident that you should choose J-K or T flip-flops for the counter mode and D flip-flops for the shift mode, for you then require only one product term per flip-flop per mode. Table A-4 summarizes the number of product terms per mode the various types of flip-flops would require.

Table A-5 shows the completed programming table for the counter/shift-register. The programming of Terms 0 to 15 reflects the flip-flop excitation equations and illustrates the value of being able to switch the flip-flops dynamically from one type of operation to another. Terms 16, 17 and 18, respectively, provide for INITIALIZE, asynchronous RESET, and STOP functions.

The programming of the two additional inputs HALT and BUSY illustrates the value of the complementary, which is made active when HALT and BUSY are Low (A in the Complement square of Term 18) and propagated into all the other terms (dot in the Complement squares of Terms 0 to 17). This means that unless the HALT and BUSY inputs are High, none of the product terms will be true and the state of the machine will not change. If the Complement Array were not used, twice the number of product terms would be required, even if one of the additional inputs were omitted.

As it is, the design uses only 19 of the 32 product terms available, so there is ample capacity for extending its capabilities. For example, the shift-left function can be augmented by a binary multiplication capability, using a D type flip-flop to make it shift one, two, or three places according to the state of two extra inputs, X and Y. Table A-6 shows the revised programming table. The binary multiplication function occupies nine additional product terms.

### ACKNOWLEDGEMENT

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## APPENDIX

### Programming an FPLS as a Counter/Shift-Register

Objective: to program a PLS155 FPLS as a count-up, count-down, shift-right, shift-left machine governed by three control terms - COUNT/SHIFT, RIGHT/UP, LEFT/DOWN. Direct implementation would result in a machine with 64 state transitions (see Table A-1), which is beyond the scope of the PLS155 or even the 28-pin PLS105. Logic reduction is therefore necessary.

As there are only four feedback variables (D, C, B, A), you can do the reduction by hand, one mode at a time; the control terms need not be included till the summary equations are written. Using the transition mapping method suggested here, you can examine the excitation equations for all types of flip-flops

(R-S, J-K, D, T) and choose those types that will perform the required functions using the fewest product terms. Table A-2 summarizes the rules for flip-flop implementation using transition maps; the transition symbols used in the table mean:

PRESENT STATE	NEXT STATE	TRANSITION SYMBOL
0	0	0
0	1	$\alpha$
1	0	$\beta$
1	1	1

Using these symbols, construct Table A-3 from Table A-1 to enable you to examine the excitation equations for all types of flip-flops. Proceeding one mode at a time, transfer the state conditions from Table A-3 to Karnaugh maps, as in Figure A-1. Following the rules in

# Introduction To Signetics Programmable Logic

AN8

**Table A-1. Present-State/Next-State Table for Counter/Shift-Register**

STATE NO.	PRESENT STATE				NEXT STATE																
					Count Down				Count Up				Shift Left				Shift Right				
	D	C	B	A	D	C	B	A	D	C	B	A	D	C	B	A	D	C	B	A	
0	0	0	0	0	1	1	1	1	0	0	0	1	0	0	0	0	0	0	0	0	0
1	0	0	0	1	0	0	0	0	0	0	1	0	0	0	1	0	0	1	0	0	0
2	0	0	1	0	0	0	0	1	0	0	1	1	0	1	0	0	0	0	0	0	1
3	0	0	1	1	0	0	1	0	0	1	0	0	0	1	1	0	0	1	0	0	1
4	0	1	0	0	0	0	1	1	0	1	0	1	1	0	0	0	0	0	0	1	0
5	0	1	0	1	0	1	0	0	0	1	1	0	0	1	1	0	1	0	1	0	0
6	0	1	1	0	0	1	0	1	0	1	1	1	1	1	0	0	0	0	1	1	1
7	0	1	1	1	0	1	1	0	1	0	0	0	1	1	1	0	1	0	1	1	1
8	1	0	0	0	0	1	1	1	1	0	0	1	0	0	0	1	0	1	0	0	0
9	1	0	0	1	1	0	0	0	1	0	1	0	0	0	1	1	1	1	0	0	0
10	1	0	1	0	1	0	0	1	1	0	1	1	0	1	0	1	0	1	0	1	0
11	1	0	1	1	1	0	1	0	1	1	0	0	0	1	1	1	1	1	0	1	1
12	1	1	0	0	1	0	1	1	1	1	0	1	1	0	0	1	1	0	1	1	0
13	1	1	0	1	1	1	0	0	1	1	1	0	1	0	1	1	1	1	1	1	0
14	1	1	1	0	1	1	1	0	1	1	1	1	1	1	0	1	0	1	1	1	1
15	1	1	1	1	1	1	1	0	0	0	0	0	1	1	1	1	1	1	1	1	1
<b>CONTROL TERMS</b>																					
COUNT/SHIFT					1				1				0				0				
RIGHT/UP					0				1				0				1				
LEFT/DOWN					1				0				1				0				

**Table A-2. Rules for Flip-Flop Implementation Using Transition Maps**

FLIP-FLOP TYPE	INPUT	MUST INCLUDE	MUST EXCLUDE	REDUNDANT
R-S	S	$a$	$\beta, 0$	1,x
	R	$\beta$	$a, 1$	0,x
D	D	$a, 1$	$\beta, 0$	x
T	T	$a, \beta$	0,1	x
J-K	J	$a$	0	1, $\beta, x$
	K	$\beta$	1	0, $a, x$

# Introduction To Signetics Programmable Logic

AN8

Table A-3. Transition Table for Counter/Shift-Register

STATE NO.	PRESENT STATE				TRANSITION															
					Count Down				Count Up				Shift Left				Shift Right			
0	D	C	B	A	D	C	B	A	D	C	B	A	D	C	B	A	D	C	B	A
1	0	0	0	0	a	a	a	a	0	0	0	a	0	0	0	a	0	0	0	0
2	0	0	0	1	0	0	0	$\beta$	0	0	a	$\beta$	0	0	a	$\beta$	a	0	0	$\beta$
3	0	0	1	0	0	0	1	$\beta$	0	a	$\beta$	$\beta$	0	a	1	0	a	0	$\beta$	1
4	0	1	0	0	0	$\beta$	a	a	0	1	0	a	a	$\beta$	0	0	0	$\beta$	a	0
5	0	1	0	1	0	1	0	$\beta$	0	1	a	$\beta$	a	$\beta$	a	$\beta$	a	$\beta$	a	$\beta$
6	0	1	1	0	0	1	$\beta$	a	0	1	1	a	a	1	$\beta$	0	0	$\beta$	1	a
7	0	1	1	1	0	1	1	$\beta$	a	$\beta$	$\beta$	$\beta$	a	1	1	$\beta$	a	$\beta$	1	1
8	1	0	0	0	$\beta$	a	a	a	1	0	0	a	$\beta$	0	0	a	$\beta$	a	0	0
9	1	0	0	1	1	0	0	$\beta$	1	0	a	$\beta$	$\beta$	0	a	1	1	a	0	$\beta$
10	1	0	1	0	1	0	$\beta$	a	1	0	1	a	$\beta$	a	$\beta$	a	$\beta$	a	$\beta$	a
11	1	0	1	1	1	0	1	$\beta$	1	a	$\beta$	$\beta$	$\beta$	a	1	1	1	a	$\beta$	1
12	1	1	0	0	1	$\beta$	a	a	1	1	0	a	1	$\beta$	0	a	$\beta$	1	a	0
13	1	1	0	1	1	1	0	$\beta$	1	1	a	$\beta$	1	$\beta$	a	1	1	1	a	$\beta$
14	1	1	1	0	1	1	$\beta$	a	1	1	1	a	1	1	$\beta$	a	$\beta$	1	1	a
15	1	1	1	1	1	1	1	$\beta$	$\beta$	$\beta$	$\beta$	$\beta$	1	1	1	1	1	1	1	1

Table A-4. Number of Product Terms Required for Counter/Shift-Register Flip-Flop Excitation

FLIP-FLOP TYPE	COUNT UP	COUNT DOWN	SHIFT RIGHT	SHIFT LEFT	TOTAL
SR only	8	8	8	8	32
JK only	4	4	8	8	24
D only	10	10	4	4	28
FPLS	4(J-K)	4(J-K)	4(D)	4(D)	16

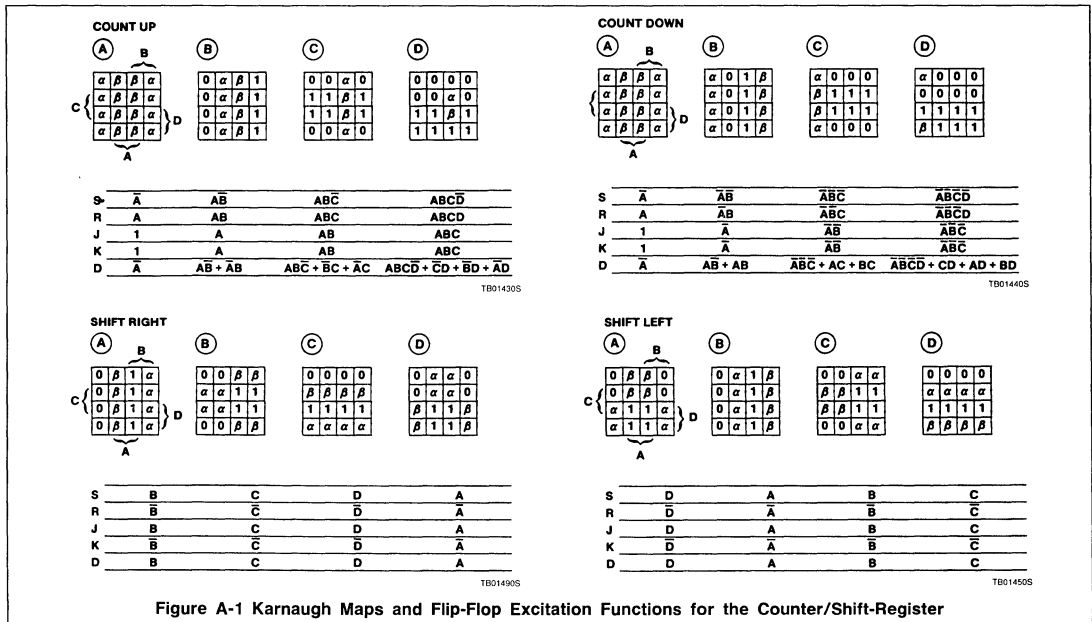


Figure A-1 Karnaugh Maps and Flip-Flop Excitation Functions for the Counter/Shift-Register

# Introduction To Signetics Programmable Logic

AN8

Table A-5. PLS155 FPLS Programming Table for the Counter/Shift-Register

PROGRAM TABLE ENTRIES		E <sub>A</sub> , E <sub>B</sub>		Q- J/K		F/F TYPE		E <sub>B</sub> = A E <sub>A</sub> = A				POLARITY															
								AND				OR						H									
								B(I)				Q(P)		Q(N)			P			B(O)							
TERM	C	3	2	1	0	7	6	5	4	3	2	1	0	3	2	1	0	7	6	5	4	3	2	1	0		
0	•	L	H	L	H	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
1	•	L	H	L	H	L	COUNT				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
2	•	L	H	L	H	L	DOWN				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
3	•	L	H	L	H	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
4	•	L	L	H	H	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
5	•	L	L	H	H	L	COUNT				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
6	•	L	L	H	H	L	UP				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
7	•	L	L	H	H	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
8	•	L	H	L	H	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
9	•	L	H	L	L	L	SHIFT				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
10	•	L	H	L	L	L	LEFT				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
11	•	L	H	L	L	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
12	•	L	L	H	L	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
13	•	L	L	H	L	L	SHIFT				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
14	•	L	L	H	L	L	RIGHT				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
15	•	L	L	H	L	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
16	•	H	-	-	-	-	INITIALIZE				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
17	•	-	-	-	-	-	RESET				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
18	A	-	-	-	-	-	STOP				-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
19																											
20																											
21																											
22																											
23																											
24																											
25																											
26																											
27																											
28																											
29																											
30																											
31																											
F <sub>C</sub>	-	-	-	-	L	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		
L <sub>B</sub>																											
L <sub>A</sub>																											
D <sub>7</sub>	•	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
D <sub>6</sub>	•	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
D <sub>5</sub>	•	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
D <sub>4</sub>																											
D <sub>3</sub>																											
D <sub>2</sub>																											
D <sub>1</sub>																											
D <sub>0</sub>	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
VARIABLE NAME		5	4	3	2	19	18	13	12	9	8	7	6	17	16	15	14										
		INIT	LEFT DOWN	RIGHT UP	COUNT SHIFT	NUMBER	THREAT	BUS	4					ACTIVE	D	C	B	A									



# AN10 4-Bit Binary-To-7 Segment Decoder

## Application Note

### Application Specific Products

#### INTRODUCTION

Using the PLS153 or PLS153A, a 4-bit binary-to-7 segment decoder may be easily constructed. This paper will cover Hex-to-7 segment decoder, BCD-to-7 segment decoder, decoder with latches, and decoder with multiplexer. The architecture of PLS153/153A is basically an AND-OR matrix. The large number of inputs of each AND term is ideal for decoder applications, and the ability to drive the entire OR array makes possible the efficient use of AND terms such that, together with the programmable output polarity, a minimum number of AND terms is needed to implement the decoder function. Another important feature of the PLS153/153A architecture is the 10 bidirectional I/O pins. The bidirectionality of these pins provides internal feedback to the AND matrix, which eliminates the need for external wiring and, more importantly, it saves I/O pin requirements. All I/O pins of the PLS153/153A have tri-state output buffers, each may be enabled or disabled by its own controlling AND terms. In applications where high current drive is necessary but low power consumption is still desirable, the AND term controlled tri-state buffers are ideal for multiplexing. The LED display may be driven at a higher current and lower duty cycle to get better brightness/current efficiency and reduce the overall power dissipation.

#### DESCRIPTION

##### Hex-To-7 Segment Decoder

A 7 segment display (Figure 1) may be used to represent a hexadecimal number as shown in Table 1. The format serves merely as an example. Some designers may prefer other configurations, particularly for letters B and D. Before implementing the truth table with programmable logic devices, one has to decide whether the outputs should be Active-High or Active-Low. If a moderate drive current of 15mA or less is needed, and if a common anode LED

display is used, then an Active-Low output configuration is sufficient. On the other hand, if only a common cathode LED display is available and the current drive requirement is not very critical, an Active-High output configuration may be used. The change of output polarity may be easily affected by putting in the POLARITY section 'H' for Active-High and 'L' for Active-Low. Since the output polarity is programmable, one may choose to describe the logic in terms of outputs equal to '1's or outputs equal to '0's.

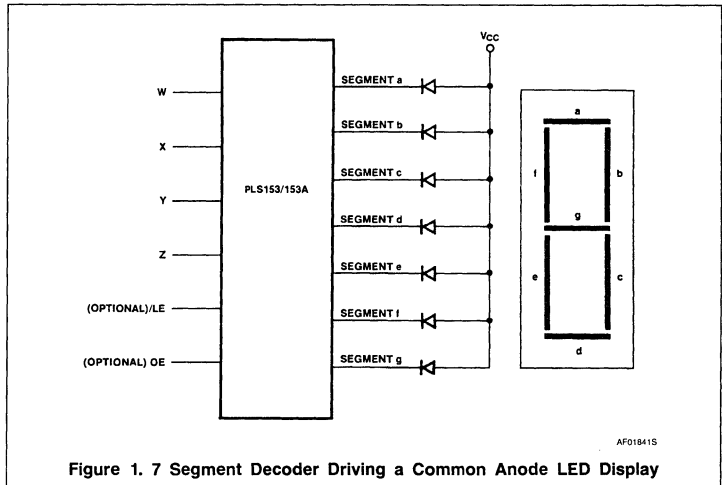


Figure 1. 7 Segment Decoder Driving a Common Anode LED Display

```

A>***** P I N   L I S T *****
      LABEL      ** FNC **PIN ----- PIN** FNC ** LABEL
W      ** I      ** 1-!   :-20 ** +5V **VCC
X      ** I      ** 2-!   :-19 ** B   **N/C
Y      ** I      ** 3-!   :-18 ** B   **N/C
Z      ** I      ** 4-!   :-17 ** B   **/SEG_A
N/C    ** I      ** 5-!   :-16 ** B   **/SEG_B
N/C    ** I      ** 6-!   :-15 ** B   **/SEG_C
N/C    ** I      ** 7-!   :-14 ** B   **/SEG_D
/DE    ** I      ** 8-!   :-13 ** B   **/SEG_E
N/C    ** B      ** 9-!   :-12 ** B   **/SEG_F
GND    ** OV     ** 10-!  :-11 ** B   **/SEG_G
  
```

TB00981S

Figure 2. Pin List of Binary-to-7 Segment Decoder

#### NOTE:

PLSXXX and 82SXXX are interchangeable part numbers.



# 4-Bit Binary-To-7 Segment Decoder

AN10

**Table 1. Truth Table of Hex-to-7-Segment Decoder**

0000 0001 0010 0011 0100 0101 0110 0111 1000 1001

1010 1011 1100 1101 1110 1111

Z	V	X	W	a	b	c	d	e	f	g
0	0	0	0	1	1	1	1	1	1	0
0	0	0	1	0	1	1	0	0	0	0
0	0	1	0	1	1	0	1	1	0	1
0	0	1	1	1	1	1	0	0	0	1
0	1	0	0	0	1	1	0	0	1	1
0	1	0	1	1	0	1	1	0	1	1
0	1	1	0	1	1	1	1	1	1	1
0	1	1	1	1	1	0	0	0	0	0
1	0	0	0	1	1	1	1	1	1	1
1	0	0	1	1	1	1	0	1	1	1
1	0	1	0	1	1	0	1	1	1	1
1	0	1	1	0	0	1	1	1	1	1
1	1	0	0	1	0	0	1	1	1	0
1	1	0	1	0	1	1	1	0	1	1
1	1	1	0	1	0	0	1	1	1	1
1	1	1	1	1	0	0	0	1	1	1

TB009905



# 4-Bit Binary-To-7 Segment Decoder

AN10

Table 3. H/L Programming Table for Binary-to-7 Segment Decoder

82S153/153A PROGRAMMING TABLE DRAWING ID: B-7-SEG DECODER REV. A  
 DESIGNER: D. K. WONG DATE: 12/15/84 POLARITY

I	AND						OR						COMMENTS				
	B(1)			B(0)			B(1)			B(0)							
	7:6	5:4	3:2:1:0	9:8	7:6	5:4	3:2:1:0	9:8	7:6	5:4	3:2:1:0	9:8		7:6	5:4	3:2:1:0	
0	L	L	L	L	L	L	L	L	.	.	.	.	.	.	.	.	A
1	L	L	L	H	L	L	L	H	.	.	.	A	.	.	.	A	A
2	L	L	H	L	L	L	H	L	.	.	.	A	.	.	.	A	A
3	L	L	H	H	L	L	H	H	.	.	.	A	.	.	.	A	A
4	L	H	L	L	L	H	L	L	.	.	.	A	.	.	.	A	A
5	L	H	L	H	L	H	L	H	.	.	.	A	.	.	.	A	A
6	L	H	H	L	L	H	H	L	.	.	.	A	.	.	.	A	A
7	L	H	H	H	L	H	H	H	.	.	.	A	.	.	.	A	A
8	H	L	L	L	H	L	L	L	.	.	.	A	.	.	.	A	B(*)
9	H	L	L	H	H	L	L	H	.	.	.	A	.	.	.	A	B
10	H	L	H	L	H	L	H	L	.	.	.	A	.	.	.	A	B
11	H	L	H	H	H	L	H	H	.	.	.	A	.	.	.	A	B
12	H	H	L	L	H	H	L	L	.	.	.	A	.	.	.	A	E
13	H	H	L	H	H	H	L	H	.	.	.	A	.	.	.	A	E
14	H	H	H	L	H	H	H	L	.	.	.	A	.	.	.	A	E
15	H	H	H	H	H	H	H	H	.	.	.	A	.	.	.	A	F
16																	
17																	
18																	
19																	
20																	
21																	
22																	
23																	
24																	
25																	
26																	
27																	
28																	
29																	
30																	
31																	
D9																	
D8																	
D7	H																
D6	H																
D5	H																
D4	H																
D3	H																
D2	H																
D1	H																
D0	H																
N																	
A																	
R																	
E																	
S																	

(\*) SINCE THIS TERM IS "INACTIVE", IT MAY BE DELETED. THEREFORE, THE TOTAL # OF TERMS REQUIRED IS 15.

TB01015

# 4-Bit Binary-To-7 Segment Decoder

AN10

```

@DEVICE TYPE
@2S153
@DRAWING
***** BINARY-TO-7 SEGMENT DECODER
@REVISION
***** REV. -
@DATE
***** OCT 1, 1984
@SYMBOL
***** FILE ID: 7deco
@COMPANY
***** SIGNETICS
@NAME
***** DAVID K. WONG
@DESCRIPTION
*****
* This circuit converts a 4-bit binary code ( HEX ) into *
* a 7-segment display. The display is a common anode 7-segment LED. *
* The output of the 82S153 goes LOW for each segment that is ON. *
*****

```

		TRUTH TABLE										
		Z	Y	X	W	a	b	c	d	e	f	g
f		0	0	0	0	0	0	0	0	0	0	1
		0	0	0	1	1	0	0	1	1	1	1
		0	0	1	0	0	0	1	0	0	1	0
e		0	0	1	1	0	0	0	0	1	1	0
		0	1	0	0	1	0	0	1	1	0	0
		0	1	0	1	0	1	0	0	1	0	0
		0	1	1	1	0	0	0	1	1	1	1
		1	0	0	0	0	0	0	0	0	0	0
		1	0	0	1	0	0	0	1	0	0	0
		1	0	1	0	0	0	0	1	0	0	0
		1	0	1	1	1	1	0	0	0	0	0
		1	1	0	0	0	1	1	0	0	0	1
		1	1	0	1	1	0	0	0	0	1	0
		1	1	1	0	0	1	1	0	0	0	0
		1	1	1	1	0	1	1	1	0	0	0

```

@COMMON PRODUCT TERM
ZER = /z * /y * /x * /w ;
ONE = /z * /y * /x * w ;
TWO = /z * /y * x * /w ;
THR = /z * /y * x * w ;
FOU = /z * y * /x * /w ;
FIV = /z * y * x * /w ;
SIX = /z * y * x * w ;
SEV = z * /y * /x * /w ;
EIG = z * /y * /x * w ;
NIN = z * /y * x * /w ;
AAA = z * /y * x * w ;
BBB = z * y * /x * /w ;
CCC = z * y * x * w ;
DDD = z * y * /x * w ;
EEE = z * y * x * /w ;
FFF = z * y * x * w ;

```

TB010205

Figure 3. Boolean Equation for Binary-to-7 Segment Decoder

# 4-Bit Binary-To-7 Segment Decoder

AN10

```

@LOGIC EQUATION
/SEG_A = ONE + FOU + BBB + DDD      ;
/SEG_B = FIV + SIX + BBB + CCC + EEE + FFF  ;
/SEG_C = TWO + CCC + EEE + FFF      ;
/SEG_D = ONE + FOU + SEV + AAA + FFF      ;
/SEG_E = ONE + THR + FOU + FIV + SEV + NIN  ;
/SEG_F = ONE + TWO + THR + SEV + DDD      ;
/SEG_G = ZER + ONE + SEV + CCC        ;

@I/O DIRECTION 150/1, 152/3, 154-9
"
*****
*           OUTPUTS ARE ENABLED WHEN /OE GOES LOW.           *
*           THEREFORE, D1..D7 = /( /OE) = OE                ;   *
*****
D1 = OE ;
D2 = OE ;
D3 = OE ;
D4 = OE ;
D5 = OE ;
D6 = OE ;
D7 = OE ;

"
*****
*           END OF LOGIC EQUATIONS                           *
*****

```

TB010005

Figure 3 (Continued)

In this example, an Active-Low output goes Low when a segment is to be turned on. The truth table shown in Table 1 is translated into an H/L programming table as shown in Table 2. Since the LED display used here is common anode, the output polarity of each output pin is programmed "L" so that an output goes low when a segment is to be turned on. The decoder takes 16 AND terms. Notice that all outputs go Low when input equals "8". If

the logic is written for "0s" instead of "1s", one AND term could be saved. Table 3 shows that the same circuit may be implemented by using only 15 AND terms. Notice that the polarity is the reverse of that of Table 2. The outputs may be turned on and off by I<sub>7</sub> /OE, which controls the 7 tri-state output buffers through control terms (AND terms D<sub>1</sub> to D<sub>7</sub>). The same design is also implemented using Boolean equations with AMAZE. Figures 2

through 4 are, respectively, pin list, logic equations, and logic simulation results of the hex-to-7 segment decoder circuit generated by AMAZE. Table 4 is the H/L table generated by AMAZE. In the process of generating Boolean equations for the decoder, common product terms are used to economize the usage of AND terms.

# 4-Bit Binary-To-7 Segment Decoder

AN10

Table 4. H/L Table Generated by AMAZE for Binary-to-7 Segment Decoder

```

Cust/Project - ***** DAVID K. WONG
Date         - ***** OCT 1, 1984
Rev/I. D.    - ***** REV. -

82S153                !     POLARITY     !
-----
T !                                     !H:H:H:H:H:H:H:H:H!
E !-----
R !           I           !           B(i)           !           B(o)           !
M !-----
!7_6_5_4_3_2_1_0!9_8_7_6_5_4_3_2_1_0!9_8_7_6_5_4_3_2_1_0!
0!- - - ,L L L H!- - - , - - - , - - - !A A, A . . A, A A A A!
1!- - - ,L H L L!- - - , - - - , - - - !A A, A . . A, A . . A!
2!- - - ,H L H H!- - - , - - - , - - - !A A, A A . . . . A!
3!- - - ,H H L H!- - - , - - - , - - - !A A, A . . . . A!
4!- - - ,L H L H!- - - , - - - , - - - !A A, . A . . , A . . A!
5!- - - ,L H H L!- - - , - - - , - - - !A A, . A . . . . A!
6!- - - ,H H L L!- - - , - - - , - - - !A A, . A A . . . . A!
7!- - - ,H H H L!- - - , - - - , - - - !A A, . A A . . . . A!
8!- - - ,H H H H!- - - , - - - , - - - !A A, . A A . . . . A!
9!- - - ,L L H L!- - - , - - - , - - - !A A, . A . . . . A!
10!- - - ,L H H H!- - - , - - - , - - - !A A, . . . A, A A A!
11!- - - ,H L L H!- - - , - - - , - - - !A A, . . . . A A A!
12!- - - ,H L H L!- - - , - - - , - - - !A A, . . . A, . . A!
13!- - - ,L L H H!- - - , - - - , - - - !A A, . . . . A A A!
14!- - - ,L L L L!- - - , - - - , - - - !A A, . . . . A A!
15!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
16!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
17!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
18!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
19!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
20!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
21!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
22!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
23!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
24!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
25!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
26!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
27!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
28!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
29!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
30!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
31!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!A A, A A A A, A A A A!
D9!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!
D8!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!
D7!L - - - - - !- - - - - !- - - - - !
D6!L - - - - - !- - - - - !- - - - - !
D5!L - - - - - !- - - - - !- - - - - !
D4!L - - - - - !- - - - - !- - - - - !
D3!L - - - - - !- - - - - !- - - - - !
D2!L - - - - - !- - - - - !- - - - - !
D1!L - - - - - !- - - - - !- - - - - !
D0!0 0 0 0,0 0 0 0!0 0,0 0 0 0,0 0 0 0!

      / N N N Z Y X W N N / / / / / N N N / / / / / N
      0 / / / / / S S S S S S S / / / S S S S S S S /
      E C C C          C C E E E E E E C C C E E E E E E E C
                        G G G G G G G          G G G G G G G
                        A B C D E F G          A B C D E F G
  
```

T8010405

# 4-Bit Binary-To-7 Segment Decoder

AN10

```

B2S153  A:7deco153.STD
" 4-bit binary to 7-segment decoder simulation
"
" INPUTS <=B(I/O)=> TRACE TERMS
" 76543210 9876543210
"
00000000 ..LLLLLLH. ;
00000001 ..HLLHHH. ;
00000010 ..LLHLLH. ;
00000011 ..LLLLHLL. ;
00000100 ..HLLHLL. ;
00000101 ..LHLLHLL. ;
00000110 ..LHLLLLL. ;
00000111 ..LLLLHHH. ;
00001000 ..LLLLLLL. ;
00001001 ..LLLLHLL. ;
00001010 ..LHLLHLL. ;
00001011 ..HLLHLLL. ;
00001100 ..LHLLHLL. ;
00001101 ..HLLHLL. ;
00001110 ..LHLLHLL. ;
00001111 ..LHLLHLL. ;
10001111 ..LHLLHLL. ;
10000000 ..LHLLHLL. ;
"
" X----- I/O CONTROL LINES
"          IIBBBBBBBI DESIGNATED I/O USAGE
"          IIBBBBBBBI ACTUAL I/O USAGE
"
" PIN LIST...
" 08 07 06 05 04 03 02 01 19 18 17 16 15 14 13 12 11 09 ;

```

Figure 4

```

***** P I N   L I S T *****
      LABEL  ** FNC **PIN  ----- PIN** FNC ** LABEL
W      ** I  ** 1-;      !-20 ** +5V **VCC
X      ** I  ** 2-;      !-19 ** B  **N/C
Y      ** I  ** 3-;      !-18 ** B  **N/C
Z      ** I  ** 4-;      8  !-17 ** B  **/SEG_A
N/C    ** I  ** 5-;      2  !-16 ** B  **/SEG_B
N/C    ** I  ** 6-;      5  !-15 ** B  **/SEG_C
N/C    ** I  ** 7-;      1  !-14 ** /B  **/SEG_D
/OE    ** I  ** 8-;      5  !-13 ** /B  **/SEG_E
N/C    ** B  ** 9-;      3  !-12 ** /B  **/SEG_F
GND    ** 0V ** 10-;     !-11 ** /B  **/SEG_G

```

Figure 5. Pin List of Binary-to-7 Segment Decoder Generated by AMAZE

## BCD-To-7 Segment Decoder

Using the same principle as in the previous example, a BCD input may be converted to a 7 segment display. If the input will always be within the range of 0000B to 1001B, the design will take ten AND terms to implement the decoding function. But if the display of an error message is desired when input exceeds 1001B, the design shown in Figures 5 and 6 and Table 5, may be used. Alternatively, the error message "E" will be displayed if the input does not equal anything between 0000B and 1001B inclusively. The circuit used to detect that none of the ten AND terms being true is shown in Figure 7 where if the input is outside of the range of 0000B to 1001B, none of the terms ZER to NIN will be active, which in turn causes the output of the NOR term to be High. The High output then causes the "E" term to be active and thus an output "E" is displayed. This scheme takes two propagation delays before "E" is displayed but only one delay for "0" to "9" to be displayed. The circuit shown in Figure 7 is implemented as shown in Table 4, column B(O)<sub>0</sub> of terms 0 to 9, and term #11. The output B(O)<sub>0</sub> becomes High when terms 0 to 9 are inactive, (T<sub>0</sub> + T<sub>1</sub> + T<sub>2</sub> + T<sub>3</sub> + T<sub>4</sub> + T<sub>5</sub> + T<sub>6</sub> + T<sub>7</sub> + T<sub>8</sub> + T<sub>9</sub>) = 0 where T<sub>0</sub> is term #0, T<sub>1</sub> is term #1, T<sub>2</sub> is . . . , etc. B(O)<sub>0</sub> is then fed back to the input of term #11 which, when active, causes outputs B and C to be High, segments B and C to turn off and the other segments to turn on. Term #10 is left blank to separate the main decoding function and the feedback function for the sake of clarity of this demonstration. A similar feature (the COMPLEMENT ARRAY) may be found in PLS155/157/159 where the feedback path is buried inside the chip without having to use up one I/O pin. Notice that this feature greatly reduces the number of AND terms needed. But for device architectures which do not allow common AND terms, this logic minimization will not be possible. Figure 8 and Table 6 implement design with AMAZE. The circuit is then simulated as shown in Figure 9.

# 4-Bit Binary-To-7 Segment Decoder

AN10

```

N@DEVICE TYPE
82S153
@DRAWING
***** BCD-TO-7 SEGMENT DECODER
@REVISION
***** REV. -
@DATE
***** OCT 1, 1984
@SYMBOL
***** FILE ID: BCD-7153
@COMPANY
***** SIGNETICS
@NAME
***** DAVID K. WONG
@DESCRIPTION
*****
* This circuit converts a 4-bit BCD code into a 7-segment display. *
* The display is a common anode 7-segment LED. *
* The output of the 82S153 goes LOW for each segment that is ON. *
*****

```

TRUTH TABLE

	Z	Y	X	W	a	b	c	d	e	f	g		
f                b	0	0	0	0	0	0	0	0	0	0	0	1	
	0	0	0	1	1	0	0	1	1	1	1	1	
	0	0	1	0	0	0	1	0	0	1	0		
e                c	0	0	1	1	0	0	0	0	1	1	0		
	0	1	0	0	1	0	0	1	1	0	0		
	0	1	0	1	0	1	0	0	1	0	0		
	0	1	1	0	0	1	0	0	0	0	0		
	0	1	1	1	0	0	0	1	1	1	1		
	1	0	0	0	0	0	0	0	0	0	0		
	1	0	0	1	0	0	0	0	1	0	0		
	1	0	1	0	1	0	0	1	1	1	1	Display E (error)	
	1	0	1	1	1	0	0	1	1	1	1	"	
	1	1	0	0	1	0	0	1	1	1	1	"	
	1	1	0	1	1	0	0	1	1	1	1	"	
	1	1	1	0	1	0	0	1	1	1	1	"	
	1	1	1	1	1	0	0	1	1	1	1	"	

```

@COMMON PRODUCT TERM
ZER = /z * /y * /x * /w ;
ONE = /z * /y * /x * w ;
TWO = /z * /y * x * /w ;
THR = /z * /y * x * w ;
FOU = /z * y * /x * /w ;
FIV = /z * y * /x * w ;
SIX = /z * y * x * /w ;
SEV = /z * y * x * w ;
EIG = z * /y * /x * /w ;
NIN = z * /y * /x * w ;
AAA = z * /y * x * /w ;
BBB = z * /y * x * w ;
CCC = z * y * /x * /w ;
DDD = z * y * /x * w ;
EEE = z * y * x * /w ;
FFF = z * y * x * w ;

```

Figure 6. Boolean Equations for BCD-to-7 Segment Decoder for AMAZE

TB010715



# 4-Bit Binary-To-7 Segment Decoder

AN10

```

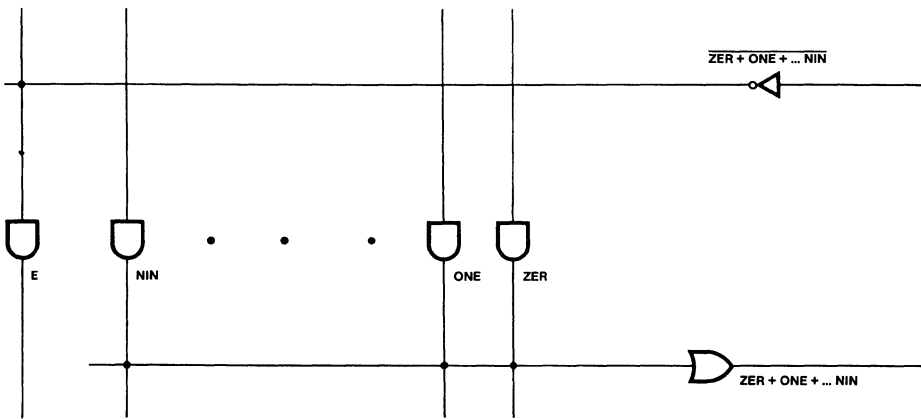
@LOGIC EQUATION
/SEG_A = ONE + FOU + AAA
/SEG_B = FIV + SIX
/SEG_C = TWO
/SEG_D = /( ZER + TWO + THR
/SEG_E = /( ZER + TWO + SIX
/SEG_F = /( ZER + FOU + FIV
/SEG_G = /( TWO + THR + FOU

@I/O DIRECTION 150/1, 152/3,
"
*****
*           OUTPUTS ARE ENA
*           THEREFORE, D1..
*****
"
D1 = OE ;
D2 = OE ;
D3 = OE ;
D4 = OE ;
D5 = OE ;
D6 = OE ;
D7 = OE ;

"
*****
*                               END
*****
"
    
```

TB01081S

Figure 6 (Continued)



LD01160S

Figure 7. Complement Array — "None of the Above" Detection Circuit

# 4-Bit Binary-To-7 Segment Decoder

AN10

Table 5. H/L Table for BCD-to-7 Segment Decoder Generated by AMAZE

```

Cust/Project - ***** DAVID K. WONG
Date         - ***** OCT 1, 1984
Rev/I. D.    - ***** REV. -

82S153                ! POLARITY !
-----
T !                    !H:H:H:H:L:L:L:L:H!
E !-----
R !           I           ! B(i)           ! B(o)           !
M !-----
---!7_6_5_4_3_2_1_0!9_8_7_6_5_4_3_2_1_0!9_8_7_6_5_4_3_2_1_0!
0!- - - ,L L L H!- - - , - - - !A A, A . . . . A A!
1!- - - ,L H L L!- - - , - - - !A A, A . . . . A A A!
2!- - - ,H L H L!- - - , - - - !A A, A . . . . A A!
3!- - - ,H L H H!- - - , - - - !A A, A . . . . A A!
4!- - - ,H H L L!- - - , - - - !A A, A . . . . A A!
5!- - - ,H H L H!- - - , - - - !A A, A . . . . A A!
6!- - - ,H H H L!- - - , - - - !A A, A . . . . A A!
7!- - - ,H H H H!- - - , - - - !A A, A . . . . A A!
8!- - - ,L H L H!- - - , - - - !A A, . A, A, A A A!
9!- - - ,L H H L!- - - , - - - !A A, . A, A, A A A!
10!- - - ,L L H L!- - - , - - - !A A, . A, A, A A A!
11!- - - ,L L L L!- - - , - - - !A A, . . A, A A A!
12!- - - ,L L H H!- - - , - - - !A A, . . A, . A A!
13!- - - ,H L L L!- - - , - - - !A A, . . A, A A A!
14!- - - ,H L L H!- - - , - - - !A A, . . A, . A A A!
15!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0 0 0 0 0!A A, A A A, A A A!
16!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
17!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
18!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
19!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
20!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
21!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
22!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
23!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
24!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
25!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
26!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
27!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
28!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
29!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
30!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
31!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!A A, A A A, A A A!
D9!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!
D8!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!
D7!L - - - - -!- - - - -!- - - - -!
D6!L - - - - -!- - - - -!- - - - -!
D5!L - - - - -!- - - - -!- - - - -!
D4!L - - - - -!- - - - -!- - - - -!
D3!L - - - - -!- - - - -!- - - - -!
D2!L - - - - -!- - - - -!- - - - -!
D1!L - - - - -!- - - - -!- - - - -!
D0!0 0 0 0,0 0 0!0 0 0 0,0 0 0 0,0 0 0 0 0!

/ N N N Z Y X W N / / / / / N N N / / / / / N
O / / / / / S S S S S S / / / S S S S S S /
E C C C C C E E E E E E C C C E E E E E E C

G G G G G G G G G G G G G G G G G G G G G G
A B C D E F G A B C D E F G
    
```

TB010905

# 4-Bit Binary-To-7 Segment Decoder

AN10

```

@DEVICE TYPE
***** 82S153
@DRAWING
***** BINARY-TO-7 SEGMENT DECODER
@REVISION
***** REV. -
@DATE
***** OCT 1, 1984
@SYMBOL
***** FILE ID: BCD77153
@COMPANY
***** SIGNETICS
@NAME
***** DAVID K. WONG
@DESCRIPTION
*****
* This circuit converts a 4-bit BCD code into a 7-segment display. *
* The display is a common anode 7-segment LED. *
* The output of the 82S153 goes LOW for each segment that is ON. *
*****

              TRUTH TABLE
          a      Z Y X W      a b c d e f g
-----
f |      | b      0 0 0 0      0 0 0 0 0 0 1
 |      | |      0 0 0 1      1 0 0 1 1 1 1
 |      | |      0 0 1 0      0 0 1 0 0 1 0
-----
e |      | c      0 0 1 1      0 0 0 0 1 1 0
 |      | |      0 1 0 0      1 0 0 1 1 0 0
 |      | |      0 1 0 1      0 1 0 0 1 0 0
-----
          d      0 1 1 0      0 1 0 0 0 0 0
          0 1 1 1      0 0 0 1 1 1 1
          1 0 0 0      0 0 0 0 0 0 0
          1 0 0 1      0 0 0 0 1 0 0

          Over Range  1 0 1 0      0 1 1 0 0 0 0  Display E (error)
          "           1 0 1 1      0 1 1 0 0 0 0  "
          "           1 1 0 0      0 1 1 0 0 0 0  "
          "           1 1 0 1      0 1 1 0 0 0 0  "
          "           1 1 1 0      0 1 1 0 0 0 0  "
          "           1 1 1 1      0 1 1 0 0 0 0  "

@COMMON PRODUCT TERM
ZER = /z * /y * /x * /w ;
ONE = /z * /y * /x * w ;
TWO = /z * /y * x * /w ;
THR = /z * /y * x * w ;
FOU = /z * y * /x * /w ;
FIV = /z * y * /x * w ;
SIX = /z * y * x * /w ;
SEV = /z * y * x * w ;
EIG = z * /y * /x * /w ;
NIN = z * /y * /x * w ;
    
```

T8011015

Figure 8. Boolean Equation for BCD-to-7 Segment Decoder

## 4-Bit Binary-To-7 Segment Decoder

AN10

```

@LOGIC EQUATION
"
*****
* When input is greater than 9, OVR ( Over Range ) will go HIGH, WHICH *
* will be fed-back to the AND array to control the segments. *
* Here the OVR pin and the feedback loop is used as COMPLEMENT ARRAY. *
* The COMPLEMENT ARRAY saves 5 P-terms but loses one I/O pin. *
*****
"

OVR = /( ZER + ONE + TWO + THR + FOU + FIV + SIX + SEV + EIG + NIN ) ;
/SEG_A = ONE + FOU ;
/SEG_B = FIV + SIX + OVR ;
/SEG_C = TWO + OVR ;
/SEG_D = ONE + FOU + SEV ;
/SEG_E = /( ZER + TWO + SIX + EIG + OVR ) ;
/SEG_F = ONE + TWO + THR + SEV ;
/SEG_G = ZER + ONE + SEV ;

@I/O DIRECTION 150/1, 152/3, 154-9
"
*****
* OUTPUTS ARE ENABLED WHEN /OE GOES LOW. *
* THEREFORE, D1..D7 = /(OE) = OE ; *
*****
"
D1 = OE ;
D2 = OE ;
D3 = OE ;
D4 = OE ;
D5 = OE ;
D6 = OE ;
D7 = OE ;

"
*****
* END OF LOGIC EQUATIONS *
*****
"

```

TB01111S

Figure 8 (Continued)



# 4-Bit Binary-To-7 Segment Decoder

AN10

```

B2S153  A:bcd77153.STD
" yhgfikuhyfouiy
"
"  INPUTS  <=B(I/O)=>  TRACE TERMS
"  76543210  9876543210
"
00000000 ..LLLLLLLH ;
00001111 ..LHLLLLLH ;
10001111 .....H ;
00000000 ..LLLLLLLH ;
01000001 ..HLLHHHLL ;
01000010 ..LHLLHLL ;
01000011 ..LLLLHHLL ;
01000100 ..HLLHHLL ;
01000101 ..LHLLHLL ;
01000110 ..LHLLLLLL ;
01000111 ..LHLLHHLL ;
01001000 ..LLLLLLLH ;
01001001 ..LHLLHLL ;
01001010 ..LHLLHLL ;
01001011 ..LHLLHLL ;
01001100 ..LHLLHLL ;
01001101 ..LHLLHLL ;
01001110 ..LHLLHLL ;
01001111 ..LHLLHLL ;
11001111 .....H ;
10000000 .....L ;
"
" X----- I/O CONTROL LINES
"  IIBBBBBBBO DESIGNATED I/O USAGE
"  IIBBBBBBBO ACTUAL I/O USAGE
"
" PIN LIST...
" 08 07 06 05 04 03 02 01 19 18 17 16 15 14 13 12 11 09 ;

```

T8011305

**Figure 9. Simulation Results of H/L Table**

## BCD-To-7 Segment Decoder with Output Latches

Output latches may be constructed by using the bidirectional I/Os of PLS153/153A as shown in Figure 10. When /LE (latch enable) is High, the output equals the input. But when /LE is Low, the output is latched. Changing the input will not effect the output. Segments a and e are used to illustrate the decoding and latch circuit as shown in Figures 11 and 12 which are expressed in H/L format as shown in Table 8. The complete design of the decoder is shown in Figures 13 and 14 and Table 7. With the output latches, the circuit cannot be tri-stated since the tri-state condition will interrupt the feedback path. An alternative approach is shown in Figure 15 where the display is a common cathode, the segment drivers are always on and the duty cycling is implemented with a digit driver which pulls the common cathode of the display to ground as the input "Duty Cycle" goes High. A common practice is to drive the segments with 10 time the desired DC current and drive the digit with a 10% duty cycle pulse. The H/L implementation is as shown in Tables 9 and 10. The "Duty Cycle" control input is generated externally.



# 4-Bit Binary-To-7 Segment Decoder

AN10

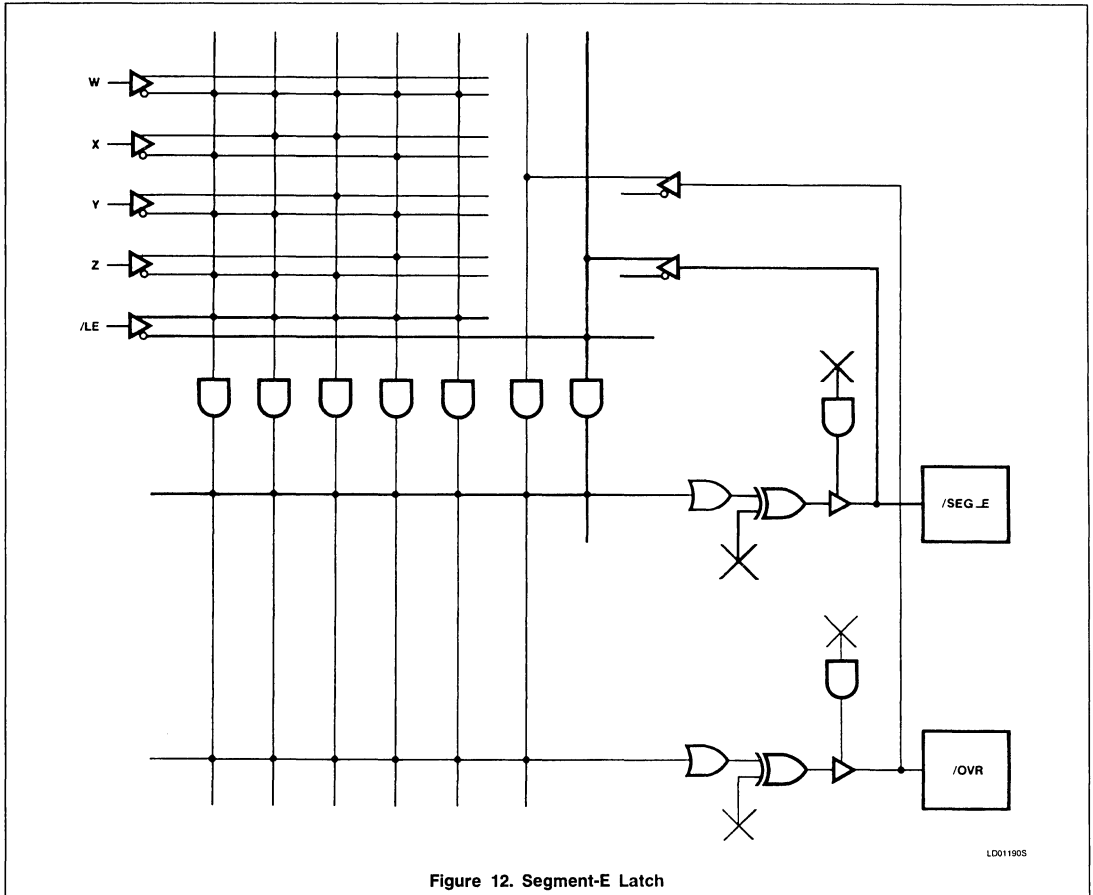


Figure 12. Segment-E Latch

```

***** P I N L I S T *****

```

LABEL	** FNC	**PIN	-----	PIN**	FNC **	LABEL
W	** I	** 1-		!-20	** +5V	**VCC
X	** I	** 2-		!-19	** B	**N/C
Y	** I	** 3-		!-18	** B	**N/C
Z	** I	** 4-	8	!-17	** 0	**/SEG_A
N/C	** I	** 5-	2	!-16	** 0	**/SEG_B
N/C	** I	** 6-	5	!-15	** 0	**/SEG_C
/LE	** I	** 7-	1	!-14	** 0	**/SEG_D
N/C	** I	** 8-	5	!-13	** /0	**/SEG_E
OVR	** /0	** 9-	3	!-12	** 0	**/SEG_F
GND	** OV	** 10-		!-11	** 0	**/SEG_G

TB01140S

Figure 13. Pin List of BCD-to-7 Segment Decoder with Latches



# 4-Bit Binary-To-7 Segment Decoder

AN10

```

@DEVICE TYPE
@2S153
@DRAWING
***** BCD-TO-7 SEGMENT DECODER
@REVISION
***** REV. -
@DATE
***** OCT 1, 1984
@SYMBOL
***** FILE ID: BCD7L153
@COMPANY
***** SIGNETICS
@NAME
***** DAVID K. WONG
@DESCRIPTION
*****
* This circuit converts a 4-bit BCD code into a 7-segment display. *
* The display is a common anode 7-segment LED. *
* The output of the 82S153 goes LOW for each segment that is ON. *
* The outputs are latched when /LE goes LOW. *
*****
                                TRUTH TABLE
                                a b c d e f g
-----
a |-----| b      Z Y X W      a b c d e f g
f |-----| g      0 0 0 0      0 0 0 0 0 0 1
 |-----|      0 0 0 1      1 0 0 1 1 1 1
 |-----|      0 0 1 0      0 0 1 0 0 1 0
e |-----| c      0 0 1 1      0 0 0 0 1 1 0
 |-----|      0 1 0 0      1 0 0 1 1 0 0
 |-----|      0 1 0 1      0 1 0 0 1 0 0
 |-----|      0 1 1 0      0 1 0 0 0 0 0
 |-----|      0 1 1 1      0 0 0 1 1 1 1
 |-----|      1 0 0 0      0 0 0 0 0 0 0
 |-----|      1 0 0 1      0 0 0 0 1 0 0

Over Range  1 0 1 0      0 1 1 0 0 0 0 Display E (error)
"           1 0 1 1      0 1 1 0 0 0 0 "
"           1 1 0 0      0 1 1 0 0 0 0 "
"           1 1 0 1      0 1 1 0 0 0 0 "
"           1 1 1 0      0 1 1 0 0 0 0 "
"           1 1 1 1      0 1 1 0 0 0 0 "

@COMMON PRODUCT TERM
ZER = /z * /y * /x * /w * /LE ;
ONE = /z * /y * /x * w * /LE ;
TWO = /z * /y * x * /w * /LE ;
THR = /z * /y * x * w * /LE ;
FOU = /z * y * /x * /w * /LE ;
FIV = /z * y * /x * w * /LE ;
SIX = /z * y * x * /w * /LE ;
SEV = /z * y * x * w * /LE ;
EIG = z * /y * /x * /w * /LE ;
NIN = z * /y * /x * w * /LE ;
"
*****
* Feedback circuits to form D-latches. *
*****

```

TB011505

Figure 14. Boolean Equation of BCD-to-7 Segment Decoder with Latches

## 4-Bit Binary-To-7 Segment Decoder

AN10

```

"
AL = LE * /SEG_A ;
BL = LE * /SEG_B ;
CL = LE * /SEG_C ;
DL = LE * /SEG_D ;
EL = LE * SEG_E ; "Note that in LOGIC EQUATION definition, SEG_E is
                    inverted. Therefore, the feedback for E has to
                    be inverted too."
FL = LE * /SEG_F ;
GL = LE * /SEG_G ;

@LOGIC EQUATION
"
*****
* When input is greater than 9, OVR ( Over Range ) will go HIGH, WHICH *
* will be fed-back to the AND array to control the segments. *
* Here the OVR pin and the feedback loop is used as COMPLEMENT ARRAY. *
* The COMPLEMENT ARRAY saves 5 P-terms but uses up one I/O pin. *
*****
"

OVR = /( ZER + ONE + TWO + THR + FOU + FIV + SIX + SEV + EIG + NIN + LE ) ;
/SEG_A = ONE + FOU + AL ;
/SEG_B = FIV + SIX + OVR + BL ;
/SEG_C = TWO + OVR + CL ;
/SEG_D = ONE + FOU + SEV + DL ;
/SEG_E = /( ZER + TWO + SIX + EIG + OVR + EL ) ;
/SEG_F = ONE + TWO + THR + SEV + FL ;
/SEG_G = ZER + ONE + SEV + GL ;

@I/O DIRECTION
"
*****
*                               END OF LOGIC EQUATIONS
*****
"

```

TB01160S

Figure 14 (Continued)



# 4-Bit Binary-To-7 Segment Decoder

AN10

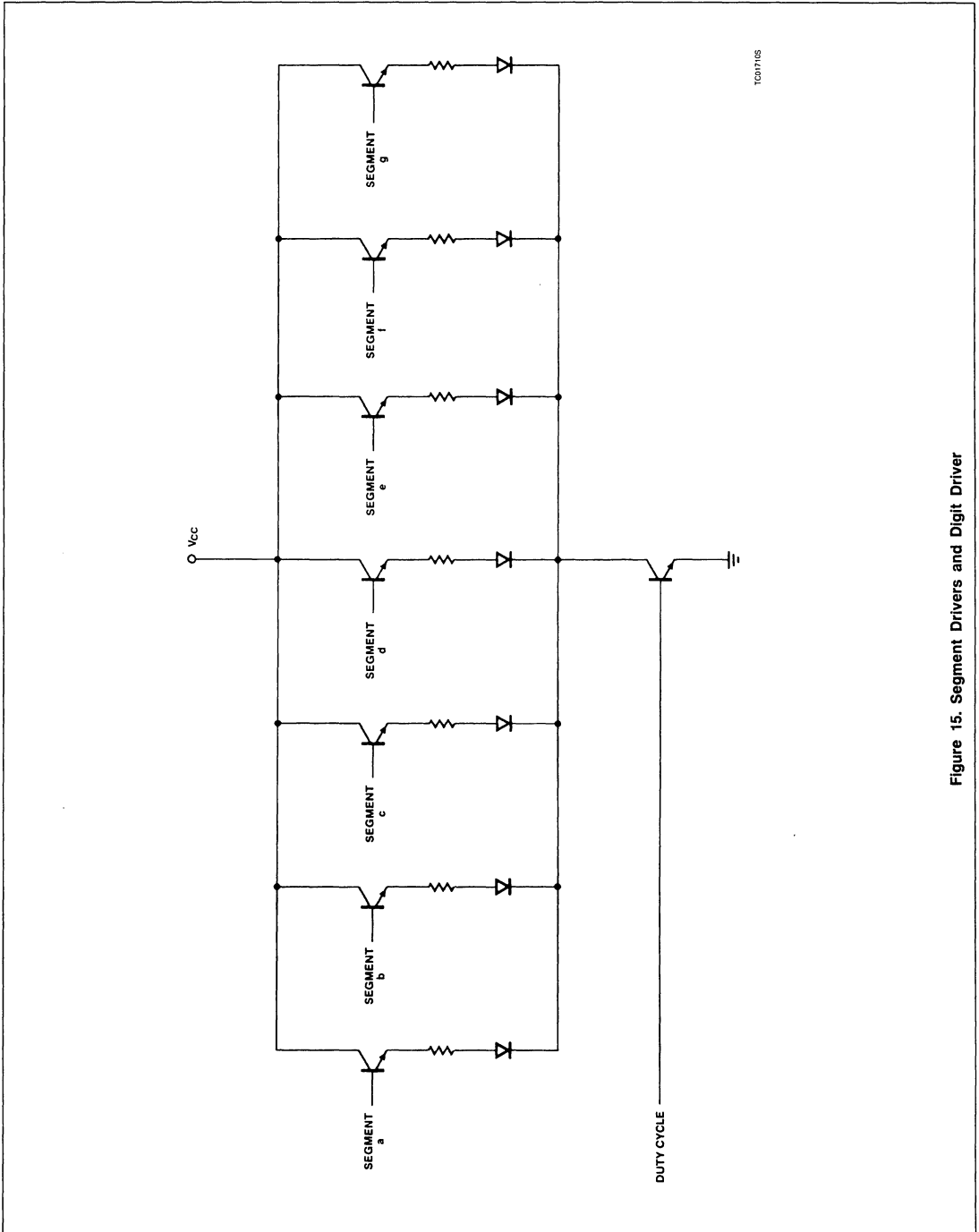


Figure 15. Segment Drivers and Digit Driver







# AN11 PLD Programmable Retriggerable One-Shot

## Application Note

### Application Specific Products

Author: David Wong

### FEATURES

- Programmable pulse-width/delay
- Maximum 256 clock cycles
- Asynchronous TRIGGER input
- Active-High and Active-Low outputs
- Asynchronous RESET
- 20-pin package

### THEORY OF OPERATION

The one-shot consists of an FPLS PLS159 and an external clock which may be part of the system in which this one-shot is to work. As shown in Figure 1 and Table 1 the FPLS is configured to have a latch and an eight-bit binary up counter which is presettable by input data to any number less than 256. Since the input data is inverted before it is loaded into the registers, counting from the comple-

ments of the input to FF will give the correct number of counts as counting from the input down to 00.

Pulse-width/delay inputs may be the outputs of another device or switches. When /RESET goes Low, flip-flops are set to all 1's (terms PB and PA). At the rising edge of the next clock, data is latched into the registers (terms LB and LA). When /TRIG goes Low, it is latched into the input latch formed by term # 0, 1, 2 and 13. The output  $O_1$  of the latch goes High and  $O_2$  goes Low which enables the 8-bit counting cycle. The  $O_1$  and / $O_1$  will maintain their output levels until the end of the counting cycle at which time the counter reaches the count FF, resets the latch by term # 13, and sets  $O_2$  High. At the rising edge of the next clock, terms LA and LB cause data to be loaded again into the registers, and the device is ready for another /TRIG input. The output wave-forms are illustrated in Figure 2.

If the /TRIG pulse-width is longer than the desired pulse-width of the one-shot, the device will react as mentioned above, and at the end of the count cycle new data will be loaded, another count cycle begins while the outputs remain set by the /TRIG input without changing throughout the change-over of one count cycle to another.  $O_{1a}$ , on the other hand, will go Low for one clock period at the change-over. As long as the /TRIG is Low,  $O_{1a}$  will continue to pulse Low for one clock period at the change-over of one count cycle to another. The output  $O_2$  will pulse High for one clock cycle at the change-over. Figure 2 illustrates output wave-forms for both cases. The output wave-forms are as illustrated in Figure 2.

The one-shot is implemented by programming the PLS159 as shown in Table 1. The logic representation of the program is shown in Figure 3.

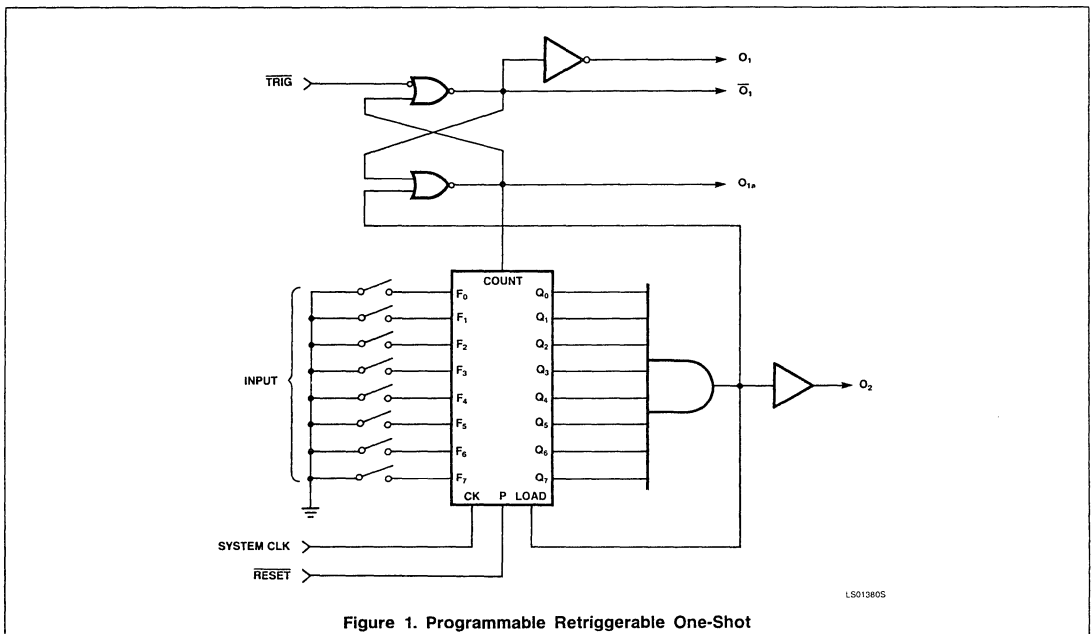


Figure 1. Programmable Retriggerable One-Shot





# PLD Programmable Retriggerable One-Shot

AN11

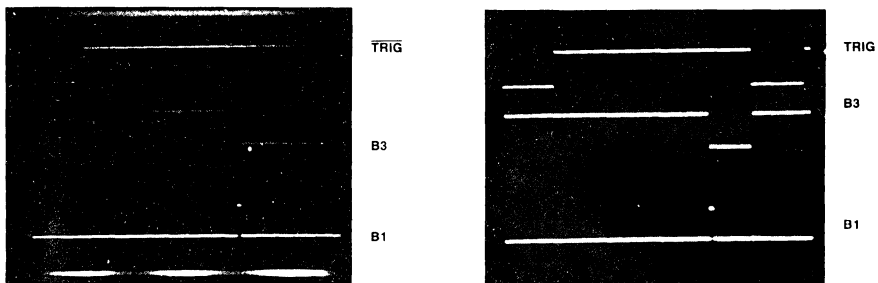
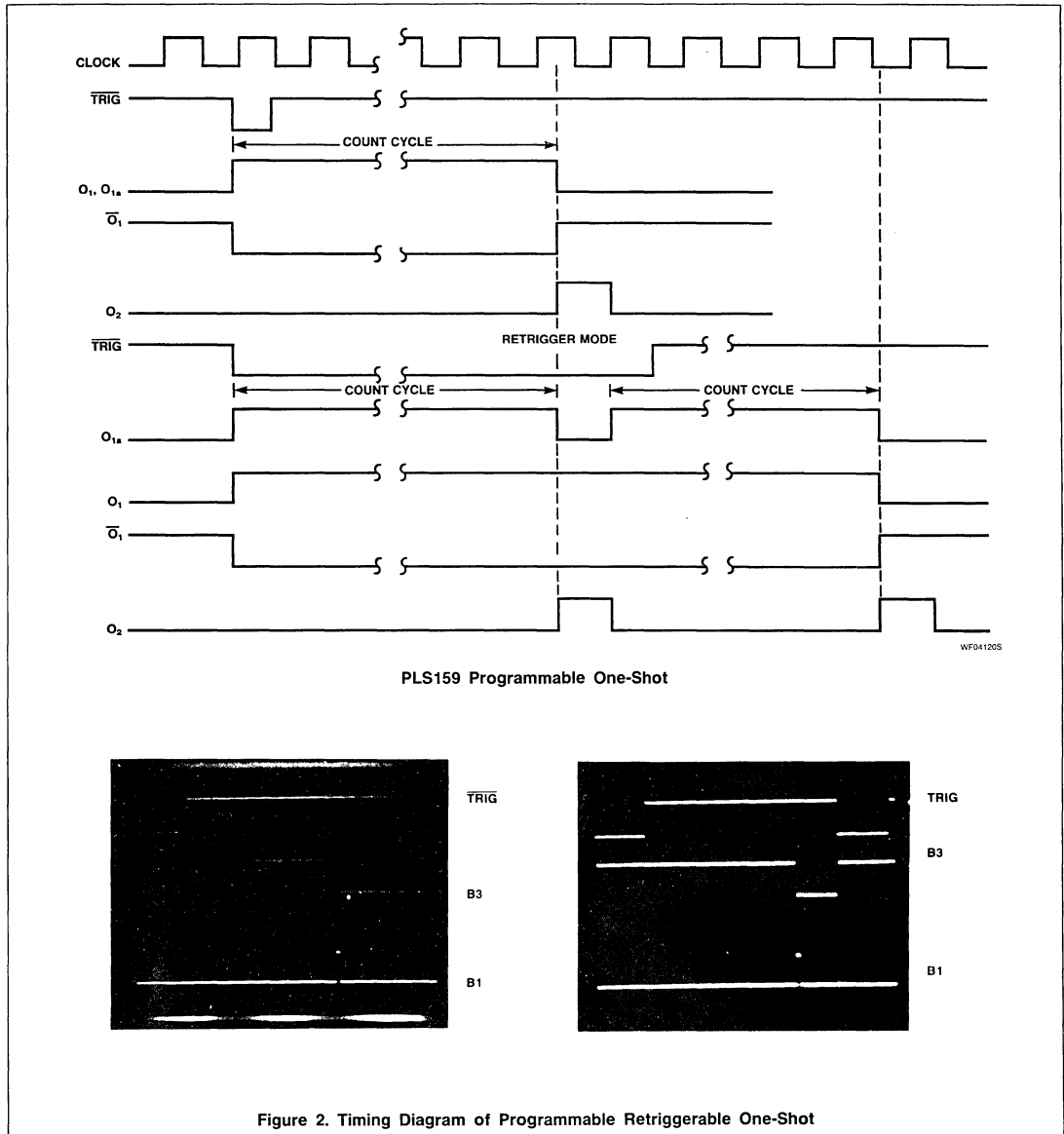


Figure 2. Timing Diagram of Programmable Retriggerable One-Shot



## AN13 Oscillator With PLS159

Application Note

### Application Specific Products

#### INTRODUCTION

The Field-Programmable Logic Sequencer PLS159 may be a self-contained system except that it requires a system clock which is generally provided by an external source. Using a simple R-C network, two bidirectional I/O pins, one can make a simple oscillator which can provide a clock frequency up to 7MHz (typical) with a pulse width of about 75ns. The frequency of oscillation is set by adjusting the RC network, or by adjusting a reference voltage, V. The circuit is shown in Figure 1. This circuit may be used to clock the flip flops on the same chip, or provide a clock for a bigger system. While this circuit uses only two AND-terms and one control term, the rest of the chip may be used for other circuits.

Initially, the capacitor has zero charge and thus is at zero volt. Output is also at a Low, which disables the tri-state buffer. As the capacitor is being charged up, its voltage increases. At about 1.6V, the non-inverting input buffer begins to turn on. One propagation delay later, the output goes High, which enables the tri-state buffer after another propagation delay. Since the tri-state buffer is unconditionally programmed to a Low, it be-

gins to discharge the capacitor at a fast rate. As the input voltage to the non-inverting buffer drops below 1.6V, the buffer begins to change state. One propagation delay later, output goes Low, which disables the tri-state buffer after another propagation delay. The R-C network is ready to start all over again.

To implement this circuit, we first choose B<sub>1</sub> to input voltage from the RC network and B<sub>0</sub> to be the output pin. As shown in Table 1, we enable the output B(O)<sub>0</sub> by "dashing out" the AND-term D<sub>0</sub>, make the output non-inverting by programming POLARITY "H" and connect it to term-0 by entering an A in column B(O)<sub>0</sub> term-0. We then program an H in B(I)<sub>1</sub>, term-0 to connect the non-inverting input of B<sub>1</sub> to term-0. Since we don't need the rest of the inputs and outputs, we "dash out" all other input entries and "dot out" all unused outputs in term-0. To create a Low output on B(O)<sub>1</sub>, we may either have a Low input on the OR and have the output non-inverted, or have a High on the input of OR and have the output inverted to produce a Low. We will arbitrarily use the second method. Here we dash out all inputs and outputs in term-1 except B(O)<sub>1</sub> which is programmed an A. We then program the POLARITY of B(O)<sub>1</sub> "L" to be inverting.

Finally we program an H in B(I)<sub>0</sub> and term-D<sub>1</sub> and dash out all unused inputs so that when B(O)<sub>0</sub> becomes High, D<sub>1</sub> will enable the output buffer B(O)<sub>1</sub>. The program is further illustrated by Figure 2.

Since the High output pulsewidth is about two propagation delays of B<sub>1</sub> to B<sub>0</sub>, it is wide enough to drive the clock input of the PLS159. If a square wave is desired, one of the flip flops may be programmed to toggle, as shown in Table 1, term-4, in which case the output frequency of the square wave is half that of B(O)<sub>0</sub>.

The stability of the output frequency can be controlled by:

1. Making V a stable voltage source,
2. making the charging current of the RC network much greater than the input current of B(I)<sub>1</sub> (see Figure 4 for input current characteristics),
3. making the period of oscillation much greater than four times the internal propagation delay (typical t<sub>PD</sub> = 35ns).

Recommendations:

- a) Use capacitance less than 500pf.
- b) Choose R such that  $V/R >> I_{IL}$  (since  $I_{IL} = -100\mu A$ , worst case, over temperature range,  $V/R$  may be 1mA, for example).

The recommendations above put a limit to the range of frequency which the PLS159 may operate in exchange for stable operating frequency. One may extend its range by reducing C to zero (remove the capacitor) and thus operate the circuit at its maximum frequency, or increase the resistance to infinite (remove the resistor), and let the external capacitor be charged by the input current I<sub>IL</sub>, which gives a much lower frequency.

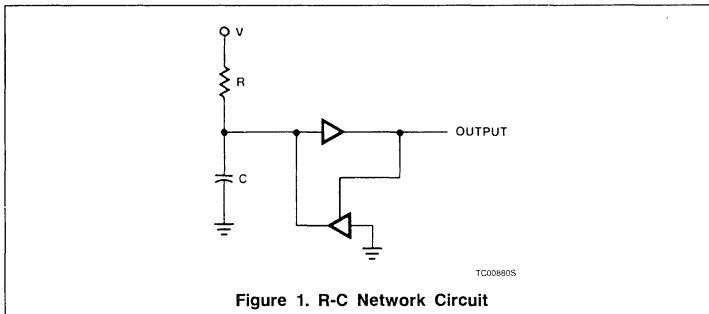


Figure 1. R-C Network Circuit

# Oscillator With PLS159

AN13

Table 1. PLS159 FPLS Program Table

CODE NO.		FF MODE										E <sub>B</sub>		E <sub>A</sub>		POLARITY		REMARKS											
T E R M	C	AND					REMARKS	(OR)					REMARKS																
		I	B(1)	Q(P)	Q(N)	B(O)																							
		3	2	1	0	3	2	1	0	7	6	5	4	3	2	1	0	3	2	1	0								
0	-	-	-	-	-	H	-	-	-	-	-	-	-	-	-	-	-	*	*	*	A	B <sub>0</sub> = B <sub>1</sub>							
1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	*	*	*	A	B <sub>0</sub> -L = LOW							
2																													
3																													
4	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	O	*	*	*	SQUARE WAVE							
5																						SEE COMMENT # 2							
6																													
7																													
8																													
9																													
10																													
11																													
12																													
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31																													
FC																													
PB																													
RB																													
LB																													
PA																													
RA																													
LA																													
D3																													
D2																													
D1																													
D0																													
PIN		5	4	3	2	9	8	7	6	19	18	17	16	15	14	13	12	19	18	17	16	15	14	13	12	9	8	7	6
REMARKS																													

PLS159

TB005105

**COMMENTS:**

- D<sub>1</sub> is controlled by B(1)<sub>0</sub>, which enables B(O)<sub>1</sub> when B(O)<sub>0</sub> outputs a High.
- Q(N)<sub>0</sub> is programmed as J-K flip-flop, and will toggle automatically at each rising-edge of the clock.

**NOTE:**

- In order for the flip-flop to work the clock out (B<sub>C</sub>) must be externally connected to pin 1.

# Oscillator With PLS159

# AN13

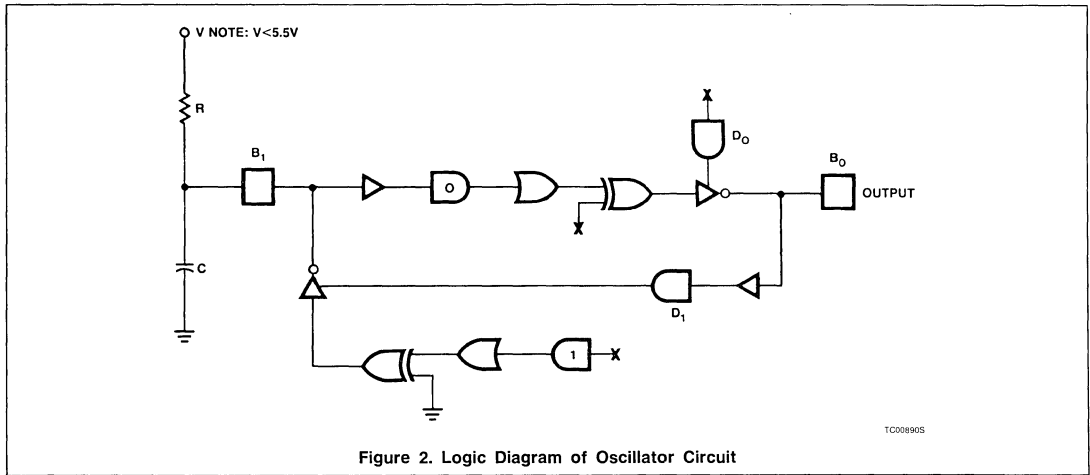
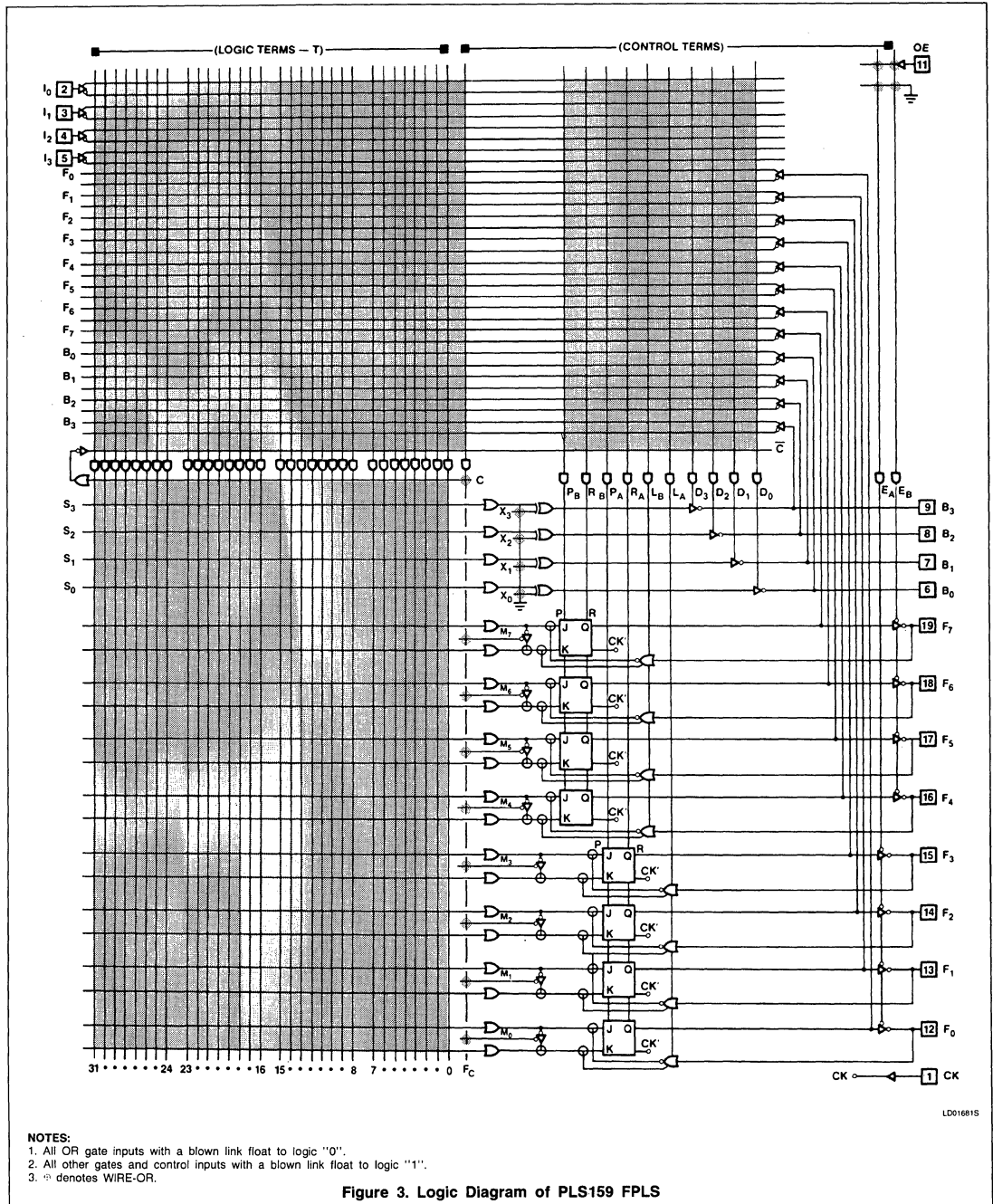


Figure 2. Logic Diagram of Oscillator Circuit

# Oscillator With PLS159

# AN13



# Oscillator With PLS159

AN13

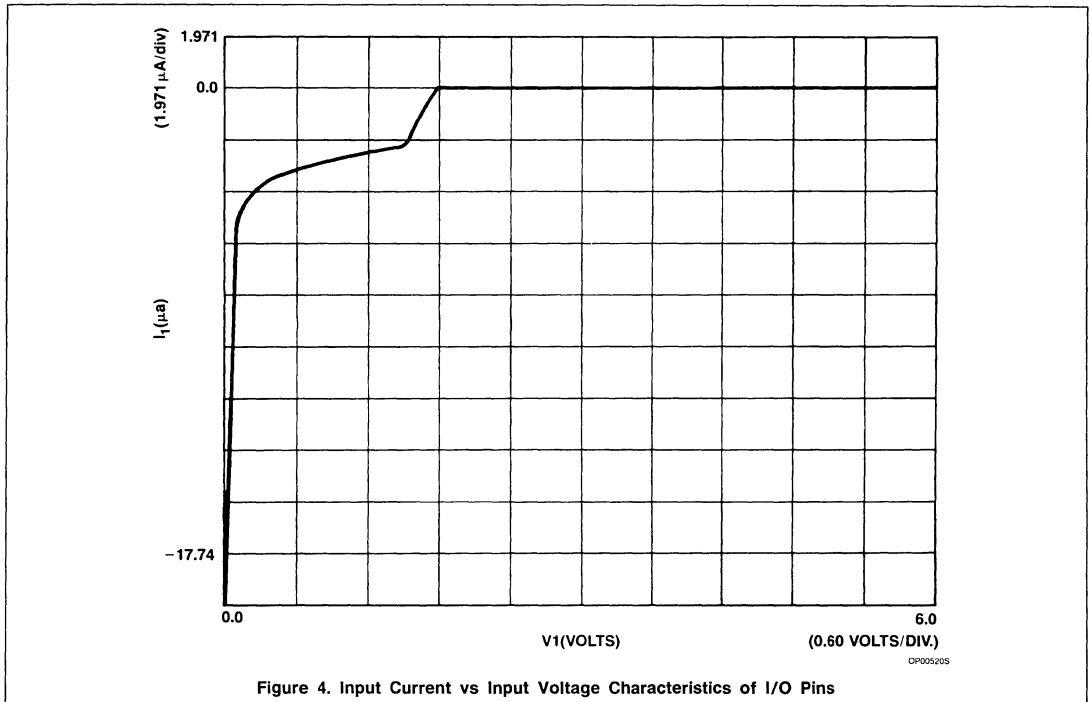


Figure 4. Input Current vs Input Voltage Characteristics of I/O Pins

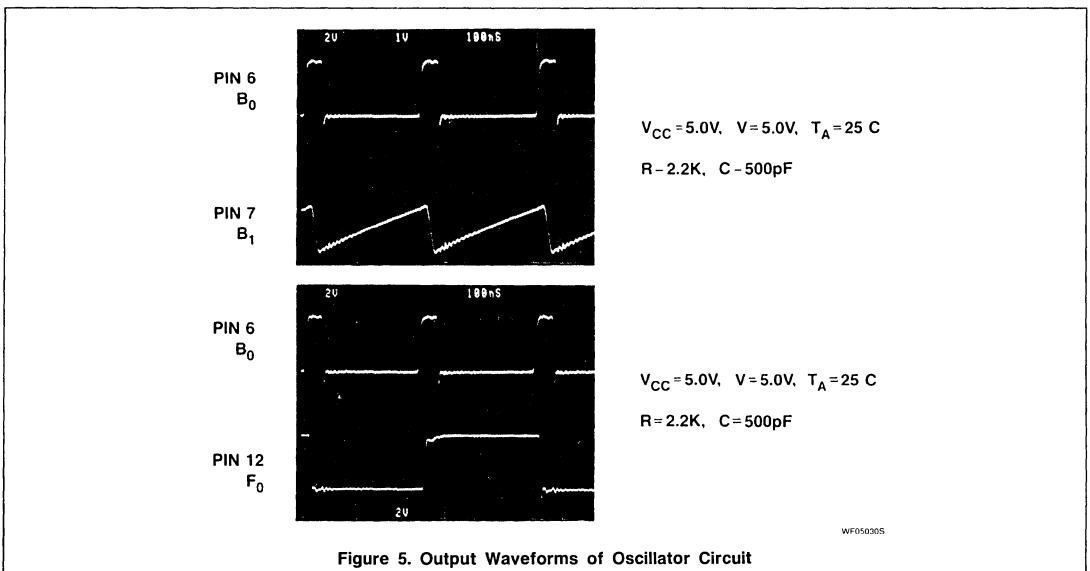


Figure 5. Output Waveforms of Oscillator Circuit



## AN14 Latches and Flip-Flops With PLS153

### Application Note

#### Application Specific Products

#### DESCRIPTION

Using the simple AND, OR and INVERT logic functions of the PLS153, memory functions such as latches and edge-triggered flip-flops may be implemented with a relatively small part of the chip and without external wiring. In this application note, we will discuss the implementation of two R-S latches, a D-latch, an edge-triggered R-S flip-flop, and an edge-triggered D flip-flop.

#### INTRODUCTION TO PLS153

To implement this function, let's first take a look at the PLS153 logic diagram and its programming table as shown in Appendices A and B. On the left side of the logic diagram (Appendix A) are eight dedicated inputs,  $I_0$  to  $I_7$ , each of which has a true and a complement output. Each output is connected to the inputs of 32 AND functions (we will call them AND-terms from now on), the outputs of which are, in turn, connected to the inputs of ten OR functions. The output of each OR function is connected to one input of an Exclusive-OR function, which is in turn connected to a non-inverting output buffer. The function of the XOR is to control the output polarity. The output, in its virgin state, is non-inverting, since one side of the XOR is

connected to ground by the fuse  $X_n$ , where  $n = 0, 1, 3...9$ . To have the output inverted, one needs only to blow fuse  $X_n$  open so that the  $X_n$  input is unconditionally High. The output buffers are all three-state buffers which may be enabled or disabled by their corresponding AND gates. The output buffers are disabled in their virgin state. All pins labeled "B" are bidirectional. Input buffers of the "B" pins are identical to those of the "I" pins.

The programming table shown in Appendix B emulates a truth table. All the inputs to the device are positioned on the left side, and all the outputs are on the right side. Each row in the table corresponds to an 18-input AND-term with up to ten outputs. On the left side, or the input side of the table, each column represents an input. The 18 columns represent input buffers  $I_0$  to  $I_7$ ,  $B_0$  to  $B_9$ . To distinguish between inputs and outputs of the bidirectional pin,  $B(I)$  is used for input and  $B(O)$  is used for outputs as shown in the programming table. On the right side of the table, each column represents an output circuit ( $B(O)_{0-9}$ ) which consists of an OR gate, an XOR, and a non-inverting three-state buffer. The output buffers are controlled by AND-terms  $D_0$  to  $D_9$ , the inputs of which may be connected to any number of the 18 inputs.

The polarity of the outputs is defined by the POLARITY entries which are on the upper right corner of the programming table.

To program the inputs to the AND-terms, an "H" will cause the fuse of the inverting input buffer to be blown, leaving the non-inverting buffer connected to the AND-term; an "L" will do the opposite. A "-" will cause both fuses to be blown, and therefore the programmed input is a "Don't care". A "0", the virgin state of the device, has both fuses intact, which causes the output of the AND-term to be unconditionally Low.

To program the outputs, a "." causes the fuse that connects the output of AND-term to the input of an OR to be blown and thus renders the output inactive. An "A" causes the fuse to remain intact and thus the output is active.

The output polarity of each output buffer may be programmed by entering an "H" or an "L" in the POLARITY section. An "L" causes the XOR to blow its grounding fuse and become inverted, whereas an "H" leaves the fuse intact and the output is non-inverted.

To AND several inputs, we put them in a row; to OR several inputs, we put them in different rows, as shown in illustrations in Appendix B.

# Latches and Flip-Flops With PLS153

AN14

## SIMPLE R-S LATCH

A simple R-S latch may be formed by cross-coupling two NAND functions together as shown in Figure 1.

As an illustration, let's assign the input R to I<sub>0</sub> of the PLS153, input S to I<sub>1</sub>, output Q to B<sub>0</sub>, and output  $\bar{Q}$  to B<sub>1</sub>. As shown in Table 1, to form the NAND gates we need to program the POLARITY Low on B(O)<sub>0</sub> and B(O)<sub>1</sub>. To unconditionally enable the output buffers, we "dash" out all inputs to D<sub>0</sub> and D<sub>1</sub>. As for the inputs, we put an "H" on I<sub>0</sub>, term-0 for the input R, non-inverted; another "H" on B(I)<sub>1</sub>, term-0 for the feedback from Q. In the same manner, we program I<sub>1</sub>, term-1 and B(O)<sub>0</sub> "H". The POLARITY, rows 0, 1, D<sub>0</sub> and D<sub>1</sub>, forms a "truth table" with which one can analyze his own or someone else's design. The program in Table 1 may be illustrated as shown in Figure 2.

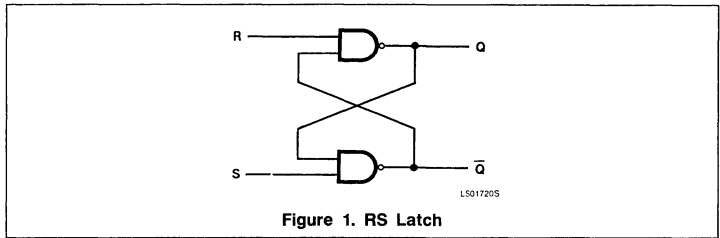


Figure 1. RS Latch

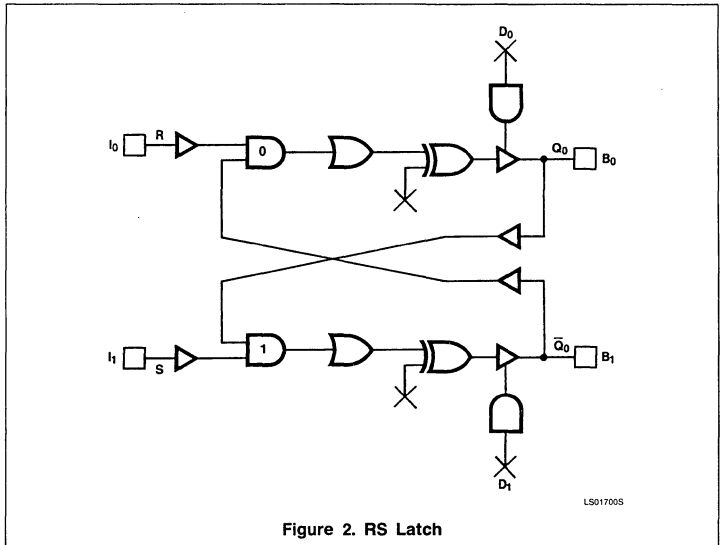


Figure 2. RS Latch



# Latches and Flip-Flops With PLS153

AN14

## ANOTHER SIMPLE R-S LATCH

Another way to implement a simple latch is shown in Figure 3, in which two NOR functions are cross-coupled to form a latch.

As with the previous example, we first define the input and output pins. For this example, we use  $I_2$  for the R input,  $I_3$  for the S input,  $B_2$  for the Q output, and  $B_3$  for the  $\bar{Q}$  output. We program  $B_2$  and  $B_3$  to have inverted outputs by programming POLARITY of  $B_2$  and  $B_3$  Low, as shown in Table 2. Terms 6 and 7 are ORed together by  $B(O)_2$ , rows 6 and 7. In the same manner  $B(O)_3$  ORs Terms 8 and 9. The programmed table of this design may be represented as shown in Figure 4.

Since each AND-term of the PLS153 can accommodate up to 18 inputs (true or inverting inputs of eight from  $I_0$  to  $I_7$  and ten from  $B_0$  to  $B_9$ ), and each OR circuit can be connected to up to thirty-two AND-terms, we can add additional features such as those shown in Figure 5.

The programming of this design is left to the reader as an exercise.

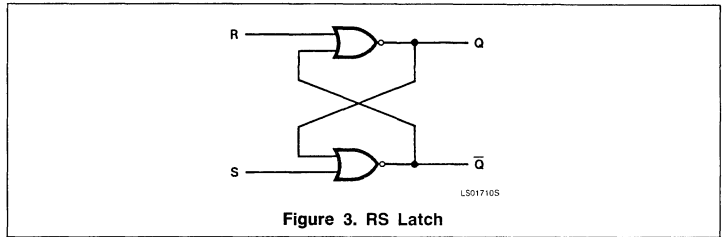


Figure 3. RS Latch

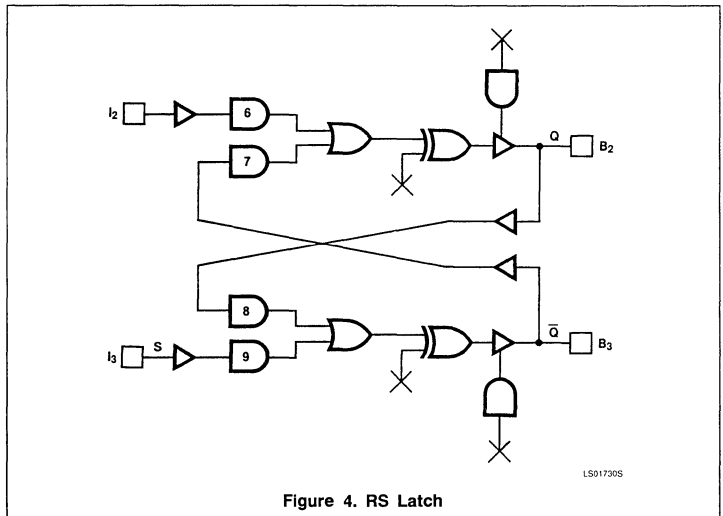


Figure 4. RS Latch

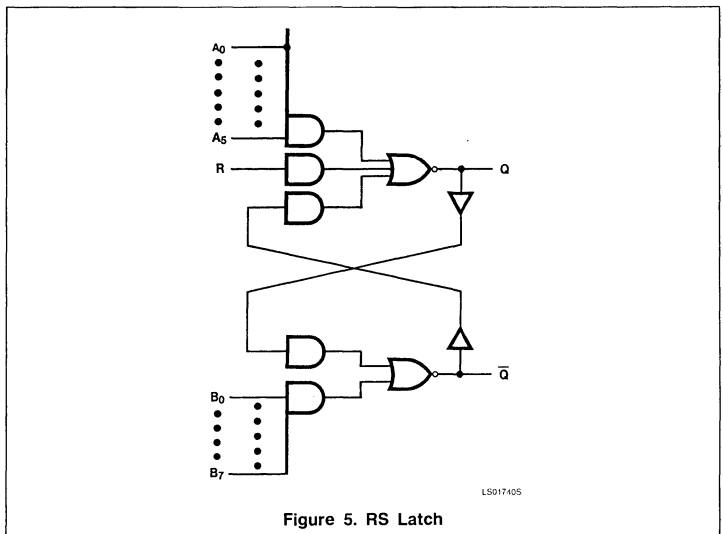


Figure 5. RS Latch



# Latches and Flip-Flops With PLS153

AN14

## D-LATCH

A simple D-latch can be constructed with an PLS153 as shown in Figure 6.

This circuit may be easily programmed into the PLS153 as shown in Table 3. The program may, in turn, be represented as shown in Figure 7.

This circuit may be expanded to have multiple D-latches using the same latch enable (LE).

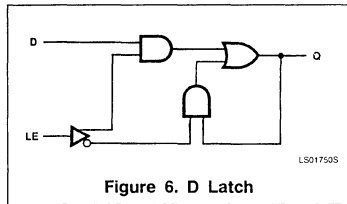


Figure 6. D Latch

## R-S FLIP-FLOP

Two R-S latches may be combined to form a master-slave flip-flop that is triggered at the rising-edge of the clock (or the falling-edge of the clock, if the designer so desires). Figure 8 shows a combination of two sets of cross-coupled NOR gates concatenated to form the flip-flop. The implementation of this circuit using PLS153 is as illustrated in Table 4 and Figure 9.

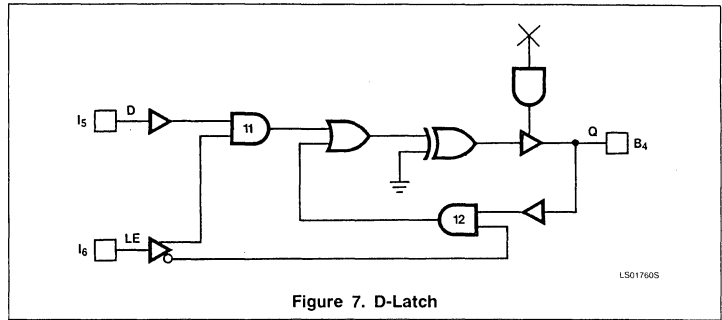


Figure 7. D-Latch

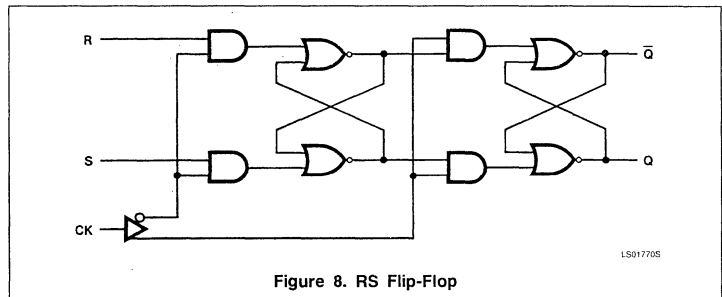


Figure 8. RS Flip-Flop

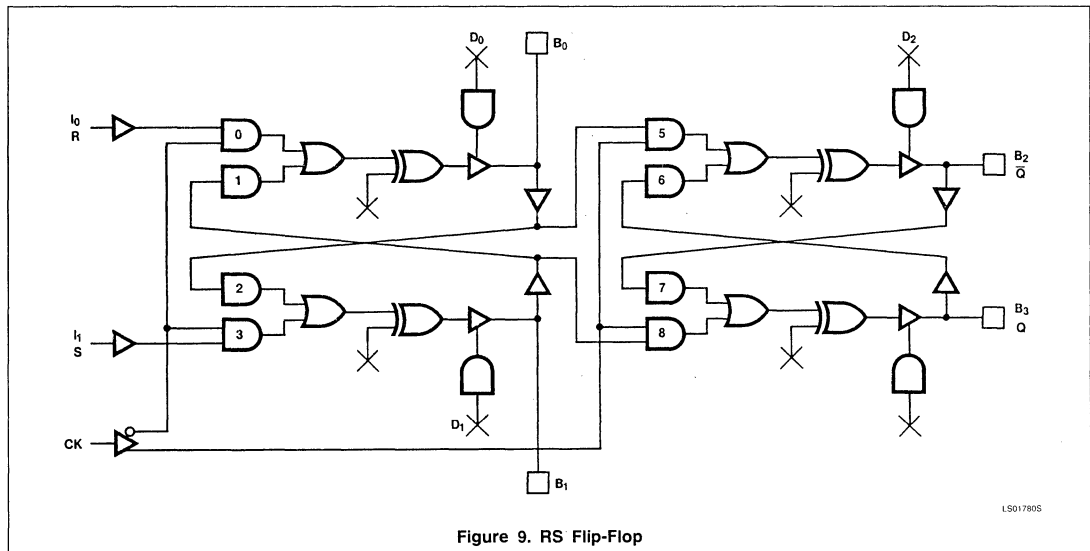


Figure 9. RS Flip-Flop

# Latches and Flip-Flops With PLS153

AN14

Table 3. PLS153/153A Programming Table

CODE NO.														POLARITY																
T E R M	AND													REMARKS	OR										REMARKS					
	I						B(I)								B(O)															
	7	6	5	4	3	2	1	0	9	8	7	6	5		4	3	2	1	0	9	8	7	6	5		4	3	2	1	0
0	-	-	-	-	-	-	H	-	-	-	-	-	-	-	-	H	-	R·Q̄	•	•	•	•	•	•	•	•	•	•	A	/(R·Q̄)
1	-	-	-	-	-	-	H	-	-	-	-	-	-	-	-	H	-	S·Q	•	•	•	•	•	•	•	•	•	•	A	/(S·Q)
2																														
3																														
4																														
5																														
6	-	-	-	-	-	H	-	-	-	-	-	-	-	-	-	-	-	R	•	•	•	•	•	•	•	•	A	•	/(R+Q̄)	
7	-	-	-	-	-	-	-	-	-	-	-	-	-	-	H	-	-	Q̄	•	•	•	•	•	•	•	•	A	•	/(Q̄+Q)	
8	-	-	-	-	-	-	-	-	-	-	-	-	-	-	H	-	-	Q	•	•	•	•	•	•	•	•	A	•	/(Q+S)	
9	-	-	-	-	H	-	-	-	-	-	-	-	-	-	-	-	-	S	•	•	•	•	•	•	•	•	A	•	/(S+Q)	
10																														
11	-	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	LE·D	•	•	•	•	•	•	A	•	•	•	/(LE·D+Q)	
12	-	L	-	-	-	-	-	-	-	-	-	-	-	H	-	-	-	LE·Q	•	•	•	•	•	•	A	•	•	•	/(LE·Q+Q)	
13																														
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D7																														
D6																														
D5																														
D4																														
D3																														
D2																														
D1																														
D0																														
PN	8	7	6	5	4	3	2	1	19	18	17	16	15	14	13	12	11	9	19	18	17	16	15	14	13	12	11	9		
REMARKS		LE	D	S	R	S	R								Q	Q	Q	Q							B <sub>4</sub>	B <sub>3</sub>	B <sub>2</sub>	B <sub>1</sub>	B <sub>0</sub>	

PLS153

1800x505





# Latches and Flip-Flops With PLS153

AN14

## D FLIP-FLOP

An edge-triggered master-slave D flip-flop may be constructed with two D-latches in the manner shown in Figure 10.

An PLS153 may be programmed as shown in Figure 11 to implement the D flip-flop which is equivalent to the circuit shown in Table 5 in the PLS153 logic representation.

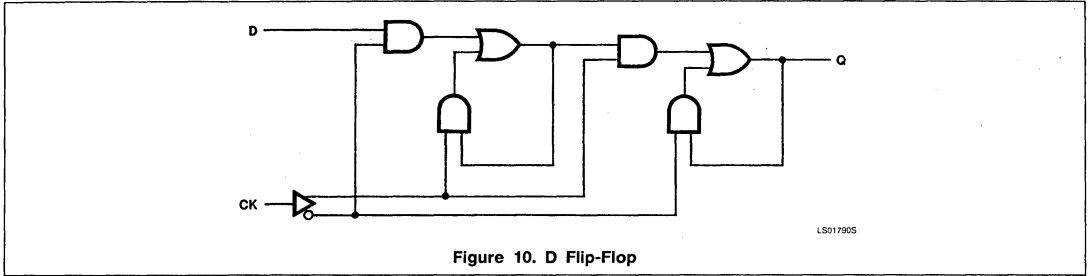


Figure 10. D Flip-Flop

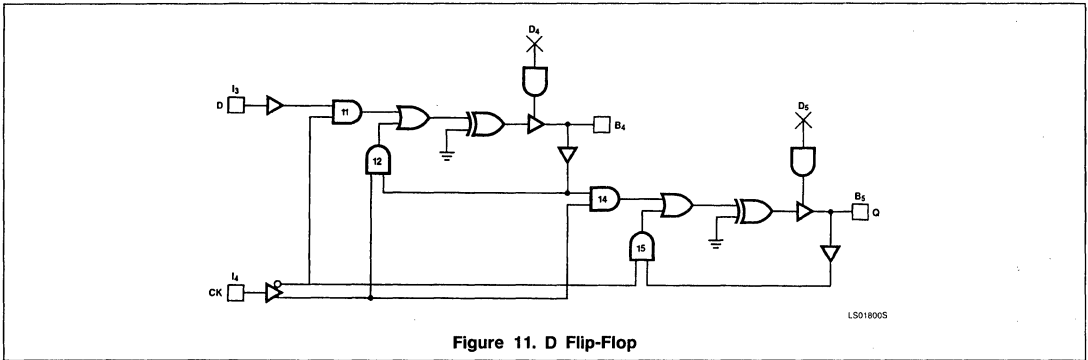


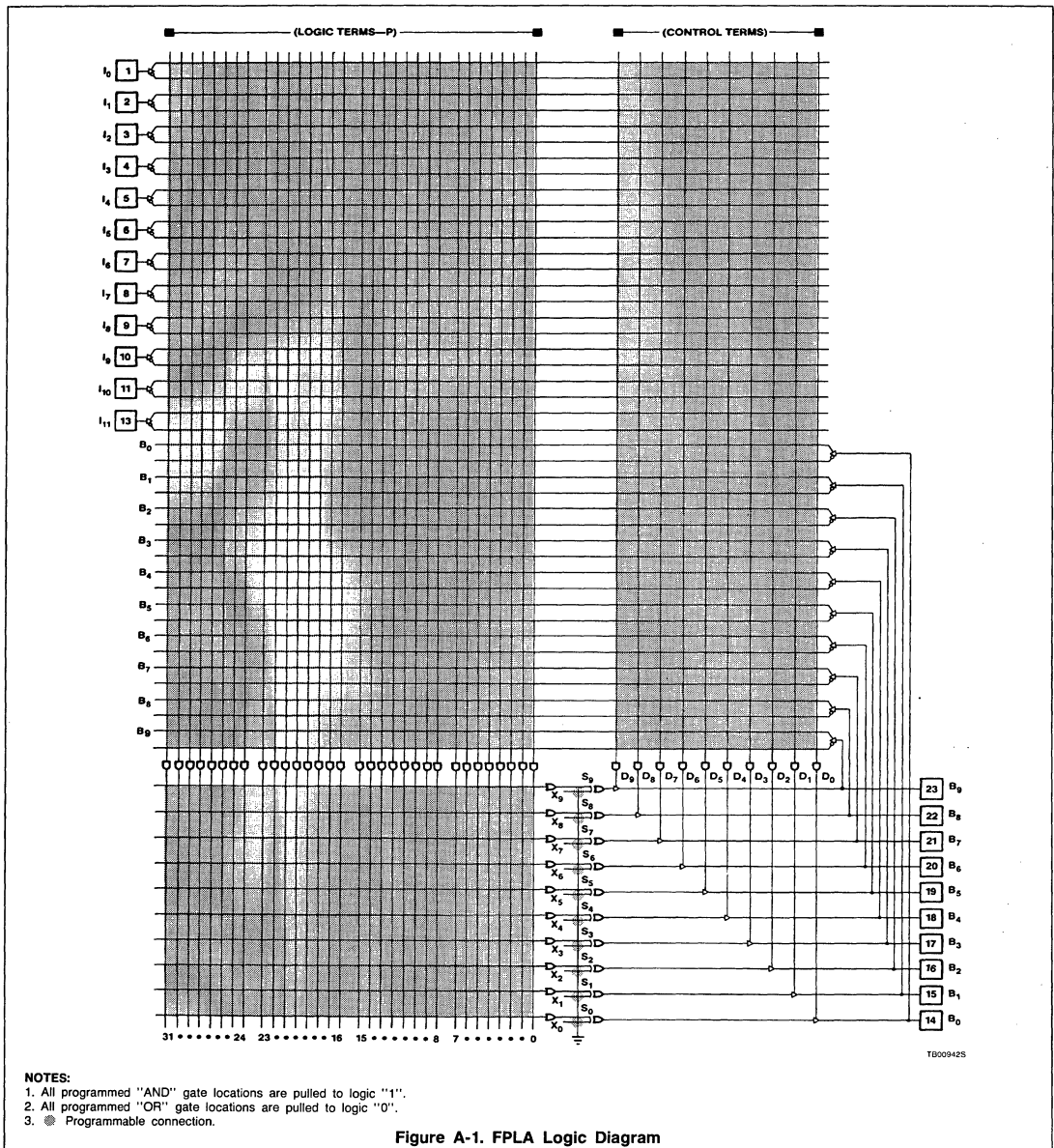
Figure 11. D Flip-Flop



# Latches and Flip-Flops With PLS153

AN14

## APPENDIX A



# Latches and Flip-Flops With PLS153

AN14

Appendix B. PLS153/153A Programming Table

CODE NO.														POLARITY										REMARKS					
TERM	AND													OR															
	B(I)													B(O)															
	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	1	0	9	8	7	6	5		4	3	2	1	0
	H	H	H	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	A	.	.	.	A	.	.	.	.	.	.
0																		A	.	.	.	A	.	.	.	.	.	.	$X = A \cdot B \cdot C \cdot D$
1																													$T = \overline{(A \cdot B \cdot C \cdot D)}$
2																													
3																													
4	L	L	L	L	-	-	-	-	-	-	-	-	-	-	-	-	A	.	.	.	A	.	.	.	.	.	.	$Y = \overline{A \cdot B \cdot C \cdot D}$	
5																												$U = \overline{(A \cdot B \cdot C \cdot D)}$	
6																													
7																													
8																													
9	-	H	L	-	-	-	-	-	-	-	-	-	-	-	-	-	B	.	.	.	A	.	.	.	A	.	.	.	$Z = (B \cdot \overline{C} + B \cdot \overline{D})$
10	-	H	-	L	-	-	-	-	-	-	-	-	-	-	-	-	B	.	.	.	A	.	.	.	A	.	.	.	$\overline{C \cdot D}$
11	-	-	L	L	-	-	-	-	-	-	-	-	-	-	-	-	$\overline{C \cdot D}$	.	.	.	A	.	.	.	A	.	.	.	$V = \overline{(B \cdot \overline{C} + B \cdot \overline{D}) + \overline{C \cdot D}}$
12																													
13																													
14																													
15																													
16																													
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D6																													
D5																													
D4																													
D3																													
D2																													
D1																													
D0																													
PN	8	7	6	5	4	3	2	1	19	18	17	16	15	14	13	12	11	9	19	18	17	16	15	14	13	12	11	9	
REMARKS	A	B	C	D					X	Y	Z			T	U	V			X	Y	Z			T	U	V			

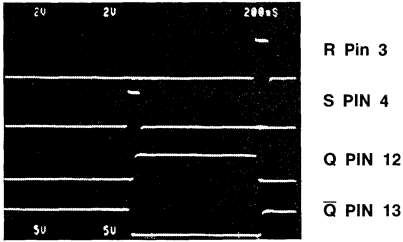
PLS153

# Latches and Flip-Flops With PLS153

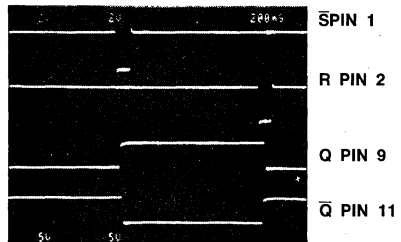
AN14

## APPENDIX C

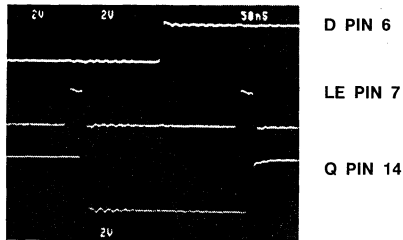
**R-S LATCH (Cross-Coupled NOR)**  
See Figures 3 and 4 and Table 2



**R-S LATCH (Cross-Coupled NAND)**  
See Figures 1 and 2 and Table 1

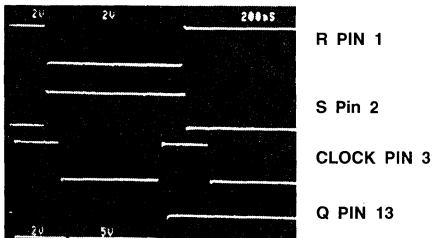


**D-LATCH**  
See Figures 6 and 7 and Table 3



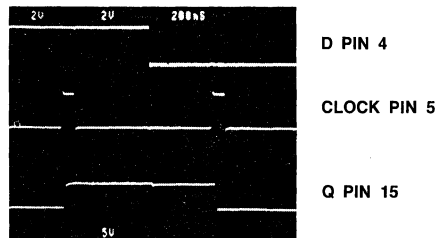
Typical set-up time  $\cong$  0ns  
Typical hold time  $\cong$  0-5ns  
Typical propagation delay  $\cong$  20ns

**EDGE-TRIGGERED R-S Flip-Flop**  
See Figures 8 and 9 and Table 4



NOTE: Timing requirements/performance are the same as the R-S latches

**EDGE-TRIGGERED D Flip-Flop -**  
See Figures 10 and 11 and Table 5



NOTE: Timing requirements/performance are the same as the D-latch

Figure C-1. Timing Photos

### Application Specific Products

#### INTRODUCTION

The PLS159 is a field programmable logic sequencer which consists of four dedicated inputs, four bidirectional I/O's, eight flip-flops, thirty two 16-input AND gates, twenty 32-input OR gates, and a complement array. Each flip-flop has a bidirectional I/O and may be individually programmed as J-K or D flip-flop, or switch between the two types dynamically. The flip-flops will accept data from the internal logic array or from the bidirectional I/O, or they may be set or reset asynchronously from the AND array. The output polarity of the four bidirectional I/O's are programmable and the direction is controlled by the AND array. Figure 1 is the logic diagram of PLS159.

#### PROGRAMMING THE PLS159

The programming table is shown in Table 1 where there is a place for everything that is

shown in Figure 1. The program table is basically divided into two main sections. The left hand side of the table, section A, represents the input side of the AND gates, while the right hand side, section B, represents the OR gates sections which includes the flip-flops and the combinatorial outputs B(0) to B(3). The flip-flops modes are defined in section C and the output polarities of the combinatorial outputs are defined in section E. The programming symbols are detailed in Figure 2.

As shown in Table 1, the programming table is very similar to a truth table. Each column in section A represents an input to the 32 AND gates, and each row represents an AND gate connecting to 17 inputs. Columns I<sub>0</sub> to I<sub>3</sub> represent the 4 dedicated inputs, I<sub>0</sub> to I<sub>3</sub>. Columns B(I)<sub>0</sub> to B(I)<sub>3</sub> represent the inputs of the 4 bidirectional I/O, B<sub>0</sub> to B<sub>3</sub>. Columns

Q(P)<sub>0</sub> to Q(P)<sub>7</sub> represent the feedback, F<sub>0</sub> to F<sub>7</sub>, from the flip-flops (the present state). Column "C" represents the complement array.

As shown in Figure 1, the outputs of the AND gates are connected to an array of OR gates which, in turn, are connected to either flip-flops or output circuits. Columns Q(N)<sub>0</sub> to Q(N)<sub>7</sub> represent the next state which the flip-flops will be in. Columns B(O)<sub>0</sub> to B(O)<sub>3</sub> represent the combinatorial outputs B<sub>0</sub> to B<sub>3</sub>.

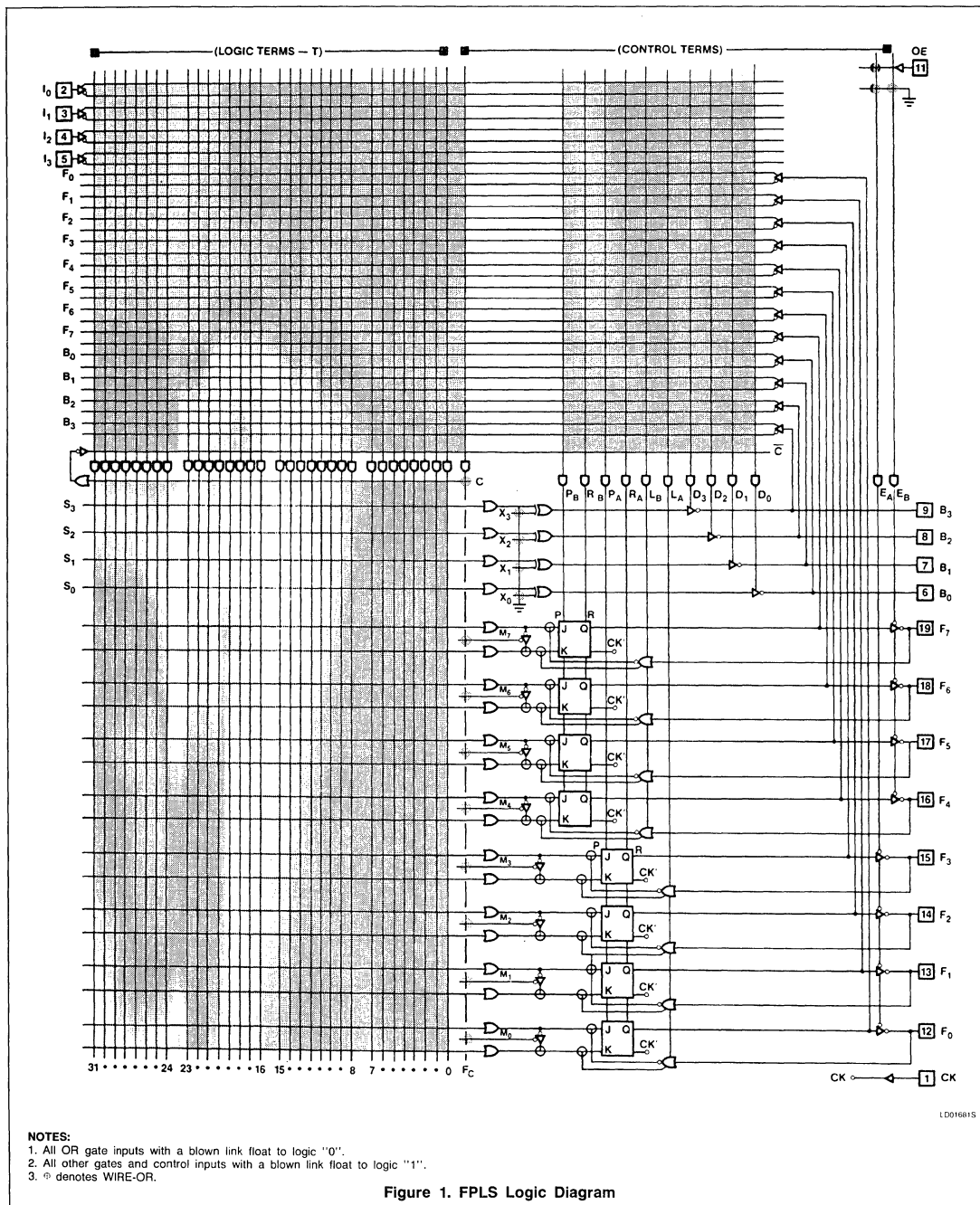
Each row represents an AND gate with 17 inputs each of which may be true and/or complement and is, therefore, a perfect decoder. Referring to the programming symbols in Figure 2, to implement the equation

$$Z = A * B * C * D,$$

all one has to do is to enter one line as shown in Table 2, term-0.

PLS159 Primer

AN15







PLS159 Primer

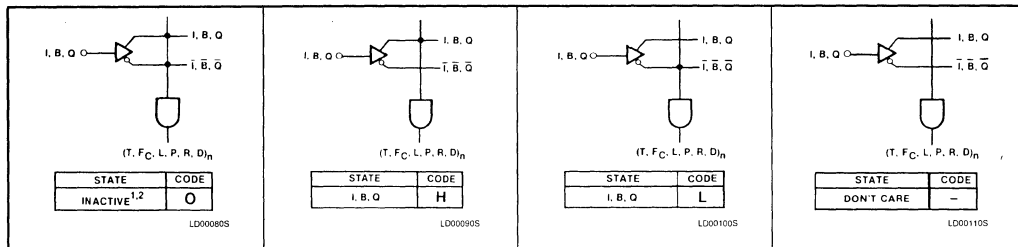
AN15

The PLS can be programmed by means of Logic Programming equipment.

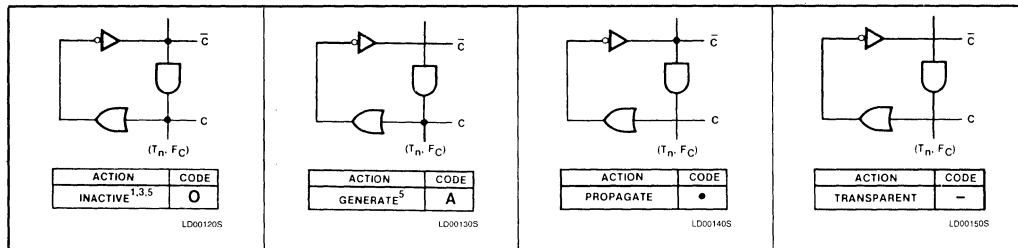
With Logic programming, the AND/OR-EX-OR input connections necessary to imple-

ment the desired logic function are coded directly from the State Diagram using the Program Tables on the following pages.

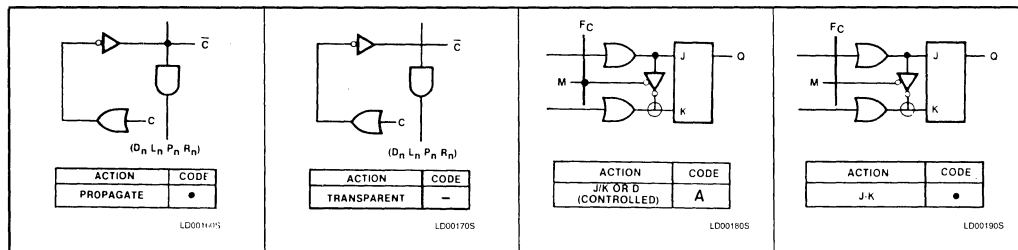
In these Tables, the logic state or action of all I/O, control, and state variables is assigned a symbol which results in the proper fusing pattern of corresponding links defined as follows:



"AND" ARRAY - (I), (B), (Qp)

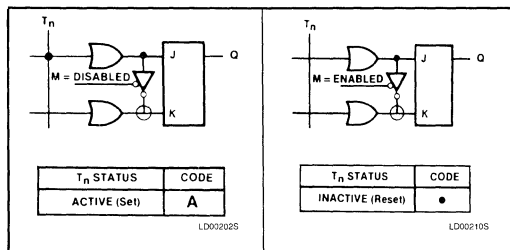


"COMPLEMENT" ARRAY - (C)



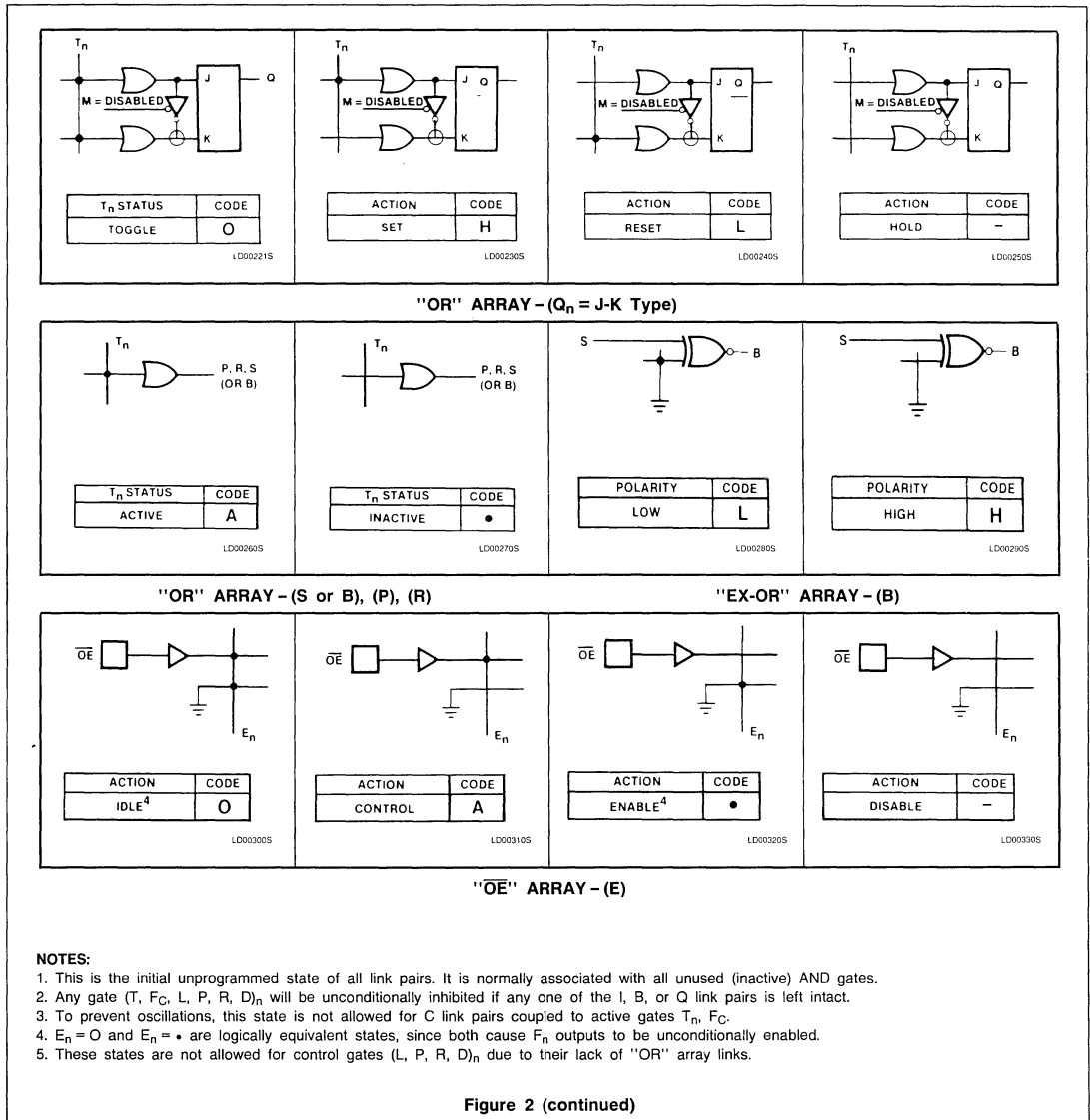
"COMPLEMENT" ARRAY (cont.)

"OR" ARRAY - (MODE)



"OR" ARRAY - (Q<sub>N</sub> = D-Type)

Figure 2





## PLS159 Primer

## AN15

Notice that only  $I_0$  to  $I_3$  on the left hand side and  $B(O)_4$  on the right hand side have entries to implement the equation. All unused columns are dashed out or dotted out.

To implement the equation

$$Y = /A * B * /C,$$

enter one line as shown in Table 2, term-2 where the entry "H" represents the non-inverting input buffer while the entry "L" represents the inverting buffer. To have the AND gate to be unconditionally "High", dash out all the inputs of that particular AND gate as shown in Table 2, term-4. The virgin condition of the device, as shipped from the factory, has all connections intact, which means that the inverting and the non-inverting buffers of the same inputs are connected together. Such connection will cause the AND gate to be unconditionally "Low" as shown in Table 2, terms 6 and 7. The unconditional High and Low states are normally useful only internally and seldom brought out to the output pins.

To implement the equation

$$W = A * /B + C * /D,$$

enter one line for  $A * /B$  and another line for  $C * /D$  as shown in Table 2, terms 9 and 10. Use one line to AND something together; use different lines to OR something together — one line per item to be OR'ed.

All the pins which are labelled B's are bidirectional I/O pins. Their input buffers are represented by the B(I) columns on the left hand side of the programming table. An "H" entry represents the non-inverting buffer and an "L" entry represents the inverting buffer. Their output buffers are represented by the B(O) columns on the right hand side of the table. An "A" entry means that the output is active (connected to the AND gates); a ""

entry means that the output is inactive (not connected). The outputs may be programmed to be inverting or noninverting. The polarity of each output is determined by its exclusive OR gate (Figure 1 and Figure 2). To have a non-inverting output, enter an "H" in the section labelled "POLARITY" (Table 1, Section E). To have an inverting output, enter an "L". For example, Table 3, terms-0 and-2 implement the equation

$$Z = /(A * B) \text{ and } Y = A * B$$

respectively. The above two equations may also be implemented by term-4 which uses the same AND gate to drive two OR gates.

Besides being able to have programmable Active-High or Active-Low output, the programmable output polarity feature also low output, the programmable output polarity feature also allows the user to minimize his AND term utilization by converting his logic equation into other forms such as conversion by De Morgan Theorem.

For example, the equation

$$X = A + B + C + D$$

takes four AND terms to implement as shown in Table 3, terms 6 to 9. By using De Morgan Theorem, the same equation is changed to

$$/W = /A * /B * /C * /D$$

The result is as shown in term 11 — a saving of three AND terms. The output buffers are disabled in their virgin states so that they all behave as inputs. The buffers are enabled or disabled by their corresponding Control AND terms  $D_0$  to  $D_3$  (see Figure 1). The Control AND terms are represented in the programming table on the last four rows on the left hand side. Dashing out all the inputs will

cause the output buffer to be unconditionally enabled, whereas a "0" (zero) will cause the buffer to be unconditionally disabled. The buffers may also be controlled by a logical condition, e.g.  $A * /B * /C$ , etc.

There are eight flip-flops on the chip each of which may be programmed as a J/K or a D flip-flop, or they may be programmed to switch dynamically. As shown in Figure 1, each flip-flop is a J/K to begin with. A tri-state inverter is connected in between the J and K inputs of each flip-flop, which when enabled by the AND gate  $F_C$ , will cause the flip-flop to function as a D flip-flop. The inverters are enabled by  $F_C$  through fuses  $M_0$  to  $M_7$ . A "" in the F/F Mode entry of the programming table means that particular fuse is to be disconnected and that particular flip-flop is to be J/K. An "A" entry will leave the M fuses intact, which allow the flip-flop to be D or J/K as controlled by the output of  $F_C$  (see Figure 2, "OR" ARRAY — (MODE)). The inputs to the flip-flops are represented by the programming table as the next state,  $Q(N)_0$  to  $7$  since their inputs are from the OR array. The outputs of these registers are connected to their respective tri-state inverting output buffers, four of which are controlled by EA and the other four by EB. A "" in EA will enable outputs  $F_0$  to  $F_3$ , whereas a "-" will disable them. An "A" will allow the output buffers to be controlled by /OE, pin 11. Table 4, terms 0, 1 and 3 represent the following equations

$$Q_0: J = A * C + /B * /E \quad \text{eq. 1}$$

$$Q_0: K = A * /C \quad \text{eq. 2}$$

Notice that the J input in equation 1 is represented by the "H" entry in terms-0 and 1, column  $Q(N)_0$  while the K input in equation 2 is represented by the "L" entry in term-3, column  $Q(N)_0$ . An undefined input, J or K, is considered "Low".





PLS159 Primer

AN15

A D flip-flop may be implemented by first entering an "A" in F/F MODE. Then enter "0" in the row F<sub>C</sub>, which will unconditionally enable the tri-state inverter between the J and K inputs. The following logic equation may be implemented as shown in Table 4, term 5

$$Q_1: D = /A * /B * /C + E.$$

Notice that the entries in term 5, columns Q(N)<sub>0</sub> to 7 are "A" and "." instead of "H" and "L" as in the case of J/K flip-flops. The entry "A" will cause the fuse connecting to the "K" input to be disconnected and the "J" fuse to be intact. Whereas the entry "." will cause both fuses to be disconnected. This feature enables the user to quickly recognize the mode in which the flip-flops are operating without having to go through the control terms. Some commercially available device programmers in the market may not have the software capability to implement this feature, in which case an "H" and a "L" may be used in place of "A" and "." respectively as shown in Table 4, terms 8 and 9.

Of course, the term F<sub>C</sub> may have inputs instead of zeros and dashes, in which case the flip-flop modes are controlled dynamically.

When both the J and K inputs are "1's", the flip-flop will toggle. A simple 3-bit counter may be implemented using only AND terms as shown in Table 4 terms 11, 12 and 13. The logic equations for the three flip-flops are as the following:

$$\begin{aligned} Q_5: T &= 1; && (Q_5 \text{ toggles unconditionally}) \\ Q_6: T &= Q_5; && (Q_6 \text{ toggles when } Q_5 = 1) \\ Q_7: T &= Q_5 * Q_6; && (Q_7 \text{ toggles when } Q_5 * Q_6 = 1) \end{aligned}$$

The above equations represent an octal up-counter. However, since the outputs of the flip-flops are inverted, the counting sequence of the outputs is that of a down-counter.

The flip-flops may be asynchronously set and reset by the Control AND terms PA/PB and

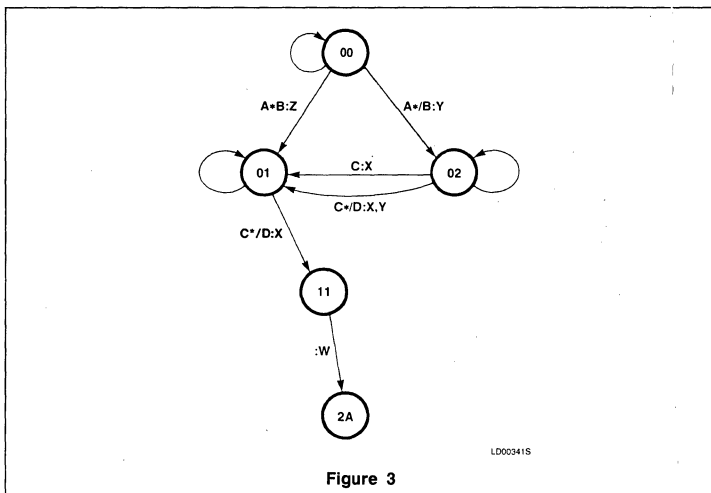


Figure 3

RA/RB respectively. As shown in Figure 1, PA and RA controls flip-flops F<sub>0</sub> to F<sub>3</sub>, while PB and RB control F<sub>4</sub> to F<sub>7</sub>.

In order to save the number of input pins, the eight flip-flops may be synchronously loaded directly from their own output pins. To use this feature, EA and/or EB must be programmed "A" or "." so that the output buffers may be disabled before loading. As shown in Figure 1, every flip-flop has an OR/NOR gate the input of which is directly connected to the output pin and the outputs of the OR/NOR are connected to the K and J inputs respectively. This OR/NOR gate inverts the input and feeds it to the flip-flop in a "wire-OR" fashion. Therefore, when loading data directly into the flip-flops from the output pins, caution must be exercised to insure that the inputs from the OR array does not interfere with the data being loaded. For example, if the data being loaded is a "1" on the output

pin, the J input will be a "0" and the K input will be a "1". If, at the same time, a "1" is present at the J-input from the OR array, the flip-flop will see "1's" in both J and K inputs. It will toggle as a result. The OR/NOR gates are enabled by the Control AND terms LA and LB. LA controls flip-flops F<sub>0</sub> to F<sub>3</sub> and LB controls F<sub>4</sub> to F<sub>7</sub>.

All Control AND terms function and are programmed in the same manner as the other AND terms. The only difference is that the Control AND terms are not connected to the OR array.

The outputs of the flip-flops may be fed back into the AND array as the present state, Q(P). The output of the AND array into the OR array and the inputs to the flip-flops is the next state, Q(N). As an example, Figure 3 is a state machine implemented in a PLS159 as shown in Table 5, terms 0 to 6.





## AN16 PLS159 As Modulo Counters

### Application Note

#### Application Specific Products

#### DESCRIPTION

The field-programmable logic sequencer (FPLS) PLS159 has eight edge-triggered flip-flops which may be individually programmed to be J/K, D, or toggle flip-flops. The detail logic diagram of the device is shown in Figure 2.

A counter may be constructed by having individual flip-flops toggle when they are at certain states. Implementing such counters requires one toggle flip-flop per bit and an associating AND gate as a decoder for each flip-flop. Such a method allows the PLS159 to be a counter from modulo 2 to 256 or from one bit to 8 bits.

#### MODULO-8 UP/DOWN COUNTER

##### The Up-Counter

The PLS159 has an inverting output buffer for each flip-flop. Therefore the counting sequence of the flip-flops is from 7 to 0 so that the outputs will count from 0 to 7. Table 1 is

the truth table of the internal counting sequence.

Table 1

COUNT	Q <sub>2</sub>	Q <sub>1</sub>	Q <sub>0</sub>
0	1	1	1
1	1	1	0
2	1	0	1
3	1	0	0
4	0	1	1
5	0	1	0
6	0	0	1
7	0	0	0

From Table 1, logic equations for the flip-flops may be generated as the following:

$$Q_0: T = 1; \quad (Q_0 \text{ unconditionally toggles})$$

$$Q_1: T = /Q_0; \quad (Q_1 \text{ toggles if } Q_0 = 0)$$

$$Q_2: T = /Q_0 * /Q_1; \quad (Q_2 \text{ toggles if both } Q_0 \text{ and } Q_1 = 0)$$

The equations are implemented as shown in Table 2, terms 0, 1, and 2. E<sub>A</sub> is enabled, and the mode for the three flip-flops is set to J/K. All unused flip-flops and outputs (the B(0)'s) associating to AND-terms are "dashed" or "dotted" out. The event to be counted is connected to the clock input, pin 1 of the device.

##### The Down-Counter

The down-counter is constructed in the same manner as the up-counter except that the counting sequence is reversed. The down-counter is implemented in Table 2, terms 4 to 6 with the corresponding flip-flop mode set to J/K and E<sub>B</sub> enabled.

##### Modulo-16 Counter

Expanding the modulo-8 counter to 4-bit, the counter becomes modulo-16, Table 3, terms 0 to 3 and the associating F/F MODE and E<sub>A</sub> implement a modulo-16 up-counter, while terms 5 to 8 and the associating F/F MODE and E<sub>B</sub> implement the modulo-16 down-counter.

# PLS159 As Modulo Counters

AN16

Table 2

CODE NO.		FF MODE										E <sub>B</sub>	E <sub>A</sub>				POLARITY														
		••••••••••										•	•																		
T E R M	AND										REMARKS	(OR)										REMARKS									
	C	I			B(I)			Q(P)				Q(N)					B(O)														
	3	2	1	0	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	3	2	1	0			
0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	0	.	.	.	.		
1	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	0	.	.	.	.		
2	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	0	.	.	.	.		
3	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
4	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	0	.	.	.	.		
5	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	0	.	.	.	.		
6	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	0	.	.	.	.		
7	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
8	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
9	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
10	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
11	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
12	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
13	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
14	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
15	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
16	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
17	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
18	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
19	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
20	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
21	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
22	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
23	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
24	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
25	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
26	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
27	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
28	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
29	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
30	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
31	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	.	.	.	.		
FC																															
PB																															
RB																															
LB																															
PA																															
RA																															
LA																															
D3																															
D2																															
D1																															
D0																															
PIN	5	4	3	2	9	8	7	6	19	18	17	16	15	14	13	12	19	18	17	16	15	14	13	12	9	8	7	6			
REMARKS																															

PLS159

T8000215



# PLS159 As Modulo Counters

# AN16

## DECADE COUNTER

### The Decade Up-Counter

The truth table of a decade counter is as shown in Table 4.

Table 4

COUNT	Q <sub>3</sub>	Q <sub>2</sub>	Q <sub>1</sub>	Q <sub>0</sub>
0	1	1	1	1
1	1	1	1	0
2	1	1	0	1
3	1	1	0	0
4	1	0	1	1
5	1	0	1	0
6	1	0	0	1
7	1	0	0	0
8	0	1	1	1
9	0	1	1	0
0	1	1	1	1

Logic equations may be generated from Table 4 as the following:

$$\begin{aligned}
 Q_0: T &= 1; \\
 Q_1: T &= /Q_0 * Q_3; \\
 Q_2: T &= /Q_0 * /Q_1 * Q_3; \\
 Q_3: T &= /Q_0 * /Q_1 * /Q_2 * Q_3 + \\
 &\quad /Q_0 * Q_1 * Q_2 * /Q_3;
 \end{aligned}$$

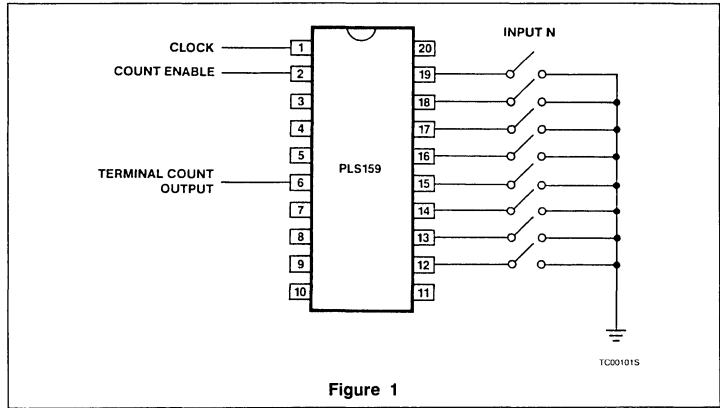


Figure 1

The equations are implemented as shown in Table 5, terms 0 to 4 and the associating flip-flop mode and E<sub>A</sub> settings.

### Decade Down-Counter

The decade down-counter is similar to the decade up-counter except that the counting sequence is reversed from 0 to 9 as shown in Table 5, terms 6 to 11 with the associating F/F MODE set to J/K and E<sub>B</sub> to ENABLE.

### Decade Down Counter

COUNT	Q <sub>7</sub>	Q <sub>6</sub>	Q <sub>5</sub>	Q <sub>4</sub>
9	0	1	1	0
8	0	1	1	1
7	1	0	0	0
6	1	0	0	1
5	1	0	1	0
4	1	0	1	1
3	1	1	0	0
2	1	1	0	1
1	1	1	1	0
0	1	1	1	1
9	0	1	1	0

$$\begin{aligned}
 Q_4: T &= 1; \\
 Q_5: T &= Q_4 * Q_5 * Q_6 * /Q_7 + \\
 &\quad Q_4 * /Q_5 * /Q_6 * Q_7 + \\
 &\quad Q_4 * Q_5 * /Q_6 * Q_7 + \\
 &\quad Q_4 * /Q_5 * Q_6 * Q_7; \\
 Q_6: T &= Q_4 * Q_5 * Q_6 * /Q_7 + \\
 &\quad Q_4 * Q_5 * /Q_6 * Q_7; \\
 Q_7: T &= Q_4 * Q_5 * Q_6 * /Q_7 + \\
 &\quad Q_4 * Q_5 * Q_6 * Q_7;
 \end{aligned}$$

### DIVIDE-BY-N COUNTER

This counter, shown in Figure 1 and Table 6, takes an input (maximum = 8 bits for each device), complements it, and counts until all flip-flops become 1, then a terminal count is sent out at B(O)<sub>0</sub> (divide-by-N). At the end of the count, where all flip-flops are 1's, terms LA and LB are activated which causes the flip-flops to load data from F<sub>0</sub> to F<sub>7</sub>, and the cycle starts again. Since there are 8 flip-flops, the maximum count is 256.

# PLS159 As Modulo Counters

AN16

Table 5

CODE NO.		FF MODE										EB		EA		POLARITY														
		••••••••••										•		•																
TERM	C	AND										REMARKS	(OR)										REMARKS							
		I			B(I)			Q(P)					Q(N)					B(O)												
		3	2	1	0	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	3	2	1	0	
0	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	0	•	•	•	
1	-	-	-	-	-	-	-	-	-	-	-	-	-	H	-	-	L	-	-	-	-	-	0	-	-	•	•	•	•	
2	-	-	-	-	-	-	-	-	-	-	-	-	-	H	-	L	L	-	-	-	-	-	0	-	-	•	•	•	•	
3	-	-	-	-	-	-	-	-	-	-	-	-	-	H	L	L	L	-	-	-	-	-	0	-	-	•	•	•	•	
4	-	-	-	-	-	-	-	-	-	-	-	-	-	L	H	H	L	-	-	-	-	-	0	-	-	•	•	•	•	
5																														
6	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	0	-	-	-	-	•	•	•	•	
7	-	-	-	-	-	-	-	-	-	L	H	H	H	-	-	-	-	0	0	0	-	-	-	-	-	•	•	•	•	
8	-	-	-	-	-	-	-	-	-	H	L	L	H	-	-	-	-	-	0	-	-	-	-	-	-	•	•	•	•	
9	-	-	-	-	-	-	-	-	-	H	L	H	H	-	-	-	-	-	0	0	-	-	-	-	-	•	•	•	•	
10	-	-	-	-	-	-	-	-	-	H	H	L	H	-	-	-	-	-	-	0	-	-	-	-	-	•	•	•	•	
11	-	-	-	-	-	-	-	-	-	H	H	H	H	-	-	-	-	0	-	-	-	-	-	-	-	•	•	•	•	
12																														
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31																														
FC																														
PB																														
RB																														
LB																														
PA																														
RA																														
LA																														
D3																														
D2																														
D1																														
D0																														
PIN		5	4	3	2	9	8	7	6	19	18	17	16	15	14	13	12	19	18	17	16	15	14	13	12	9	8	7	6	
REMARKS																														

PLS159

18000325





# AN17 Electronic Combination Lock

## Application Note

### Application Specific Products

#### INTRODUCTION

A combination lock may be opened by entering the correct numbers which match the preset security code that may be of any number of digits. Using a PLS157, an electronic combination lock with user settable security code may be constructed. The security code may be one to five hexadecimal digits that can be preset by the user. The lock takes a 4-bit binary input as the "combination" and a "Data Valid" input, which means that the combination may be five digits long and each digit may be from 0 to F. If the input matches the preset digit of the security code, the lock will wait for the next digit. If the input does not match the corresponding digit of the security code, the lock will reset itself to the first digit position again. The user may use as many as five digits for the combination which may be set by using five DIP switches or other means. The lock may be used in conjunction with a 4-bit binary encoded rotary switch, or an encoded push button key pad, or an optical card reader, or a magnetic strip reader. The design takes advantage of the six JK flip-flops of the PLS157, the bidirectional I/O's, the complement array, and the general architecture of common product terms.

#### DESCRIPTION

Figure 1 shows an example of an electronic lock which uses five DIP switches to set the security code (hexadecimal 0 to E, F is reserved for reset), a 4-bit binary encoded rotary switch to enter the combination at  $I_0$  to  $I_3$ , and a single pole double throw push button switch, "Data Valid", as the clock which is debounced by the associated circuitry of pin  $B_5$ . The security code is set with five DIP switches which are connected to a four line

input ( $B(I)_0$  to  $B(I)_3$ ). The five DIP switches are multiplexed by the outputs of the flip-flops,  $F_0$  to  $F_4$ . In normal operation, one of the F/F outputs is Low (the content of the register being a "1") while the other five are High. The operation is actually a shift register with a zero bit shifting through five one's. Therefore only one DIP switch is pulled Low (selected) at any one time while the rest is deselected. The pin named "MATCH",  $B(O)_4$ , is an I/O which outputs a High if the input matches the corresponding digit of the security code, otherwise it outputs a Low. A High output of  $B(O)_4$  enables the shift register to shift one position while a Low causes the shift register to reset to the starting position which is a "1" in F/ $F_0$  (flip-flop 0) ( $F_0$  is Low due the output inverter) and "0's" in the other five ( $F_1$  to  $F_5$  = High). The state diagram of the design is as shown in Figure 2 where the state numbers are expressed in two hexadecimal digits. The least significant digit consists of  $F_3$ ,  $F_2$ ,  $F_1$ , and  $F_0$ ; whereas the most significant digit consists of  $F_5$ , and  $F_4$ . At the top of the state diagram, the power-up and reset state is 00 hex. When the outputs have more than one Low, as sometimes happens during power-up, the circuit automatically resets the registers to 00 hex which causes all outputs to be High in order to prevent more than one DIP switch being enabled. After power-up or reset, pushing the "Data Valid" button will initialize the circuit to have the first digit of the security code enabled. Subsequently, any false entry will cause the circuit to go back to the initialized state of 01 hex. When the first digit is correctly set and the "Data Valid" button pressed, the circuit goes to 02 hex and the second DIP switch is enabled while the first DIP switch is disabled. The circuit is now ready for the second digit. By repeating the process, the circuit keeps shifting the "1" in

the shift register until it reaches F/ $F_5$  at which time the Low output may be used to trigger a solenoid. If at any time of the sequence, an incorrect digit is entered, the circuit reverts back to the initialized state of 01 hex.

Notice that any of the five outputs from  $F_1$  to  $F_5$  may be used as an output. Therefore, if, for example, a two digit security code is used, only two DIP switches are needed and the output is taken from  $F_2$  to trigger a solenoid. After the last digit has been entered, all DIP switches are deselected and the inputs  $B(I)_0$  to  $B(I)_3$  become 1111 binary, or F hex. Therefore, the hex number F is not used as a valid code but as an initialization input entered at  $I_0$  to  $I_3$ . When the hex number F is entered, the circuit initializes itself to the 01 hex state. After the last digit of the security code has been entered, if the "Data Valid" button is pressed again, the circuit sees a false entry and reinitializes itself.

The design is implemented using a PLS157 as shown in Table 1, H/L Programming Table of Electronic Lock. P-terms 0 to 14 are programmed as decoders. If an input matches the corresponding digit of the security code, one of the p-terms will be active which causes  $B(O)_4$  to output a High which, in turn, enables the registers to shift to the next digit by terms 16 to 20. In the event that an incorrect input is entered,  $B(O)_4$  outputs a Low which, in turn, causes the registers to be set 000001 binary by term 21. If an input of F is entered, term 15 causes the registers to be 000001. Terms 22 to 29 and RB ensure that no more than one register is "1" at a time. Terms 22 to 28 are connected to the complement array, which in turn, drives terms 29 and RB to set the registers to 000000 when terms 22 to 28 are inactive.



# Electronic Combination Lock

AN17

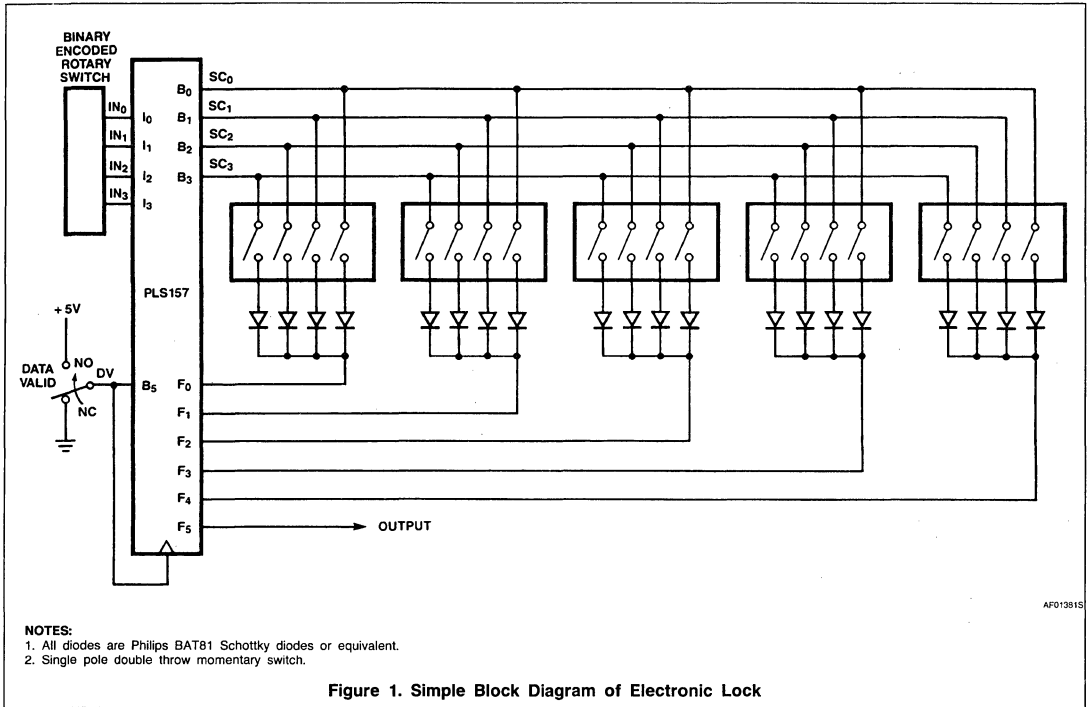


Figure 1. Simple Block Diagram of Electronic Lock

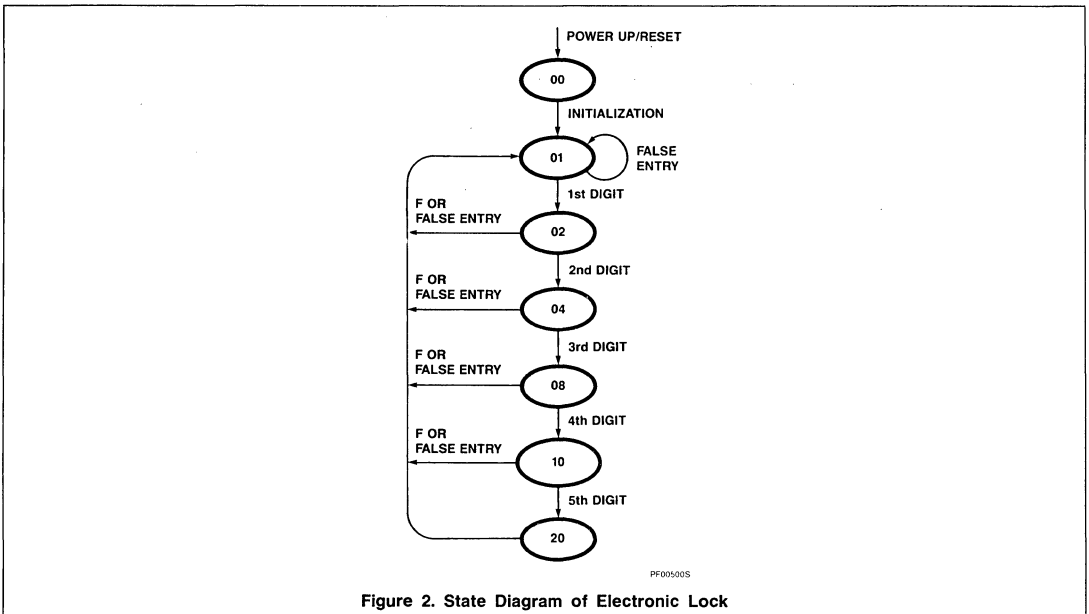


Figure 2. State Diagram of Electronic Lock



# AN18 Schmitt Trigger Using PLS153 and PLS159

## Application Note

### Application Specific Products

#### INTRODUCTION

One of the many features of the PLS153 to 159 series is the availability of individually controlled Tri-state I/O pins. Taking advantage of this feature, a Schmitt trigger may be constructed using one input pin, two bidirectional I/O pins and additional components of three resistors. The two threshold voltages, as well as the hysteresis, are determined by the values of the three resistors and the parameters of the PLS153/159 device, which are 1) input threshold voltage,  $V_{TH}$ , 2) High output voltage,  $V_{OH}$ , and 3) Low output voltage,  $V_{OL}$ . The circuit may be simplified if Schmitt function is needed only on Low going High or High going Low, and if the hysteresis and threshold voltages are not important.

#### DESCRIPTION

A simplified block diagram of a non-inverting Schmitt trigger is shown in Figure 1 where  $R_1$ ,  $R_2$ , and  $R_3$ , form two pairs of voltage dividers one of which get into action at input voltage direction of High going Low and the other Low going High. Assuming that input voltage starts at zero volt, the output voltage is therefore at  $V_{OL}$  which causes  $Q_2$  to pull  $R_3$  towards ground. As the input voltage increases, only a fraction of the voltage is

impressed upon the input buffer due to the dividing network  $R_1$  and  $R_3$ . As soon as the input voltage reaches a point where  $V_1 = V_{TH}$  ( $V_{TH} = 1.38V$  typical), the output switches to  $V_{OH}$  which, in turn, turns off  $Q_2$  and turns on  $Q_1$ .  $V_1$  will jump to a value greater than  $V_{TH}$  and  $Q_1$  then pulls the input pin, through  $R_2$ , towards  $V_{OH}$ , which in turn locks the output to a High state even if the input voltage fluctuates, as long as it does not fluctuate outside of the designed hysteresis. When the input voltage goes from a High to a Low, the Schmitt function repeats itself except that  $Q_1$  and  $Q_2$  reverse their roles.

The triggering voltages,  $V_H$  (Low going High) and  $V_L$  (High going Low) are:

$$V_H = V_{TH} [(R_1 + R_3)/R_3] - V_{OL} (R_1/R_3);$$

$$V_L = V_{TH} [(R_1 + R_2)/R_2] - V_{OH} (R_1/R_2);$$

where, at room temperature,  $V_{CC} = 5.0V$ ,  $I_{OH}/I_{OL} < 1mA$ .  $V_{TH}$  is the threshold voltage of the device, typically 1.38V;  $V_{OL}$  is the output Low voltage of the device, typically 0.36V at  $|I_{OL}| < 1mA$ ;  $V_{OH}$  is the output High voltage of the device, typically 3.8V at  $|I_{OH}| < 1mA$ .

The implementation of Figure 1 using PLS153/153A is as shown in Table 1, and Figure 2a. A scope photo of the operation of the circuit is shown in the Appendix. The

implementation using PLS159 is shown in Table 2 and Figure 2b. In Tables 1 & 2,  $V_1$  is the input pin,  $V_0$  is the output pin,  $V_2$  is the output which pulls down  $V_1$  and  $V_3$  is the output pin that pulls up  $V_1$ . The Schmitt output is available at pin  $B_0$  for external use, and is available internally at the input buffers of  $I_0$  and  $B(I)_0$ . However, there is a propagation delay between the two signals from the  $I_0$  buffer and the  $B(I)_0$  buffer.

An inverting Schmitt triggered buffer may be constructed using the same principle. A simple block diagram of such inverter is shown in Figure 3a. The circuit is implemented using H/L programming table as shown in Table 3 for PLS153 and Table 4 for PLS159. Table 3 is also represented in logic symbols in Figure 3b. If the voltage levels ( $V_L$  and  $V_H$ ) and the hysteresis are not critical, one I/O pin may be used to pull the input pin High and Low. Therefore one I/O pin and a resistor may be saved. The drawback is that the range of  $V_H$  and  $V_L$  is quite limited. The circuit is as shown in Figure 4.

If Schmitt function is needed only in one direction, one of the resistor/output circuit may be eliminated. The circuit is as shown in Figure 5.

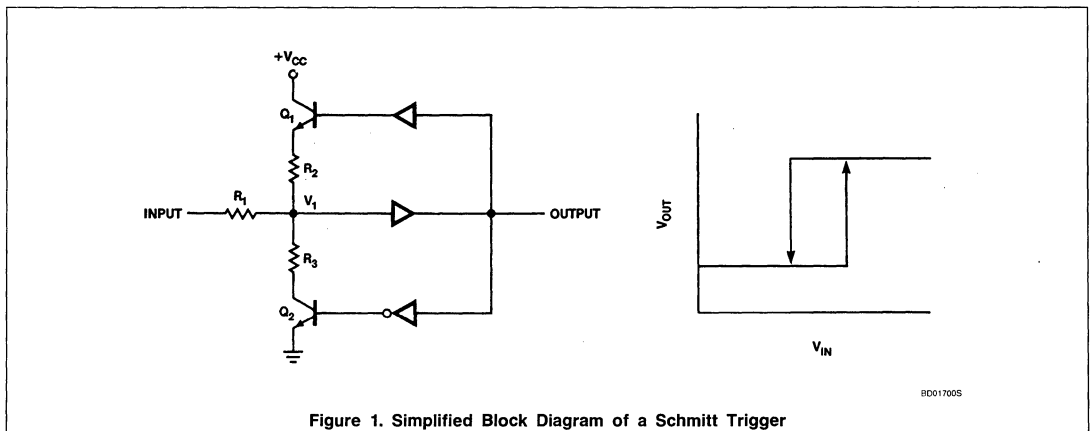


Figure 1. Simplified Block Diagram of a Schmitt Trigger

# Schmitt Trigger Using PLS153 and PLS159

AN18

Table 1. PLS153/153A Programming Table

CODENO.														POLARITY									
TERM	AND										REMARKS	OR										REMARKS	
	B(I)											B(O)											
	7	6	5	4	3	2	1	0	9	8		7	6	5	4	3	2	1	0				
0	-	-	-	-	-	-	H	-	-	-	-	-	-	-	-	-	-	•	•	A	NON-INV. BUFFER		
1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	•	A	•	OUTPUT VOL		
2	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	A	•	•	OUTPUT VOL		
3																							
4																							
5																							
6	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	A	A		SAME AS		
7																					TERMS 1 + 2		
8																					WITH		
9																					B(6)4 = V <sub>2</sub>		
10																					B(6)5 = V <sub>2</sub>		
11																							
12																							
13																							
14																							
15																							
16																							
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28																							
29																							
30																							
31																							
D9																							
D8																							
D7																							
D6																							
D5																							
D4																							
D3																							
D2																					L H		
D1																					L H		
D0																					L H		
PN	8	7	6	5	4	3	2	1	19	18	17	16	15	14	13	12	11	9					
REMARKS								V <sub>1</sub>														V <sub>2</sub> V <sub>2</sub> V <sub>0</sub>	

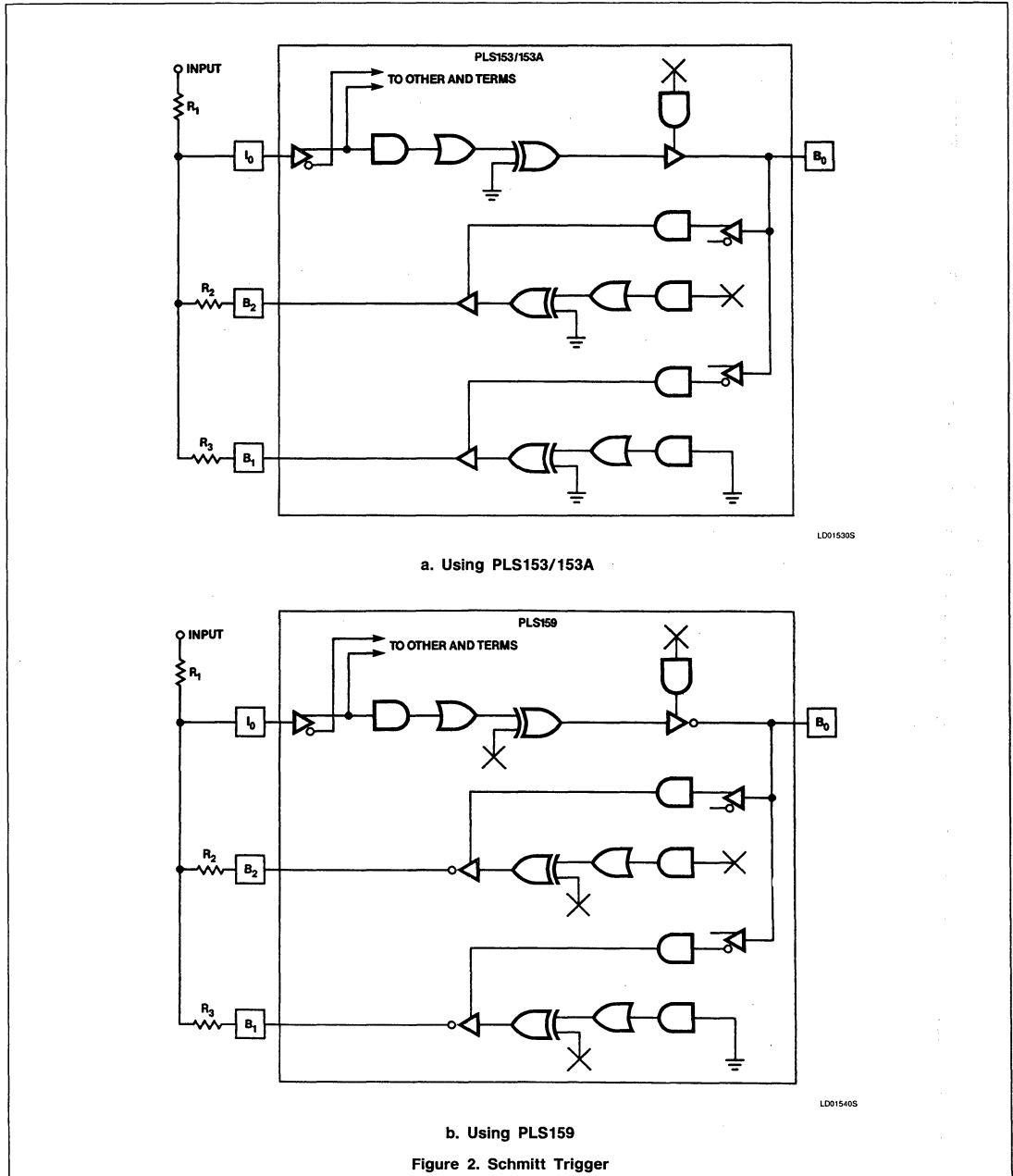
PLS153

NOTE:  
Schmitt trigger output may be obtained from both .1<sub>0</sub> and B(1)<sub>0</sub> to drive the AND-ARRAY.

T801730S

# Schmitt Trigger Using PLS153 and PLS159

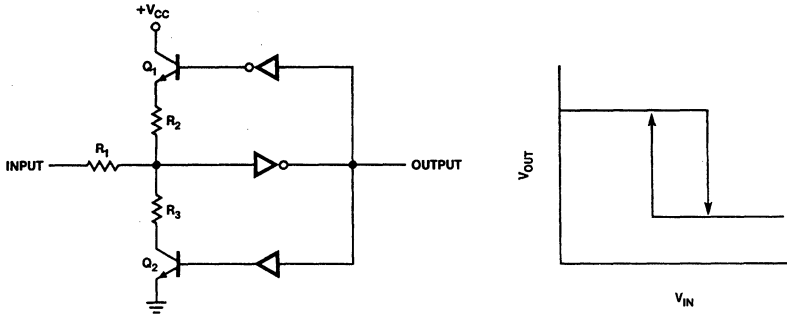
AN18





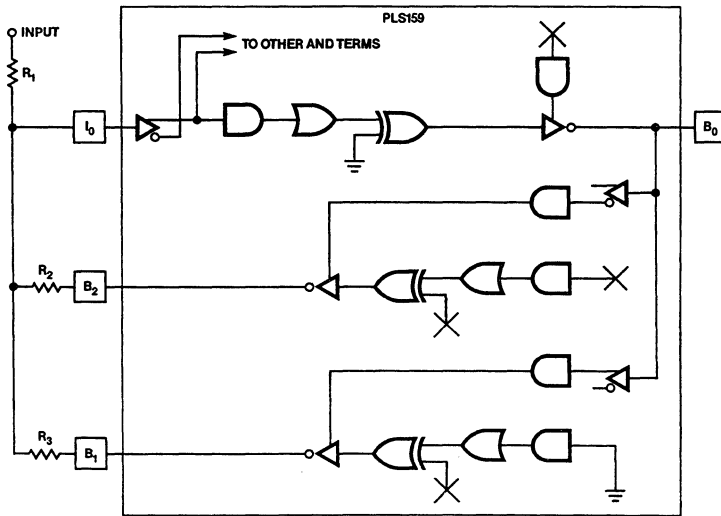
# Schmitt Trigger Using PLS153 and PLS159

## AN18



BD017105

a. Simplified Block Diagram



LD015505

b. Using PLS159

Figure 3. Inverting Schmitt Trigger

# Schmitt Trigger Using PLS153 and PLS159

AN18

Table 3. PLS153/153A Programming Table

CODENO.													POLARITY				REMARKS												
T E R M	AND										OR																		
	B(I)										B(O)																		
	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2		1	0	REMARKS									
0	-	-	-	-	-	-	H	-	-	-	-	-	-	-	-	-	-	-	• • A	INV. BUFFER									
1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	• • A	OUTPUT V <sub>OH</sub>									
2	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	A • •	OUTPUT V <sub>OL</sub>									
3																													
4																													
5																													
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D9																													
D8																													
D7																													
D6																													
D5																													
D4																													
D3																													
D2																													
D1																													
D0																													
PN	8	7	6	5	4	3	2	1	19	18	17	16	15	14	13	12	11	9	19	18	17	16	15	14	13	12	11	9	
REMARKS								V <sub>1</sub>																			V <sub>2</sub>	V <sub>3</sub>	V <sub>6</sub>

PLS153

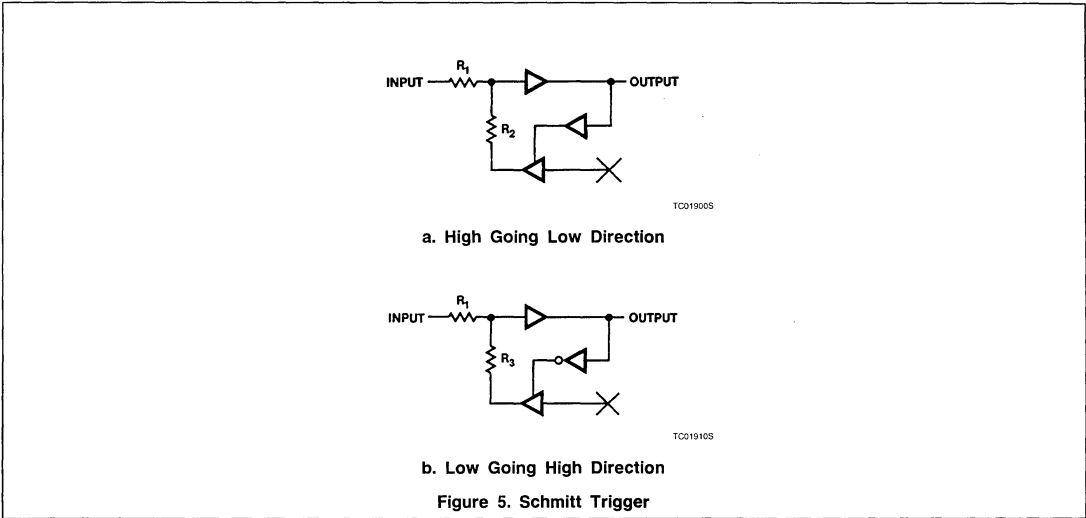
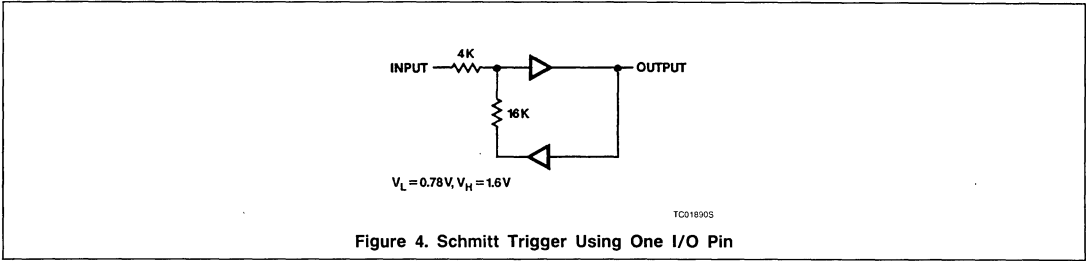
T8015805



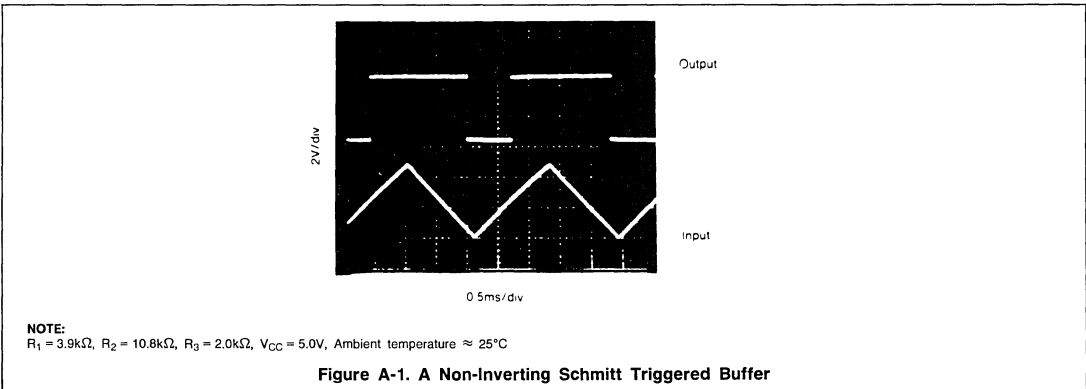


# Schmitt Trigger Using PLS153 and PLS159

AN18



## APPENDIX A



### Application Specific Products

#### DESCRIPTION

A PLS159 is used to implement a pair of dice. Each die is represented by a series of six different state transitions. Two push button switches are used to "roll" the dice; in other words start/stop the state transitions. Each push button controls one die. When the switches are held low, the state transitions take place for each die and the result is displayed when a push button is released.

Each die is made up of seven LED's which are connected to the outputs of the PLS159. The system also contains its own oscillator which generates the clock cycle necessary for the state transitions.

The random release of the push button provides a random output. The high frequency of the internal oscillator and the fact that the switches are not debounced, add more "randomness" to each event.

The overall system configuration is shown in Figure 3.

#### LOGIC IMPLEMENTATION

The configuration of each die is shown in Figure 1, with each letter representing an LED.

To represent the numbers one through six the LED's are turned on as shown in Figure 2.

Table 1 is the truth table generated from Figure 2.

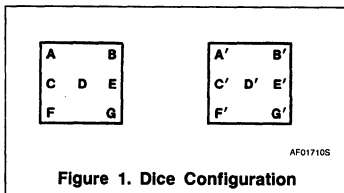


Figure 1. Dice Configuration

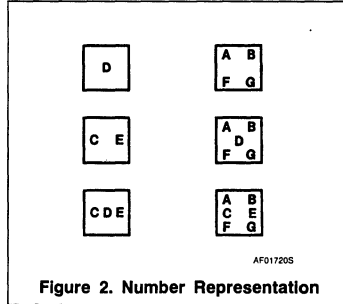


Figure 2. Number Representation

Table 1. Truth Table for Dice

	A	B	C	D	E	F	G
One	0	0	0	1	0	0	0
Two	0	0	1	0	1	0	0
Three	0	0	1	1	1	0	0
Four	1	1	0	0	0	1	1
Five	1	1	0	1	0	1	1
Six	1	1	1	0	1	1	1

The result of Table 1 is the following logic equations:

$$\begin{aligned}
 A &= \text{Four} + \text{Five} + \text{Six}; \\
 B &= \text{Four} + \text{Five} + \text{Six}; \\
 C &= \text{Two} + \text{Three} + \text{Six}; \\
 D &= \text{One} + \text{Three} + \text{Five}; \\
 E &= \text{Two} + \text{Three} + \text{Six}; \\
 F &= \text{Four} + \text{Five} + \text{Six}; \\
 G &= \text{Four} + \text{Five} + \text{Six};
 \end{aligned}$$

As can be seen from the above logic equations:

$$\begin{aligned}
 A &\equiv B \equiv F \equiv G; \\
 C &\equiv E;
 \end{aligned}$$

Table 2 is the result of Table 1 and the above common terms.

Table 2. Truth Table for PLS159 Outputs

	A, B, F, G	C, E	D
One	0	0	1
Two	0	1	0
Three	0	1	1
Four	1	0	0
Five	1	0	1
Six	1	1	0

For each die, three outputs of the PLS159 are needed to implement the logic in Table 2. These outputs are connected to the LED's as follows:

$$\begin{aligned}
 F0: & A, B, F, G; \\
 F1: & C, E; \\
 F2: & D;
 \end{aligned}$$

Similarly for the second die:

$$\begin{aligned}
 F3: & A', B', F', G'; \\
 F4: & C', E'; \\
 F5: & D';
 \end{aligned}$$

# Electronic Dice

# AN19

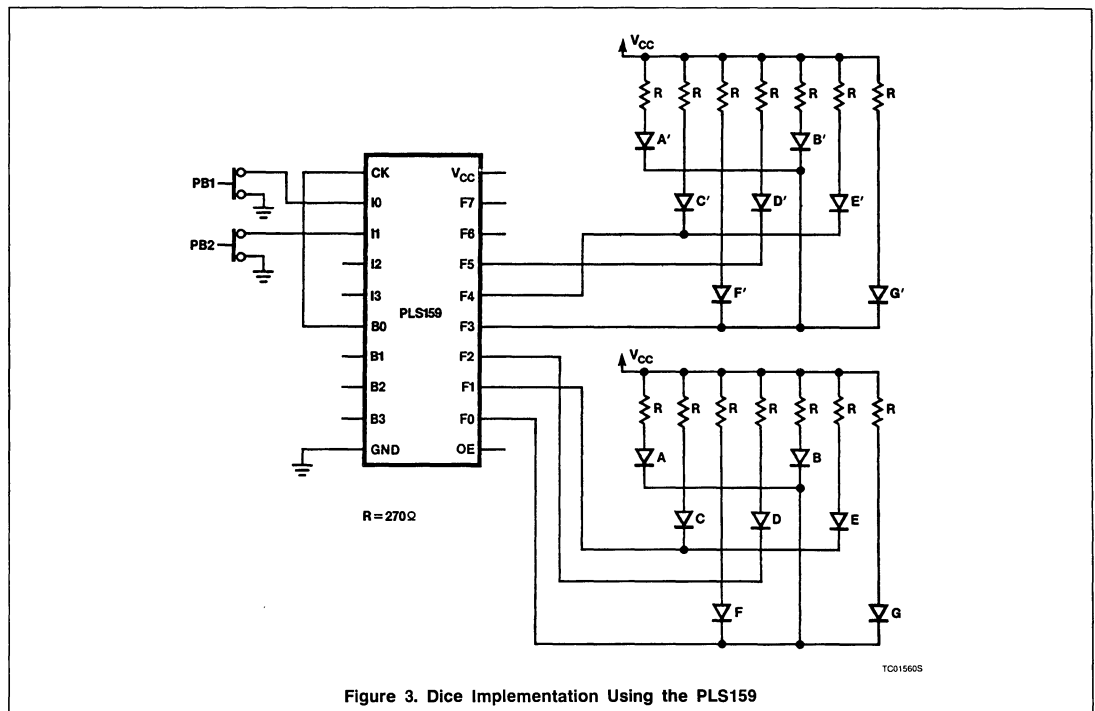


Figure 3. Dice Implementation Using the PLS159

# Electronic Dice

# AN19

### STATE TRANSITIONS

Figure 4 shows two arbitrary state transition sequences which are used to implement each die.

These state transitions are implemented in the program table of the PLS159.

### INTERNAL OSCILLATOR

An internal oscillator is also implemented for the system. The internal configuration of the oscillator is shown in Figure 5. For a detailed explanation of the implementation of this oscillator see AN13: Oscillator with the PLS159. B0 is connected externally to the clock input of the PLS159.

### EXPLANATION OF PROGRAM TABLE

The program table for the two dice is shown in Table 3.

Terms 0 - 5 and 7 - 12 represent the state transitions for each die.

Terms 14 - 15 and 17 - 18 reset the flip-flops to HLL and HLH if undefined states occur, such as during power up.

Terms 20 and 21 and output controls terms D1 and D2 are used to implement the internal oscillator (see AN13).

Inputs I0 and I1 are connected to the two push button switches which roll the dice. These inputs are programmed to be Active-Low. When the push button is closed the state transitions take place, and upon release of the push button, the current states are displayed on the outputs.

The outputs of the PLS159 are inverted and this must be taken into consideration when assigning "H" and "L"'s to the F0, F1, F2, F3, F4, and F5. These assignments are shown in Table 4. All the flip-flops are set to be of the J-K type.

Table 4. H And L Assignment

	F2, F5	F1, F4	F0, F3
One	H	L	L
Two	L	H	L
Three	H	H	L
Four	L	L	H
Five	H	L	H
Six	L	H	H

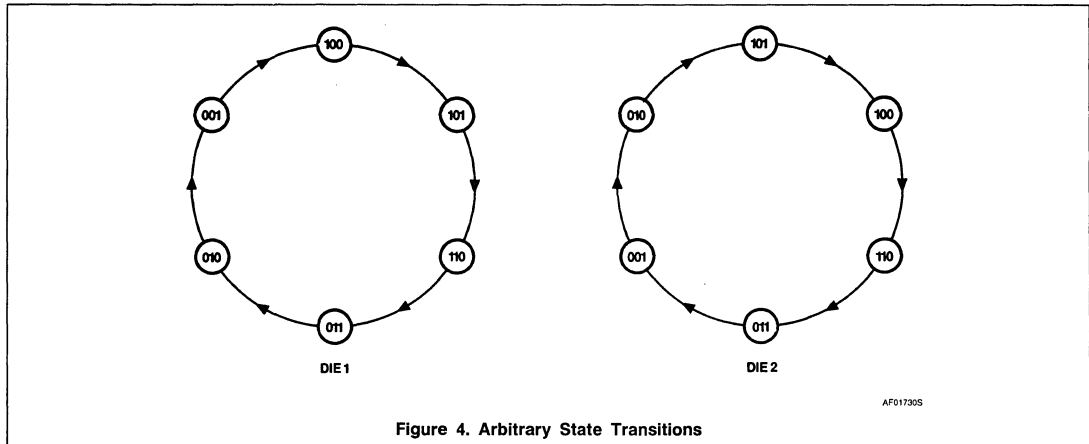


Figure 4. Arbitrary State Transitions

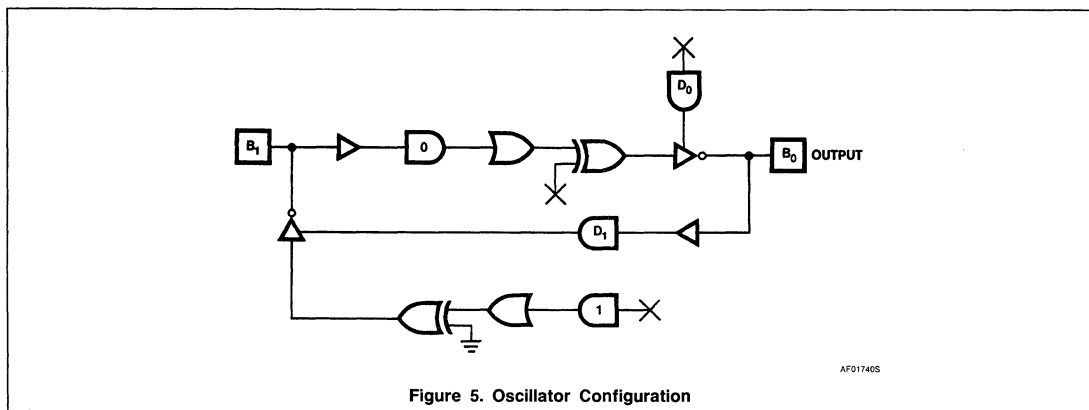


Figure 5. Oscillator Configuration



## AN21 9-Bit Parity Generator/Checker With 82S153/153A

### Application Note

#### Application Specific Products

#### INTRODUCTION

This application note presents the design of a parity generator using Signetics PLD, 82S153 or 82S153A, which enables the designers to customize their circuits in the form of "sum-of-products". The PLA architecture and the 10 bi-directional I/O's make it possible to implement the 9-bit parity generator/checker in one chip without any external wiring between pins. A logic diagram of the device is shown in Appendix A.

The parity of an 8-bit word is generated by counting the number of "1's" in the word. If the number is odd, the word has odd parity. If the number is even, the word has even parity. Thus, a parity generator designed for even parity, for example, will generate a "0" if the parity is even, or a "1" if parity is odd. Conversely, an odd parity generator will generate a "0" if the parity of the word is odd, or a "1" if the parity is even. This bit is then concatenated to the word making it 9-bits

long. When the word is used elsewhere, its parity may be checked for correctness.

#### FEATURES

- Generates even and odd parities (SUM<sub>E</sub> and SUM<sub>O</sub>)
- SUM<sub>E</sub> = "1" for even parity, "0" for odd parity
- SUM<sub>O</sub> = "1" for odd parity, "0" for even parity
- Generate parity or check for parity errors
- Cascaded to expand word length

#### DESCRIPTION

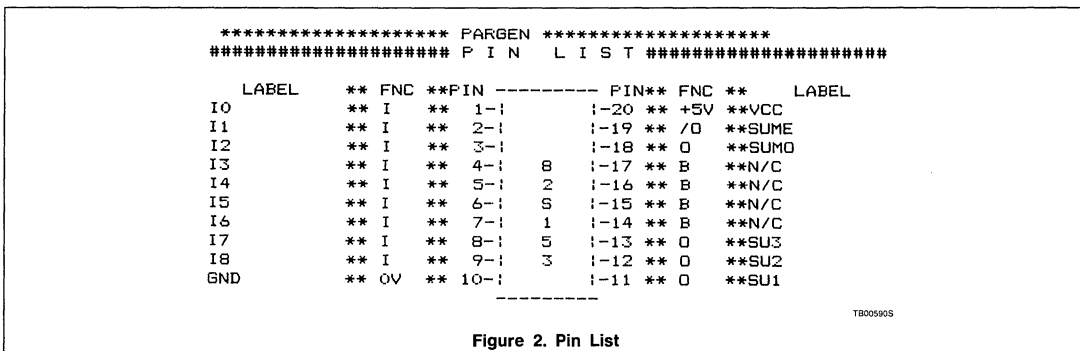
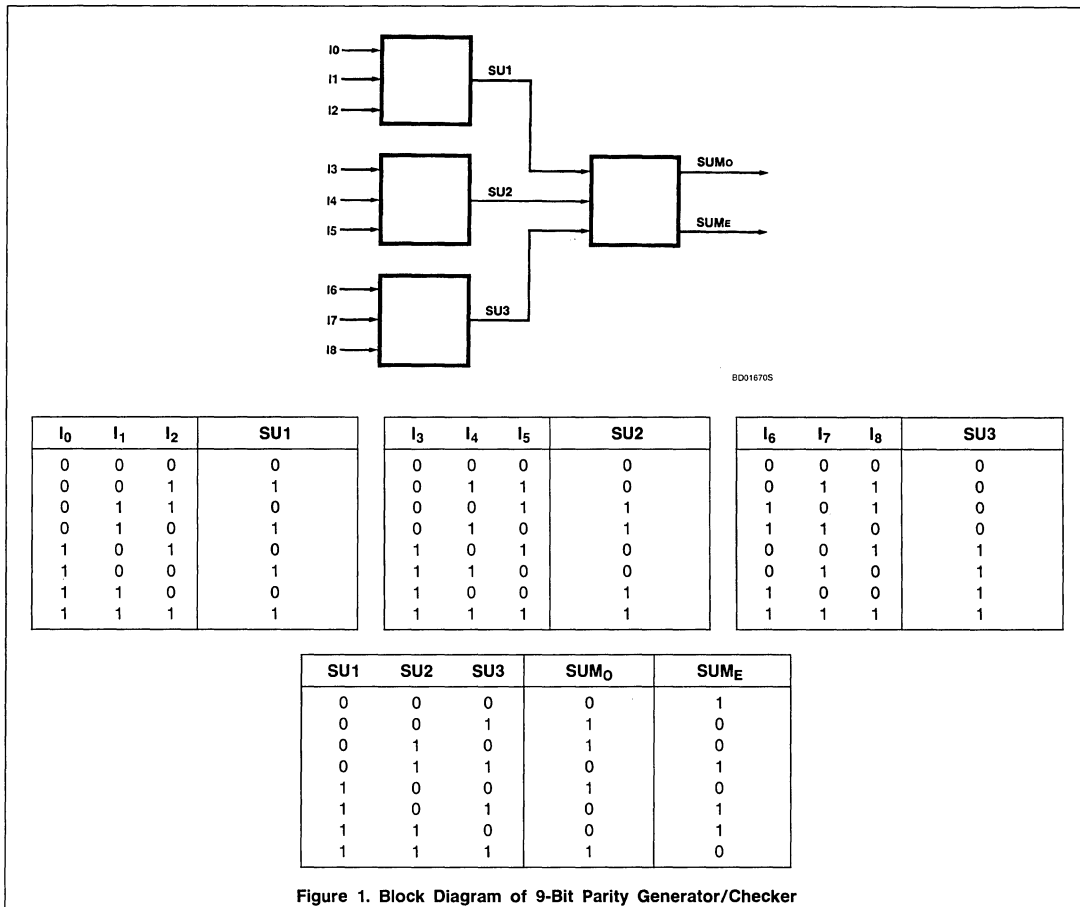
The most straight forward way of implementing the parity generator/checker is to take the 9-input truth table (8 inputs for the 8-bit word, and 1 input for cascading the previous stage) and put it in a 256 × 4 PROM. Since there are 2<sup>9</sup> combinations and half of them is odd,

the other half is even, the circuit will take 256 terms. An alternative is to divide the 9-bits into 3 groups of 3-bits as shown in Figure 1. If the sum of the 3-bits is odd, then the intermediate output SU1, or SU2, or SU3 equals 1. Otherwise it equals 0. The intermediate results are grouped together and SUM<sub>O</sub> becomes "1" if the sum is odd, otherwise SUM<sub>O</sub> equals "0". The circuit is implemented using AMAZE as shown in Figure 3. SU1 is an intermediate output for inputs I<sub>0</sub>, I<sub>1</sub> and I<sub>2</sub>. In the same manner, SU2 and SU3 are intermediate outputs for I<sub>3</sub>, I<sub>4</sub>, I<sub>5</sub> and I<sub>6</sub>, I<sub>7</sub>, I<sub>8</sub>. The design uses up 16 product terms and 5 control terms leaving 16 product terms and 4 bi-directional I/O's to implement other logic designs.

The design is tested by using the logic simulator provided by AMAZE. The input test vector is chosen to exhaustively test for all 8 input combinations at all 4 sections of the circuit.

# 9-Bit Parity Generator/Checker With 82S153/153A

AN21





# 9-Bit Parity Generator/Checker With 82S153/153A

AN21

```

***** PARGEN *****
@DEVICE TYPE
82S153
@DRAWING
***** PARITY GENERATOR/CHECKER
@REVISION
***** REV. -
@DATE
***** xx/xx/xxxx
@SYMBOL
***** FILE ID: PARGEN
@COMPANY
***** SIGNETICS
@NAME
@DESCRIPTION
*****
* This circuit is a 9-bit parity generator/checker commonly used *
* for error detection in high speed data transmission/retrieval. *
* The odd parity output (SUMO) is high when the sum of the data *
* bits is odd. Otherwise it is low. *
* The even parity output (SUME) is high when the sum of the data *
* bits is even. It is low otherwise. *
*****
@COMMON PRODUCT TERM
@I/O DIRECTION
"
*****
* SU1, SU2 and SU3 are outputs which are defined in the PIN LIST *
* and therefore they don't need to be defined here again. *
*****
@OUTPUT POLARITY
"
*****
* The output polarities of different outputs are defined in the *
* PIN LIST. They don't have to be defined again here. *
*****
@LOGIC EQUATION
"
*****
* SU1, SU2, and SU3 are intermediate terms *
*****
TRUTH TABLE
-----
          INPUTS                OUTPUTS
          SU3  SU2  SU1          SUMO   SUME = /SUMO
          18   17   16          SU3
          15   14   13          SU2
          12   11   10          SU1

          0   0   0           0       1
          0   0   1           1       0
          0   1   0           1       0
          0   1   1           0       1
          1   0   0           1       0
          1   0   1           0       1
          1   1   0           0       1
          1   1   1           1       0
"

SU1 = /12 * /11 * I0 + /12 * I1 * /10 +
      I2 * /11 * /10 + I2 * I1 * I0 ;
SU2 = /15 * /14 * I3 + /15 * I4 * /13 +
      I5 * /14 * /13 + I5 * I4 * I3 ;
SU3 = /18 * /17 * I6 + /18 * I7 * /16 +
      I8 * /17 * /16 + I8 * I7 * I6 ;
SUMO = /SU1 * /SU2 * SU3 + /SU1 * SU2 * /SU3 +
        SU1 * /SU2 * /SU3 + SU1 * SU2 * SU3 ;
SUME = /( /SU1 * /SU2 * SU3 + /SU1 * SU2 * /SU3 +
          SU1 * /SU2 * /SU3 + SU1 * SU2 * SU3) ;

```

TB005805

Figure 3. AMAZE Implementation of the Parity Generator/Checker Circuit



## 9-Bit Parity Generator/Checker With 82S153/153A

AN21

```

"
*****
* This is a test pattern for the 9-bit parity generator/checker *
* circuit. The simulator will use this file as an input to *
* simulate the logical function. *
*****

"          SS          EXPECTED
          UU          SSS          OUTPUTS
"IIIIIIII MBBBBBUUI          BBBB
"76543210 E076543218          98321
LLLLLLLLL ///////////////L          "LLLLL
HLHLHLHL ///////////////H          "LHLHL
LHLHLHL ///////////////H          "LHLHL
HHLHLHL ///////////////L          "HLLHH
LLHLHLHL ///////////////H          "LHLHL
HLLHLHL ///////////////L          "HLHLH
LHLHLHL ///////////////L          "HLHLH
HHHHHHH ///////////////H          "LHHHH
QUIT

```

TB006005

## a. Input Pattern PARGEN.TST

```

82S153 A:pargen.STD
" This file is the result of logic simulation of the parity generator/checker
" circuit. The inputs are read from input file PARGEN.TST
"
" INPUTS <=B(I/O)=> TRACE TERMS
" 76543210 9876543210
"
00000000 HL....LLLO ;
10110100 LH....LLH1 ;
01100110 LH....LHL1 ;
11010010 HL....LHH0 ;
00101101 LH....HLL1 ;
10011001 HL....HLH0 ;
01001011 HL....HHLO ;
11111111 LH....HHH1 ;
"
" ----- I/O CONTROL LINES
" 00IIII000I DESIGNATED I/O USAGE
" 00IIII000I ACTUAL I/O USAGE
"
" PIN LIST...
" 08 07 06 05 04 03 02 01 19 18 17 16 15 14 13 12 11 09 ;

```

TB006015

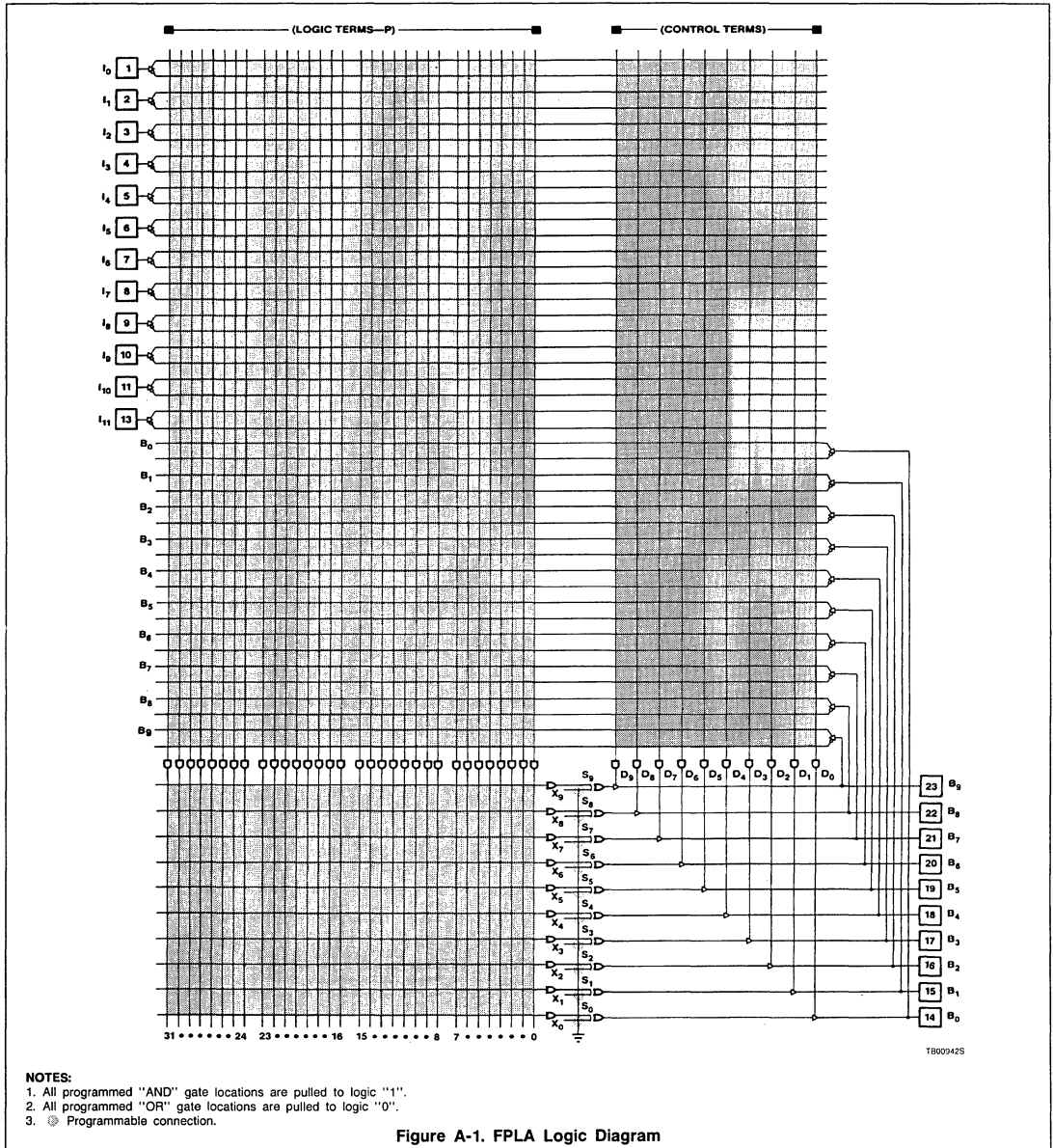
## b. Output File From SIMULATOR

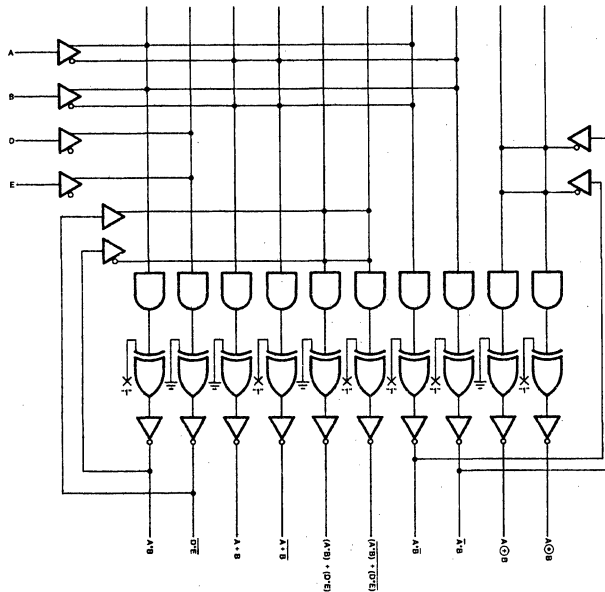
Figure 4. Test Vectors

# 9-Bit Parity Generator/Checker With 82S153/153A

## AN21

### APPENDIX A





BO016805

a. Basic Gates Configuration

\*\*\*\*\* TK151-1 \*\*\*\*\*  
\*\*\*\*\* P I N L I S T \*\*\*\*\*

LABEL	** FNC **	**PIN	-----	PIN**	FNC **	LABEL
A	** I	** 1-:		1-20	** +5V	**VCC
B	** I	** 2-:		1-19	** 0	**A_NDR_B
D	** I	** 3-:		1-18	** /0	**A_OR_B
E	** I	** 4-:	B	1-17	** /0	**D_NAND_E
N/C	** I	** 5-:	2	1-16	** 0	**A_AND_B
N/C	** I	** 6-:	S	1-15	** /0	**AB_OR_DE
N/C	** /B	** 7-:	1	1-14	** 0	**AB_NOR_DE
N/C	** /B	** 8-:	5	1-13	** /0	**A_XOR_B
A-_N_B	** 0	** 9-:	1	1-12	** 0	**A_EGU_B
GND	** 0V	** 10-:		1-11	** 0	**A_N_B-

TB006405

b. Pin List

Figure 1

```

***** TK151-1 *****
@DEVICE TYPE
***** 82S151
@DRAWING
***** FIGURE 1. BASIC GATE CONFIGURATIONS
@REVISION
***** TK151-1 REV. 0
@DATE
***** JULY 10, 1985
@SYMBOL
***** TK151-1
@COMPANY
***** SIGNETICS
@NAME
***** DAVID K. WONG
@DESCRIPTION
This file contains the 6 basic logic gates: AND, NAND, OR, NOR, XOR and EQU.
@COMMON PRODUCT TERM
@I/O DIRECTION
@OUTPUT POLARITY
@I/O STEERING
@LOGIC EQUATION
A_AND_B = A * B ;
D_NAND_E = /( D * E ) ;
A_OR_B = /( /A * /B ) ;
A_NOR_B = /A * /B ;
AB_OR_DE = /( / (A_AND_B) * D_NAND_E ) ;
AB_NOR_DE = /( / (A_AND_B) * D_NAND_E ;
A_N_B = A * /B ;
A-_N_B = /A * B ;
A_XOR_B = /( / (A_N_B-) * / (A-_N_B) ) ; " Equivalent to (A * /B) + (/A * B) "
A_EQU_B = /(A_N_B-) * / (A-_N_B) ; " Equivalent to (/A * /B) + (A * B) "
    
```

TB006305

c. Boolean Equations of Basic Gate Configurations

Figure 1 (Continued)

Table 1. Program Table of Basic Gate Configurations

```

***** TK151-1 *****
Cust/Project - ***** DAVID K. WONG
Date - ***** JULY 10, 1985
Rev/I. D. - ***** TK151-1 REV. 0

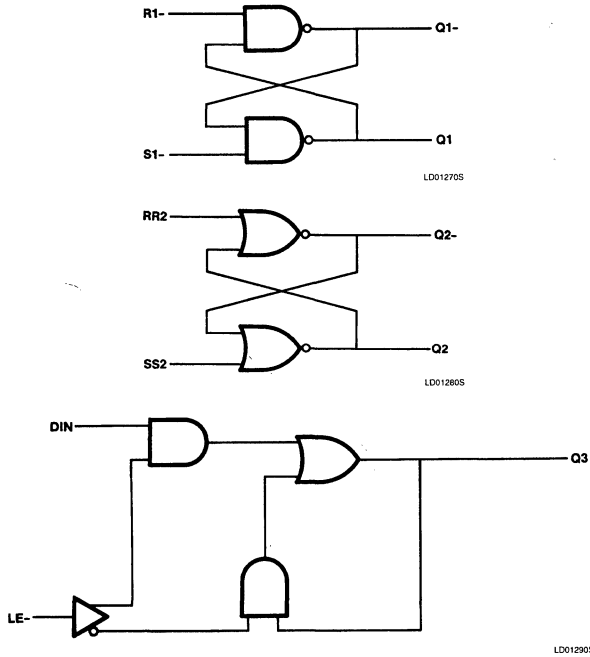
82S151 DIR !A:A:A:A:A:A:A:A:A:A:A:A:A:A:A:A!
T ! PQL !H:L:L:L:H:L:L:H:H:H:L:L!
E !-----!
R ! I ! B(i) !
M !-----!1 1-----!
15.4.3.2.1.0!1.0.9.8.7.6.5.4.3.2.1.0!
0!0 0,0 0 0 0!0 0 0 0,0 0 0 0 0 0 0 0!
1!0 0,0 0 0 0!0 0 0 0,0 0 0 0 0 0 0!
2!-,-,- H L!-,-,-,-,-,-,-,-!
3!-,-,- L H!-,-,-,-,-,-,-,-!
4!-,-,-,-,-,-,-,-,-,-,-,-,-,-!
5!-,-,-,-,-,-,-,-,-,-,-,-,-,-!
6!-,-,-,-,-,-,-,-,-,-,-,-,-,-!
7!-,-,-,-,-,-,-,-,-,-,-,-,-,-!
8!-,-,-,-,-,-,-,-,-,-,-,-,-,-!
9!-,-,-,-,-,-,-,-,-,-,-,-,-,-!
10!-,-,-,-,-,-,-,-,-,-,-,-,-,-!
11!-,-,-,-,-,-,-,-,-,-,-,-,-,-!
D2!-,-,-,-,-,-,-,-,-,-,-,-,-,-!
D1!-,-,-,-,-,-,-,-,-,-,-,-,-,-!
DO!-,-,-,-,-,-,-,-,-,-,-,-,-,-!

N N E D B A A A D A A A A A A A N N
/ / / / / / / / / / / / / / / /
C C N O R A N O N A L X E N C C
O R A N O N O N O Q N
R N D R O R O U B
B D R R B
B B D B B
E E D
E
    
```

TB006805

PLS151 Toolkit

AN22



a. Basic Latches Configuration

\*\*\*\*\* TK151-2 \*\*\*\*\*  
 \*\*\*\*\* P I N L I S T \*\*\*\*\*

LABEL	** FNC	**PIN	-----	PIN**	FNC **	LABEL
R1-	** I	** 1-!		1-20	** +5V	**VCC
S1-	** I	** 2-!		1-19	** /0	**Q1
RR2	** I	** 3-!		1-18	** /0	**Q1-
SS2	** I	** 4-!	8	1-17	** 0	**Q2
DIN	** I	** 5-!	2	1-16	** 0	**Q2-
LE-	** I	** 6-!	S	1-15	** /0	**Q3
N/C	** /B	** 7-!	1	1-14	** 0	**D_N_LE
N/C	** /B	** 8-!	5	1-13	** 0	**Q3_N_LE-
N/C	** /B	** 9-!	1	1-12	** /B	**N/C
GND	** OV	** 10-!		1-11	** /B	**N/C

b. Pin List

Figure 2

```

***** TK151-2 *****
@DEVICE TYPE
@S2S151
@DRAWING
***** FIGURE 2. BASIC LATCHES CONFIGURATION
@REVISION
***** TK151-2 REV. 0
@DATE
***** JULY 10, 1985
@SYMBOL
***** TK151-2
@COMPANY
***** SIGNETICS
@NAME
***** DAVID K. WONG
@DESCRIPTION
This files contains basic configurations of two RS-latches and a D-latch.
@COMMON PRODUCT TERM
@I/O DIRECTION
@OUTPUT POLARITY
@I/O STEERING
@LOGIC EQUATION

" *****
  * CROSS-COUPLED NAND RS-LATCH *
  ***** "
Q1- = /( /R1- * Q1 ) ;
Q1  = /( /S1- * Q1- ) ;

" *****
  * CROSS-COUPLED NOR RS-LATCH *
  ***** "
Q2- = RR2 * Q2 ;
Q2  = SS2 * Q2- ;

" *****
  * D-LATCH *
  ***** "
D_N_LE = DIN * LE- ;
QS_N_LE = QS * /LE- ;
QS      = /( /D_N_LE ) * /( /QS_N_LE- ) ;
    
```

TB006605

c. Boolean Equations of Basic Latches Configuration

Figure 2 (Continued)

Table 2. Program Table of Basic Latches

```

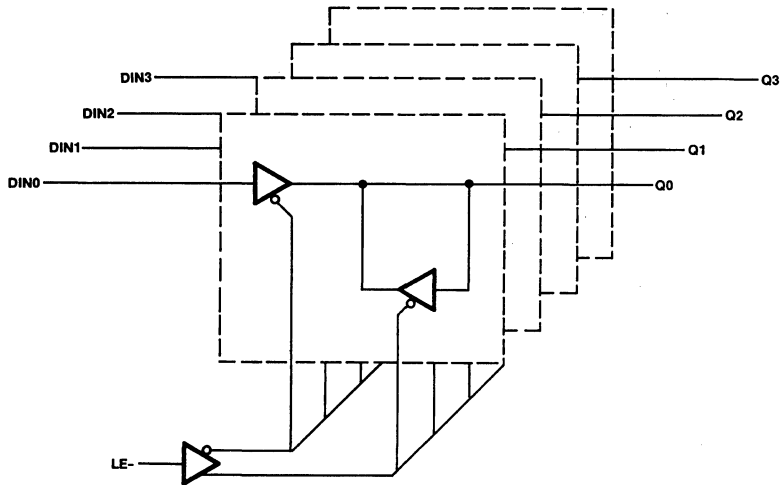
***** TK151-2 *****
Cust/Project - ***** DAVID K. WONG
Data        - ***** JULY 10, 1985
Rev/I. D.   - ***** TK151-2 REV. 0

S2S151  DIR  !A:A:A:A:A:A:A:A:A:A:A:A!
T !      PDL  !L:L:L:H:H:L:L:H:H:L:L:L:L!
E !
R !      I   !      B(1)  !
M -----:1 1-----
15 4 3 2 1 0:1 0 9 8 7 6 5 4 3 2 1 0:
0:0 0,0 0 0 0:0 0 0 0,0 0 0 0 0 0 0 0:
1:0 0,0 0 0 0:0 0 0 0,0 0 0 0 0 0 0 0:
2:0 0,0 0 0 0:0 0 0 0,0 0 0 0 0 0 0 0:
3:0 0,0 0 0 0:0 0 0 0,0 0 0 0 0 0 0 0:
4:0 0,0 0 0 0:0 0 0 0,0 0 0 0 0 0 0 0:
5:L -,- - -!:- -,-,H - -,-,- - -!
6:H H,- - -!:- -,-, - -,-,- - -!
7:-,- - -!:- -,-,L L -,-,- - -!
8:-,-,H - -!:- -,-,H -,-,-,- - -!
9:-,-,H - -!:- -,-,H -,-,-,- - -!
10:-,-, - -!:- -,-,L:H - -,-,-,- - -!
11:-,-, - L -!:- -,-,H -,-,-,- - -!
D2:0 0,0 0 0 0:0 0 0 0,0 0 0 0 0 0 0 0:
D1:-,- - -!:- -,-, - -,-,- - -!
D0:-,- - -!:- -,-, - -,-,- - -!

L D S R S R Q Q Q Q Q D Q N N N N N
E I S R 1 1 1 1 2 2 3 3 / / / / /
- N 2 2 - - - - - N - C C C C C
      L
      E
      L
      E
      -
    
```

TB007105





LD013005

a. 4-Bit D-Latch

```

***** TK151-3 *****
***** P I N   L I S T *****

```

LABEL	** FNC	**PIN	-----	PIN**	FNC **	LABEL
DIN0	** I	** 1-	1	1-20	** +5V	**VCC
DIN1	** I	** 2-	1	1-19	** B	**Q0
DIN2	** I	** 3-	1	1-18	** B	**Q1
DIN3	** I	** 4-	8	1-17	** B	**Q2
LE-	** I	** 5-	2	1-16	** B	**Q3
N/C	** I	** 6-	S	1-15	** B	**FB0
N/C	** /B	** 7-	1	1-14	** B	**FB1
N/C	** /B	** 8-	5	1-13	** B	**FB2
N/C	** /B	** 9-	1	1-12	** B	**FB3
GND	** OV	** 10-	1	1-11	** /B	**N/C

TB007005

b. Pin List

Figure 3

```

***** TK151-3 *****
@DEVICE TYPE
82S151
@DRAWING
***** FIGURE 3. 4 BIT D-LATCH
@REVISION
***** TK151-3 REV. 0
@DATE
***** JULY 10, 1985
@SYMBOL
***** TK151-3
@COMPANY
***** SIGNETICS
@NAME
***** DAVID K. WONG
@DESCRIPTION
This file contains a 4-bit D-latch. External jumper is required for each latch
between Qn and FBn. When LE- is HIGH, outputs Q0, Q1, Q2, and Q3 are active and
outputs FBO, FB1, FB2, and FB3 are tri-stated. Qn, therefore, equals Dn when
LE- is HIGH. When LE- becomes LOW, Q outputs are tri-stated, and FB outputs are
active. Since FB outputs feedback to their own inputs, they are latched to
whatever level the Q outputs were in when LE- goes from HIGH to LOW.
@COMMON PRODUCT TERM
@I/O DIRECTION
D0 = / ( /LE- ) ;
D1 = / ( LE- ) ;
@OUTPUT POLARITY
@I/O STEERING
@LOGIC EQUATION
Q0 = DINO ;
Q1 = DIN1 ;
Q2 = DIN2 ;
Q3 = DIN3 ;
FBO = Q0 ;
FB1 = Q1 ;
FB2 = Q2 ;
FB3 = Q3 ;
    
```

TB00695S

c. Boolean Equations of 4-Bit D-Latch

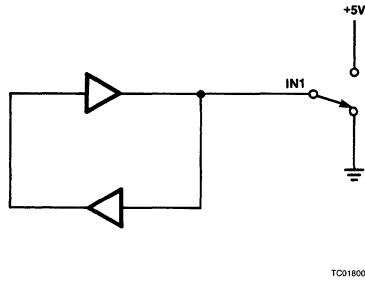
Figure 3 (Continued)

Table 3. Program Table of 4-Bit D-Latch

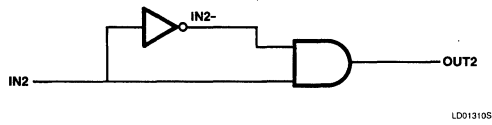
```

***** TK151-3 *****
Cust/Project - ***** DAVID K. WONG
Date - ***** JULY 10, 1985
Rev/I. D. - ***** TK151-3 REV. 0
-----
82S151 DIR !A:A:A:A:A:A:A:A:A:A!
T ! POL !H:H:H:H:H:H:H:H:L:L:L:L!
E !-----!
R ! I ! B(i) !
M !-----! 1 1
!5_4_3_2_1_0!1_0_9_8_7_6_5_4_3_2_1_0!
0!0 0,0 0 0 0!0 0 0 0,0 0 0 0,0 0 0 0!
1!0 0,0 0 0 0!0 0 0 0,0 0 0 0,0 0 0 0!
2!0 0,0 0 0 0!0 0 0 0,0 0 0 0,0 0 0 0!
3!0 0,0 0 0 0!0 0 0 0,0 0 0 0,0 0 0 0!
4! - - - - -! - H - - - - -!
5! - - - - -! - H - - - - -!
6! - - - - -! - H - - - - -!
7! - - - - -! - H - - - - -!
8! - - - - -! - H - - - - -!
9! - - - - -! - H - - - - -!
10! - - - - -! - H - - - - -!
11! - - - - -! - H - - - - -!
D2!0 0,0 0 0 0!0 0 0 0,0 0 0,0 0 0 0!
D1! - H - - - - -! - - - - -!
DO! - L - - - - -! - - - - -!
-----
N L D D D D Q Q Q Q F F F N N N N
/ E I I I I 0 1 2 3 B B B B / / /
C - N N N N 0 1 2 3 C C C C
3 2 1 0
    
```

TB00746S



Switch Debouncer



Pulse Shaper

a. Single Pin Switch Debouncer and Pulse Shaper

```

***** TK151-4 *****
***** P I N   L I S T *****

```

LABEL	** FNC	**PIN	-----	PIN** FNC	** LABEL
IN2	** I	** 1-		!-20 ** +5V	**VCC
N/C	** I	** 2-		!-19 ** 0	**IN1
N/C	** I	** 3-		!-18 ** /0	**IN2-
N/C	** I	** 4-	8	!-17 ** 0	**OUT2
N/C	** I	** 5-	2	!-16 ** /B	**N/C
N/C	** I	** 6-	S	!-15 ** /B	**N/C
N/C	** /B	** 7-	1	!-14 ** /B	**N/C
N/C	** /B	** 8-	S	!-13 ** /B	**N/C
N/C	** /B	** 9-	1	!-12 ** /B	**N/C
GND	** OV	** 10-		!-11 ** /B	**N/C

T800730S

b. Pin List

Figure 4

```

***** TK151-4 *****
@DEVICE TYPE
S2S151
@DRAWING
***** PLS151 TOOLKIT FIGURE 4
@REVISION
***** tk151-4 REV. 0
@DATE
***** JULY 10, 1985
@SYMBOL
***** TK151-4
@COMPANY
***** SIGNETICS
@NAME
***** DAVID K. WONG
@DESCRIPTION
This file contains a single pin debouncer and a pulse shaper.
@COMMON PRODUCT TERM
@I/O DIRECTION
@OUTPUT POLARITY
@I/O STEERING
@LOGIC EQUATION
" *****
 * DEBOUNCER -- This circuit uses one bidirectional pin to de- *
 * bounce a single pole double throw switch. When *
 * the switch is thrown to its opposit polarity, *
 * it shorts the output to Vcc or ground. One pro- *
 * pagation delay later, the output is switched to *
 * the same polarity as the switch. *
 ***** "
IN1 = IN1 ;

" *****
 * PULSE SHAPER -- This circuit creates a LOW-to-HGH glitch *
 * which has the pulse width of one prop delay. *
 * Wider pulse width may be generated with add- *
 * itional feedback loops. *
 ***** "
IN2 = /( IN2 ) ;
OUT2 = IN2 - * IN2 ;
    
```

TB007205

c. Boolean Equations of Single Pin and Pulse Shaper  
Figure 4 (Continued)

Table 4. Program Table of Single Pin Debouncer and Shaper

```

***** TK151-4 *****
Cust/Project - ***** DAVID K. WONG
Date        - ***** JULY 10, 1985
Rev/I. D.   - ***** tk151-4 REV. 0

S2S151  DIR  !A:A:A:A:A:A:A:A:A:A:A:A:A:A!
-----
T !      PQL  !H:L:H:L:L:L:L:L:L:L:L:L!
E !-----
R !      I    !      B(i)
H !-----
!5.4.3.2.1.0!1.0.9.8.7.6.5.4.3.2.1.0!
-----
0!0 0,0 0 0!0!0 0 0,0 0 0,0 0 0,0 0 0!
1!0 0,0 0 0!0!0 0 0,0 0 0,0 0 0,0 0 0!
2!0 0,0 0 0!0!0 0 0,0 0 0,0 0 0,0 0 0!
3!0 0,0 0 0!0!0 0 0,0 0 0,0 0 0,0 0 0!
4!0 0,0 0 0!0!0 0 0,0 0 0,0 0 0,0 0 0!
5!0 0,0 0 0!0!0 0 0,0 0 0,0 0 0,0 0 0!
6!0 0,0 0 0!0!0 0 0,0 0 0,0 0 0,0 0 0!
7!0 0,0 0 0!0!0 0 0,0 0 0,0 0 0,0 0 0!
8!0 0,0 0 0!0!0 0 0,0 0 0,0 0 0,0 0 0!
9!- , - - - H!- H - - , - - - , - - -!
10!- , - - - H!- H - - , - - - , - - -!
11!- , - - - !H - - , - - - , - - -!
D2!0 0,0 0 0!0!0 0 0,0 0 0,0 0 0,0 0 0!
D1!0 0,0 0 0!0!0 0 0,0 0 0,0 0 0,0 0 0!
DO!- , - - - !- - - , - - - , - - -!

N N N N I I I O N N N N N N N N N
/ / / / N N N U / / / / / / / /
C C C C C 2 1 2 T C C C C C C C C C
- 2
    
```

TB006505

## Application Specific Products

### INTRODUCTION

THE PLS168/168A is a bipolar Field-Programmable Logic Sequencer as shown in Figure 1, which consists of 12 inputs, a 48 product term PLA and 14 R/S flip-flops. Out of the 14 flip-flops, six are buried State Registers ( $P_4 - P_9$ ), four Output Registers ( $F_0 - F_3$ ), and four Dual-purpose Registers ( $P_0 - P_3$ ), which may be used as Output or State Registers. All flip-flops are positive edge-triggered. They are preset to "1" at power-up, or may be asynchronously set to "1" by an optional PR/OE pin, which may be programmed either as a preset pin or as an Output Enable pin. Additional features includes the Complement Array and diagnostics features.

### ARCHITECTURE

As shown in Figure 2, the device is organized as a decoding AND-OR network which drives a set of registers some of which, in turn, feedbacks to the AND/OR decoder while the rest serve as outputs. Outputs  $P_0$  to  $P_3$  may be programmed to feedback to the AND/OR decoder as State Registers and, at the same time, used as outputs. The user now can design a 10-bit state machine without external wiring. The AND/OR array is the classical PLA structure in which the outputs of all the AND gates can be programmed to drive all

the OR gates. The schematic diagram of the AND-OR array is shown in Figure 3. This structure provides the user a very structured design methodology which can be automated by CAD tools, such as Signetics AMAZE software package. The output of the PLA is in the form of sum-of-products which, together with the RS flip-flops, is the ideal structure for implementation of state machines. (Refer to Appendix A for a brief description of synchronous finite state machines.)

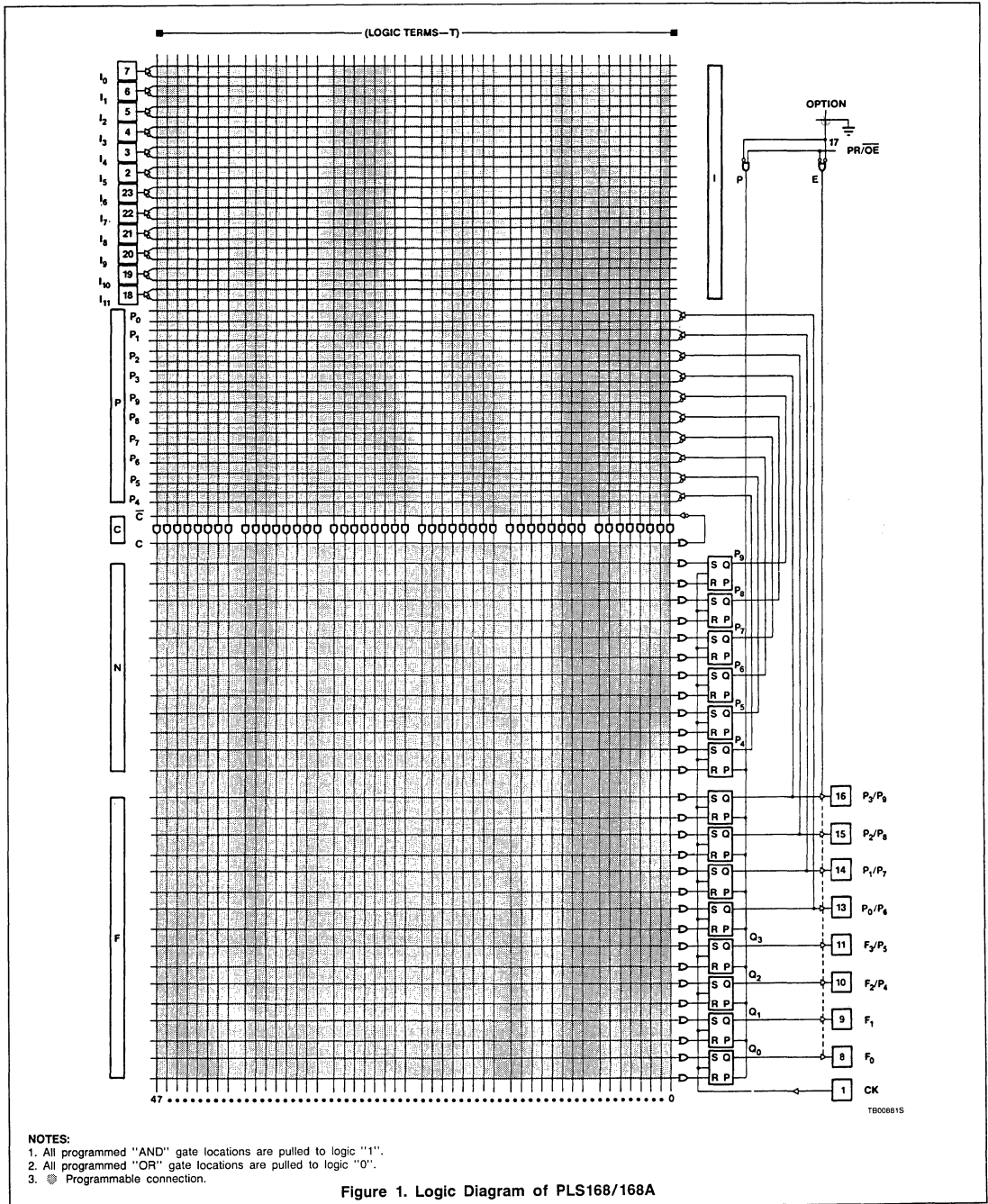
### Design Tools

A direct approach to implement a design using the PLS168/168A is the H/L table supplied in the data sheet as shown in Table 1. The table is organized according to input and output of the PLA decoding network. The lefthand side of the table represent the inputs to the AND-array, which includes input from input pins and present state information from the feedback buffers which feedback the contents of the State Register. The righthand side of the table represents the output of the OR-array, which drives the State and Output Registers as the next state and output. Each column in the lefthand side of the table represents an input buffer, which may be inverting, non-inverting, disconnected or unprogrammed. Each column in the righthand side of the table represents a pair of outputs to the flip-flops, which may be set, reset,

disconnected, or unprogrammed. The programming symbols are H, L, -, and 0. (See Figure 4 for details.) For inputs buffers, "H" means that the non-inverting buffer is connected, "L" means that the inverting buffer is connected, "-" means that both inverting and non-inverting buffers are disconnected, and "0" means that both inverting and non-inverting buffers are connected which causes that particular AND-term to be unconditionally Low. On the output side of the table, "H" means that the particular AND-term is connected to the OR-term on the "S" input of the particular flip-flop, "L" means that the AND-term is connected to the "R" side, "-" means that the AND-term is not connected to the flip-flop at all, and "0" means that the AND-term is connected to both the "S" and "R" sides. More details of the symbols and their meanings are shown in Appendix B. Each row in the table represents an AND-term. There are 48 AND-terms in the device. Therefore, there are 48 rows in the table. An example of implementing a transition from one state to another is shown in Figure 4a. The state diagram can be implemented by the PLS168 as shown in Figure 4b. The state diagram is translated into H/L format as shown in Figure 4c. The first column on the lefthand side of the table is for the Complement Array which will be discussed in detail in the next section.

PLS168/168A Primer

AN23





PLS168/168A Primer

AN23

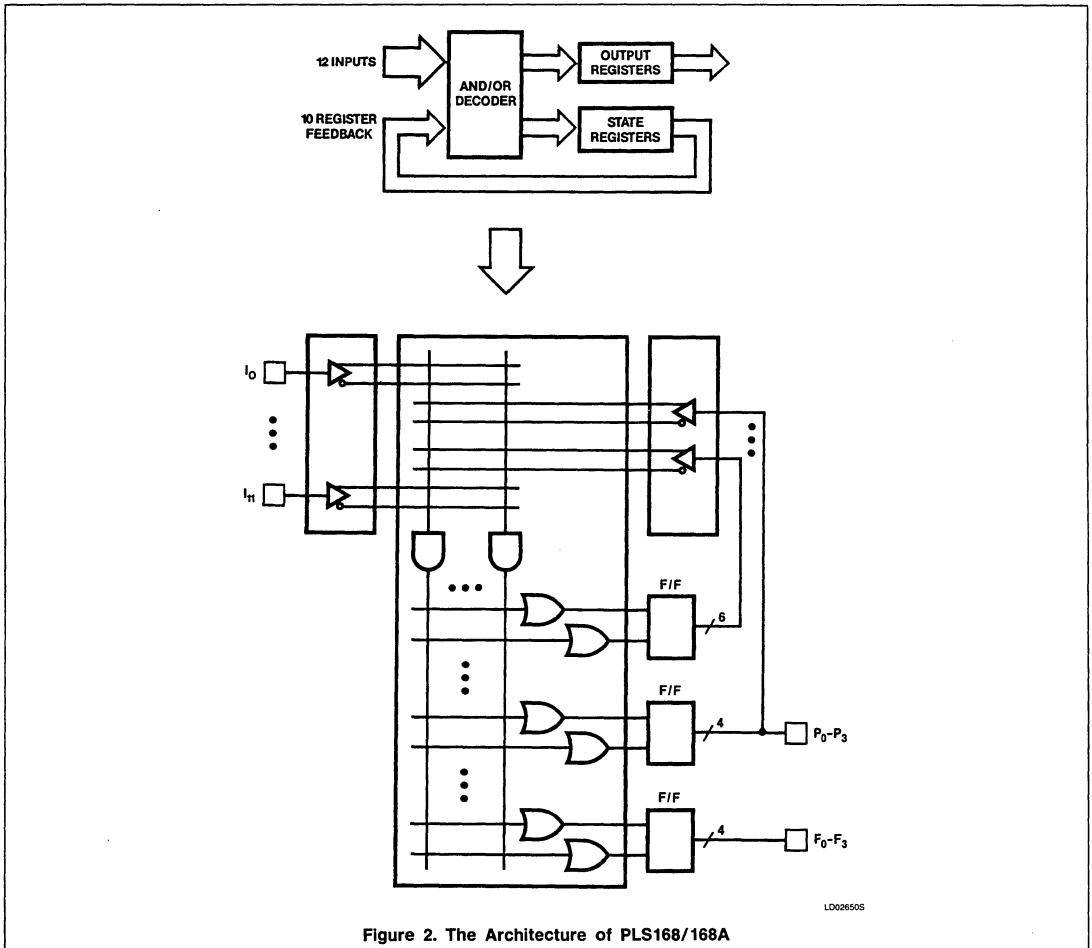


Figure 2. The Architecture of PLS168/168A



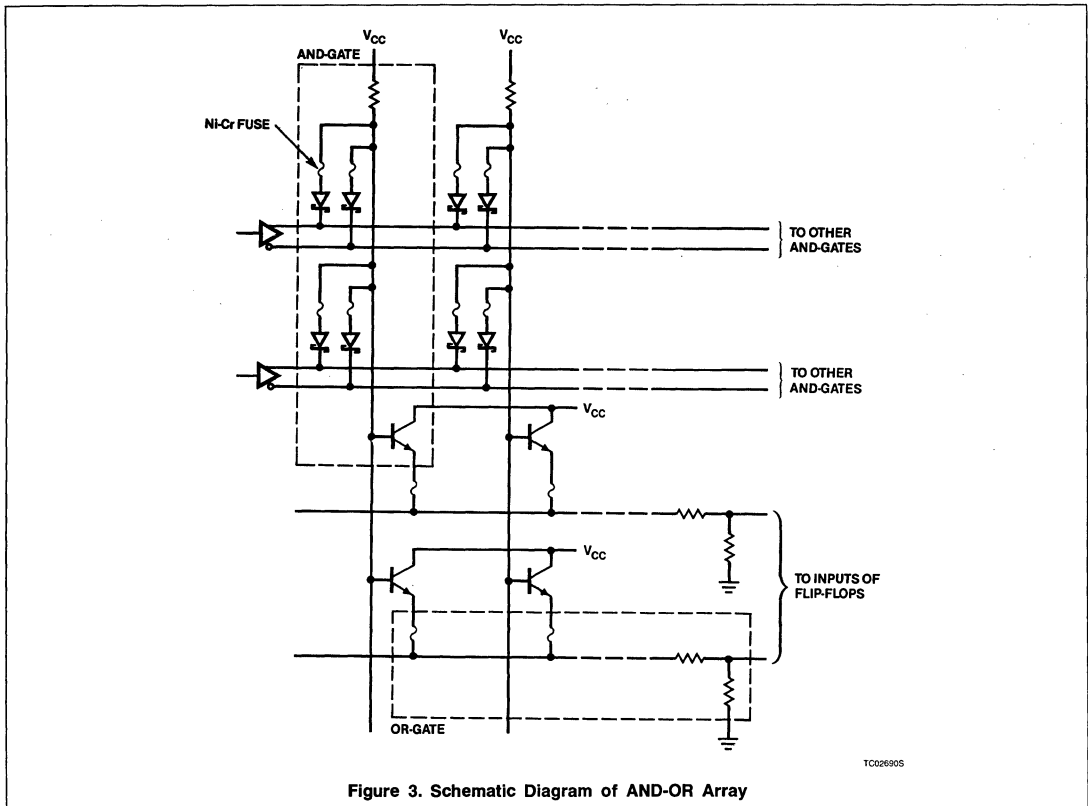
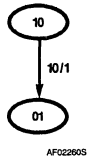


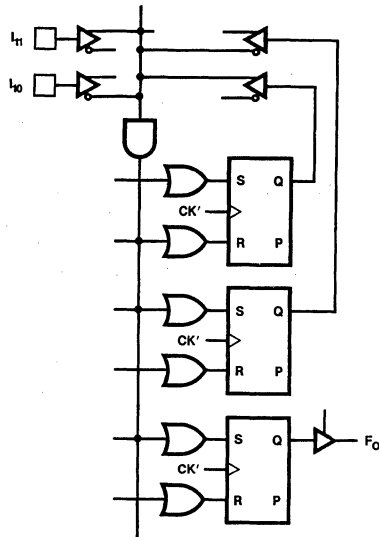
Figure 3. Schematic Diagram of AND-OR Array

PLS168/168A Primer

AN23



a. State Diagram



LS050405

b. Implementation of State Diagram (a) With PLS168

TERM	AND														OPTION (PR/OE)																																										
	C	INPUT							PRESENT STATE							NEXT STATE							OUTPUT																																		
		1	1	0	9	8	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	1	0	3	2	1	0																			
00	-	H	L	-	-	-	-	-	-	-	-	-	-	-	-	-	H	L	-	-	-	-	-	-	-	-	-	-	L	H	-	-	-	-	H	-	-	-																			
01																																																									
PIN NO.	1	1	2	2	2	2	2	3	4	5	6	7																								1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1			
NAME	IN1	IN0																																				OUT0																			

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c. PLS168 Programming Table

Figure 4. Implementing State Machine with PLS168

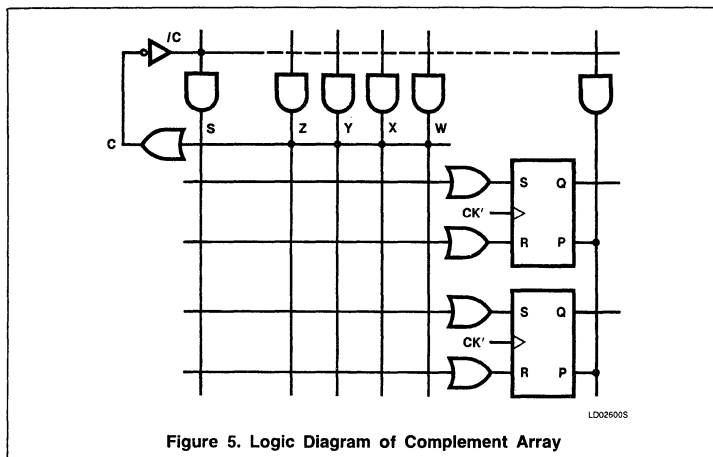


Figure 5. Logic Diagram of Complement Array

**Complement Array**

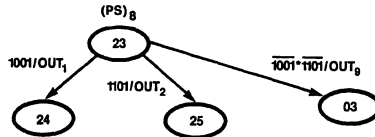
An additional feature is the Complement Array, which is often used to provide escape vectors in case the state machines get into undefined states during power-up or a timing violation due to asynchronous inputs. A logic diagram of the Complement Array is shown in Figure 5. The output of the Complement Array is normally Low when one or more AND-terms are High. If all of the AND-terms are Low, then the output of the Complement

Array will be High. In this example, if each AND-term is a decoder for a particular state and input combination, and if the circuit gets into an undefined state, none of the AND-terms will be High. Therefore, the output /C will be High, which will then enable the AND-term S which in turn may be used to reset all registers to Low or High as predefined. The state machine thus escapes from being in an undefined state by using the Complement Array and one AND-term. Without the Complement Array an alternate way of escaping

from being in an undefined state is by defining all possible states which are not being defined. This method may require quite a few AND-terms depending on the design. Another application for the Complement Array is illustrated by the following example. As shown in Figure 6, when the machine is in state 23, if input vector equals 1001, it will go to next state 24. If the input is 1101, then go to state 25. But if the input is neither 1001 nor 1101, then go to state 03. It takes only two terms to implement the first two transition vectors. To implement the third vector "go to state 03 if input is neither 1001 nor 1101", the Complement Array accepts the outputs of the first two AND-terms as inputs. If the input vector is neither 1001 nor 1101, then both terms will be Low, which causes the output of the Complement Array (/C) to be High. A third AND-term is used to AND state 24 and /C together to set the registers to state 03. The State Diagram is translated into AMAZE syntax as shown in Figure 6b, where all vectors are in square brackets and the Complement Array is represented by the ELSE statement. The State diagram Figure 6a can also be expressed in the format of a program table as shown in Figure 6c. The complement array may be used to exit from different present states to different next states. It can be used many times in one state machine design as shown in Figures 7a, b, and c where the state diagram is implemented using the AMAZE state equation syntax and the H/L format.

PLS168/168A Primer

AN23



NOTE:  $\overline{1001} * \overline{1101} = \overline{1001 + 1101}$

AF022415

a. State Diagram

WHILE [23]  
 IF [1001] THEN [24] WITH  
 [OUT1]  
 IF [1101] THEN [25] WITH  
 [OUT2]  
 ELSE: [03] WITH [OUT9]

b. AMAZE State Equation Syntax

T E R M	AND														OPTION (PR/OE)														
	C	INPUT							PRESENT STATE							NEXT STATE							OUTPUT						
		1	1	0	9	8	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	1	0	3	2	1	0	
00	A	H	L	L	H	-	-	-	-	-	-	-	-	H	L	L	L	H	H	-	-	H	L	L	H	L	L	H	
01	A	H	H	L	H	-	-	-	-	-	-	-	-	H	L	L	L	H	H	-	-	H	L	L	H	L	L	H	
02	•	-	-	-	-	-	-	-	-	-	-	-	-	H	L	L	L	H	H	-	-	L	L	L	L	H	H	-	
03																													
04																													
05																													
PIN NO.	1	1	1	2	2	2	2	2	3	2	3	4	5	6	7							1	1	1	1	1	1	1	
	8	9	0	1	2	3	2	3	4	5	6	7										6	5	4	3	1	0	9	8
N A M E	IN3	IN2	IN1	IN0																						OP3	OP2	OP1	OP0

COMPLEMENT ARRAY

PRESENT STATE = 23 (HEX)

NEXT STATE: 24 (HEX) / 25 (HEX) / 03 (HEX)

OUT1 = 0001  
 OUT2 = 0010  
 OUTG = 1001

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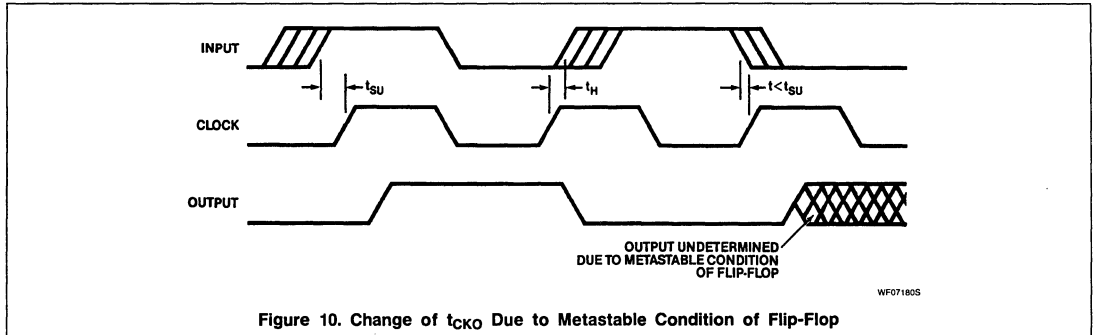
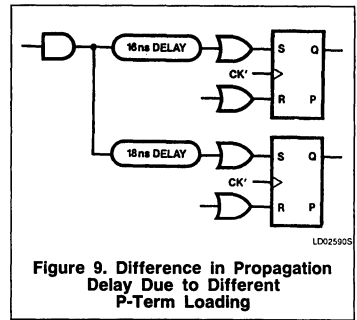
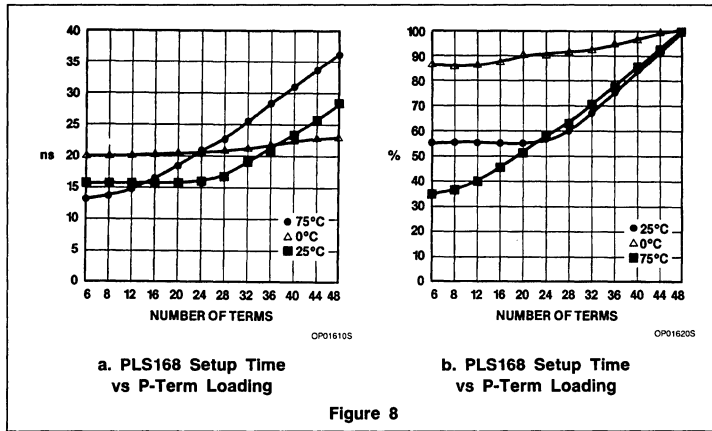
c. H/L Format

Figure 6. Application of Complement Array



# PLS168/168A Primer

# AN23



## PLS168/168A Primer

## AN23

### Optional Preset/Output Enable

The PR/OE pin provides the user with the option of either using that pin to control the Tri-state output buffers of the Output Registers, or have that pin to asynchronously preset all registers to High. The purpose of the preset function is to provide the system a way to set the PLS168 to a known state, all Highs. The output enable function are sometimes used where the state machine is connected to a bus which is shared by other output circuits. It is also used during power-up sequence to keep the PLS168 from sending power glitches to other circuits which it drives. By programming the PR/OE pin to control the Tri-state output buffers, the preset function is permanently disabled. By programming the PR/OE pin to control the asynchronous preset of the registers, the output buffers are permanently enabled. While using the preset function to asynchronously preset the register, if a rising edge of the clock occurs while the preset input is High, the registers will remain preset. Normal flip-flop operation will resume only after the preset input is Low and the rising edge of the next clock. Setting the registers to a predefined pattern other than all Highs may be accomplished by using a dedicated p-term, which is activated by an input pin which will also inhibit all other p-terms which are being used. The inhibiting of other p-terms eliminates the problem of undetermined state of an RS flip-flop caused by having Highs on both R and S inputs.

### Diagnostic Features

In debugging a state machine, sometimes it is necessary to know what is the content of the state register. The buried State Register may be read by applying +10V on I<sub>0</sub>, which will cause the contents of register bits P<sub>4</sub> to P<sub>5</sub>, P<sub>6</sub> to P<sub>9</sub> to be displayed on output pins F<sub>2</sub> to F<sub>3</sub> and P<sub>0</sub> and P<sub>3</sub> respectively. While the device can handle the +10V on pin I<sub>0</sub>, prolonged and continuous use will cause the chip to heat up since more power is being dissipated at +10V. To facilitate more expedient functional tests, synchronous preset vectors as described above may be used to set the State Register to different states without having to go through the entire sequence.

### Timing Requirements

Since the PLS168 is intended to be a synchronous finite state machine, the inputs are expected to be synchronous to the clock and set-up and hold time requirements are expected to be met. In general, the set-up time requirement is measured at its worst case as having the entire AND-array connected to the OR-term being measured and there is only one active AND-term to drive the entire line. The set-up time decreases from there as less p-terms are used. This is due to the capacitance of the unused AND-terms being removed from the line. Figure 8a shows the typical set-up time requirement of a PLS168A device. Figure 8b shows the normalized set-up time as a percentage of the worst case,

which is with 48 terms connected. In a typical state machine design, some flip-flops will change states more frequently than others. Those that change more frequently will have more p-term loading on its OR gates than those that change states less frequently. The different loadings on the OR-terms cause different delay on the inputs of the flip-flops as shown in Figure 9. If an input fails to meet the set-up time specification, it is possible that the resultant of the input change gets to one set of flip-flops before the rising edge of the clock while it gets to other flip-flops during or after the clock's rising edge. The result is that some flip-flops have changed states and some have not, or some get into metastable condition as shown in Figure 10. The state machine is now either out of sequence or is in an undefined state. This problem often occurs with asynchronous inputs which is generated totally independent of the clock on the system. A common remedy for the problem of asynchronous inputs is to use latches or flip-flops to catch the input and then synchronously feed it to the state machine. This minimizes the problem with the different propagation delays due to different p-term loading. But there is still a finite probability that the external latches or flip-flops will get into metastable condition, which may be propagated into the state machine. Nevertheless, the window for the flip-flops in state machine to get into undefined states or metastable condition is narrowed by a great extent.

# PLS168/168A Primer

# AN23

## APPENDIX A

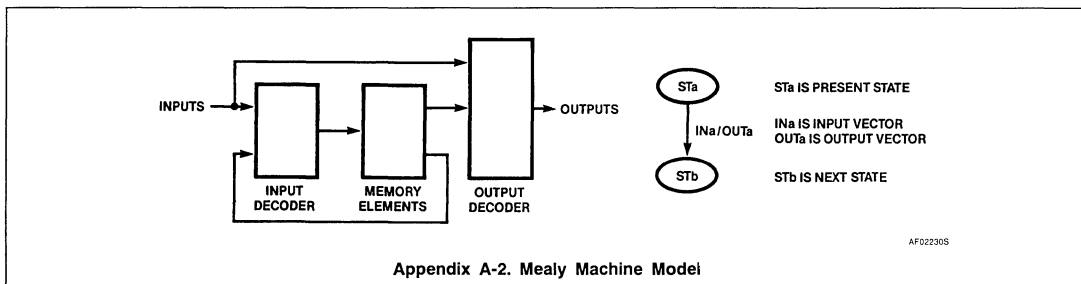
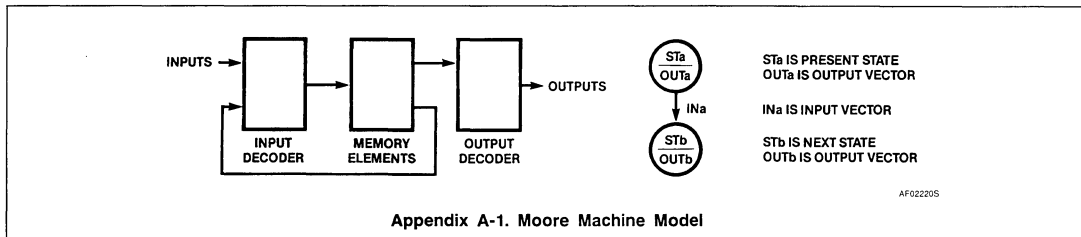
### INTRODUCTION TO STATE MACHINE

A state machine is a synchronous sequential circuit which interprets inputs and generates outputs in accordance with a predetermined logic sequence. It is analogous to running a computer program with a computer. The state machine, with its sequence coded in hard-

ware, can run much faster than a computer running the sequence in software. Therefore, it is often used in controller applications where speed is important.

Generally, state machines may be classified as Mealy or Moore machines as shown in Figures 1a and 1b. The fundamental difference of the two types are: the output of a Moore machine is a dependent of only the

state of the memory elements whereas the output of a Mealy machine is a dependent of both the state of the memory elements and the inputs to the state machine. The figures also show graphic representations of the logic sequence in the form of state diagram in which the bubbles represent state vectors, and the arrows represent transitions from present states to next states.





# PLS168/168A Primer

# AN23

## APPENDIX B

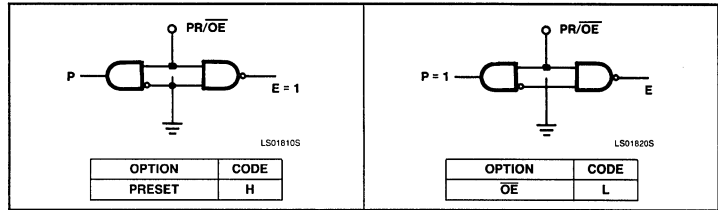
### LOGIC PROGRAMMING

The FPLS can be programmed by means of Logic programming equipment.

With Logic programming, the AND/OR gate input connections necessary to implement the desired logic function are coded directly from the State Diagram using the Program Table on the following page.

In this table, the logic state or action of control variables C, I, P, N, and F, associated with each Transition Term  $T_n$ , is assigned a symbol which results in the proper fusing pattern of corresponding link pairs, defined as follows:

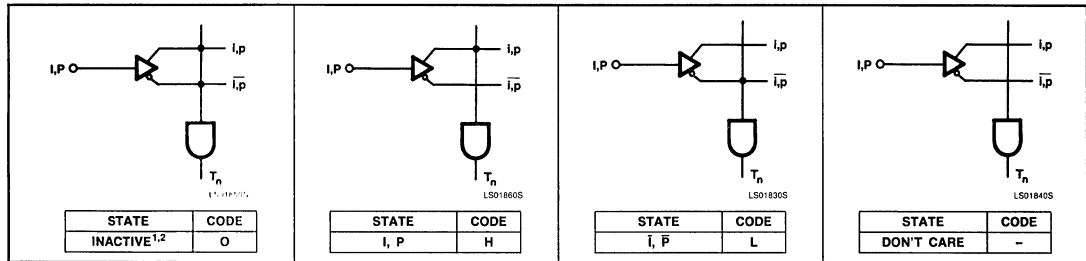
### PRESET/OE OPTION - (P/E)



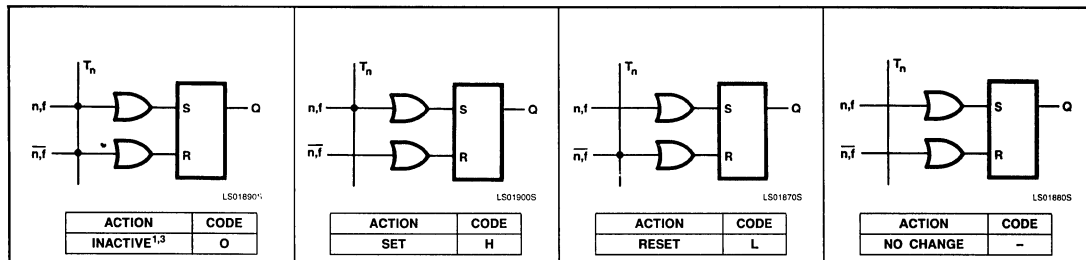
#### PROGRAMMING:

The PLS168A has a power-up preset feature. This feature insures that the device will power-up in a known state with all register elements (state and output register) at a logic high (H). When programming the device it is important to realize this is the initial state of the device. You *must* provide a next state jump if you do not wish to use all highs (H) as the present state.

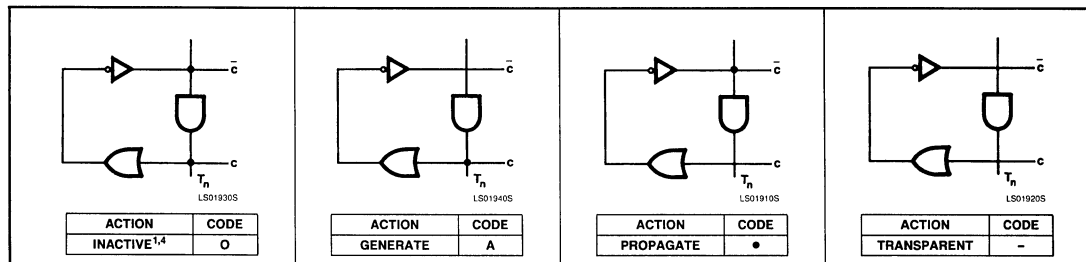
### "AND" ARRAY - (I), (P)



### "OR" ARRAY - (N), (F)



### "COMPLEMENT" ARRAY - (C)



#### NOTES:

1. This is the initial unprogrammed state of all link pairs. It is normally associated with all unused (inactive) AND gates  $T_n$ .
2. Any gate  $T_n$  will be unconditionally inhibited if any one of its I or P link pairs is left intact.
3. To prevent simultaneous Set and Reset flip-flop commands, this state is not allowed for N and F link pairs coupled to active gates  $T_n$  (see flip-flop truth tables).
4. To prevent oscillations, this state is not allowed for C link pairs coupled to active gates  $T_n$ .

# AN24 PLS173 as a 10-Bit Comparator, 74LS460

## Application Note

### Application Specific Products

#### DESCRIPTION

The PLS173 is a 24-pin PLA device which has 10 bidirectional outputs and 12 dedicated inputs. The output of the device is the sum of products of the inputs. The polarity of each output may be individually programmed as Active-High or Active-Low. A logic diagram of the device is shown in Appendix A. A 10-bit comparator similar to the 74LS460 compares two 10-bit data inputs to establish if EQUIVALENCE or NOT EQUIVALENCE exists. The output has True and Complement comparison status outputs. The logic diagram of the comparator is shown in Figure 1.

The truth table is as shown in Table 1 where vectors a and b are 10-bit inputs to A9 to A0 and B9 to B0. If the input to A9-A0 is bit-to-bit equivalent to the input to B9-B0, the two input vectors are considered EQUIVALENT, and output EQ goes High and NE goes Low. If the two input vectors are not bit-to-bit equivalent, then EQ goes Low and NE goes High. The circuit is implemented with AMAZE as shown in Figures 2a, 2b and 2c. The result of logic simulation of the circuit is shown in Figure 2d.

Notice that on the OR side of the program table in Figure 5, all the fuses in the OR-term are intact, which means that all the AND-terms are still connected to all the OR-terms. This feature provides for future modification. But if all the unused AND-terms are deleted, the device will run faster. There are also many unused AND-terms which will provide for future modification. But if they are deleted (both on the AND and OR side), it will amount to about 450µA per term power saving. Figure 3 is the program table with all unused terms deleted.

Table 1. Function Table

A <sub>9</sub> - A <sub>0</sub>	B <sub>9</sub> - B <sub>0</sub>	EQ	NE
a	a	H	L
b	b	H	L
a	b	L	H
b	a	L	H

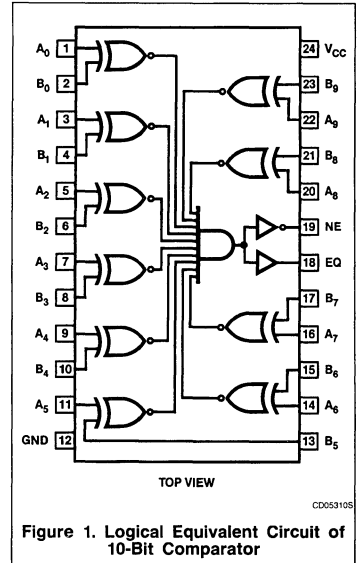


Figure 1. Logical Equivalent Circuit of 10-Bit Comparator

```

***** AN24_173 *****
***** P I N   L I S T *****

  LABEL  ** FNC **PIN  -----  PIN** FNC ** LABEL
A0      ** I   ** 1-!   !-24 ** +5V **VCC
B0      ** I   ** 2-!   !-23 ** I   **B9
A1      ** I   ** 3-!   !-22 ** I   **A9
B1      ** I   ** 4-!   B   !-21 ** I   **B8
A2      ** I   ** 5-!   2   !-20 ** I   **A8
B2      ** I   ** 6-!   S   !-19 ** 0   **NE
A3      ** I   ** 7-!   1   !-18 ** /0  **EQ
B3      ** I   ** 8-!   7   !-17 ** I   **B7
A4      ** I   ** 9-!   3   !-16 ** I   **A7
B4      ** I   ** 10-!  !-15 ** I   **B6
A5      ** I   ** 11-!  !-14 ** I   **A6
GND     ** 0V  ** 12-!  !-13 ** I   **B5
  
```

T8017705

a. Pin List of 10-Bit Comparator

Figure 2

## PLS173 as a 10-Bit Comparator, 74LS460

AN24

```

***** AN24_173 *****
@DEVICE TYPE
82S173
@DRAWING
..... 10-BIT COMPARATOR USING PLS173
@REVISION
..... REV-0
@DATE
..... OCT-14-85
@SYMBOL
..... AN24_173
@COMPANY
..... SIGNETICS
@NAME
..... DAVID WONG
@DESCRIPTION
This circuit compares two 10-bit inputs. If they are bit-to-bit equivalent,
outputs EQ goes HIGH and NE goes LOW. If the inputs are not bit-to-bit equiv-
alent to each other, outputs EQ goes LOW and NE goes HIGH.
@COMMON PRODUCT TERM

T0 = A0 * /B0 ;
T1 = /A0 * B0 ;
T2 = A1 * /B1 ;
T3 = /A1 * B1 ;
T4 = A2 * /B2 ;
T5 = /A2 * B2 ;
T6 = A3 * /B3 ;
T7 = /A3 * B3 ;
T8 = A4 * /B4 ;
T9 = /A4 * B4 ;
T10 = A5 * /B5 ;
T11 = /A5 * B5 ;
T12 = A6 * /B6 ;
T13 = /A6 * B6 ;
T14 = A7 * /B7 ;
T15 = /A7 * B7 ;
T16 = A8 * /B8 ;
T17 = /A8 * B8 ;
T18 = A9 * /B9 ;
T19 = /A9 * B9 ;

@I/O DIRECTION
@OUTPUT POLARITY
@LOGIC EQUATION

EQ = /( T0 + T1 + T2 + T3 + T4 + T5 + T6 + T7 + T8 + T9 +
        T10 + T11 + T12 + T13 + T14 + T15 + T16 + T17 + T18 + T19 ) ;

NE =    T0 + T1 + T2 + T3 + T4 + T5 + T6 + T7 + T8 + T9 +
        T10 + T11 + T12 + T13 + T14 + T15 + T16 + T17 + T18 + T19 ;

```

TB01780S

## b. Boolean Equations of 10-Bit Comparator

Figure 2 (Continued)



## PLS173 as a 10-Bit Comparator, 74LS460

AN24

```

B2S173  A:AN24_173.STD
" AMAZE FILE ID: AN24_173
" LOGIC SIMULATION OF 10-BIT COMPARATOR
"
" <==INPUTS==> <=B(I/O)=>  TRACE TERMS
" 11
" 109B76543210 9876543210
"
000000000000 0000LH0000 ;
010000000000 0000HL0000 ;
100000000000 0000HL0000 ;
110000000000 0000LH0000 ;
000100000000 0000HL0000 ;
001000000000 0000HL0000 ;
001100000000 0000LH0000 ;
000001000000 0000HL0000 ;
000010000000 0000HL0000 ;
000011000000 0000LH0000 ;
000000100000 0000HL0000 ;
000000100000 0000HL0000 ;
000000110000 0000LH0000 ;
000000001000 0000HL0000 ;
000000001000 0000HL0000 ;
000000001100 0000LH0000 ;
000000000010 0000HL0000 ;
000000000010 0000HL0000 ;
000000000011 0000LH0000 ;
000000000000 0100HL0000 ;
000000000000 1000HL0000 ;
000000000000 1100LH0000 ;
000000000000 0001HL0000 ;
000000000000 0010HL0000 ;
000000000000 0011LH0000 ;
000000000000 0000HL0100 ;
000000000000 0000HL1000 ;
000000000000 0000LH1100 ;
000000000000 0000HL0001 ;
000000000000 0000HL0010 ;
000000000000 0000LH0011 ;
"
" ----- I/O CONTROL LINES
"          IIII00IIII DESIGNATED I/O USAGE
"          IIII00IIII ACTUAL I/O USAGE
"
" PINLIST...
" 13 11 10 09 08 07 06 05 04 03 02 01
" 23 22 21 20 19 18 17 16 15 14 ;

```

TB01600S

d. Test Vectors Generated by AMAZE After Logic Simulation

Figure 2 (Continued)

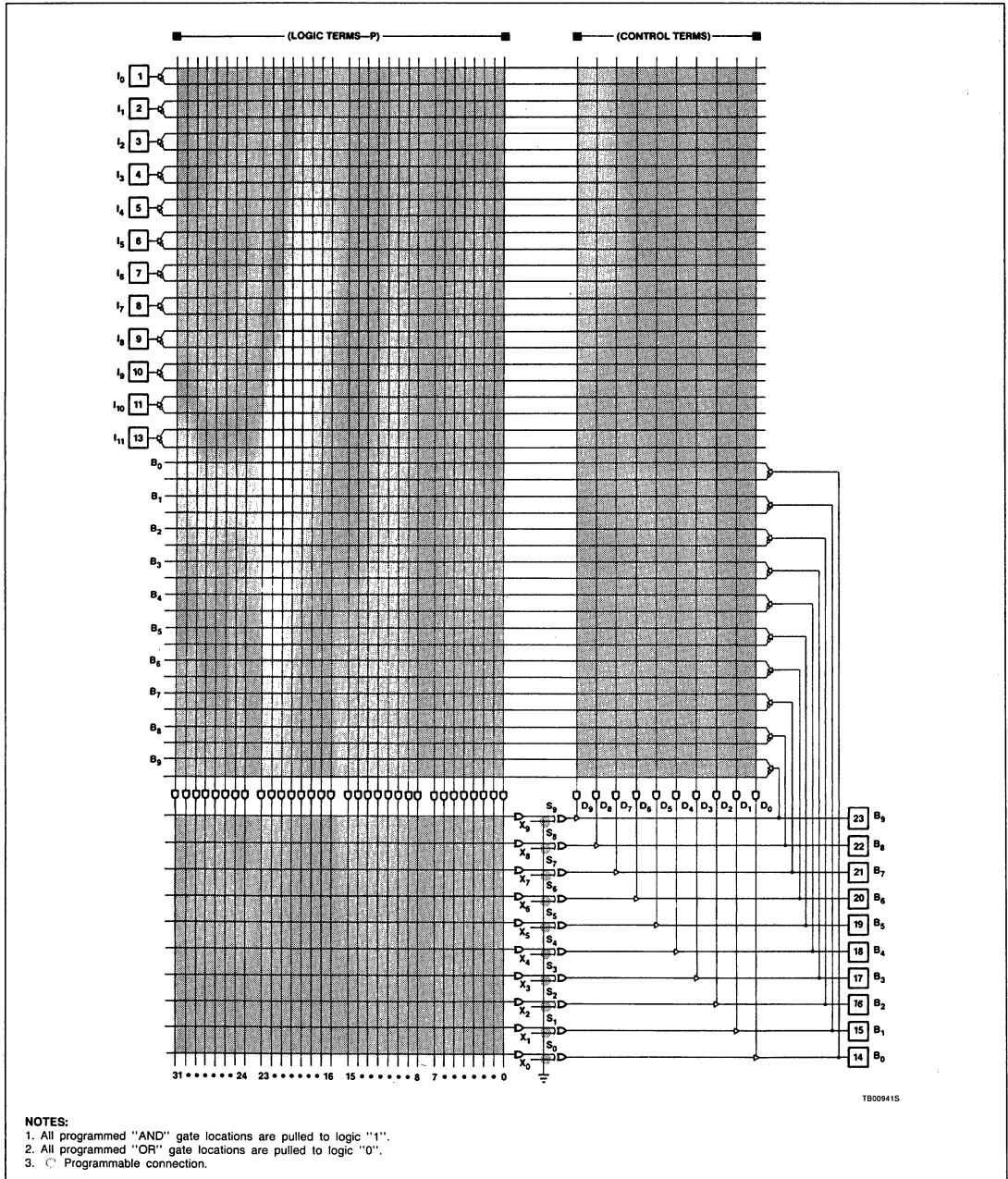


# PLS173 as a 10-Bit Comparator, 74LS460

AN24

## APPENDIX A

### FPLA LOGIC DIAGRAM FOR PLS173



### Application Specific Products

#### DESCRIPTION

The following is the implementation of a counter/controller using a PLS157. This system counts and controls the number of entries to a certain media. For example, it can be used as a parking-lot controller to keep track of the number of cars entering a parking lot, and restricting any entries when the parking lot is full.

The design utilizes the six registers, six bi-directional I/O lines and the general architecture of the PLS157. In this design, the user can set the maximum number of entries using

external switches. Since the six registers in the device are used as a six-bit counter, the maximum number that can be set is  $2^6$ . However, the design can be cascaded to increase the number of entries.

#### SYSTEM OPERATION

The basic system configuration is shown in Figure 1. As can be seen from this figure, the system can be expanded indefinitely. All the devices in cascade are identical to each other. Whenever there is a need for expanding the maximum number of counts, a device

can be programmed identical to the device(s) already in the system and added in cascade.

There are external switches connected to the bi-directional inputs of the flip-flops. The user sets the maximum count in binary with the switches and loads the value into the registers. If the maximum count necessary exceeds the number available in one device, then another device is cascaded to the existing device. For example, in a system with two devices, the maximum available increases to  $2^{12}$  or 4096.

When the maximum count is set, the control circuitry is used to keep track of the number of entries and exits. In the case of a parking lot, a pressure sensor can be used at the entrance and exit to generate a pulse which triggers the control circuitry. An alternative could be light beam sensors to generate the necessary pulses.

The operation of the system is such that each entry decreases the maximum count stored in the registers by one. When the count is zero, it means that the media is full and the control circuitry generates a signal to disable any further entries to the system. On the other hand, each exit increases the count by one. Since it is assumed that the media is empty when the maximum count is set, it is, therefore, impossible to physically count past the maximum set number. This is due to the fact that there cannot be more exits from the system than the actual number of objects residing in the system. If there are objects in the system when the maximum number is set, these objects should also be taken into consideration when setting the maximum count.

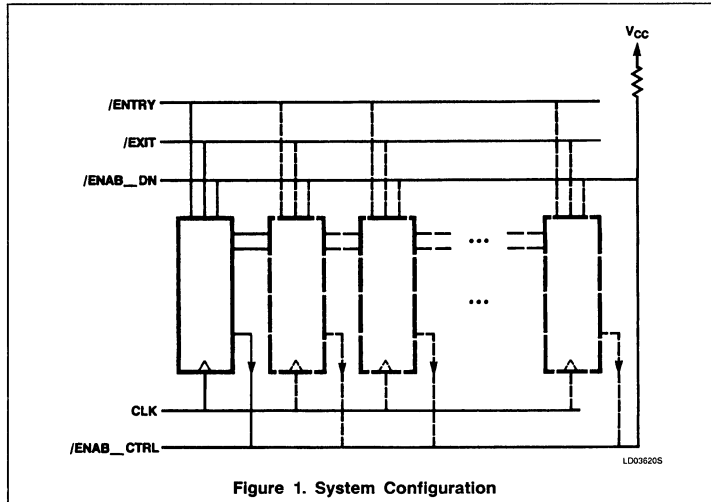


Figure 1. System Configuration

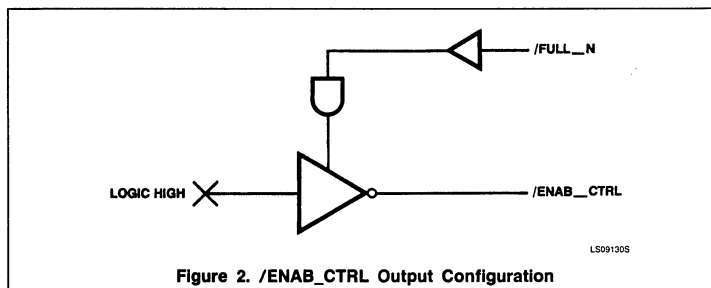


Figure 2. /ENAB\_CTRL Output Configuration

#### CONTROL SIGNALS

The following is the explanation of the control signals shown in Figure 1.

The /ENTRY and /EXIT inputs signify an entrance or exit to or from the respective media and are triggered from the sensors at the entrance and exit. Each entry causes a count-down from the maximum set number until all the flip-flops are low. This means that the system is full and the count-down should be disabled.



# A Simple Entry/Exit Metering Device

AN25

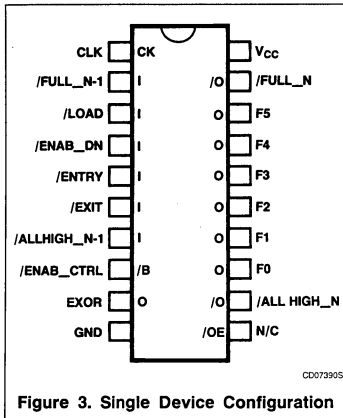


Figure 3. Single Device Configuration

When all the flip-flops are low, the /FULL\_N signal which is an Active-Low output is activated. The count-down is enabled by the /ENAB\_DN input, which is connected externally to the /ENAB\_CTRL line. The /ENAB\_CTRL is a Tri-state output which is controlled by the /FULL\_N signal. When all the flip-flops are low, the /FULL\_N signal deactivates the /ENAB\_CTRL output as shown in Figure 2.

All of the /ENAB\_CTRL outputs are connected to the /ENAB\_CTRL bus as shown in Figure 1. When the media is full, all the /ENAB\_CTRL signals are deactivated which cause the count-down to be disabled.

An exit causes a count up. As mentioned before, the total number of exits from the system cannot exceed the total number of entries.

The /ALLHIGH\_N signal is an Active-Low output which becomes low when all the flip-flops are high. Figure 3 shows the configuration of a single device.

The /FULL\_N and /ALLHIGH\_N signals are used to activate the /FULL\_N-1 and /ALLHIGH\_N-1 of a cascaded device. These

signals will be explained in detail shortly. The /FULL\_N signal is also used to trigger any control circuitry used to restrict any further entries to the system. In the case of a parking lot, the /FULL\_N can be used to activate a light or close the entrance gate.

The EXOR output is used to clock the system and is externally connected to the CLK input of the device. The EXOR generates a clock pulse when either an exit or entry take place. This restricts the system from counting if a simultaneous entry and exit takes place.

To set the maximum count, the user can use switches connected to inputs F0-F5 of the device(s). Then by bringing the /LOAD input low and triggering the /ENTRY or /EXIT inputs to generate a clock pulse, the data from these switches can be latched into the registers.

## CASCADE DEVICE EXAMPLE

This is an example of two cascaded devices. Figure 4 shows the cascade configuration of devices 'A' and 'B'. For the sake of simplicity, it is assumed that each device contains only two registers. This assumption gives clarity to the explanation, and can be extended to cover the six registers contained in each device.

As an example, it is assumed that the maximum count to be implemented in this example is 1001 in binary. In other words, the maximum number of entries is set to be 'ten'. F0A and F1A are the registers in device A, and F0B and F1B are the registers in device B. 10 is the input sequence to device A.

The count-up and count-down sequences are shown in Table 1.

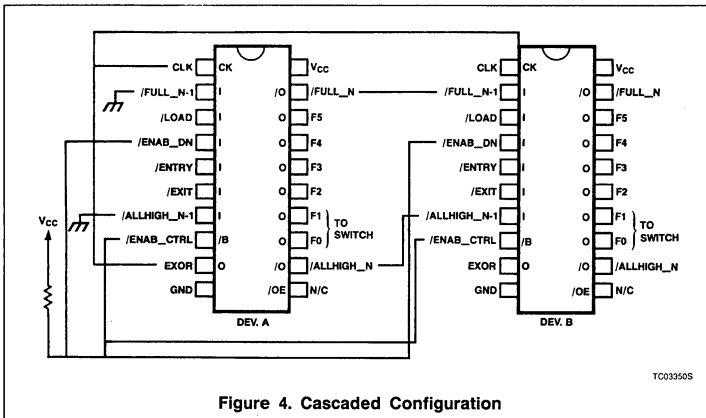


Figure 4. Cascaded Configuration

Table 1. An Up/Down Count Sequence Example

	DEV. B		DEV. A		DEV. B		DEV. A	
	F0B	F1B	F0A	F1A	F0B	F1B	F0A	F1A
1	0	0	0	1	0	0	0	1
2	1	0	0	0	0	0	0	1
3	0	1	1	0	0	0	1	0
4	0	0	0	1	0	1	0	0
5	1	1	0	0	0	0	1	1
6	0	0	1	1	0	1	0	0
7	0	1	0	0	0	0	1	1
8	1	0	1	1	0	1	0	0
9	0	0	0	0	1	0	1	1
10	0	0	0	0	0	0	0	0
11	1	1	1	1	1	1	1	1
12	0	0	0	0	0	0	0	0
13	1	1	1	1	1	1	1	1
14	0	0	0	0	0	0	0	0
15	1	1	1	1	1	1	1	1
16	0	0	0	0	0	0	0	0
17	1	1	1	1	1	1	1	1
18	0	0	0	0	0	0	0	0
19	1	1	1	1	1	1	1	1
20	0	0	0	0	0	0	0	0
21	1	1	1	1	1	1	1	1
22	0	0	0	0	0	0	0	0
23	1	1	1	1	1	1	1	1
24	0	0	0	0	0	0	0	0
25	1	1	1	1	1	1	1	1
26	0	0	0	0	0	0	0	0
27	1	1	1	1	1	1	1	1
28	0	0	0	0	0	0	0	0

Table 2. Count Sequence

NO.	F5	F4	F3	F2	F1	F0
0	0	0	0	0	0	0
1	0	0	0	0	0	1
2	0	0	0	0	1	0
3	0	0	0	0	1	1
4	0	0	0	1	0	0
5	0	0	0	1	0	1
6	0	0	0	1	1	0
7	0	0	0	1	1	1
8	0	0	1	0	0	0
9	0	0	1	0	0	1
10	0	1	0	0	0	0
11	0	1	0	0	0	1
12	0	1	0	1	0	0
13	0	1	0	1	0	1
14	0	1	1	0	0	0
15	0	1	1	0	0	1
16	1	0	0	0	0	0
17	1	0	0	0	0	1
18	1	0	0	1	0	0
19	1	0	0	1	0	1
20	1	0	1	0	0	0
21	1	0	1	0	0	1
22	1	1	0	0	0	0
23	1	1	0	0	0	1
24	1	1	1	0	0	0
25	1	1	1	0	0	1
26	1	1	1	1	0	0
27	1	1	1	1	0	1
28	0	0	0	0	0	0

# A Simple Entry/Exit Metering Device

AN25

In the 1001 example, F0B is the MSB (Most Significant Bit) and F1A is the LSB (Least Significant Bit). As can be seen in Table 1, a count-down occurs in device 'B', when F0A and F1A are both low. When F0A and F1A are low, this means that the /FULL\_N signal is active. The /FULL\_N-1 input of device 'B' is connected to the FULL\_N output of device 'A'. Therefore, a count down occurs in device 'B' only when the input to /FULL\_N-1 goes low. In this manner, the count-down sequence in Table 1 can be implemented.

Similarly, for the count-up sequence, a count-up occurs in device 'B' only when both F0A and F1A are high. At this point, the /ALLHIGH\_N signal becomes active. Therefore, a count-up occurs in device 'B' only when /ALLHIGH\_N of device 'A' is active.

## UP/DOWN COUNTERS

An up-down counter is implemented in each device to keep track of the number of entries and exits. To implement these counters the flip-flops are set in the toggle mode. Table 2 shows the count sequence.

The following conditions are true for the count-up sequence:

Table 3a

REGISTER	TRUE CONDITION FOR TOGGLE
F0	Unconditionally Toggle
F1	F0
F2	F0*F1
F3	F0*F1*F2
F4	F0*F1*F2*F3
F5	F0*F1*F2*F3*F4

Similarly, for the count-down sequence:

Table 3b

REGISTER	TRUE CONDITION FOR TOGGLE
F0	Unconditionally Toggle
F1	/F0
F2	/F0*/F1
F3	/F0*/F1*/F2*
F4	/F0*/F1*/F2*/F3
F5	/F0*/F1*/F2*/F3*/F4*

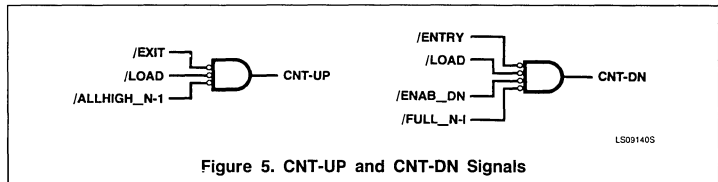


Figure 5. CNT-UP and CNT-DN Signals

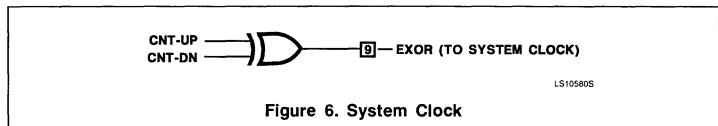


Figure 6. System Clock

```

File Name : METER
Date : 10/31/1985
Time : 14:35:31

##### P I N L I S T #####
      LABEL  ** FNC **PIN  ----- PIN** FNC ** LABEL
CLK         ** CK  ** 1-1    1-20 ** +5V **VCC
/FULL_N-1   ** I   ** 2-1    1-19 ** /0  **/FULL_N
/LOAD       ** I   ** 3-1    1-18 ** 0   **F5
/ENAB_DN    ** I   ** 4-1    P  1-17 ** 0   **F4
/ENTRY      ** I   ** 5-1    L  1-16 ** 0   **F3
/EXIT       ** I   ** 6-1    X  1-15 ** 0   **F2
/ALLHIGH_N-1** I   ** 7-1    1  1-14 ** 0   **F1
/ENAB_CTRL  ** /B  ** 8-1    5  1-13 ** 0   **F0
EXDR        ** 0   ** 9-1    7  1-12 ** /0  **/ALLHIGH_N
GND         ** 0V  ** 10-1   7  1-11 ** /OE **N/C
    
```

Figure 7

## CONTROL SIGNALS

The following are the control signals used to control the operation of the devices:

The logic diagram for generating the 'CNT-UP' and 'CNT-DN' signals is shown in Figure 5.

As can be seen from this figure, a count-up occurs when the following is true:

- a) An exit takes place and,
- b) the system is not loading in any data and,
- c) the previous stage has generated the /ALLHIGH\_N-1 signal.

A count-down occurs when:

- a) An entry takes place and,
- b) the system is not loading in any data and,
- c) the previous stage has generated the /FULL\_N-1 signal and,
- d) the media is not full, thus /ENAB\_DN signal is low.

The system clock is generated using the CNT-UP and CNT-DN signals. The system is

to be clocked only when an exit or entry takes place. In order to prevent the system from being clocked when a simultaneous entry and exit takes place, these two signals are exclusive-OR'ed (Figure 6).

The equations shown in (Tables 3a and 3b) are generated using Signetics AMAZE software (Figures 7 and 8). The resulting program table is shown in Table 4.

# A Simple Entry/Exit Metering Device

AN25

```

@DEVICE TYPE
FLX157
@DRAWING
@REVISION
@DATE
10-31-85

@SYMBOL
ENTR/EXIT METER

@COMPANY
SIGNETICS

@NAME
ALI GHEISSARI

@DESCRIPTION
*****
* The following is the implementation of a Entry/Exit Meter. A *
* application of this device would be in controlling the number of *
* entries to a certain media. An example is a parking lot controller *
* for restricting the number of cars entering the lot. *
* The maximum number is programmable and the design can be cacaded to *
* Accomodate an increase in the number of entries. *
* The system counts down from the maximum set number to zero *
* The number of exits cannot exceed the maximum count set by the *
* external switches,therefore the upper limit on the count will never *
* be exceeded. *
*****

@COMMON PRODUCT TERM
UPCNT = /LOAD * EXIT * ALLHIGH_N-1; "UPCNT is the signal generated for "
"activating the count-up from the ENTRY "
"input and the ALLHIGH signal from any "
"connected devices "

DNCNT = /LOAD * ENTRY * FULL_N-1; "DNCNT is similar to UPCNT except it is "
"generated for the count down "

ALL-HIGH = /F0 * /F1 * /F2 * /F3 * /F4 * /F5;
ALL-LOW = F0 * F1 * F2 * F3 * F4 * F5;

@COMPLEMENT ARRAY
/C = /(0);

@I/O DIRECTION
D0 = 0; "/EXIT is an input "
D1 = 0; "ALLHIGH_N-1 is an input "
D2 = /FULL_N; "When maximum count is reached /FULL_N "
"disables /ENAB-CTRL which in turn disables "
"the device(s) from counting down "
"/ENAB-CTRL is connected to the ENAB_DN of the "
" device(s) "

D3 = 1; "EXOR is an output "
D4 = 1; "/ALLHIGH_N is an output "
D5 = 1; "/FULL_N is an output "

```

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Figure 8

## A Simple Entry/Exit Metering Device

AN25

```

@OUTPUT POLARITY
X2 = 0;           "/ENAB_CTRL is active low           "
X3 = 1;           "EXOR is active high             "
X4 = 0;           "/ALLHIGH_N is active low         "
X5 = 0;           "/FULL_N is active low           "

@FLIP FLOP CONTROL
FC = 1;           "All flip flops are J-K             "

@OUTPUT ENABLE
"NOT USED"

@REGISTER LOAD
LA = LOAD;        "Load the registers with the number set   "
LB = LOAD;        "by the input switches                   "

@ASYNCHRONOUS PRESET/RESET
"NOT USED"

@FLIP FLOP MODE
"NOT USED"

@LOGIC EQUATION
EXOR = UPCNT*/DNCNT + DNCNT*/UPCNT; "Output count pulse only if there is not "
                                     "a simultaneous entry and exit        "
/FULL_N = /( ALL-LOW * /LOAD);      "indicates when maximum count is reached "
/ALLHIGH_N = /( ALL-HIGH * /LOAD);  "shows when empty                       "
/ENAB_CTRL = /(1);                  "puts low on the ENAB_CTRL bus         "

"The following is the implementation of the counter together with the "
"necessary logic."

/F0: T = (ENAB_DN * DNCNT) + UPCNT;

/F1: T = (ENAB_DN * F0 * DNCNT) + (/F0 * UPCNT);

/F2: T = (ENAB_DN * F0 * F1 * DNCNT) + (/F0 * /F1 * UPCNT);

/F3: T = (ENAB_DN * F0 * F1 * F2 * DNCNT) +
        (/F0 * /F1 * /F2 * UPCNT);

/F4: T = (ENAB_DN * F0 * F1 * F2 * F3 * DNCNT) +
        (/F0 * /F1 * /F2 * /F3 * UPCNT);

/F5: T = (ENAB_DN * F0 * F1 * F2 * F3 * F4 * DNCNT) +
        (/F0 * /F1 * /F2 * /F3 * /F4 * UPCNT);

```

TD019405

Figure 8 (Continued)



### Application Specific Products

#### FEATURES

- 100% functional replacement for all 20-pin PALs
- I/O propagation delay: 20ns (max)
- Security fuse lock
- 10 inputs
- 8 bidirectional I/O lines
- Tri-state outputs have programmable polarity
- Architecture: 8 groups of nine AND gates. Total of 72 product terms
- Software support on Signetics AMAZE
- Complete TTL compatibility
- Each bidirectional I/O has individually controllable output enable

#### ARCHITECTURE

The PLHS18P8A is an oxide-isolated, bipolar field-programmable logic array. This device is configured as a decoding two-level AND-OR (sum of products) structure. The PLHS18P8A block diagram is shown in Figure 1. All the AND gates are linked to ten inputs ( $I_0 - I_9$ ) and eight bidirectional I/O lines ( $B_{(0)} - B_{(7)}$ ). These links can be made via the on-chip true/complement buffers. The 72 AND gates are configured in 8 groups which contain 9 AND gates each. In every group, eight AND gates are used for user-defined logic functions and the ninth AND gate is used as a tri-state output enable control. This gives the user capability to control the output enable by means of a product term. The outputs of the eight logical product terms are ORed together (see Figure 1). The output polarity of each OR gate is individually programmable via an Exclusive-OR gate. The user has a choice of Active-Low or Active-High on each of the eight outputs. Figure 2 shows the logic diagram of the PLHS18P8A.

#### HOW A DEVICE IS PROGRAMMED

There are three main programmable sections on the PLHS18P8A:

- A. The AND array.
- B. The output polarity.
- C. The security fuse.

**A. The AND Array**—The AND array fuses are back-to-back diode pairs which act as open connections in a virgin device. These open connections are configured as 'Don't Cares' ('-') in an unprogrammed device. The open connections are pulled to a logic High ('1') (see Figure 3). Consequently, all unprogrammed AND locations are pulled to a logic High ('1') state. This means that in an unprogrammed device, all the product terms are active. During fusing, current is avalanched across individual diode pairs. This essentially short circuits the diode and provides a connection for the associated product term. Figure 3 shows how a typical connection is made to the AND array (see Appendix B for a description of the vertical fuses).

The inputs to the AND array consist of 10 dedicated inputs ( $I_0 - I_9$ ) and 8 bidirectional I/Os ( $B_{(0)} - B_{(7)}$ ). Initially, all these inputs are configured as 'Don't Cares' ('-'). These inputs can be connected to the AND array through an inverting or non-inverting buffer. The AND gate can be connected to the inverting buffer by programming the inverting fuse. Similarly, a connection can be made to the non-inverting buffer by programming the non-inverting fuse. Disabling an AND term is achieved by implementing a logical Low ('0') on the output of the specified AND gate. When both fuses of an input (e.g.  $I_0$  and  $\bar{I}_0$ ) are programmed, both the inverting and non-inverting buffers are connected to the inputs of the AND gate. To achieve this a '0' should be entered on the program table under the specified input. This will in turn create a logical Low ('0') on the output. To avoid any glitches on the output, it is a good practice to program all inputs to force a logical Low ('0').

In each block of nine AND gates, one gate is used as an output enable control for the tri-state output (Terms 0, 9, 18, 27, 36, 45, 54, 63, designated as D on Table 2). The remaining eight gates are connected to a fixed OR gate. Since in the unprogrammed state the outputs of all the AND gates are at logic High ('1'), the output of the OR gate also acquires a logic High state. Therefore the user is responsible for deactivating any unwanted product terms. This is done by creating a logic

Low ('0') on the outputs of the unwanted product terms as previously explained. Moreover, the output buffer is always enabled since the product term controlling the tri-state output buffer also has a logic High state. If any of the bidirectional pins are to be defined as inputs, the product term controlling the specified bidirectional pin must be disabled. The bidirectional pin can also be configured as a dynamic I/O by defining the required logic for the output-enable-control product term.

The actual programming of the PLHS18P8A is carried out according to JEDEC<sup>1</sup> standards and the specific programming algorithm developed for the part.

According to JEDEC standards on data preparation for the PLD programmer, a "1" specifies a high impedance for the specified fuse and "0" a low impedance for the designated fuse.

For the AND array, the programming algorithm leaves the fuse intact (open-circuited) when a JEDEC "1" is specified. Consequently, a JEDEC "0" programs and short circuits the specified fuse. The programming algorithm is different for the output polarity and will be explained in the next paragraph on Special Conditions for the Output Polarity.

**B. Special Conditions For The Output Polarity**—In an unprogrammed device, all the output polarities are configured as inverting buffers. In this state, the device will have logic Low on all its outputs. The outputs of the PLHS18P8A are configured as tri-state buffers. The two inputs of each Ex-OR gate are connected as follows: one input is connected to the output of the fixed OR gate. The second input is a connection to ground (logic Low) through a fusible link.

As mentioned earlier, an unprogrammed fuse acts as an open connection which is pulled to a logic High. Therefore the output of the Ex-OR gate acts as an inverting buffer. When the fuse is programmed, there is a connection between ground (logic Low) and the input of the Ex-OR gate. This will cause the Ex-OR gate to act as a non-inverting buffer.

1. For more information on standard data transfer format between the data preparation system and PLD programmer, refer to JEDEC—Solid State Engineering Council publications.

# PLHS18P8A Primer

# AN26

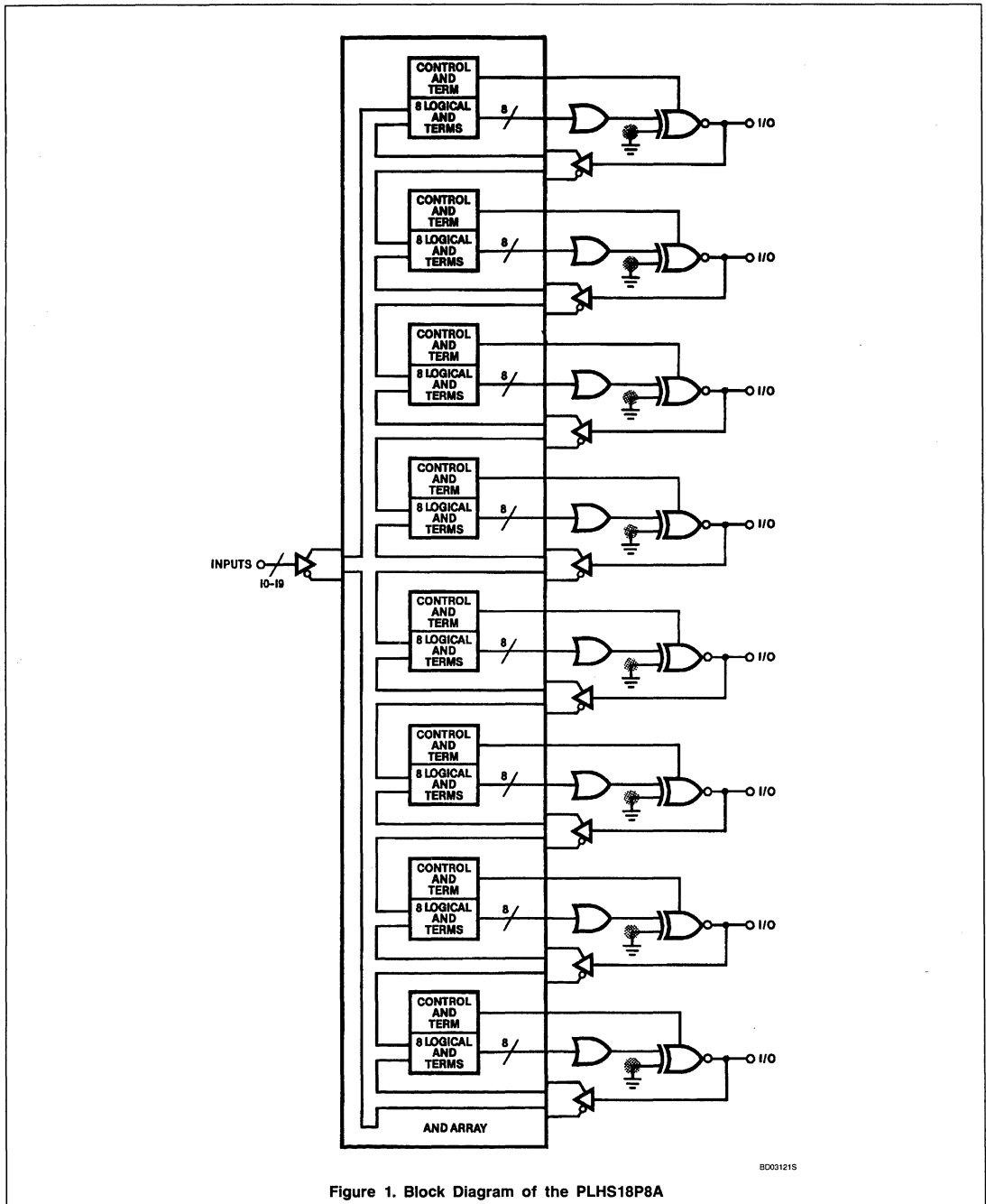
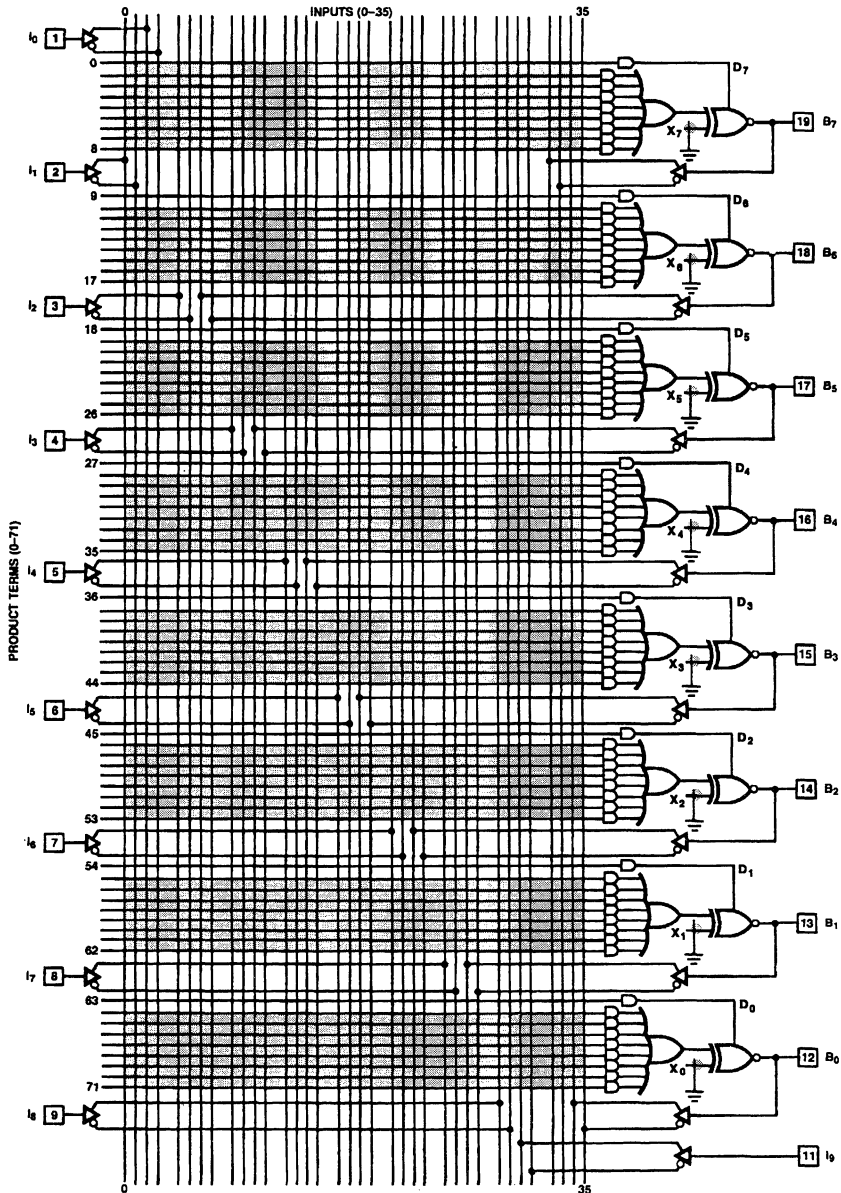


Figure 1. Block Diagram of the PLHS18P8A

PLHS18P8A Primer

AN26



NOTES:

1. All unprogrammed or virgin "AND" gate locations are pulled to logic "1".
2. All unprogrammed or virgin "OR" gate locations are pulled to logic "1".
3. ● Programmable corrections.

Figure 2. Logic Diagram of the PLHS18P8A

LD026225



# PLHS18P8A Primer

# AN26

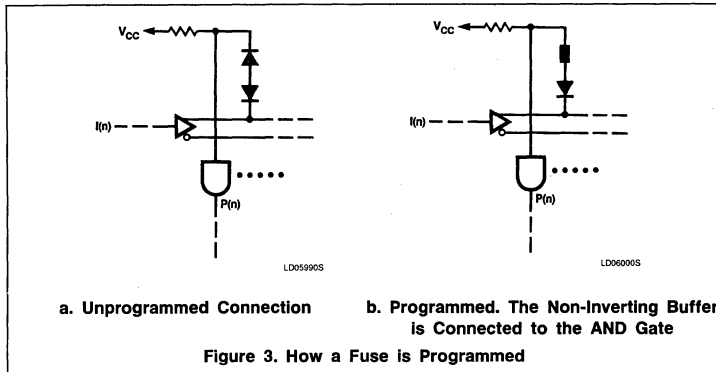


Figure 3. How a Fuse is Programmed

The procedure for programming this fuse depends on the programmer manufacturer and is explained in the manufacturer's operations manual.

## DESIGN TOOLS FOR THE PLHS18P8A

Many CAD tools such as Signetics' AMAZE software<sup>2</sup> are available to implement designs using the PLHS18P8A. The AMAZE software enables the user to enter the design in the form of Boolean equations or via the program table shown in Table 2. This program table is a one-to-one map of all the programmable links of Figure 2. The following explains the implementation of designs using the program table. Also, an example on using the Boolean Logic Entry program of the AMAZE software is given.

**Using PTE (Program Table Entry)** — Assume that Z is a typical logic function with the following equation:

$$Z = P_0 + P_1$$

Where P<sub>0</sub> and P<sub>1</sub> are product terms with the following equations:

$$P_0 = A * B * C$$

$$P_1 = /A * B * /D$$

The program table in Table 2 is used to implement this equation. Table 3 shows the implementation of the logic function using the PTE. The first group of AND terms is used to implement this function. B(7) is used for the output, I<sub>0</sub>, I<sub>1</sub>, and I<sub>2</sub> as inputs.

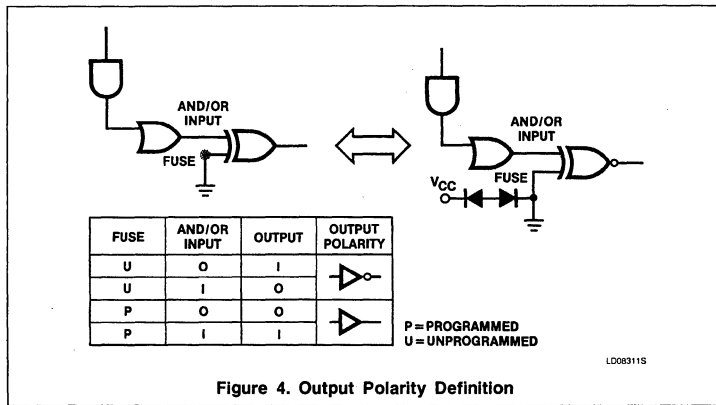


Figure 4. Output Polarity Definition

Table 1. Programming Algorithm

JEDEC SPECIFICATION	AND ARRAY FUSE PROGRAMMING ALGORITHM	OUTPUT POLARITY FUSE PROGRAMMING ALGORITHM
1 — High impedance	Fuse unprogrammed (open circuit)	Fuse programmed (short circuit)
0 — Low impedance	Fuse programmed (short circuit)	Fuse unprogrammed (open circuit)

Figure 4 shows the definition of the output polarity for the PLHS18P8A. As can be seen, the output configuration of the PLHS18P8A is equivalent to an Ex-OR gate.

The programming algorithm for the output polarity section of the PLHS18P8A is different from that of the AND array. For the output polarity a JEDEC "1" (high impedance) programs (short circuits) the Ex-OR gate fuse, whereas a "0" (low impedance) leaves the fuse intact (open circuit).

The programming specifications are transparent to the user and do not need to be taken

into consideration when designing with the PLHS18P8A. Table 1 shows the resulting programming algorithm from the JEDEC specification.

**C. The Security Fuse** — Programming equipment used to program the PLHS18P8A are capable of determining the logic pattern stored in this device (see Appendix A). The security fuse can be blown to disable the programmer from reading the pattern in a programmed device. This feature adds a measure of protection for proprietary designs.

— Term 0 is the direction control term. It is the tri-state output enable control term. Since Z is configured as an output, leaving Term 0 in its unprogrammed state causes the output to be unconditionally enabled.

— Term 1 is the P-term labeled P<sub>0</sub>, where A\*/B\*C is designated by HLH in columns I<sub>0</sub>, I<sub>1</sub>, and I<sub>2</sub>.

— Term 2 is the P-term labeled P<sub>1</sub>, where /A\*B\*/D is designated by LHL in columns I<sub>0</sub>, I<sub>1</sub>, and I<sub>2</sub>.

— Terms 3, 4, 5, 6, 7. At least one input (or all the inputs) *must be set to zero* to disconnect these terms from the OR gate.

— The output polarity for B(7) is H, and this is entered in the 'Polarity' section.

**Using BLAST (Boolean Logic And State Transfer)** — The BLAST module in AMAZE can be used to implement the above equation. Figures 5 and 6 show the pin list and logic equation format. Table 4 is the program table generated from these equations.

2. Refer to Signetics Programmable Logic Data Manual for a complete description of the AMAZE programmable logic development software.



PLHS18P8A Primer

AN26

Cust/project -PLHS18P8A Primer  
 Date -May 1986  
 Rev/I. D. -  
 Comments:  
 Program Table for implementing  
 $Z = PO + P1$   
 where:  
 $PO = A.(/B).C$   
 $P1 = (/A).B.(/D)$

PLHS18PB										POLARITY										
VARIABLE																				
T	NAME																			
E	I	D	B	A	B(1)					Z	B(0)									
N	9	8	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0		
0!	-	-	-	-	-	-	-	-	-	-	-	D	/	/	/	/	/	/		
1!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
2!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
3!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
4!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
5!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
6!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
7!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
8!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
9!	-	-	-	-	-	-	-	-	-	-	-	D	/	/	/	/	/	/		
10!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
11!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
12!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
13!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
14!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
15!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
16!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
17!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
18!	-	-	-	-	-	-	-	-	-	-	-	D	/	/	/	/	/	/		
19!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
20!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
21!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
22!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
23!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
24!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
25!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
26!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
27!	-	-	-	-	-	-	-	-	-	-	-	D	/	/	/	/	/	/		
28!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
29!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
30!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
31!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
32!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
33!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
34!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
35!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
36!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
37!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
38!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
39!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
40!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
41!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
42!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
43!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
44!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
45!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
46!	-	-	-	-	-	-	-	-	-	-	-	D	/	/	/	/	/	/		
47!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
48!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
49!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
50!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
51!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
52!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
53!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
54!	-	-	-	-	-	-	-	-	-	-	-	D	/	/	/	/	/	/		
55!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
56!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
57!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
58!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
59!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
60!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
61!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
62!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
63!	-	-	-	-	-	-	-	-	-	-	-	D	/	/	/	/	/	/		
64!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
65!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
66!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
67!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
68!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
69!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
70!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		
71!	-	-	-	-	-	-	-	-	-	-	-	A	/	/	/	/	/	/		

→ Tri-state always enable  
 → PO = A\*/B\*C  
 → P1 = A\*/B\*/D

Table 3. Implementation of the Function "Z" Using PTE

TB03071S

## PLHS18P8A Primer

AN26

```

File Name : 18PRIMER
Date : 5/22/1986
Time : 13:52:54

***** P I N L I S T *****

LABEL  ** FNC **PIN ----- PIN** FNC ** LABEL
A      ** I  ** 1-1  P 1-20 ** +5V **VCC
B      ** I  ** 2-1  L 1-19 ** 0  **Z
C      ** I  ** 3-1  H 1-18 ** /O  **INVERT
D      ** I  ** 4-1  S 1-17 ** I  **INPUT
N/C    ** I  ** 5-1  1 1-16 ** B  **BIDIR
N/C    ** I  ** 6-1  S 1-15 ** /B  **/BIDIR
N/C    ** I  ** 7-1  P 1-14 ** /B  **N/C
N/C    ** I  ** 8-1  S 1-13 ** /B  **N/C
N/C    ** I  ** 9-1  A 1-12 ** /B  **N/C
GND    ** OV ** 10-1  | 1-11 ** I  **N/C

```

TB000015

Figure 5

```

File Name : 18PRIMER
Date : 5/22/1986
Time : 13:53:59

@DEVICE TYPE
PLHS18P8A
@DRAWING
..... PLHS18P8A PRIMER

@REVISION
..... PLHS18P8A REV '-'

@DATE
..... May 1986

@SYMBOL
..... PLHS18P8A

@COMPANY
..... SIGNETICS

@NAME
..... Ali Sheissari

@DESCRIPTION
*****
* This is an example of implementing equations for *
* the PLHS18P8A using AMAZE *
*****

@COMMON PRODUCT TERM
P0 = A * /B * C; " P0 and P1 are used to declare common "
P1 = /A * /B * /D; " product terms. "

@I/O DIRECTION
D7 = 1; " Defines B7 to be an output "
D6 = 1; " Defines B6 to be an output "
D5 = 0; " Defines B5 to be an input "
D4 = A; " B4 an output when A is true otherwise an input "
D3 = B; " B3 an output when B is true otherwise an input "

@OUTPUT POLARITY
X7 = 0; " Documents the output polarity as active high "
X6 = 1; " Documents the output polarity as active high "
X4 = 0; " Documents the output polarity as active high "
X3 = 1; " Documents the output polarity as active high "

@LOGIC EQUATION
"Examples of some simple equations "
Z = P0 + P1;

INVERT = /( INPUT );

BIDIR = /BIDIR * B ;

/BIDIR = /( A * C * D * /Z * INVERT * INPUT * BIDIR );

```

TB000015

Figure 6. Boolean Equation File



# PLHS18P8A Primer

# AN26

## APPENDIX A

### Programmiers

The PLHS18P8A can be programmed by means of logic programming equipment. With Logic Programming, the AND/Ex-OR gate input connections necessary to implement the desired logic are coded directly from the logic equations using the program table shown in Table 2.

The symbols used in the program table correspond to the fusing pattern of the corresponding link pairs, defined in Figure 6.

To program the device, the address of every fuse to be programmed must be entered in the programmer. This is a tedious and error-prone method of implementing the required logic pattern. Using CAD software, such as Signetics' AMAZE software, enables users to go directly from program table or logic equations to a fuse plot. The fuse plot can be downloaded to a programmer through a serial port. The downloaded fuse plot is in JEDEC format.

## APPENDIX B

The vertical fuse is the latest in programmable logic technology. It combines reliability,

low capacitance and testability in an incredibly small space.

The vertical fuse takes advantage of the properties of silicon and aluminum. The virgin fuse is a three-layer device: a shallow layer of N-type silicon on top, a layer of P-type silicon in the middle, and a layer of N-type silicon on the bottom. This forms a pair of PN diodes, back-to-back, which will not allow current to pass under normal circumstances.

There is a cap of aluminum on top of this structure. During programming, high current conditions (50 to 100 times what is seen during normal operation) is induced by avalanche breakdown of the reverse-biased diode. The aluminum will "spike" through the shallow N-type layer. Once the aluminum has spiked through, the top diode in the pair is shorted out. The whole vertical fuse will then look like a pure PN diode. Before programming, the fuse is an excellent blocking element, having current leakages in the order of nanoamps. After programming, the fuse is set as a small, well-defined diode.

### QUALITY

Besides the AC and DC parametrics, each and every fuse goes through three tests for forward characteristics, reverse characteris-

tics, and programmability. Extensive on-chip test circuitry ensures full AC parametric testing before and after the part is programmed. This insures that the customer receives the highest possible fusing yield which is made possible by vertical fuses. Vertical fuses also offer the smallest and fastest array structure together with the highest reliability possible.

## APPENDIX C

### Test Array

The PLHS18P8A may be subjected to AC and DC parametric tests prior to programming via an on-chip test array. Table C1 shows the test columns in the part. The test sequence is as follows.

Test column 1 is connected to B(O)0, 2, 4, 6 while test column 2 is connected to B(O)1, 3, 5, 7. Applying 10V to Pin 11 will put all the outputs in the Active-High mode and tri-state its associated input buffer.

Applying 10V to Pin 8 will disable B(O) 0 - 3, enable B(O) 4 - 7, tri-state B(I) 4 - 7, tri-state its associated input buffer, disable the AND array and enable test columns 1 and 2. The test columns are defined during programming by the PLD programmer.

**Table C1. Test Columns of PLHS18P8A**

TEST COLUMN	INPUTS																	
	Is								B(Is)									
	9	8	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
1	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H	H
2	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L

## Application Specific Products

## INTRODUCTION

The PLHS473 is a 24-pin field-programmable logic array (FPLA) which has 11 dedicated inputs, 2 dedicated outputs and 9 bidirectional I/Os. The logic array consists of 24 programmable product terms which are connected to 22 programmable OR terms in the classical PLA architecture. A functional diagram is shown in Figure 1. The shaded areas represent programmable interconnects between vertical and horizontal lines. Eleven dedicated inputs,  $I_0$  to  $I_{10}$ , are located on the upper lefthand corner of the diagram, and the 9 bidirectional I/Os,  $B_0$  to  $B_8$  are located on the lower righthand corner. All inputs to the AND array have true and inverting input buffers. The output portion of the 9 bidirectional I/Os and 2 outputs may be programmed to be Active-High or Active-Low by altering fuses  $X_0$  to  $X_8$ ,  $X_A$  and  $X_B$  which are connected to one leg of the Exclusive-OR gates. Each output is connected to two OR-terms, one of which provides the logic function OR to the output while the other provides the ENABLE function for the tri-state output buffer. Alternatively, each output may be configured to emulate an open-collector output by programming the output to an unconditional LOW and apply the logic function on the tri-state controlling OR-term as shown in Figure 2. In addition, the PLHS473 has a security fuse which may be programmed to lock out unauthorized access to the fuse map of the design.

This device is fabricated with an oxide-isolation process for the best speed/power performance. The programmable element is a "vertical fuse" which is actually two PN diodes connected back-to-back (anode-to-anode

stacked on top of one another) as shown in the insets of Figure 1. The fuses are normally open-circuited. To program a fuse, a sufficiently high voltage is applied across the two diodes such that one diode breaks down which induces metal migration across the PN junction of the avalanched diode. This technology allows smaller chip size and faster speed performance. The guaranteed propagation delay may be tested by using the two factory-programmed test columns and a test row as a test vehicle for speed testing. These test columns are to be deleted automatically in the process of programming.

The vertical fuses of an unprogrammed device, being normally open-circuited, set all AND terms to a High state and disconnected to all OR terms. The OR terms are normally Low when they are not connected to the AND terms. Once an AND term is programmed to make connections with the OR array, it cannot be disconnected. However, AND terms may be disabled by having the true and inverting input buffers (e.g.,  $A^*/A$ ,  $B^*/B$ , etc.) of all inputs connected to the AND term which is to be disabled.

While even a single input, ( $A^*/A$ ), will hold the AND term to a Low, glitches may develop if the input voltage changes state. Therefore, it is recommended that the complementary buffers of all inputs in the disabled AND term be connected.

## Programming the PLHS473

The programming table and symbols of the PLHS473 are shown in Table 1 where there is a place for every function that is shown in Figure 1. The table is divided into two main

sections. The left side of the table, sections A and B, represents the input side of the AND array (section A has all dedicated inputs  $I_0$  to  $I_{10}$ , section B has inputs from the bidirectional I/Os  $B_0$  to  $B_8$ ), whereas the right side, sections C, D, and E, represents the outputs of the OR array. Section C represents the OR array which controls the tri-state output buffers of the bidirectional I/Os  $B_0$  to  $B_8$  and outputs  $O_A$  and  $O_B$ , while section D represents the OR array which drives the outputs. Section E controls the output polarity of each output. As shown in Table 1, the program table is very similar to a truth table. Each row represents one of the 24 product terms, while each column in sections A and B represents an input to the 24 product terms and in sections C and D, each column represents an output. The intersection of a column and a row in sections A and B represents four possible fuse configurations, namely, 1) both inverting and non-inverting input buffers are connected to the AND term, 2) only the inverting buffer is connected, 3) only the non-inverting input buffer is connected, and 4) both inverting and non-inverting buffers are disconnected. These four configurations are represented as "0", "L", "H", and "-", respectively. Each intersection of a row and a column in sections C and D involves only two fuse configurations, either connected or disconnected. Therefore, the entry there is either "A" or "-", respectively. In the polarity control section (section E), each square represents the configuration of the fuse connected to the Exclusive-OR, which is connected to a particular output pin. An "H" represents an Active-High or non-inverting output, an "L" represents an Active-Low or inverting output. See Table 1 for further details.

PLHS473 Primer

AN27

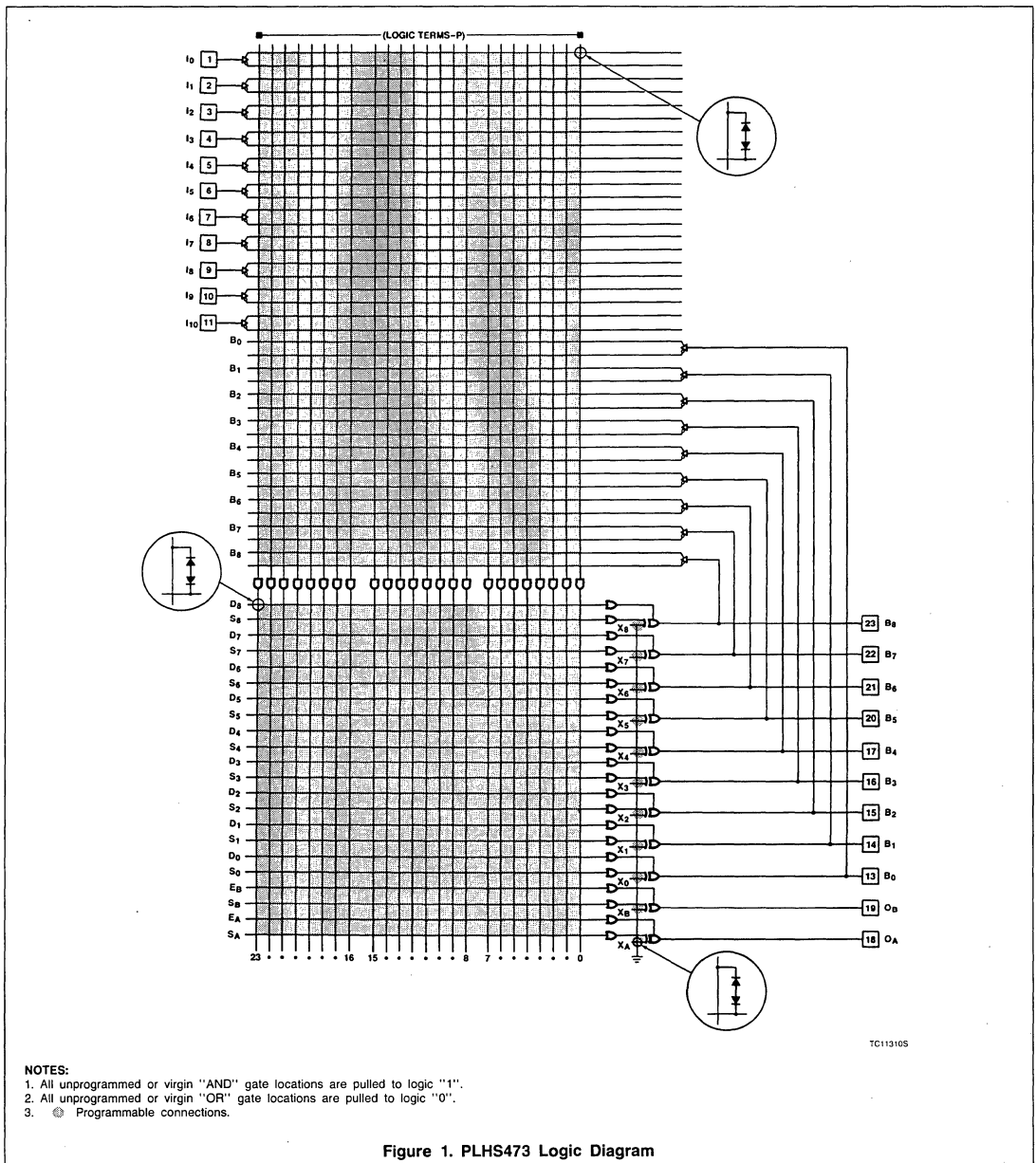


Figure 1. PLHS473 Logic Diagram

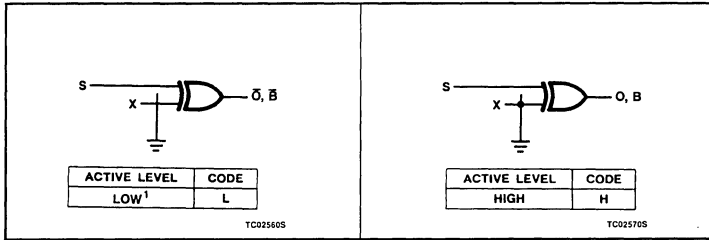




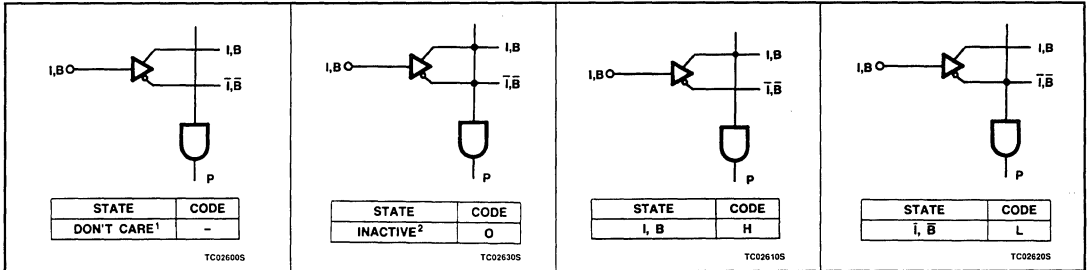
PLHS473 Primer

AN27

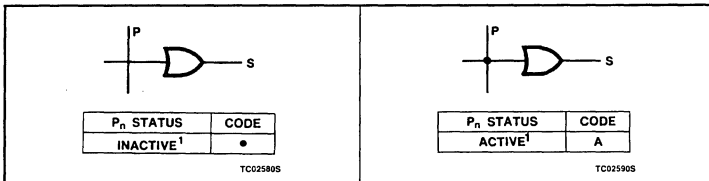
OUTPUT POLARITY — (0, B)



AND ARRAY — (I, B)



OR ARRAY — (O, B)



VIRGIN STATE

A factor shipped virgin device contains all fusible links.

1. All output at "L" polarity.
2. All P<sub>n</sub> terms are enable.
3. All P<sub>n</sub> terms are active on all outputs.

NOTES:

1. This is the initial unprogrammed state of all link pairs.
2. Any gate P<sub>n</sub> will be unconditionally inhibited if any one of its (I, B) link pairs is programmed for a connection.

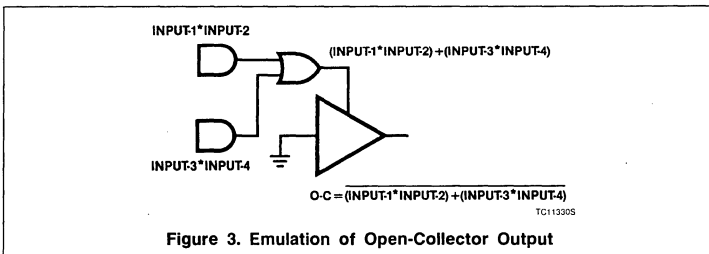


Figure 3. Emulation of Open-Collector Output



PLHS473 Primer

AN27

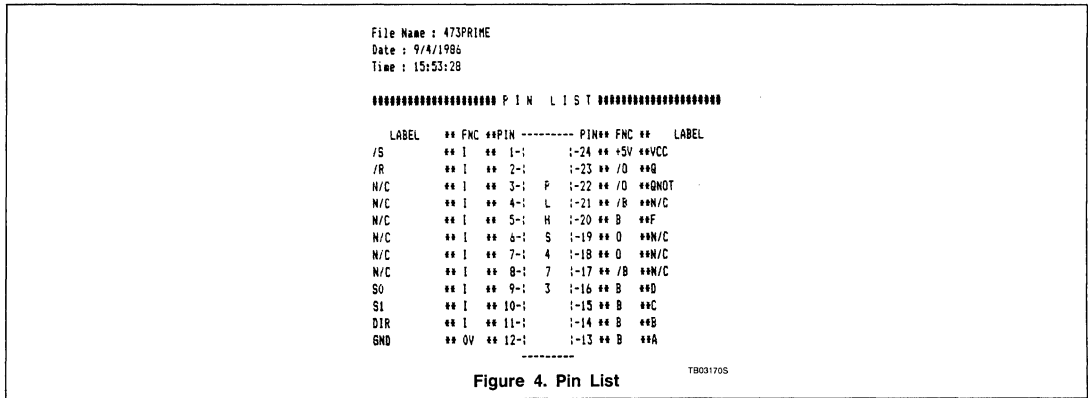


Figure 4. Pin List

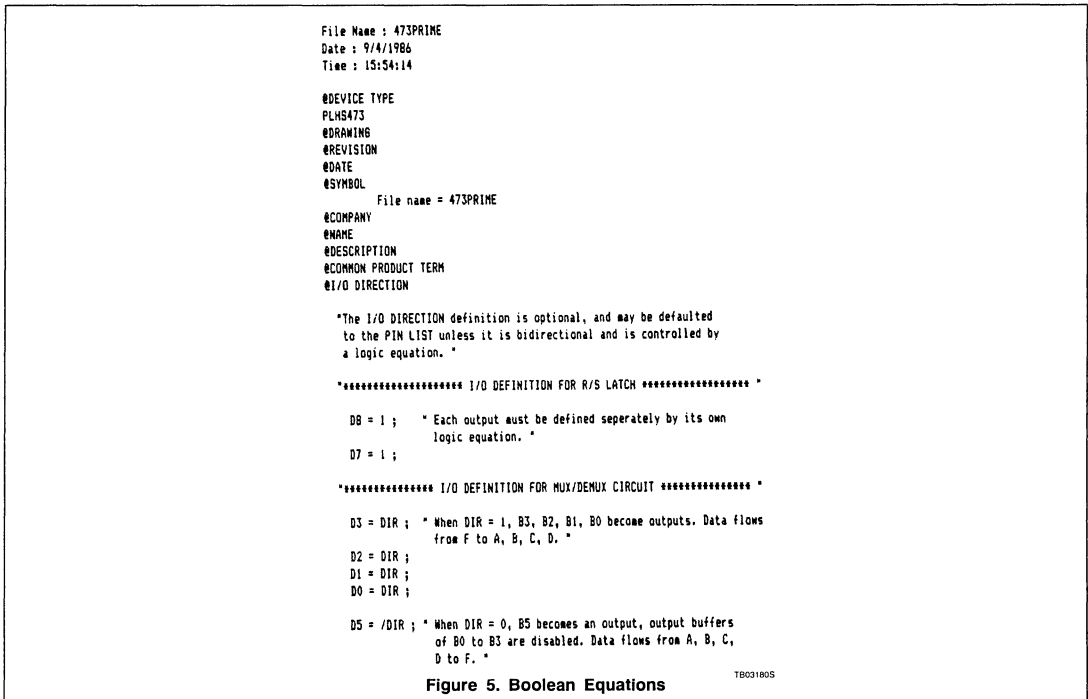


Figure 5. Boolean Equations

## PLHS473 Primer

## AN27

## @OUTPUT POLARITY

\* The definition of output polarity is optional and may be defaulted the PIN LIST. \*

\* \*\*\*\*\* POLARITY DEFINITION FOR R/S LATCH \*\*\*\*\* \*

X8, X7 = 1 ; \* Outputs with the same polarity may be defined in the same equation. Since the outputs Q and QNOT are defined as active LOW, this equation causes the XOR to function as an inverter. \*

\* \*\*\*\*\* POLARITY DEFINITION FOR MUX/DEMUX CIRCUIT \*\*\*\*\* \*

X5, X3, X2, X1, X0 = 0 ; \* Outputs B0, B1, B2, B3, B5 are active HIGH. \*

## @LOGIC EQUATION

\* \*\*\*\*\* EQUATIONS FOR R/S LATCH \*\*\*\*\* \*

Q = /( /S \* QNOT ) ; \* The equation must use the format output = /( ..... ); since output Q is defined as active LOW. \*

QNOT = /( /R \* Q ) ;

\* \*\*\*\*\* EQUATIONS FOR MUX/DEMUX CIRCUIT \*\*\*\*\* \*

F = ( A \* /S0 \* /S1 ) +  
 ( B \* S0 \* /S1 ) +  
 ( C \* /S0 \* S1 ) +  
 ( D \* S0 \* S1 ) ;

A = ( F \* /S0 \* /S1 ) ;  
 B = ( F \* S0 \* /S1 ) ;  
 C = ( F \* /S0 \* S1 ) ;  
 D = ( F \* S0 \* S1 ) ;

Figure 5. Boolean Equations (Continued)

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PLHS473 Primer

AN27

```

File Name : 473PRIME
Date : 9/4/1986
Time : 15:56:24

Cust/Project -
Date -
Rev/I. D. -

PLHS473                                ! POLARITY !
-----
T !                                     !LLLLLHLLLLH!
E !
R !      I      ! B(i) !E   D   !O   B(o) !
M !19876543210!876543210!88876543210!88876543210!
--10-----!-----!-----!-----!
0!-----H!-H-----!AA..A.A...!AAA.A.A...!
1!-----H!-H-----!AA..A.A...!AA.AA.A...!
2!-LL-----!-----H!AA..A.A...!AA..AAA...!
3!-LH-----!-----H!AA..A.A...!AA..AAA...!
4!-HL-----!-----H!AA..A.A...!AA..AAA...!
5!-HH-----!-----H!AA..A.A...!AA..AAA...!
6!-LL-----!-----H!AA..A.A...!AA..A.A.A...!
7!-LH-----!-----H!AA..A.A...!AA..A.A.A...!
8!-HL-----!-----H!AA..A.A...!AA..A.A.A...!
9!-HH-----!-----H!AA..A.A...!AA..A.A.A...!
10!-----!-----!AAAAA.A...!AA..A.A...!
11!H-----!-----!AA..A.AAAA!AA..A.A...!
12!L-----!-----!AA..AAA...!AA..A.A...!
13!-----!-----!.....!.....!
14!-----!-----!.....!.....!
15!-----!-----!.....!.....!
16!-----!-----!.....!.....!
17!-----!-----!.....!.....!
18!-----!-----!.....!.....!
19!-----!-----!.....!.....!
20!-----!-----!.....!.....!
21!-----!-----!.....!.....!
22!-----!-----!.....!.....!
23!-----!-----!.....!.....!

DSSNNNNN// QQNFDCBA                    NNNQNFDCBA
I10/////RS N/ /                          // N/ /
R CCCCCC  OC C                            CC OC C
T                                             T

```

Figure 6. Program Table

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# AN28

## High-Speed 12-Bit Tracking A/D Converter Using PLS179

### Application Note

### Application Specific Products

### INTRODUCTION

The general technique underlying the operation of this A/D converter is illustrated by the functional block diagram in Figure 1. The system consists of a D/A converter, a comparator circuit, and digital logic circuitry. The digital logic circuitry outputs a digital value which is converted to analog by the D/A converter.

The comparator senses when the output is greater or less than the input and causes the digital circuit to decrement or increment its digital output respectively. The initial conversion is completed in 13 clock cycles. If tracking mode is used, the A/D converter then tracks the input voltage as it changes by incrementing or decrementing 1-LSB per clock. The tracking function makes it possible to make an A/D conversion in one clock cycle if the input changes less than the value of 1-LSB per clock period. The conversion may be halted and the digital output, as well as the converted analog output from DAC, will hold their output constant indefinitely. This feature works well as sample-and-hold since its output voltage will not decay over time whereas the output of an analog sample/hold will decay due to charge leakages.

In order to avoid the violation of setup time by the output of the comparator, its output is latched. There is a built-in 2-phase clock in U2 which may be used to drive the logic circuitry and the latch of the comparator (see Signetics NE5105 data sheet for details on output latches of voltage comparators).

The analog input voltage may be sampled and held by an analog sample/hold circuit to

keep the input to the ADC from changing. The DONE output may be used to control the sample-and-hold if needed.

This paper discusses only the digital circuit which contains the SAR and the Up/Down Counter. The analog circuits are not within the scope of this paper.

### SAR

Two PLS179s are connected together to form a 12-bit shift register and up/down counter. The schematic diagram of the A/D converter is shown in Figure 2. U2 contains bits 0 to 4 and U1 contains Bits 5 to 11. Interconnects are made as shown in the diagram. The digital output to the DAC is in natural binary format (e.g. 0000 0000 0000 equal zero, and 1111 1111 1111 is full scale or 4095). After the /ST input becomes 0, at the rising edge of the next clock, the SAR is initialized to half-scale (1000 0000 0000) and the DONE flip-flop is reset to output 0 which causes the open-collector output /DONE\_OC to become high impedance. The digital output is converted by the DAC and is compared to the analog input voltage by the comparator. If the digital output is greater than the analog input, the SAR shifts the 1 to next MSB to the right. The content of the SAR becomes (0100 0000 0000). If the digital output is still greater than the input, the SAR shifts right one bit again. The content of the SAR then becomes (0010 0000 0000). The shifting of 1 to the next MSB is equivalent to reducing by half the value of the bit under consideration. If the output is still too large, the SAR reduces it by half again by shifting to the right one more time.

The SAR keeps shifting to the right until the digital output is less than the input. When the output is less than the input, the SAR adds one bit to the next MSB while keeping all the higher order bits unchanged. For example, if the current output is 0001 0000 0000 and the output is less than the input, the SAR adds one bit to the right at the next clock. The output becomes 0001 1000 0000. The output is again compared to the input. If the addition of that one bit is too much, it will be shifted to the right until the output becomes less than the input. When that happens, that SAR will again add one bit to the right. The algorithm of the SAR may be summarized as the following: If the output is greater than the input, shift to the right; otherwise add one bit to the right. This process continues until all 12 bits have been operated on. The last bit (Bit 0) is always changed from 0 to 1, which is used as the condition to set DONE to 1 which, in turn, sets open-collector output, /DONE\_OC, to 0.

### UP/DOWN COUNTER

After DONE becomes 1, if /ST and /HOLD are 1 and /TRACK is 0, the SAR turns into a 12-bit up/down counter. If the analog input voltage increases, the counter will increment by 1 at every clock until it matches the input. If the input decreases, the counter will decrement by 1. When /HOLD becomes 0, the counter is inhibited and the output is held indefinitely. The counters consist of 12 toggle flip-flops and 2 p-terms per flip-flop for directional control. The counter will operate only

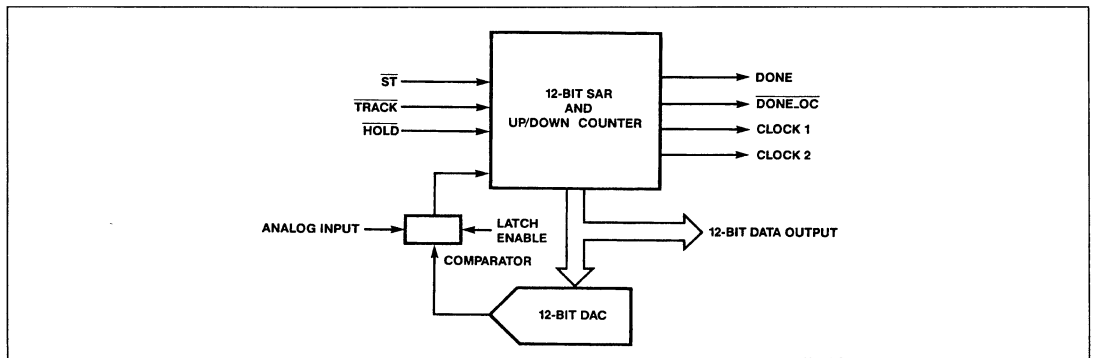


Figure 1. Functional Block Diagram of 12-Bit High-Speed A/D Converter

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# High-Speed 12-Bit Tracking A/D Converter Using PLS179

AN28

after the approximation cycle is completed and DONE is 1.

Since the /ST and /HOLD inputs may be asynchronous with the clock, in order to minimize the possibilities of having a metastable condition from happening, these inputs close-up are latched by flip-flops /START of U1 and /HLD of U2 respectively. Once they are latched, subsequent operation begins at the rising-edge of the next clock. The output of the comparator may be latched to prevent setup time violation. (Signetics NE5105 is a high-speed comparator with an output latch. External latch may be used with other comparators.)

### CLOCKS

U2 generates an optional 2-phase clock which may be used to control the latch of the comparator. The two clocks are basically 180° out of phase and CLOCK2 has an additional 25ns propagation delay behind CLOCK1. CLOCK2 is used to drive the clock-inputs of the PLS179 devices.

The clock frequency is controlled by R and C. Those who want to use the built-in clock

should experiment with RC time constants for the best value. It is recommended that the capacitance should be less than 1000pF for best results (see Ap Note AN13 for more detail).

### DONE AND /DONE\_OC

The output DONE is reset to 0 when /ST is 0. It remains 0 until the approximation cycle is completed. After the least significant bit becomes 1, the DONE bit becomes 1 at the next clock. It remains 1 until it is reset again by input /ST.

The /DONE\_OC output is configured to emulate an open-collector output. The output is programmed to have a logic 0. When DONE is 0, the Tri-state output buffer is set to Hi-Z condition. As soon as DONE equals 1, the Tri-state buffer is enabled and /DONE\_OC becomes 0.

In the initial phase of A/D conversion, 13 clock cycles are required. It is essential that the input voltage to the comparator remains unchanged while the SAR is converting. It may be necessary to have a sample/hold at

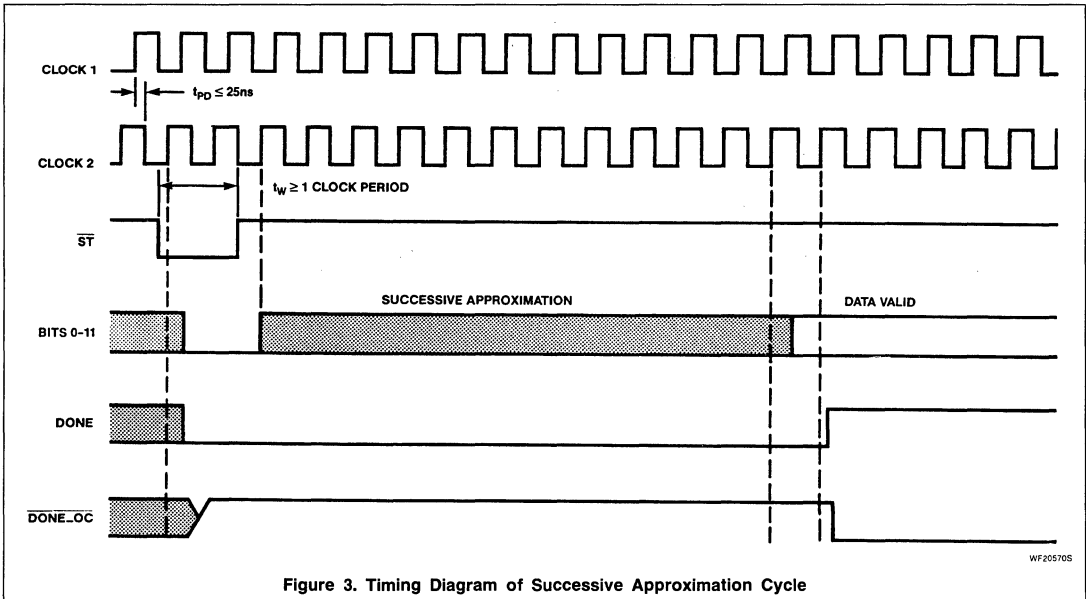
the front end. The DONE output may be used to control the analog sample/hold circuit.

### INPUT LATCHES

Flip-flop /START and 2 p-terms in U1 are configured as a non-inverting D flip-flop. The input, /ST, and the output /START have the same polarities. Flip-flop /HLD and 2 p-terms in U2 also form a non-inverting D flip-flop. The output /HLD and the input /HOLD have the same polarities.

### AMAZE IMPLEMENTATION

The implementation of the logic circuit using AMAZE is as shown in the appendices. The SAR circuit is first designed as a state machine (file name: ADCS.SEE). It is then partitioned into two PLS179s after proper pin assignments are made. Then the up/down counter, input latches, 2-phase clocks and the open-collector output, are implemented by using Boolean equations in their respective .BEE files (file names: ADCB1.BEE and ADCB2.BEE) in AMAZE. The files are then assembled to produce the fuse-maps of PLS179 (ADCB1.STD and ADCB2.STD).



## High-Speed 12-Bit Tracking A/D Converter Using PLS179

AN28

## APPENDIX A: STATE EQUATIONS OF SAR

```

File Name : ADCS
Date : 10/21/1986
Time : 11:2:14

@DEVICE SELECTION
ADCB1/PLS179
ADCB2/PLS179

@STATE VECTORS
[ /START, BIT11, BIT10, BIT9, BIT8, BIT7, BIT6, BIT5, BIT4, BIT3, BIT2,
BIT1, BIT0, DONE ]

INIT          = 0 ---- - - - - - b ; "START CONVERSION PROCESS"
HALFSCALE    = - 1000 0000 0000 0 b ; "SET SAR TO HALF SCALE"
ST2048       = 1 1000 0000 0000 0 b ; "PRESENT STATE = 2048 (HALF SCALE)"
ST1024       = 1 -100 0000 0000 0 b ;
ST512        = 1 --10 0000 0000 0 b ;
ST256        = 1 ---1 0000 0000 0 b ;
ST128        = 1 ---- 1000 0000 0 b ;
ST64         = 1 ---- -100 0000 0 b ;
ST32         = 1 ---- --10 0000 0 b ;
ST16         = 1 ---- ---1 0000 0 b ;
ST8          = 1 ---- ---- 1000 0 b ;
ST4          = 1 ---- ---- -100 0 b ;
ST2          = 1 ---- ---- --10 0 b ;
ST1          = 1 ---- ---- ---1 0 b ;

AD1024       = - -1-- - - - - - b ; "ADD 1 BIT TO THE RIGHT"
AD512        = - - -1- - - - - - b ;
AD256        = - - --1- - - - - - b ;
AD128        = - - ---1- - - - - - b ;
AD64         = - - ---- 1-- - - - - b ;
AD32         = - - ---- -1- - - - - b ;
AD16         = - - ---- --1- - - - - b ;
AD8          = - - ---- ---1- - - - b ;
AD4          = - - ---- ---- 1-- - - b ;
AD2          = - - ---- ---- -1- - - b ;
AD1          = - - ---- ---- --1- - - b ;
END          = - - ---- ---- ---1 b ;

SH1024       = - - 01-- - - - - - b ; "SHIFT ONE BIT TO THE RIGHT"
SH512        = - - -01- - - - - - b ;
SH256        = - - --01- - - - - - b ;
SH128        = - - ---0 1-- - - - - b ;
SH64         = - - ---- 01-- - - - - b ;
SH32         = - - ---- -01- - - - - b ;
SH16         = - - ---- --01- - - - - b ;
SH8          = - - ---- ---0 1-- - - b ;
SH4          = - - ---- ---- 01-- - - b ;
SH2          = - - ---- ---- -01- - - b ;
SH1          = - - ---- ---- --01- - - b ;
SH0          = - - ---- ---- ---0 1 b ;

@INPUT VECTORS
[ COMPARE ]
GREATER = 1 b ; "IF DIGITAL OUTPUT IS GREATER THAN ANALOG INPUT, ...."
LESS    = 0 b ; "IF DIGITAL OUTPUT IS LESS THAN ANALOG INPUT, ...."

@OUTPUT VECTORS

```

TB033205

## High-Speed 12-Bit Tracking A/D Converter Using PLS179

AN28

## APPENDIX A: STATE EQUATIONS OF SAR (Continued)

```
@TRANSITIONS
WHILE [ INIT ]
  IF [ ] THEN [ HALFSCALE ] "INITIALIZE REGISTER TO HALF SCALE"
WHILE [ ST2048 ]
  IF [ GREATER ] THEN [ SH1024 ] "IF GREATER THAN, SHIFT 1 BIT"
  IF [ LESS ] THEN [ AD1024 ] "IF LESS THAN, ADD 1 BIT"
WHILE [ ST1024 ]
  IF [ GREATER ] THEN [ SH512 ]
  IF [ LESS ] THEN [ AD512 ]
WHILE [ ST512 ]
  IF [ GREATER ] THEN [ SH256 ]
  IF [ LESS ] THEN [ AD256 ]
WHILE [ ST256 ]
  IF [ GREATER ] THEN [ SH128 ]
  IF [ LESS ] THEN [ AD128 ]
WHILE [ ST128 ]
  IF [ GREATER ] THEN [ SH64 ]
  IF [ LESS ] THEN [ AD64 ]
WHILE [ ST64 ]
  IF [ GREATER ] THEN [ SH32 ]
  IF [ LESS ] THEN [ AD32 ]
WHILE [ ST32 ]
  IF [ GREATER ] THEN [ SH16 ]
  IF [ LESS ] THEN [ AD16 ]
WHILE [ ST16 ]
  IF [ GREATER ] THEN [ SH8 ]
  IF [ LESS ] THEN [ AD8 ]
WHILE [ ST8 ]
  IF [ GREATER ] THEN [ SH4 ]
  IF [ LESS ] THEN [ AD4 ]
WHILE [ ST4 ]
  IF [ GREATER ] THEN [ SH2 ]
  IF [ LESS ] THEN [ AD2 ]
WHILE [ ST2 ]
  IF [ GREATER ] THEN [ SH1 ]
  IF [ LESS ] THEN [ AD1 ]
WHILE [ ST1 ]
  IF [ GREATER ] THEN [ SH0 ]
  IF [ ] THEN [END]
```

TB033305

## High-Speed 12-Bit Tracking A/D Converter Using PLS179

AN28

## APPENDIX B: PIN LISTS

File Name : ADCB2  
Date : 10/21/1986  
Time : 10:58:26

\*\*\*\*\* P I N L I S T \*\*\*\*\*

LABEL	** FNC	**PIN	-----	PIN**	FNC **	LABEL
CLOCK	** CK	** 1-!		!-24	** +5V	**VCC
/START	** I	** 2-!		!-23	** /B	**/DONE_OC
COMPARE	** I	** 3-!		!-22	** B	**N/C
/HOLD	** I	** 4-!	P	!-21	** 0	**/HLD
/TRACK	** I	** 5-!	L	!-20	** 0	**BIT4
BITS	** I	** 6-!	S	!-19	** 0	**BIT3
N/C	** I	** 7-!	1	!-18	** 0	**BIT2
N/C	** I	** 8-!	7	!-17	** 0	**BIT1
N/C	** I	** 9-!	9	!-16	** 0	**BIT0
RC	** /B	** 10-!		!-15	** 0	**DONE
CLOCK1	** 0	** 11-!		!-14	** /0	**CLOCK2
GND	** OV	** 12-!		!-13	** /OE	**N/C

TB003405

File Name : ADCB1  
Date : 10/21/1986  
Time : 10:53:17

\*\*\*\*\* P I N L I S T \*\*\*\*\*

LABEL	** FNC	**PIN	-----	PIN**	FNC **	LABEL
CLOCK	** CK	** 1-!		!-24	** +5V	**VCC
/ST	** I	** 2-!		!-23	** /B	**N/C
COMPARE	** I	** 3-!		!-22	** 0	**/START
/HLD	** I	** 4-!	P	!-21	** 0	**BIT11
/TRACK	** I	** 5-!	L	!-20	** 0	**BIT10
BIT4	** I	** 6-!	S	!-19	** 0	**BIT9
BIT3	** I	** 7-!	1	!-18	** 0	**BIT8
BIT2	** I	** 8-!	7	!-17	** 0	**BIT7
BIT1	** I	** 9-!	9	!-16	** 0	**BIT6
BIT0	** I	** 10-!		!-15	** 0	**BIT5
DONE	** I	** 11-!		!-14	** /B	**N/C
GND	** OV	** 12-!		!-13	** /OE	**N/C

TB003705

## High-Speed 12-Bit Tracking A/D Converter Using PLS179

AN28

## APPENDIX C: BOOLEAN EQUATIONS OF UP/DOWN COUNTER AND INPUT LATCH

```

File Name : ADCB1
Date : 10/21/1986
Time : 10:54:48

@DEVICE TYPE
PLS179
@DRAWING
@REVISION
@DATE
@SYMBOL
FILE NAME : ADCB1

@COMPANY
@NAME
@DESCRIPTION
@COMMON PRODUCT TERM
@COMPLEMENT ARRAY
@I/O DIRECTION
@OUTPUT POLARITY
@FLIP FLOP CONTROL
FC = 1 ; "SET ALL FLIP FLOP TO BE J/K"

@OUTPUT ENABLE
@REGISTER LOAD
@ASYNCHRONOUS PRESET/RESET
@FLIP FLOP MODE
@LOGIC EQUATION
"NON-INVERTING INPUT LATCH: /START = /ST "
START : J = ST ;
      K = /ST ;
"UP/DOWN COUNTER ROUTINE"
/BIT5 : T = /START * TRACK * DONE * /HLD * COMPARE * /BIT0 * /BIT1 *
           /BIT2 * /BIT3 * /BIT4 +
           /START * TRACK * DONE * /HLD * /COMPARE * BIT0 * BIT1 *
           BIT2 * BIT3 * BIT4 ;
/BIT6 : T = /START * TRACK * DONE * /HLD * COMPARE * /BIT0 * /BIT1 *
           /BIT2 * /BIT3 * /BIT4 * /BITS +
           /START * TRACK * DONE * /HLD * /COMPARE * BIT0 * BIT1 *
           BIT2 * BIT3 * BIT4 * BITS ;
/BIT7 : T = /START * TRACK * DONE * /HLD * COMPARE *
           /BIT0 * /BIT1 * /BIT2 * /BIT3 * /BIT4 * /BITS * /BIT6 +
           /START * TRACK * DONE * /HLD * /COMPARE *
           BIT0 * BIT1 * BIT2 * BIT3 * BIT4 * BITS * BIT6 ;
/BIT8 : T = /START * TRACK * DONE * /HLD * COMPARE * /BIT0 * /BIT1 *
           /BIT2 * /BIT3 * /BIT4 * /BITS * /BIT6 * /BIT7 +
           /START * TRACK * DONE * /HLD * /COMPARE * BIT0 * BIT1 *
           BIT2 * BIT3 * BIT4 * BITS * BIT6 * BIT7 ;
/BIT9 : T = /START * TRACK * DONE * /HLD * COMPARE * /BIT0 * /BIT1 *
           /BIT2 * /BIT3 * /BIT4 * /BITS * /BIT6 * /BIT7 * /BIT8 +
           /START * TRACK * DONE * /HLD * /COMPARE * BIT0 * BIT1 *
           BIT2 * BIT3 * BIT4 * BITS * BIT6 * BIT7 * BIT8 ;
/BIT10 : T = /START * TRACK * DONE * /HLD * COMPARE * /BIT0 * /BIT1 *
            /BIT2 * /BIT3 * /BIT4 * /BITS * /BIT6 * /BIT7 * /BIT8 *
            /BIT9 +
            /START * TRACK * DONE * /HLD * /COMPARE * BIT0 * BIT1 *
            BIT2 * BIT3 * BIT4 * BITS * BIT6 * BIT7 * BIT8 *
            BIT9 ;
/BIT11 : T = /START * TRACK * DONE * /HLD * COMPARE * /BIT0 * /BIT1 *
            /BIT2 * /BIT3 * /BIT4 * /BITS * /BIT6 * /BIT7 * /BIT8 *
            /BIT9 *
            /BIT10 +
            /START * TRACK * DONE * /HLD * /COMPARE * BIT0 * BIT1 *
            BIT2 * BIT3 * BIT4 * BITS * BIT6 * BIT7 * BIT8 *
            BIT9 * BIT10 ;

```

TB033905

## High-Speed 12-Bit Tracking A/D Converter Using PLS179

AN28

## APPENDIX C: BOOLEAN EQUATIONS OF UP/DOWN COUNTER AND INPUT LATCH (Continued)

```

File Name : ADCB2
Date : 10/21/1986
Time : 10:58:56

@DEVICE TYPE
PLS179
@DRAWING
@REVISION
@DATE
@SYMBOL
FILE NAME : ADCB2

@COMPANY
@NAME
@DESCRIPTION
@COMMON PRODUCT TERM
@COMPLEMENT ARRAY
@I/O DIRECTION
DO = RC ; "RC OSCILLATOR"
DS = DONE ; "ENABLE /DONE_OC TO OUTPUT A LOGIC LOW."
@OUTPUT POLARITY
@FLIP FLOP CONTROL
FC = 1 ;
@OUTPUT ENABLE
@REGISTER LOAD
@ASYNCHRONOUS PRESET/RESET
@FLIP FLOP MODE
"MO, M1, M2, M3, M4, M5 = 1 ; SET F0 - F5 TO J/K FLIP FLOPS."

@LOGIC EQUATION
"NON-INVERTING INPUT LATCH : /HLD = /HOLD "
HLD : J = HOLD ;
K = /HOLD ;

"UP/DOWN COUNTER ROUTINE"
/BIT0 : T = /START * TRACK * DONE * /HLD ;
/BIT1 : T = /START * TRACK * DONE * /HLD * /COMPARE * BIT0 +
        /START * TRACK * DONE * /HLD * /COMPARE * /BIT0 ;
/BIT2 : T = /START * TRACK * DONE * /HLD * /COMPARE * BIT0 * BIT1 +
        /START * TRACK * DONE * /HLD * /COMPARE * BIT0 * /BIT1 ;
/BIT3 : T = /START * TRACK * DONE * /HLD * /COMPARE * BIT0 * BIT1 *
        /START * TRACK * DONE * /HLD * /COMPARE * /BIT0 * /BIT1 * /
BIT2 +
        /START * TRACK * DONE * /HLD * /COMPARE * /BIT0 * /BIT1 * /
BIT2 ;
/BIT4 : T = /START * TRACK * DONE * /HLD * /COMPARE * BIT0 * BIT1 *
        /START * TRACK * DONE * /HLD * /COMPARE * /BIT0 * /BIT1 * /
BIT2 *
        BITS +
        /START * TRACK * DONE * /HLD * /COMPARE * /BIT0 * /BIT1 * /
BIT2 *
        /BITS ;
/DONE_OC = /( 1 ) ;

"RC OSCILLATOR"
RC = /(1) ;
CLOCK1 = RC ;
CLOCK2 = /( CLOCK1 ) ; "BUILT-IN DELAY OF 1 tPD"

```

TB020805







### Application Specific Products

#### SUMMARY

The evolution of Programmable Logic Devices (PLD's) has led to the birth of a new generation of programmable devices designated as PML (Programmable Macro Logic). The immense versatility of these devices brings them closer as plausible alternatives to semicustom design approaches in low-to-medium ranges of applications. The following paper begins with a background on PML and a brief description of the PML basic architecture (See Reference 1.) Next, the first PML devices are introduced with a detailed discus-

sion of the PLHS501. The implementation of PML in the AMAZE software package is presented. A system level example intends to demonstrate the capabilities of PML as an eloquent and efficient design alternative.

#### THE EMERGENCE OF THE THIRD GENERATION PLD ARCHITECTURE

PML was introduced at WESCON '85 by Signetics Corporation. The unique architecture of PML breaks away into a new era of

programmable logic devices. The purpose of the PML architecture is to overcome the two level AND-OR bottleneck and provide the user with a higher level of logic integration. Current PLD's rely on two levels of logic transformation to implement combinational logic in Sum-Of-Products (SOP) form. In addition various PLD's make use of higher level macros such as flip-flops to form sequential logic functions. These macros connect the AND-OR chain to dedicated I/O pins.

Figure 1 show the basic architecture of one of the most recent PAL<sup>TM</sup> devices. It is clear that this architecture is inefficient in making full use of the available on-chip resources. This is due to the fact that an unused I/O macro will be wasted and remains futile.

For example, if an I/O pin is used as an input, the output macros are all wasted. Obviously, such an architecture cannot provide the user with an increase in the levels of logic integration. The PML device takes advantage of the fundamental architecture shown in Figure 2 to overcome these deficiencies and waste of on-chip resources. As shown in Figure 2, PML incorporates the NAND-NAND gate equivalence to break the AND-OR bottleneck.

The core of the PML is the programmable NAND-NAND network which connects the input and output macros to each other. Thus the inputs, outputs, and function macros are all connected by a single array.

At the present, two devices are under development which employ the above architecture. Both devices are fabricated by the Signetics state-of-the-art oxide isolation process and are packaged in 52-pin PLCC.

The first device available will be the PLHS501. The seemingly simple structure of this device can implement every logic function furnished by the current PAL<sup>TM</sup>/PLA devices. Although the PLHS501 is principally a combinational logic device, its unique architecture makes it an ideal tool for applications involving asynchronous state machines (See Reference 2.)

The PLHS502 is a sequential logic device. It supplements the PLHS501 features with sixteen edge-triggered flip-flops. The device can provide diverse applications encompassing synchronous and asynchronous state machine designs.

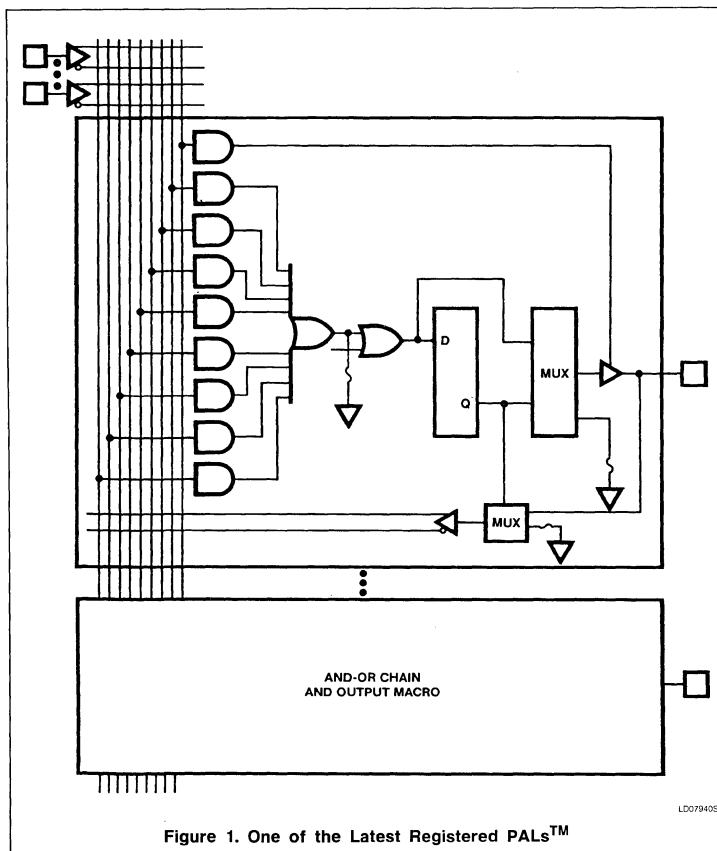


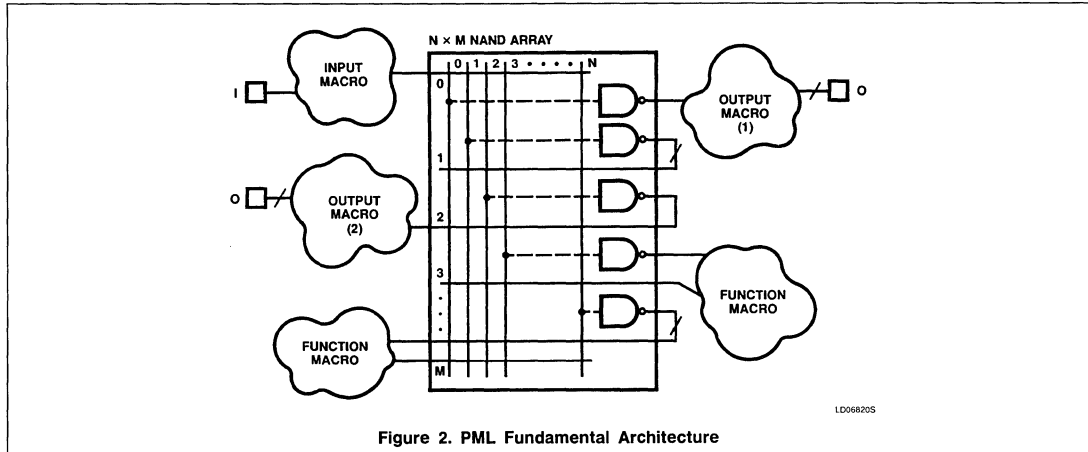
Figure 1. One of the Latest Registered PALs<sup>TM</sup>

# PLHS501 Programmable Macro Logic Primer

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**Table 1. Functional Description of PLHS501 I/O Pins**

PIN NO.	IDENTIFIER	FUNCTION
41-45, 47-52, 1-7, 9-14	I0-I23	Dedicated inputs
37-40	/B0-/B3	Fuse-programmable bidirectional I/Os with Active-Low outputs. Can be configured as open-collector outputs.
15-18	B4-B7	Logic controlled bidirectional I/Os with Active-High Tri-state outputs.
28-29 30-31 32-33 35-36	X0-X1 X2-X3 X4-X5 X6-X7	Pairs of Tri-state Exclusive-OR outputs that have common Output Enable.
19, 21 22-23	O0-O1 O2-O3	Pairs of dedicated Active-Low Tri-state output buffers. Each pair has common Output Enable control.
24-25 26-27	O4-O5 O6-O7	Pairs of dedicated Active-High Tri-state output buffers. Each pair has common Output Enable control.



**Figure 2. PML Fundamental Architecture**

# PLHS501 Programmable Macro Logic Primer

AN29

## THE PLHS501 PML

The PLHS501 architecture in Figure 3 exhibits an exquisite logic tool. The device provides a combination of 72 NAND terms, 24 dedicated inputs (I0-I23), eight bidirectional I/O's (B0-B7), eight exclusive-OR outputs (X0-X7),

and eight dedicated outputs (O0-O7). Figure 4 shows the PLHS501 logic diagram and Table 1 illustrates the functional breakdown of the PLHS501 I/O pins.

Since the output of each NAND term feeds back to the inputs of the NAND array, intri-

cate logic functions can be implemented without wasting valuable I/O pins. For example, in order to implement an internal 'RS' latch in a combinational PAL<sup>TM</sup>/PLD, at least two inputs and two outputs are required. The same internal latch can be configured by the PLHS501 without using any I/O pins.

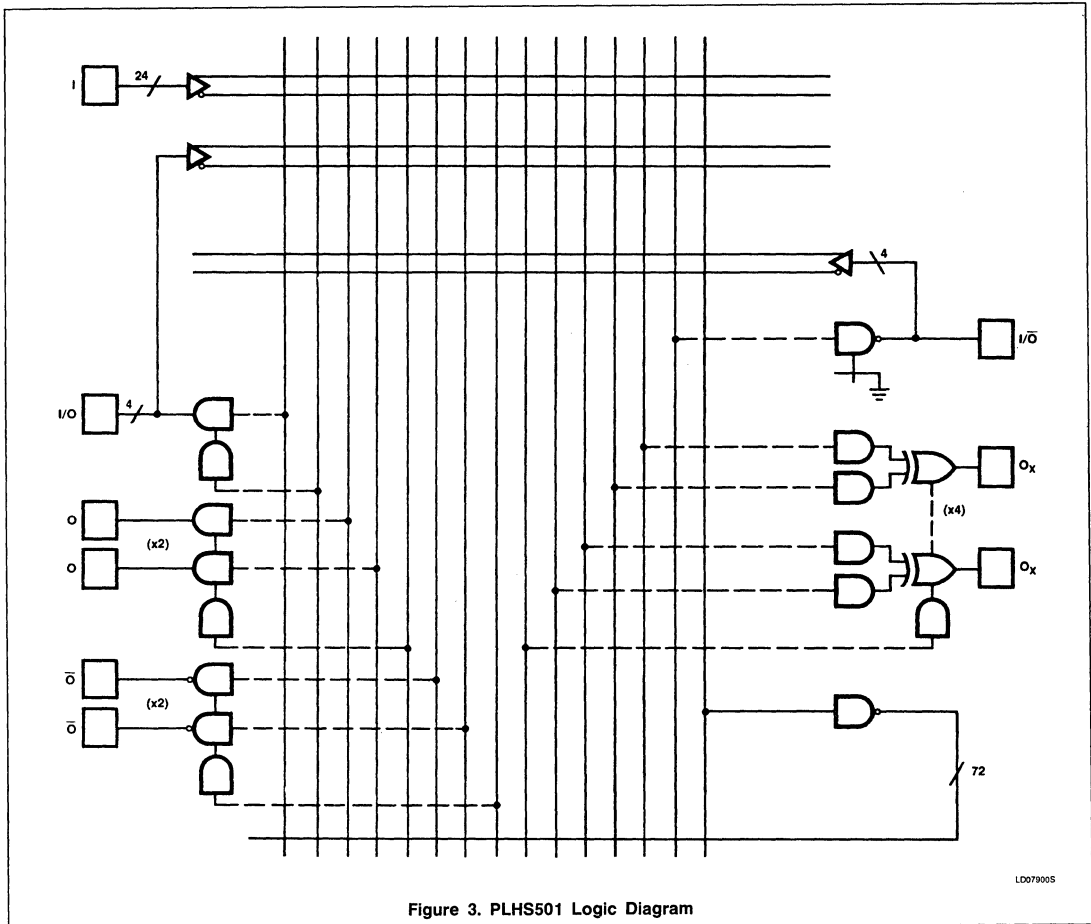


Figure 3. PLHS501 Logic Diagram

LD079005

# PLHS501 Programmable Macro Logic Primer

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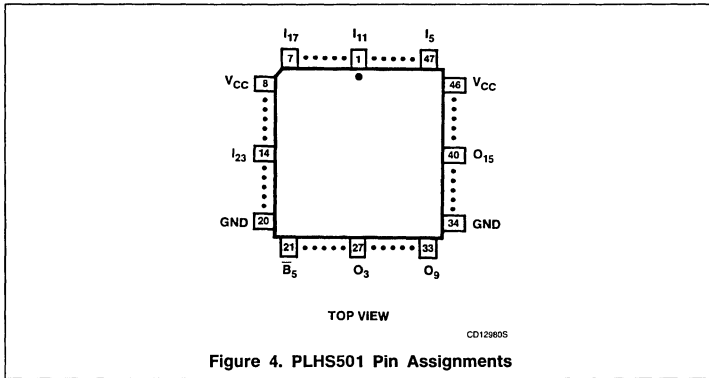
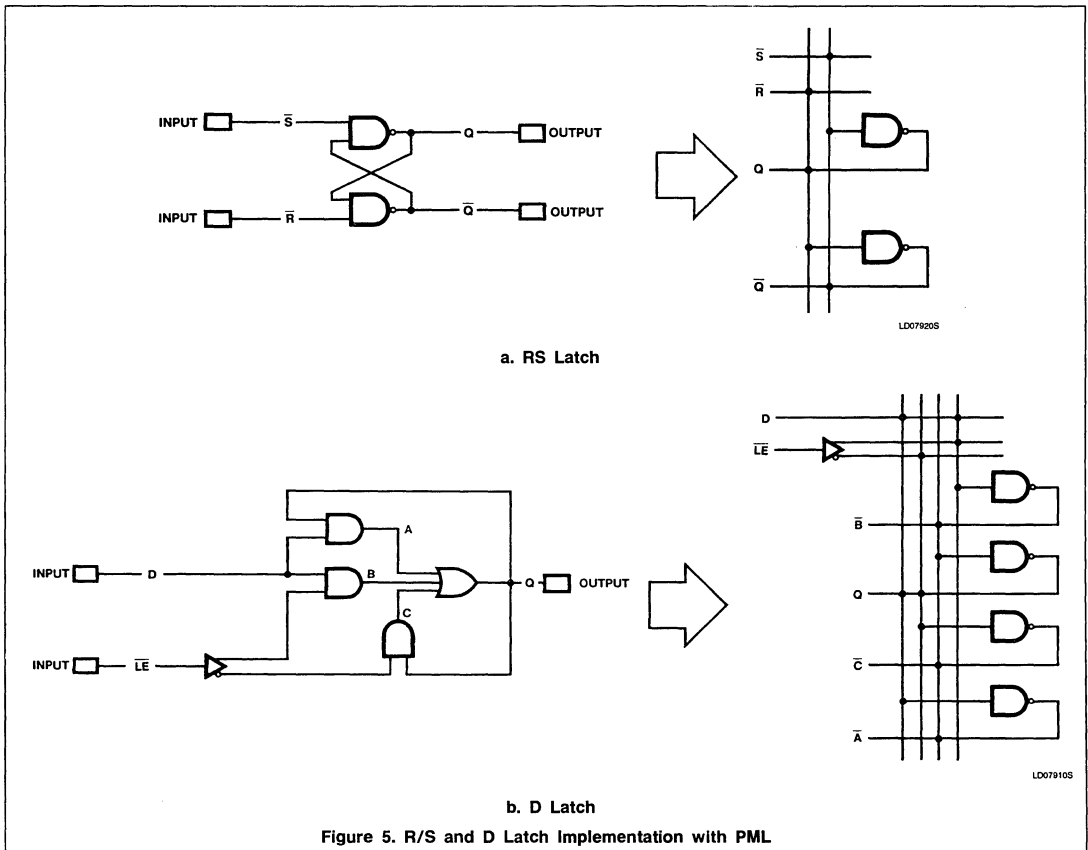


Figure 4. PLHS501 Pin Assignments

Figure 5 illustrates how 'RS' and 'D' latches are implemented in the PLHS501.

Another eminent application of the PLHS501 is in generating asynchronous state machines.

The blend of internal feedback paths together with the abundant number of gates makes this device suitable for designing asynchronous state machines which employ propagation delays of feedback paths as memory elements as shown in Figure 6. (See Reference 2.)



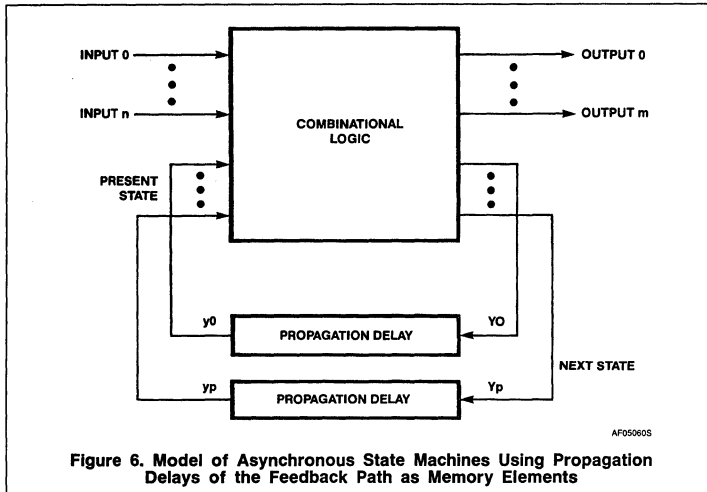
a. RS Latch

b. D Latch

Figure 5. R/S and D Latch Implementation with PML

# PLHS501 Programmable Macro Logic Primer

# AN29



**Figure 6. Model of Asynchronous State Machines Using Propagation Delays of the Feedback Path as Memory Elements**

graphs briefly explain the implementation of PML in the AMAZE structure.

### BLAST

The basic elements of BLAST are:

1. Boolean Equation Entry (BEE).
2. State Equation Entry (SEE).
3. Schematic To Boolean Converter (STBC).
  1. BEE accepts user defined logic in the form of boolean equations and produces an AMAZE standard fuse file. The boolean notation in BEE will account for the following PML features.
    - a. The single array architecture provides an option to specify the number of logic (gate) levels that accommodate a specified function. The number of gate levels dictate the delay between the inputs and outputs. The number of logic levels for each function can be specified using the following notation:

LABEL [ number of logic levels ] = equation; where LABEL is the user designated name of the output pin.

- b. Some outputs have more than one gate associated with them (for example, registered or EXOR outputs). The input SIDE of these outputs can be specifically defined. For example:
 

Pin Label: R = eqn;  
              S = eqn;
- c. User definable CLOCK Logic (e.g. as in the PLHS502) can be specified.
- d. For PML devices the Sum-of-Products (SOP) can be defined as common terms.

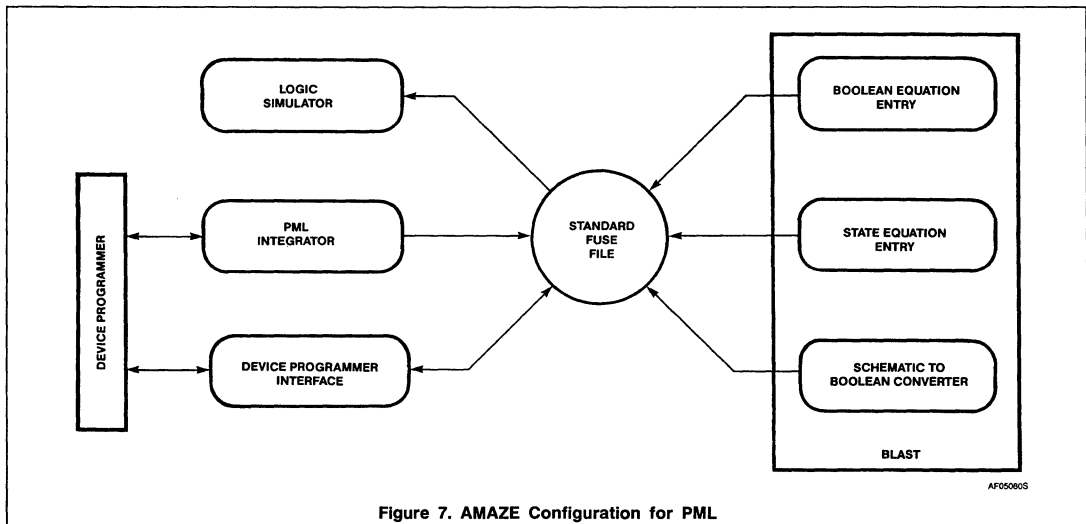
### PML DEVELOPMENT SOFTWARE

Programmable logic development software has become an integral part of the PLD design process. Without software tools PLDs become perplexing devices which are inconvenient to use. Development software enables the user to take full advantage of the programmable logic's resources. The complexity of the PML devices makes software an indispensable element in the design process. The AMAZE PLD design software, as noted in Reference 3, has been developed for Signetics programmable logic devices. PML

design and development will be fully supported by AMAZE. Figure 7 shows the AMAZE configuration for supporting PML. The structure of the software is based on the following modules:

- .BLAST (Boolean Logic And State Transfer entry)
- .DPI (Device Programmer Interface)
- .SIM (PLD functional SIMulator)
- .PI (PML Integrator)

The foundation for the above modules is an AMAZE standard fuse file (STD). The STD file is the common means of communication between all the modules. The following para-



**Figure 7. AMAZE Configuration for PML**

# PLHS501 Programmable Macro Logic Primer

AN29

2. SEE accepts state machine definitions and produces the AMAZE standard fuse file. Particularly, SEE will include asynchronous state machine implementations utilizing the PLHS501.

3. STBC convert schematic netlists produced by CAD systems such as Futurenet™, Daisy, and Mentor into an AMAZE BEE file. STBC will fully embody the PML in the following manner:

a. De Morgan's theorem is applied to produce equations in SOP form. All the functions in SOP form are then converted into their NAND- NAND equivalent.

b. The converter will determine the polarity and the number of levels in each equation and will automatically determine the correct output polarity.

## DPI

Device Programmer Interface provides the interface between the AMAZE standard fuse file and a commercial programmer. It allows the transmission of data to and from the device programmer.

## SIM

The functional simulator uses the AMAZE standard fuse file in the following manner:

a. An event driven simulator will assess the delays within the PML in order to properly simulate the pattern.

b. Automatically generates test vectors for the pattern simulation.

## PI

The PML Integrator is a conversion that transforms various PAL™ or PLD circuits into a PML device. It will automatically fit multiple PAL™/PLD devices into a single PML. It is capable of automatically receiving patterns from a commercial device programmer and downloading it back to the programmer after the PML transformation. The implementation of an 'Integrator' will allow the automatic conversion of numerous PAL™/PLDs into a single PML device.

AMAZE will not be the total extent of development software available for the PML devices. The task of implementing PML design software is already underway by a number of different vendors of CAD software.

## PLHS501 DESIGN EXAMPLE

The following example intends to manifest the capabilities of the PLHS501. Figure 8 shows a system formed with TTL logic. The system requirements make it imperative only to use discrete asynchronous latches. Thus, none of the 7 latches in the system can be directly replaced by registers. The system diagram is drafted using Futurenet™ DASH-2 Schematic Designer. The system is partitioned into two PLS173s and one PLS153. In order to convert the system into its targeted PLD's, the PINLIST (see Figures 9a-9c) has to be defined. Using the AMAZE PIN-LIST editor, the specified PLD's are labeled with the same labels as those on the system schematic (Figure 8). After the declaration of labels, AMAZE automatically converts the system to the designated PLDs. The AMAZE

generated boolean equation files are shown in Figures 9a, 9b, and 9c. Figure 10 shows the overall system implemented with PLDs. The logic condensation capabilities of PML makes it feasible to replace the whole system by a single PLHS501 (Figure 11). The PLHS501 in this design will still have ample space for any future additions.

The above example demonstrates only part of the PLHS501 capabilities. The introduction of PML devices and their immense logic power will pave the way for a new generation of efficient and elegant systems.

## REFERENCES

1. Cavlan, Napoleone 1985. "Third Generation PLD Architecture Breaks AND-OR Bottleneck", WESCON 1985 Conference Proceedings.
2. Wong, David K. "Third Generation PLS Architecture and its Applications", Electro 1986 Conference Proceedings.
3. "1986 PLD Data Manual", Signetics Corporation.

# PLHS501 Programmable Macro Logic Primer

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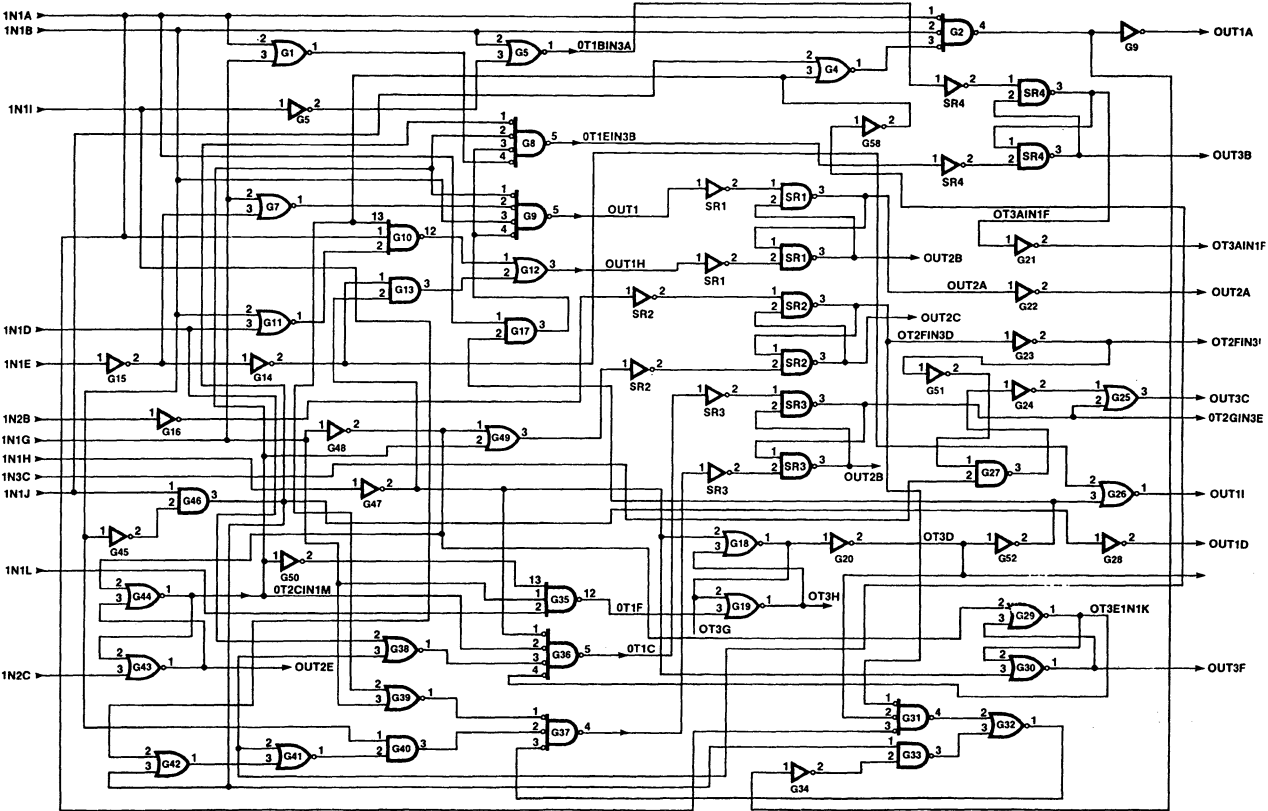


Figure 8. System Implemented with TTL Logic

LM70385

## PLHS501 Programmable Macro Logic Primer

AN29

File Name : PART1  
Date : 12/10/1986  
Time : 18:25:54

##### P I N L I S T #####

LABEL	** FNC	**PIN	-----	PIN** FNC	** LABEL
IN1A	** I	** 1-1		1-24 ** +5V	**VCC
IN1B	** I	** 2-1		1-23 ** 0	**OUT1I
OT3G	** I	** 3-1		1-22 ** 0	**OUT1H
IN1D	** I	** 4-1	P	1-21 ** 0	**OUT1G
IN1E	** I	** 5-1	L	1-20 ** 0	**OT1F
OT3AIN1F	** I	** 6-1	S	1-19 ** 0	**OT1EIN3B
IN1G	** I	** 7-1	1	1-18 ** 0	**OUT1D
IN1H	** I	** 8-1	7	1-17 ** 0	**OT1C
IN1I	** I	** 9-1	3	1-16 ** 0	**OT1BIN3A
IN1J	** I	** 10-1		1-15 ** 0	**OUT1A
OT3EIN1K	** I	** 11-1		1-14 ** I	**OT2CIN1M
GND	** OV	** 12-1		1-13 ** I	**IN1L

TB034005

File Name : PART1  
Date : 12/10/1986  
Time : 18:26:56

@DEVICE TYPE

PLS173

@DRAWING

@REVISION

@DATE

@SYMBOL

@COMPANY

@NAME

PART1

@DESCRIPTION

@I/O DIRECTION

@LOGIC EQUATION

OUT1A = /IN1A\*/IN1B\*(IN1J+/OT3AIN1F);

OT1BIN3A = /IN1B\*IN1I;

OT1C = /IN1H+OT2CIN1M+/IN1D\*/OT3AIN1F+OT3EIN1K;

OUT1D = IN1B+/IN1J;

OT1EIN3B = /IN1B\*IN1J+OT2CIN1M+/OT3G\*IN1A+/IN1A\*/IN1G;

OT1F = OT2CIN1M\*/IN1G\*/IN1L;

OUT1G = OT2CIN1M+/IN1G\*IN1E+IN1B+/OT3G\*IN1A;

OUT1H = /IN1H\*(IN1E)+OT3AIN1F+/IN1A+IN1B+IN1D;

OUT1I = (/IN1E)\*OT3G;

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Figure 9a. Part 1: PLS173





PLHS501 Programmable Macro Logic Primer

AN29

File Name : PART2  
 Date : 12/10/1986  
 Time : 18:30:42

##### P I N L I S T #####

LABEL	** FNC	**PIN	-----	PIN**	FNC **	LABEL
IN1A	** I	** 1-		1-24	** +5V	**VCC
IN2B	** I	** 2-		1-23	** B	**N/C
IN2C	** I	** 3-		1-22	** B	**N/C
IN1G	** I	** 4-	P	1-21	** 0	**OT2GIN3E
IN1I	** I	** 5-	L	1-20	** 0	**/OT2FIN3D
IN1J	** I	** 6-	S	1-19	** 0	**OT2CIN1M
IN1B	** I	** 7-	1	1-18	** 0	**OUT2E
OUT1G	** I	** 8-	7	1-17	** 0	**OUT2D
OUT1H	** I	** 9-	3	1-16	** 0	**OUT2C
OT1C	** I	** 10-		1-15	** 0	**OUT2B
OT3AIN1F	** I	** 11-		1-14	** /0	**/OUT2A
GND	** 0V	** 12-		1-13	** I	**OT3G

TB034205

File Name : PART2  
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@DEVICE TYPE

PLS173

@DRAWING

@REVISION

@DATE

@SYMBOL

@COMPANY

@NAME

PART2

@DESCRIPTION

@I/O DIRECTION

@LOGIC EQUATION

```

/OUT2A = /((OUT2B*/OUT1G));
OUT2B =OUT1H+OUT2A;
OUT2C =OT2CIN1M+ /IN1G+OT2FIN3D;
OUT2D =OT3AIN1F*/IN1G+(/OT3AIN1F*((IN1B+ /IN1J)*/IN1I))*IN1B
      +(OT2FIN3D*/OT3G*/IN1A)*(( /IN1A*/IN1B*(IN1J+ /OT3AIN1F))
      */IN1B*IN1J))+ /OT2GIN3E;
OUT2E = /OT2CIN1M*/IN2C;
OT2CIN1M =IN1G*/OUT2E;
/OT2FIN3D = /((OUT2C*(IN2B)));
OT2GIN3E = /OUT2D+OT1C;
    
```

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Figure 9b. Part 2: PLS173



PLHS501 Programmable Macro Logic Primer

AN29

File Name : PART2  
 Date : 12/10/1986  
 Time : 18:32:35

Cust/Project - PART2  
 Date -  
 Rev/I. D. -

PLB173		POLARITY																																	
T !		!HrHrHrHrHrHrHrHrHrL!																																	
E !																																			
R !		I								B(i)								B(o)																	
M ! 1 1																																			
		1	0	9	8	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	1	0		
0!					L																			H	A	A	.	.	.	.	.	A	!		
1!					H																					A	A	.	.	.	.	A	!		
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3!																								H	A	A	.	.	.	.	A	!			
4!																										A	A	.	.	.	.	A	!		
5!																										A	A	.	.	.	.	A	!		
6!					H																					A	A	.	.	.	.	A	!		
7!					L																					A	A	.	.	.	.	A	!		
8!					L																					A	A	.	.	.	.	A	!		
9!					L																					A	A	.	.	.	.	A	!		
10!					L																					A	A	.	.	.	.	A	!		
11!																										A	A	.	.	.	.	A	!		
12!																										A	A	.	.	.	.	A	!		
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14!																										A	A	.	.	.	.	A	!		
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D3!																																			
D2!																																			
D1!																																			
D0!																																			

O	O	O	O	I	I	I	I	I	I	N	N	O	/	O	O	O	O	/	N	N	O	/	O	O	O	O	/					
T	T	T	U	U	N	N	N	N	N	N	/	/	T	O	T	U	U	U	U	U	O	/	/	T	O	T	U	U	U	U	O	
3	3	1	T	T	1	1	1	1	2	2	1	C	C	2	T	2	I	T	T	U	C	C	2	T	2	T	T	T	T	U	O	
G	A	C	1	1	B	J	I	G	C	B	A			G	2	C	2	2	2	2	T			G	2	C	2	2	2	2	T	
I			H	G										I	F	I	E	D	C	B	2			I	F	I	E	D	C	B	2	
N														N	I	N					A			N	I	N					A	
1														3	N	1							3	N	1							
F														E	3	M							E	3	M							
														D									D									

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Figure 9b. Part 2: PLS173 (Continued)

PLHS501 Programmable Macro Logic Primer

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 Time : 18:35:38

##### P I N L I S T #####

LABEL	** FNC	**PIN	-----	PIN**	FNC	** LABEL
OT1BIN3A	** I	** 1-		1-20	** +5V	**VCC
OT1EIN3B	** I	** 2-		1-19	** B	**N/C
IN3C	** I	** 3-	P	1-18	** B	**N/C
OT2IN3D	** I	** 4-	L	1-17	** 0	**OT3H
OT2GIN3E	** I	** 5-	S	1-16	** /0	**/OT3G
OT1F	** I	** 6-	1	1-15	** 0	**OUT3F
IN1L	** I	** 7-	5	1-14	** 0	**OT3EIN1K
IN1H	** I	** 8-	3	1-13	** 0	**OUT3D
/OT3AIN1F	** /0	** 9-		1-12	** 0	**OUT3C
GND	** OV	** 10-		1-11	** 0	**IN1G

TB034405

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 Time : 18:36:18

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 PLS153  
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 @REVISION  
 @DATE  
 @SYMBOL  
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 @NAME  
 @DESCRIPTION  
 @COMMON PRODUCT TERM  
 @I/O DIRECTION  
 @OUTPUT POLARITY  
 @LOGIC EQUATION

TB034407

Figure 9c. Part 3: PLS153



# PLHS501 Programmable Macro Logic Primer

AN29

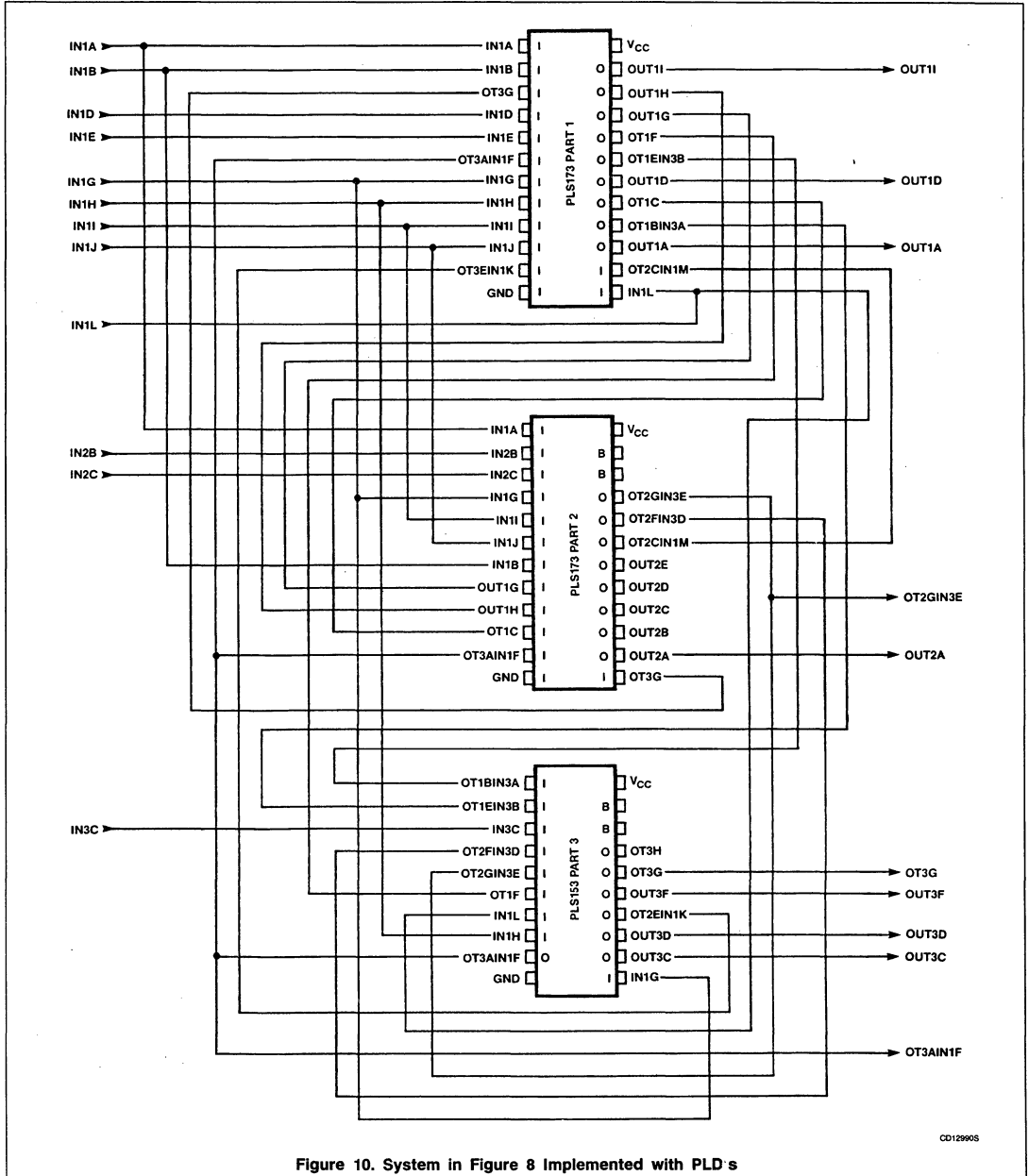


Figure 10. System in Figure 8 Implemented with PLD s

CD12990S

PLHS501 Programmable Macro Logic Primer

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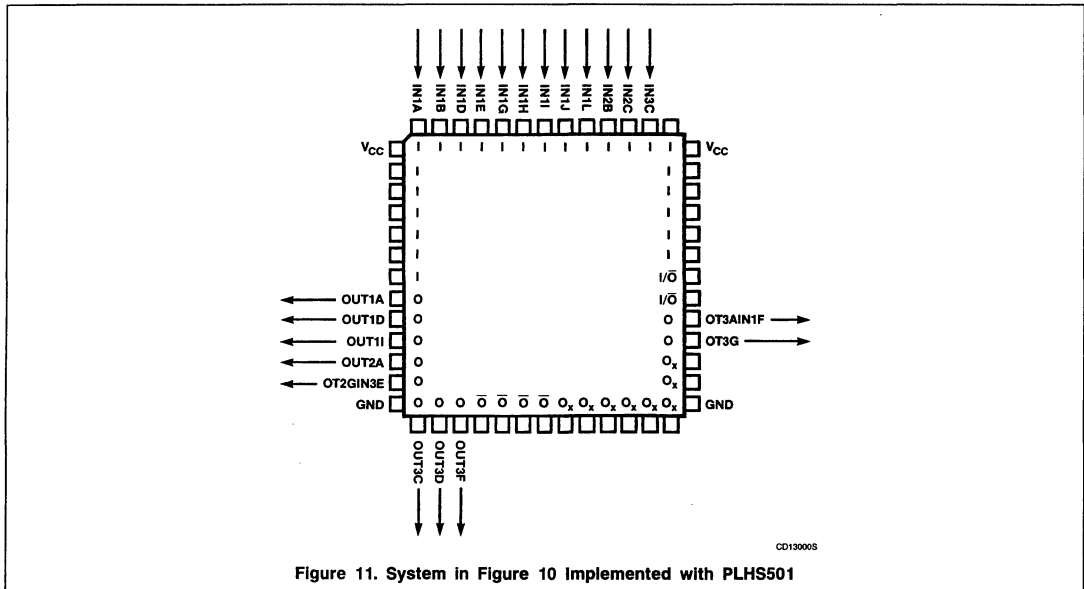


Figure 11. System in Figure 10 Implemented with PLHS501

## Application Specific Products

### INTRODUCTION TO PML DESIGN CONCEPTS

Programmable Macro Logic, an extension of the Programmable Logic Array (PLA) concept combines a programming or fuse array with an array of wide input NAND gates wherein each gate folds back upon itself and all other such NAND gates. This is called a foldback NAND structure and its basic elements have been outlined previously (Cavlan<sup>1</sup>, Wong<sup>2</sup>, Gheissari and Safari<sup>3</sup>).

The choice of an internal NAND logic cell is appropriate because the cell is functionally complete, requiring but a single cell type to generate any Boolean function. A cell within the PLHS501 may be configured to accommodate from one to 32 inputs from the outside world, and up to 72 inputs from within the chip. Because the user can select either direct or inverted input variables, and either a direct or complemented output, the NAND function can generate, with a single pass through the programming array, the basic four logic functions of AND, OR, NAND, NOR. All these basic functions, can be extremely wide, of course (see Figure 1.1). This convenient structure allows efficient exploitation of all widely used minimization techniques (Karnaugh Maps, Quine-McCluskey, Boolean Algebra, etc.).

The obvious extensions to additional combinational functions for decoding, multiplexing and general Boolean functions is straightforward. Adding feedback to the system expands the range of realizable functions to include sequential as well as combinational functions. Figure 1.2 illustrates the basic arrangement of the PLHS501. Because of the large number of inputs each NAND gate has available, logic functions that require several levels of conventional 4 or 8 input gates may be able to be reduced to 1 or 2 levels. However, it is important to realize that unlike AND-OR PLD architectures, more than 2 levels of logic may be implemented in the PLHS501 without wasting output or input pins. Up to 72 levels of logic may be implemented due to each of the 72 foldback NAND gates.

So far, the concept of a "macro" is still not evident. Two ways for the generation of a macro exist — namely, hard and soft. Borrowing from the concept in computer programming wherein a section of code (called a macro) is repeated every time its use is required, we can establish subfunctions which can be repeated each time required. The user defined or soft macro can be one which will generate a function by fused interconnect. When a fixed design function is provided, it is a hard macro. This may be an optimized structure like a flip-flop or an adder,

or some other function which is generated on the foundation, by the manufacturer. Soft macros are seldom optimized or precisely consistent, but hard macros are both optimized and unalterable.

When a user function for a particular use is isolated, defined and repetition of the function is required, special software constructs are provided which will allow it to be defined as a soft macro and efficiently replicated. For higher performance and functional density, an array of choices which contain optimized functions or hard macros will be offered in successor chips. In particular, the PLHS502 (described in Section 4) will include an array of flip-flops for high performance state machine design.

Optimizing combinational functions in PML consists largely in making choices and trade-offs. For single output logic functions, the choice is obvious from the truth table. If a particular function's truth table has fewer entries that are logical zeroes than logical ones, product of sums should be chosen and the appropriate OR-AND structure generated. Otherwise, the usual sum of products should be chosen, minimizing as usual, before dropping into the two level AND-OR structure (using the NAND-NAND realization). Combining the availability of inversion at the input and output of the chip, the NAND-NAND structure can perform either the OR-AND or the AND-OR rendition of a function with equal ease, using precisely the same number of logic levels. The designer needs only to choose the optimal rendition to suit his needs (see Table 1.1). Truth tables with 50% ones can use either version at the designers whim unless other uses arise.

### PERFORMANCE

The PLHS501 (Figure 1.2) is a high speed, oxide isolated, vertically fused PML device containing 72 internal NAND functions which are combined with 24 dedicated inputs, 8 bidirectionals and 16 dedicated outputs. A large collection of applications, both combinational and sequential, may be configured using this part which looks roughly like a small, user definable gate array. For the sake of clarity, worst case passing a signal from an input, making one pass through the NAND array (output terms) and exiting an output takes around 25 nanoseconds with each incremental pass through the NAND foldback array taking about 8 nanoseconds.

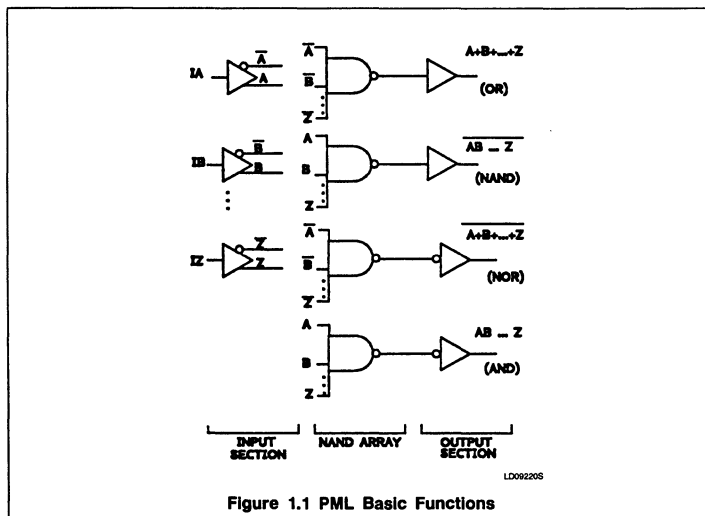


Figure 1.1 PML Basic Functions



# Designing with Programmable Macro Logic

**TABLE 1.1 EXAMPLE DEMONSTRATION**

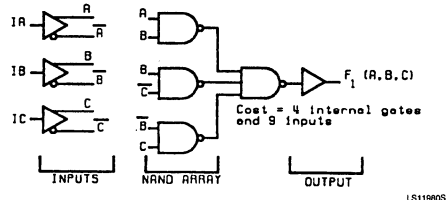
$$F_1(A, B, C) = \overline{ABC} + \overline{A}BC + \overline{A}B\overline{C} + \overline{A}BC + \overline{A}BC$$

A	B	C	f1
0	0	0	0
0	0	1	1
0	1	0	1
0	1	1	0
1	0	0	0
1	0	1	1
1	1	0	1
1	1	1	1

C \ AB	AB			
	00	01	11	10
0	0	1	1	0
1	1	0	1	1

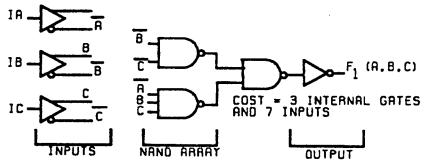
The optimal choice would be to generate the zero entries.

If we group on the one entries we shall get:  $F_1 = \overline{A}B + \overline{B}C + BC$



LS119905

If we group on the zero entries we get instead:  $F_1 = (B + C)(A + B + C)$



LS119905

# Designing with Programmable Macro Logic

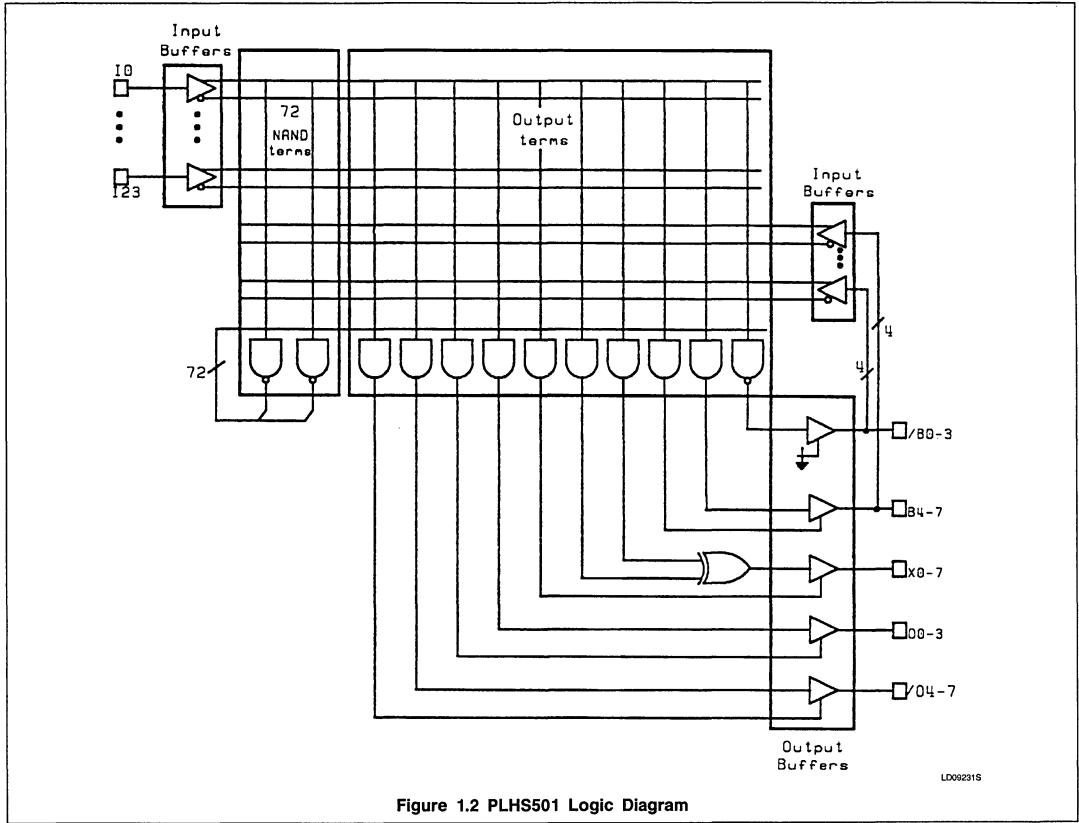


Figure 1.2 PLHS501 Logic Diagram

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## Designing with Programmable Macro Logic

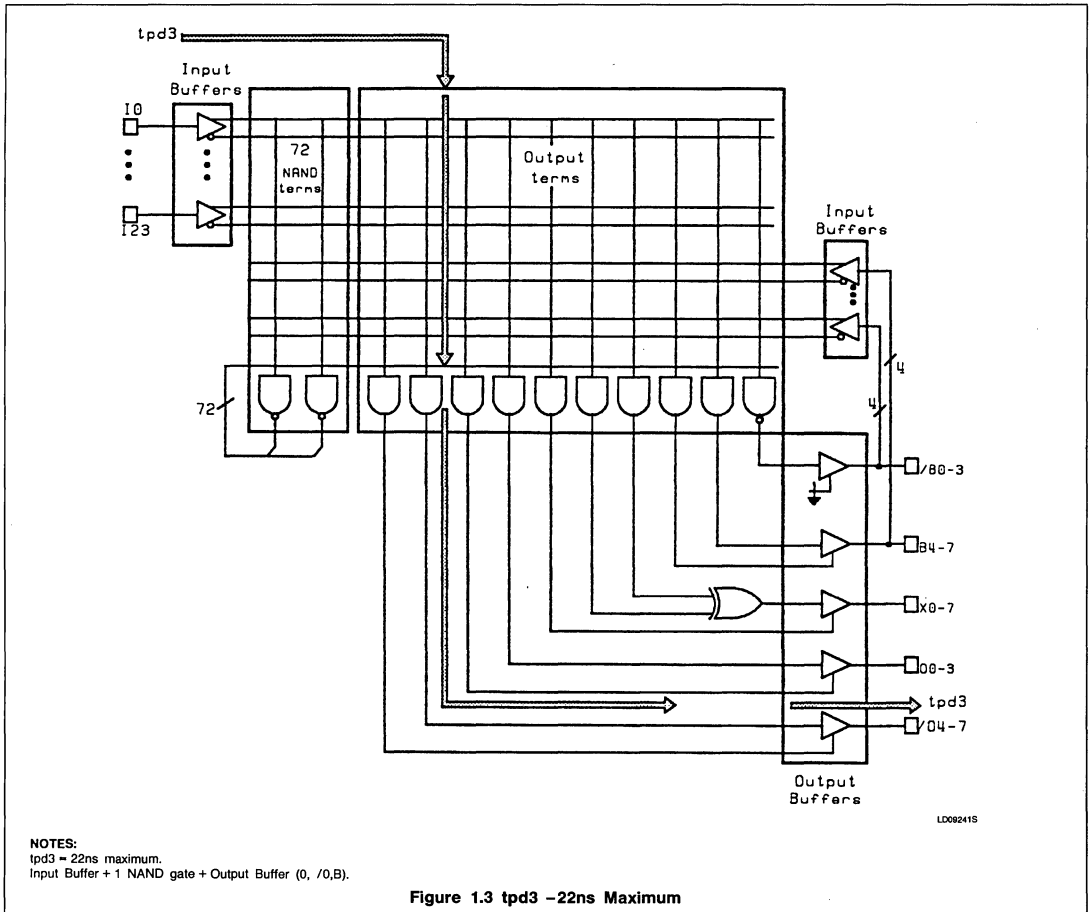
The data sheet first lists some maximum propagation delays from an input, through a NAND output term and out through various output gates. Secondly, it lists maximum propagation delays from an input, through a NAND foldback term, through a NAND output term and out through the different output gates.

It is intriguing that subtracting one from the other yields a NAND foldback gate delay of 5 to 6ns when the worst case gate delay of an internal foldback gate is listed as 8ns. This is due to the fact that a gate has less of a delay when it's output is falling (tPHL) than when it's output is rising (tPLH). When passing a signal through two NAND gates one gate will

have less of a delay than the other, and since the individual rise and fall delays are not specified, this causes the apparent discrepancy between the two delays.

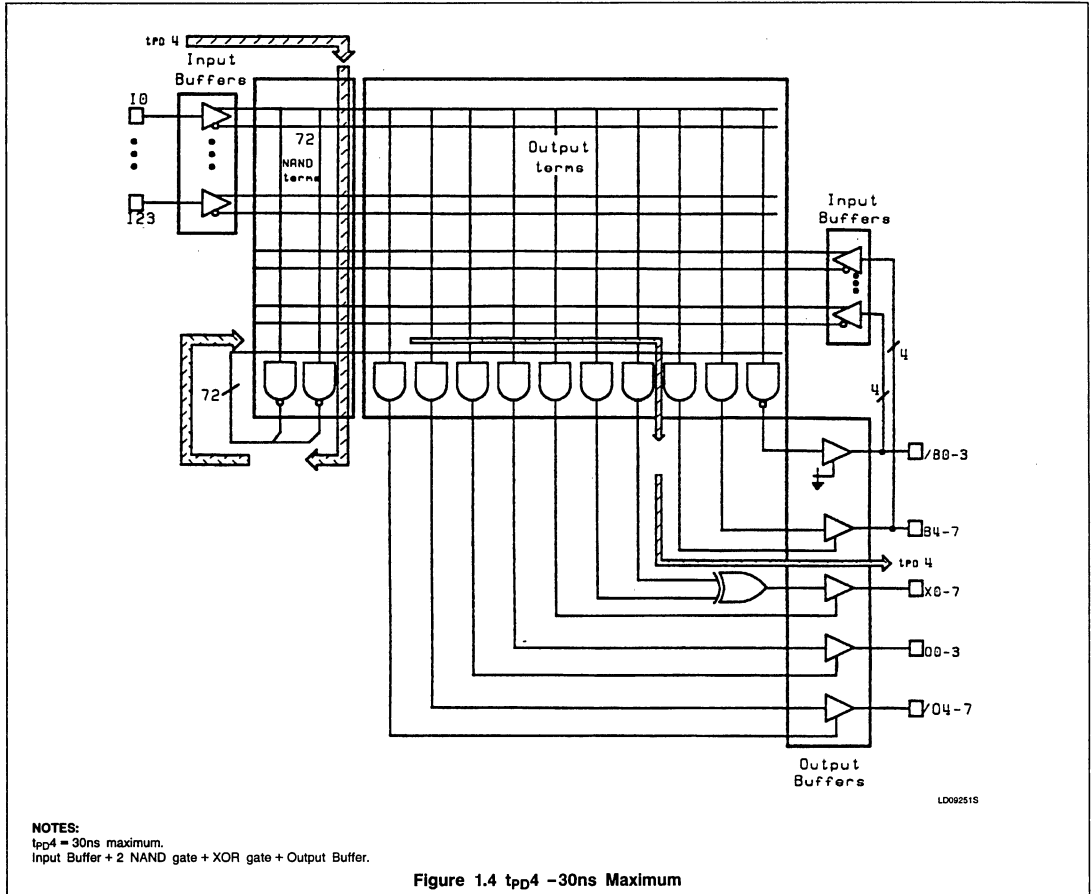
Figure 1.3, Figure 1.4, Figure 1.5 and Figure 1.6 show graphically the timing paths listed in the PLHS501 data sheet.

### PLHS501 TIMING



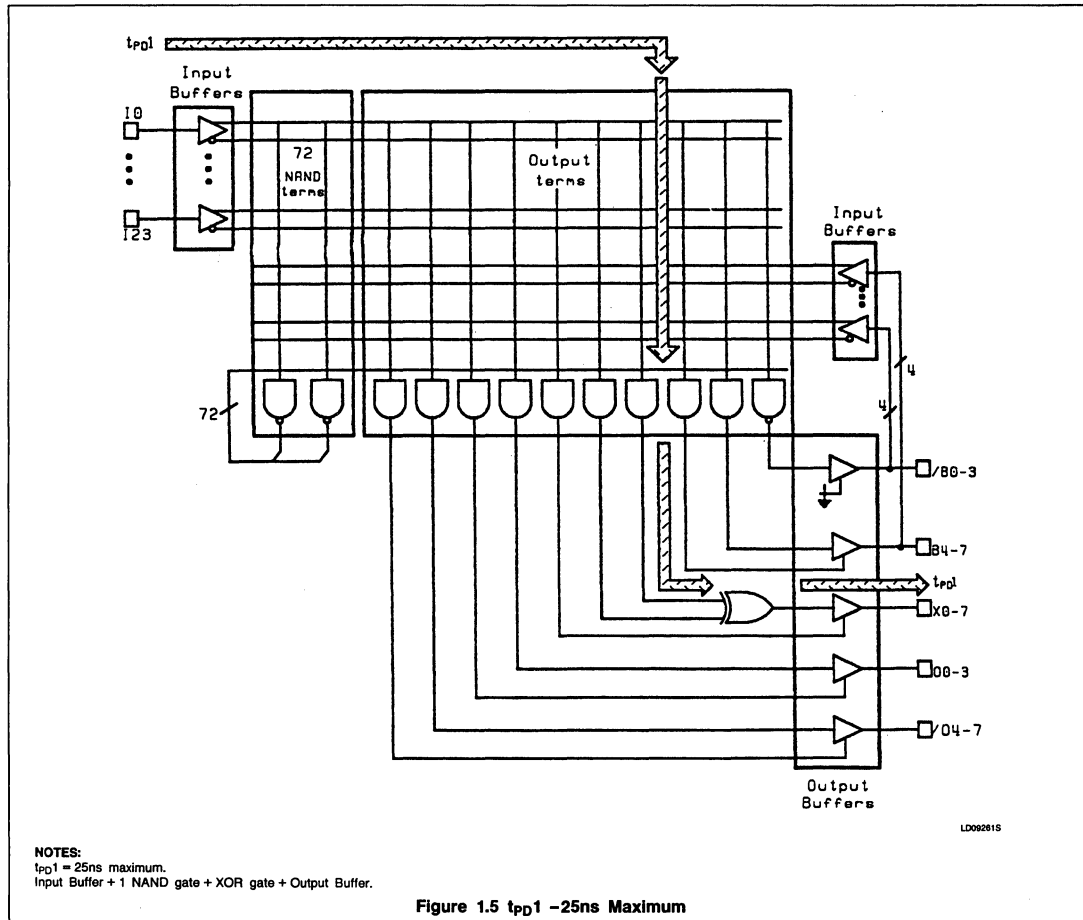
# Designing with Programmable Macro Logic

## PLHS501 TIMING (Continued)



# Designing with Programmable Macro Logic

## PLHS501 TIMING (Continued)



# Designing with Programmable Macro Logic

## PLHS501 TIMING INTERNAL

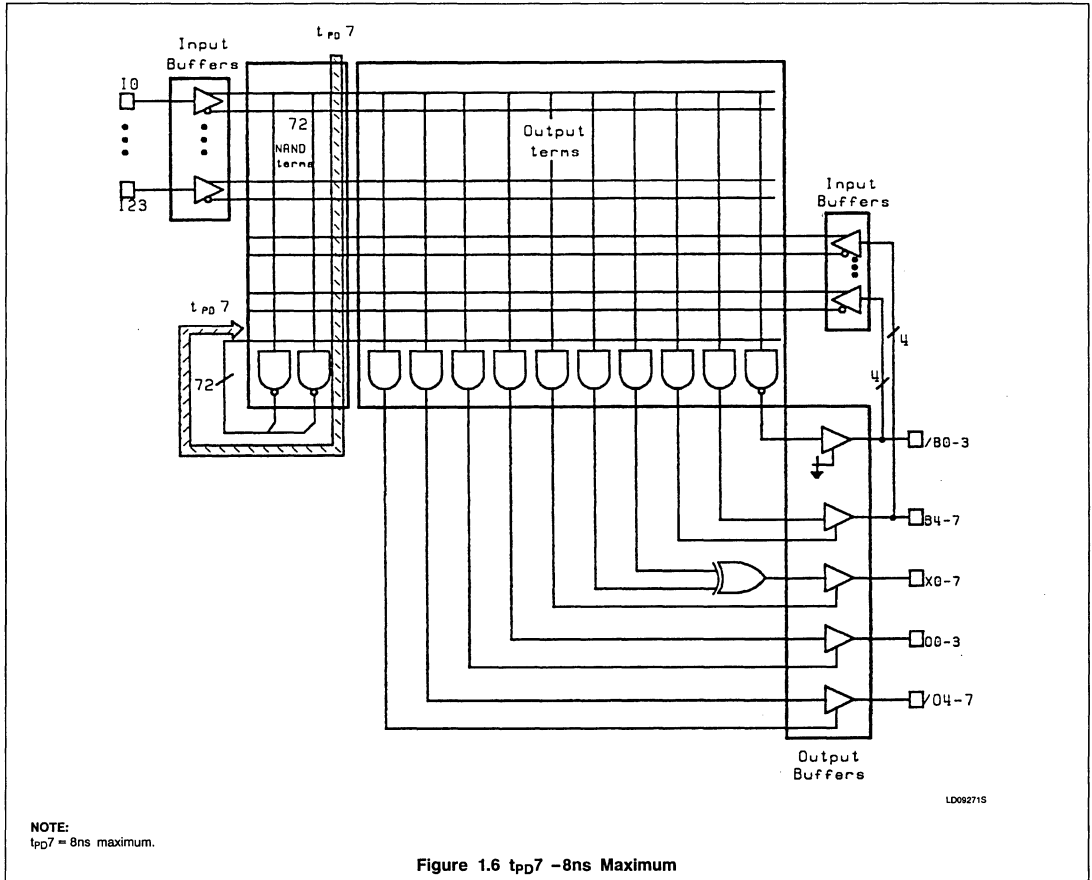


Figure 1.6  $t_{pd7} - 8\text{ns}$  Maximum

## Designing with Programmable Macro Logic

### NAND GATE FLIP-FLOPS

Various types of flip-flops and latches may be constructed using the NAND gate building blocks of the PLHS501. A typical 7474 type of edge-triggered D flip-flop requires 6 NAND gates as shown in Figure 1.7.

No additional gates are required to implement asynchronous set and reset functions to the flip-flop. The equations necessary for AMAZE to implement the D flip-flop are shown in Figure 1.8. However, please note that the equations of Figure 1.8 define a D flip-flop configured as a divide by 2 (i.e., QN is connected to the data input) whereas Figure 1.7 shows a general case. Also note that flip-flops with some additional features may be constructed without using more than the six NAND gates. This is possible because of the large number of inputs associated with each NAND gate. For instance, a flip-flop may be required to have a clock gated by one or more signals. Using the PLHS501, it may be implemented by adding additional input signal

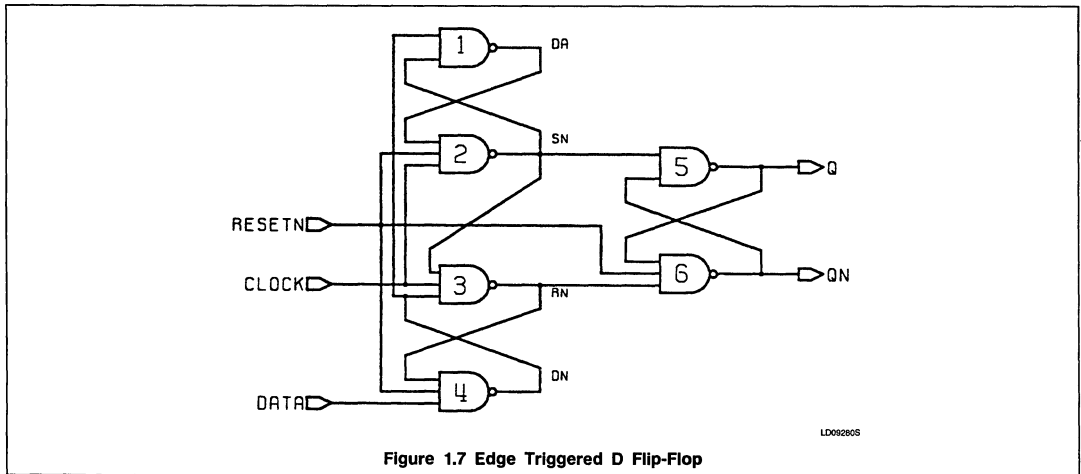
names to NAND gate equations of gates #2 and #3 of Figure 1.7. If the data input is to the AND of several signals, extra inputs to NAND gate #4 may be used. Or if additional set or reset lines are required, they may be added simply by using more of the inputs of each NAND gate connected to the main set or reset.

Figure 1.10 shows two simulations of the same flip-flop. The first one is at a little less than maximum frequency, for clarity in following the waveforms, and the second is at the maximum toggling frequency. For these simulations each NAND gate has a maximum t<sub>pHL</sub> or t<sub>pLH</sub> of 8nsec (which is the gate delay of a NAND gate in the PLHS501's foldback array). First of all, it can be seen from these simulations that for proper simulation or testing of such a device a set or reset input is mandatory. Both Q and QN outputs are unknown no matter what the inputs do, until they are put into a known state by either a set or reset input. Secondly, various timing parameters

such as propagation delay, as well as setup and hold times may be determined. For the general case, referring to Figure 1.7:

$$T_{setup} = t_{pd4} + t_{pd1}, \quad T_{hold} = t_{pd3} + t_{pd4} + \text{Clock to } Q = t_{pd3} + t_{pd6} + t_{pd5}.$$

Therefore, performance of the flip-flop depends a great deal on which gates in the PLHS501 are used, either NAND gates in the foldback array or output NAND gates, connected to bidirectional pins. As a test of the simulation, a D flip-flop connected as a divide by 2 was constructed using only the foldback NAND terms (see Figure 1.8). An output NAND term was used to invert the QN output and drive an output buffer. The only inputs were the clock and a reset. The data input to the flop was driven internally by the QN output. According to the simulation, it was possible to drive the clock at a frequency of 25Mhz and this small circuit also functioned at that frequency.



# Designing with Programmable Macro Logic

##### P I N L I S T #####

Left	Right
LABEL ** FNC **PIN	PIN** FNC ** LABEL
VCC ** +5V ** 8-	-46 ** +5V **VCC
N/C ** I ** 9-	-45 ** I **N/C
N/C ** I ** 10-	-44 ** I **N/C
N/C ** I ** 11-	-43 ** I **N/C
N/C ** I ** 12-	-42 ** I **N/C
CLK ** I ** 13-	-41 ** I **N/C
RST ** I ** 14-	-40 ** /O **N/C
N/C ** I ** 15-	-39 ** /O **N/C
N/C ** I ** 16-	-38 ** /O **N/C
N/C ** I ** 17-	-37 ** /O **O0
N/C ** I ** 18-	-36 ** O **N/C
N/C ** O ** 19-	-35 ** O **N/C
GND ** 0V ** 20-	-34 ** 0V **GND

```

File Name : 1flop
Date : 12/3/1987
Time : 10:1:22
@DEVICE TYPE PLHS501
@DRAWING
@REVISION
@DATE
@SYMBOL
@COMPANY
@NAME
@DESCRIPTION
Single D flip-flop connected as
divide-by-two for test
@INTERNAL NODE
CSN0,CRN0,CQ0,CQN0;
@COMMON PRODUCT TERM
@I/O DIRECTION
@I/O STEERING
@LOGIC EQUATION
O0 = /(CQN0);
CSN0 = /(CLK*RST*(((CSN0*(((CQN0*RST*CRN0))))));
CRN0 = /(CSN0*CLK*(((CQN0*RST*CRN0)));
CQ0 = /(CSN0*CQN0);
CQN0 = /(CRN0*CQ0*RST);
    
```

TU036305

Figure 1.8 PLHS501 Test Flip-Flop

PLHS501

```

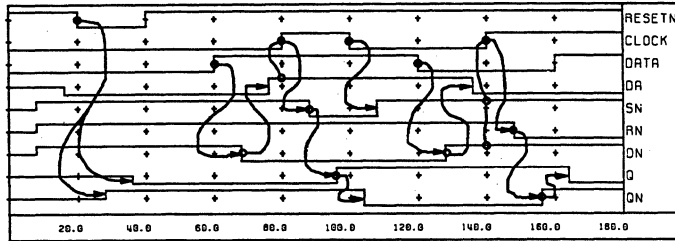
77666666666555555555444444444433333333332222222211111111110000000000
10987654321098765432109876543210987654321098765432109876543210
IIIIIIIIIIIIIIIIIIIIIIIIIIIBBBBBBBB
22221111111111000000000000000000
32109876543210987654321076543210
----- Col for /B 0
..... A..
HH----- Col for P 0
..... A...
-H----- Col for P 1
..... A...A
H----- Col for P 2
..... A...A
----- Col for P 3
..... A...A
H----- Col for P 4
..... AA.
----- Col for P 5
..... A.A
    
```

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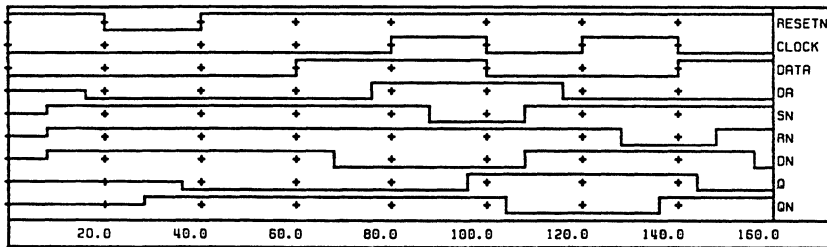
Figure 1.9 Partial PLHS501 Fusemap Showing Test Flip-Flop Fusing



# Designing with Programmable Macro Logic



WF231605



WF231705

Figure 1.10 Waveforms of Test Flip-Flop

## Application Specific Products

### FUNCTIONAL FIT

In the late 1960's and early 1970's designers used SSI, MSI and small amounts of early LSI to generate logic solutions. Frustrated by the lack of wide input gates to accommodate a lot of product terms for two level solutions, they turned toward the budding ROM and PROM products. These devices relied on literally realizing a function by generating its truth table in silicon. The logic function had to have each logical one and zero realized distinctly as an entry for a particular combination of input variables, usually supplied on the address lines of the memory. Observing that many such truth tables were dense in ones or zeroes and sparse in the remainder, a cadre of initial manufacturers emerged with focus on supplying a programmable product with a few AND gates and OR gates which were versatile enough to compete against the ROM/PROM parts. The gimmick supplied by these PLA manufacturers was to illustrate the functional equivalency of the PLA to the PROM by comparing the number of product terms (to be shortened to "p-terms") the PLA supplied and comparing this to the width and depth of available PROMs. P-terms became the "currency" of the PLA world and a designer only had to assess the equivalent number of Boolean product terms required by his function to determine whether a particular PLA was a suitable candidate for his design.

Almost in parallel, gate arrays became available. These provided an array of identical, fixed input gates (usually two input NANDs or NORs). These were generated in a regular fashion on a substrate which had a fixed input/output pin arrangement. Also recognizing that all logic functions could be built from the appropriate two input gates, when interconnected correctly, manufacturers offered these devices to customers who required increased density.

The designer's responsibility was to generate what would ultimately be a metal interconnect pattern of his design. Special tools were required to allow an untrained system designer to do this successfully. Flip-flops, decoders, registers, adders, etc., could all be generated from the low level gate building blocks.

The currency of gate arrays became known as gate equivalent functions. That is, with a limited number of available gates on a substrate, the user needed to know precisely how many gates were used up, on a function by function basis, to generate each piece of his design. A D flip-flop requires about six gates, a D latch four, a 3 to 8 decoder takes about 14 gates and so forth. This allowed estimation regarding whether the function could conceivably be fit onto a particular substrate or not. Manufacturers had to offer multiple foundations so that a designer could be assured that his design would result in a working I.C.

The classic method of estimating whether a logic function would fit into a PLA was to determine the number of I/O pads required and the number of product terms required to generate the logical function, then select the PLA. For a gate array, the required measure included the I/O pad arrangement but substituted the number of available gates to generate the logical function (usually by table lookup). In an attempt to reconcile the two measures, Hartman<sup>4</sup> has evolved a formula for his product line. A calculation using this method and developing an appropriate "exchange rate" is shown in Table 2.1 for the PLHS501 and PLHS502. An alternate method of generating an estimate is to consider the gate equivalent of generating, say for the PLHS501, a gate equivalent of the part in an optimistic functional configuration (72 occurrences of a 32 input NAND gate). Figure 2.1

shows how this will result in over 2000 equivalent gates. Conversely, by stacking the NAND gates into D flip-flops, its least efficient function, the PLHS501 will have a gate equivalent of only about 100 gates.

The most rational method of assessing fit is to isolate functions and identify the correct configuration in terms of gates, to allow direct tally of the gates used, to generate the proposed configuration. Table 2.2 may assist in doing this analysis. Note that all basic gates require precisely one gate to generate the function. Also note the occurrence of functions in the table which could never be generated as standard I.C.'s previously. The procedure is to tally the design against a total budget of 72 multiple input NAND gates.

Table 2.2 is illustrative only, and should by no means be taken as complete. It may be simply expanded by designing the proposed function with disregard to the usual restrictions on the number of inputs to a gate, realize the function as one, two, three, or more levels of interconnected logic and count the number of gate occurrences required. Special software has been provided to allow pyramided logic structures to be generated under the designer's control. These structures may, however, be no deeper than 72 levels for the PLHS501. Functions should be generated in accord with the guidelines mentioned before, for selecting an optimal 2 level logical solution.

It is an interesting observation that manufacturers of gate arrays and standard cell products which offer embedded PROMS, ROMS or RAMS have not successfully described these embedded functions in terms of equivalent gates, but rather resort to other means (such as divulging their relative area with respect to the area of a basic gate). There is, as yet, no standard in this arena.

# Designing with Programmable Macro Logic

**TABLE 2.1 EQUIVALENCY RATIO**

Hartman's method is based on a CMOS gate array equivalency wherein 4 transistors constitute a 2 input NAND or NOR gate, equal to one gate. Thus, his "exchange rate" is as follows:

$$\begin{aligned}
 \text{E.R.} &= 4 \times \# \text{ inputs} \\
 &+ 9 \times \# \text{ FFs} \\
 &+ 7 \times \# \text{ 3-State outputs} \\
 &+ (15 \text{ to } 30) \times \# \text{ OR outputs from the AND/OR array.}
 \end{aligned}$$

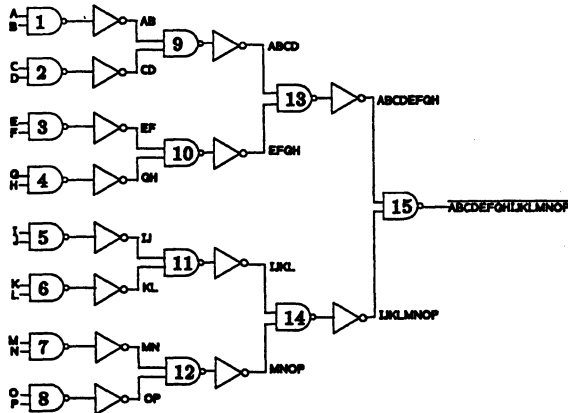
**For the PLHS501:** (using CMOS numbers which may be inappropriate)

$$\begin{aligned}
 \text{E.R.} &= 4 \times 32 \\
 &+ 9 \times 0 \\
 &+ 7 \times 24 \\
 &+ (15 \text{ to } 30) \times 50\% \text{ of } 72 \text{ feedbacks} = 836 \text{ to } 1376 \text{ gates}
 \end{aligned}$$

**For the PLHS502:**

$$\begin{aligned}
 \text{E.R.} &= 4 \times 32 \\
 &+ 9 \times 16 \\
 &+ 7 \times 12 \\
 &+ (15 \text{ to } 30) \times 50\% \text{ of } 64 \text{ feedback} = 962 \text{ to } 1502 \text{ gates}
 \end{aligned}$$

Being for two bipolar I.C.'s, in this case, the method may be inappropriate, but may be taken as an estimating procedure.



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**NOTE:**  
Double this and add one for a 32 input NAND.

**Figure 2.1 16 Input NAND Formed from 2 Input Gates**

## Designing with Programmable Macro Logic

**TABLE 2.2 PLHS501 GATE COUNT EQUIVALENTS**

FUNCTION	PLHS501 INTERNAL NAND EQUIVALENT	COMMENTS
<b>Gates</b>		
NANDs	1	For 1 to 32 input variables.
ANDs	1	For 1 to 32 input variables.
NORs	1	For 1 to 32 input variables.
ORs	1	For 1 to 32 input variables.
<b>Decoders</b>		
3 to 8	8	Inverted inputs available.
4 to 16	16	Inverted inputs available.
5 to 32	32	Inverted inputs available (24 chip outputs only).
<b>Encoders</b>		
8 to 3	15	Inverted inputs, 2 logic levels.
16 to 4	32	Inverted inputs, 2 logic levels.
32 to 5	41	Inverted inputs, 2 logic levels, factored solution.
<b>Multiplexers</b>		
4 to 1	5	Inverted inputs available.
8 to 1	9	
16 to 1	17	
27 to 1	28	Can address only 27 <u>external</u> inputs — more if internal.
<b>Flip-Flops</b>		
D-FF	6	With asynch S-R
T-FF	6	With asynch S-R
J-K-FF	8	With asynch S-R
<b>Adders</b>		
8-bit	45	Full carry look-ahead (four levels of logic)
<b>Barrel Shifters</b>		
8-bit	72	2 levels of logic

## Application Specific Products

### DESIGN EXAMPLES

Most designers tend to view a PLD as a mechanism for collecting logical glue within a system. That is, those pieces which tie together the larger LSI microprocessors, controllers, RAMs, ROMs, UARTs, etc. However, there is a tendency of viewing a gate array as an entire system on a chip. PML based products will fit well in either casting as will be demonstrated by a series of small but straightforward examples. For starters, we shall examine how the fusing process embeds functions, progress to glue-like decoding operations and finally demonstrate some

coprocessor like functions as well as home-made "standard products".

The method of associating gates within the NAND foldback structure is depicted in Figure 3.1 wherein a simple three to eight decoder is fused into the array. The corresponding inputs are on the left and outputs at the top. This figure shows inputs and their inverse formed in the array resulting in a solution that requires 6 inverting NANDs that would probably be best generated at the input receivers. Hence, this diagram could be trimmed by six gates, down to eight to achieve the function. Figure 3.2 shows two consecutive D-flip-flop

fusing images. Note that asynchronous sets and resets may be achieved for free, in this version. In both Figures 3.1 and 3.2 the gates are numbered in a one-to-one arrangement. As well, the accompanying equations are in the format used by Signetics AMAZE design software. For clarity, consider the gate labeled 2A in Figure 3.1. Schematically, this is shown as a 3 input NAND. However, in the fused depiction, it combines from three intermediate output points with the dot intersect designation. Hence, all gates are drawn as single input NANDs whose inputs span the complete NAND gate foldback structure.

### 1 OF 8 DECODER/DEMULTIPLEXER

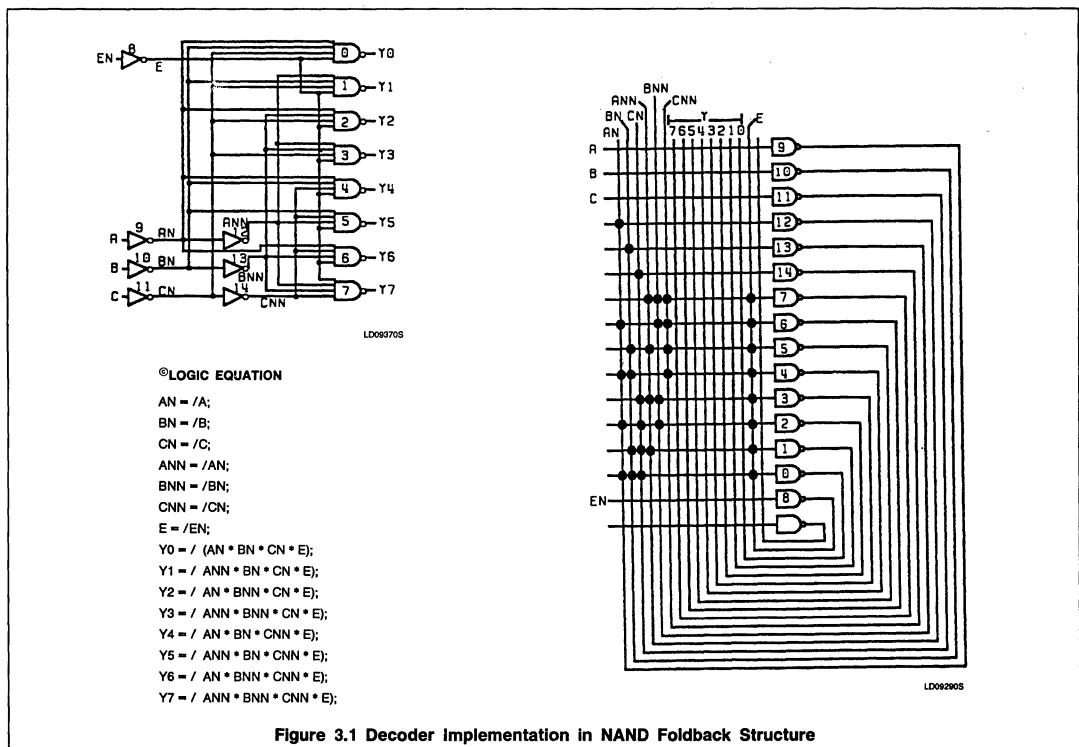


Figure 3.1 Decoder Implementation in NAND Foldback Structure

# Designing with Programmable Macro Logic

## TWO EDGE-TRIGGERED FLIP-FLOPS

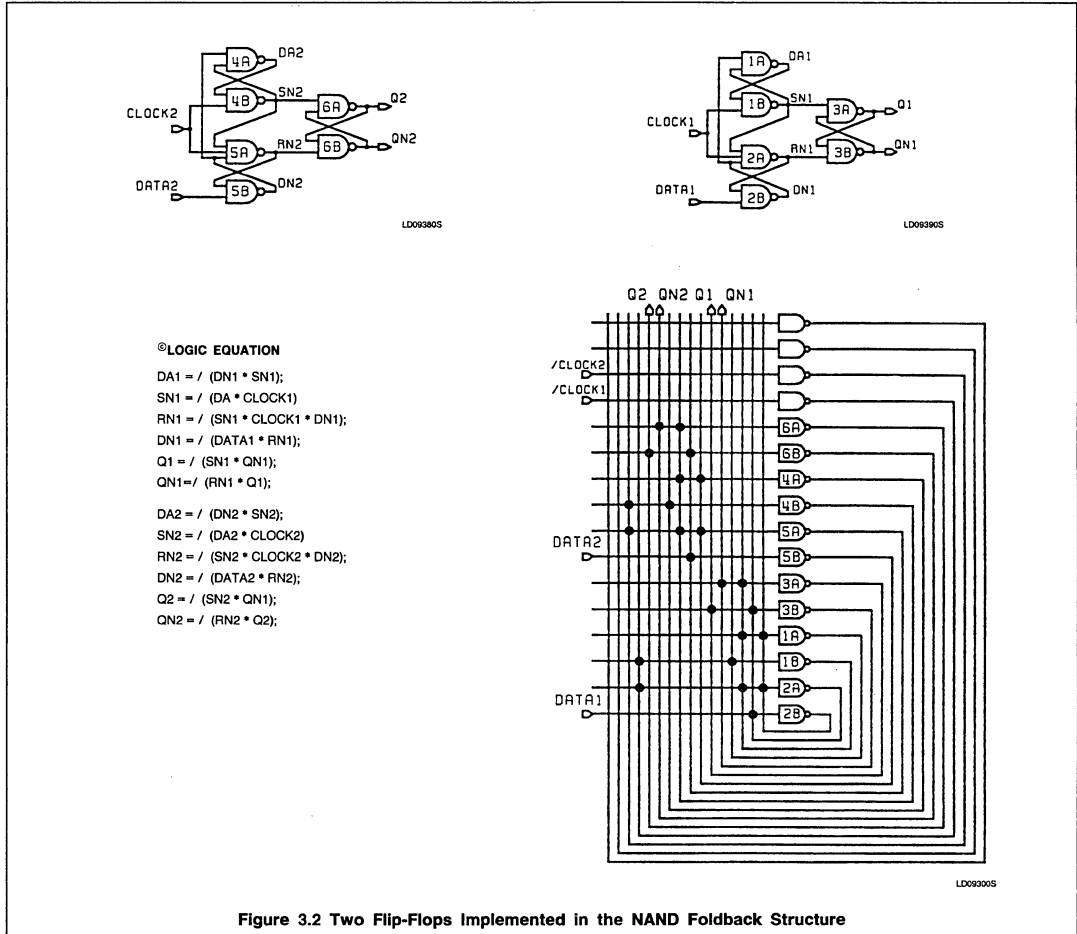


Figure 3.2 Two Flip-Flops Implemented in the NAND Foldback Structure

One straightforward example of using a PLHS501 is shown in Figure 3.3. Here, the device is configured to accept the 23 upper address lines generated by a 68000 microprocessor. By selecting the direct and complemented variables, at least 16 distinct address selections can be made using only the dedicated outputs. The designer can combine additional VME bus strobes, or other control signals to qualify the decode or, define 8 additional outputs for expanded selection. As well, the designer could transform the bidirectionals to inputs and decode over a 32 bit

space, selecting combinations off of a 32 bit wide address bus. Because this simple level of design requires only NAND output terms plus 4 NAND gates in the foldback array (for inversion of signals connected to O3.O0), there may be as many as 68 remaining gates to accomplish additional handshaking or logical operations on the input variables.

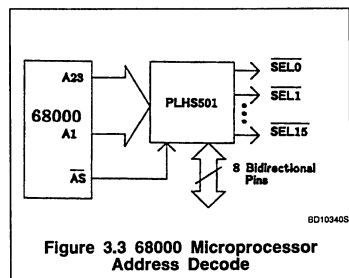
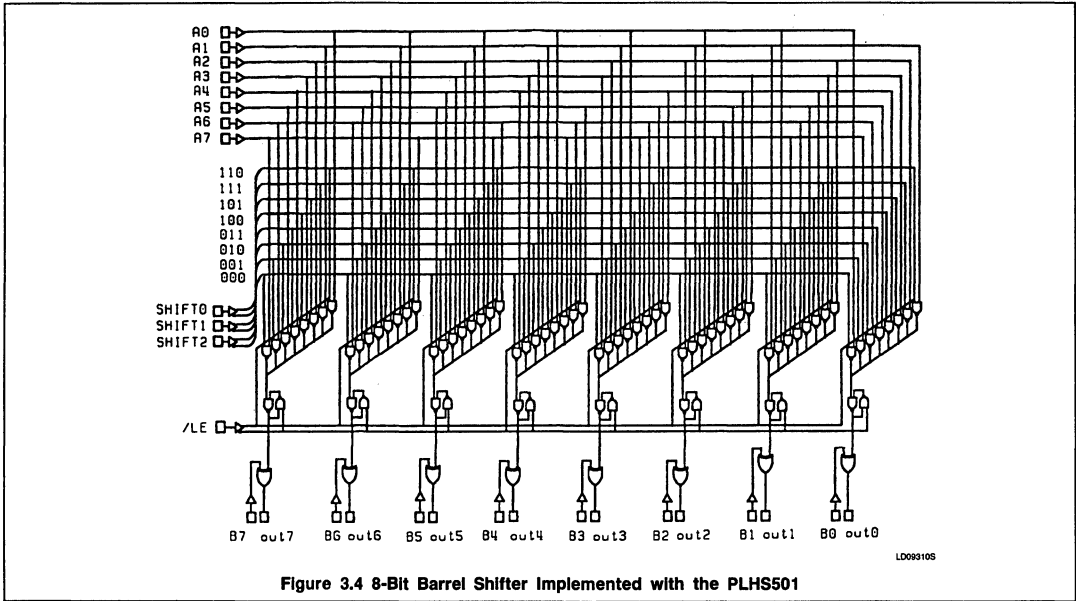


Figure 3.3 68000 Microprocessor Address Decode

## Designing with Programmable Macro Logic



**Figure 3.4 8-Bit Barrel Shifter Implemented with the PLHS501**

An eight bit barrel shifter exploits most of the PLHS501 as depicted in Figure 3.4. This implementation utilizes all 72 internal fold-back NANDs in a relatively brute force configuration as well as 8 output NANDs to generate transparent latched and shifted results. The shift position here is generated by the shift 0, shift 1 and shift 2 inputs which are distinguished and selected from the input cells. Variations on this idea of data manipulation could include direct passing data, mirror

imaged data (bit reversal) or byte swapping to name a few.

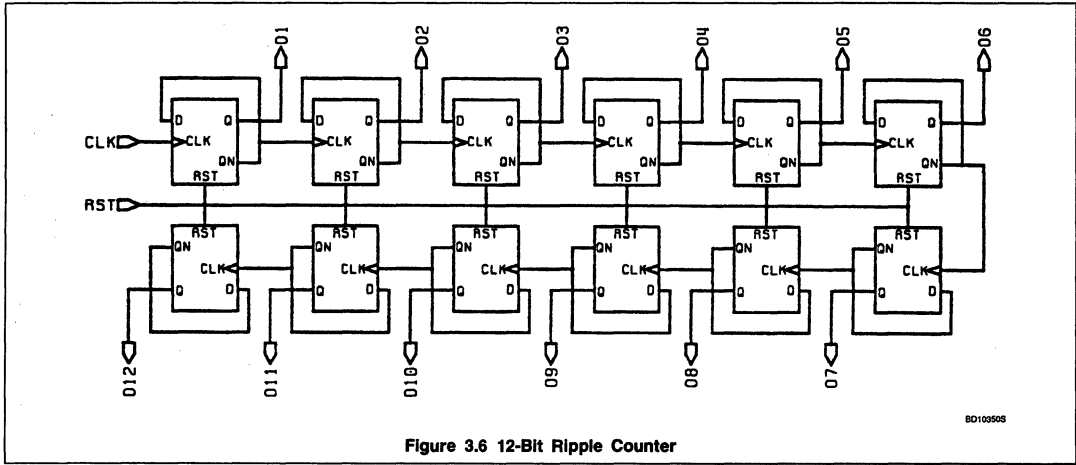
Part of an eight bit, look-ahead parallel adder is shown in Figure 3.5. Gates necessary to form the level-0 generate and propagate, as well as the XOR output gates generating the resulting sum are not shown. The reader should be aware that this solution exploits four layers of pyramided gates and only utilizes a total of about 58 gates. Additional

comparison or Boolean operations could still be generated with remaining NAND functions to achieve additional arithmetic operations. This application should make the reader aware of a new class of applications achievable with third generation PLDs — user definable I/O coprocessors. The approach of increasing microprocessor performance by designing dedicated task coprocessors is now within the grasp of user definable single chip solutions.





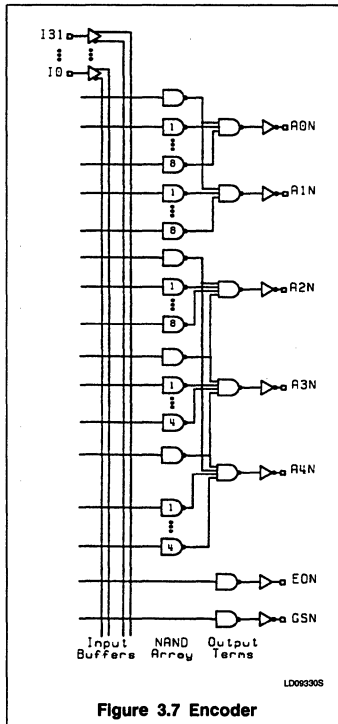
## Designing with Programmable Macro Logic



**Figure 3.6 12-Bit Ripple Counter**

Figure 3.7 shows a 32 to 5-bit priority encoder. This sort of device could generate encoded vector interrupts for 32 contending devices. Of particular interest is the fact that ordinary encoders are not this wide. The designer is, of course, not constrained to generating combinational functions in even powers of two. Thus, the PLHS501 can easily perform customized functions like a 5 to 27 decoder or a 14 to 4 encoder or, even an 18 to 7 multiplexor. For the sake of optimization, the designer is encouraged to implement precisely the function he needs, no more and no less!

The design examples given are illustrative of some typical operations used in ordinary systems. In each case, the example could be thought of as simply an "off the shelf" standard solution to an every day problem (i.e., a de facto standard product).



**Figure 3.7 Encoder**

## Application Specific Products

### SUCCESSOR ARCHITECTURES

The design examples described and Table 2.2 illustrate the combinational power and the sequential limitations of the PLHS501 - Signetics first PML entry. Clearly, the next family members must address the flip-flop issue, and they do. The PLHS502 (Figure 4.1) shows a similar NAND function array of 64 gates with the vital addition of 8 buried D-flip-flops and 8 buried S-R flip-flops. Again, 16 pins are devoted to dedicated outputs, 20 straight inputs, 4 clock or general

inputs and 8 bidirectionals can be configured to expand input or output capabilities. Slated to operate in the middle 30MHz clocking range, this part greatly expands the sequencer capability beyond the initial PLHS501. The PLHS502 application range will include state machines like CRC generation/detection, Bus handshakers, LAN handshaking, arithmetic coprocessors, single chip systems and a complete bevy of general sequencer operations such as sequence generation and detection. It should be emphasized that the

NAND array is fully connected and circumvents limitations on connectivity as found in other PLD products.

Almost simultaneous with the arrival of the PLHS502 (a bipolar part) will be the first CMOS PML entry. Expanding on the functional capabilities of the PLHS502, the CMOS part will offer 52 flip-flops in a variety of natural configurations with a NAND array near 200 gates. Due to complexity and density, the part will combine a distinctive power-save option and the benefits of scan-design.

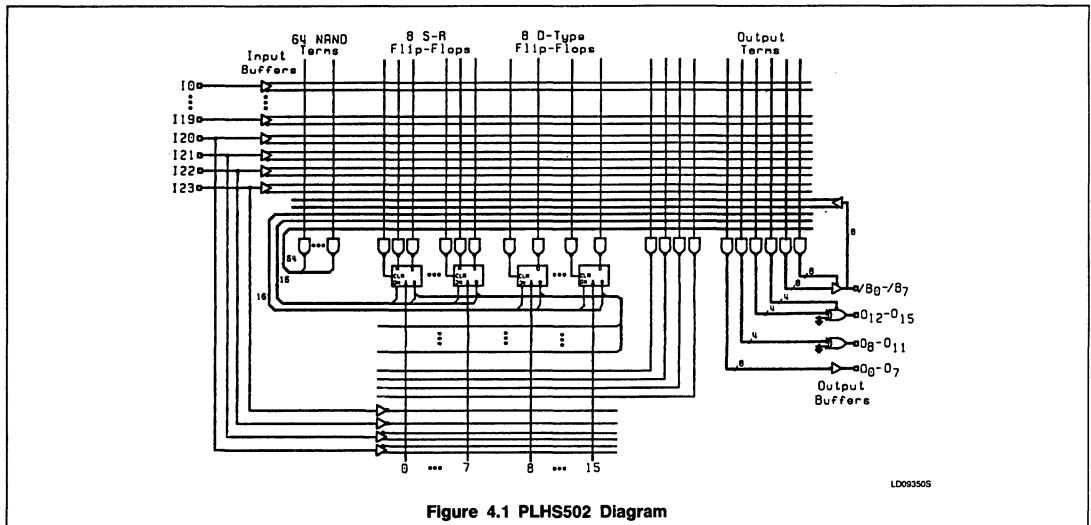


Figure 4.1 PLHS502 Diagram

## Application Specific Products

### SUPPORT ISSUES

The current PML architecture, the PLHS501, is adequately supported by Signetics AMAZE software. Offered free to qualified users, AMAZE can generate the required design files, fusemaps and simulations within the appropriate modules of AMAZE. From a simple menu driven environment on an IBM personal computer (or compatible under MS/DOS), the user can generate a design with logic equations, state equations or schematic entry (using FutureNet Dash or ORCAD SDT software). Once the design is entered, the user must "assemble" it prior to fusing the PML product. If required, the user may simulate the assembled file to determine the accuracy and functional operation of his design. Iteration between design entry, assembly and simulation may be required, depending on the users expectations and the completeness of design. Automatic test vector generation is a simulation option. Currently,

the designer may fuse his design using either a DATA I/O Unisite programmer, a Stag ZL-30A or a STREBOR fusing system with corresponding configuration modules.

The AMAZE product is fully contained and complete except for the schematic capture program. Although it is used for the complete line of Signetics PLD products (PLAs, Sequencers and PROMs), it has undergone additional modification to support special features required by the nature of the PML products. These include the following:

- **Internal Nodes** — the ability to define and refer to nodes completely within the array and isolated from direct contact with the device I/O pins.
- **Bracket Freezing** — the ability to tag (with square brackets) a Boolean subfunction which is not to be optimized by the AMAZE assembler but is to be realized within the design explicitly as described by equation.

Both features are key to the AMAZE approach to macro generation. In particular, "bracket freezing" allows the designer to make tradeoffs between wide and shallow combinational paths and long, narrow combinational paths.

In the current rendition of AMAZE, automatic placement and interconnect of the fused Boolean functions is the recommended approach. Should the user decide to intervene, a special fuse table editor exists for manual alteration of the design file. This is not the recommended approach, but it also serves as a diagnostic tool to review design placement and interconnect.

Future directions for software support include enhanced simulation, exhaustive automatic Boolean optimization, the development of a full library of macros, automatic design partitioning and a wide assortment of bells and whistles.

## Application Specific Products

### PLHS501 EXAMPLES USING AMAZE REVISION 1.6

- Simple gate implementations
- 8-bit barrel shifter
- 12-bit comparator with dual 1 of 8 decoders
- 8-bit carry look-ahead adder
- 32 to 5 priority encoder
- 8-bit shift register with 3-bit counter and sequence detector
- 4-bit synchronous counter

Following are six example applications for the PLHS501 using AMAZE Rev. 1.6. They should not be viewed as showing all possible capabilities of the device. They have been designed to demonstrate some of the PLHS501 features, syntax of AMAZE, and to give the reader some ideas for possible circuit implementations.

Note that these examples were written using AMAZE Rev. 1.6. Although Signetics will try to keep succeeding versions of AMAZE compatible, it may be necessary to change some syntax rules. Therefore, please refer to your AMAZE manual for any notes on differences, if using a revision later than Rev. 1.6.

### SIMPLE GATE IMPLEMENTATIONS

In this example six functions were implemented for each of the three major types of output structures. The six functions are AND/OR, AOI, NAND, AND, OR and NOR. A requirement for the AND/OR and AOI gates was to use only two gates each from the foldback array and to combine these product terms in one NAND output gate. To achieve this result, it was necessary for the /B and /O outputs to write equations using internal nodes and brackets around the equation. Refer to Figures 6.1 and 6.2.

For the simulation (Figures 6.3 and 6.4) a binary count of 0 through 15 hex was applied to the input D-A. Each output of the log file was checked against anticipated and other device outputs of the same function for correct operation.

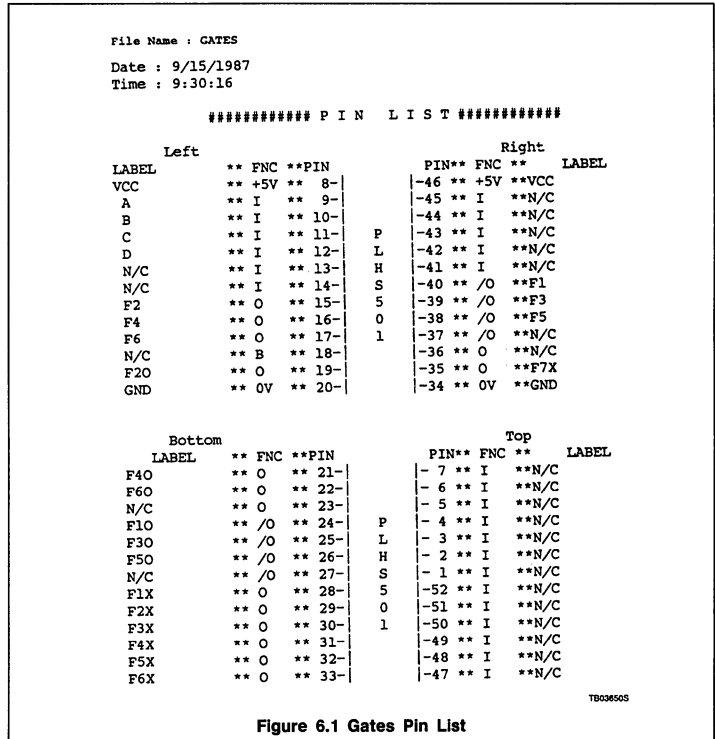


Figure 6.1 Gates Pin List



# Designing with Programmable Macro Logic

```

PLHS501          GATES          Time - 13:59:42 Date - 9/14/1987
- <-----INPUTS-----> < B,/B > < XOR > < /O,O > TRACE TERMS
- 222211111111111
- 321098765432109876543210 76543210 76543210 76543210
-
11000011111111111111111111111111 HHLHLHLH LLHLHLHL LLHLHLHL ;
11100011111111111111111111111111 HLLHLHLH LLLHLHLH LHLHLHLH ;
11010011111111111111111111111111 HLLHLHLH LLLHLHLH LHLHLHLH ;
11110011111111111111111111111111 HLLLHHHL LLLHLHLH LHHHHLHL ;
11001011111111111111111111111111 HLLHLHLH LHLHLHLH LHLHLHLH ;
11101011111111111111111111111111 HLLHLHLH LHLHLHLH LHLHLHLH ;
11011011111111111111111111111111 HLLHLHLH LHLHLHLH LHLHLHLH ;
11111011111111111111111111111111 HLLLHHHL LHLHLHLH LHHHHLHL ;
11000111111111111111111111111111 HLLHLHLH LHLHLHLH LHLHLHLH ;
11100111111111111111111111111111 HLLHLHLH LHLHLHLH LHLHLHLH ;
11010111111111111111111111111111 HLLHLHLH LHLHLHLH LHLHLHLH ;
11110111111111111111111111111111 HLLLHHHL LHLHLHLH LHHHHLHL ;
11001111111111111111111111111111 HLLHLHLH LLLHLHLH LHHHHLHL ;
11101111111111111111111111111111 HLLLHHHL LLLHLHLH LHHHHLHL ;
11011111111111111111111111111111 HLLHLHLH LLLHLHLH LHHHHLHL ;
11111111111111111111111111111111 HLLHLHLH LLLHLHLH LHLHLHLH ;
-
- ----- I/O CONTROL LINES
- 00000000 DESIGNATED I/O USAGE
- 00000000 ACTUAL I/O USAGE
-
- PINLIST...
- 14 13 12 11 10 09 07 06 05 04 03 02 01 52 51 50 49 48 47 45 44 43 42 41
- 18 17 16 15 40 39 38 37 36 35 33 32 31 30 29 28
- 27 26 25 24 23 22 21 19 ;

```

TB009605

Figure 6.4 Gates Simulation Log File

# Designing with Programmable Macro Logic

## 8 BIT BARREL SHIFTER

This 8-bit shifter will shift to the right, data applied to A7 – A0 with the result appearing on OUT7 – OUT0. Data may be shifted by 1 to 7 places by indicating the desired binary count on pins SHIFT2 – SHIFT0. Data applied to the OUT0 position for a shift of 1. For a shift of 0, A7 will appear on OUT7.

Also included is a transparent latch for the output bits. The input 'COMPLMTO' will invert all output bits simultaneously and input /OE will 3-State all outputs.

```

File Name : BRLSHFT
Date : 9/15/1987
Time : 9:31:58

##### P I N   L I S T #####

          Left                               Right
 LABEL   ** FNC **PIN                       PIN** FNC ** LABEL
VCC      ** +5V ** 8- |                       -46 ** +5V **VCC
A2       ** I   ** 9- |                       -45 ** I   **N/C
A3       ** I   **10- |                      -44 ** I   **N/C
A4       ** I   **11- |      P                -43 ** I   **N/C
A5       ** I   **12- |      L                -42 ** I   **N/C
A6       ** I   **13- |      H                -41 ** I   **N/C
A7       ** I   **14- |      S                -40 ** /O  **L0
L4       ** O   **15- |                       -39 ** /O  **L1
L5       ** O   **16- |      0                -38 ** /O  **L2
L6       ** O   **17- |      1                -37 ** /O  **L3
L7       ** O   **18- |                       -36 ** O   **OUT7
N/C      ** O   **19- |                       -35 ** O   **OUT6
GND      ** OV  **20- |                       -34 ** OV  **GND

          Bottom                             Top
 LABEL   ** FNC **PIN                       PIN** FNC ** LABEL
N/C      ** O   **21- |                       -7 ** I   **A1
N/C      ** O   **22- |                       -6 ** I   **A0
N/C      ** O   **23- |                       -5 ** I   **SHIFT2
N/C      ** /O  **24- |      P                -4 ** I   **SHIFT1
N/C      ** /O  **25- |      L                -3 ** I   **SHIFT0
N/C      ** /O  **26- |      H                -2 ** I   **COMPLMTO
N/C      ** /O  **27- |      S                -1 ** I   **/LE
OUT0     ** O   **28- |      5                -52 ** I   **/OE
OUT1     ** O   **29- |      0                -51 ** I   **N/C
OUT2     ** O   **30- |      1                -50 ** I   **N/C
OUT3     ** O   **31- |                       -49 ** I   **N/C
OUT4     ** O   **32- |                       -48 ** I   **N/C
OUT5     ** O   **33- |                       -47 ** I   **N/C
    
```

Figure 6.5 Barrel Shifter Pin List

TB037005

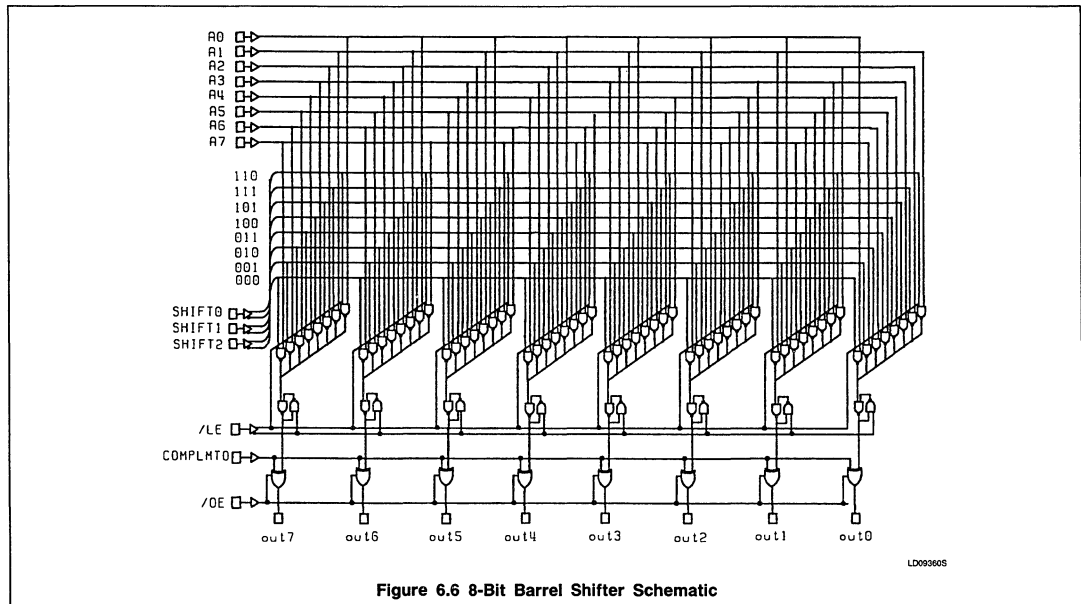


Figure 6.6 8-Bit Barrel Shifter Schematic

LD092605

## Designing with Programmable Macro Logic

```

File Name : BRLSHFT
Date : 9/15/1987
Time : 9:32:14

@DEVICE TYPE
PLHS501
@DRAWING
@REVISION
@DATE
@SYMBOL
@COMPANY
@NAME
@DESCRIPTION

8 Bit Barrel Shifter
with 3-state latched outputs

@INTERNAL NODE
nod1,nod2,nod3,nod4,nod5,nod6,nod7,nod8;
nod9,nod10,nod11,nod12,nod13,nod14,nod15,nod16;
nod17,nod18,nod19,nod20,nod21,nod22,nod23,nod24;
nod25,nod26,nod27,nod28,nod29,nod30,nod31,nod32;
i3,i2,i1,i0;
@COMMON PRODUCT TERM
rot0 = /shift2 * /shift1 * /shift0;
rot1 = /shift2 * /shift1 * shift0;
rot2 = /shift2 * shift1 * /shift0;
rot3 = /shift2 * shift1 * shift0;
rot4 = shift2 * /shift1 * /shift0;
rot5 = shift2 * /shift1 * shift0;
rot6 = shift2 * shift1 * /shift0;
rot7 = shift2 * shift1 * shift0;
@I/O DIRECTION
xe0 = ce;
xe1 = ce;
xe2 = ce;
xe3 = ce;
@I/O STEERING
@LOGIC EQUATION

17 = /{a7 * rot0 * /le +
      a6 * rot1 * /le +
      a5 * rot2 * /le +
      a4 * rot3 * /le +
      a3 * rot4 * /le +
      a2 * rot5 * /le +
      a1 * rot6 * /le +

```

TB027105

Figure 6.7 Barrel Shifter Boolean Equations



## Designing with Programmable Macro Logic

```

a0 * rot7 * /1e +
1e * /17);

16 = /{a6 * rot0 * /1e +
a5 * rot1 * /1e +
a4 * rot2 * /1e +
a3 * rot3 * /1e +
a2 * rot4 * /1e +
a1 * rot5 * /1e +
a0 * rot6 * /1e +
a7 * rot7 * /1e +
1e * /16};

15 = /{a5 * rot0 * /1e +
a4 * rot1 * /1e +
a3 * rot2 * /1e +
a2 * rot3 * /1e +
a1 * rot4 * /1e +
a0 * rot5 * /1e +
a7 * rot6 * /1e +
a6 * rot7 * /1e +
1e * /15};

14 = /{a4 * rot0 * /1e +
a3 * rot1 * /1e +
a2 * rot2 * /1e +
a1 * rot3 * /1e +
a0 * rot4 * /1e +
a7 * rot5 * /1e +
a6 * rot6 * /1e +
a5 * rot7 * /1e +
1e * /14};

nod1 = {a3 * rot0 * /1e};
nod2 = {a2 * rot1 * /1e};
nod3 = {a1 * rot2 * /1e};
nod4 = {a0 * rot3 * /1e};
nod5 = {a7 * rot4 * /1e};
nod6 = {a6 * rot5 * /1e};
nod7 = {a5 * rot6 * /1e};
nod8 = {a4 * rot7 * /1e};
i3 = [1e * 13];

13 = /{[nod1*/nod2*/nod3*/nod4*/nod5*/nod6*/nod7*/nod8*/i3]};

nod9 = {a2 * rot0 * /1e};
nod10 = {a1 * rot1 * /1e};

```

TB03720S

Figure 6.7 Barrel Shifter Boolean Equations (Continued)

## Designing with Programmable Macro Logic

```

nod11= [a0 * rot2 * /1e];
nod12= [a7 * rot3 * /1e];
nod13= [a6 * rot4 * /1e];
nod14= [a5 * rot5 * /1e];
nod15= [a4 * rot6 * /1e];
nod16= [a3 * rot7 * /1e];
i2 = [1e * i2];

12 = /([/nod9*/nod10*/nod11*/nod12*/nod13*/nod14*/nod15*/nod16*/i2]);

nod17= [a1 * rot0 * /1e];
nod18= [a0 * rot1 * /1e];
nod19= [a7 * rot2 * /1e];
nod20= [a6 * rot3 * /1e];
nod21= [a5 * rot4 * /1e];
nod22= [a4 * rot5 * /1e];
nod23= [a3 * rot6 * /1e];
nod24= [a2 * rot7 * /1e];
i1 = [1e * i1];

11 = /([/nod17*/nod18*/nod19*/nod20*/nod21*/nod22*/nod23*/nod24*/i1]);

nod25= [a0 * rot0 * /1e];
nod26= [a7 * rot1 * /1e];
nod27= [a6 * rot2 * /1e];
nod28= [a5 * rot3 * /1e];
nod29= [a4 * rot4 * /1e];
nod30= [a3 * rot5 * /1e];
nod31= [a2 * rot6 * /1e];
nod32= [a1 * rot7 * /1e];
i0 = [1e * i0];

10 = /([/nod25*/nod26*/nod27*/nod28*/nod29*/nod30*/nod31*/nod32*/i0]);

out7 : xr1 = /17;
      xr2 = complmto;
out6 : xr1 = /16;
      xr2 = complmto;
out5 : xr1 = /15;
      xr2 = complmto;
out4 : xr1 = /14;
      xr2 = complmto;
out3 : xr1 = 13;
      xr2 = complmto;
out2 : xr1 = 12;
      xr2 = complmto;
out1 : xr1 = 11;

TB037305

out0 : xr1 = 10;
      xr2 = complmto;

TB037405

```

Figure 6.7 Barrel Shifter Boolean Equations (Continued)





## Designing with Programmable Macro Logic

```

File Name : 12BITCMP
Date : 9/15/1987
Time : 9:36:0

##### P I N   L I S T #####

      Left                                     Right
  LABEL  ** FNC **PIN | PIN** FNC ** LABEL
VCC      ** +5V ** 8- | -46 ** +5V **VCC
B5       ** I   ** 9- | -45 ** I   **A4
B7       ** I   **10- | -44 ** I   **A3
B8       ** I   **11- | P  -43 ** I   **A2
B9       ** I   **12- | L  -42 ** I   **A1
B10      ** I   **13- | H  -41 ** I   **A0
B11      ** I   **14- | S  -40 ** /O **CMPOUT
ENCOMP   ** I   **15- | 5  -39 ** I   **DA2
DCDREN   ** I   **16- | 0  -38 ** I   **DA1
RW       ** I   **17- | 1  -37 ** I   **DA0
N/C      ** B   **18- |   -36 ** O   **R7
W0       ** O   **19- |   -35 ** O   **R6
GND      ** OV  **20- | -34 ** OV   **GND

      Bottom                                   Top
  LABEL  ** FNC **PIN | PIN** FNC ** LABEL
W1       ** O   **21- | - 7 ** I   **B5
W2       ** O   **22- | - 6 ** I   **B4
W3       ** O   **23- | - 5 ** I   **B3
W4       ** /O  **24- | ← P - 4 ** I   **B2
W5       ** /O  **25- | L  - 3 ** I   **B1
W6       ** /O  **26- | H  - 2 ** I   **B0
W7       ** /O  **27- | S  - 1 ** I   **A11
R0       ** O   **28- | 5  -52 ** I   **A10
R1       ** O   **29- | 0  -51 ** I   **A9
R2       ** O   **30- | 1  -50 ** I   **A8
R3       ** O   **31- |   -49 ** I   **A7
R4       ** O   **32- |   -48 ** I   **A6
R5       ** O   **33- | -47 ** I   **A5
    
```

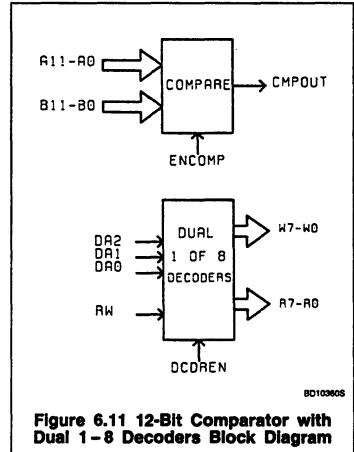
TB007705

**Figure 6.10 12-Bit Comparator Pin List**

### 12 BIT COMPARATOR WITH DUAL 1 OF 8 DECODERS

Two functions that are very often associated with controlling I/O parts are address comparison and address decoding. In this example, both functions are programmed into a PLHS501 using 52 out of the 72 foldback NAND terms.

The comparator compares 12 bits on inputs A11 - A0 to inputs B11 - B0 when the input 'ENCMP' is High. Output 'CMPOUT' will become active-Low when all 12 bits of the A input match the B. Selection between the two decoders is done with input 'R/W'. Only one output may be active (Low) at a time. Although currently separate functions, the decoder enable may be derived internally from 'CMPOUT' freeing 2 bidirectional pins which together with available foldback NAND terms, may be used to incorporate a third function.



**Figure 6.11 12-Bit Comparator with Dual 1 - 8 Decoders Block Diagram**

## Designing with Programmable Macro Logic

```
File Name : 12BITCMP
Date : 9/15/1987
Time : 9:36:17
```

```
@DEVICE TYPE
PLHS501
@DRAWING
@REVISION
@DATE
@SYMBOL
@COMPANY
@NAME
@DESCRIPTION
```

12-bit address comparator and dual 1 of 8 decoders

```
@INTERNAL NODE
axb0,axb1,axb2,axb3,axb4,axb5,axb6;
axb7,axb8,axb9,axb10,axb11;
@COMMON PRODUCT TERM
ad0=/da2*/dal*/da0*dcdrn;
ad1=/da2*/dal* da0*dcdrn;
ad2=/da2* dal*/da0*dcdrn;
ad3=/da2* dal* da0*dcdrn;
ad4= da2*/dal*/da0*dcdrn;
ad5= da2*/dal* da0*dcdrn;
ad6= da2* dal*/da0*dcdrn;
ad7= da2* dal* da0*dcdrn;
@I/O DIRECTION
@I/O STEERING
@LOGIC EQUATION
```

"12-Bit Address Comparator"

```
axb0 = a0*/b0 + /a0*b0;
axb1 = a1*/b1 + /a1*b1;
axb2 = a2*/b2 + /a2*b2;
axb3 = a3*/b3 + /a3*b3;
axb4 = a4*/b4 + /a4*b4;
axb5 = a5*/b5 + /a5*b5;
axb6 = a6*/b6 + /a6*b6;
axb7 = a7*/b7 + /a7*b7;
axb8 = a8*/b8 + /a8*b8;
axb9 = a9*/b9 + /a9*b9;
axb10 = a10*/b10 + /a10*b10;
axb11 = a11*/b11 + /a11*b11;
```

TB03780S

```
cmpout = /(axb0*/axb1*/axb2*/axb3*/axb4*/axb5*/axb6*/axb7*/axb8*/axb9*
/axb10*/axb11*encmp);
```

"Dual 1 of 8 decoders

```
- da2-da0 are address inputs
- dcdren is an enable input
- rw selects which group of 8 outputs r7-r0 or w7-w0
  will have the decoded active low output"
```

```
w7 = /(ad7*/rw);
w6 = /(ad6*/rw);
w5 = /(ad5*/rw);
w4 = /(ad4*/rw);
w3 = /(ad3*/rw);
w2 = /(ad2*/rw);
w1 = /(ad1*/rw);
w0 = /(ad0*/rw);
```

```
r7 = /(ad7* rw);
r6 = /(ad6* rw);
r5 = /(ad5* rw);
r4 = /(ad4* rw);
r3 = /(ad3* rw);
r2 = /(ad2* rw);
r1 = /(ad1* rw);
r0 = /(ad0* rw);
```

TB03780S

Figure 6.12 12-Bit Comparator Boolean Equations

## Designing with Programmable Macro Logic

```

* Simulation inputs for 12BITCMP
* <-----INPUTS-----> < B,/B >
* 2222HHHHHHHHHH
* 32HL98765432HL98765432HL 765432HL
*
LLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLL -LLL-LLL "disable comp"
LLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLL -LLH-LLL "enable comp"
HLLHLLHLLHLLHLLHLLHLLHLLHLLHLLHLLHLLHLL -LLH-LLL "comp AA"
LHLHLHLHLHLHLHLHLHLHLHLHLHLHLHLHLHLHL -LLH-LLL "comp 55"
HHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHH -LLH-LLL "comp FP"
HHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHHH -LLH-LLL "A not equal B"
LLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLL -LHL-LLL "enable decoder W"
LLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLL -HHL-LLL "enable decoder R"
LLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLL -HHL-LH "count 1"
LLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLL -HHL-LHL " 2"
LLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLL -HHL-LHH " 3"
LLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLL -HHL-HLL " 4"
LLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLL -HHL-HLH " 5"
LLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLL -HHL-HHL " 6"
LLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLL -HHL-HHH " 7"
LLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLL -LHL-HHH "enable decoder W"
QUIT

```

TB038005

Figure 6.13 12-Bit Comparator Simulation Input File

```

PLHS501      12BITCMP      Time - 15:0:58 Date - 9/14/1987
* <-----INPUTS-----> < B,/B > < XOR > < /O,O > TRACE TERMS
* 2222111111111111
* 321098765432109876543210 76543210 76543210 76543210
*
0000000000000000000000000000 H000H000 HHHHHHHH HHHHHHHH ;
0000000000000000000000000000 H00L0000 HHHHHHHH HHHHHHHH ;
1010101010101010101010101010 H00L0000 HHHHHHHH HHHHHHHH ;
0101010101010101010101010101 H00L0000 HHHHHHHH HHHHHHHH ;
1111111111111111111111111111 H00L0000 HHHHHHHH HHHHHHHH ;
1111111111110111111111111111 H00L0000 HHHHHHHH HHHHHHHH ;
0000000000000000000000000000 H010H000 HHHHHHHH HHHHHHHL ;
0000000000000000000000000000 H110H000 HHHHHHHL HHHHHHHH ;
0000000000000000000000000000 H110H001 HHHHHHLH HHHHHHHH ;
0000000000000000000000000000 H110H010 HHHHLLHH HHHHHHHH ;
0000000000000000000000000000 H110H011 HHHHLLHH HHHHHHHH ;
0000000000000000000000000000 H110H100 HHLHLHHH HHHHHHHH ;
0000000000000000000000000000 H110H101 HHLHLHHH HHHHHHHH ;
0000000000000000000000000000 H110H101 HHLHLHHH HHHHHHHH ;
0000000000000000000000000000 H110H101 HHLHLHHH HHHHHHHH ;
0000000000000000000000000000 H110H111 LHHLHHHH HHHHHHHH ;
0000000000000000000000000000 H010H111 HHHHHHHH LHHLHHHH ;
*
* ----- I/O CONTROL LINES
* OIIIOIII DESIGNATED I/O USAGE
* OIIIOIII ACTUAL I/O USAGE
*
* PINLIST...
14 13 12 11 10 09 07 06 05 04 03 02 01 52 51 50 49 48 47 45 44 43 42 41
18 17 16 15 40 39 38 37 36 35 33 32 31 30 29 28
27 26 25 24 23 22 21 19 ;

```

TB038105

Figure 6.14 12-Bit Comparator Simulation Log File

# Designing with Programmable Macro Logic

## 8-BIT CARRY LOOK-AHEAD ADDER

This function may be used as part of an ALU design or simply to off-load a microprocessor. Figure 6.16 is a block diagram showing the individual components needed for each bit.

A carry input (C0) is provided along with a carry output (C8). The result of an addition between the inputs A7 - A0 and B7 - B0 occurs on outputs SUM7 - SUM0.

File Name : 8BITADDR  
Date : 9/15/1987  
Time : 9:37:21

##### P I N L I S T #####

Left			Right		
LABEL	** FNC	**PIN	PIN** FNC	** LABEL	LABEL
VCC	** +5V	** 8-	-46	** +5V	**VCC
A2	** I	** 9-	-45	** I	**N/C
A3	** I	** 10-	-44	** I	**N/C
A4	** I	** 11-	-43	** I	**N/C
A5	** I	** 12-	-42	** I	**N/C
A6	** I	** 13-	-41	** I	**N/C
A7	** I	** 14-	-40	** /O	**N/C
N/C	** B	** 15-	-39	** /O	**N/C
N/C	** B	** 16-	-38	** /O	**N/C
N/C	** B	** 17-	-37	** /O	**N/C
N/C	** B	** 18-	-36	** O	**SUM7
C8	** O	** 19-	-35	** O	**SUM6
GND	** OV	** 20-	-34	** OV	**GND

Bottom			Top		
LABEL	** FNC	**PIN	PIN** FNC	** LABEL	LABEL
N/C	** O	** 21-	-7	** I	**A1
N/C	** O	** 22-	-6	** I	**A0
N/C	** O	** 23-	-5	** I	**B7
N/C	** /O	** 24-	-4	** I	**B6
N/C	** /O	** 25-	-3	** I	**B5
N/C	** /O	** 26-	-2	** I	**B4
N/C	** /O	** 27-	-1	** I	**B3
SUM0	** O	** 28-	-52	** I	**B2
SUM1	** O	** 29-	-51	** I	**B1
SUM2	** O	** 30-	-50	** I	**B0
SUM3	** O	** 31-	-49	** I	**C0
SUM4	** O	** 32-	-48	** I	**N/C
SUM5	** O	** 33-	-47	** I	**N/C

TB008205

Figure 6.15 8-Bit Adder Pin List

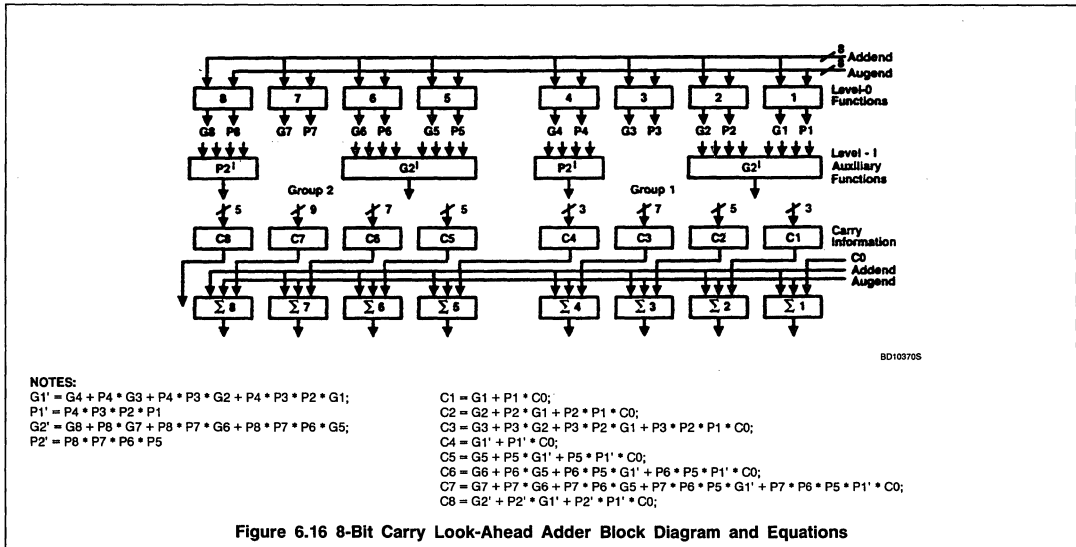


Figure 6.16 8-Bit Carry Look-Ahead Adder Block Diagram and Equations



## Designing with Programmable Macro Logic

```

File Name : 8BITADDR
Date : 9/15/1987
Time : 9:37:36
@DEVICE TYPE
PLHS501
@DRAWING
@REVISION
@DATE
@SYMBOL
@COMPANY
@NAME
@DESCRIPTION
8 Bit Carry Look-Ahead Adder

@INTERNAL NODE
g8, g1, g2, g3, g4, g5, g6, g7;
p8, p1, p2, p3, p4, p5, p6, p7;
gn8, gn1, gn2, gn3, gn4, gn5, gn6, gn7;
c1, c2, c3, c4, c5, c6, c7;
g1_1, g2_1;
@COMMON PRODUCT TERM
@I/O DIRECTION
@I/O STEERING
@LOGIC EQUATION

"level-0 functions"
gn1 = /(a0*b0);
p1 = /(a0*/b0);
g1 = /gn1;

gn2 = /(a1*b1);
p2 = /(a1*/b1);
g2 = /gn2;

gn3 = /(a2*b2);
p3 = /(a2*/b2);
g3 = /gn3;

gn4 = /(a3*b3);
p4 = /(a3*/b3);
g4 = /gn4;

gn5 = /(a4*b4);
p5 = /(a4*/b4);
g5 = /gn5;

gn6 = /(a5*b5);

```

TB038305

**Figure 6.17 8-Bit Adder Boolean Equations**

```

p6 = /(a5*/b5);
g6 = /gn6;

gn7 = /(a6*b6);
p7 = /(a6*/b6);
g7 = /gn7;

gn8 = /(a7*b7);
p8 = /(a7*/b7);
g8 = /gn8;

"level-1 functions"
g1_1 = g4 + p4*g3 + p4*p3*g2 + p4*p3*p2*g1;
g2_1 = g8 + p8*g7 + p8*p7*g6 + p8*p7*p6*g5;

"carry information"
c1 = g1 + p1*c0;
c2 = g2 + p2*g1 + p2*p1*c0;
c3 = g3 + p3*g2 + p3*p2*g1 + p3*p2*p1*c0;
c4 = g1_1 + p4*p3*p2*p1*c0;
c5 = g5 + p5*g1_1 + p5*p4*p3*p2*p1*c0;
c6 = g6 + p6*g5 + p6*p5*g1_1 + p6*p5*p4*p3*p2*p1*c0;
c7 = g7 + p7*g6 + p7*p6*g5 + p7*p6*p5*g1_1 +
      p7*p6*p5*p4*p3*p2*p1*c0;
c8 = g2_1 + p8*p7*p6*p5*g1_1 + p8*p7*p6*p5*p4*p3*p2*p1*c0;

"addition functions"
sum0 : xr1 = c0;
      xr2 = p1 * gn1;
sum1 : xr1 = c1;
      xr2 = p2 * gn2;
sum2 : xr1 = c2;
      xr2 = p3 * gn3;
sum3 : xr1 = c3;
      xr2 = p4 * gn4;
sum4 : xr1 = c4;
      xr2 = p5 * gn5;
sum5 : xr1 = c5;
      xr2 = p6 * gn6;
sum6 : xr1 = c6;
      xr2 = p7 * gn7;
sum7 : xr1 = c7;
      xr2 = p8 * gn8;

```

TB040705

**Figure 6.17 8-Bit Adder Boolean Equations (Continued)**

```

* 8 Bit Adder Simulation input
*
* <-----INPUTS-----> < B,/B >
* 2222HHHHHHHHHHH1
* 321098765432109876543210 76543210
*
* LLLLLLLLLLLLLLLLLHHHHHHH ----- "0 + 0"
* HHHHHHLLLLLLLLLHHHHHHH ----- "0 + FF"
* HHHHHHLLLLLLLLLHHHHHHH ----- "1 + FF"
* LHHHHHLLLLLLLLLHHHHHHH ----- "0 + 7F + CARRY IN"
* HLHLHLHLHLHLHLHLHHHHH ----- "AA + 55"
* HLHLHLHLHLHLHLHLHHHHH ----- "AA + 55 + CARRY IN"
* LLLLLLLLLLLLLLLLLHHHHHHH ----- "3F + 1F"
*
* QUIT

```

TB038405

**Figure 6.18 8-Bit Adder Simulation Input File**

# Designing with Programmable Macro Logic

```

PLHS501          8BITADDR          Time = 15:41:33 Date = 9/14/1987
-
- <-----INPUTS-----> < B,/B > < XOR > < /O,O > TRACE TERMS
- 2222111111111111
- 321098765432109876543210 76543210 76543210 76543210
-
000000000000000001111111 HHHLLLLL LLLLLLLL LLLLHHHL ;
1111110000000010111111 HHHLLLLL HHHHHHHH LLLLHHHL ;
1111110000000100111111 HHHLLLLL LLLLLLLL LLLLHHHH ;
0111110000000011111111 HHHLLLLL HLLLLLLL LLLLHHHL ;
1010100010101010111111 HHHLLLLL HHHHHHHH LLLLHHHL ;
1010100010101011111111 HHHLLLLL LLLLLLLL LLLLHHHH ;
0011111000111110111111 HHHLLLLL LHLHHHHL LLLLHHHL ;
-
- ----- I/O CONTROL LINES
- 00000000 DESIGNATED I/O USAGE
- 00000000 ACTUAL I/O USAGE
-
- PINLIST...
- 14 13 12 11 10 09 07 06 05 04 03 02 01 52 51 50 49 48 47 45 44 43 42 41
- 18 17 16 15 40 39 38 37 36 35 33 32 31 30 29 28
- 27 26 25 24 23 22 21 19 ;

```

TB03850S

Figure 6.19 8-Bit Adder Simulation Log File

# Designing with Programmable Macro Logic

File Name : ENCODER  
 Date : 9/15/1987  
 Time : 9:38:43

\*\*\*\*\* P I N L I S T \*\*\*\*\*

Left			Right		
LABEL	** FNC	**PIN	PIN** FNC	** LABEL	
VCC	** +5V	** 8-	-46 ** +5V	**VCC	
I18N	** I	** 9-	-45 ** I	**I4N	
I19N	** I	** 10-	-44 ** I	**I3N	
I20N	** I	** 11-	-43 ** I	**I2N	P
I21N	** I	** 12-	-42 ** I	**I1N	L
I22N	** I	** 13-	-41 ** I	**I0N	H
I23N	** I	** 14-	-40 ** I	**I31N	S
I24N	** I	** 15-	-39 ** I	**I30N	5
I25N	** I	** 16-	-38 ** I	**I29N	0
I26N	** I	** 17-	-37 ** I	**I28N	1
I27N	** I	** 18-	-36 ** O	**N/C	
N/C	** O	** 19-	-35 ** O	**A4N	
GND	** 0V	** 20-	-34 ** 0V	**GND	

Bottom			Top		
LABEL	** FNC	**PIN	PIN** FNC	** LABEL	
N/C	** O	** 21-	- 7 ** I	**I17N	
N/C	** O	** 22-	- 6 ** I	**I16N	
N/C	** O	** 23-	- 5 ** I	**I15N	
N/C	** /O	** 24-	- 4 ** I	**I14N	P
N/C	** /O	** 25-	- 3 ** I	**I13N	L
N/C	** /O	** 26-	- 2 ** I	**I12N	H
N/C	** /O	** 27-	- 1 ** I	**I11N	S
G5N	** O	** 28-	-52 ** I	**I10N	5
E0N	** O	** 29-	-51 ** I	**I9N	0
A0N	** O	** 30-	-50 ** I	**I8N	1
A1N	** O	** 31-	-49 ** I	**I7N	
A2N	** O	** 32-	-48 ** I	**I6N	
A3N	** O	** 33-	-47 ** I	**I5N	

Figure 6.20 Encoder Pin List

TB038605

## 32- to 5-BIT PRIORITY ENCODER

This relatively simple example demonstrates the capability of the PLHS501 to be programmed with functions that are not available in 'standard' device libraries. The equations may look difficult at first glance. However, there is a pattern to the encoding. Referring to Figure 6.21 Lab4 - Lab1 are terms that are common to several outputs (A4n - A0n). Separating them from the main equations allows a total reduction in the numbers of gates used.

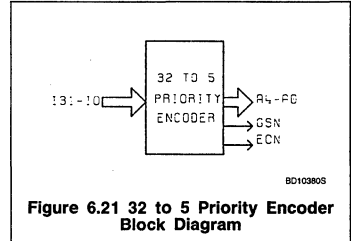


Figure 6.21 32 to 5 Priority Encoder Block Diagram

## Designing with Programmable Macro Logic

```

File Name : ENCODER
Date : 9/15/1987
Time : 9:39:1

@DEVICE TYPE
PIHS501
@DRAWING
@REVISION
@DATE
@SYMBOL
@COMPANY
@NAME
@DESCRIPTION
32 TO 5 PRIORITY ENCODER

@COMMON PRODUCT TERM
cpt1 = i26n*i27n*i28n*i29n*i30n*i31n;
cpt2 = i20n*i21n*i22n*i23n*i24n*i25n;
cpt3 = i14n*i15n*i16n*i17n*i18n*i19n;
cpt4 = i8n*i9n*i10n*i11n*i12n*i13n;

@INTERNAL NODE
eo lab1 lab2 lab3 lab4
@I/O DIRECTION
@I/O STEERING

@LOGIC EQUATION
lab1 = ( /i31n
+ [/i27n*i28n*i29n*i30n*i31n]
+ [/i23n*i24n*i25n*cpt1]
+ [/i19n*cpt2*cpt1]
+ [/i15n*i16n*i17n*i18n*i19n*cpt2*cpt1]
+ [/i11n*i12n*i13n*cpt3*cpt2*cpt1]
+ [/i7n*cpt4*cpt3*cpt2*cpt1]
+ [/i3n*i4n*i5n*i6n*i7n*cpt4*cpt3*cpt2*cpt1]);
lab2 = ( [/i23n*i24n*i25n*cpt1]
+ [/i22n*i23n*i24n*i25n*cpt1]
+ [/i21n*i22n*i23n*i24n*i25n*cpt1]
+ [/i20n*i21n*i22n*i23n*i24n*i25n*cpt1]);
lab3 = ( [/i15n*i16n*i17n*i18n*i19n*cpt2*cpt1]
+ [/i14n*i15n*i16n*i17n*i18n*i19n*cpt2*cpt1]
+ [/i13n*cpt3*cpt2*cpt1]
+ [/i12n*i13n*cpt3*cpt2*cpt1]);
lab4 = ( /i31n
+ [/i30n*i31n]
+ [/i29n*i30n*i31n]
+ [/i28n*i29n*i30n*i31n]

```

TB038705

Figure 6.22 Encoder Boolean Equations

## Designing with Programmable Macro Logic

```

+ [/i27n*i28n*i29n*i30n*i31n]
+ [/i26n*i27n*i28n*i29n*i30n*i31n]
+ [/i25n*cpt1]
+ [/i24n*i25n*cpt1]);
eo = /(i0n*i1n*i2n*i3n*i4n*i5n*i6n*i7n
*i8n*i9n*i10n*i11n*i12n*i13n*i14n*i15n
*i16n*i17n*i18n*i19n*i20n*i21n*i22n*i23n
*i24n*i25n*cpt1);
gsn = /eo;
ecn = eo;
a0n = /( lab1
+ [/i29n*i30n*i31n]
+ [/i25n*cpt1]
+ [/i21n*i22n*i23n*i24n*i25n*cpt1]
+ [/i17n*i18n*i19n*cpt2*cpt1]
+ [/i13n*cpt3*cpt2*cpt1]
+ [/i9n*i10n*i11n*i12n*i13n*cpt3*cpt2*cpt1]
+ [/i5n*i6n*i7n*cpt4*cpt3*cpt2*cpt1]
+ [/i1n*i2n*i3n*i4n*i5n*i6n*i7n*cpt4*cpt3*cpt2*cpt1]);
a1n = /( lab1
+ [/i30n*i31n]
+ [/i26n*i27n*i28n*i29n*i30n*i31n]
+ [/i22n*i23n*i24n*i25n*cpt1]
+ [/i18n*i19n*cpt2*cpt1]
+ [/i14n*i15n*i16n*i17n*i18n*i19n*cpt2*cpt1]
+ [/i10n*i11n*i12n*i13n*cpt3*cpt2*cpt1]
+ [/i6n*i7n*cpt4*cpt3*cpt2*cpt1]
+ [/i2n*i3n*i4n*i5n*i6n*i7n*cpt4*cpt3*cpt2*cpt1]);
a2n = /( /i31n
+ [/i30n*i31n]
+ [/i29n*i30n*i31n]
+ [/i28n*i29n*i30n*i31n]
+ lab2
+ lab3
+ [/i7n*cpt4*cpt3*cpt2*cpt1]
+ [/i6n*i7n*cpt4*cpt3*cpt2*cpt1]
+ [/i5n*i6n*i7n*cpt4*cpt3*cpt2*cpt1]
+ [/i4n*i5n*i6n*i7n*cpt4*cpt3*cpt2*cpt1]);
a3n = /( lab4
+ lab3
+ [/i11n*i12n*i13n*cpt3*cpt2*cpt1]
+ [/i10n*i11n*i12n*i13n*cpt3*cpt2*cpt1]
+ [/i9n*i10n*i11n*i12n*i13n*cpt3*cpt2*cpt1]
+ [/i8n*i9n*i10n*i11n*i12n*i13n*cpt3*cpt2*cpt1]);
a4n = /( lab4
+ lab2
+ [/i19n*cpt2*cpt1]
+ [/i18n*i19n*cpt2*cpt1]
+ [/i17n*i18n*i19n*cpt2*cpt1]
+ [/i16n*i17n*i18n*i19n*cpt2*cpt1]);

```

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**Figure 6.22 Encoder Boolean Equations (Continued)**

# Designing with Programmable Macro Logic

```

* 32 to 5 Priority Encoder Simulation Input
*
##### "Inputs all high"
##### "I31 - LSB low"
##### "I0 - MSB low"
##### "I30 low"
##### "I29"
##### "I28"
##### "I27"
##### "I26"
##### "I25"
##### "I24"
##### "I23"
##### "I22"
##### "I21"
##### "I20"
##### "I19"
##### "I18"
##### "I17"
##### "I16"
##### "I15"
##### "I14"
##### "I13"
##### "I12"
##### "I11"
##### "I10"
##### "I9"
##### "I8"
##### "I7"
##### "I6"
##### "I5"
##### "I4"
##### "I3"
##### "I2"
##### "I1"
##### "I0"
##### "ALL HIGH"
##### "ALL LOW"
##### "Several simultaneously"
QUIT

```

TB029005

Figure 6.23 Encoder Simulation Input File

## Designing with Programmable Macro Logic

```

PLHS501          ENCODER          Time - 15:50:28 Date - 9/14/1987
-
- <-----INPUTS-----> < B,/B > < XOR > < /O,O > TRACE TERMS
- 2222111111111111
- 321098765432109876543210 76543210 76543210 76543210
-
11111111111111111111 11111111 1AHHHHLH LLLLHHHH ;
11111111111111111111 11110111 1LLELLHL LLLLHHHH ;
11111111111111111110 11111111 1AHHHHLH LLLLHHHH ;
11111111111111111111 11111011 1LLELLHL LLLLHHHH ;
11111111111111111111 11111101 1LLELLHL LLLLHHHH ;
11111111111111111111 11111110 1LLLHHHL LLLLHHHH ;
11111111111111111111 01111111 1LLELLHL LLLLHHHH ;
11111111111111111111 10111111 1LLELLHL LLLLHHHH ;
11111111111111111111 11011111 1LLELLHL LLLLHHHH ;
11111111111111111111 11101111 1LLELLHL LLLLHHHH ;
01111111111111111111 11111111 1LLELLHL LLLLHHHH ;
10111111111111111111 11111111 1LLELLHL LLLLHHHH ;
11011111111111111111 11111111 1LLELLHL LLLLHHHH ;
11101111111111111111 11111111 1LLELLHL LLLLHHHH ;
11110111111111111111 11111111 1LLELLHL LLLLHHHH ;
11111011111111111111 11111111 1LLELLHL LLLLHHHH ;
11111011111111111111 11111111 1LLELLHL LLLLHHHH ;
11111101111111111111 11111111 1LLELLHL LLLLHHHH ;
11111101111111111111 11111111 1LLELLHL LLLLHHHH ;
11111110111111111111 11111111 1LLELLHL LLLLHHHH ;
11111110111111111111 11111111 1LLELLHL LLLLHHHH ;
11111111011111111111 11111111 1LLELLHL LLLLHHHH ;
11111111011111111111 11111111 1LLELLHL LLLLHHHH ;
11111111101111111111 11111111 1LLELLHL LLLLHHHH ;
11111111101111111111 11111111 1LLELLHL LLLLHHHH ;
11111111110111111111 11111111 1LLELLHL LLLLHHHH ;
11111111110111111111 11111111 1LLELLHL LLLLHHHH ;
11111111111011111111 11111111 1LLELLHL LLLLHHHH ;
11111111111101111111 11111111 1LLELLHL LLLLHHHH ;
11111111111110111111 11111111 1LLELLHL LLLLHHHH ;
11111111111111011111 11111111 1LLELLHL LLLLHHHH ;
11111111111111101111 11111111 1LLELLHL LLLLHHHH ;
11111111111111110111 11111111 1LLELLHL LLLLHHHH ;
11111111111111111011 11111111 1LLELLHL LLLLHHHH ;
11111111111111111101 11111111 1LLELLHL LLLLHHHH ;
11111111111111111110 11111111 1LLELLHL LLLLHHHH ;
11111111111111111111 11111111 1LLELLHL LLLLHHHH ;
00000000000000000000 00000000 1LLLHLHL LLLLHHHH ;
111011101111011110111011 11101101 1LLLHLHL LLLLHHHH ;
-
- ----- I/O CONTROL LINES
- IIIIIIII DESIGNATED I/O USAGE
- IIIIIIII ACTUAL I/O USAGE
-
- PINLIST...
- 14 13 12 11 10 09 07 06 05 04 03 02 01 52 51 50 49 48 47 45 44 43 42 41
- 18 17 16 15 40 39 38 37 36 35 33 32 31 30 29 28
- 27 26 25 24 23 22 21 19 ;

```

TB039205

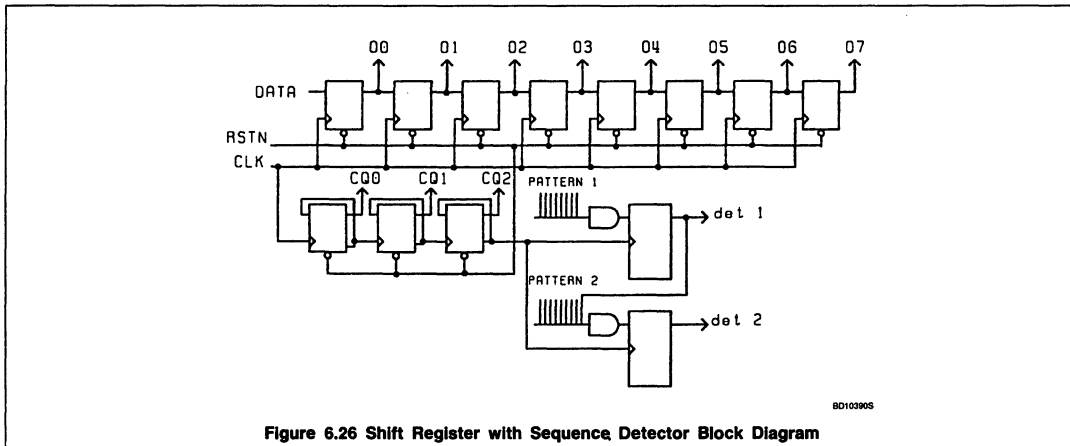
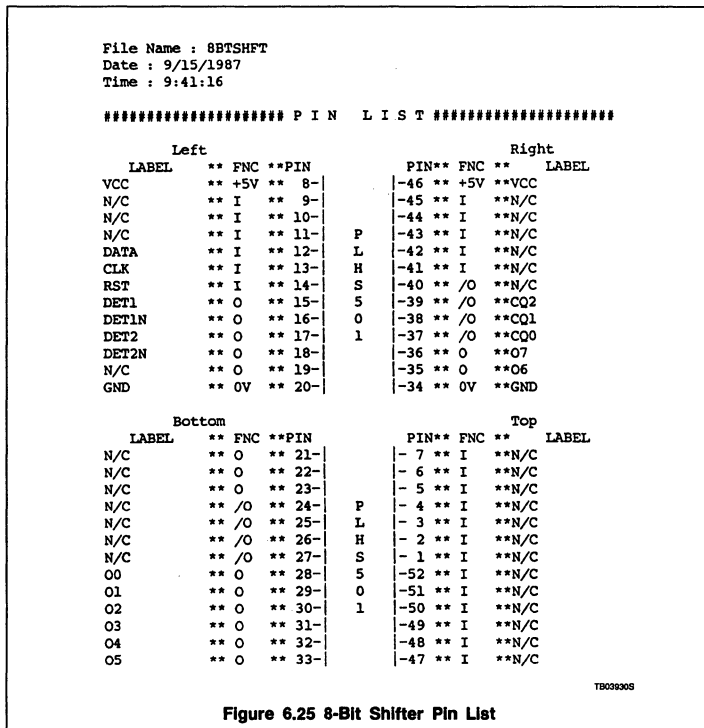
Figure 6.24 Encoder Simulation Log File

# Designing with Programmable Macro Logic

## 8-BIT SHIFT REGISTER WITH SEQUENCE DETECTOR

This example demonstrates an application using D type edge-triggered flip-flops. Six NAND gates are used for each flip-flop (Figure 3.2). Note that to add an asynchronous reset and/or set to any flip-flop requires no additional gates. Also, every flip-flop must have a reset or set line to initialize it. Without being initialized, the simulator will not be able to determine the output states as it could power-up in either a set or reset condition. An uninitialized flip-flop will cause AMAZE 1.6 to display a message indicating the outputs are not stabilized within a certain time period.

As can be seen from the block diagram (Figure 6.26) this design consists of an 8-bit shift register, 3-bit ripple counter and 2 flip-flops that are set only upon detection of specific patterns. The patterns are read from the Q and QN outputs of the shift register. Since the input to the second flip-flop has the output of the first flip-flop as a product term, detection of the first pattern is a requirement for the detection of the second.





# Designing with Programmable Macro Logic

```

File Name : 8BTSHFT
Date : 9/15/1987
Time : 9:41:35

@DEVICE TYPE
FLH501
@DRAWING
@REVISION
@DATE
@SYMBOL
@COMPANY
@NAME
@DESCRIPTION

8 Bit Shift Register with 16 bit Sequence Detector

@INTERNAL NODE
SNO,RNO,Q0;
SN1,RN1,Q1;
SN2,RN2,Q2;
SN3,RN3,Q3;
SN4,RN4,Q4;
SN5,RN5,Q5;
SN6,RN6,Q6;
SN7,RN7,Q7;
CSNO,CRNO,CQNO;
CSN1,CRN1,CQN1;
CSN2,CRN2,CQN2;
PSNO,PRNO;
PSN1,PRN1;
@COMMON PRODUCT TERM
PAT1 = Q7*Q6*Q5*Q4*Q3*Q2*Q1*Q0;
PAT2 = Q7*Q6*Q5*Q4*Q3*Q2*Q1*Q0;
@I/O DIRECTION
@I/O STEERING
@LOGIC EQUATION

"8 D-TYPE FLIP FLOPS CONNECTED AS SHIFT REGISTER"

SNO = /(CLK*RST*([SNO*([DATA*RST*RNO]))));
RNO = /(SNO*CLK*([DATA*RST*RNO]));
Q0 = /(SNO*([RNO*Q0*RST]));

SN1 = /(CLK*RST*([SN1*([Q0*RST*RN1]))));
RN1 = /(SN1*CLK*([Q0*RST*RN1]));
Q1 = /(SN1*([RN1*Q1*RST]));

```

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Figure 6.27 8-Bit Shifter Boolean Equations

## Designing with Programmable Macro Logic

```

SN2 = /(CLK*RST*(/(SN2*([Q1*RST*RN2]))));
RN2 = /(SN2*CLK*(/[Q1*RST*RN2]));
Q2 = /(SN2*(/[RN2*Q2*RST]));

SN3 = /(CLK*RST*(/(SN3*([Q2*RST*RN3]))));
RN3 = /(SN3*CLK*(/[Q2*RST*RN3]));
Q3 = /(SN3*(/[RN3*Q3*RST]));

SN4 = /(CLK*RST*(/(SN4*([Q3*RST*RN4]))));
RN4 = /(SN4*CLK*(/[Q3*RST*RN4]));
Q4 = /(SN4*(/[RN4*Q4*RST]));

SN5 = /(CLK*RST*(/(SN5*([Q4*RST*RN5]))));
RN5 = /(SN5*CLK*(/[Q4*RST*RN5]));
Q5 = /(SN5*(/[RN5*Q5*RST]));

SN6 = /(CLK*RST*(/(SN6*([Q5*RST*RN6]))));
RN6 = /(SN6*CLK*(/[Q5*RST*RN6]));
Q6 = /(SN6*(/[RN6*Q6*RST]));

SN7 = /(CLK*RST*(/(SN7*([Q6*RST*RN7]))));
RN7 = /(SN7*CLK*(/[Q6*RST*RN7]));
Q7 = /(SN7*(/[RN7*Q7*RST]));

O0 = Q0;
O1 = Q1;
O2 = Q2;
O3 = Q3;
O4 = Q4;
O5 = Q5;
O6 = Q6;
O7 = Q7;

"3 D-TYPE FLIP FLOPS CONNECTED AS A RIPPLE COUNTER"

CSN0 = /(CLK*RST*(/(CSN0*(/[CQNO*RST*CRNO]))));
CRNO = /(CSN0*CLK*(/[CQNO*RST*CRNO]));
CQ0 = /(CSN0*CQNO);
CQNO = /(CRNO*CQ0*RST);

CSN1 = /(CQNO*RST*(/(CSN1*(/[CQN1*RST*CRN1]))));
CRN1 = /(CSN1*CQNO*(/[CQN1*RST*CRN1]));
CQ1 = /(CSN1*CQN1);
CQN1 = /(CRN1*CQ1*RST);

CSN2 = /(CQN1*RST*(/(CSN2*(/[CQN2*RST*CRN2]))));
CRN2 = /(CSN2*CQN1*(/[CQN2*RST*CRN2]));
CQ2 = /(CSN2*CQN2);
CQN2 = /(CRN2*CQ2*RST);

```

TB039505

"2 D-TYPE FLIP FLOPS USED FOR PATTERN SEQUENCE DETECTION.  
Sequence to be detected is 16 bits - 55AA Hex.  
When the pattern is detected, pin det2 will go high.

In this example, both pattern 1 and pattern 2 are set to FF hex. To change the pattern to 55AA, the STD file (P68 and P70) was edited using FTE. This was necessary because AMAZE 1.6 only allows 40 internal labels, so it was not possible to reference the QN nodes of the shift register flip-flops."

```

PSNO = /(CQN2*RST*(/(PSNO*(/[PAT1*RST*PRNO]))));
PRNO = /(PSNO*CQN2*(/[PAT1*RST*PRNO]));
DET1N = (PSNO/DET1);
DET1 = (PRNO/DET1N*RST);

PSN1 = /(CQN2*RST*(/(PSN1*(/[PAT2*DET1*RST*PRN1]))));
PRN1 = /(PSN1*CQN2*(/[PAT2*DET1*RST*PRN1]));
DET2N = (PSN1/DET2);
DET2 = (PRN1/DET2N*RST);

```

TB039605

Figure 6.27 8-Bit Shifter Boolean Equations (Continued)

# Designing with Programmable Macro Logic

```
----- Col for P 67  
...A.....A.....  
H----- Col for P 68  
.....A.....A.....A.....A.....A.....  
----- Col for P 69  
.A.....A.....  
H-----H----- Col for P 70  
.....A.....A.....A.....A.....A.....  
----- Col for P 71  
.....  
HHHH
```

Original STD file showing P 68 and P 70

```
----- Col for P 67  
...A.....A.....  
H----- Col for P 68  
.....A.....A.....A.....A.....A.....  
----- Col for P 69  
.A.....A.....  
H-----H----- Col for P 70  
.....A.....A.....A.....A.....A.....  
----- Col for P 71  
.....  
HHHH
```

TB029705

Figure 6.28 Portion of STD Files





# Designing with Programmable Macro Logic

## 4-BIT SYNCHRONOUS COUNTER

This counter produces a binary count on outputs Count3-Count0. Note the required reset (RST) input to initialize all of the flip-flops. The inputs for each flip-flop were first determined by drawing the desired output waveforms. Next, Karnaugh maps were used to reduce the number of terms and determine the logic equations for the input to each flip-flop. This technique could be used to construct a counter whose outputs produce some count other than binary.

The simulation only consists of a reset, followed by a number of clocks to count from 0 through 15 and back to 0.

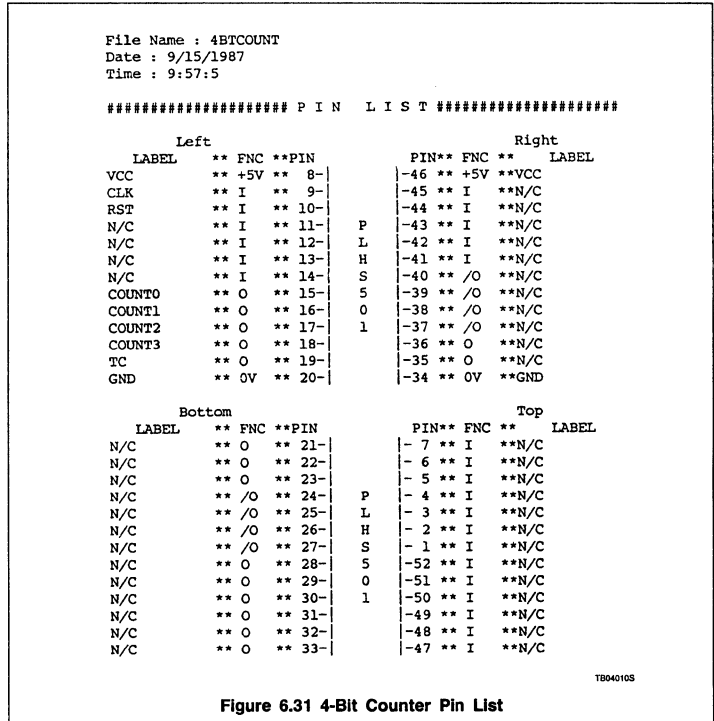


Figure 6.31 4-Bit Counter Pin List

## Designing with Programmable Macro Logic

```

File Name : 4BTCOUNT
Date : 9/15/1987
Time : 9:57:28

@DEVICE TYPE
PLHS01
@DRAWING
@REVISION
@DATE
@SYMBOL
@COMPANY
@NAME
@DESCRIPTION

    4 bit synchronous counter

@INTERNAL NODE
data1,data2,data3;
csn0,crn0,cq0,cqn0;
csn1,crn1,cq1,cqn1;
csn2,crn2,cq2,cqn2;
csn3,crn3,cq3,cqn3;
@COMMON PRODUCT TERM
@I/O DIRECTION
@I/O STEERING
@LOGIC EQUATION

"INPUTS FOR EACH FLIP-FLOP"

DATA1 = [(CQ1*CQ0)+(CQ1*CQ0)];
DATA2 = [(CQ0*CQ1+CQ2)+(CQ0*CQ2)+(CQ1*CQ2)];
DATA3 = [(CQ2*CQ3)+(CQ0*CQ3)+(CQ0*CQ1+CQ2*CQ3)+(CQ1*CQ3)];

"4 D-TYPE FLIP FLOPS CONNECTED AS A SYNCHRONOUS COUNTER"

CSN0 = /(CLK*RST*([CSN0*([CQ0*RST*CRN0]))]);
CRN0 = /(CSN0*CLK*([CQ0*RST*CRN0]);
CQ0 = /(CSN0*CQ0);
CQN0 = /(CRN0*CQ0*RST);

CSN1 = /(CLK*RST*([CSN1*([DATA1*RST*CRN1]))]);
CRN1 = /(CSN1*CLK*([DATA1*RST*CRN1]);
CQ1 = /(CSN1*CQ1);
CQN1 = /(CRN1*CQ1*RST);

CSN2 = /(CLK*RST*([CSN2*([DATA2*RST*CRN2]))]);
CRN2 = /(CSN2*CLK*([DATA2*RST*CRN2]);
CQ2 = /(CSN2*CQ2);
CQN2 = /(CRN2*CQ2*RST);

CSN3 = /(CLK*RST*([CSN3*([DATA3*RST*CRN3]))]);
CRN3 = /(CSN3*CLK*([DATA3*RST*CRN3]);
CQ3 = /(CSN3*CQ3);
CQN3 = /(CRN3*CQ3*RST);

"Connection to output pins"

count0=cq0;
count1=cq1;
count2=cq2;
count3=cq3;

"TERMINAL COUNT PIN"

TC=(CQ0*CQ1*CQ2*CQ3);

```

TB040205

TB040305

Figure 6.32 4-Bit Counter Boolean Equations

# Designing with Programmable Macro Logic

```
-  
- 4 Bit Synchronous Counter Simulation Input  
-  
HHHHL##### "RESET"  
HHHHL##### "COUNT1"  
HHHHL##### "COUNT2"  
HHHHL##### "COUNT3"  
HHHHL##### "COUNT4"  
HHHHL##### "COUNT5"  
HHHHL##### "COUNT6"  
HHHHL##### "COUNT7"  
HHHHL##### "COUNT8"  
HHHHL##### "COUNT9"  
HHHHL##### "COUNT10"  
HHHHL##### "COUNT11"  
HHHHL##### "COUNT12"  
HHHHL##### "COUNT13"  
HHHHL##### "COUNT14"  
HHHHL##### "COUNT15"  
HHHHL##### "COUNT0"  
QUIT
```

TB04040S

Figure 6.33 4-Bit Counter Simulation Input File





Application Specific Products

### INDEX

A	PLASTIC: Leaded Chip Carrier .....	10-3
F	CERAMIC: Dual-In-Line .....	10-6
FA	CERAMIC: Dual-In-Line With Quartz Window .....	10-8
N	PLASTIC: Dual-In-Line .....	10-10



# Package Outlines

## PLASTIC PLCC

1. Package dimensions conform to JEDEC specifications for standard Leaded Chip Carrier outline (PLCC) package.
2. Controlling dimensions are given in inches with dimensions in millimeters contained in parentheses.
3. Dimensions and tolerancing per ANSI Y14.5M - 1982.
4. "D-E" and "F-G" are reference datums on the molded body and do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm (0.006") on any side.
5. Pin numbers start with pin #1 and continue counterclockwise when viewed from the top.
6. Lead material: Olin 194 (Copper Alloy) or equivalent, solder dipped.
7. Body material: Plastic (Epoxy).
8. Thermal resistance values are determined by temperature sensitive parameter (TSP) method. This method uses the

forward voltage drop of a calibrated diode to measure the change in junction temperature due to a known power application. Test condition for these values follow:

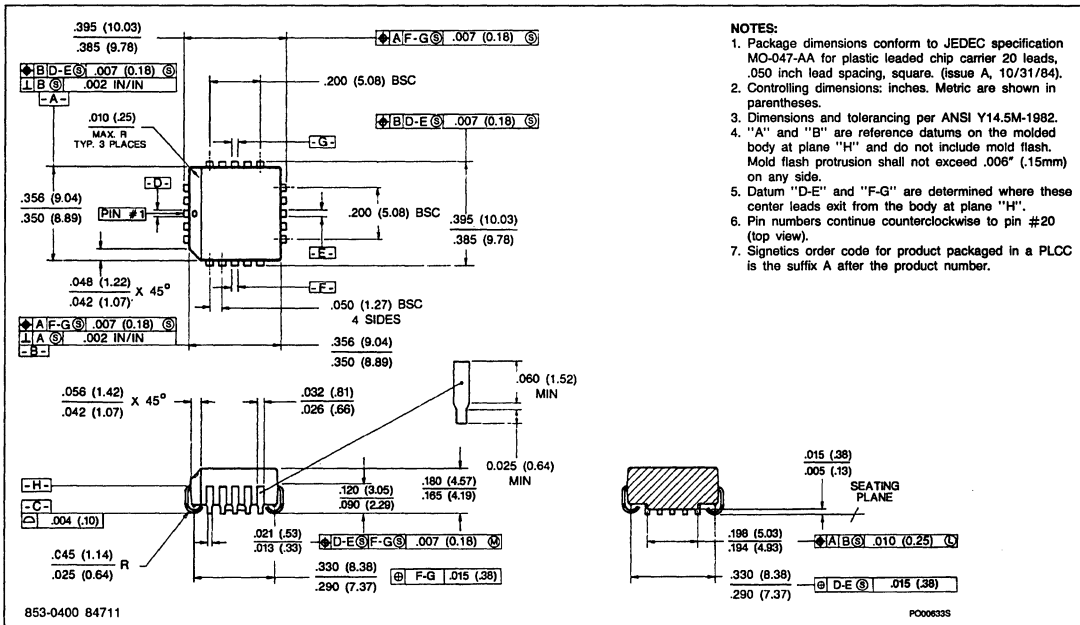
Test Ambient — Still Air  
 Test Fixture —  $\theta_{JA}$  — Glass epoxy test board (2.24" × 2.24" × 0.062")  
 $\theta_{JC}$  — Water cooled heat sink

## PLASTIC LEADED CHIP CARRIER (PLCC)

NO. OF LEADS	PACKAGE CODE	DESCRIPTION
20	A	350mil-wide
28	A	450mil-wide
52	A	750mil-wide
68	A	950mil-wide

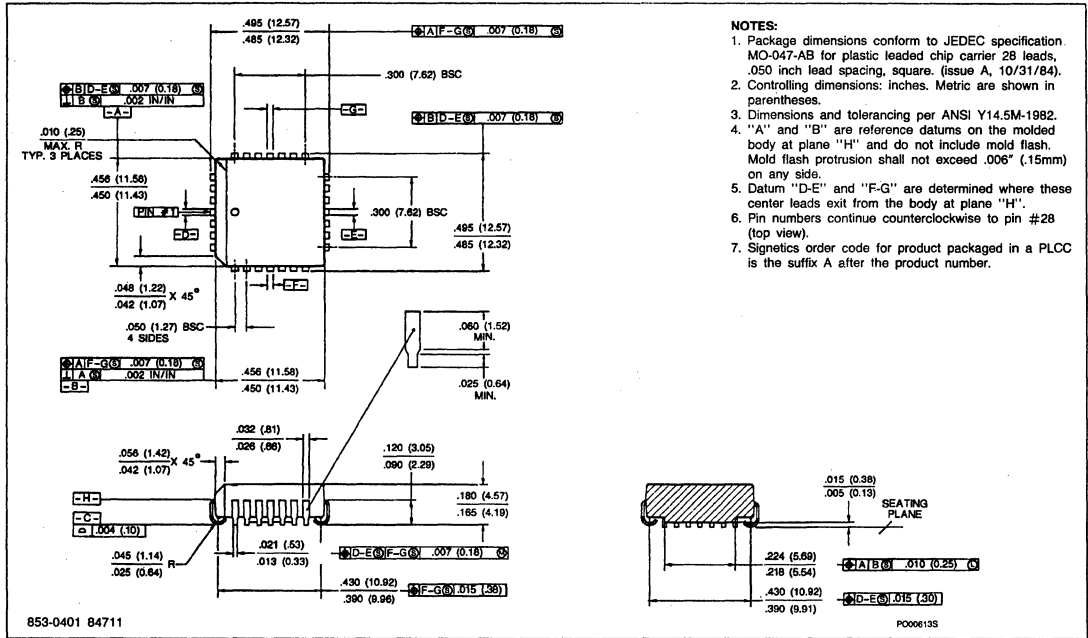
TYPICAL $\theta_{JA}/\theta_{JC}$ VALUES (°C/W)			
Die Size	Power Dissipation (W)	Average $\theta_{JA}$	Average $\theta_{JC}$
20K	.75	70	30
25K	1.0	61	23
50K	1.0	42	15

## 20-PIN PLASTIC PLCC (A PACKAGE)



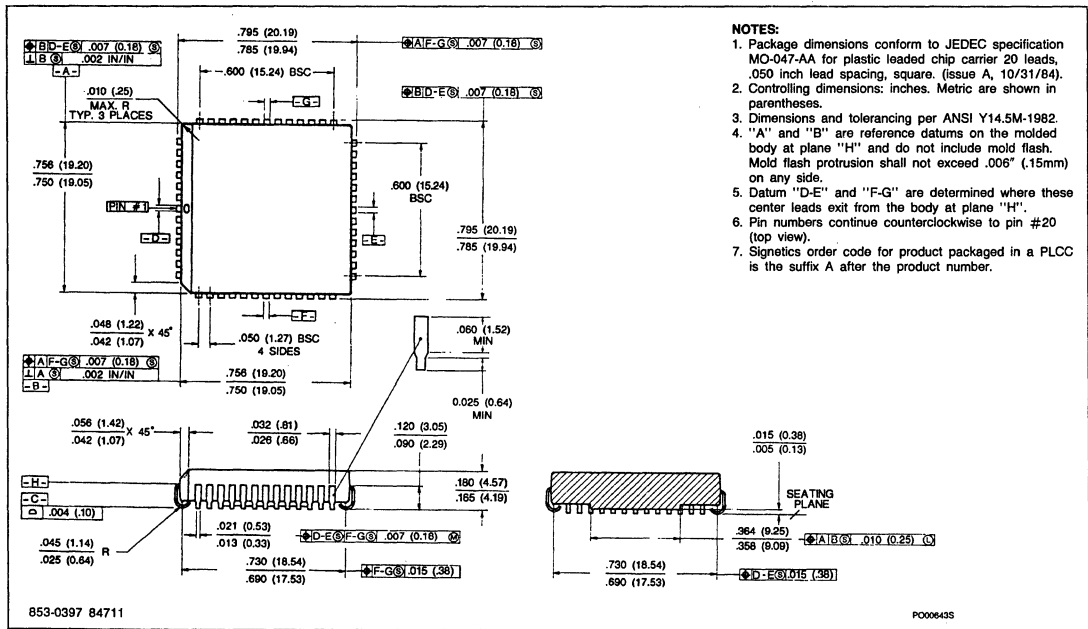
# Package Outlines

## 28-PIN PLASTIC PLCC (A PACKAGE)



- NOTES:**
1. Package dimensions conform to JEDEC specification MO-047-AS for plastic leaded chip carrier 28 leads, .050 inch lead spacing, square. (issue A, 10/31/84).
  2. Controlling dimensions: inches. Metric are shown in parentheses.
  3. Dimensions and tolerancing per ANSI Y14.5M-1982.
  4. "A" and "B" are reference datums on the molded body at plane "H" and do not include mold flash. Mold flash protrusion shall not exceed .006" (.15mm) on any side.
  5. Datum "D-E" and "F-G" are determined where these center leads exit from the body at plane "H".
  6. Pin numbers continue counterclockwise to pin #28 (top view).
  7. Signetics order code for product packaged in a PLCC is the suffix A after the product number.

## 52-PIN PLASTIC PLCC (A PACKAGE)



- NOTES:**
1. Package dimensions conform to JEDEC specification MO-047-AA for plastic leaded chip carrier 20 leads, .050 inch lead spacing, square. (issue A, 10/31/84).
  2. Controlling dimensions: inches. Metric are shown in parentheses.
  3. Dimensions and tolerancing per ANSI Y14.5M-1982.
  4. "A" and "B" are reference datums on the molded body at plane "H" and do not include mold flash. Mold flash protrusion shall not exceed .006" (.15mm) on any side.
  5. Datum "D-E" and "F-G" are determined where these center leads exit from the body at plane "H".
  6. Pin numbers continue counterclockwise to pin #20 (top view).
  7. Signetics order code for product packaged in a PLCC is the suffix A after the product number.



# Package Outlines

## HERMETIC CERDIP

1. Package dimensions conform to JEDEC specifications for standard Ceramic Dual Inline (Cerdip) package.
2. Controlling dimensions are given in inches with dimensions in millimeters, mm, contained in parentheses.
3. Dimensions and tolerancing per ANSI Y14.5M - 1982.
4. Pin numbers start with pin #1 and continue counterclockwise when viewed from the top.
5. These dimensions measured with the leads constrained to be perpendicular to plane T.
6. Lead material: ASTM alloy F-30 (Alloy 42) or equivalent - tin plated or solder dipped.
7. Body Material: Ceramic with glass seal at leads.
8. Thermal resistance values are determined by temperature sensitive parameter (TSP) method. This method uses the

forward voltage drop of a calibrated diode to measure the change in junction temperature due to a known power application. Test condition for these values follow:

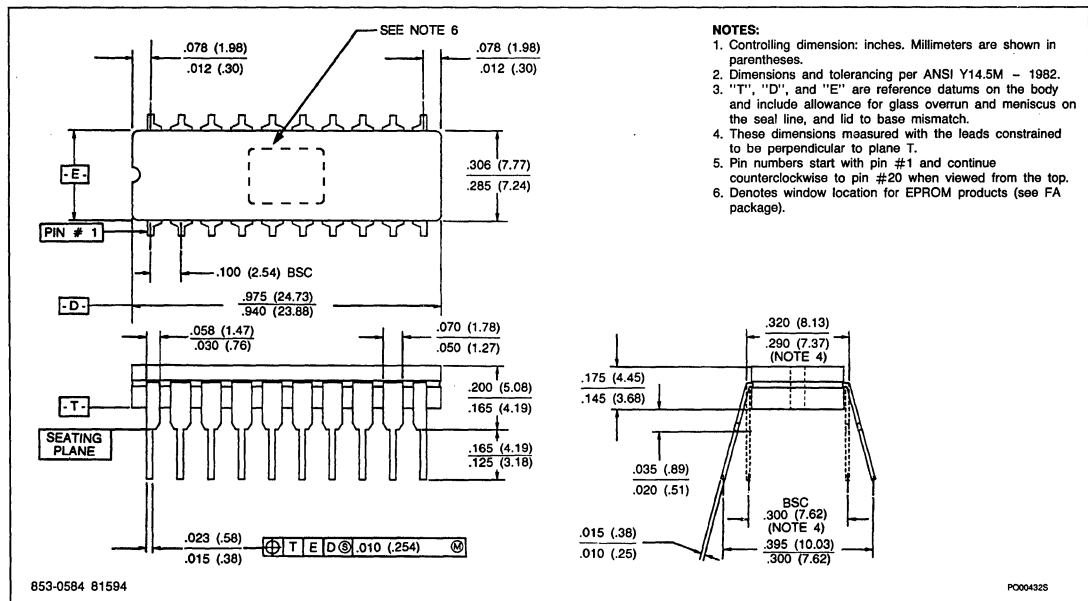
- Test Ambient — Still Air
- Test Fixture —  $\theta_{JA}$  - Textool ZIF socket with 0.04" stand-off
- $\theta_{JC}$  - Water cooled heat sink

## HERMETIC DUAL-IN-LINE PACKAGES

NO. OF LEADS	PACKAGE CODE	DESCRIPTION
20	F	300mil-wide
24	F	300mil-wide
28	F	600mil-wide

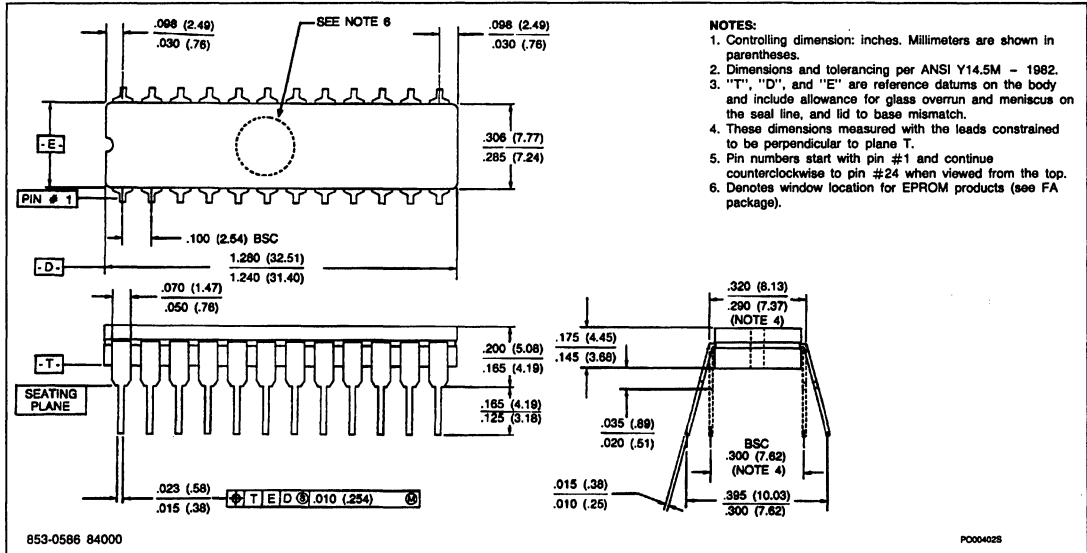
TYPICAL $\theta_{JA}/\theta_{JC}$ VALUES (°C/W)			
Die Size	Power Dissipation (W)	Average $\theta_{JA}$	Average $\theta_{JC}$
20K	.75	70	7.8
25K	1.0	62	6.9
30K	1.0	48	6.3

## 20-PIN CERAMIC DIP (F PACKAGE)

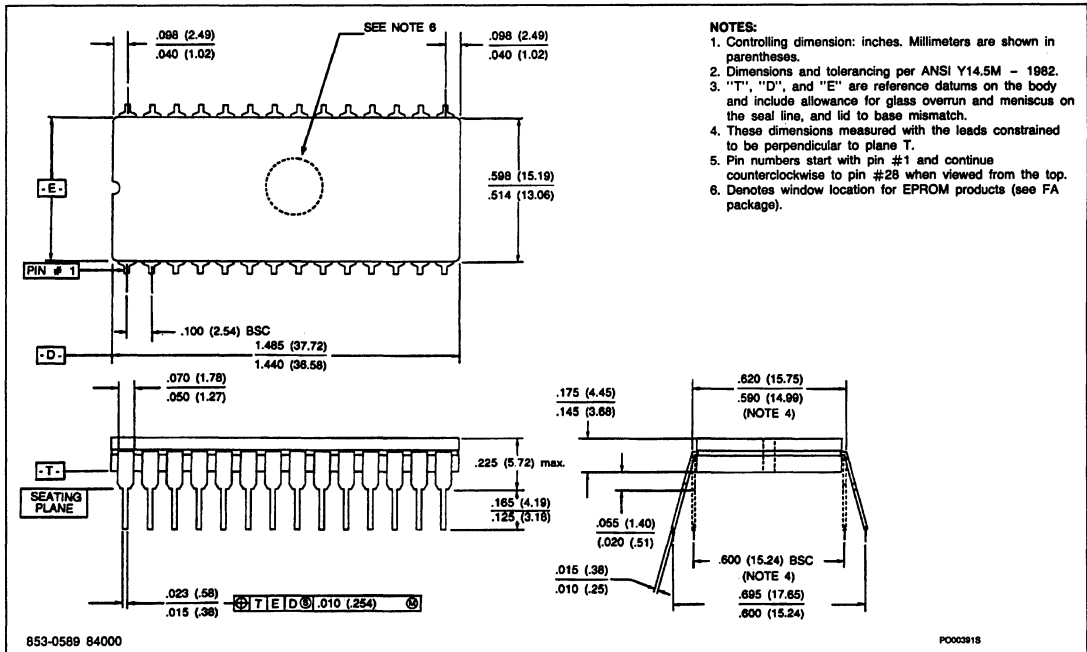


# Package Outlines

## 24-PIN CERAMIC DIP (F PACKAGE)



## 28-PIN CERAMIC DIP (F PACKAGE)





## Package Outlines

### HERMETIC CERDIP WITH QUARTZ WINDOW

- Package dimensions conform to JEDEC specifications for standard Ceramic Dual Inline (Cerdip) package.
- Controlling dimensions are given in inches with dimensions in millimeters, mm, contained in parentheses.
- Dimensions and tolerancing per ANSI Y14.5M - 1982.
- Pin numbers start with pin #1 and continue counterclockwise when viewed from the top.
- These dimensions measured with the leads constrained to be perpendicular to plane T.
- Lead material: ASTM alloy F-30 (Alloy 42) or equivalent - tin plated or solder dipped.
- Body Material: Ceramic with glass seal at leads.
- Thermal resistance values are determined by temperature sensitive parameter (TSP) method. This method uses the

forward voltage drop of a calibrated diode to measure the change in junction temperature due to a known power application. Test condition for these values follow:

Test Ambient — Still Air

Test Fixture —  $\theta_{JA}$  - Textool ZIF socket with 0.04" stand-off

$\theta_{JC}$  - Water cooled heat sink

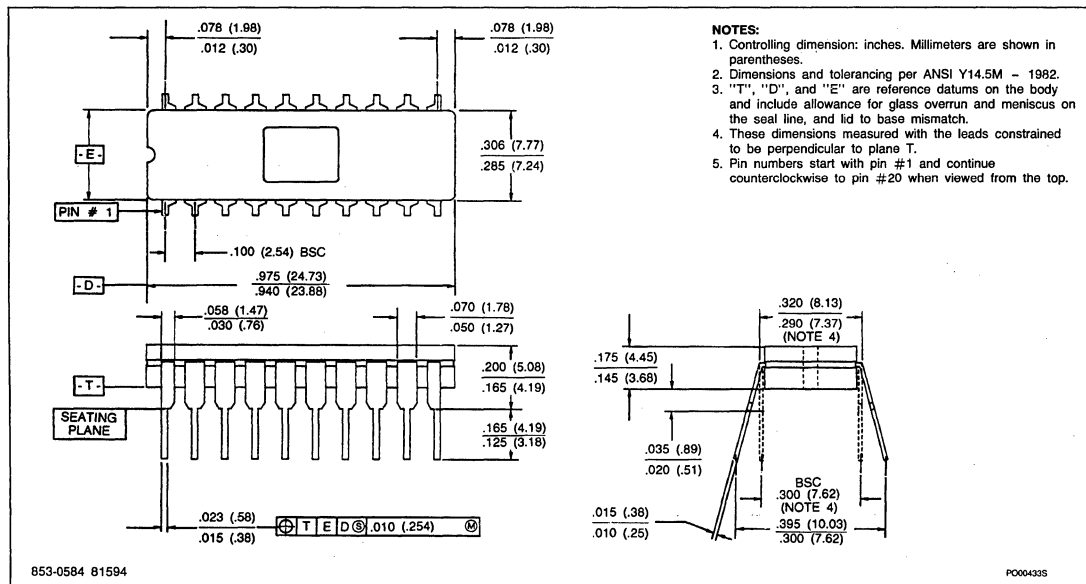
### HERMETIC DUAL-IN-LINE PACKAGES WITH QUARTZ WINDOW

NO. OF LEADS	PACKAGE CODE	DESCRIPTION
20	FA	300mil-wide
24	FA	300mil-wide
28	FA	600mil-wide

### TYPICAL $\theta_{JA}/\theta_{JC}$ VALUES ( $^{\circ}\text{C}/\text{W}$ )

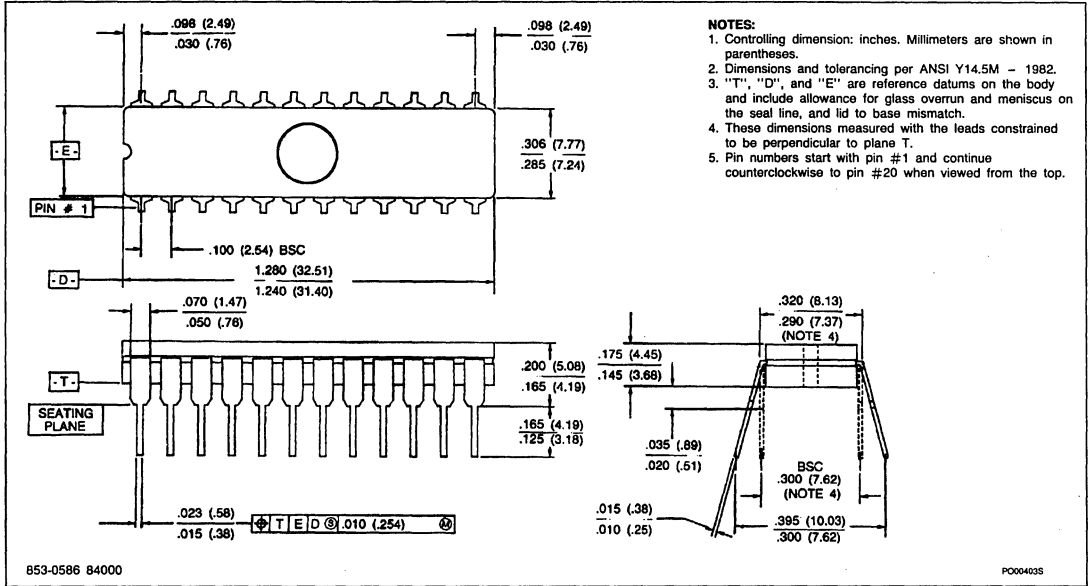
Die Size	Power Dissipation (W)	Average $\theta_{JA}$	Average $\theta_{JC}$
25K	.5	67	7.8
30K	.5	52	7.0

### 20-PIN CERAMIC DIP WITH QUARTZ WINDOW (FA PACKAGE)

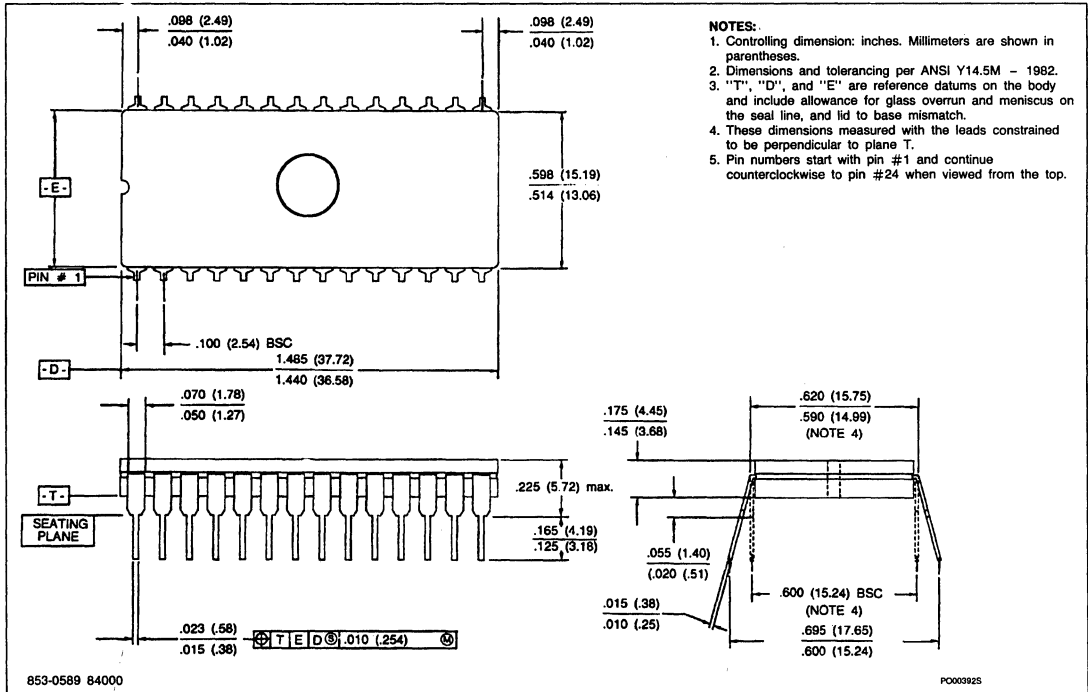


# Package Outlines

## 24-PIN CERAMIC DIP WITH QUARTZ WINDOW (FA PACKAGE)



## 28-PIN CERAMIC DIP WITH QUARTZ WINDOW (FA PACKAGE)



# Package Outlines

## PLASTIC DIP

1. Package dimensions conform to JEDEC specification MS-001-AA for standard Plastic Dual In-line (DIP) package.
2. Controlling dimensions are given in inches with dimensions in millimeters, mm, contained in parentheses.
3. Dimensions and tolerancing per ANSI Y14.5M - 1982.
4. "T", "D" and "E" are reference datums on the molded body and do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.01 inch (0.25mm) on any side.
5. These dimensions measured with the leads constrained to be perpendicular to plane T.
6. Pin numbers start with pin #1 and continue counterclockwise when viewed from the top.
7. Lead material: Olin 194 (Copper Alloy) or equivalent, solder dipped.
8. Body material: Plastic (Epoxy)
9. Thermal resistance values are determined by temperature sensitive parameter (TSP) method. This method uses the

forward voltage drop of a calibrated diode to measure the change in junction temperature due to a known power application. Test condition for these values follow:

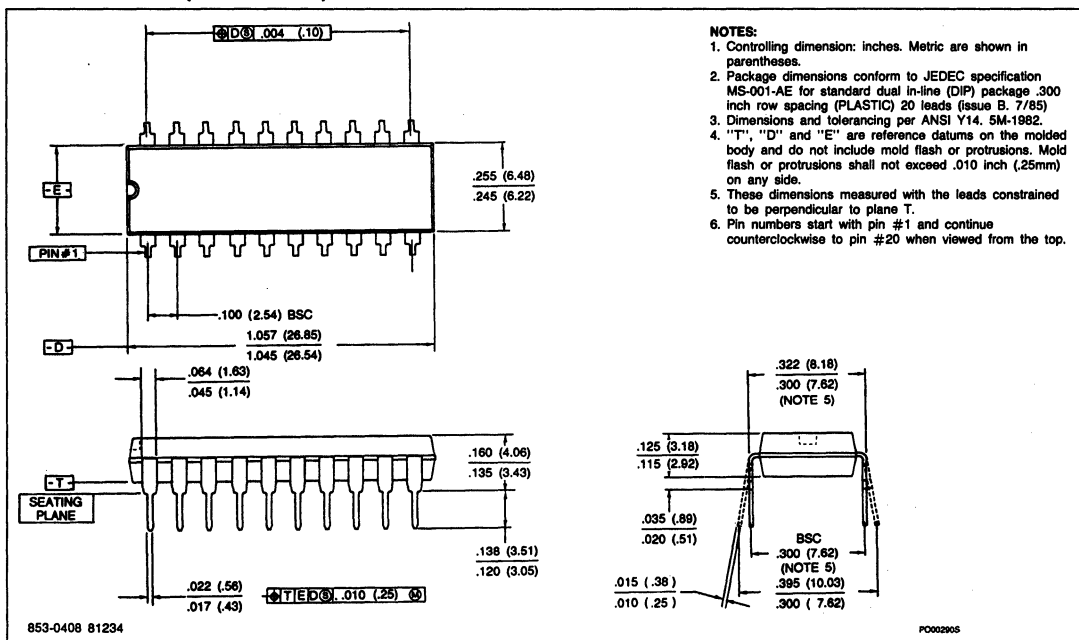
- Test Ambient — Still Air
- Test Fixture —  $\theta_{JA}$  - Textool ZIF socket with 0.04" stand-off
- $\theta_{JC}$  - Water cooled heat sink

## PLASTIC DUAL-IN-LINE PACKAGES

NO. OF LEADS	PACKAGE CODE	DESCRIPTION
20	N	Cu. Lead Frame 300mil-wide
24	N	Cu. Lead Frame 300mil-wide
28	N	Cu. Lead Frame 600mil-wide

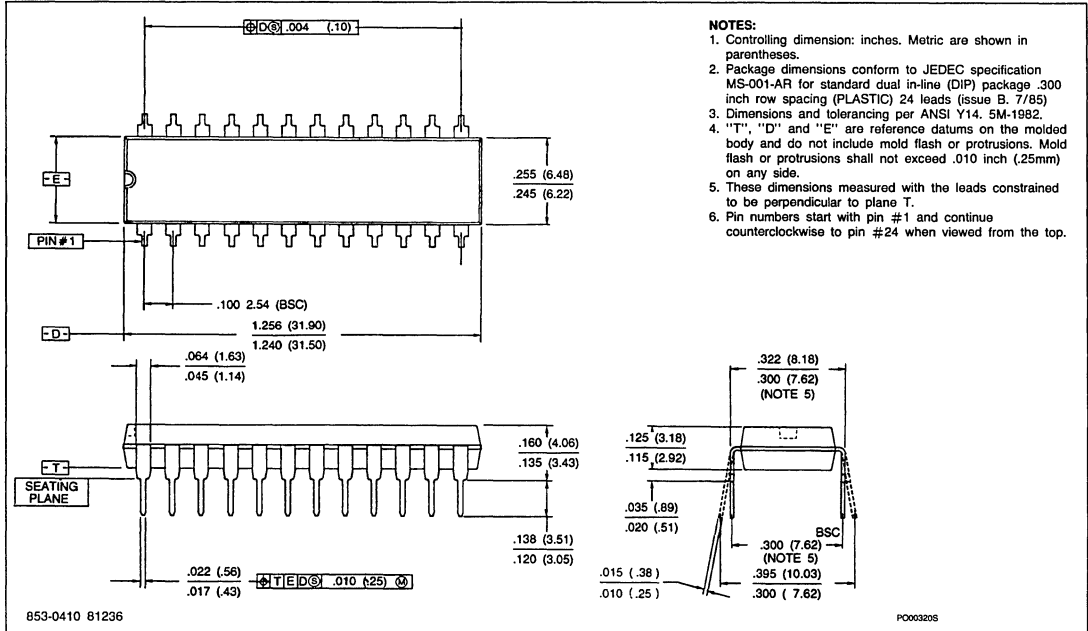
TYPICAL $\theta_{JA}/\theta_{JC}$ VALUES ( $^{\circ}\text{C}/\text{W}$ )			
Die Size	Power Dissipation (W)	Average $\theta_{JA}$	Average $\theta_{JC}$
20K	.75	61	25
25K	1.0	55	25
50K	1.0	46	18

## 20-PIN PLASTIC (N PACKAGE)

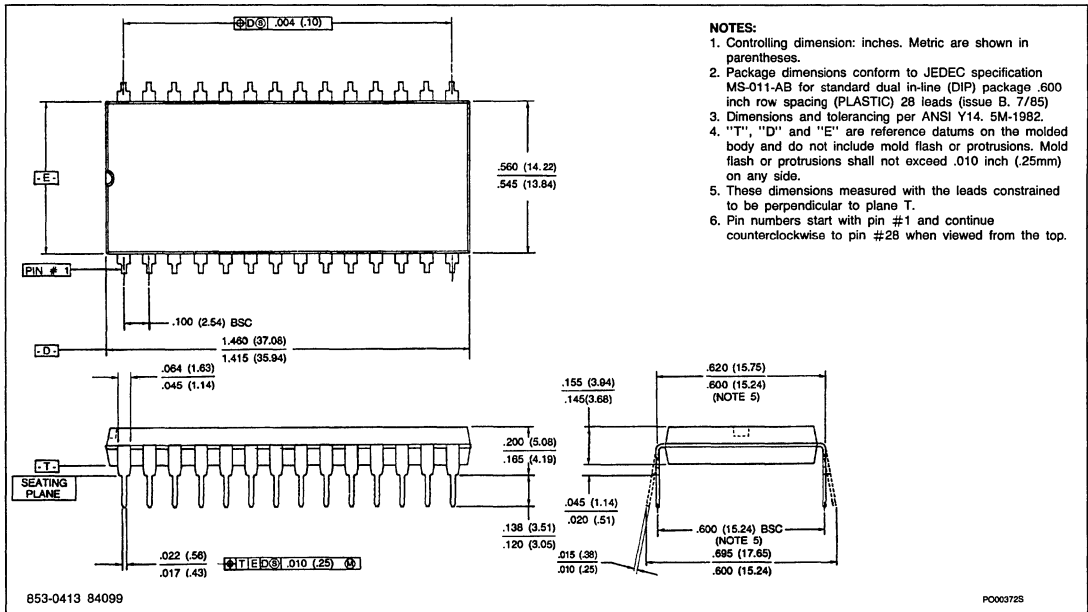


# Package Outlines

## 24-PIN PLASTIC (N PACKAGE)



## 28-PIN PLASTIC (N PACKAGE)





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